

Name: Kaushen Mahbub

ID: 16172103282

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Answer to the question no - 1(a)

Delay calculation:-

$$\text{crystal frequency} = 13.0592$$

$$\text{DS80C420 clock per MC} = 1$$

$$13.0592 / 1 = 13.0592$$

$$\therefore \text{MC} = \frac{1}{13.0592}$$

$$= 0.077 \text{ } \mu\text{s}$$

```
#include <reg51.h>
```

```
#define LINK P2;
```

```
sbit sw = P2^6
```

```
void Timedelay(void);
```

```
void main(void)
```

```
{  
    unsigned char i;
```

NAME: KAUSHAL MANUB

ID: 16172103280

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```
while (1)
{
    sw = 1;
    if (sw == 0)
    {
        blink = ~blink;
        for (j=0; j<30; j++)
        {
            timedelay();
        }
    }
    else
    {
        blink = ~blink;
        for (j=0; j<26; j++)
        {
            timedelay();
        }
    }
}
```

Name: Kawsar Mahbub  
ID: 16172103282

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```
void timedelay (void)
```

```
{
```

```
    TMOD = 0x10;
```

```
    TL1 = 0xBA;
```

```
    TH1 = 0xFE
```

```
    TR1 = 1;
```

```
    while (TF1 == 0)
```

```
    {
```

```
        TR1 = 0;
```

```
        TF1 = 0;
```

```
    }
```

```
}
```

FEBA = 65210 in dec

$65536 - 65210 = 326$

$326 \times 0.077 = 25$

$30 \times 25 = 750 \text{ ms}$

$26 \times 25 = 650 \text{ ms}$

Name: Kawsheer Mahbub

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Answer to the question no-1(b)

```
#include <reg51.h>
```

```
void main(void)
```

```
{
```

```
    unsigned char mydata[] = {0x35, 0x65  
                                , 0x5F, 0x57H, 0xE7};
```

```
    unsigned char sum=0;
```

```
    unsigned char x;
```

```
    unsigned char checksumbyte;
```

```
    for (x=0; x<5; x++)
```

```
    {
```

```
        sum = sum + mydata[x];
```

```
    }
```

```
    checksumbyte = ~sum + 1;
```

```
    checksumbyte = checksumbyte + sum;
```

```
    if (checksumbyte == 0)
```

```
    {
```

```
        P1 = 'G';
```

```
    }
```

```
    else
```

```
    {
```

```
        P1 = 'B';
```

```
    }
```





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For 2nd line:

$$10 + 00 + 10 + 00 + 75 + 20 + AA + 75 + A0 + AA + 7D + FA \\ + 11 + 1E + 80 + E4 + 7C + 2B + 7C + 4F = 800$$

After dropping the carry = 00

After 2's complement = 00

it didn't match with checksum  
now,

$$800 + 03 = 803$$

After dropping the carry we did not  
get 00 so data are corrupted.

For 3rd line:

$$07 + 00 + 20 + 00 + DB + FE + DE + FF + DD + FG \\ + 22 = 5D0$$

After dropping the carry = D0

" 2's complement = 30

it didn't match with checksum

Name: Kawsheer Mahbub

ID: 16172103282

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now

$$500 + 45 = 545$$

After dropping the carry we did not get 00. so data are corrupted.

Name: Kawsar Mahbub

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ID: 16172103282

Answer to the question no-2(b)

```
#include <reg51.h>
```

```
void main(void)
```

```
{
```

```
    A = 5;
```

```
    R1 = 0;
```

```
    unsigned char bedbyte;
```

```
    unsigned char w = A;
```

```
    unsigned char z = R1;
```

```
    w = w << 0x0F;
```

```
    w = w << 4;
```

```
    z = z << 0x0F;
```

```
    bedbyte = w | z;
```

```
    R2 = bedbyte;
```

```
}
```



Name: Kawsher Mahbub

ID: 16172103282

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### Answer to the question no-3(a)

To Build a sensor based automated locker system we need 1 Arduino UNO, 1 servo motor, 1 PIR sensor and 3 led with different color.

Now first connect the PIR sensor ~~with~~<sup>to</sup> arduino's ~~pin~~ pin 2 and ~~power~~ 5V & GND pin. Then servo motor to pin 9, 5V and GND pin. Then connect ~~to~~ 3 led to 7, 8, 12.

Now if any object came around to PIR sensor lock will be open by servo and <sup>green</sup> led will be on.

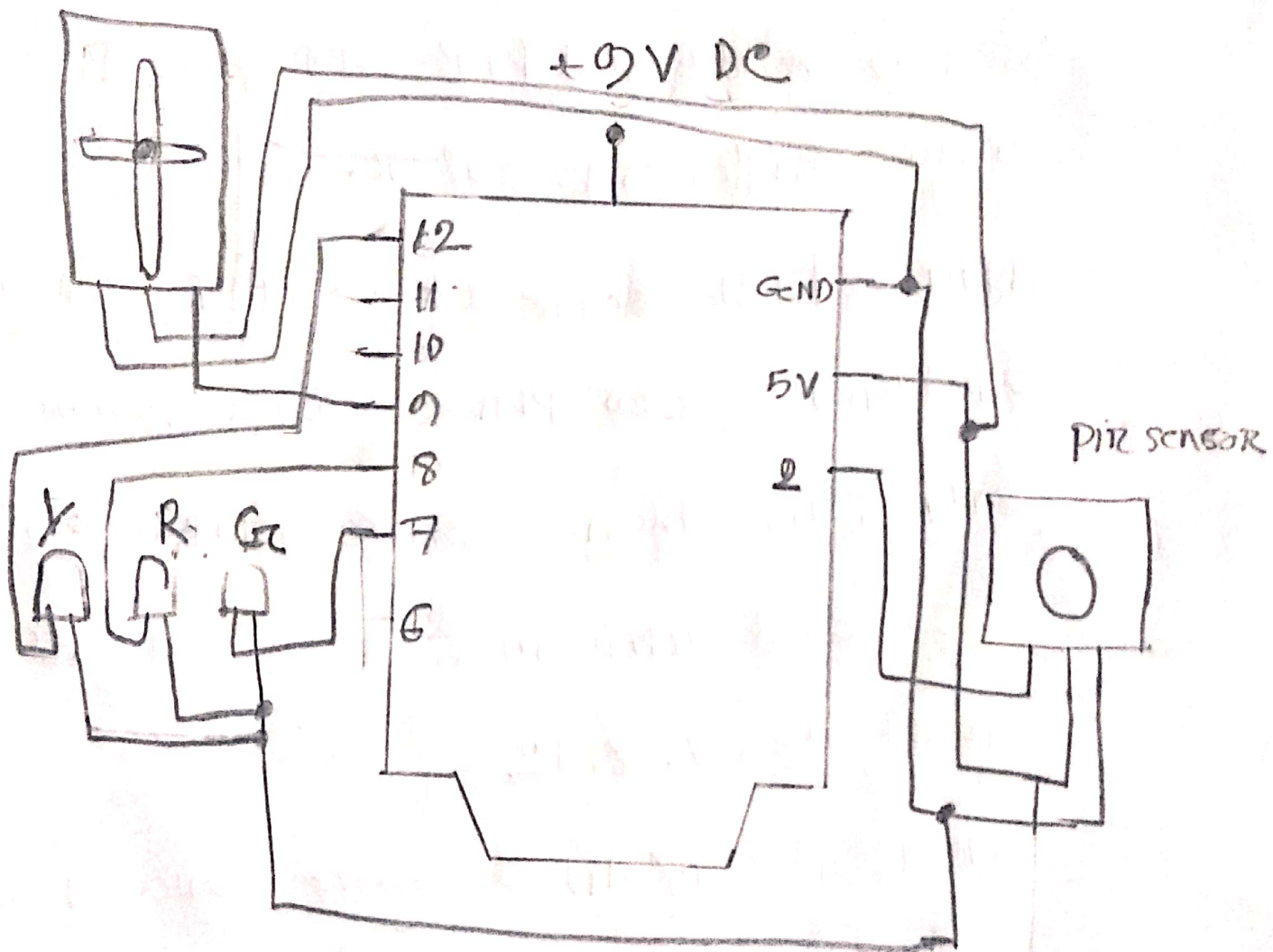
Appropriate figure and code given below.

Name: Kawsher Mahbub

ID: 16172103282

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Servo motor



Name: KAW shen Mahbub

ID: 16172103282

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```
# include <servo.h>
```

```
# define ledG 7
```

```
# define ledR 8
```

```
# define ledY 12
```

```
Servo object_servo;
```

```
int interncount = 0;
```

```
void setup()
```

```
{  pinMode(ledG, OUTPUT);
```

```
    pinMode(ledR, OUTPUT);
```

```
    pinMode(ledY, OUTPUT);
```

```
    digitalWrite(ledG, LOW);
```

```
    digitalWrite(ledR, LOW);
```

```
    digitalWrite(ledY, LOW);
```

```
    serial begin (9600);
```

```
    object_servo.attach(9);
```

```
    attachInterrupt (0, change, RISING);
```

```
    object_servo.write(0);
```

```
}
```



Name: Kawsar Mahub

ID: 16172103282

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void loop ( )

```
{  
  intercounter ++;  
  digitalWrite (ledR, HIGH);  
  digitalWrite (ledG, LOW);  
  delay (300);  
  digitalWrite (ledR, LOW);  
  digitalWrite (ledG, HIGH);  
  delay (300);  
  if (intercount == 10)  
  {  
    intercount = 0;  
    digitalWrite (ledY, LOW);  
    object-servo.write (0);  
  }  
}
```

void change ( )

```
{  
  digitalWrite (ledY, HIGH);  
  object-servo.write (90);  
}
```



Name: Kawsar Mahbub

ID: 18172103282

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Answer to the question no- 3(b)

MOV A, #DE7H

SETB P1.5

SETB P1.5

SETB P1.5

MOV R5, #8

Here: RRC A

MOV P1.5, C

DJNZ R5, Here

SETB P1.5

SETB P1.5

SETB P1.5

Name: Kaw Shon Mahbub

ID: 16172103282

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Answer to the question no-4(a)

- (a)  $T = 1/35 = 28.57 \text{ ms}$ , the period of square wave.
- (b)  $1/2$  of it for high and low portion of the pulse is  $14.285 \text{ ms}$ .
- (c)  $14.285 \div 1.085 \mu\text{s} = 13165$  and  $65536 - 13165 = 52371$  and in hex it is  $\text{CC93}$ .
- (d)  $\text{TL} = 93$  and  $\text{TH} = \text{CC}$  (hex).

MOV TMOD, # 01H

Again: MOV TLO, # 93H

MOV TH0, # 0CCH

SETB TR0

Back: JNB TFO, Back

CLR TR0

CLR P2.3

~~Sjmp Again~~

~~CLR TFO~~

CLR TFO

Sjmp Again

Name: Kawsar Mahbub  
ID: 16172103282

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Answer to the question no-4(b)

MOV R0, #40H

MOV R2, #5

CLR A

MOV R5, A

Again: ADD, A, @R0

DA A

JNE Next

INC R5

Next: INC R0

DJNZ R2, Again