Lecture 10

# Binary Search Trees I

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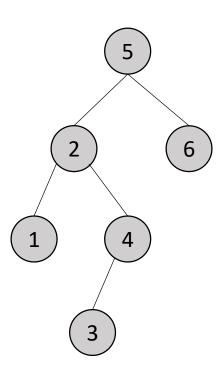
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# Binary Search Tree

- Trees are generally used for index & search.
  - Values in the left subtree are smaller than the root.
  - Values in the right subtree are greater than the root.
- Three new functions to effectively design the tree are needed: insert, remove, search.

```
typedef struct Node {
    int data;
    struct Node* left;
    struct Node* right;
} Node;

Node* createNode(int data) {
    Node* newNode = (Node*)malloc(sizeof(Node));
    if (!newNode) {
        printf("Memory allocation failed\n");
        exit(1);
    }
    newNode->data = data;
    newNode->left = NULL;
    newNode->right = NULL;
    return newNode;
}
```



#### **BST** Insert

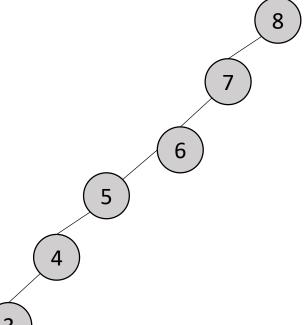
```
Node* insert(Node* node, int data) {
    if (node == NULL) {
        return createNode(data);
    }
    if (data < node->data) {
            node->left = insert(node->left, data);
        } else if (data > node->data) {
                node->right = insert(node->right, data);
        }
        return node;
}
```

- The shape of the tree will change according to the insertion order.
  - No balancing!

```
Node* root = NULL;

root = insert(root, 8);
root = insert(root, 7);
root = insert(root, 6);
root = insert(root, 5);
root = insert(root, 4);
root = insert(root, 3);
root = insert(root, 2);
root = insert(root, 1);
```

Inorder traversal: 1 2 3 4 5 6 7 8
Preorder traversal: 8 7 6 5 4 3 2 1
Postorder traversal: 1 2 3 4 5 6 7 8



(1)

#### **BST** Insert

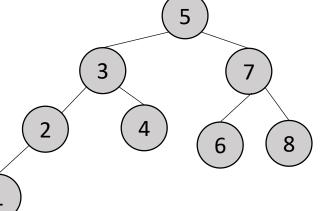
```
Node* insert(Node* node, int data) {
    if (node == NULL) {
        return createNode(data);
    }
    if (data < node->data) {
        node->left = insert(node->left, data);
    } else if (data > node->data) {
        node->right = insert(node->right, data);
    }
    return node;
}
```

- The shape of the tree will change according to the insertion order.
  - No balancing!

```
Node* root = NULL;

root = insert(root, 5);
root = insert(root, 3);
root = insert(root, 7);
root = insert(root, 2);
root = insert(root, 4);
root = insert(root, 1);
root = insert(root, 6);
root = insert(root, 8);
```

Inorder traversal: 1 2 3 4 5 6 7 8
Preorder traversal: 5 3 2 1 4 7 6 8
Postorder traversal: 1 2 4 3 6 8 7 5

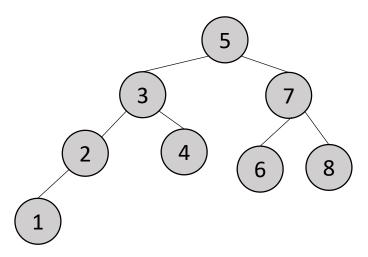


#### **BST Search**

```
bool search(Node* node, int key) {
   if (node == NULL) {
       return false;
   printf("Current Node: %d\n", node->data);
   if (node->data == key) {
       return true;
   if (key < node->data) {
       return search(node->left, key);
   return search(node->right, key);
```

```
Current Node: 5
Current Node: 3
Current Node: 4
Found value 4
```

- Search function performs a breadth-first search (BFS) using a queue to find a node with the specified key.
- Example: How to find «4»?

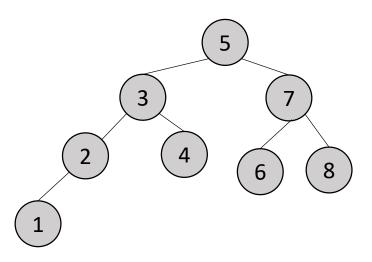


#### BST Maximum & Minimum

```
Node* minValueNode(Node* node) {
   Node* current = node;
   while (current && current->left != NULL) {
      current = current->left;
   }
   return current;
}
```

```
Node* maxValueNode(Node* node) {
   Node* current = node;
   while (current && current->right != NULL) {
        current = current->right;
   }
   return current;
}
```

Checking right/left branches is a valid strategy to find maximum/minimum.



```
printf("Minimum value in the tree: %d\n", minValueNode(root)->data);
printf("Maximum value in the tree: %d\n", maxValueNode(root)->data);
```

Minimum value in the tree: 1
Maximum value in the tree: 8

#### How to find the median?

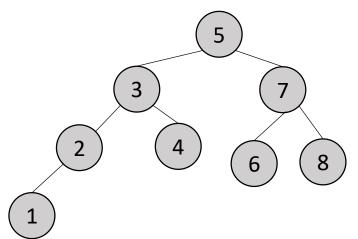
• We need to find the element count N, and then the  $\left(\frac{N}{2}+1\right)^{th}$  element.

```
int countNodes(Node* root) {
   if (root == NULL) {
      return 0;
   }
   return 1 + countNodes(root->left) + countNodes(root->right);
}
```

```
void findNthNode(Node* root, int* currentCount, int n, int* result) {
    if (root == NULL) {
        return;
    }

    findNthNode(root->left, currentCount, n, result);

    (*currentCount)++;
    if (*currentCount == n) {
        *result = root->data;
        return;
    }
    findNthNode(root->right, currentCount, n, result);
}
```

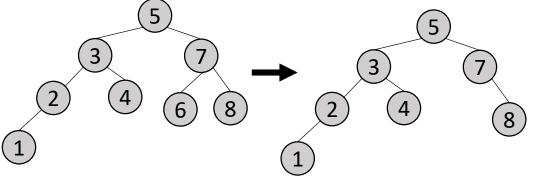


```
float findMedian(Node* root) {
   if (root == NULL) {
       return 0.0;
   int totalNodes = countNodes(root);
   if (totalNodes % 2 == 1) {
       int medianValue = 0;
       int currentCount = 0;
       findNthNode(root, &currentCount, (totalNodes / 2) + 1, &medianValue);
       return (float)medianValue;
    } else {
       int leftMiddleValue = 0, rightMiddleValue = 0;
       int currentCount = 0;
       findNthNode(root, &currentCount, totalNodes / 2, &leftMiddleValue);
       currentCount = 0;
       findNthNode(root, &currentCount, (totalNodes / 2) + 1, &rightMiddleValue);
       return (leftMiddleValue + rightMiddleValue) / 2.0;
```

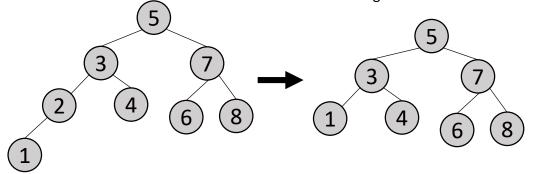
#### **BST** Remove

```
Node* removeNode(Node* root, int key) {
    if (root == NULL) {
       return root;
    if (key < root->data) {
       root->left = removeNode(root->left, key);
    } else if (key > root->data) {
       root->right = removeNode(root->right, key);
    } else {
       if (root->left == NULL) {
           Node* temp = root->right;
            free(root);
           return temp;
         else if (root->right == NULL) {
           Node* temp = root->left;
           free(root);
           return temp;
       Node* temp = minValueNode(root->right);
       root->data = temp->data;
       root->right = removeNode(root->right, temp->data);
   return root;
```

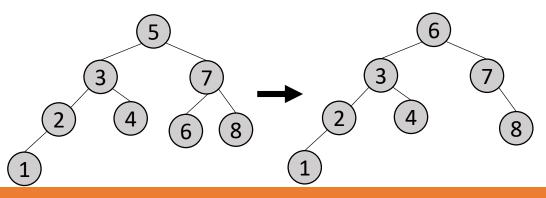
- There are three cases to remove a node from a binary search tree.
  - Leaf Node: The node to be removed has no children.



• One Child: The node to be removed has either a left or a right child.



• Two Children: The node to be removed has both a left and a right child.



# Big-O Time Complexities of the Functions

- createNode
- insert
- search
- maximum/minimum
- countnodes
- findNthNode
- findMedian
- removeNode

## Big-O Time Complexities of the Functions

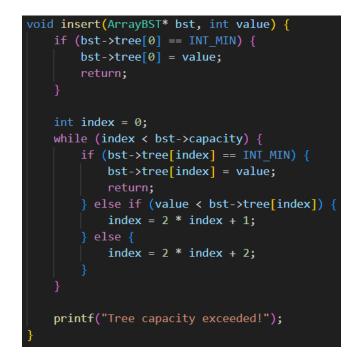
- createNode: O(1)
- insert: O(logn) for best case, O(n) for worst case
- search: O(logn) for best case, O(n) for worst case
- maximum/minimum: O(logn) for best case, O(n) for worst case
- countnodes: O(n)
- findNthNode: O(n)
- findMedian: O(n)
- removeNode: O(logn) for best case, O(n) for worst case

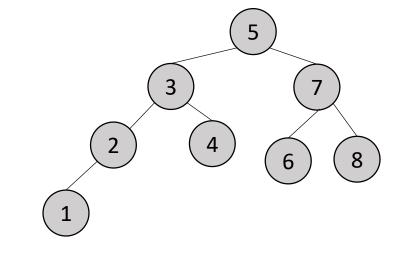
### A Vector-Based Structure for Binary Trees

- Another method to represent a binary tree T, involves assigning numbers to its nodes.
  - For each node v in T, we define an integer f(v).
  - If v is the root of T, then f (v) = 0
  - If v is the left child of node u, then f(v) = 2 f(u) + 1.
  - If v is the right child of node u, then f(v) = 2 f(u) + 2

```
typedef struct {
    int* tree;
    int capacity;
} ArrayBST;
```

```
void create(ArrayBST* bst, int capacity) {
   bst->capacity = capacity;
   bst->tree = (int*)malloc(capacity * sizeof(int));
   if (bst->tree == NULL) {
      printf("Memory allocation failed.\n");
      exit(1);
   }
   for (int i = 0; i < capacity; i++) {
      bst->tree[i] = INT_MIN;
   }
}
```



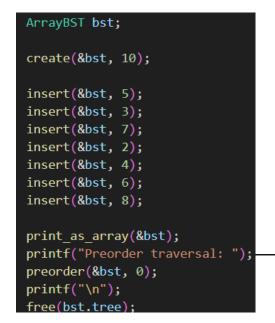


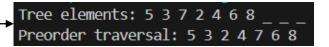
0	1	2	3	4	5	6	7
5	3	7	2	4	6	8	1

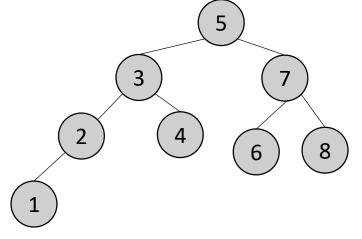
### A Vector-Based Structure for Binary Trees

```
void print_as_array(ArrayBST* bst) {
    printf("Tree elements: ");
    for (int i = 0; i < bst->capacity; i++) {
        if (bst->tree[i] == INT_MIN) {
            printf("_ ");
        } else {
            printf("%d ", bst->tree[i]);
        }
    }
    printf("\n");
}
```

```
void preorder(ArrayBST* bst, int index) {
   if (index >= bst->capacity || bst->tree[index] == INT_MIN) {
      return;
   }
   printf("%d ", bst->tree[index]);
   preorder(bst, 2 * index + 1);
   preorder(bst, 2 * index + 2);
}
```







0	1	2	3	4	5	6	7
5	3	7	2	4	6	8	1