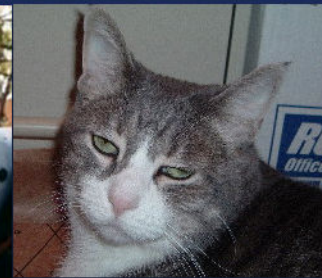
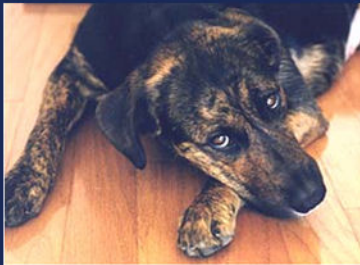
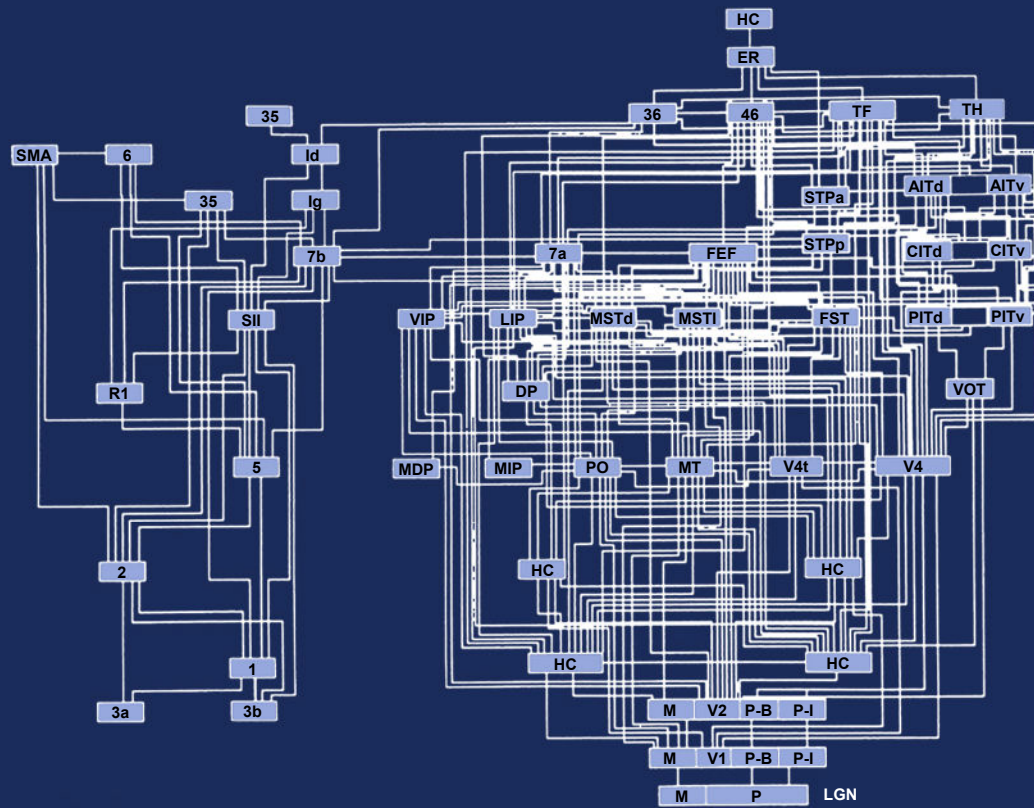


**Mary saw the puppy in the window.  
She wanted it.**







- Knowledge is distributed hierarchically
- Self training through changing sensory patterns
- Each region is similar



46 TF TH

STPa

AITd AITv

7a FEF STPp

CITv CITd

VIP LIP MSTd MSTI FST

PITd PITv

DP VOT

MDP MIP PO MT V4t

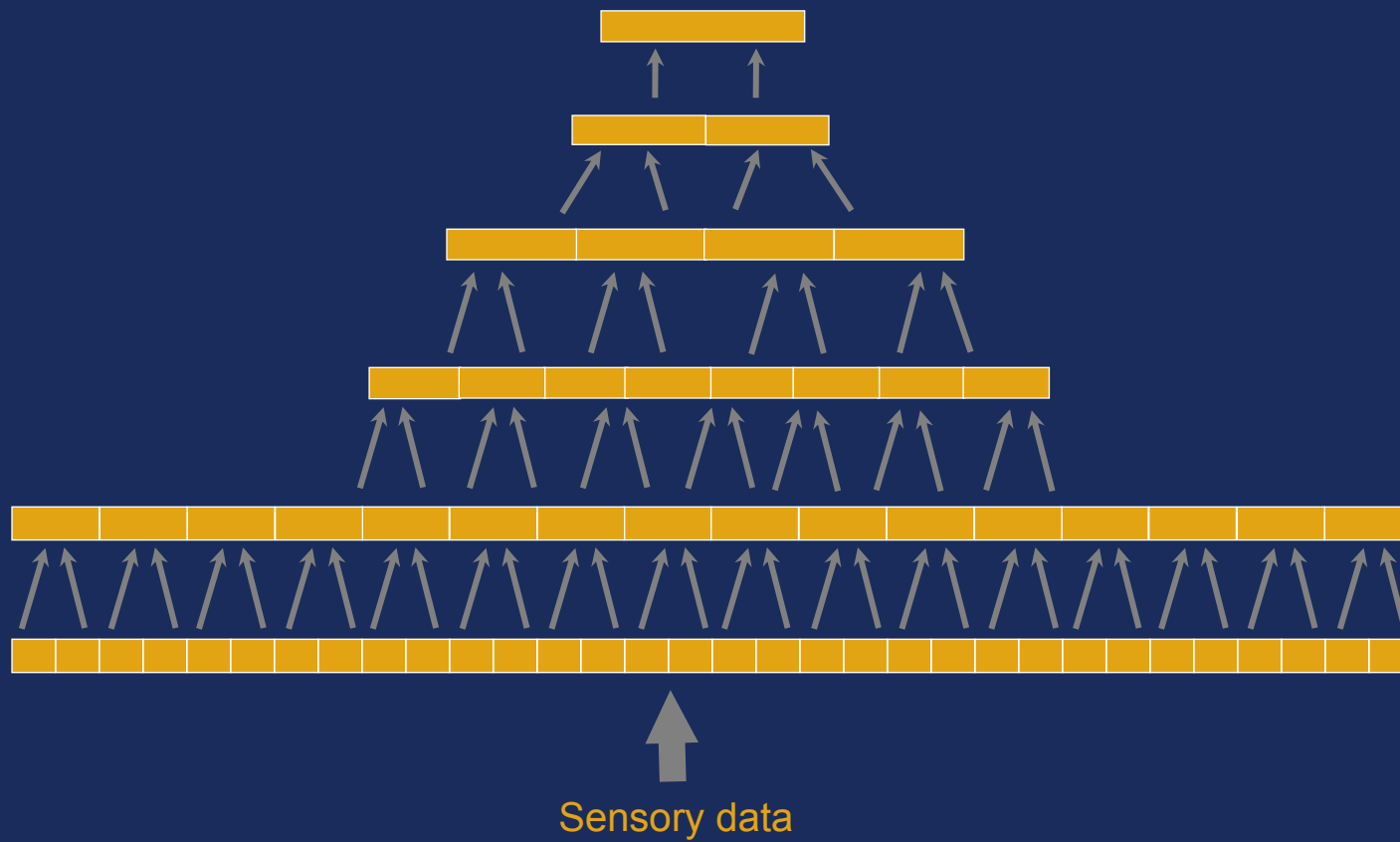
V4

PIP

V3A

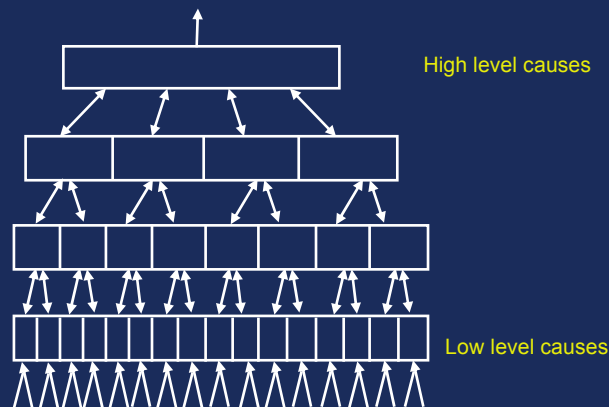
V2

V1





# Hierarchical Temporal Memory



All nodes do same thing

- Learn common spatial patterns
- Learn common sequences

Sequence names passed up

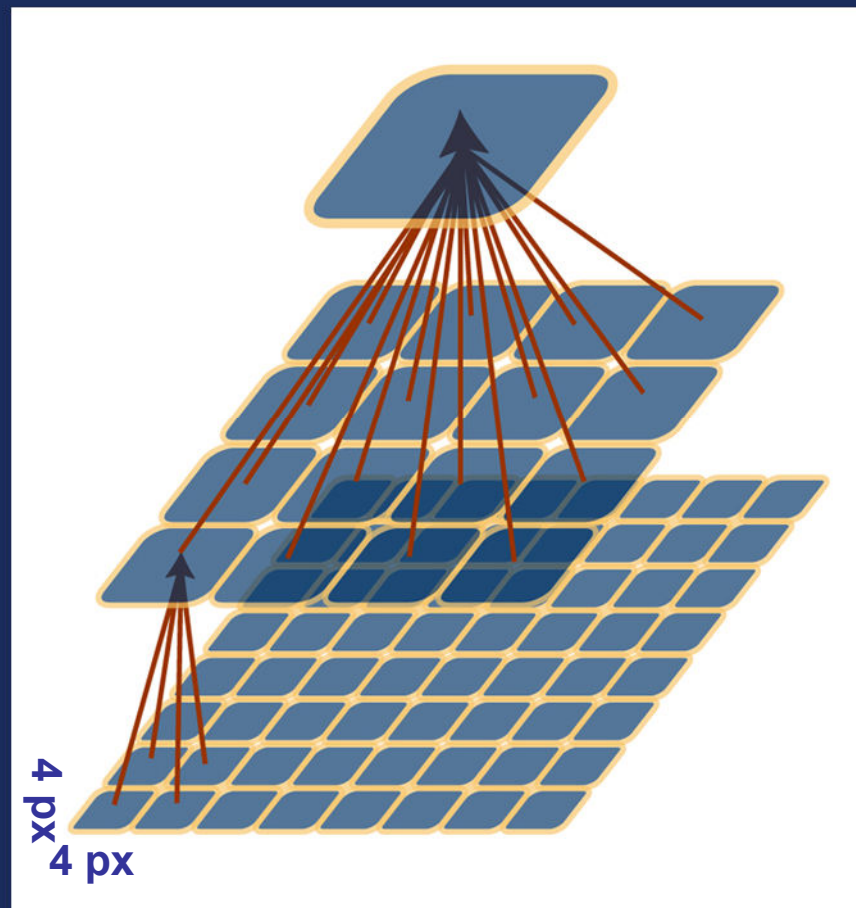
Predicted spatial patterns passed down

Creates hierarchical model of causes

Bayesian methods resolve ambiguity



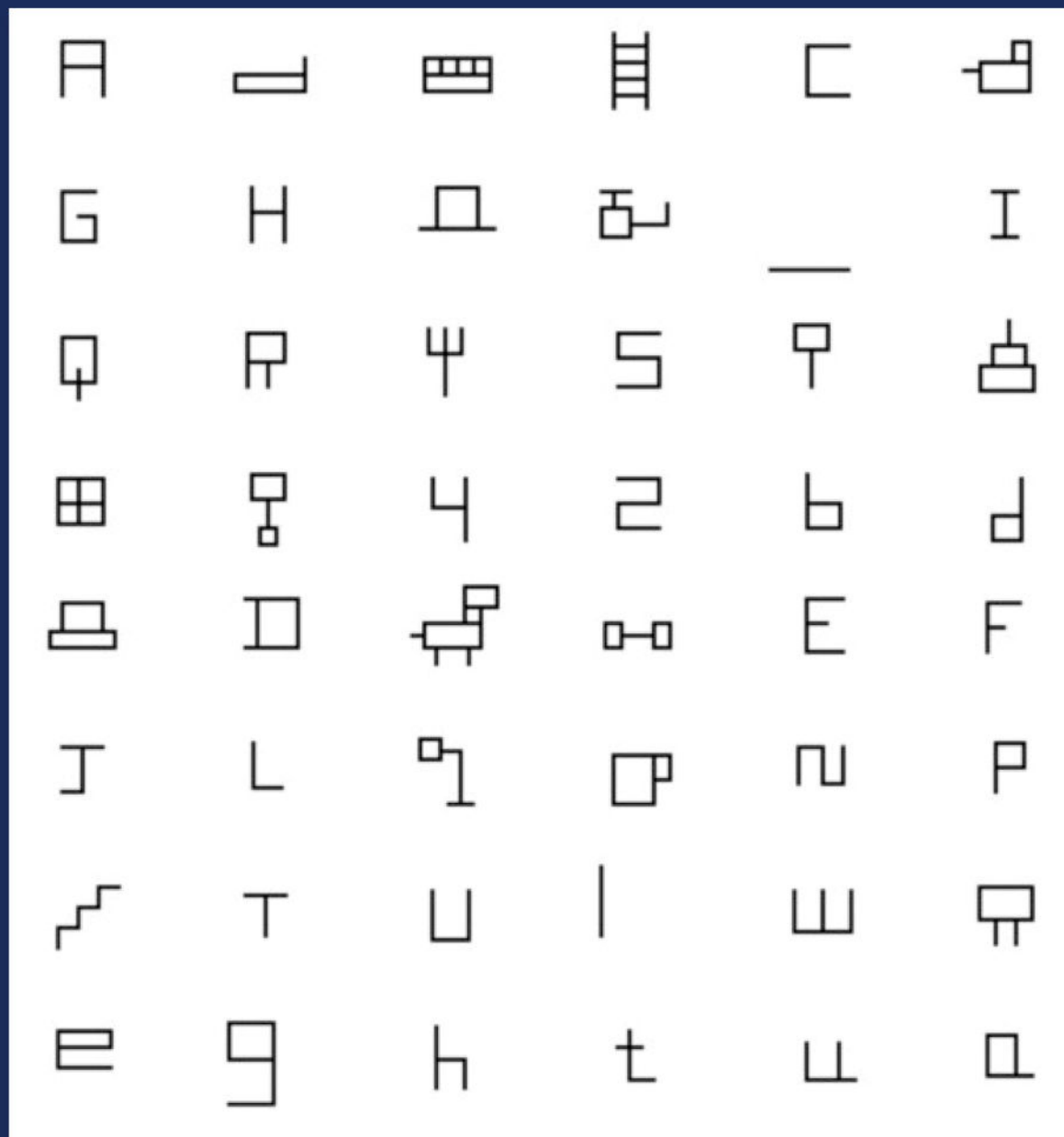
# Pictures: Simple Vision System (32 x 32 Pixels)













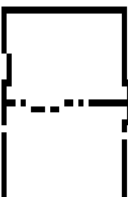






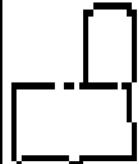




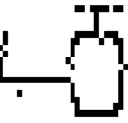


















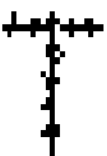








Level 3

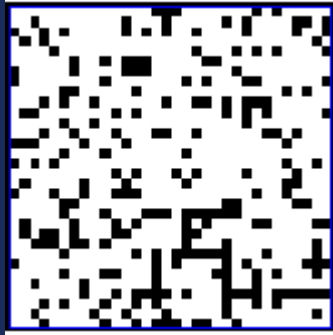
Level 2

Level 1



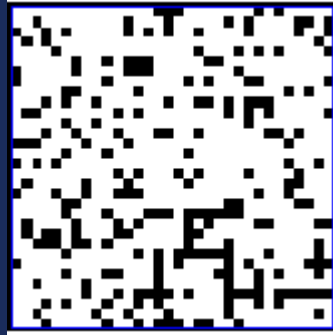
DOG	DUMB BELL	ENGLISH A	ENGLISH T	HELICOPTER	MUG	ENGLISH E	ENGLISH Q	ENGLISH S	CAT
									
									
									
									
									

# Time Based Inference



# Time Based Inference

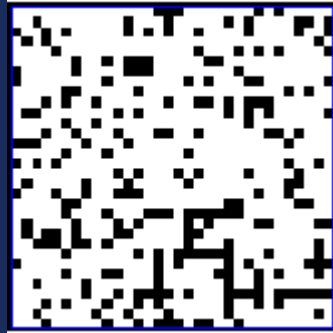
Static inference  
(with noise)



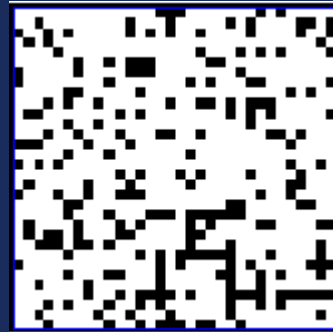
19%

# Time Based Inference

Static inference  
(with noise)

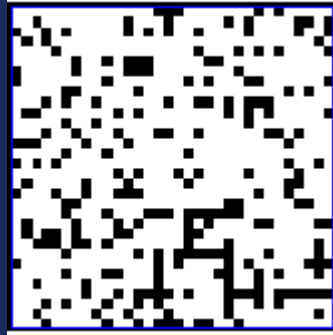


19%

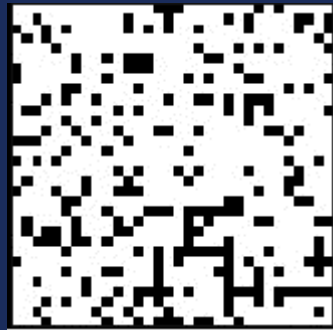


# Time Based Inference

Static inference  
(with noise)



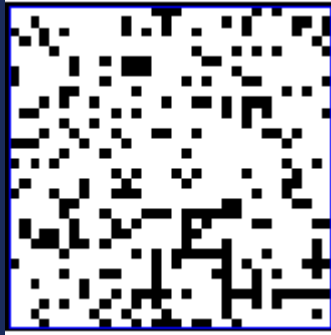
19%





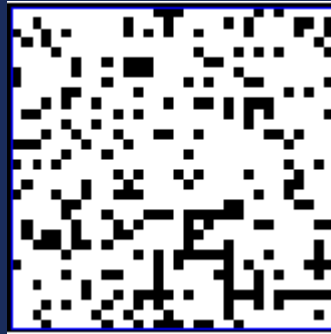
# Time Based Inference

Static inference  
(with noise)



19%

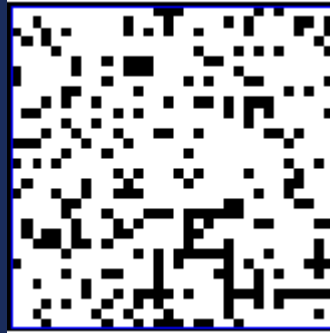
Time based inference  
(with noise)



52%

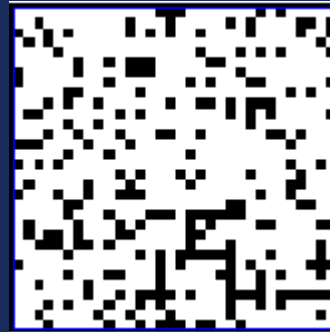
# Time Based Inference

Static inference  
(with noise)

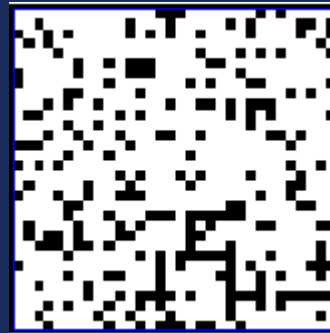


19%

Time based inference  
(with noise)

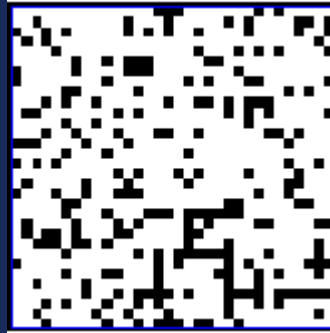


52%



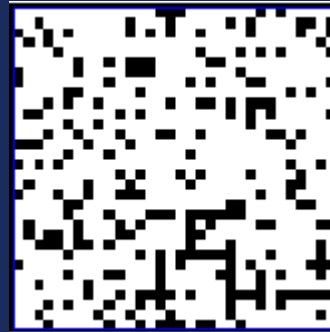
# Time Based Inference

Static inference  
(static noise)

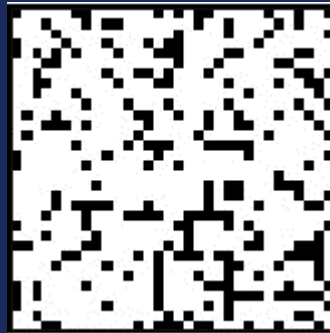


19%

Time based inference  
(with noise)

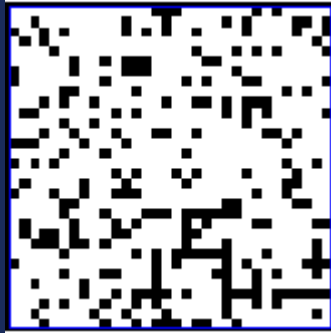


52%



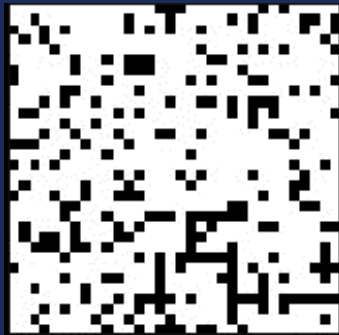
# Time Based Inference

Static inference  
(with noise)



19%

Time based inference  
(with noise)



52%



Click in box on the left to play video

Time based inference  
(with dynamic noise)



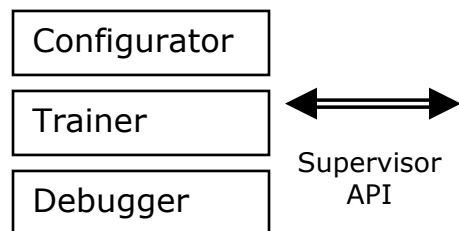
40%



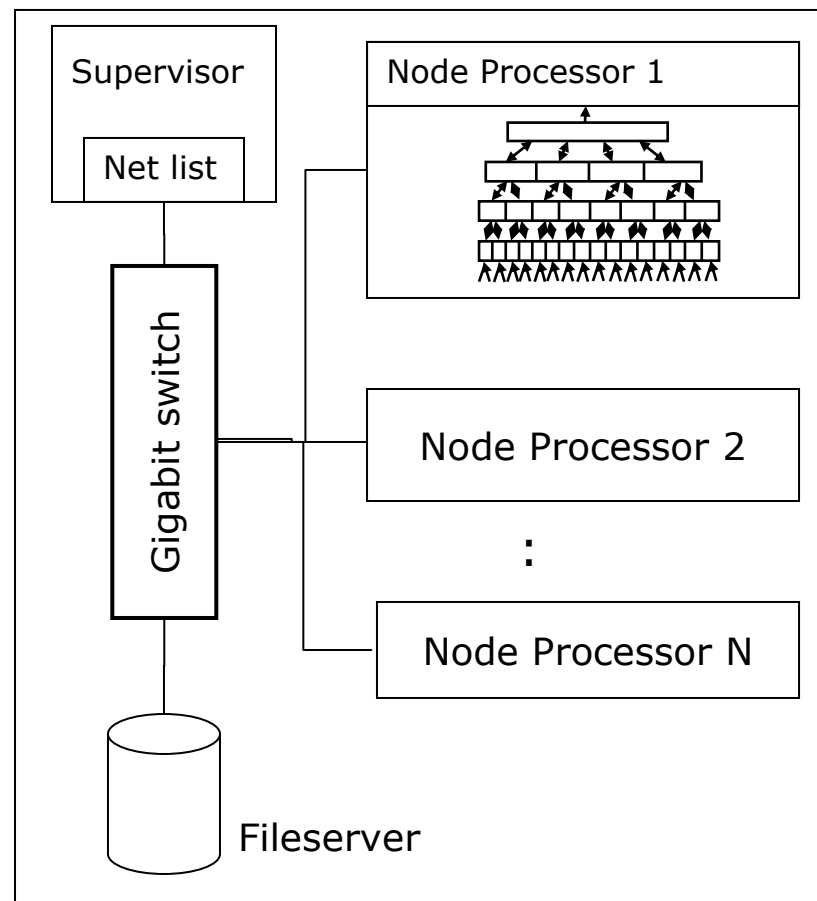
Click in box on the left to play video

# NuPIC, Numenta Platform for Intelligent Computing

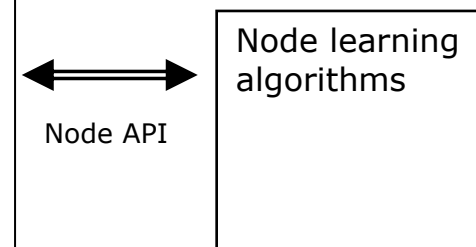
## 2) Dev Tools



## 1) Run time environment



## 3) Learning Algorithms



# HTM Applications Using NuPIC 07

- 100-200 developers, 8 NPP partners
- Gaming: Motion capture inference  
Visual object editor
- Auto: Lane change prediction
- Voice: Speaker and gender identification
- Vision: Visual object recognition
- Process Control: Power network analysis

# HTM Vision System Using NuPIC 08

- sample categories -



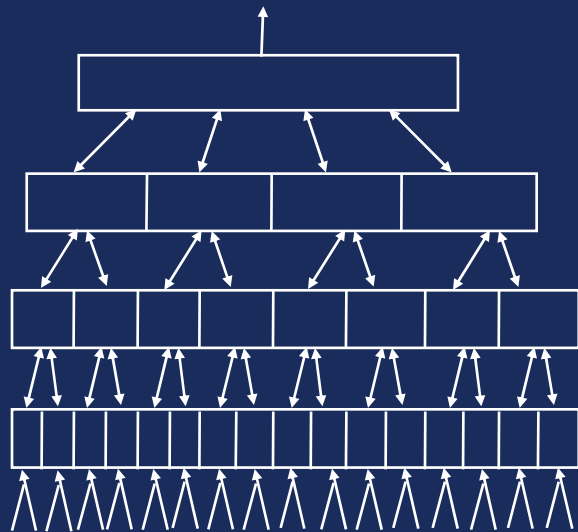


# HTM Vision System

- novel recognized images -



# Benefits of Hierarchical Memory



Sensory data

- Efficient (storage, training time)
- Self-learning
- Generalization
- Prediction / Behavior
- Matches hierarchical world

For additional multimedia material: See <http://www.isscc.org>

