

# 统计信号处理

## 第十一章

# 简单假设检验 I (确定信号的检测)

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# 内容概要

- 一、匹配滤波器
- 二、广义匹配滤波器
- 三、二元通信
- 四、多元通信
- 五、小结

# 一、匹配滤波器

两类假设：

$$H_0 : x[n] = w[n], n = 0, 1, \dots, N-1$$

$$H_1 : x[n] = s[n] + w[n], n = 0, 1, \dots, N-1$$

其中信号  $s[n]$  是已知的， $w[n]$  是均值为零、方差为  $\sigma^2$  的高斯白噪声。如何判断是否存在信号？

采用NP准则，若似然比

$$L(\mathbf{x}) = \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} > \gamma$$

则判  $H_1$

$$p(\mathbf{x}; H_1) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - s[n])^2 \right\}$$

$$p(\mathbf{x}; H_0) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} x^2[n] \right\}$$

$$L(\mathbf{x}) = \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} = \exp \left\{ -\frac{1}{2\sigma^2} \left( \sum_{n=0}^{N-1} s^2[n] - 2 \sum_{n=0}^{N-1} x[n] s[n] \right) \right\}$$

$$l(\mathbf{x}) = \ln L(\mathbf{x}) = -\frac{1}{2\sigma^2} \left( \sum_{n=0}^{N-1} s^2[n] - 2 \sum_{n=0}^{N-1} x[n] s[n] \right)$$

$$L(\mathbf{x}) = \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} > \gamma \quad \Rightarrow \quad l(\mathbf{x}) > \ln \gamma$$

$$T(\mathbf{x}) \quad \frac{\sum_{n=0}^{N-1} x[n] s[n]}{\sum_{n=0}^{N-1} s^2[n]} > \gamma'$$

$$T(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s[n] > \gamma'$$

- 相关器(correlator)
- 仿形相关器(replica-correlator)

## ● 另一种解读

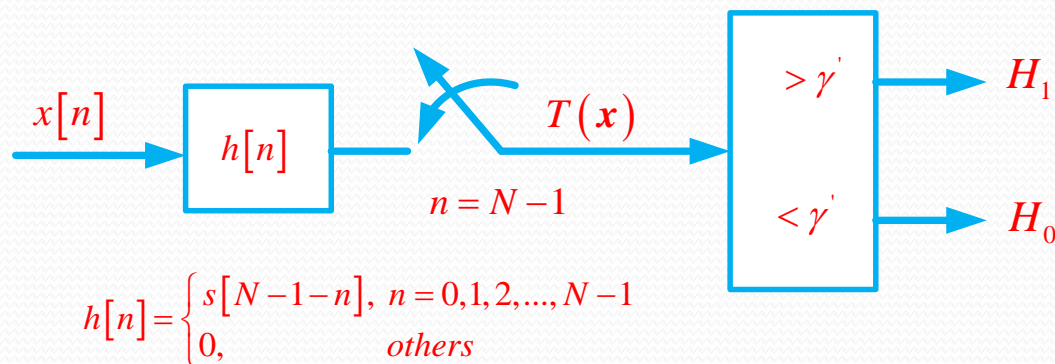
$$T(\mathbf{x}) = \sum_{n=0}^{N-1} x[n]s[n] > \gamma'$$

- 对冲击响应为  $h[n]$  ( $0 \leq n \leq N-1$  时非零) 的FIR滤波器, 其输出为

$$y[n] = \sum_{k=0}^n x[k]h[n-k] \quad \Rightarrow \quad y[N-1] = \sum_{k=0}^{N-1} x[k]h[N-1-k]$$

- 若取  $h[n] = s[N-1-n]$

$$y[N-1] = \sum_{k=0}^{N-1} x[k]h[N-1-k] = \sum_{k=0}^{N-1} x[k]s[k]$$



匹配滤波器  
(matched-filter)

## ● 从输出信噪比(output SNR)的角度

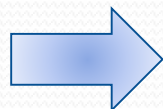
$$y[N-1] = \sum_{k=0}^{N-1} x[k] h[N-1-k]$$

输出信噪比(output SNR):

$$\eta = \frac{E^2(y[N-1]; H_1)}{\text{var}(y[N-1]; H_0)} = \frac{\left\{ E \left( \sum_{k=0}^{N-1} (s[k] + w[k]) h[N-1-k] \right) \right\}^2}{E \left\{ \left( \sum_{k=0}^{N-1} w[k] h[N-1-k] - 0 \right)^2 \right\}} = \frac{\left( \sum_{k=0}^{N-1} s[k] h[N-1-k] \right)^2}{E \left\{ \left( \sum_{k=0}^{N-1} w[k] h[N-1-k] \right)^2 \right\}}$$

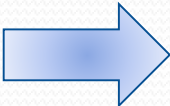
$$\text{令 } \mathbf{s} = [s[0], s[1], \dots, s[N-1]]^T, \quad \mathbf{h} = [h[N-1], h[N-2], \dots, h[0]]^T$$


$$\mathbf{w} = [w[0], w[1], \dots, w[N-1]]^T$$


$$\eta = \frac{(\mathbf{h}^T \mathbf{s})^2}{E \left\{ (\mathbf{h}^T \mathbf{w})^2 \right\}}$$

$$\eta = \frac{(\mathbf{h}^T \mathbf{s})^2}{E\{(\mathbf{h}^T \mathbf{w})^2\}} = \frac{(\mathbf{h}^T \mathbf{s})^2}{E\{\mathbf{h}^T \mathbf{w} \mathbf{w}^T \mathbf{h}\}} = \frac{(\mathbf{h}^T \mathbf{s})^2}{\mathbf{h}^T E\{\mathbf{w} \mathbf{w}^T\} \mathbf{h}} = \frac{(\mathbf{h}^T \mathbf{s})^2}{\sigma^2 \mathbf{h}^T \mathbf{h}}$$

利用Cauchy-Schwarz不等式:  $(\mathbf{h}^T \mathbf{s})^2 \leq (\mathbf{h}^T \mathbf{h})(\mathbf{s}^T \mathbf{s})$



$$\eta \leq \frac{\mathbf{s}^T \mathbf{s}}{\sigma^2}$$
 当且仅当  $\mathbf{h} = c\mathbf{s}$  时取等号  

 即  $h[n] = cs[N-1-n]$

$$y[N-1] = \sum_{k=0}^{N-1} x[k]h[N-1-k]$$

$$\eta = \frac{\left( \sum_{k=0}^{N-1} h[N-1-k]s[k] \right)^2}{E\left\{ \left( \sum_{k=0}^{N-1} h[N-1-k]w[k] \right)^2 \right\}}$$

——成比例的系数不会影响检测性能!

——匹配滤波使输出信噪比最大!

## ● 匹配滤波器的性能

$$T(\mathbf{x}) = \sum_{n=0}^{N-1} x[n]s[n]$$

### ● 在 $H_0$ 假设下

$$E(T(\mathbf{x}); H_0) = E\left(\sum_{n=0}^{N-1} w[n]s[n]\right) = 0$$

$$\sum_{n=0}^{N-1} s^2[n] = \varepsilon \quad \text{——信号功率}$$

$$\text{var}(T(\mathbf{x}); H_0) = \text{var}\left(\sum_{n=0}^{N-1} w[n]s[n]\right) = \sum_{n=0}^{N-1} \text{var}(w[n]) s^2[n] = \sum_{n=0}^{N-1} \sigma^2 s^2[n] = \sigma^2 \varepsilon$$

### ● 在 $H_1$ 假设下

$$E(T(\mathbf{x}); H_1) = E\left(\sum_{n=0}^{N-1} (s[n] + w[n])s[n]\right) = E\left(\sum_{n=0}^{N-1} s^2[n]\right) = \varepsilon$$

$$\text{var}(T(\mathbf{x}); H_1) = \text{var}\left(\sum_{n=0}^{N-1} (s[n] + w[n])s[n]\right) = \text{var}\left(\sum_{n=0}^{N-1} w[n]s[n]\right) = \sigma^2 \varepsilon$$



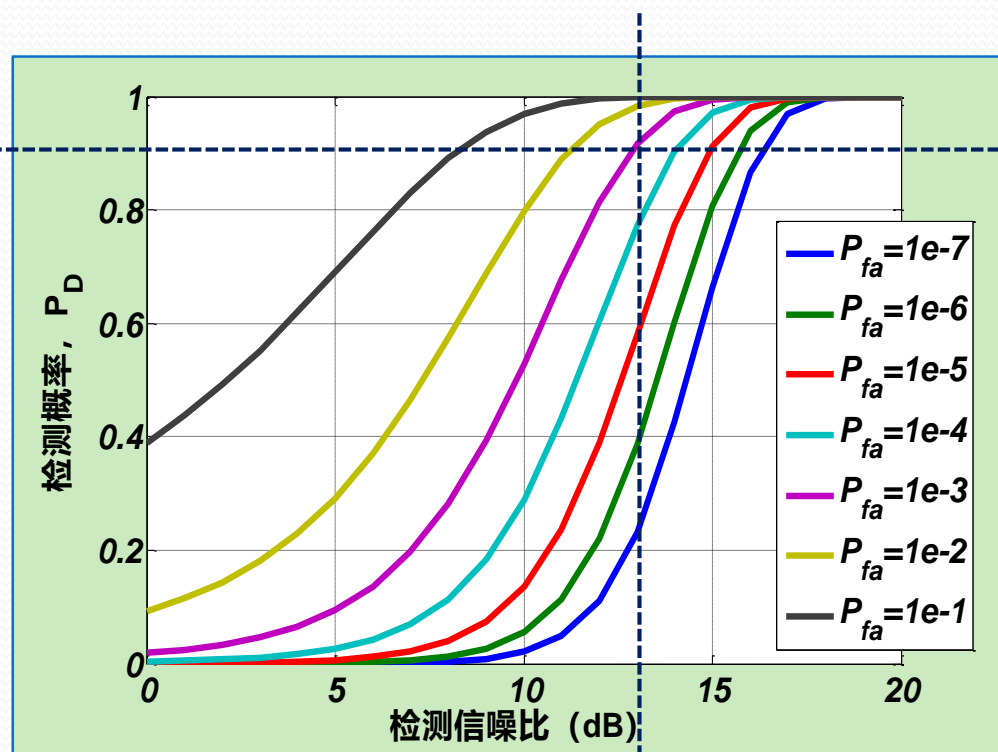
$$T(\mathbf{x}) \sim \begin{cases} N(0, \sigma^2 \varepsilon), & H_0 \\ N(\varepsilon, \sigma^2 \varepsilon), & H_1 \end{cases}$$

$$\Rightarrow \left\{ \begin{array}{l} P_{fa} = \Pr(T(\mathbf{x}) > \gamma'; H_0) = Q(\gamma' / \sqrt{\sigma^2 \varepsilon}) \Rightarrow \gamma' = \sqrt{\sigma^2 \varepsilon} Q^{-1}(P_{fa}) \\ P_D = \Pr(T(\mathbf{x}) > \gamma'; H_1) = Q((\gamma' - \varepsilon) / \sqrt{\sigma^2 \varepsilon}) \end{array} \right.$$

$$\Rightarrow P_D = Q\left(Q^{-1}(P_{fa}) - \frac{\varepsilon}{\sqrt{\sigma^2 \varepsilon}}\right)$$

$$= Q\left(Q^{-1}(P_{fa}) - \sqrt{\frac{\varepsilon}{\sigma^2}}\right)$$

✓ 对1e-3虚警率，0.9以上检测概率，所需最低信噪比约为  
**13dB**



$$\text{检测性能: } P_D = Q\left(Q^{-1}(P_{fa}) - \sqrt{\frac{\varepsilon}{\sigma^2}}\right)$$

● 如何改善性能?

——检测性能只与信号能量  $\varepsilon$  有关, 与信号波形无关

$\varepsilon = \sum_{n=0}^{N-1} s^2[n]$

- ✓ 增大  $s[n]$ 
  - $H_1: x[n] = s[n] + w[n], n = 0, 1, \dots, N-1$
  - $T(\mathbf{x}) = \sum_{n=0}^{N-1} (s[n] + w[n]) s[n]$
- ✓ 增大  $\varepsilon$ 
  - 增大信号发射功率 ✓
  - 增大本地信号功率 ✗
- ✓ 增大  $N$  ✓
  - 增加信号预检测积分时间
  - 实际系统改善性能常用的方式

●  $H_0$  时

$$E(T(\mathbf{x}); H_0) = E\left(\sum_{n=0}^{N-1} w[n] s[n]\right) = 0$$

$$\text{var}(T(\mathbf{x}); H_0) = \text{var}\left(\sum_{n=0}^{N-1} w[n] s[n]\right) = \sum_{n=0}^{N-1} \text{var}(w[n]) s^2[n] = \sum_{n=0}^{N-1} \sigma^2 s^2[n] = \sigma^2 \varepsilon$$

●  $H_1$  时

$$E(T(\mathbf{x}); H_1) = E\left(\sum_{n=0}^{N-1} (s[n] + w[n]) s[n]\right) = E\left(\sum_{n=0}^{N-1} s^2[n]\right) = \varepsilon \quad \text{处理增益}$$

$$\text{var}(T(\mathbf{x}); H_1) = \text{var}\left(\sum_{n=0}^{N-1} (s[n] + w[n]) s[n]\right) = \sum_{n=0}^{N-1} \text{var}(w[n]) s^2[n] = \sigma^2 \varepsilon$$

## 二、广义匹配滤波器

两类假设：

$$H_0 : x[n] = w[n], n = 0, 1, \dots, N-1$$

$$H_1 : x[n] = s[n] + w[n], n = 0, 1, \dots, N-1$$

其中信号  $s[n]$  是已知的， $w[n]$  是零均值高斯有色噪声，且  $\mathbf{w} \sim N(0, \mathbf{C})$   
如何判断是否存在信号？

采用NP准则，若似然比

$$L(\mathbf{x}) = \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} > \gamma$$

则判  $H_1$

$$p(\mathbf{x}; H_1) = \frac{1}{(2\pi)^{N/2} \det^{1/2}(\mathbf{C})} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \mathbf{s})^T \mathbf{C}^{-1} (\mathbf{x} - \mathbf{s}) \right\}$$

$$p(\mathbf{x}; H_0) = \frac{1}{(2\pi)^{N/2} \det^{1/2}(\mathbf{C})} \exp \left\{ -\frac{1}{2} \mathbf{x}^T \mathbf{C}^{-1} \mathbf{x} \right\}$$

$$l(\mathbf{x}) = \ln \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} = -\frac{1}{2} \left( (\mathbf{x} - \mathbf{s})^T \mathbf{C}^{-1} (\mathbf{x} - \mathbf{s}) - \mathbf{x}^T \mathbf{C}^{-1} \mathbf{x} \right) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s} - \frac{1}{2} \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}$$

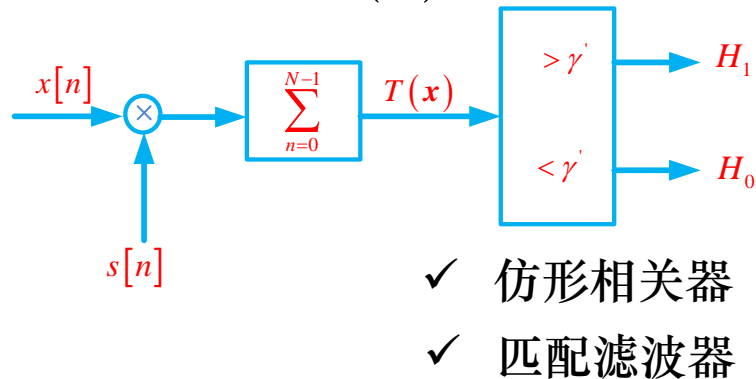
$$l(\mathbf{x}) = \ln \frac{p(\mathbf{x}; H_1)}{p(\mathbf{x}; H_0)} > \ln \gamma$$

$$\underbrace{\mathbf{x}^T \mathbf{C}^{-1} \mathbf{s}}_{T(\mathbf{x})} > \underbrace{\ln \gamma + \frac{1}{2} \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}}_{\gamma'}$$

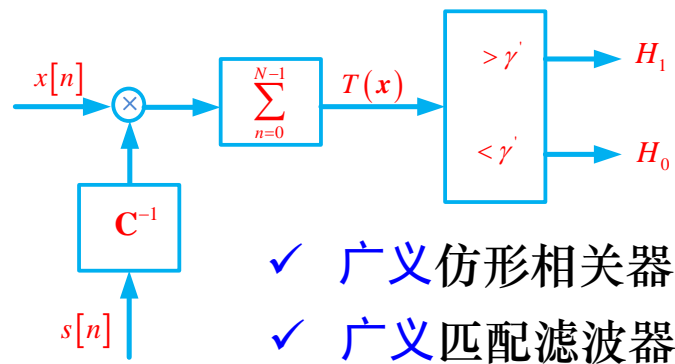
$$\underbrace{T(\mathbf{x}) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s}}_{\gamma'}$$

- 修正后的信号
- 广义仿形相关器
- 广义匹配滤波器

高斯白噪声时:  $T(\mathbf{x}) = \mathbf{x}^T \mathbf{s}$



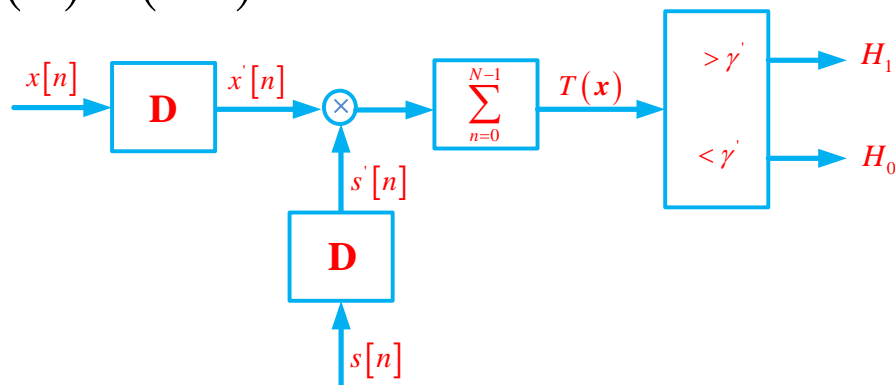
高斯有色噪声时:  $T(\mathbf{x}) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s}$



令  $\mathbf{C}^{-1} = \mathbf{D}^T \mathbf{D}$   $\Rightarrow T(\mathbf{x}) = (\mathbf{D}\mathbf{x})^T \mathbf{D}\mathbf{s}$  ——匹配滤波的思想

$\mathbf{D}$  称为预白化矩阵(whitening matrix)

$$T(\mathbf{x}) = (\mathbf{D}\mathbf{x})^T \mathbf{D}\mathbf{s}$$



$$\mathbf{x} = \mathbf{s} + \mathbf{w}$$

$$\mathbf{D}\mathbf{x} = \mathbf{D}\mathbf{s} + \mathbf{D}\mathbf{w}$$

## ● 广义匹配滤波器的性能

$$T(\mathbf{x}) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s}$$

### ● 在 $H_0$ 假设下

$$E(T(\mathbf{x}); H_0) = E(\mathbf{w}^T \mathbf{C}^{-1} \mathbf{s}) = 0$$

$$\text{var}(T(\mathbf{x}); H_0) = \text{var}(\mathbf{w}^T \mathbf{C}^{-1} \mathbf{s}) = E\left((\mathbf{w}^T \mathbf{C}^{-1} \mathbf{s} - 0)^2\right) = E(\mathbf{s}^T \mathbf{C}^{-1} \mathbf{w} \mathbf{w}^T \mathbf{C}^{-1} \mathbf{s}) = \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}$$

### ● 在 $H_1$ 假设下

$$E(T(\mathbf{x}); H_1) = E((\mathbf{s} + \mathbf{w})^T \mathbf{C}^{-1} \mathbf{s}) = \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}$$

$$\text{var}(T(\mathbf{x}); H_1) = \text{var}((\mathbf{s} + \mathbf{w})^T \mathbf{C}^{-1} \mathbf{s}) = \text{var}(\mathbf{w}^T \mathbf{C}^{-1} \mathbf{s}) = \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}$$

$$T(\mathbf{x}) \sim \begin{cases} N(0, \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}), & H_0 \\ N(\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}, \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}), & H_1 \end{cases}$$

$$\left. \begin{aligned} P_{fa} = \Pr(T(\mathbf{x}) > \gamma'; H_0) &= Q\left(\frac{\gamma'}{\sqrt{\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}}}\right) \Rightarrow \gamma' = \sqrt{\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}} Q^{-1}(P_{fa}) \\ P_D = \Pr(T(\mathbf{x}) > \gamma'; H_1) &= Q\left(\frac{\gamma' - \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}}{\sqrt{\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}}}\right) \end{aligned} \right\}$$

$$\Rightarrow P_D = Q\left(Q^{-1}(P_{fa}) - \sqrt{\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s}}\right)$$

——检测性能不仅与信号能量有关，而且与信号波形有关

——不同于高斯白噪声时的情况

## ● 信号优化设计

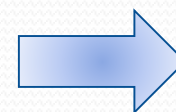
$$\max_s \{ \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s} \}$$

$$s.t. \quad \mathbf{s}^T \mathbf{s} = \varepsilon$$



$$J = \mathbf{s}^T \mathbf{C}^{-1} \mathbf{s} + \lambda (\varepsilon - \mathbf{s}^T \mathbf{s})$$

$$\frac{\partial J}{\partial \mathbf{s}} = 0$$

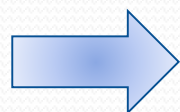


✓  $\mathbf{s}$  为特征向量

✓  $\lambda$  为特征值

$$\mathbf{C}^{-1} \mathbf{s} = \lambda \mathbf{s}$$

$$\mathbf{s}^T \mathbf{s} = \varepsilon$$



$$\underline{\mathbf{s}^T \mathbf{C}^{-1} \mathbf{s} = \lambda \varepsilon}$$

选择信号为  $\mathbf{C}^{-1}$  最大特征值所对应的特征向量

## ● 一般线性模型下信号检测

两类假设：

$$H_0 : \mathbf{x} = \mathbf{w}$$

$$H_1 : \mathbf{x} = \mathbf{H}\boldsymbol{\theta}_1 + \mathbf{w}$$

其中观测矩阵  $\mathbf{H}$  和参数矢量  $\boldsymbol{\theta}_1$  是已知的， $\mathbf{w}$  是零均值高斯噪声，且  $\mathbf{w} \sim N(0, \mathbf{C})$

NP检测器：  $T(\mathbf{x}) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s} = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{H} \boldsymbol{\theta}_1 \Rightarrow T(\mathbf{x}) = \{\mathbf{H}^T \mathbf{C}^{-1} \mathbf{x}\}^T \boldsymbol{\theta}_1 \Rightarrow$

$$T(\mathbf{x}) = \left\{ \left( \mathbf{H}^T \mathbf{C}^{-1} \mathbf{H} \right) \left( \mathbf{H}^T \mathbf{C}^{-1} \mathbf{H} \right)^{-1} \mathbf{H}^T \mathbf{C}^{-1} \mathbf{x} \right\}^T \boldsymbol{\theta}_1$$

$\boldsymbol{\theta}_1$  的MVU估计为：  $\hat{\boldsymbol{\theta}}_1 = \left( \mathbf{H}^T \mathbf{C}^{-1} \mathbf{H} \right)^{-1} \mathbf{H}^T \mathbf{C}^{-1} \mathbf{x}$

$\Rightarrow T(\mathbf{x}) = \hat{\boldsymbol{\theta}}_1^T \left( \mathbf{H}^T \mathbf{C}^{-1} \mathbf{H} \right) \boldsymbol{\theta}_1 = \hat{\boldsymbol{\theta}}_1^T \mathbf{C}_{\hat{\boldsymbol{\theta}}_1}^{-1} \boldsymbol{\theta}_1$

对比  $T(\mathbf{x}) = \mathbf{x}^T \mathbf{C}^{-1} \mathbf{s}$

MVU    协方差阵    真值

相同思路：

**“先估计，再检测”**

——估计与检测间联系

——检测理论中广泛应用



# 三、二元通信

二元通信信号检测问题：

$$H_0 : x[n] = s_0[n] + w[n], \quad n = 0, 1, \dots, N-1$$

$$H_1 : x[n] = s_1[n] + w[n], \quad n = 0, 1, \dots, N-1$$

其中信号  $s_0[n], s_1[n]$  假定是已知的， $w[n]$  是均值为零、方差为  $\sigma^2$  的高斯白噪声。如何使错误概率最小化？

为使错误概率最小

$$\frac{p(\mathbf{x} | H_1)}{p(\mathbf{x} | H_0)} > \frac{P(H_0)}{P(H_1)} = \gamma \quad \text{时, 判 } H_1$$

最小错误概率  
判决准则

若先验概率相同

$$p(\mathbf{x} | H_1) > p(\mathbf{x} | H_0)$$

最大似然判  
决准则

$$p(\mathbf{x} | H_i) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - s_i[n])^2 \right\}$$

我们判使

$$D_i^2 = \sum_{n=0}^{N-1} (x[n] - s_i[n])^2 = \|\mathbf{x} - \mathbf{s}_i\|^2$$

✓ 最小距离接收机  
✓ 最小距离分类器 (模式识别)

最小的假设  $H_i$  成立

$$D_i^2 = \sum_{n=0}^{N-1} x^2[n] + \sum_{n=0}^{N-1} s_i^2[n] - 2 \sum_{n=0}^{N-1} x[n] s_i[n]$$

➡  $T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \sum_{n=0}^{N-1} s_i^2[n]$

$\mathcal{E}_i$

$$T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \mathcal{E}_i$$

—— 匹配滤波的思想  
—— 与谁匹配得好就判给谁

## ● 二元通信的性能

错误概率

$$\begin{aligned}P_e &= \Pr\{\text{判}H_0, H_1\text{为真}\} + \Pr\{\text{判}H_1, H_0\text{为真}\} \\&= P(H_0, H_1) + P(H_1, H_0) \\&= P(H_0 | H_1)P(H_1) + P(H_1 | H_0)P(H_0)\end{aligned}$$

若先验概率相同

$$\begin{aligned}P_e &= \frac{1}{2}\{P(H_0 | H_1) + P(H_1 | H_0)\} \\&= \frac{1}{2}\{\Pr(T_0(\mathbf{x}) - T_1(\mathbf{x}) > 0 | H_1) + \Pr(T_1(\mathbf{x}) - T_0(\mathbf{x}) > 0 | H_0)\}\end{aligned}$$

令  $T(\mathbf{x}) = T_1(\mathbf{x}) - T_0(\mathbf{x})$

$$P_e = \frac{1}{2}\{\Pr(T(\mathbf{x}) < 0 | H_1) + \Pr(T(\mathbf{x}) > 0 | H_0)\}$$

$$T(\mathbf{x}) = T_1(\mathbf{x}) - T_0(\mathbf{x})$$

$$= \left\{ \sum_{n=0}^{N-1} x[n] s_1[n] - \frac{1}{2} \sum_{n=0}^{N-1} s_1^2[n] \right\} - \left\{ \sum_{n=0}^{N-1} x[n] s_0[n] - \frac{1}{2} \sum_{n=0}^{N-1} s_0^2[n] \right\}$$

$$= \sum_{n=0}^{N-1} x[n] (s_1[n] - s_0[n]) - \frac{1}{2} \left( \sum_{n=0}^{N-1} s_1^2[n] - \sum_{n=0}^{N-1} s_0^2[n] \right)$$

• 在  $H_0$  假设下

$$E\{T(\mathbf{x}) | H_0\} = E\left\{ \sum_{n=0}^{N-1} (s_0[n] + w[n]) (s_1[n] - s_0[n]) - \frac{1}{2} \left( \sum_{n=0}^{N-1} s_1^2[n] - \sum_{n=0}^{N-1} s_0^2[n] \right) \right\}$$

$$= -\frac{1}{2} \sum_{n=0}^{N-1} (s_1[n] - s_0[n])^2 = -\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2$$

$$\text{var}\{T(\mathbf{x}) | H_0\} = \text{var}\left\{ \sum_{n=0}^{N-1} (s_0[n] + w[n]) (s_1[n] - s_0[n]) - \frac{1}{2} \left( \sum_{n=0}^{N-1} s_1^2[n] - \sum_{n=0}^{N-1} s_0^2[n] \right) \right\}$$

$$= \text{var}\left\{ \sum_{n=0}^{N-1} w[n] (s_1[n] - s_0[n]) \right\} = \sum_{n=0}^{N-1} (s_1[n] - s_0[n])^2 \text{var}(w[n])$$

$$= \sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2$$

- 在  $H_1$  假设下

$$\begin{aligned} E\{T(\mathbf{x}) | H_1\} &= \frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2 \\ \text{var}\{T(\mathbf{x}) | H_1\} &= \sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2 \end{aligned} \quad \Rightarrow \quad T(\mathbf{x}) \sim \begin{cases} N\left(-\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2, \sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2\right), & H_0 \\ N\left(\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2, \sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2\right), & H_1 \end{cases}$$

因此，错误概率为：

$$\begin{aligned} P_e &= \frac{1}{2} \left\{ \Pr(T(\mathbf{x}) < 0 | H_1) + \Pr(T(\mathbf{x}) > 0 | H_0) \right\} = \frac{1}{2} \left\{ 1 - \Pr(T(\mathbf{x}) > 0 | H_1) + \Pr(T(\mathbf{x}) > 0 | H_0) \right\} \\ &= \frac{1}{2} Q\left(\frac{\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2}{\sqrt{\sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2}}\right) + \frac{1}{2} Q\left(\frac{\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2}{\sqrt{\sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2}}\right) = Q\left(\frac{\frac{1}{2} \|\mathbf{s}_1 - \mathbf{s}_0\|^2}{\sqrt{\sigma^2 \|\mathbf{s}_1 - \mathbf{s}_0\|^2}}\right) = Q\left(\frac{1}{2} \sqrt{\frac{\|\mathbf{s}_1 - \mathbf{s}_0\|^2}{\sigma^2}}\right) \end{aligned}$$

$$\begin{aligned} \|\mathbf{s}_1 - \mathbf{s}_0\|^2 &= (\mathbf{s}_1 - \mathbf{s}_0)^T (\mathbf{s}_1 - \mathbf{s}_0) \\ &= \underline{\mathbf{s}_1^T \mathbf{s}_1 + \mathbf{s}_0^T \mathbf{s}_0 - 2\mathbf{s}_1^T \mathbf{s}_0} \end{aligned}$$

$$2\bar{\varepsilon} \quad \text{平均信号能量} \quad \bar{\varepsilon} = (\mathbf{s}_1^T \mathbf{s}_1 + \mathbf{s}_0^T \mathbf{s}_0) / 2$$

$$= 2\bar{\varepsilon} (1 - \rho_s) \quad \xrightarrow{\hspace{10em}} \quad P_e = Q\left(\sqrt{\frac{\bar{\varepsilon} (1 - \rho_s)}{2\sigma^2}}\right)$$

$$\text{信号相关系数} \quad \rho_s = \frac{\mathbf{s}_1^T \mathbf{s}_0}{(\mathbf{s}_1^T \mathbf{s}_1 + \mathbf{s}_0^T \mathbf{s}_0) / 2}$$

$$P_e = Q\left(\sqrt{\frac{\bar{\varepsilon}(1-\rho_s)}{2\sigma^2}}\right), \rho_s = \frac{\mathbf{s}_1^T \mathbf{s}_0}{(\mathbf{s}_1^T \mathbf{s}_1 + \mathbf{s}_0^T \mathbf{s}_0)/2}$$

- 信号相关系数越小，越易区分不同信号，错误概率越小
- 在信号功率一定情况下，为使  $P_e$  最小，应尽量减小相关系数

### ➤ 相移键控(PSK)

$$s_0[n] = A \cos(2\pi f_0 n), \quad n = 0, 1, \dots, N-1$$

$$s_1[n] = -A \cos(2\pi f_0 n), \quad n = 0, 1, \dots, N-1$$

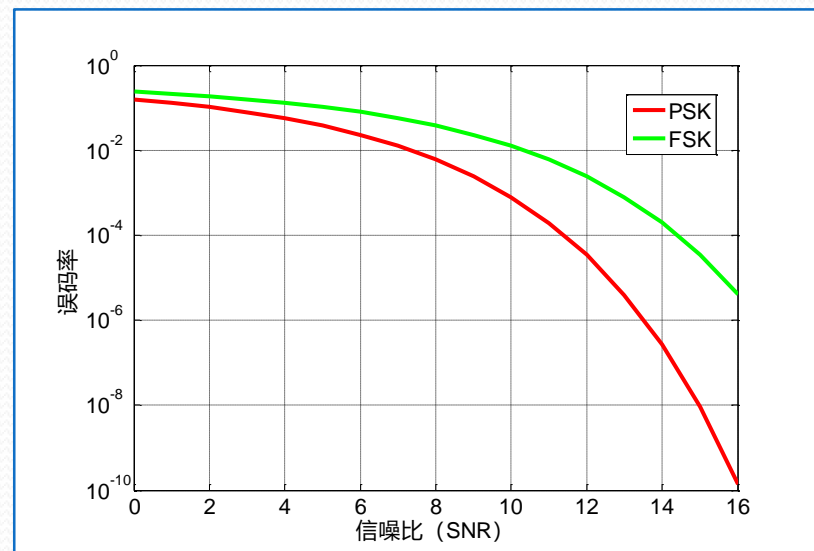
$$P_e = Q\left(\sqrt{\frac{\bar{\varepsilon}}{\sigma^2}}\right)$$

### ➤ 频移键控(FSK)

$$s_0[n] = A \cos(2\pi f_0 n), \quad n = 0, 1, \dots, N-1$$

$$s_1[n] = A \cos(2\pi f_1 n), \quad n = 0, 1, \dots, N-1$$

$$P_e = Q\left(\sqrt{\frac{\bar{\varepsilon}}{2\sigma^2}}\right)$$



## 四、多元通信

多元通信信号检测问题：

$$H_i : x[n] = s_i[n] + w[n], \quad n = 0, 1, \dots, N-1$$

其中信号  $s_i[n]$  假定是已知的,  $w[n]$  是均值为零、方差为  $\sigma^2$  的高斯白噪声。如何使错误概率最小化？

为使错误概率最小

$$\max_i P(H_i | \mathbf{x})$$

最大后验概率判决准则

若先验概率相同

$$\max_i P(\mathbf{x} | H_i)$$

最大似然判决准则

$$p(\mathbf{x} | H_i) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - s_i[n])^2 \right\}$$

我们判使  $D_i^2 = \sum_{n=0}^{N-1} (x[n] - s_i[n])^2$  最小的假设  $H_i$  成立

$$D_i^2 = \sum_{n=0}^{N-1} x^2[n] + \sum_{n=0}^{N-1} s_i^2[n] - 2 \sum_{n=0}^{N-1} x[n] s_i[n]$$

➡

$$T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \sum_{n=0}^{N-1} s_i^2[n]$$

$$T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \varepsilon_i$$

当各信号能量相等时，有

$$T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \varepsilon$$



## ● 错误概率

$$P_e = \sum_{j=0}^{M-1} \sum_{\substack{i=0 \\ i \neq j}}^{M-1} P(H_i, H_j) = \sum_{j=0}^{M-1} \sum_{\substack{i=0 \\ i \neq j}}^{M-1} P(H_i | H_j) P(H_j)$$

当先验概率相同时，有

$$\begin{aligned} P_e &= \frac{1}{M} \sum_{j=0}^{M-1} \sum_{\substack{i=0 \\ i \neq j}}^{M-1} P(H_i | H_j) \\ &= \frac{1}{M} \sum_{j=0}^{M-1} \Pr(T_j < \max\{T_0, \dots, T_{j-1}, T_{j+1}, \dots, T_{M-1}\} | H_j) \quad T_j(\mathbf{x}) \text{ 简记为 } T_j \\ &= \Pr(T_j < \max\{T_0, \dots, T_{j-1}, T_{j+1}, \dots, T_{M-1}\} | H_j) \\ &= \Pr(T_0 < \max\{T_1, T_2, \dots, T_{M-1}\} | H_0) \\ &= 1 - \Pr(\max\{T_1, T_2, \dots, T_{M-1}\} < T_0 | H_0) \\ &= 1 - \Pr(T_1 < T_0, T_2 < T_0, \dots, T_{M-1} < T_0 | H_0) \\ &= 1 - \int_{-\infty}^{+\infty} \Pr(T_1 < t, T_2 < t, \dots, T_{M-1} < t | T_0 = t, H_0) p_{T_0}(t) dt \end{aligned}$$

## ● 一种特例——若信号是正交的

$$\text{cov}(T_i(\mathbf{x}), T_j(\mathbf{x}) | H_l) = E\left\{\left(T_i(\mathbf{x}) - E(T_i(\mathbf{x}))\right)\left(T_j(\mathbf{x}) - E(T_j(\mathbf{x}))\right) | H_l\right\}$$

$$\begin{aligned} T_i(\mathbf{x}) = \sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \varepsilon & \quad \Rightarrow \quad E\{T_i(\mathbf{x}) | H_l\} = E\left(\sum_{n=0}^{N-1} x[n] s_i[n] - \frac{1}{2} \varepsilon | H_l\right) \\ & = E\left(\sum_{n=0}^{N-1} (s_l[n] + w[n]) s_i[n] - \frac{1}{2} \varepsilon | H_l\right) \\ & = \sum_{n=0}^{N-1} s_l[n] s_i[n] - \frac{1}{2} \varepsilon \end{aligned}$$

$$\Rightarrow \{T_i(\mathbf{x}) - E(T_i(\mathbf{x}))\} | H_l = \sum_{n=0}^{N-1} (s_l[n] + w[n]) s_i[n] - \sum_{n=0}^{N-1} s_l[n] s_i[n] = \sum_{n=0}^{N-1} w[n] s_i[n]$$

$$\begin{aligned} \Rightarrow \text{cov}(T_i(\mathbf{x}), T_j(\mathbf{x}) | H_l) & = E\left(\sum_{n=0}^{N-1} w[n] s_i[n] \sum_{m=0}^{N-1} w[m] s_j[m]\right) \\ & = E\left(\sum_{n=0}^{N-1} \sum_{m=0}^{N-1} w[n] w[m] s_i[n] s_j[m]\right) \end{aligned}$$

$$\begin{aligned}
\text{cov}(T_i(\mathbf{x}), T_j(\mathbf{x}) | H_l) &= E \left( \sum_{n=0}^{N-1} \sum_{m=0}^{N-1} w[n] w[m] s_i[n] s_j[m] \right) \\
&= \sum_{n=0}^{N-1} \sum_{m=0}^{N-1} E(w[n] w[m]) s_i[n] s_j[m] \\
&= \sigma^2 \sum_{n=0}^{N-1} s_i[n] s_j[n]
\end{aligned}$$

若信号是正交的，即对  $i \neq j$  有  $\sum_{n=0}^{N-1} s_i[n] s_j[n] = 0$ ，此时

$$\text{cov}(T_i(\mathbf{x}), T_j(\mathbf{x}) | H_l) = 0$$

这说明  $T_i(\mathbf{x}), T_j(\mathbf{x})$  不相关。又由于  $T_i(\mathbf{x})$  是高斯的，因此意味着  $T_i(\mathbf{x}), T_j(\mathbf{x})$  **相互独立**


$$P_e = 1 - \int_{-\infty}^{+\infty} \Pr(T_1 < t, T_2 < t, \dots, T_{M-1} < t | T_0 = t, H_0) p_{T_0}(t) dt$$

$$P_e = 1 - \int_{-\infty}^{+\infty} \prod_{j=1}^{M-1} \Pr(T_j < t | H_0) p_{T_0}(t) dt$$

在  $H_0$  条件下

$$T_j = \sum_{n=0}^{N-1} x[n]s_j[n] - \frac{1}{2}\varepsilon = \sum_{n=0}^{N-1} (s_0[n] + w[n])s_j[n] - \frac{1}{2}\varepsilon \sim \begin{cases} N\left(\frac{\varepsilon}{2}, \sigma^2\varepsilon\right), & j=0 \\ N\left(-\frac{\varepsilon}{2}, \sigma^2\varepsilon\right), & j \neq 0 \end{cases}$$

$$P_e = 1 - \int_{-\infty}^{+\infty} \prod_{j=1}^{M-1} \Pr(T_j < t | H_0) p_{T_0}(t) dt$$


$$P_e = 1 - \int_{-\infty}^{+\infty} \underbrace{\Phi^{M-1}\left(\frac{t + \varepsilon/2}{\sqrt{\sigma^2\varepsilon}}\right)}_u \frac{1}{\sqrt{2\pi\sigma^2\varepsilon}} \exp\left\{-\frac{1}{2\sigma^2\varepsilon}\left(t - \frac{\varepsilon}{2}\right)^2\right\} dt$$
$$= 1 - \int_{-\infty}^{+\infty} \Phi^{M-1}(u) \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2}\left(u - \sqrt{\frac{\varepsilon}{\sigma^2}}\right)^2\right\} du$$

- 错误概率，随信噪比  $\varepsilon / \sigma^2$  增加而减小
- 错误概率，随“元”  $M$  增加而增大——因需区分更多信号

# ● 无误码数据传输的极限

分组数据传输：以  $L$  位表示一组数据，其无误码传输的极限？

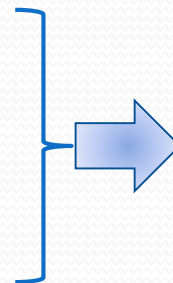
离散化后信号  
能量可表示为

$$\varepsilon = \sum_{n=0}^{N-1} s^2[n\Delta] = \frac{LPT}{\Delta}$$

$P$  : 发射功率

$T$  : 每“位”持续时间

$\Delta$  : 采样间隔



$$P_e = 1 - \int_{-\infty}^{+\infty} \Phi^{M-1}(u) \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2}\left(u - \sqrt{\frac{\varepsilon}{\sigma^2}}\right)^2\right\} du$$

$$P_e = 1 - \int_{-\infty}^{+\infty} \Phi^{M-1}(u) \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2}\left(u - \sqrt{\frac{LPT}{\Delta\sigma^2}}\right)^2\right\} du$$

可证明，当  $\frac{PT}{\Delta\sigma^2} > 2\ln 2$  时， $P_e \rightarrow 0$

$$\frac{PT}{\Delta\sigma^2} > 2\ln 2 \Rightarrow \frac{P \frac{1}{R}}{\Delta\sigma^2} > 2\ln 2 \Rightarrow R < \frac{P}{2\sigma^2 \Delta \ln 2} = \frac{P}{2N_0 B \Delta \ln 2} = \frac{P}{2N_0 B \frac{1}{2B} \ln 2}$$

香农信  
道容量

$$C = \lim_{B \rightarrow \infty} B \log_2 \left( 1 + \frac{P}{N_0 B} \right) = \frac{P}{N_0 \ln 2}$$

$$\longleftrightarrow = \frac{P}{N_0 \ln 2}$$

# 五、小结

- 高斯噪声中已知信号检测问题

➤ NP准则 { **匹配滤波器** (高斯白噪声) —— **匹配滤波的思想!**  
广义匹配滤波器 (高斯色噪声)

➤ 最小错误概率判决准则  $\xrightarrow{\text{先验概率相同}}$  最大似然判决准则  $\xrightarrow{\quad}$  **最小距离判决 (接收/分类/...)** { 二元通信时  
多元通信时

- 重点：** 具体应用，及与其他课程间的联系——**知识体系**