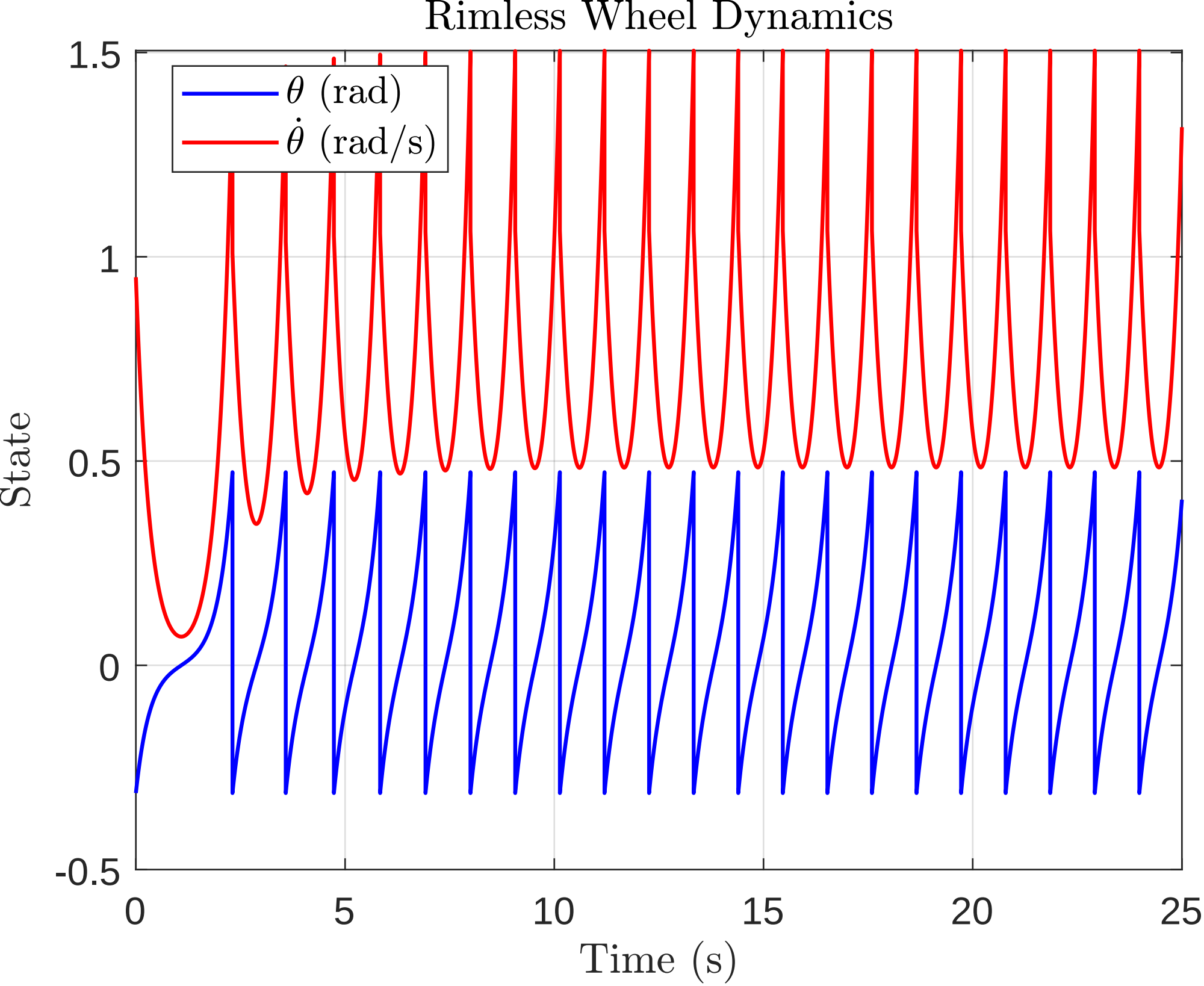
Rimless Wheel Dynamics
θ (rad)
$\dot{\theta}$ (rad/s)
State
Time (s)
1.5
1
0.5
0
-0.5
0
5
10
15
20
25