Hongje Seong

Contact

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The 3rd Eng. building,
Yonsei university,
50 Yonsei-ro,
Seodaemun-Gu,
Seoul, 120-749, Korea

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Languages

Korean, English

Interests

Computer vision and machine learning

Education

03/18 - Present	**Ph.D. student** School of Electrical & Electronic Engineering *Advisor: Prof. Euntai Kim*	Yonsei University
03/12 - 02/18	**B.S.** School of Electrical & Electronic Engineering	Yonsei University

Experience

03/18 - Present	**Yonsei University** *Research Assistant* @ CILAB Participation in several research projects	Seoul, Korea
03/18 - 12/18	**Yonsei University** *Teaching Assistant* • Data Structure and Algorithms • Introduction Artificial Intelligence	Seoul, Korea

Publications

Journal

Indoor Place Category Recognition for a Cleaning Robot by Fusing a Probabilistic Approach and Deep Learning
Soowook Choe*, Hongje Seong*, and Euntai Kim
IEEE Transactions on Cybernetics, 2021. (Accepted)

FOSNet: An End-to-End Trainable Deep Neural Network for Scene Recognition
Hongje Seong, Junhyuk Hyun and Euntai Kim
IEEE Access, vol. 8, no. 1, pp. 82066-82077, December, 2020.

Conference

Unsupervised Domain Adaptation for Semantic Segmentation by Content Transfer
Suhyeon Lee, Junhyuk Hyun, Hongje Seong, and Euntai Kim
in Proc. of the Thirty-Fifth AAAI Conference on Artificial Intelligence (*AAAI*), February, 2021.

Kernelized Memory Network for Video Object Segmentation
Hongje Seong, Junhyuk Hyun, and Euntai Kim
in Proc. of the European Conference on Computer Vision (*ECCV*), August, 2020.

Is Whole Object Information Helpful for Scene Recognition?
Hongje Seong, Junhyuk Hyun, and Euntai Kim
in Proc. of the 17th International Conference on Ubiquitous Robots (*UR*), June, 2020.

A Kernel-based Approach for Video Object Segmentation
Hongje Seong, Junhyuk Hyun, and Euntai Kim
in The 2020 DAVIS Challenge on Video Object Segmentation (*DAVIS'20, CVPRW*), June, 2020.

Video Multitask Transformer Network
Hongje Seong, Junhyuk Hyun and Euntai Kim
in Proc. of the IEEE International Conference on Computer Vision Workshops (*CoVieW'19, ICCVW*), October, 2019.

Partial Convolution for Scene Recognition
Hongje Seong, Junhyuk Hyun, Seongwon Lee and Euntai Kim
in Proc. of the 19th International Conference on Control, Automation and Systems (*ICCAS*), October, 2019.

Scene Recognition via Object-to-Scene Class Conversion: End-to-End Training
Hongje Seong, Junhyuk Hyun, Hyunbae Chang, Suhyeon Lee, Suhan Woo and Euntai Kim
in Proc. of the International Joint Conference on Neural Networks (*IJCNN*), July, 2019.

Weakly Supervised Temporal Localization in Video Scene Recognition
Junhyuk Hyun, Hongje Seong, Suhyeon Lee, Suhan Woo and Euntai Kim
in Proc. of the 18th International Conference on Control, Automation and Systems (*ICCAS*), October, 2018.

New Feature-level Video Classification via Temporal Attention Model
Hongje Seong, Junhyuk Hyun, Suhyeon Lee, Suhan Woo, Hyunbae Chang and Euntai Kim
in Proc. of the 1st Workshop and Challenge on Comprehensive Video Understanding in the Wild (*CoVieW'18, ACM MM Workshop*), October, 2018.

Awards

2020	**3rd Place Award**	DAVIS'20 (CVPR Workshop)
	The 2020 DAVIS Challenge on Video Object Segmentation (DAVIS 2020)	
2019	**Best Poster Award 3rd Place**	School of Electrical & Electronic Engineering, Yonsei University
	Workshop on Frontiers of Electrical Engineering (FREE) 2019	
2018	**2nd Place Award**	CoVieW'18 (ACM MM Workshop)
	The 1st Workshop and Challenge on Comprehensive Video Understanding in the Wild (CoVieW 2018)	
2017	**4th Place Award**	Korea Transportation Safety Authority (TS) & Korea Auto-Vehicle Safety Association (KASA)
	Autonomous Car Racing in 2017 International Student Car Competition	

Patents

Apparatus for predicting traffic line of box-level multiple object using only position information of box-level multiple object
Euntai Kim, Youngjo Lee, Hongje Seong and Junhyuk Hyun
Korea - Application No. 10-2020-0149533

Apparatus for predicting movement of box-level object using only position information of box-level object
Euntai Kim, Youngjo Lee, Hongje Seong and Junhyuk Hyun
Korea - Application No. 10-2020-0149532

Pixel Level Video Object Tracking Apparatus Using Box Level Object Position Information
Euntai Kim, Hongje Seong, Youngjo Lee and Junhyuk Hyun
Korea - Application No. 10-2020-0030214
International (PCT) - Application No. PCT/KR2020/005383

Action Recognition Method and Apparatus in Untrimmed Videos Based on Artificial Neural Network
Euntai Kim, Hongje Seong and Junhyuk Hyun
Korea - Application No. 10-2020-0029743

Apparatus for Recognizing a Place based on Artificial Neural Network and Learning Method thereof
Euntai Kim, Hongje Seong, Junhyuk Hyun, Suhyeon Lee, Suhan Woo and Hyunbae Chang
Korea - Application No. 10-2019-0041544
International (PCT) - Application No. PCT/KR2020/001018

Apparatus and Method for Detecting Object based on Heterogeneous Sensor
Euntai Kim, Junhyuk Hyun, Suhyeon Lee, Suhan Woo and Hongje Seong
Korea - Application No. 10-2018-0055179
Korea - Registration No. 10-2138681

Method and Apparatus for Generating Scene Situation Information of Video Using Differentiation
of Image Feature and Supervised Learning
Euntai Kim, Junhyuk Hyun, Suhyeon Lee, Suhan Woo and Hongje Seong
Korea - Application No. 10-2018-0049520
Korea - Registration No. 10-2120453

Projects

(09/17-12/20) Research on Fundamental Technology for Deep Learning-Based Semantic State Understanding
National Research Foundation of Korea (NRF)

(09/17-05/19) Development of part-based pedestrian detection and tracking system for autonomous vehicle
National Research Foundation of Korea (NRF)

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