

## MEEG 311 – Lecture 23 Vibration and Control

## Ioannis Poulakakis 15 November 2018

## Goals:

- Introduction to frequency response:
  - System: Linear, time invariant, stable
  - Input: Sinusoidal function at frequency omega
  - Output: Sinusoidal function at frequency omega (same as the input), with amplitude and phase different from that of the input
- The magnitude and phase of the output is computed by the magnitude and phase of the transfer function with the substitution s= j omega
- Bode diagrams: Magnitude (definition of dB) and phase plots

