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Second and Higher Order in Perturbation Theory

In general, we need to compute matrix elements of the form

$$\langle f | T [\mathcal{H}_{\underline{I}}(x_1) \dots \mathcal{H}_{\underline{I}}(x_n)] | i \rangle$$

We will make use of Wick's Theorem.

Wick's Theorem tells us how to convert time-ordered products of operators to normal ordered products of operators.

Consider our scalar field operator

$$\phi(x) = \phi^{(+)}(x) + \phi^{(-)}(x)$$

where

$$\phi^{(+)}(x) = \int \frac{d^3k}{(2\pi)^3} e^{-ik \cdot x} \hat{a}(\vec{k})$$

$$\phi^{(-)}(x) = \int \frac{d^3k}{(2\pi)^3} e^{ik \cdot x} \hat{a}^\dagger(\vec{k})$$

Let $x^0 > y^0$. Then

$$\begin{aligned} T[\phi(x)\phi(y)] &= \phi(x)\phi(y) \\ &= [\phi^{(+)}(x) + \phi^{(-)}(x)][\phi^{(+)}(y) + \phi^{(-)}(y)] \end{aligned}$$

$$= \phi^{(+)}(x) \phi^{(+)}(y) + \phi^{(+)}(x) \phi^{(-)}(y)$$

$$+ \phi^{(-)}(x) \phi^{+}(y) + \phi^{(-)}(x) \phi^{(-)}(y)$$

$$= \phi^{(+)}(x) \phi^{(+)}(y) + \phi^{(+)}(x) \phi^{(-)}(y)$$

$$+ \phi^{(-)}(y) \phi^{(+)}(x)$$

$$- \phi^{(-)}(y) \phi^{(+)}(x)$$

$$+ \phi^{(-)}(x) \phi^{(+)}(y) + \phi^{(-)}(x) \phi^{(-)}(y)$$

$$= \phi^{(+)}(x) \phi^{(+)}(y) + \phi^{(-)}(y) \phi^{(+)}(x)$$

$$+ \phi^{(-)}(x) \phi^{(+)}(y) + \phi^{(-)}(x) \phi^{(-)}(y)$$

$$+ [\phi^{(+)}(x), \phi^{(-)}(y)]$$

$$= : \phi(x) \phi(y) : + [\phi^{(+)}(x), \phi^{(-)}(y)]$$

Bzw

$$[\phi^{(+)}(x), \phi^{(-)}(y)] = \int \frac{d^3 k}{(2\pi)^3} \frac{d^3 k'}{(2\pi)^3} \frac{1}{\sqrt{2E(k)}} \frac{1}{\sqrt{2E(k')}} e^{-ik \cdot x} e^{ik' \cdot y}$$

$$\times [\hat{a}(\vec{k}), \hat{a}^\dagger(\vec{k}')]]$$

$$= \int \frac{d^3 k}{(2\pi)^3} \frac{d^3 k'}{(2\pi)^3} \frac{1}{\sqrt{2E(k)}} \frac{1}{\sqrt{2E(k')}} e^{-ik \cdot x} e^{ik' \cdot y} (2\pi i) \delta^{(3)}(\vec{k} - \vec{k}')$$

$$= \int \frac{d^3 k}{(2\pi)^3} \frac{1}{2E(k)} e^{-ik \cdot (x - y)}$$

$$= \Delta(x-y)$$

That is

$$T[\phi(x)\phi(y)] = :\phi(x)\phi(y): + \Delta(x-y)$$

For $y^0 > x^0$, we get

$$T[\phi(x)\phi(y)] = :\phi(x)\phi(y): + \Delta(y-x)$$

All of this can be succinctly written

$$T[\phi(x)\phi(y)] = :\phi(x)\phi(y): + \Delta_F(x-y)$$

Now let's generalize this to 4 fields (to see how the pattern goes).

$$T[\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)\phi_4(x_4)]$$

$$= :\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)\phi_4(x_4): + \overline{\phi_1(x_1)\phi_2(x_2)}\phi_3(x_3)\phi_4(x_4)$$

$$+ \overline{\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)}\phi_4(x_4) + \overline{\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)\phi_4(x_4)}$$

$$+ \phi_1(x_1)\overline{\phi_2(x_2)\phi_3(x_3)}\phi_4(x_4) + \dots$$

$$+ \overline{\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)}\phi_4(x_4) + \overline{\phi_1(x_1)\phi_2(x_2)\phi_3(x_3)\phi_4(x_4)} + \dots$$

$$\begin{aligned}
= & : \phi_1 \phi_2 \phi_3 \phi_4 : + \Delta_F(x_1 - x_2) : \phi_3 \phi_4 : + \dots \\
& + \Delta_F(x_1 - x_2) \Delta_F(x_3 - x_4) + \Delta_F(x_1 - x_3) \Delta_F(x_2 - x_4) \\
& + \Delta_F(x_1 - x_4) \Delta_F(x_2 - x_3)
\end{aligned}$$

When taking

$$\langle 0 | T [\phi_1 \phi_2 \phi_3 \phi_4] | 0 \rangle$$

only the fully contracted terms survive!

With this machinery, let's compute nucleon-nucleon scattering in scalar Yukawa theory.

$$\textcircled{1} \quad \psi \psi \rightarrow \psi \psi$$

$$|i\rangle = \sqrt{2E(\vec{p}_1)} \sqrt{2E(\vec{p}_2)} \hat{a}^\dagger(\vec{p}_1) \hat{a}^\dagger(\vec{p}_2) |0\rangle$$

$$|f\rangle = \sqrt{2E(\vec{p}_1)} \sqrt{2E(\vec{p}_2)} \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) |0\rangle$$

The first order that contributes to scattering is second order, and the matrix element is

$$\langle f | \frac{(-ig)^2}{2} \int d^4x d^4y T [\psi^\dagger(x) \psi(x) \phi(x) \psi^\dagger(y) \psi(y) \phi(y)] | i \rangle$$

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Let's use Wick's Theorem to evaluate the time-ordered product,

$$T [\psi^\dagger(x) \psi(x) \phi(x) \psi^\dagger(y) \psi(y) \phi(y)]$$

$$= : \psi^\dagger(x) \psi(x) \phi(x) \psi^\dagger(y) \psi(y) \phi(y) :$$

$$+ \overline{\psi^\dagger(x) \psi(x) \phi(x) \psi^\dagger(y) \psi(y)} \phi(y)$$

$$+ \psi^\dagger(x) \overline{\psi(x) \phi(x) \psi^\dagger(y) \psi(y)} \phi(y)$$

$$+ \psi^\dagger(x) \psi(x) \overline{\phi(x) \psi^\dagger(y) \psi(y) \phi(y)} :$$

$$= : \psi^\dagger(x) \psi(x) \phi(x) \psi^\dagger(y) \psi(y) \phi(y) :$$

$$+ \Delta_F^\psi(y-x) : \psi(x) \phi(x) \psi^\dagger(y) \phi(y) :$$

$$+ \Delta_F^\psi(x-y) : \psi^\dagger(x) \phi(x) \psi(y) \phi(y) :$$

$$+ \Delta_F^\phi(x-y) : \psi^\dagger(x) \psi(x) \psi^\dagger(y) \psi(y) :$$

} all 0 because there is no
spin in the initial or
final state

So, we are left to compute

$$\left(\frac{-ig}{2}\right)^2 \int d^4x d^4y \Delta_F^\phi(x-y) \langle 0 | : \psi^\dagger(x) \psi(x) \psi^\dagger(y) \psi(y) : | 0 \rangle$$

=

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$$= \frac{(-ig)^2}{2} \int d^4x d^4y \int_F^d (x-y) \sqrt{2E(\vec{p}_1)} \sqrt{2E(\vec{p}_2)} \sqrt{2E(\vec{p}_1)} \sqrt{2E(\vec{p}_2)} \\ \times \int \frac{d^3k_1}{(2\pi)^3} \frac{d^3k_2}{(2\pi)^3} \frac{d^3k_3}{(2\pi)^3} \frac{d^3k_4}{(2\pi)^3} \frac{1}{\sqrt{2E(\vec{k}_1)}} \frac{1}{\sqrt{2E(\vec{k}_2)}} \frac{1}{\sqrt{2E(\vec{k}_3)}} \frac{1}{\sqrt{2E(\vec{k}_4)}}$$

$$\langle 0 | \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) : [e^{ik_1 \cdot x} \hat{b}^\dagger(\vec{k}_1) + e^{-ik_1 \cdot x} \hat{a}(\vec{k}_1)] \\ \times [e^{ik_2 \cdot y} \hat{b}^\dagger(\vec{k}_2) + e^{-ik_2 \cdot y} \hat{a}(\vec{k}_2)] \\ \times [e^{ik_3 \cdot y} \hat{a}^\dagger(\vec{k}_3) + e^{-ik_3 \cdot y} \hat{b}^\dagger(\vec{k}_3)] \\ \times [e^{ik_4 \cdot y} \hat{a}^\dagger(\vec{k}_4) + e^{-ik_4 \cdot y} \hat{b}^\dagger(\vec{k}_4)] : \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle$$

$\hat{b}^\dagger(\vec{k}_1)$ and $\hat{b}^\dagger(\vec{k}_2)$ will annihilate to the left. They commute with $\hat{a}(\vec{q}_1)$ and $\hat{a}(\vec{q}_2)$. Then

$$\langle 0 | \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) \hat{b}^\dagger(\vec{k}_1) = 0$$

and in turn

$$\langle 0 | \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) \hat{b}^\dagger(\vec{k}_2) = 0$$

Similarly $\hat{b}(\vec{k}_3)$ and $\hat{b}(\vec{k}_4)$ annihilate to the right and commute with $\hat{a}^\dagger(\vec{q}_1)$ and $\hat{a}^\dagger(\vec{q}_2)$. Then

$$\hat{b}(\vec{k}_4) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle = 0$$

and in turn

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$$\hat{a}(\vec{k}_3) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) |0\rangle = 0$$

Therefore, the only term that survives in the normal-ordered product above is

$$\begin{aligned} & \langle 0 | \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) : \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{k}_3) \hat{a}^\dagger(\vec{k}_4) : \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle \\ &= \langle 0 | \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) \hat{a}^\dagger(\vec{k}_3) \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle \\ &= \langle 0 | \hat{a}(\vec{q}_1) \hat{a}^\dagger(\vec{k}_3) \hat{a}(\vec{q}_2) \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle \\ &+ \langle 0 | \hat{a}(\vec{q}_1) \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) \\ &= \dots \end{aligned}$$

(7a-b) >

The end result is:

$$\begin{aligned} & (2\pi)^{12} \left[\overset{(A)}{\delta^{(3)}(\vec{q}_1 - \vec{k}_3)} \overset{(B)}{\delta^{(3)}(\vec{q}_2 - \vec{k}_4)} + \delta^{(3)}(\vec{q}_1 - \vec{k}_4) \delta^{(3)}(\vec{q}_2 - \vec{k}_3) \right] \\ & \times \left[\overset{(C)}{\delta^{(3)}(\vec{q}_1 - \vec{k}_1)} \overset{(D)}{\delta^{(3)}(\vec{q}_2 - \vec{k}_2)} + \delta^{(3)}(\vec{q}_1 - \vec{k}_2) \delta^{(3)}(\vec{q}_2 - \vec{k}_1) \right] \end{aligned}$$

Then, we have

$$\begin{aligned} & \frac{(-ig)^2}{2} \int d^4x d^4y \frac{1}{F} (x-y) \sqrt{2E(\vec{q}_1)} \sqrt{2E(\vec{q}_2)} \sqrt{2E(\vec{q}_1)} \sqrt{2E(\vec{q}_2)} \\ & \times \int \frac{d^3k_1}{(2\pi)^3} \frac{d^3k_2}{(2\pi)^3} \frac{d^3k_3}{(2\pi)^3} \frac{d^3k_4}{(2\pi)^3} \frac{1}{\sqrt{2E(\vec{k}_1)}} \frac{1}{\sqrt{2E(\vec{k}_2)}} \frac{1}{\sqrt{2E(\vec{k}_3)}} \frac{1}{\sqrt{2E(\vec{k}_4)}} \\ & \times e^{-ik_1 \cdot x} e^{-ik_2 \cdot y} e^{ik_3 \cdot y} e^{ik_4 \cdot y} \end{aligned}$$

$$\begin{aligned}
& = \langle 0 | \hat{a}^\dagger(\vec{k}_3) \hat{a}(\vec{q}_1) \hat{a}(\vec{q}_2) \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle \\
& \textcircled{1} + \langle 0 | \hat{a}(\vec{q}_2) \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) \\
& + \langle 0 | \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{q}_1) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) \\
& \textcircled{2} + \langle 0 | \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1)
\end{aligned}$$

$$\begin{aligned}
& \textcircled{1} = \langle 0 | \hat{a}^\dagger(\vec{k}_4) \hat{a}(\vec{q}_2) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) \\
& + \langle 0 | \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) \\
& = \langle 0 | \hat{a}(\vec{k}_1) \hat{a}^\dagger(\vec{q}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) \\
& + \langle 0 | \hat{a}(\vec{k}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) \\
& = \langle 0 | \hat{a}^\dagger(\vec{q}_1) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) \\
& + \langle 0 | \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) \\
& + \langle 0 | \hat{a}^\dagger(\vec{q}_2) \hat{a}(\vec{k}_1) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2) \\
& = \langle 0 | \hat{a}^\dagger(\vec{q}_2) \hat{a}(\vec{k}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2)
\end{aligned}$$

$$\textcircled{A} \times \textcircled{C} = (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1)$$

$$\textcircled{A} \times \textcircled{D} + (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2)$$

$$\begin{aligned}
& \textcircled{2} \quad \langle 0 | \hat{a}(\vec{k}_1) \hat{a}^\dagger(\vec{q}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) \\
& + \langle 0 | \hat{a}(\vec{k}_1) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) \\
& = \langle 0 | \hat{a}^\dagger(\vec{q}_1) \hat{a}(\vec{k}_1) \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) \\
& + \langle 0 | \hat{a}(\vec{k}_2) \hat{a}^\dagger(\vec{q}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) \\
& + \langle 0 | \hat{a}^\dagger(\vec{q}_2) \hat{a}(\vec{k}_1) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1) \\
& = \langle 0 | \hat{a}^\dagger(\vec{q}_2) \hat{a}(\vec{k}_2) | 0 \rangle (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) \\
& + (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1)
\end{aligned}$$

$$\begin{aligned}
\textcircled{3} \times \textcircled{C} &= (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) \\
\textcircled{3} \times \textcircled{D} &+ (2\pi)^3 \delta^{(3)}(\vec{k}_1 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_3 - \vec{q}_2) (2\pi)^3 \delta^{(3)}(\vec{k}_4 - \vec{q}_1) (2\pi)^3 \delta^{(3)}(\vec{k}_2 - \vec{q}_1)
\end{aligned}$$

$$\times (\pi)^{12} \left[\delta^{(3)}(\vec{p}_1 - \vec{k}_3) \delta^{(3)}(\vec{q}_1 - \vec{k}_4) + \delta^{(3)}(\vec{q}_1 - \vec{k}_4) \delta^{(3)}(\vec{p}_2 - \vec{k}_3) \right] \\ \times \left[\delta^{(3)}(\vec{p}_1 - \vec{k}_1) \delta^{(3)}(\vec{q}_2 - \vec{k}_2) + \delta^{(3)}(\vec{q}_2 - \vec{k}_2) \delta^{(3)}(\vec{p}_2 - \vec{k}_1) \right]$$

$$= \frac{(-ig)^2}{2} \int d^4x d^4y \Delta_F^\phi(x-y) \\ \times \left\{ e^{-i\vec{p}_1 \cdot x} e^{-i\vec{p}_2 \cdot y} e^{i\vec{p}_1 \cdot x} e^{i\vec{p}_2 \cdot y} \right. \\ + e^{-i\vec{p}_2 \cdot x} e^{-i\vec{p}_1 \cdot y} e^{i\vec{p}_1 \cdot x} e^{i\vec{p}_2 \cdot y} \\ + e^{-i\vec{p}_1 \cdot x} e^{-i\vec{p}_2 \cdot y} e^{i\vec{p}_2 \cdot x} e^{i\vec{p}_1 \cdot y} \\ \left. + e^{-i\vec{p}_2 \cdot x} e^{-i\vec{p}_1 \cdot y} e^{i\vec{p}_2 \cdot x} e^{i\vec{p}_1 \cdot y} \right\}$$

$$= \frac{(-ig)^2}{2} \int d^4x d^4y \Delta_F^\phi(x-y) \\ \times \left\{ e^{-i(\vec{p}_1 - \vec{p}_1) \cdot x} e^{-i(\vec{p}_2 - \vec{p}_2) \cdot y} \right. \\ + e^{-i(\vec{p}_2 - \vec{p}_1) \cdot x} e^{-i(\vec{p}_1 - \vec{p}_2) \cdot y} \\ + e^{-i(\vec{p}_1 - \vec{p}_2) \cdot x} e^{-i(\vec{p}_2 - \vec{p}_1) \cdot y} \\ \left. + e^{-i(\vec{p}_2 - \vec{p}_2) \cdot x} e^{-i(\vec{p}_1 - \vec{p}_1) \cdot y} \right\}$$

$$= (-ig)^2 \int d^4x d^4y \Delta_F^\phi(x-y) \left\{ e^{-i(\vec{p}_1 - \vec{p}_1) \cdot x} e^{-i(\vec{p}_2 - \vec{p}_2) \cdot y} \right. \\ \left. + e^{-i(\vec{p}_2 - \vec{p}_1) \cdot x} e^{-i(\vec{p}_1 - \vec{p}_2) \cdot y} \right\}$$

The last equality is due to the fact that

$$\Delta_F^\phi(x-y) = \Delta_F^\phi(y-x)$$

Inserting

$$\Delta_F^\phi(x-y) = i \int \frac{d^4 k}{(2\pi)^4} \frac{1}{k^2 - m^2 + i\epsilon} e^{-ik \cdot (x-y)}$$

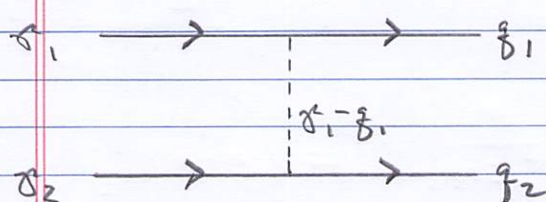
we now have

$$\begin{aligned} & (-ig)^2 i \int \frac{d^4 k}{(2\pi)^4} \frac{1}{k^2 - m^2 + i\epsilon} \\ & \times \int d^4 x d^4 y e^{-ik \cdot (x-y)} \left\{ e^{-i(x_1 - y_1) \cdot x} e^{-i(x_2 - y_2) \cdot y} + e^{-i(y_2 - x_1) \cdot x} e^{-i(x_1 - y_2) \cdot y} \right\} \\ & = (-ig)^2 i \int \frac{d^4 k}{(2\pi)^4} \frac{1}{k^2 - m^2 + i\epsilon} \\ & \times (2\pi)^8 \left[\delta^{(4)}(k + p_1 - p_2) \delta^{(4)}(k - p_2 + p_2) \right. \\ & \quad \left. + \delta^{(4)}(k + p_2 - p_1) \delta^{(4)}(k - p_1 + p_2) \right] \\ & = (-ig)^2 i (2\pi)^4 \left\{ \frac{1}{(p_1 - p_2)^2 - m^2 + i\epsilon} \delta^{(4)}[(p_1 - p_1) - p_2 + p_2] \right. \\ & \quad \left. + \frac{1}{(p_2 - p_1)^2 - m^2 + i\epsilon} \delta^{(4)}[(p_1 - p_2) - p_1 + p_2] \right\} \end{aligned}$$

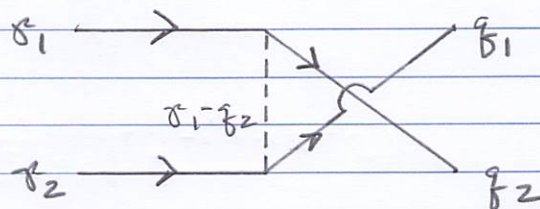
= ...

$$i(-ig)^2 \left\{ \frac{1}{(p_1 - p_1')^2 - m^2} + \frac{1}{(p_1 - p_2')^2 - m^2} \right\} (2\pi)^4 \delta^4(p_1 + p_2 - p_1' - p_2')$$

We can write down 2 Feynman Diagrams associated with each term above.



t - channel



u - channel

While Wick's Theorem helped in reducing the number of terms in our calculations of S-matrix elements, the number of terms remained daunting (imagine even higher orders in perturbation theory!).

Feynman Diagrams eliminate all of this intermediate work. What are the rules?

From our calculation of pion decay and nucleon-nucleon scattering in scalar Yukawa theory, we see that the final result for the S-matrix element can be obtained from the Feynman diagram(s) for the interaction using the following rules:

- ① For each vertex, assign a factor of $-ig$.
- ② For each internal line, assign a factor of $\frac{1}{k^2 - m^2}$.
- ③ Multiply by $(2\pi)^4 \delta^4(\dots)$, corresponding to conservation of energy.