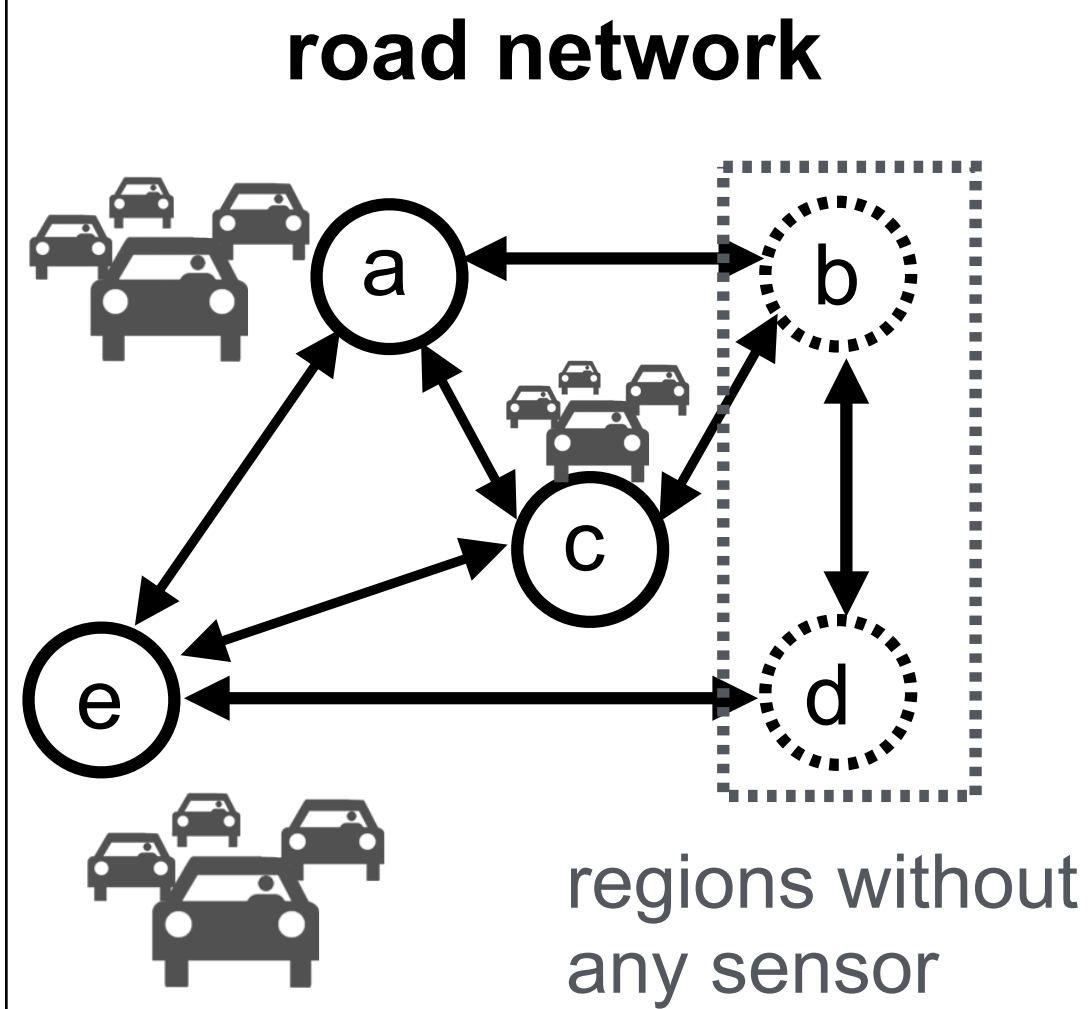


1. Traffic Prediction with Partially Observed History



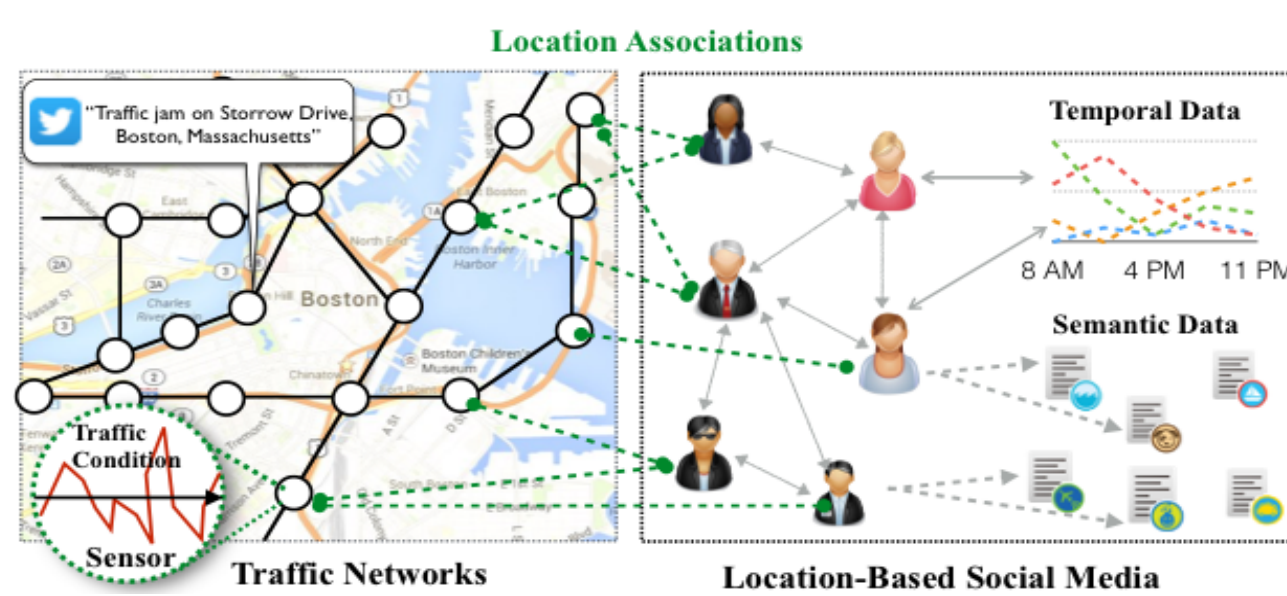
1. Problem Studied: Traffic Prediction with Partially Observed Traffic History.

2. Traffic Prediction: Infer the traffic conditions in the future time span for a geographical area.

3. Partially Observed History: In the target area, some locations are not deployed with any sensors, their historical traffic conditions are not available.

4. The Goal: Make good predictions for every location in the target area based on the partially observed traffic history.

2. Location-Based Social Media (LBSM)



LBSM Used: Twitter

Table 1: Average # of tweets in each region under different spatiotemporal resolutions in our dataset.

Temporal Resolution	Spatial Resolution	Ave. #Tweets
12 hours	1 × 1	47,113
1 hour	1 × 1	3,926
1 hour	2 × 2	1,306
1 hour	3 × 3	554
1 hour	4 × 4	389
1 hour	30 × 30	15

Target Area: Greater Los Angeles

Why LBSM ?

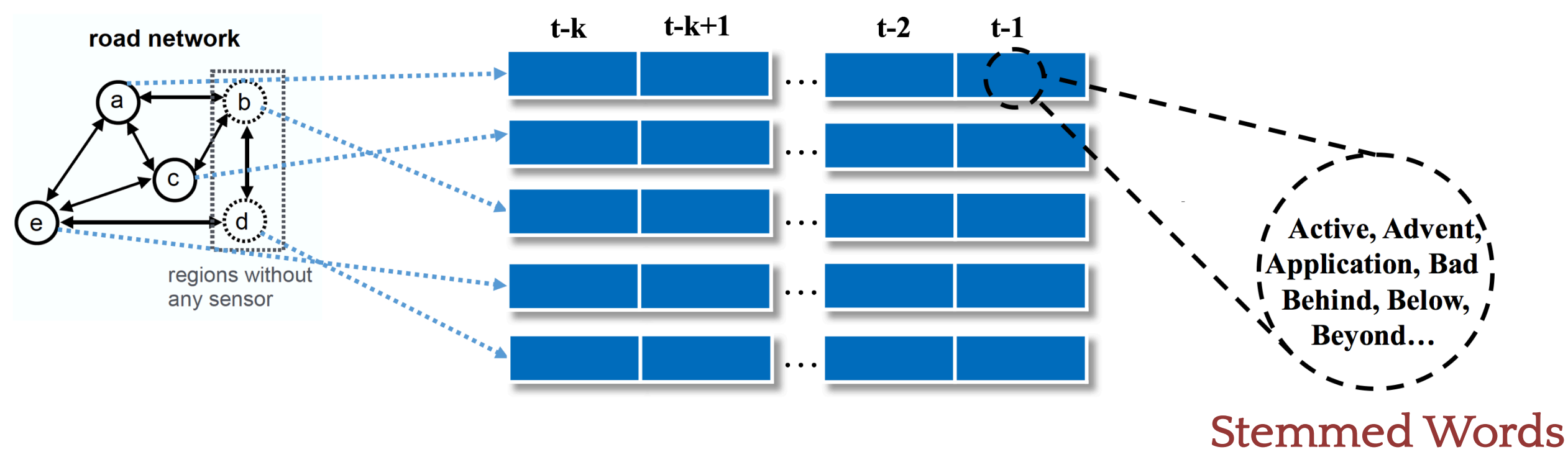
1. Cover much **wider range** of geographic areas.
2. Provide **abundant information** about the road users in real-time.
3. Dictation Systems (e.g. Siri) in smart phones or smart cars allow road user to post contents in LBSM **easily**.
4. By mining the **semantic** and **spatial** information from LBSM, we can effectively infer the future traffic conditions for many areas, including the road segments without sensors.

Challenge 0: How to incorporate LBSM semantics into traffic prediction?

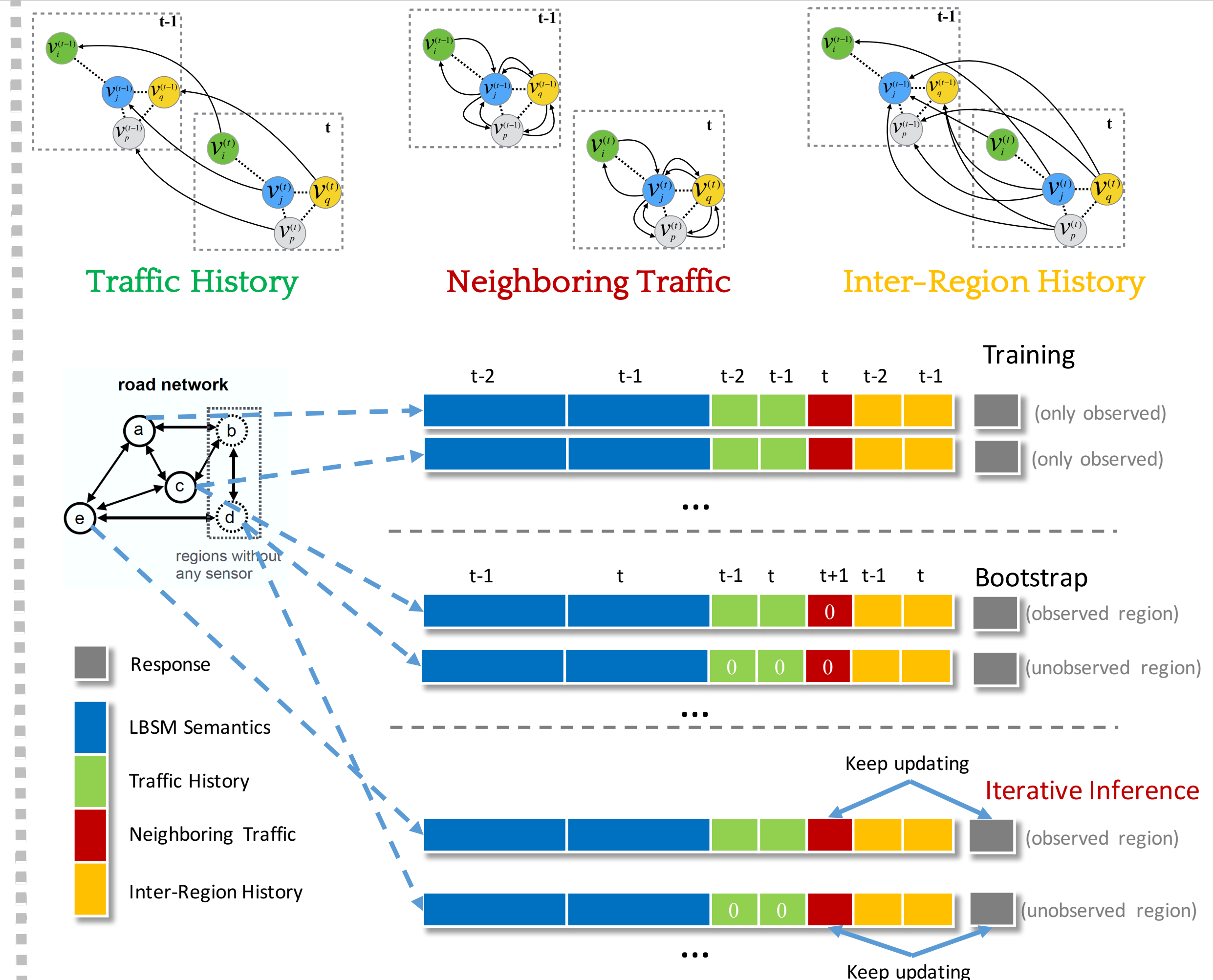
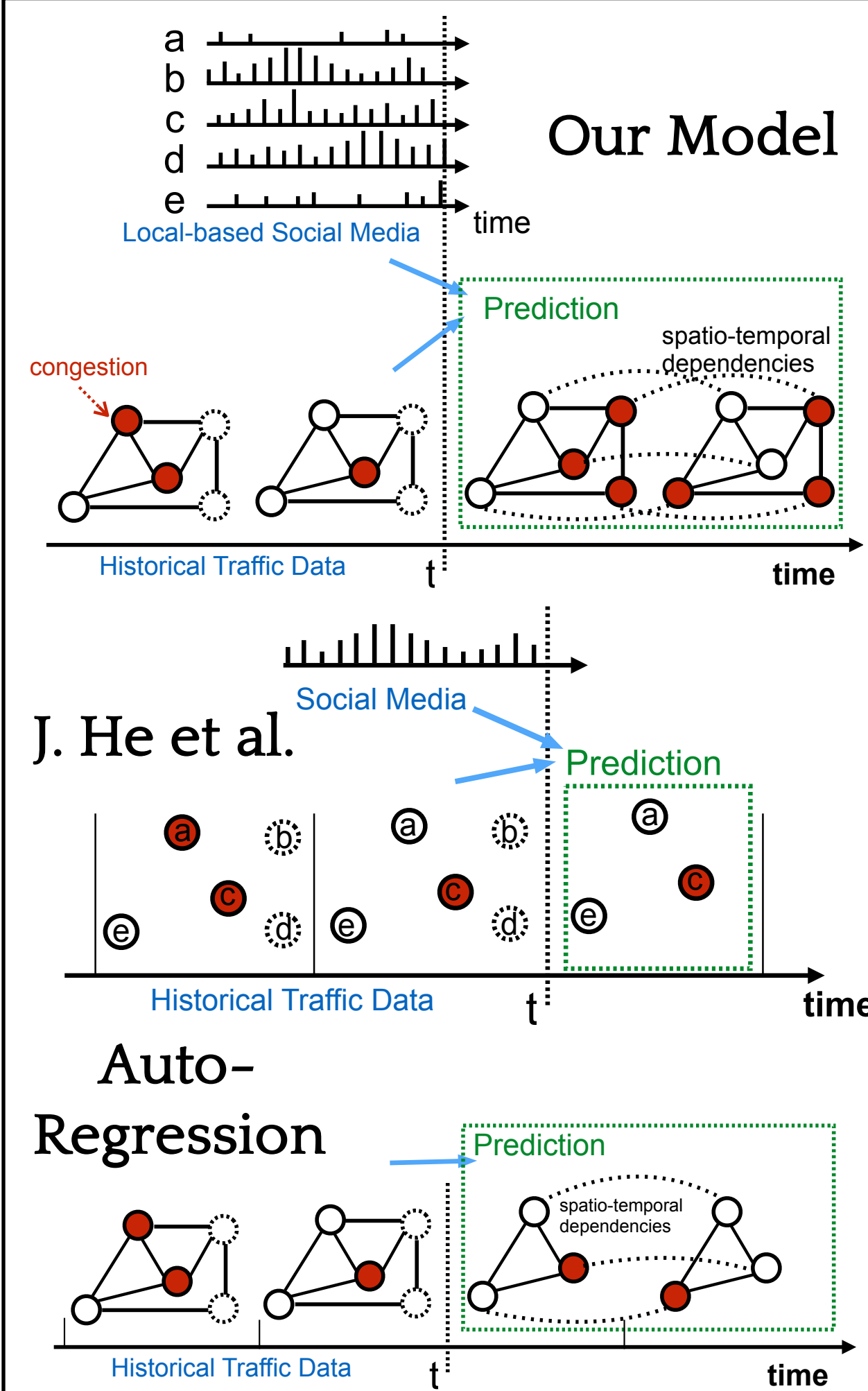
Challenge 1: Lack of Traffic History Information for Some Locations.

Challenge 2: Sparsity of LBSM Information at Fine Granularities (Table 1).

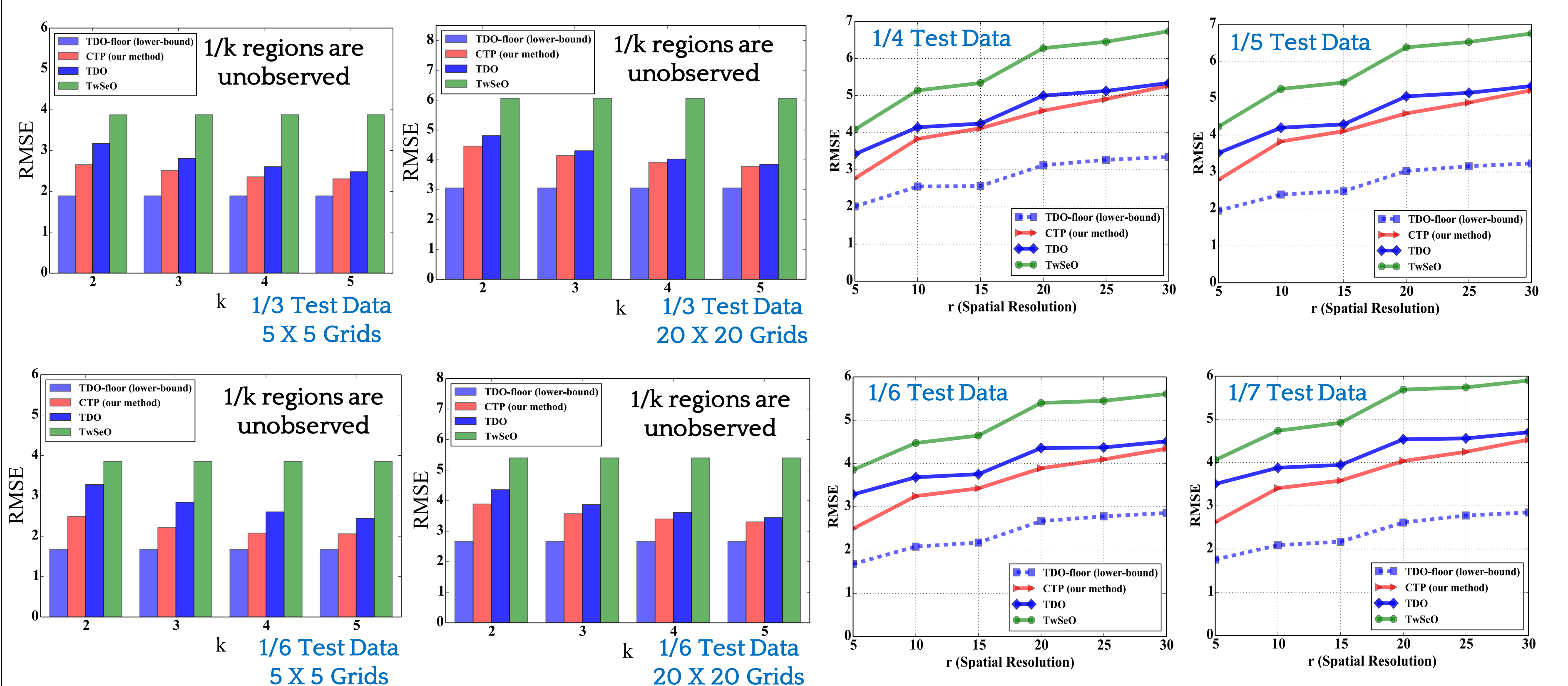
Bag-of-words Representation



3. Collective Inference Framework



4. Experiment Results



5. Acknowledgement

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