

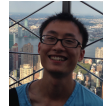
## Lecture 3: Introduction to MIPS

(CPEG323: Intro. to Computer System Engineering)

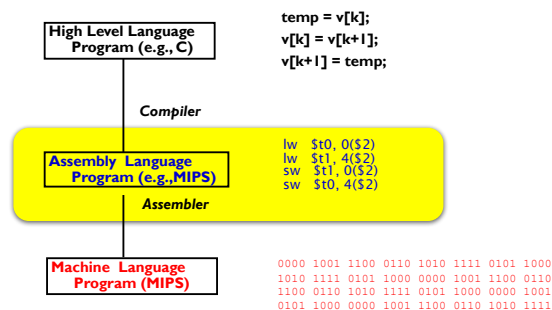
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## Announcement

- MP1 out
- Lecture plans for the next two weeks
  - September 10 to 14: number representation
    - By TA Fateme
  - September 17 to 19: c programming (bit wise operation)
    - By TA Kuang
- September 21: MIPS (cont.)



## Levels of Program Code



## Assembly Language

- A language that computers can understand
- **Instructions**
  - CPU's primitives operations
  - E.g., words that a computer can understand
- **Instruction Set Architecture**
  - Vocabulary that a computer can understand
  - E.g., MIPS, ARM, Intel x86, RISC-V, ...
- CPU belong to families based on the ISAs.
  - E.g., iPhone's is different from the Mac's, but same as the iPad's.

## Instruction set architectures



- The ISA is an interface between software and hardware
  - the hardware “promises” to implement all ISA instructions
  - the software uses ISA primitives to build complex programs
- The instruction set architecture affects the hardware design
  - simple ISAs require simpler, cheaper processors
- Also affects software design
  - simple ISAs result in longer programs

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## History of ISA

- Early trend was to add more and more instructions to new CPUs to do elaborate operations.
  - e.g., VAX architecture had an instruction to multiply polynomials
- RISC (Reduced Instruction Set Computing) design principle:
  - Keep the instruction set small and simple, make it easier to build fast hardware
  - Let software do complicated operations by composing simpler ones.

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## RISC Design Principles

- A number of the more common strategies include:
  - Fixed instruction length, generally a single word;
  - Simplified addressing modes;
  - Fewer and simpler instructions in the instruction set;
  - Only load and store instructions access memory;
  - Let the compiler do it.

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## MIPS - Instruction Set in CPEG323

- MIPS: semiconductor company that built one of the first commercial RISC architecture (1984-2013).
- Advantages:
  - An elegant example of *RISC* architectures.
  - Real, yet simple.
  - Still used in many places, primarily in embedded systems such as routers and game devices.

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## What you will need to learn for Exams

- You must become “fluent” in MIPS assembly:
  - Translate from C to MIPS and MIPS to C
- Example: Translate the following recursive C function into MIPS  

```
int pow(int n, int m) {  
    if (m == 1)  
        return n;  
    return n * pow(n, m-1);  
}
```

**How are arguments passed?**

**How are values returned?**

**How are complex expressions broken into simple instructions?**

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## Registers – Assembly Variables

- High-Level Programming languages
  - variables (the number could vary, and be very large)
- Assembly languages
  - registers (fixed, smaller number)
- MIPS Instruction Set has 32 registers, each of which holds a 32-bit value.
  - Benefit:
    - Fast (because they are directly in hardware)
  - Drawback:
    - Need to be careful with the efficient use of registers (because of the limited number)

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## MIPS register names

- MIPS register names begin with a **\$**. There are two naming conventions:
  - by number: **\$0 \$1 \$2 ... \$31**
  - by (mostly) two-character names, such as:  
**\$a0-\$a3 \$s0-\$s7 \$t0-\$t9 \$sp \$ra**
- Not all of the registers are equivalent:
  - e.g., register \$0 or \$zero always contains the value 0
  - some have special uses, by convention (\$sp holds “stack pointer”)
- You have to be a little careful in picking registers for your programs
  - for now, stick to the registers \$t0-\$t9

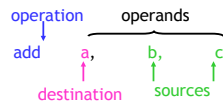
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## MIPS Arithmetic Operations

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## MIPS: register-to-register, three address

- MIPS is a **register-to-register**, or **load/store**, architecture
  - Destination and sources of instructions must all be registers
- MIPS uses **three-address** instructions for data manipulation
  - Each ALU instruction contains a **destination** and two **sources**.
  - For example, an addition instruction ( $a = b + c$ ) has the form:



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## Basic arithmetic and logic operations

- The basic integer arithmetic operations include the following:

add    sub    mul    div

- And here are a few bitwise operations:

and    or    xor    nor

- Remember that these all require three register operands; for example:

```
add $t0, $t1, $t2    # $t0 = $t1 + $t2
mul $s1, $s1, $a0    # $s1 = $s1 x $a0
```

Note: a full MIPS ISA reference can be found in Appendix A (linked from website)

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## Larger expressions

- Complex arithmetic expressions may require multiple MIPS operations
- Example:  $t0 = (t1 + t2) \times (t3 - t4)$

```
add $t0, $t1, $t2      # $t0 contains $t1 + $t2
sub $t6, $t3, $t4      # temp value $t6 = $t3 - $t4
mul $t0, $t0, $t6      # $t0 contains the final product
```

- Temporary registers may be necessary, since each MIPS instructions can access only two source registers and one destination
  - in this example, we could re-use \$t3 instead of introducing \$t6
  - must be careful not to modify registers that are needed again later

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## How are registers initialized?

- Special MIPS instructions allow you to specify a signed constant, or “immediate” value, for the second source instead of a register
  - e.g., here is the immediate add instruction, **addi**:

```
addi $t0, $t1, 4      # $t0 = $t1 + 4
```

- Immediate operands can be used in conjunction with the **\$zero** register to write constants into registers:

```
addi $t0, $0, 4      # $t0 = 4
```

Shorthand: **li**  $\rightarrow$  **\$t0, 4**      # \$t0 = 4  
(pseudo-instruction)

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## Our first MIPS program

- Let's translate the following C++ program into MIPS:

```
void main() {
    int i = 516;
    int j = i*(i+1)/2;
    i = i + j;
}

main:                      # start of main
    li    $t0, 516        # i = 516
    addi $t1, $t0, 1      # i + 1
    mul $t1, $t0, $t1     # i * (i + 1)
    li    $t2, 2
    div $t1, $t1, $t2     # j = i*(i+1)/2
    add $t0, $t0, $t1     # i = i + j

    jr    $ra            # return
```

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## Data Transfer

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## What if we need more space?

- Data can be stored in the memory and then transferred to/from the registers.

### • Data transfer instructions:

- Memory to register: lw, lb
- Register to memory: sw, sb

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## How to Specify Source and Destination?

### • Register:

- specified by the numbers or the names

### • Memory address:

- Memory can be seen as a single one-dimensional array.
- MIPS memory is byte-addressable: each memory address references an 8-bit quantity.

Address	0	1	2	3	4	5	6	7	8	9	10	...
8-bit data												

- A memory address can be specified as the sum of the following two values:

- A register containing a pointer to memory
- A numerical offset (in bytes)
- For example, 8(\$t0) specifies the memory address pointed to by the value in \$t0 plus 8 bytes.

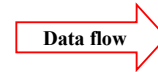
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## Transfer from Memory to Register



- MIPS instructions: **lw** and **lb** (load word or load byte)
- Example: **lw \$t0,12(\$s0)**
  - It computes the memory address by summing up the value in \$s0 and 12, reads the value from the computed memory address, and stores the value into register \$t0

## Transfer from Register to Memory



- MIPS instruction: **sw** and **sb** (store word and store byte)
- Example: **sw \$t0,12(\$s0)**
  - It read the value from register \$t0 and then store in memory. The memory address is computed by adding the values in \$t0 and 12.

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## Example MIPS code using data transfer

```
.data
from: .byte 1
to: .byte 0

.text
main:
    la    $t0, from
    lb    $t1, 0($t0)
    la    $t0, to
    sb    $t1, 0($t0)
```

```
char from = 1, to = 0;

void main() {
    to = from;
}
```

## Another Example

- Assume A is an array of 100 words, variables g and h map to registers \$s1 and \$s2, the starting address, or base address, of the array A is in \$s3
  - $A[10] = h + A[3];$
- Turns into
  - lw \$t0,12(\$s3) # Temp reg \$t0 gets A[3]
  - add \$t0,\$s2,\$t0 # t0 = h + A[3]
  - sw \$t0,40(\$s3) # A[10] = h + A[3]

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