MATH-458 Programming Concepts in Scientific Computing: Nonlinear Solvers

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1 Installation

```
This program requires C++11 minimum.

Step 1: Clone the repository.

$ git clone https://c4science.ch/diffusion/1726/pcsc-nonlinear-systems-project.git

Or

$ git clone ssh://git@c4science.ch/diffusion/1726/pcsc-nonlinear-systems-project.git

Step 2: Use CMAKE to prepare the source code for compilation.
```

```
$ cmake -DCMAKE_BUILD_TYPE= -G "CodeBlocks - Unix Makefiles"
```

Step 3: Compile the code

\$ make

2 List of Features

This program includes a family of Nonlinear solvers. Precisely, the following five methods are available: the Aitken Method, the Bisection Method, the Chord Method, and the Newton Method. Description of each algorithm in detail are present in Section 6.

After compiling the program via make, it can be run by typing,

\$./RunMain

into a terminal followed by command line options as described in Section 3.

We provide a few example files to demonstrate the formatting necessary to load systems of equations.

3 Usage

3.1 Command Line Flags

```
Scalar Usage:
./RunMain -m %s -e '%s' -d '%s' -xi %d -nmax %i -t %d -v %b -l %d -u %d -mod %i
System of Equations Usage:
./RunMain -f %s -j '%s' -xv '%s' -m %s -nmax %i -t %d -v %b -mod %i
Scalar Nonlinear Solver Requirement:
        -m,--method
                            Specify Non-Linear Solver
                            Mathematical expression to solve enclosed in ''
        -e,--expression
        -d,--derivative
                            The derivative to solve enclosed in '' [only for the Newton]
System of Equations Requirement:
        -f
                            File containing the system of equations
                            File containing the jacobian of the system of equations
        -j
        -f
                            File containing the initial vector
```

Optional:

```
-h,--help Show this help message
-xi Initial guess of the solution [default: 0.0]
```

```
Maximum number of iterations [default: 1000]
-nmax
-t
                    The convergence tolerance [default: 0.001]
                    print all intermediate calculations [default: false]
-v
-1
                    The lower bound of the search interval [default: -1.0]
                    The upper bound of the search interval [default: 1.0]
-11
                    The multiplicity of the root of the equation
-mod
```

Non-Linear Solvers:

aitken Aitken Method bisection Bisection Method Chord Method chord fixedpoint Fixed Point Method

Newton Method

newton

3.2Examples

Aitken Method:

```
./RunMain -m aitken -e '2x-5'
```

Fixed Point Method:

```
./RunMain -m fixedpoint -e 'cos(x)'
```

Bisection Method:

```
./RunMain -m bisection -e '2x-5' -l -5 -u 10
```

Newton Method with an equation and derivative:

```
./RunMain -m Newton -e 'x^2-5' -d '2x'
```

Newton Method for system of equations:

```
./RunMain -m Newton -f Equations.txt -j Jacobian.txt -xv initialVector.txt
```

4 **Tests**

The program will test all Algorithms, and sub-tools utilized to ensure correct results. The tests can be initiated by running them via:

\$./RunFunctionTests

TODO 5

- 1. Expand system of equations to the Secant method.
- 2. Expand system of equations to the Bisection method.
- 3. Expand system of equations beyond 3D.
- 4. Implement intelligent starting value(s) if not provided by user
- 5. Implement intelligent value variance to overcome zero derivative
- 6. Implement GUI interface for inputs

6 Algorithms

6.1 Bisection Method

The bisection method is based on Theorem 1.

```
Theorem 1. (Zeros of a continuous functions)
Given a continuous function f:[a,b] \to R, such that f(a)f(b) < 0, then \exists at least an \alpha \subset (a,b) such that f(\alpha) = 0.
```

Starting from $I_0 = [a,b]$, the bisection method generates a sequence of subintervals $I_k = [a(k),b(k)]$, $k \ge 0$, with $I_k \subset I_k 1$, $k \ge 1$, and enjoys the property that f(a(k))f(b(k)) < 0.

Algorithm 1 Bisection Method

```
1: k \leftarrow 0, a^{(0)} \leftarrow a, b^{(0)} \leftarrow b, x^{(0)} \leftarrow (a^{(0)} + b^{(0)})/2

2: while x^{(k)} - x^{(k-1)} > \text{tol and } k < k_{max} \text{ do}

3: if f(x^{(k-1)}) == 0 then return \alpha = x^{(k-1)}

4: else

5: if f(x^{(k-1)})f(a^{(k-1)}) < 0 then

6: set a^{(k)} = a^{(k-1)} and b^{(k)} = x^{(k-1)}

7: if f(x^{(k-1)})f(b^{(k-1)}) < 0 then

8: set a^{(k)} = x^{(k-1)} and b^{(k)} = b^{(k-1)}

9: set x^{(k)} = (a^{(k)} + b^{(k)})/2

10: return \alpha = x^{(k)}
```

6.2 Newton/Quasi-Newton Methods

Assuming that $f \subset C^0(I)$ and is differentiable in the interval $I = (a,b) \subseteq R$, the equation of a tangenet line to the curve (x, f(x)) at coordinate $x^{(k)}$, where $x^{(k)} \subset I$, is $y(x) = f(x^{(k)}) + df(x^{(k)})(x - x^{(k)})$. If we assume $y(x^{(k)}) = 0$, $x^{(k+1)}$ can be computed from Eq. 1.

$$x^{(k+1)} = x^{(k)} - \frac{f(x^{(k)})}{g^{(k)}} \tag{1}$$

with $q^{(k)}$ determining the method as Newton (Eq. 2) or Chord (Eq. 3):

$$q^{(k)} = \frac{df(x^{(k)})}{dx} \tag{2}$$

$$q^{(k)} = \frac{f(x^{(k)}) - f(x^{(k-1)})}{x^{(k)} - x^{(k-1)}}$$
(3)

Algorithm 2 General quasi-Newton Method

```
1: k \leftarrow 0, set initial guess x^{(0)}

2: while x^{(k)} - x^{(k-1)} > \text{tol and } k < k_{max} do

3: x^{(k+1)} = x^{(k)} - \frac{f(x^{(k)})}{(q^{(k)})}

4: k = k + 1;

5: return \alpha = x^{(k)}
```

6.3 Fixed Point Iteration

For a given $f: [a,b] \to R$, the problem can be transformed from f(x) = 0 into an equivalent problem $x - \phi(x) = 0$. The auxiliary function $\phi: [a,b] \to R$ has to chosen in such a way that $\phi(\alpha) = \alpha$ whenever $f(\alpha) = 0$. Finding the fixed points of the mapping ϕ thus results in finding the roots of the original equation f(x), hence the name fixed point iteration.

Algorithm 3 Fixed point iterations

```
1: k \leftarrow 0, set initial guess x^{(0)}

2: while x^{(k)} - x^{(k-1)} > tol and k < k_{max} do

3: x^{(k+1)} = \phi(x^{(k)})

4: k = k + 1;

5: return \alpha = x^{(k)}
```

6.4 Aitken Method

Aitkens method provides a way to accelerate the convergence of iterative methods for finding the roots of a function. The general algorithm is shown below.

Algorithm 4 Aitken Method

```
1: k \leftarrow 0, set initial guess x^{(0)}

2: Calculate x^{(1)} using any iterative method.

3: while x^{(k)} - x^{(k-1)} > \text{tol and } k < k_{max} \mathbf{do}

4: Calculate x^{(k+2)}.

5: Modify x^{(k+2)} using x^{(k+2)} = x^{(k)} - \frac{(x^{(k+1)} - x^{(k)})^2}{(x^{(k)} - 2*x^{(k+1)} + x^{(k+2)})}

6: k = k + 1;

7: return \alpha = x^{(k)}
```