

REPRESENTATION THEORY I

Jendrik Stelzner

April 12, 2015

Contents

1	Basic Definitions	2
2	Nilpotent and solvable Lie algebras	8

1 Basic Definitions

Definition. A k -Lie algebra is a vector space \mathfrak{g} (over some field k) together with a k -bilinear map

$$[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$$

satisfying the following:

1. $[\cdot, \cdot]$ is *alternating*, i.e. $[x, x] = 0$ for every $x \in \mathfrak{g}$.
2. The *Jacobi identity*

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0 \quad \text{for all } x, y, z \in \mathfrak{g}.$$

$[\cdot, \cdot]$ is called a *Lie bracket*.

Remark. $[\cdot, \cdot]$ is antisymmetric, i.e. $[y, x] = -[x, y]$ for all $x, y \in \mathfrak{g}$, because

$$0 = [x + y, x + y] = [x, x] + [x, y] + [y, x] + [y, y] = [x, y] + [y, x].$$

Definition. Let A be a k -algebra. A *derivation of A* is a k -linear map $d: A \rightarrow A$ such that

$$d(ab) = d(a)b + ad(b) \quad \text{for all } a, b \in A.$$

We set

$$\text{Der}(A) := \{d: A \rightarrow A \mid d \text{ is a derivation of } A\}.$$

Remark. $\text{Der}(A)$ is clearly a k -vector space.

Examples. 1. Any vector space V becomes a Lie algebra via

$$[x, y] = 0 \quad \text{for all } x, y \in V.$$

2. Any associative k -algebra A becomes a Lie algebra via

$$[a, b] = ab - ba \quad \text{for all } a, b \in A.$$

It is clear that $[\cdot, \cdot]$ is alternating and the Jacobi identity can be verified by some easy calculation.

In particular $M_n(k)$ is a Lie algebra via

$$[A, B] = AB - BA \quad \text{for all } A, B \in M_n(k).$$

This is called the *general linear Lie algebra* and is denoted by $\mathfrak{gl}_n(k)$ or $\mathfrak{gl}(n, k)$.

More generally for any k -vector space the space $\text{End}_k(V)$ becomes a Lie algebra via

$$[\varphi_1, \varphi_2] := \varphi_1 \circ \varphi_2 - \varphi_2 \circ \varphi_1 \quad \text{for all } \varphi_1, \varphi_2 \in \text{End}_k(V).$$

This is called the *general linear Lie algebra for V* and is denoted by $\mathfrak{gl}(V)$.

A Lie algebra \mathfrak{g} is called *linear* if $\mathfrak{g} \subseteq \mathfrak{gl}(V)$ for some finite dimensional vector space V .

3. Let A be a k -algebra. $\text{Der}(A)$ is a Lie algebra via

$$[d, d'] := d \circ d' - d' \circ d \quad \text{for all } d, d' \in \text{Der}(A).$$

Is an easy calculation to show that $[d, d']$ is again a derivation. Notice that the Jacobi identity for $\text{Der}(A)$ follows from the Jacobi identity for $\mathfrak{gl}(A)$.

We will now look at how to construct new Lie algebras from old ones.

Definition. Let \mathfrak{g}_1 and \mathfrak{g}_2 be Lie algebras over the same field k . Then the *product* of \mathfrak{g}_1 and \mathfrak{g}_2 is defined as the k -vector space $\mathfrak{g}_1 \times \mathfrak{g}_2$ together with the Lie bracket

$$[(x_1, y_1), (x_2, y_2)] = ([x_1, x_2], [y_1, y_2]) \quad \text{for all } (x_1, y_1), (x_2, y_2) \in \mathfrak{g}_1 \times \mathfrak{g}_2.$$

Let \mathfrak{g} be a Lie algebra over k and A an associative, commutative k -algebra. Then $\mathfrak{g} \otimes_k A$ is a Lie algebra via

$$[x \otimes a, y \otimes b] = [x, y] \otimes (ab) \quad \text{for all } x, y \in \mathfrak{g} \text{ and } a, b \in A.$$

Definition. Let \mathfrak{g} be a Lie algebra and $A = k[t, t^{-1}]$ be the algebra of Laurent polynomials over k . Then

$$\mathcal{L}(\mathfrak{g}) := \mathfrak{g} \otimes_k A$$

with the Lie bracket as above is called the *loop (Lie) algebra* of \mathfrak{g} .

Another example of construction new Lie algebras from old ones are *central extensions*: Let \mathfrak{g} be any k -Lie algebra.

$$\tilde{\mathfrak{g}} := \mathfrak{g} \otimes k = \{x + \lambda c \mid x \in \mathfrak{g}, \lambda \in k\},$$

where we understand c as a formal variable. Suppose that $\kappa: \mathfrak{g} \times \mathfrak{g} \rightarrow k$ is a k -bilinear map satisfying the following properties:

1. κ is antisymmetric, i.e. $\kappa(x, y) = -\kappa(y, x)$ for all $x, y \in \mathfrak{g}$.
2. The 2-cocycle condition

$$\kappa([x, y], z) + \kappa([y, z], x) + \kappa([z, x], y) = 0 \quad \text{for all } x, y, z \in \mathfrak{g}.$$

Then $\tilde{\mathfrak{g}}$ becomes a Lie algebra via

$$[x + \lambda c, y + \mu c] := [x, y] + \kappa(x, y)\lambda\mu c.$$

Note that c is central in $\tilde{\mathfrak{g}}$ in the sense that $[x, c] = 0$ for all $x \in \mathfrak{g}$.

Example. Let $\mathfrak{g} = \mathfrak{gl}_n(k)$. We define a symmetric bilinear form on \mathfrak{g} via

$$(A, B)_{\text{tr}} = \text{tr}(AB).$$

We define a bilinear form

$$\mathcal{L}(\mathfrak{g}) \times \mathcal{L}(\mathfrak{g}) \rightarrow k[t, t^{-1}], (x \otimes p, y \otimes q) \mapsto (x, y)_{\text{tr}} pq$$

We now get a 2-cocycle $\kappa: \mathcal{L}(\mathfrak{g}) \times \mathcal{L}(\mathfrak{g}) \rightarrow k$ via

$$\kappa(a, b) := \text{Res} \left(\frac{\partial a}{\partial t}, b \right).$$

κ is also antisymmetric: Let $a = x \otimes t^i$ and $b = y \otimes t^j$ with $x, y \in \mathfrak{g}$ and $i, j \in \mathbb{Z}$. Then

$$\begin{aligned}\kappa(x \otimes t^i, y \otimes t^j) &= \text{Res}(ix \otimes t^{i-1}, y \otimes t^j) = \text{Res}(it^{i+j-1}(x, y)_{\text{tr}}) \\ &= \begin{cases} i(x, y)_{\text{tr}} & \text{if } i + j = 0, \\ 0 & \text{otherwise.} \end{cases}\end{aligned}$$

In the same way we find that

$$\kappa(y \otimes t^j, x \otimes t^i) = \begin{cases} j(x, y)_{\text{tr}} & \text{if } i + j = 0, \\ 0 & \text{otherwise.} \end{cases}$$

Since $(\cdot, \cdot)_{\text{tr}}$ is symmetric we find that

$$\begin{aligned}\kappa(x \otimes t^i, y \otimes t^j) &= \begin{cases} i(x, y)_{\text{tr}} & \text{if } i + j = 0, \\ 0 & \text{otherwise,} \end{cases} \\ &= \begin{cases} -j(x, y)_{\text{tr}} & \text{if } i + j = 0, \\ 0 & \text{otherwise,} \end{cases} \\ &= -\kappa(y \otimes t^j, x \otimes t^i).\end{aligned}$$

As for all algebraic structures morphisms are of interest.

Definition. Given k -Lie algebras \mathfrak{g}_1 and \mathfrak{g}_2 a *homomorphism of Lie algebras* $\mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ is a k -linear map $f: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ such that

$$f([x, y]) = [f(x), f(y)] \quad \text{for all } x, y \in \mathfrak{g}_1.$$

Examples. 1. For any Lie algebra \mathfrak{g} the identity $\text{id}_{\mathfrak{g}}: \mathfrak{g} \rightarrow \mathfrak{g}$ is a Lie algebra homomorphism.

2. Given Lie algebras $\mathfrak{g}_1, \mathfrak{g}_2$ and \mathfrak{g}_3 and Lie algebra homomorphisms $f_1: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ and $f_2: \mathfrak{g}_2 \rightarrow \mathfrak{g}_3$ the composition $f_2 \circ f_1: \mathfrak{g}_1 \rightarrow \mathfrak{g}_3$ is also a homomorphism of Lie algebras.

Remark. We find that we have a category of k -Lie algebras. An *isomorphism of k -Lie algebras* is an isomorphism in the category of k -Lie algebras. Clearly every isomorphism is an homomorphism and bijective. The converse also holds: If $f: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ is a bijective homomorphism of k -Lie algebras, then the k -linear map $f^{-1}: \mathfrak{g}_2 \rightarrow \mathfrak{g}_1$ is also an homomorphism of k -Lie algebras, because for all $x, y \in \mathfrak{g}_2$

$$\begin{aligned}f^{-1}([x, y]) &= f^{-1}([f(f^{-1}(x)), f(f^{-1}(y))]) \\ &= f^{-1}(f([f^{-1}(x), f^{-1}(y)])) \\ &= [f^{-1}(x), f^{-1}(y)].\end{aligned}$$

So an isomorphism of Lie algebras is just a homomorphism of Lie algebras which is bijective.

Definition. Let \mathfrak{g} be a k -Lie algebra. A *representation* of \mathfrak{g} is a k -vector space V together with a homomorphism of Lie algebras $\rho: \mathfrak{g} \rightarrow \mathfrak{gl}(V)$.

Remark. Equivalently a representation of \mathfrak{g} is a k -vector space V together with a k -bilinear map $\mathfrak{g} \times V \rightarrow V, (x, v) \mapsto x.v$ such that

$$x.y.v - y.x.v = [x, y].v \quad \text{for all } x, y \in \mathfrak{g} \text{ and } v \in V.$$

Definition. Let \mathfrak{g} be a Lie algebra. Then

$$\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g}), x \mapsto [x, \cdot]$$

is called the *adjoint representation* of \mathfrak{g} .

Remark. That ad is a homomorphism of Lie algebras is equivalent to

$$\text{ad}([x, y])(z) = [\text{ad}(x), \text{ad}(y)](z) \quad \text{for all } x, y, z \in \mathfrak{g}.$$

Because

$$\text{ad}([x, y])(z) = [[x, y], z] = -[z, [x, y]]$$

and

$$\begin{aligned} [\text{ad}(x), \text{ad}(y)](z) &= (\text{ad}(x) \circ \text{ad}(y))(z) - (\text{ad}(y) \circ \text{ad}(x))(z) \\ &= [x, [y, z]] - [y, [x, z]] = [x, [y, z]] + [y, [z, x]] \end{aligned}$$

this is equivalent to the Jacobi identity.

Definition. Let \mathfrak{g} be a k -Lie algebra. A *Lie subalgebra* of a \mathfrak{g} is a k -linear subspace $L \subseteq \mathfrak{g}$ such that

$$[x, y] \in L \quad \text{for all } x, y \in L.$$

An *ideal* inside \mathfrak{g} is a k -linear subspace $I \subseteq \mathfrak{g}$ such that

$$[x, y] \in I \quad \text{for all } x \in \mathfrak{g} \text{ and } y \in I.$$

We denote ideals by $I \triangleleft \mathfrak{g}$.

For a Lie algebra \mathfrak{g} and a subalgebra $\mathfrak{h} \subseteq \mathfrak{g}$ it is clear that \mathfrak{h} becomes a Lie algebra by restricting the Lie bracket of \mathfrak{g} to \mathfrak{h} . The inclusion $\mathfrak{h} \hookrightarrow \mathfrak{g}$ is then clearly a homomorphism of Lie algebras.

Also notice that every ideal inside \mathfrak{g} is also a subalgebra of \mathfrak{g} .

Example. Let $\mathfrak{g} = \mathfrak{gl}_n(k)$. Then

$$\mathfrak{sl}_n(k) = \{A \in \mathfrak{g} \mid \text{tr } A = 0\}$$

is a subalgebra. Even more

$$\mathfrak{sl}_n(k) = [\mathfrak{g}, \mathfrak{g}].$$

To see this first notice that on the one hand $A, B \in \mathfrak{g}$

$$\text{tr}[A, B] = \text{tr}(AB - BA) = \text{tr}(AB) - \text{tr}(BA) = \text{tr}(AB) - \text{tr}(AB) = 0.$$

Therefore $[\mathfrak{g}, \mathfrak{g}] \subseteq \mathfrak{sl}_n(k)$. On the other hand notice that $\mathfrak{sl}_n(k)$ has a basis given by the elementary matrices e_{ij} with $1 \leq i \neq j \leq n$ and $e_{11} - e_{ii}$ with $1 < i \leq n$. Each of these matrices is given as a commutator, namely $e_{ij} = [e_{ii}, e_{ij}]$ for $1 \leq i \neq j \leq n$ and $e_{11} - e_{ii} = [e_{1i}, e_{i1}]$ for $1 < i \leq n$. Therefore $\mathfrak{sl}_n(k) \subseteq [\mathfrak{g}, \mathfrak{g}]$.

We have similar properties for ideals inside of Lie algebras as for ideals inside of a ring: For a collection of ideals I_λ , $\lambda \in \Lambda$, their intersection $\bigcap_{\lambda \in \Lambda} I_\lambda$ and their sum $\sum_{\lambda \in \Lambda} I_\lambda$ are also ideals inside \mathfrak{g} . For ideals $I, J \triangleleft \mathfrak{g}$ the subspace $[I, J]$ is also an ideal inside \mathfrak{g} . (For any two subsets $X, Y \subseteq \mathfrak{g}$ we denote by $[X, Y]$ the linear subspace generated by the commutators $[x, y]$ with $x \in X, y \in Y$.) To see that $[I, J]$ is an ideal notice that for any $x \in I, y \in J$ and $z \in \mathfrak{g}$

$$[z, [x, y]] = -[x, \underbrace{[y, z]}_{\in J}] - [y, \underbrace{[z, x]}_{\in I}].$$

Remark. If \mathfrak{g} is a Lie algebra and $I \triangleleft \mathfrak{g}$ then the quotient vector space \mathfrak{g}/I is also a Lie algebra via

$$[x + I, y + I] = [x, y] + I.$$

It is easy to see that this bilinear map is well-defined. The properties for the Lie bracket on \mathfrak{g}/I follow from the ones for the Lie bracket on \mathfrak{g} .

From the definition of the Lie bracket on \mathfrak{g}/I it is clear that the canonical projection $\pi: \mathfrak{g} \rightarrow \mathfrak{g}/I$ is a homomorphism of Lie algebras.

We have the usual theorems about homomorphisms and ideals.

Proposition 1. Let \mathfrak{g}_1 and \mathfrak{g}_2 be Lie algebras and $f: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ a homomorphism of Lie algebras.

1. $\ker f \triangleleft \mathfrak{g}_1$ is an ideal.
2. $\text{im } f \subseteq \mathfrak{g}_2$ is a Lie subalgebra.
3. If $I \triangleleft \mathfrak{g}_1$ is an ideal with $\ker f \subseteq I$ then there exists a unique homomorphism of Lie algebras $\tilde{f}: \mathfrak{g}_1/I \rightarrow \mathfrak{g}_2$ with $f = \tilde{f} \circ \pi$ where $\pi: \mathfrak{g}_1 \rightarrow \mathfrak{g}_1/I$ is the canonical projection.

$$\begin{array}{ccc} \mathfrak{g}_1 & & \\ \pi \downarrow & \searrow f & \\ \mathfrak{g}_1/I & \xrightarrow{\exists! \tilde{f}} & \mathfrak{g}_2 \end{array}$$

4. If $I, J \triangleleft \mathfrak{g}$ are subideals with $I \subseteq J$ then J/I is an ideal inside \mathfrak{g}/I and the map

$$(\mathfrak{g}/I)/(J/I) \rightarrow \mathfrak{g}/I, (x + I) + (J/I) \mapsto x + I$$

is a natural isomorphism of Lie algebras.

5. If $I, J \triangleleft \mathfrak{g}$ are subideals then there is a natural isomorphism

$$(I + J)/J \rightarrow I/(I \cap J)$$

defined by

$$(x + J) + I \mapsto x + (I \cap J) \quad \text{for every } x \in I$$

is a natural isomorphism of Lie algebras.

Definition. Let \mathfrak{g} be a Lie algebra. The *center* of \mathfrak{g} is

$$Z(\mathfrak{g}) := \{x \in \mathfrak{g} \mid [x, y] = 0 \text{ for every } y \in \mathfrak{g}\} = \ker \text{ad}.$$

\mathfrak{g} is called *abelian* if $[\mathfrak{g}, \mathfrak{g}] = 0$.

Clearly \mathfrak{g} is abelian if and only if $Z(\mathfrak{g}) = \mathfrak{g}$. Notice that $[\mathfrak{g}, \mathfrak{g}]$ and $Z(\mathfrak{g})$ are ideals inside \mathfrak{g} .

Definition. A Lie algebra \mathfrak{g} is *simple* if 0 and \mathfrak{g} are the only ideals inside \mathfrak{g} and \mathfrak{g} is not abelian.

Lemma 2. Let \mathfrak{g} be a simple Lie algebra. Then $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{g}$ and $Z(\mathfrak{g}) = 0$.

Proof. Because \mathfrak{g} is simple it is not abelian. Therefore $[\mathfrak{g}, \mathfrak{g}] \neq 0$ and $Z(\mathfrak{g}) \neq \mathfrak{g}$. Since $[\mathfrak{g}, \mathfrak{g}]$ and $Z(\mathfrak{g})$ are ideals inside \mathfrak{g} it follows that $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{g}$ and $Z(\mathfrak{g}) = 0$. \square

Corollary 3. Let \mathfrak{g} be simple. Then $\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$ is injective. In particular \mathfrak{g} is linear.

Proof. This directly follows from $\ker \text{ad} = Z(\mathfrak{g}) = 0$. \square

Theorem 4 (Ado). Any finite dimensional Lie algebra is linear.

A proof of Ado's theorem will (maybe) be given later.

Remark. For a Lie algebra \mathfrak{g} the ideal $[\mathfrak{g}, \mathfrak{g}]$ is the minimal ideal inside \mathfrak{g} such that $\mathfrak{g}/[\mathfrak{g}, \mathfrak{g}]$ is abelian. Furthermore given any abelian Lie algebra \mathfrak{h} any homomorphism of Lie algebras $\mathfrak{g} \rightarrow \mathfrak{h}$ factorizes through a unique homomorphism of Lie algebras $\mathfrak{g}/[\mathfrak{g}, \mathfrak{g}] \rightarrow \mathfrak{h}$.

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\quad} & \mathfrak{h} \\ & \searrow & \nearrow \\ & \mathfrak{g}/[\mathfrak{g}, \mathfrak{g}] & \end{array} \quad \exists!$$

Examples. 1. Since $[\mathfrak{gl}_n(k), \mathfrak{gl}_n(k)] = \mathfrak{sl}_n(k) \neq \mathfrak{gl}_n(k)$ we find that $\mathfrak{gl}_n(k)$ is not simple.

2. Let $\mathfrak{g} = \mathfrak{sl}_2(k)$. Then \mathfrak{g} is simple if and only if $\text{char } k \neq 2$. To see this consider the basis

$$e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

of $\mathfrak{sl}_2(k)$. Then

$$[e, h] = -2e, [e, f] = h, [h, f] = -2f.$$

If $\text{char } k = 2$ then h spans a 1-dimensional ideal, thus $\mathfrak{sl}_2(k)$ is not simple. Suppose that $\text{char } k \neq 2$ and let $I \subseteq \mathfrak{sl}_2(k)$ be an ideal with $I \neq 0$. It is clear that if I contains one of the basis vectors e, h or f it follows that $I = \mathfrak{sl}_2(k)$. Let $x \in I$ with $x \neq 0$ and write $x = \alpha e + \beta h + \gamma f$. Then

$$[e, x] = -2\beta e + \gamma h \quad \text{and} \quad [e, [e, x]] = -2\gamma e.$$

Since $\gamma = 0$ or $\gamma \neq 0$ we find that $e \in I$.

Remark. $\mathfrak{sl}_n(\mathbb{C})$ is simple for all $n \geq 2$.

2 Nilpotent and solvable Lie algebras

Definition. Let A be a k -algebra. An element $a \in A$ is called *nilpotent* if $a^n = 0$ for some $n \geq 1$. Given a Lie algebra \mathfrak{g} an element $x \in \mathfrak{g}$ is called *ad-nilpotent* if $\text{ad}(x) \in \text{End}_k(\mathfrak{g})$ is nilpotent.

Definition. Let \mathfrak{g} be a Lie algebra. Define $\mathfrak{g}^0 := \mathfrak{g}$ and $\mathfrak{g}^{i+1} := [\mathfrak{g}, \mathfrak{g}^i]$ for all $i \geq 0$. Then

$$\mathfrak{g} = \mathfrak{g}^0 \supseteq \mathfrak{g}^1 \supseteq \mathfrak{g}^2 \supseteq \dots$$

is called the *central series* of \mathfrak{g} . Also define $\mathfrak{g}^{(0)} := \mathfrak{g}$ and $\mathfrak{g}^{(i+1)} := [\mathfrak{g}^{(i)}, \mathfrak{g}^{(i)}]$ for all $i \geq 0$. Then

$$\mathfrak{g}^{(0)} \supseteq \mathfrak{g}^{(1)} \supseteq \mathfrak{g}^{(2)} \supseteq \dots$$

is called the *derived series* of \mathfrak{g} . \mathfrak{g} is called *nilpotent* if $\mathfrak{g}^i = 0$ for some i and *solvable* if $\mathfrak{g}^{(i)} = 0$ for some i .

It is clear that every nilpotent Lie algebra is also solvable.

Examples. 1. Because $[\mathfrak{gl}_n(\mathbb{C}), \mathfrak{gl}_n(\mathbb{C})] = \mathfrak{sl}_n(\mathbb{C})$ and $[\mathfrak{sl}_n(\mathbb{C}), \mathfrak{sl}_n(\mathbb{C})] = \mathfrak{sl}_n(\mathbb{C})$ for $n \geq 2$ (since $\mathfrak{sl}_n(\mathbb{C})$ is simple) $\mathfrak{gl}_n(\mathbb{C})$ is not simple.

2. If \mathfrak{g} is abelian then \mathfrak{g} is nilpotent.

3. A Heisenberg Lie algebra consists of a real vector space with basis $P_1, \dots, P_n, Q_1, \dots, Q_n, C$ together with the Lie bracket satisfying the following conditions:

$$[P_i, P_j] = [Q_i, Q_j] = [P_i, C] = [Q_i, C] = 0 \quad \text{and} \quad [P_i, Q_j] = \delta_{ij}C.$$

This defines a nilpotent Lie algebra.

Proposition 5. Let \mathfrak{g} be a Lie algebra.

1. If \mathfrak{h} is a Lie algebra and $f: \mathfrak{g} \rightarrow \mathfrak{h}$ a Lie algebra homomorphism then $f(\mathfrak{g}^i) = f(\mathfrak{g}^i)$ and $f(\mathfrak{g}^{(i)}) = f(\mathfrak{g}^{(i)})$ for all $i \geq 0$.
2. If \mathfrak{g} is nilpotent (resp. solvable) then any Lie subalgebra $\mathfrak{h} \subseteq \mathfrak{g}$ and any quotient of \mathfrak{g} (by an ideal) is nilpotent (resp. solvable).
3. If $I \triangleleft \mathfrak{g}$ with $I \subseteq Z(\mathfrak{g})$ and \mathfrak{g}/I is nilpotent then \mathfrak{g} is nilpotent.
4. If $\mathfrak{g} \neq 0$ is nilpotent then $Z(\mathfrak{g}) \neq 0$.
5. If \mathfrak{g} is nilpotent and $x \in \mathfrak{g}$ then x is ad-nilpotent.
6. If $I \triangleleft \mathfrak{g}$ then I^i and $I^{(i)}$ are ideals inside \mathfrak{g} for all $i \geq 0$.

Proof. 1. It suffices to show that for any two subsets $X, Y \subseteq \mathfrak{g}$

$$f([X, Y]) = [f(X), f(Y)]$$

the statement then follows inductively. It holds because f is a Lie algebra homomorphism and therefore

$$\begin{aligned} f([X, Y]) &= f(\text{span}_k\{[x, y] \mid x \in X, y \in Y\}) \\ &= \text{span}_k\{f([x, y]) \mid x \in X, y \in Y\} \\ &= \text{span}_k\{[f(x), f(y)] \mid x \in X, y \in Y\} \\ &= \text{span}_k\{[x', y'] \mid x' \in f(X), y' \in f(Y)\} \\ &= [f(X), f(Y)]. \end{aligned}$$

2. The statement about subalgebras is clear since $\mathfrak{h}^i \subseteq \mathfrak{g}^i$ and $\mathfrak{h}^{(i)} \subseteq \mathfrak{g}^{(i)}$ for all i . The statement about quotient follow using the canonical projection $\pi: \mathfrak{g}/I$ where $I \triangleleft \mathfrak{g}$. Because π is a Lie algebra homomorphism we have

$$(\mathfrak{g}/I)^i = \pi(\mathfrak{g})^i = \pi(\mathfrak{g}^i) = 0$$

for i big enough. For solvable \mathfrak{g} the corresponding statements follow in the same way.

3. Let $\pi: \mathfrak{g} \rightarrow \mathfrak{g}/I$ be the canonical projection. Because \mathfrak{g}/I is nilpotent there exists some $i \geq 0$ with $(\mathfrak{g}/I)^i = 0$ and therefore

$$0 = (\mathfrak{g}/I)^i = \pi(\mathfrak{g})^i = \pi(\mathfrak{g}^i).$$

Thus $\mathfrak{g}^i \subseteq I \subseteq Z(G)$ and hence $\mathfrak{g}^{i+1} = 0$.

4. Let $i \geq 1$ be minimal such that $\mathfrak{g}^{i-1} \neq 0$ but $\mathfrak{g}^i = 0$. Then $\mathfrak{g}^{i-1} \subseteq Z(\mathfrak{g})$ and therefore $Z(\mathfrak{g}) \neq 0$.

5. Since \mathfrak{g} is nilpotent $\mathfrak{g}^i = 0$ for some $i \geq 0$. Then

$$(\text{ad}(x))^i(\mathfrak{g}) \subseteq \mathfrak{g}^i = 0,$$

so $(\text{ad}(x))^i = 0$.

6. This follows inductively by using that $[I, J]$ is an ideal inside \mathfrak{g} for any $I, J \triangleleft \mathfrak{g}$. □