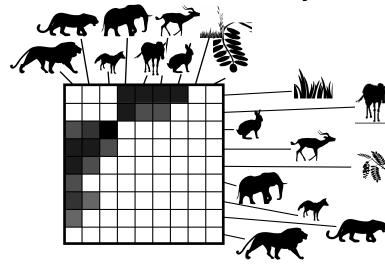
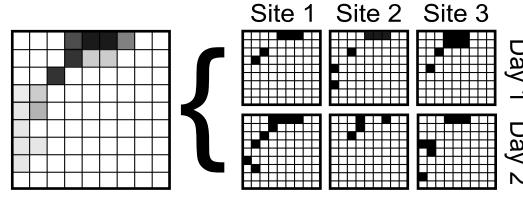


+ Interaction Uncertainty

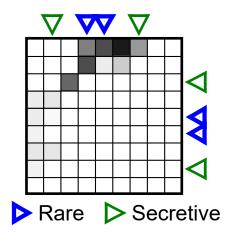




+ Process Uncertainty



+ Detection Uncertainty



Observed matrix

