

# Deep RL Learning - Deep Reinforcement learning for robots

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**Abstract**—In this project we create

**Index Terms**—Reinforcement learning, Deep Learning, Robotics, ROS.

## 1 INTRODUCTION

**M**OBILE robots

## 2 BACKGROUND / FORMULATION

Because

### 2.1 RTABMap Slam

In this project we demonstrate

- Wheel Odometry Measures the distance traveled by each wheel.
- Hokuyo Laser Rangefinder Mounted on top of the cylinder.
- RGB-Depth Camera Mounted on the front of the cylinder.

## 3 CONFIGURATION

Much

### 3.1 RTABMap Config

The configuration

### 3.2 Robot Config

The robot used in this project,

## 4 RESULTS

Map generation was reasonable, but not perfect as detailed below.

### 4.1 Results - Kitchen and Dining World

From Run1 Fig 1

From Run2 Fig ?? it is seen that RTABMap was able to detect 46 loop closures and generate a recognizable 3D map. However, again some flaws are evident. For example it is evident that RTABMap was unable to detect the correspondence of the stool images and there are thus 'ghost' stool images.

## 5 DISCUSSION

The maps

## 6 CONCLUSION / FUTURE WORK

The project

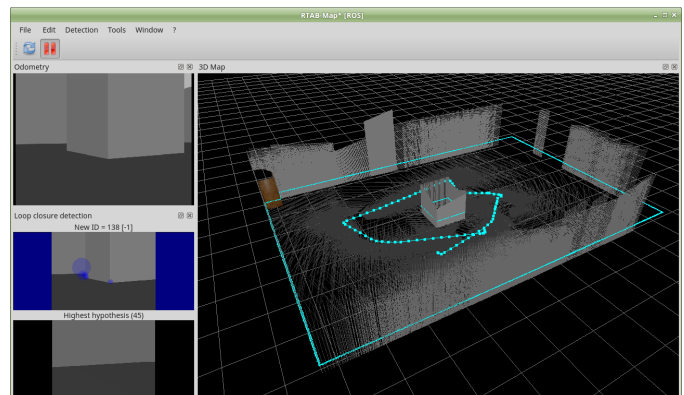


Fig. 1. Kitchen and Dining World DBView Run1