Hongje Seong

Contact

C607 The 3rd Eng. building, Yonsei university, 50 Yonsei-ro, Seodaemun-Gu, Seoul, 120-749, Korea

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Languages

Korean, English

Interests

Computer vision, scene recognition, video object segmentation, and video matting

Education

03/18 - Present **Ph.D. student** School of Electrical & Electronic Engineering

Advisor: Prof. Euntai Kim

03/12 - 02/18 **B.S.** School of Electrical & Electronic Engineering

Yonsei University

Yonsei University

Experience

03/21 - 12/21 . **Adobe Research**

San Jose, CA, USA (remote)

Research Intern

Mentors: Joon-Young Lee, Seoung Wug Oh, and Brian Price

03/18 - Present **Yonsei University**

Seoul, Korea

Research Assistant @ CILAB
Participation in several research projects

03/18 - 12/18 Yonsei University

Seoul. Korea

Yonsei University *Teaching Assistant*

• Data Structure and Algorithms

• Introduction Artificial Intelligence

Publications

Journal

Indoor Place Category Recognition for a Cleaning Robot by Fusing a Probabilistic Approach and Deep Learning

Soowook Choe*, Hongje Seong*, and Euntai Kim (*equal contribution)

IEEE Transactions on Cybernetics (TCYB), 2021. (Accepted)

Universal Pooling - A New Pooling Method for Convolutional Neural Networks Junhyuk Hyun, Hongje Seong, and Euntai Kim

Expert Systems With Applications (ESWA), vol. 180, pp. 115084, October, 2021.

FOSNet: An End-to-End Trainable Deep Neural Network for Scene Recognition Hongje Seong, Junhyuk Hyun, and Euntai Kim

IEEE Access, vol. 8, pp. 82066-82077, December, 2020.

Conference

Iteratively Selecting an Easy Reference Frame Makes Unsupervised Video Object Segmentation Easier

Youngjo Lee, Hongje Seong, and Euntai Kim

AAAI Conference on Artificial Intelligence (AAAI), February, 2022.

Graph-Based Point Tracker for 3D Object Tracking in Point Clouds

Minseong Park, Hongje Seong, Wonje Jang, and Euntai Kim

AAAI Conference on Artificial Intelligence (AAAI), February, 2022.

Hierarchical Memory Matching Network for Video Object Segmentation

Hongje Seong, Seoung Wug Oh, Joon-Young Lee, Seongwon Lee, Suhyeon Lee, and Euntai Kim

IEEE/CVF International Conference on Computer Vision (ICCV), October, 2021.

Unsupervised Domain Adaptation for Semantic Segmentation by Content Transfer

Suhyeon Lee, Junhyuk Hyun, Hongje Seong, and Euntai Kim

AAAI Conference on Artificial Intelligence (AAAI), February, 2021.

Kernelized Memory Network for Video Object Segmentation

Hongje Seong, Junhyuk Hyun, and Euntai Kim

European Conference on Computer Vision (ECCV), August, 2020.

A Kernel-based Approach for Video Object Segmentation

Hongje Seong, Junhyuk Hyun, and Euntai Kim

IEEE/CVF Conference on Computer Vision and Pattern Recognition Workshops (*CVPRW, DAVIS'20*), June, 2020.

Video Multitask Transformer Network

Hongje Seong, Junhyuk Hyun, and Euntai Kim

IEEE/CVF International Conference on Computer Vision Workshops (*ICCVW, CoVieW'19*), October, 2019.

Scene Recognition via Object-to-Scene Class Conversion: End-to-End Training

Hongje Seong, Junhyuk Hyun, Hyunbae Chang, Suhyeon Lee, Suhan Woo, and Euntai Kim

International Joint Conference on Neural Networks (IJCNN), July, 2019.

Improving Nighttime Object Detection by Generating Synthetic Nighttime Dataset from Daytime Dataset

Youngjo Lee, Suhyeon Lee, Hongje Seong, and Euntai Kim

International Conference on Control, Automation and Systems (ICCAS), October, 2021.

Loop Closure Detection in Crowded Place

Seongwon Lee, HyungGi Jo, Hongje Seong, and Euntai Kim

IEEE Region 10 Symposium (TENSYMP), August, 2021.

Metric Learning in Mini-batch for Robust 6-DoF Camera Relocalization in Outdoor Environments Gyuhyeon Pak, Hongje Seong, and Euntai Kim

International Conference on Ubiquitous Robots (UR), June, 2021.

The Effective Method for 3D LiDAR Point Clouds Processing

Youngjoo Kim, Hongje Seong, Wonje Jang, and Euntai Kim

International Conference on Ubiquitous Robots (UR), June, 2021.

Is Whole Object Information Helpful for Scene Recognition?

Hongje Seong, Junhyuk Hyun, and Euntai Kim

International Conference on Ubiquitous Robots (UR), June, 2020.

Partial Convolution for Scene Recognition

Hongje Seong, Junhyuk Hyun, Seongwon Lee, and Euntai Kim

International Conference on Control, Automation and Systems (ICCAS), October, 2019.

Weakly Supervised Temporal Localization in Video Scene Recognition

Junhyuk Hyun, Hongje Seong, Suhyeon Lee, Suhan Woo, and Euntai Kim

International Conference on Control, Automation and Systems (ICCAS), October, 2018.

New Feature-level Video Classification via Temporal Attention Model

Hongje Seong, Junhyuk Hyun, Suhyeon Lee, Suhan Woo, Hyunbae Chang, and Euntai Kim

The 1st Workshop and Challenge on Comprehensive Video Understanding in the Wild (ACM MM Workshop, CoVieW'18), October, 2018.

Awards

2020	3rd Place Award The 2020 DAVIS Challenge on Vio	DAVIS'20 (CVPR Workshop) deo Object Segmentation (DAVIS 2020)
2019	Best Poster Award 3rd Place Workshop on Frontiers of Electric	School of Electrical & Electronic Engineering, Yonsei University cal Engineering (FREE) 2019
2018	2nd Place Award The 1st Workshop and Challenge (CoVieW 2018)	CoVieW'18 (ACM MM Workshop) on Comprehensive Video Understanding in the Wild
2017	4th Place Award Autonomous Car Racing in 2017	Korea Transportation Safety Authority (TS) & Korea Auto-Vehicle Safety Association (KASA) International Student Car Competition

Patents

Apparatus and method for domain adaptation using zero style loss Euntai Kim, Suhyeon Lee, Junhyuk Hyun, and Hongje Seong

Korea - Application No. 10-2021-0003078

Apparatus and method for solving class imbalance problem of domain adaptation using content transfer

Euntai Kim, Suhyeon Lee, Hongje Seong, and Junhyuk Hyun

Korea - Application No. 10-2021-0003077

Apparatus for predicting traffic line of box-level multiple object using only position information of box-level multiple object

Euntai Kim, Youngjo Lee, Hongje Seong, and Junhyuk Hyun

Korea - Application No. 10-2020-0149533

Apparatus for predicting movement of box-level object using only position information of box-level object

Euntai Kim, Youngjo Lee, Hongje Seong, and Junhyuk Hyun

Korea - Application No. 10-2020-0149532

Pixel Level Video Object Tracking Apparatus Using Box Level Object Position Information Euntai Kim, Hongje Seong, Youngjo Lee, and Junhyuk Hyun

Korea - Application No. 10-2020-0030214

International (PCT) - Application No. PCT/KR2020/005383

Action Recognition Method and Apparatus in Untrimmed Videos Based on Artificial Neural Network Euntai Kim, Hongje Seong, and Junhyuk Hyun

Korea - Application No. 10-2020-0029743

Apparatus for Recognizing a Place based on Artificial Neural Network and Learning Method thereof Euntai Kim, Hongje Seong, Junhyuk Hyun, Suhyeon Lee, Suhan Woo, and Hyunbae Chang

Korea - Application No. 10-2019-0041544

Korea - Registration No. 10-2211842

International (PCT) - Application No. PCT/KR2020/001018

Apparatus and Method for Detecting Object based on Heterogeneous Sensor

Euntai Kim, Junhyuk Hyun, Suhyeon Lee, Suhan Woo, and Hongje Seong

Korea - Application No. 10-2018-0055179

Korea - Registration No. 10-2138681

Method and Apparatus for Generating Scene Situation Information of Video Using Differentiation of Image Feature and Supervised Learning

Euntai Kim, Junhyuk Hyun, Suhyeon Lee, Suhan Woo, and Hongje Seong

Korea - Application No. 10-2018-0049520

Korea - Registration No. 10-2120453



(09/17-12/20) Research on Fundamental Technology for Deep Learning-Based Semantic State Understanding

National Research Foundation of Korea (NRF)

(09/17-05/19) Development of part-based pedestrian detection and tracking system for autonomous vehicle

National Research Foundation of Korea (NRF)

Activities

Reviewer

Elsevier Pattern Recognition Elsevier Knowledge-Based Systems Elsevier Applied Soft Computing

Last updated: 1st December 2021