

# REPRESENTATION THEORY I

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## 1 Basic Definitions

**Definition.** A Lie algebra is a vector space  $\mathfrak{g}$  (over some field  $k$ ) together with a bilinear map

$$[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$$

satisfying the following:

1.  $[\cdot, \cdot]$  is alternating, i.e.  $[x, x] = 0$  for every  $x \in \mathfrak{g}$ .
2. The Jacobi identity

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0 \quad \text{for all } x, y, z \in \mathfrak{g}.$$

$[\cdot, \cdot]$  is called a Lie bracket.