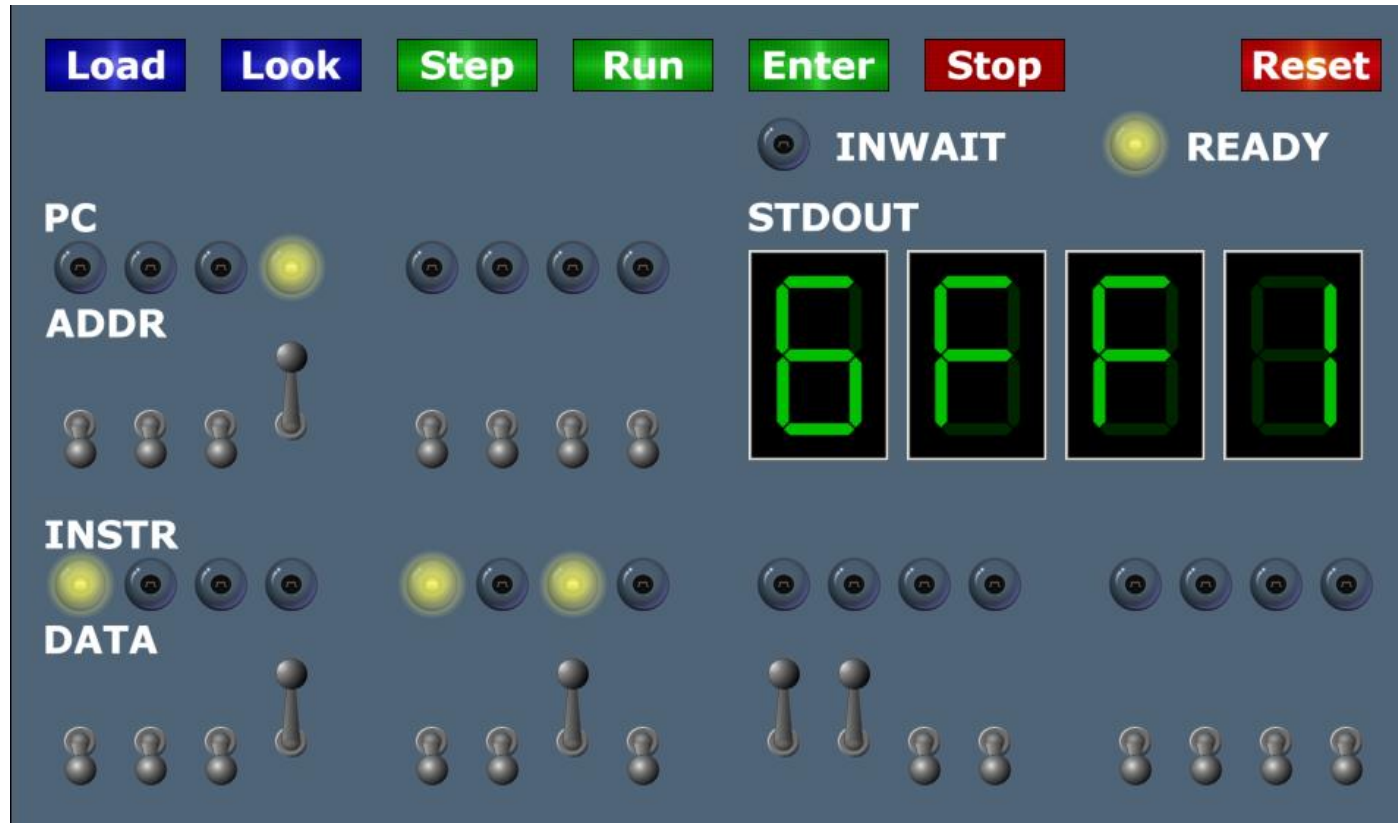


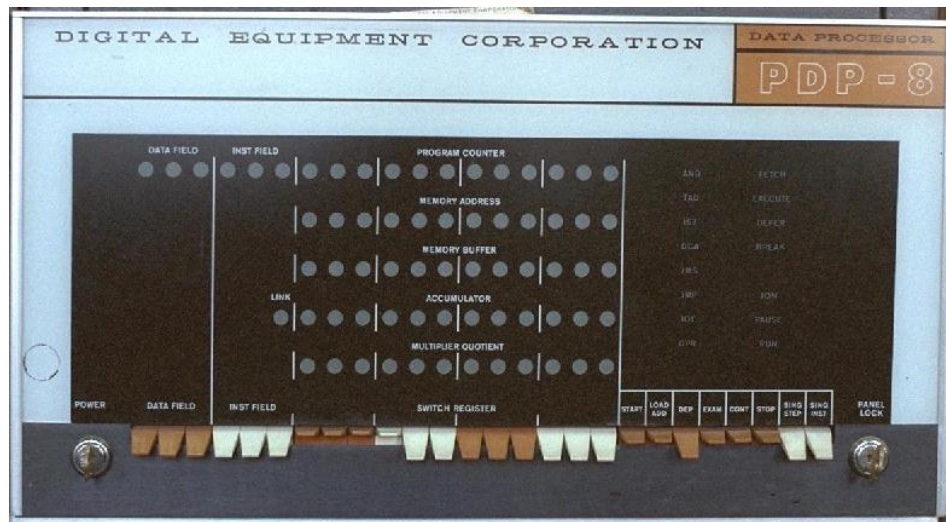
5. The TOY Machine



What is TOY?

An imaginary machine similar to:

- Ancient computers.
- Today's microprocessors.



Why Study TOY?

Machine language programming

- How do Java programs relate to computer?
- Key to understanding Java references.
- Some situations today where it is really necessary.

Computer architecture

- How does it work?
- How is a computer put together?



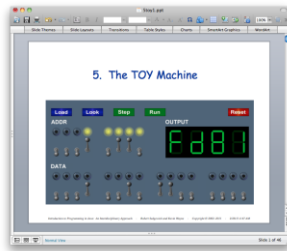
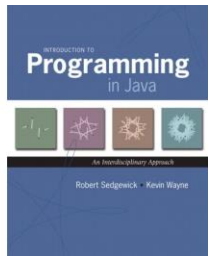
Games, Scientific
Computing, GPU (Graphics
Card) Programming

TOY machine: Optimized for simplicity, not cost or speed.

Data and Programs Are Just Bits

Each bit consists of two states:

- Switch is on or off; wire has high voltage or low voltage.



Everything in a computer is stored as bits.

- Data *and programs*
- Text, pictures, sounds, movies, programs, ...

Compilers

Compilers translate from high-level languages (like Java) to native machine instructions (bits).

```
int x = 8;  
int y = 5;  
int sum = x + y;
```

Compilation

00: 0008	8
01: 0005	5
02: 0000	0
10: 8A00	RA ← mem[00]
11: 8B01	RB ← mem[01]
12: 1CAB	RC ← RA + RB
13: 9C02	mem[02] ← RC
14: 0000	halt

	Java	TOY
Variable names	✓	✗
Function names	✓	✗
Structure	✓	✗
Types	✓	✗
Error Checking	✓	✗
*, /, %, useful libraries	✓	✗
Bits	✗	✓

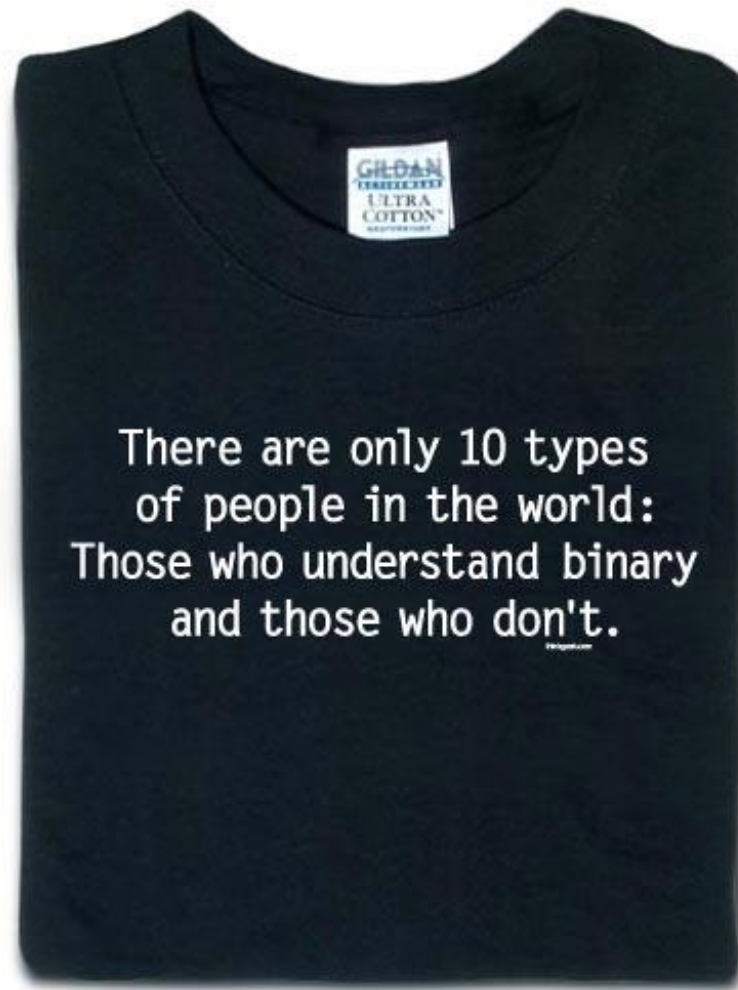
memory addresses

instructions (bits, written in hex)

assembly (human-readable mnemonics)

add.toy

Binary People



<http://www.thinkgeek.com/tshirts-apparel/unisex/frustrations/5aa9>

Inside the TOY Box

Switches: Input data and programs.

Lights: View data.

Memory:

- Stores data and programs.
- 256 16-bit "words."
- Special word for stdin / stdout.

Program counter (PC):

- An extra 8-bit register.
- Next instruction to be executed.

Registers:

- Fastest form of storage.
- Scratch space during computation.
- 16 16-bit registers.
- Register 0 is always 0.

Arithmetic-Logic Unit (ALU): Manipulate data stored in registers.

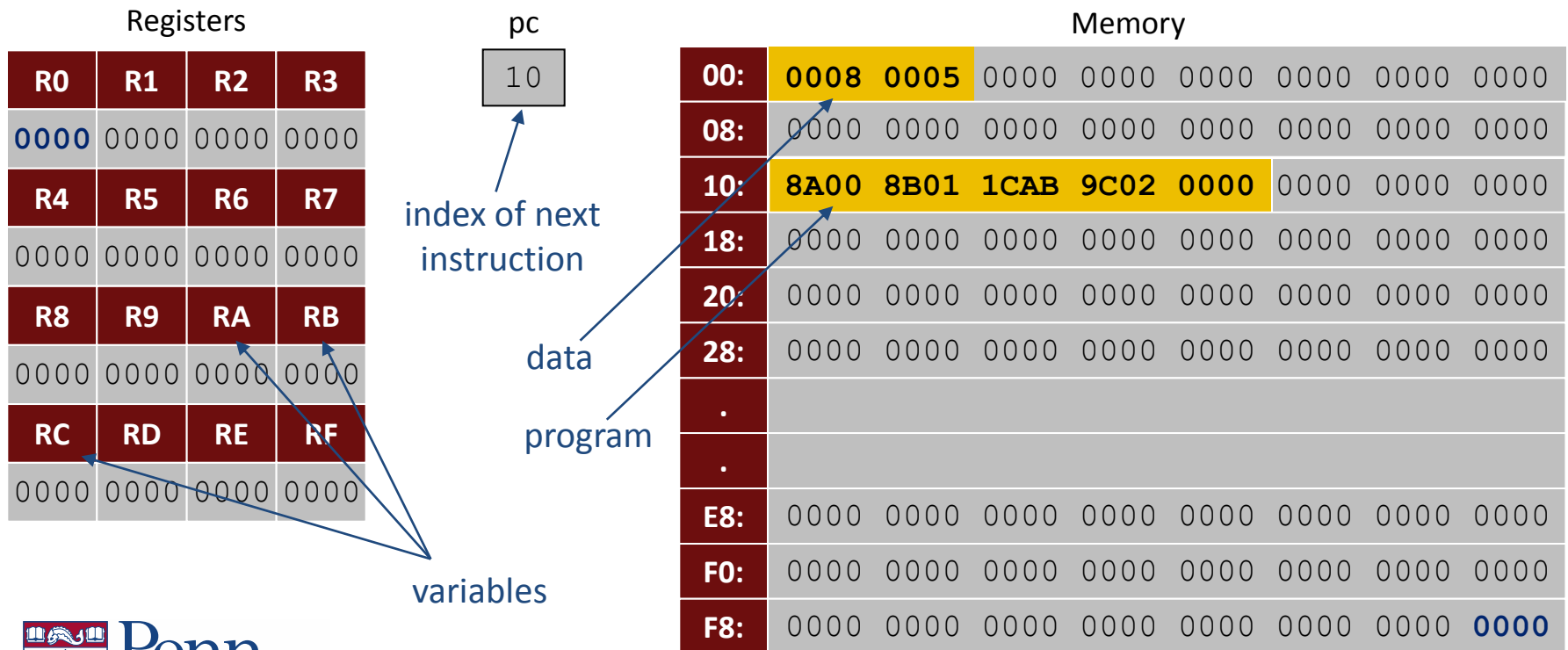
Standard input/output: Interact with outside world.



TOY Machine "Core" Dump

A **core dump** is the contents of machine at a particular place and time.

- Record of what program has done.
- Completely determines what machine will do.



A Sample Program

A sample program: Adds $0008 + 0005 = 000D$.

RA	RB	RC
0000	0000	0000

Registers

pc
10

Program Counter

00: 0008	8
01: 0005	5
02: 0000	0
10: 8A00	RA ← mem[00]
11: 8B01	RB ← mem[01]
12: 1CAB	RC ← RA + RB
13: 9C02	mem[02] ← RC
14: 0000	halt

↑
TOY memory
(program and data)

↑
add.toy
comments

A Sample Program

Program counter: The pc is initially 10, so the machine interprets 8A00 as an instruction.

RA	RB	RC	pc
0000	0000	0000	10



Index of next
instruction to execute.

00:	0008	8
01:	0005	5
02:	0000	0
10:	8A00	RA ← mem[00]
11:	8B01	RB ← mem[01]
12:	1CAB	RC ← RA + RB
13:	9C02	mem[02] ← RC
14:	0000	halt

add.toy

Load

Load [opcode 8]

- Loads the contents of some memory location into a register.
- 8A00 means "load the contents of memory cell 00 into register A."

RA	RB	RC
0000	0000	0000

pc
10

```
00: 0008    8
01: 0005    5
02: 0000    0
```

```
10: 8A00    RA ← mem[00]
11: 8B01    RB ← mem[01]
12: 1CAB    RC ← RA + RB
13: 9C02    mem[02] ← RC
14: 0000    halt
```

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0
8 ₁₆				A ₁₆				00 ₁₆							
opcode				dest d				addr							

Load

Load [opcode 8]

- Loads the contents of some memory location into a register.
- 8B00 means "load the contents of memory cell 00 into register B."

RA	RB	RC
0008	0000	0000

pc
11

```

00: 0008    8
01: 0005    5
02: 0000    0

10: 8A00    RA ← mem[00]
11: 8B01    RB ← mem[01]
12: 1CAB    RC ← RA + RB
13: 9C02    mem[02] ← RC
14: 0000    halt
  
```

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	0	0	0	1	0	1	1	0	0	0	0	0	0	0	1
8 ₁₆				B ₁₆				01 ₁₆							
opcode				dest d				addr							

Add

Add [opcode 1]

- Add contents of two registers and store sum in a third
- 1CAB means "add the contents of registers A and B and put the result in register C."

RA	RB	RC
0008	0005	0000

pc
12

00:	0008	8
01:	0005	5
02:	0000	0
10:	8A00	RA \leftarrow mem[00]
11:	8B01	RB \leftarrow mem[01]
12:	1CAB	RC \leftarrow RA + RB
13:	9C02	mem[02] \leftarrow RC
14:	0000	halt

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	1	1	1	0	0	1	0	1	0	1	0	1	1
1 ₁₆				C ₁₆				A ₁₆				B ₁₆			
opcode				dest d				source s				source t			

Store

Store [opcode 9]

- Stores the contents of some register into a memory cell.
- 9C02 means "store the contents of register C into memory cell 02."

RA	RB	RC
0008	0005	000D

pc
13

```

00: 0008    8
01: 0005    5
02: 0000    0

10: 8A00    RA ← mem[00]
11: 8B01    RB ← mem[01]
12: 1CAB    RC ← RA + RB
13: 9C02    mem[02] ← RC
14: 0000    halt
    
```

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	0	1	0	1	1	0	0	0	0	0	0	0	0	2	0
9 ₁₆				C ₁₆				02 ₁₆							
opcode				dest d				addr							

Halt

Halt [opcode 0]

- Stop the machine.

RA	RB	RC
0008	0005	000D

pc
14

```
00: 0008    8
01: 0005    5
02: 0000    0

10: 8A00    RA ← mem[00]
11: 8B01    RB ← mem[01]
12: 1CAB    RC ← RA + RB
13: 9C02    mem[02] ← RC
14: 0000    halt
```

Program and Data

Program: Sequence of 16-bit integers, interpreted one way.

Data: Sequence of 16-bit integers, interpreted other way.

Program Counter (pc): Holds memory address of the next "instruction" and determines which integers get interpreted as instructions.

16 instruction types: Changes contents of registers, memory, and pc in specified, well-defined ways.

Instructions

→	0:	halt
→	1:	add
	2:	subtract
	3:	and
	4:	xor
	5:	shift left
	6:	shift right
	7:	load address
→	8:	load
→	9:	store
	A:	load indirect
	B:	store indirect
	C:	branch zero
	D:	branch positive
	E:	jump register
	F:	jump and link

TOY Instruction Set Architecture

TOY instruction set architecture (ISA):

- Interface that specifies behavior of machine.
- 16 register, 256 words of main memory, 16-bit words.
- 16 instructions.

Each instruction consists of 16 bits:

- Bits 12-15 encode one of 16 instruction types or opcodes.
- Bits 8-11 encode destination register d.
- Bits 0-7 encode:

[Format 1] source registers s and t

← add, subtract, ...

[Format 2] 8-bit memory address or constant

← load, store, ...

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	1	0	1	1	1	0	1	0	0	0	0	0	0	1	0	0
Format 1	opcode				dest d				source s				source t			
Format 2	opcode				dest d				addr							

Interfacing with the TOY Machine

To enter a program or data:

- Set 8 memory address switches.
- Set 16 data switches.
- Press Load: data written into addressed word of memory.

To view the results of a program:

- Set 8 memory address switches.
- Press **Look**: contents of addressed word appears in lights.



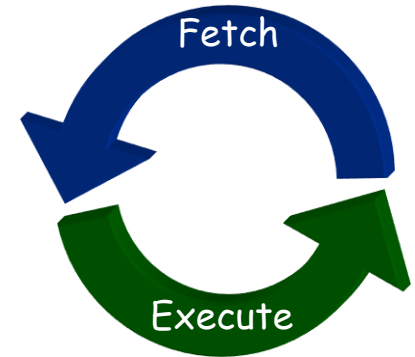
Interfacing with the TOY Machine

To execute the program:

- Set 8 memory address switches to address of first instruction.
- Press **Look** to set pc to first instruction.
- Press **Run** to repeat fetch-execute cycle until halt opcode.

Fetch-execute cycle:

- Fetch: get instruction from memory.
- Execute: update pc, move data to or from memory and registers, perform calculations.



Flow Control

Flow Control

- To harness the power of TOY, need loops and conditionals.
- Manipulate **pc** to control program flow.

```
if (boolean expression) {  
    statement 1 ;  
    statement 2 ;  
}
```

```
while (boolean expression) {  
    statement 1 ;  
    statement 2 ;  
}
```

Branch if zero [opcode C]

- Changes **pc** depending on whether value of some register is zero.
- Used to implement: **for, while, if-else**.

Branch if positive [opcode D]

- Changes **pc** depending on whether value of some register is positive.
- Used to implement: **for, while, if-else**.

An Example: Multiplication

Multiply: Given integers **a** and **b**, compute **c = a × b**.

TOY multiplication: No direct support in TOY hardware.

Brute-force multiplication algorithm:

- Initialize **c** to 0.
- Add **b** to **c**, **a** times.

```
int a = 3;  
int b = 9;  
int c = 0;  
  
while (a != 0) {  
    c = c + b;  
    a = a - 1;  
}
```

brute force multiply in Java

Issues ignored: Slow, overflow, negative numbers.

Multiply

```
0A: 0003    3 ← inputs
0B: 0009    9
0C: 0000    0 ← output

0D: 0000    0 ← constants
0E: 0001    1

10: 8A0A    RA ← mem[0A]      a = 3;
11: 8B0B    RB ← mem[0B]      b = 9;
12: 8C0D    RC ← mem[0D]      c = 0;

13: 810E    R1 ← mem[0E]      always 1

14: CA18    if (RA == 0) pc ← 18  while (a != 0) {
15: 1CCB    RC ← RC + RB          c = c + b;
16: 2AA1    RA ← RA - R1          a = a - 1;
17: C014    pc ← 14              }

18: 9C0C    mem[0C] ← RC
19: 0000    halt
```

loop

`multiply.toy`

Step-By-Step Trace

```

10: 8A0A  RA ← mem[0A]
11: 8B0B  RB ← mem[0B]
12: 8C0D  RC ← mem[0D]
13: 810E  R1 ← mem[0E]
14: CA18  if (RA == 0) pc ← 18
15: 1CCB  RC ← RC + RB
16: 2AA1  RA ← RA - R1
17: C014  pc ← 14
14: CA18  if (RA == 0) pc ← 18
15: 1CCB  RC ← RC + RB
16: 2AA1  RA ← RA - R1
17: C014  pc ← 14
14: CA18  if (RA == 0) pc ← 18
15: 1CCB  RC ← RC + RB
16: 2AA1  RA ← RA - R1
17: C014  pc ← 14
14: CA18  if (RA == 0) pc ← 18
18: 9C0C  mem[0C] ← RC
19: 0000  halt
    
```

<u>R1</u>	<u>RA</u>	<u>RB</u>	<u>RC</u>
	0003		
		0009	
			0000
0001			
			0009
	0002		
			0012
	0001		
			001B
	0000		

multiply.toy

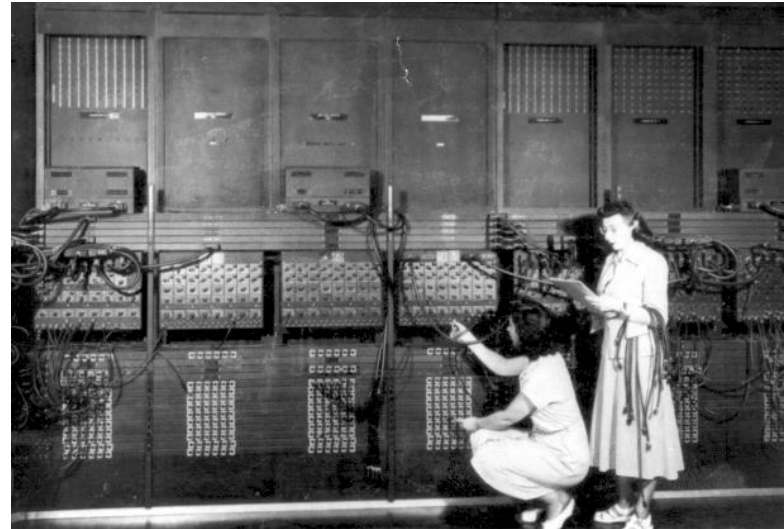
A Little History

Electronic Numerical Integrator and Calculator (ENIAC):

- First widely known general purpose electronic computer.
- Conditional jumps, programmable.
- Programming: change switches and cable connections.
- Data: enter numbers using punch cards.



John Mauchly (left) and J. Presper Eckert (right)
http://cs.swau.edu/~durkin/articles/history_computing.html



ENIAC, Ester Gerston (left), Gloria Gordon (right)
US Army photo: <http://ftp.arl.mil/ftp/historic-computers>

Standard Output

- Writing to memory location `FF` sends one word to TOY stdout.
- Ex. `9AFF` writes the integer in register `A` to stdout.

```
00: 0000    0
01: 0001    1

10: 8A00    RA ← mem[00]      a = 0
11: 8B01    RB ← mem[01]      b = 1
                                do {
12: 9AFF    write RA to stdout    print a
13: 1AAB    RA ← RA + RB          a = a + b
14: 2BAB    RB ← RA - RB          b = a - b
15: DA12    if (RA > 0) goto 12    } while (a > 0)
16: 0000    halt
```

`fibonacci.toy`

```
0000
0001
0001
0002
0003
0005
0008
000D
0015
0022
0037
0059
0090
00E9
0179
0262
03DB
063D
0A18
1055
1A6D
2AC2
452F
6FF1
```

Standard Input

- Loading from memory address `FF` loads one word from `stdin`.
- Ex. `8AFF` reads an integer from `stdin` and puts it in register `A`.

Ex: read in a sequence of integers and print their sum.

- In Java, stop reading when EOF.
- In TOY, stop reading when user enters `0000`.

```
while (!StdIn.isEmpty()) {  
    a = StdIn.readInt();  
    sum = sum + a;  
}  
StdOut.println(sum);
```

00: 0000	0
10: 8C00	RC ← mem[00]
11: 8AFF	read RA from stdin
12: CA15	if (RA == 0) pc ← 15
13: 1CCA	RC ← RC + RA
14: C011	pc ← 11
15: 9CFF	write RC
16: 0000	halt

00AE
0046
0003
0000
00F7

An Efficient Multiplication Algorithm

Inefficient multiply:

- Brute force multiplication algorithm loops a times.
- In worst case, 65,535 additions!

"Grade-school" multiplication:

- Always 16 additions to multiply 16-bit integers.

[illegible]

[illegible]

Binary Multiplication

Grade school binary multiplication algorithm to compute $c = a \times b$.

- Initialize $c = 0$.
- Loop over i bits of b .
- if $b_i = 0$, do nothing
- if $b_i = 1$, shift a left i bits and add to c

$b_i = i^{\text{th}}$ bit of b

1 0 1 1	a
* 1 1 0 1	b
1 0 1 1	$a \ll 0$
0 0 0 0	
1 0 1 1	$a \ll 2$
1 0 1 1	$a \ll 3$
1 0 0 0 1 1 1 1	c

Implement with built-in TOY shift instructions.

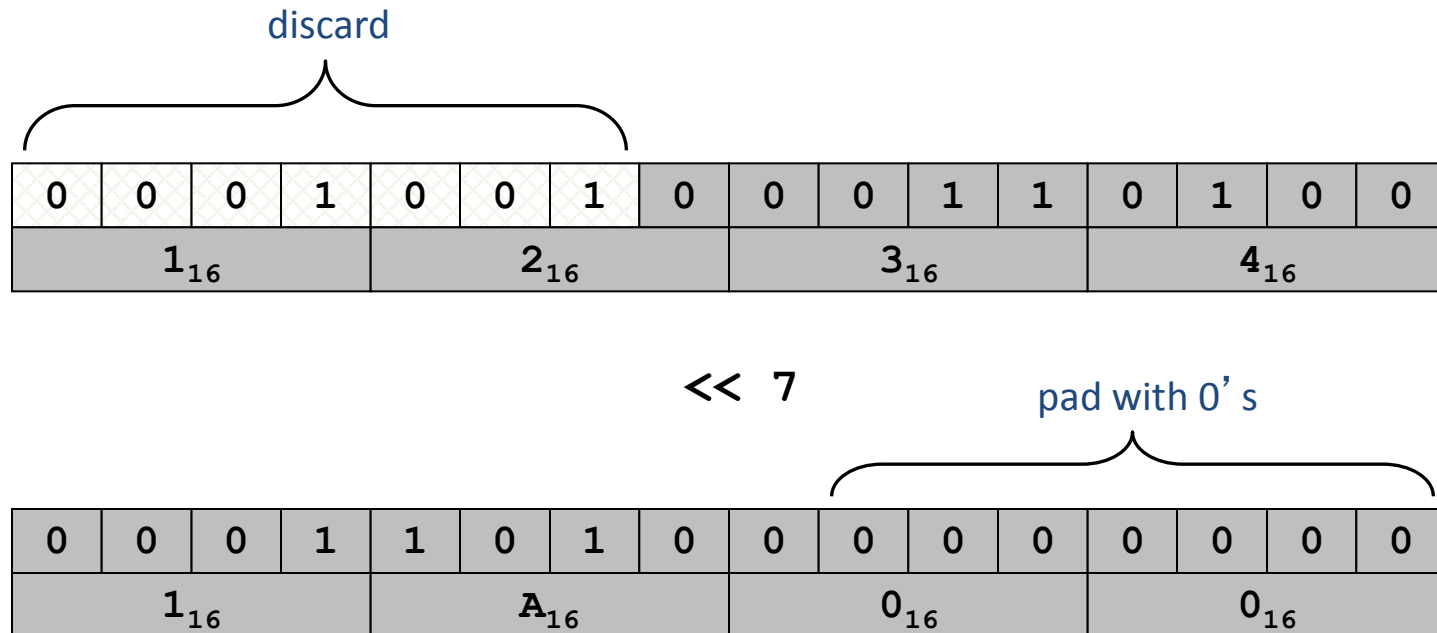
```
int c = 0;
for (int i = 15; i >= 0; i--)
    if (((b >> i) & 1) == 1)
        c = c + (a << i);
```

$b_i = i^{\text{th}}$ bit of b

Shift Left

Shift Left [opcode 5]

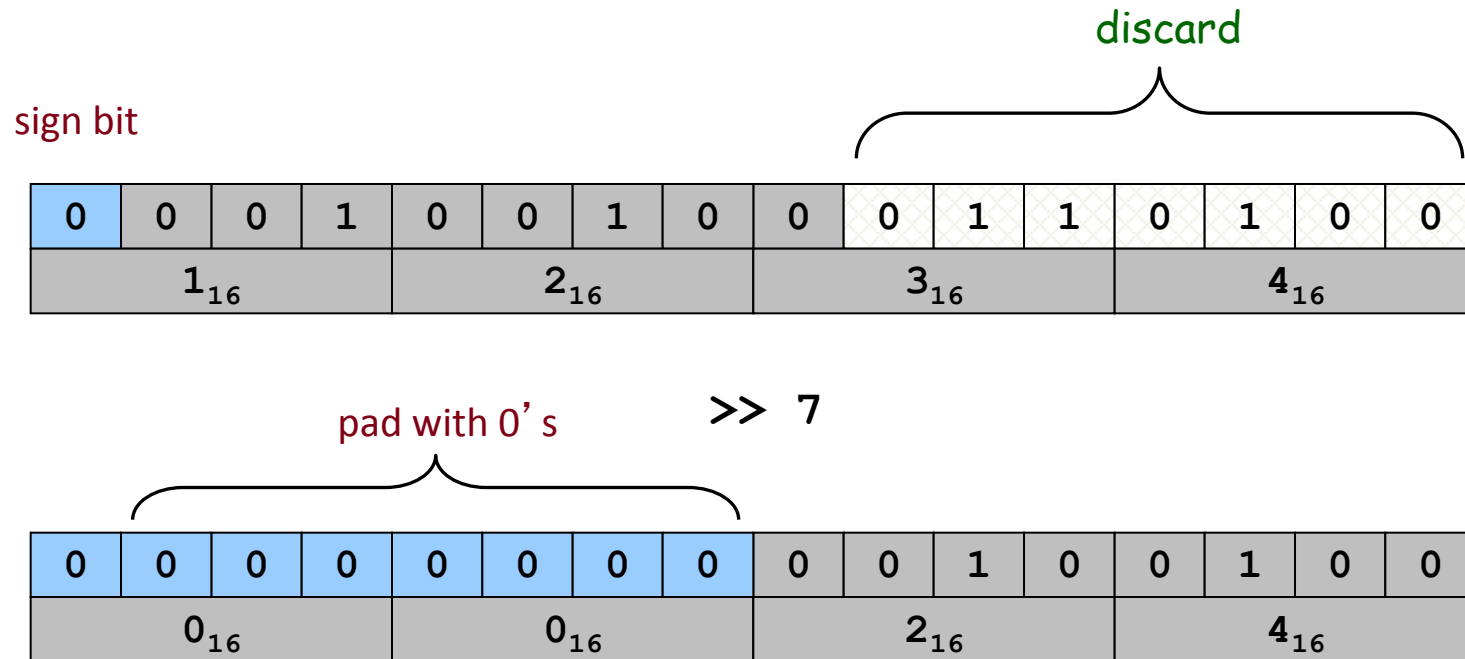
- Move bits to the left, padding with zeros as needed.
 - $1234_{16} \ll 7_{16} = 1A00_{16}$



Shift Right

Shift Right [opcode 6]

- Move bits to the right, padding with sign bit as needed.
 - $1234_{16} \gg 7_{16} = 0024_{16}$

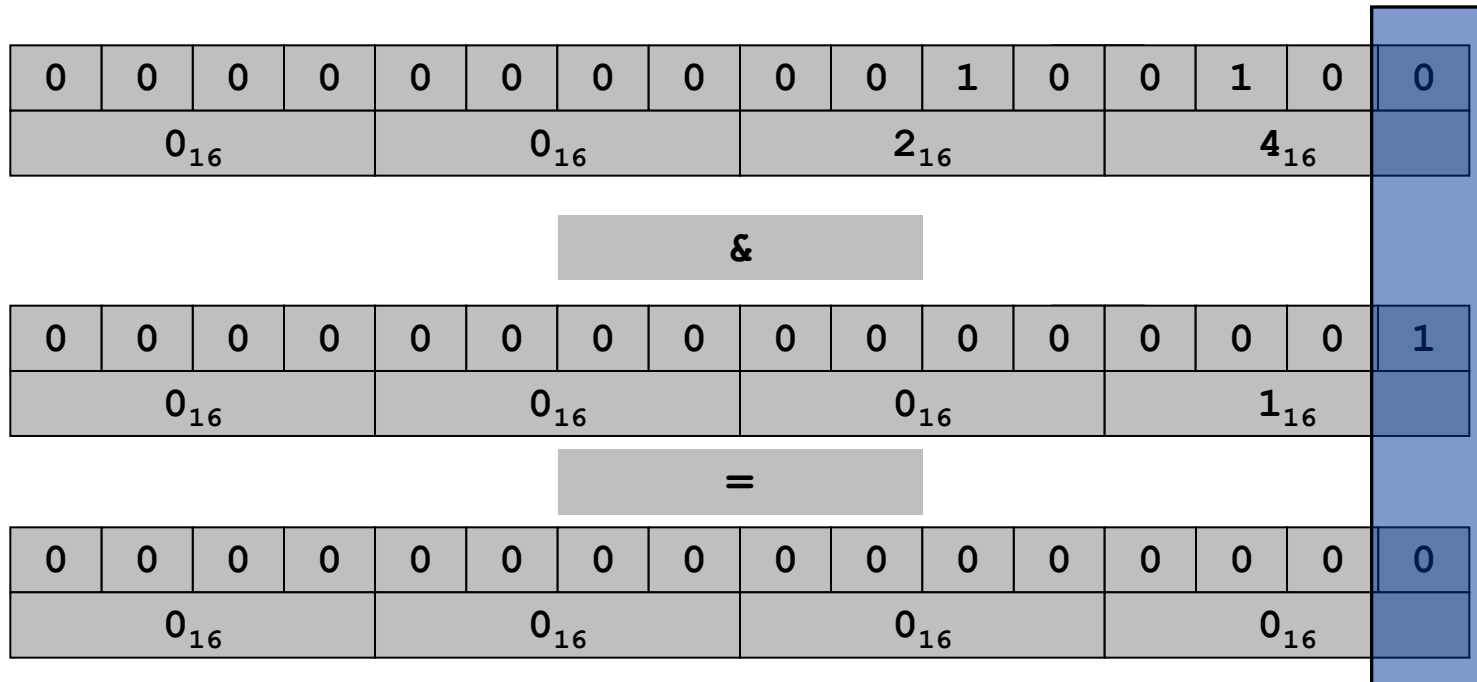


Bitwise AND

Logical AND [opcode B]

- Logic operations are BITWISE.
 - $002416 \ \& \ 000116 = 000016$

x	y	&
0	0	0
0	1	0
1	0	0
1	1	1



Shifting and Masking

Shift and mask: get the 7th bit of 1234

- Compute $1234_{16} \gg 7_{16} = 0024_{16}$
- Compute $0024_{16} \& 1_{16} = 0_{16}$

0	0	0	1	0	0	1	0	0	0	1	1	0	1	0	0
1_{16}				2_{16}				3_{16}				4_{16}			

$\gg 7$

0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
0_{16}				0_{16}				2_{16}				4_{16}			

$\&$

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1
0_{16}				0_{16}				0_{16}				1_{16}			

$=$

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0_{16}				0_{16}				0_{16}				0_{16}			

Binary Multiplication

0A:	0003	3	←	inputs
0B:	0009	9	←	
0C:	0000	0	←	output
0D:	0000	0		
0E:	0001	1	←	constants
0F:	0010	16		

10:	8A0A	RA ← mem[0A]	a	
11:	8B0B	RB ← mem[0B]	b	
12:	8C0D	RC ← mem[0D]	c = 0	
13:	810E	R1 ← mem[0E]	always 1	
14:	820F	R2 ← mem[0F]	i = 16	← 16 bit words

loop

branch

```

do {
15: 2221  R2 ← R2 - R1      i--
16: 53A2  R3 ← RA << R2    a << i
17: 64B2  R4 ← RB >> R2    b >> i
18: 3441  R4 ← R4 & R1      bi = ith bit of b
19: C41B  if (R4 == 0) goto 1B    if bi is 1
1A: 1CC3  RC ← RC + R3          add a << i to sum
1B: D215  if (R2 > 0) goto 15    } while (i > 0);

```

1C: 9C0C mem[0C] ← RC

multiply-fast.toy



Bitwise XOR

Bitwise XOR [opcode 4]

- Logic operations are BITWISE.

$$- 1234_{16} \wedge FAD2_{16} = E8E6_{16}$$

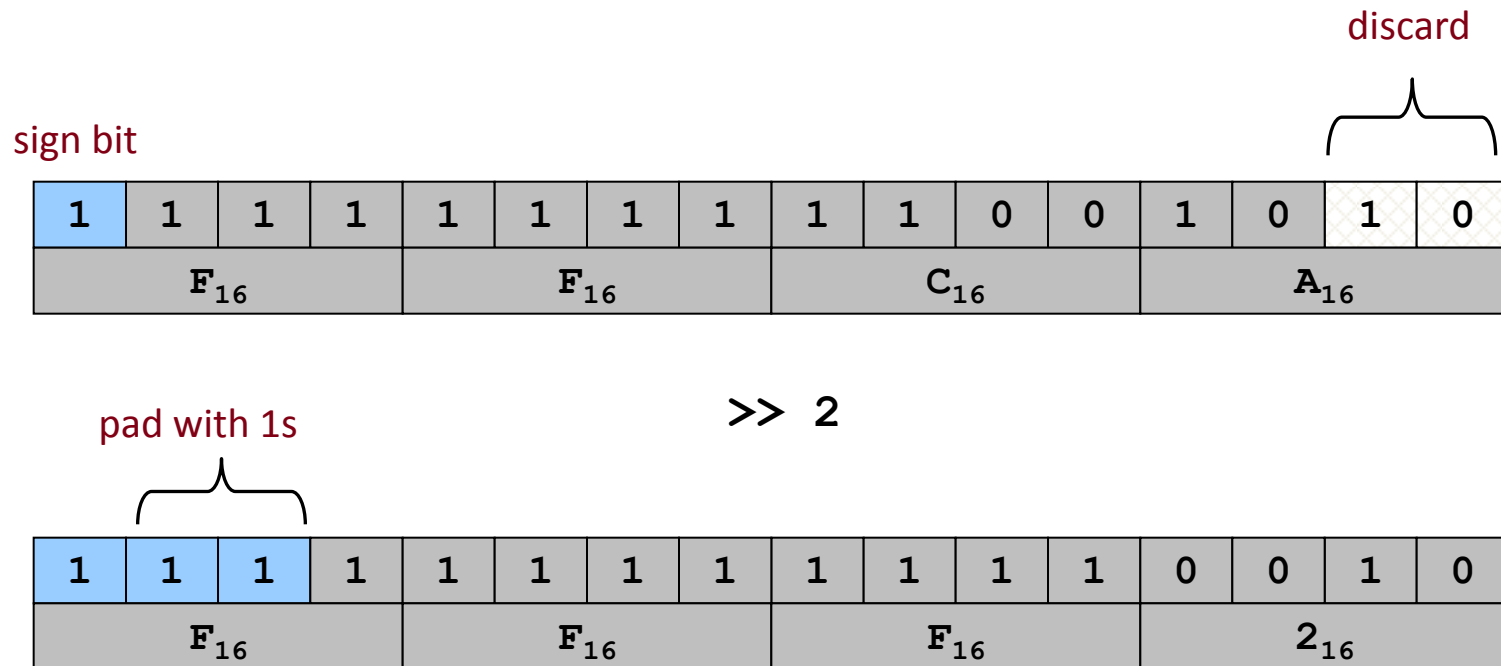
x	y	^
0	0	0
0	1	1
1	0	1
1	1	0

0	0	0	1	0	0	1	0	0	0	1	1	0	1	0	0	
1 ₁₆				2 ₁₆				3 ₁₆					4 ₁₆			
													^			
1	1	1	1	1	0	1	0	1	1	0	1	0	0	1	0	
F ₁₆				A ₁₆				D ₁₆					2 ₁₆			
													=			
1	1	1	0	1	0	0	0	1	1	1	0	0	1	1	0	
E ₁₆				8 ₁₆				E ₁₆					6 ₁₆			

Shift Right (Sign Extension)

Shift Right [opcode 6]

- Move bits to the right, padding with sign bit as needed.
 - $\text{FFCA}_{16} \gg 2_{16} = \text{FFF2}_{16}$
 - $-53_{10} \gg 2_{10} = -13_{10}$



Load Address (a.k.a. Load Constant)

Load Address [opcode 7]

- Loads an 8-bit integer into a register.
- $7A30$ means load the value 30 into register A.

Applications.

register stores "pointer" to a memory cell

```
a = 0x30;
```

Java code

- Load a small constant into a register.
- Load a 8-bit memory address into a register.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	1	1	1	1	0	1	0	0	0	1	1	0	0	0	0
7 ₁₆				A ₁₆				3 ₁₆				0 ₁₆			
opcode				dest d				addr							

Arrays in TOY

TOY main memory is a giant array

- Can access memory cell 30 using load and store.
- 8C30 means load mem[30] into register C.
- Goal: access memory cell i where i is a variable.

...	...
30	0000
31	0001
32	0001
33	0002
34	0003
35	0005
36	0008
37	000D
...	...

TOY memory

Load Indirect [opcode A]

- AC06 means load mem[R6] into register C.

Store Indirect [opcode B]

- BC06 means store contents of register C into mem[R6].



variable index

```
for (int i = 0; i < N; i++)  
    a[i] = StdIn.readInt();  
  
for (int i = 0; i < N; i++)  
    StdOut.println(a[N-i-1]);
```

TOY Implementation of Reverse

TOY implementation of reverse:

- Read in a sequence of integers and store in memory 30, 31, 32, ... until reading 0000.
- Print sequence in reverse order.

10: 7101 R1 ← 0001

11: 7A30 RA ← 0030

12: 7B00 RB ← 0000

constant 1

a[]

n

while(true) {

c = StdIn.readInt();

if (c == 0) break;

memory address of a[n]

a[n] = c;

n++;

}

13: 8CFF read RC

14: CC19 if (RC == 0) goto 19

15: 16AB R6 ← RA + RB

16: BC06 mem[R6] ← RC

17: 1BB1 RB ← RB + R1

18: C013 goto 13

read in the data

TOY Implementation of Reverse

TOY implementation of reverse:

- Read in a sequence of integers and store in memory 30, 31, 32, ... until reading 0000.
- Print sequence in reverse order.

```
10: 7101  R1 ← 0001          constant 1
11: 7A30  RA ← 0030          a[]
12: 7B00  RB ← 0000          n

                                while(true) {
13: 8CFF  read RC              c = StdIn.readInt();
14: CC19  if (RC == 0) goto 19  if (c == 0) break;
15: 16AB  R6 ← RA + RB          memory address of a[n]
16: BC06  mem[R6] ← RC          a[n] = c;
17: 1BB1  RB ← RB + R1          n++;
18: C013  goto 13              }
```

print in reverse order

Unsafe Code at any Speed

Q. What happens if we make array start at 00 instead of 30?

A. Self modifying program; can overflow buffer and run arbitrary code!

```
10: 7101  R1 ← 0001      constant 1
11: 7A00  RA ← 0000      a[]
12: 7B00  RB ← 0000      n

                                while(true) {
13: 8CFF  read RC          c = StdIn.readInt();
14: CC19  if (RC == 0) goto 19  if (c == 0) break;
15: 16AB  R6 ← RA + RB        address of a[n]
16: BC06  mem[R6] ← RC        a[n] = c;
17: 1BB1  RB ← RB + R1        n++;
18: C013  goto 13            }
```

```
% more crazy8.txt
1 1 1 1 1 1 1 1
1 1 1 1 1 1 1 1
8888 8810
98FF C011
```


What If We Lose Control (in C or C++)?

Buffer overflow:

- Array `buffer[]` has size 100.
- User might enter 200 characters.
- Might lose control of machine behavior.

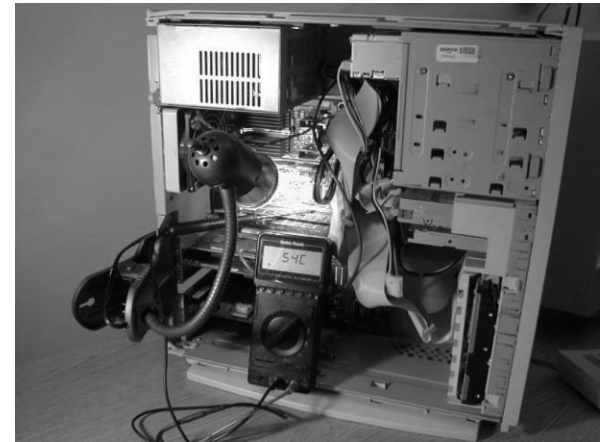
```
#include <stdio.h>
int main(void) {
    char buffer[100];
    scanf("%s", buffer);
    printf("%s\n", buffer);
    return 0;
}
```

unsafe C program

Consequences: Viruses and worms.

Java enforces security:

- Type safety.
- Array bounds checking.
- Not foolproof.



shine 50W bulb at DRAM
[Appel-Govindavajhala '03]

Buffer Overflow Attacks

Stuxnet Worm [July 2010]

- Step 1. Natanz centrifuge fuel-refining plant employee plugs in USB flash drive.
- Step 2. Data becomes code by exploiting Window buffer overflow; machine is Owned.
- Step 3. Uranium enrichment in Iran stalled.



More buffer overflow attacks: Duqu, Flame, Morris worm, Code Red, SQL Slammer, iPhone unlocking, Xbox softmod, JPEG of death, ...

Lesson:

- Not easy to write error-free software.
- Embrace Java security features.
- Keep your OS patched.

Dumping

Q. Work all day to develop operating system in `mem[10]` to `mem[FF]`.
How to save it?

A. Write `dump.toy` and run it to dump contents of memory onto tape.

```
00: 7001    R1 ← 0001
01: 7210    R2 ← 0010          i = 10
02: 73FF    R3 ← 00FF

                                do {
03: AA02    RA ← mem[R2]        a = mem[i]
04: 9AFF    write RA            print a
05: 1221    R2 ← R2 + R1        i++
06: 2432    R4 ← R3 - R2
07: D403    if (R4 > 0) goto 03 } while (i < 255)
08: 0000    halt
```

`dump.toy`

Booting

Q. How do you get it back?

A. Run `boot.toy` and to read `mem[10]` to `mem[FF]` from tape.

```
00: 7001    R1 ← 0001
01: 7210    R2 ← 0010           i = 10
02: 73FF    R3 ← 00FF

                                do {
03: 8AFF    read RA                read a
04: BA02    mem[R2] ← RA          mem[i] = a
05: 1221    R2 ← R2 + R1          i++
06: 2432    R4 ← R3 - R2
07: D403    if (R4 > 0) goto 0    } while (i < 255)
08: 0000    halt
```

`boot.toy`

A Little History

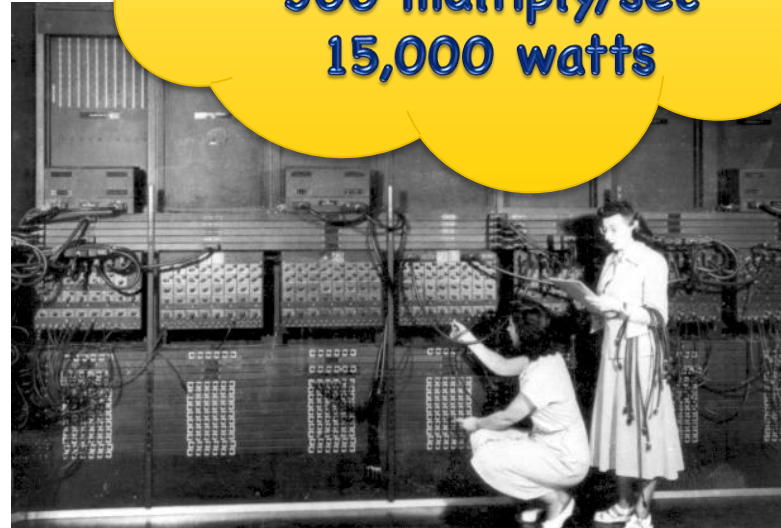
Electronic Numerical Integrator and Calculator (ENIAC):

- First widely known general purpose electronic computer
- Conditional jumps, programmable.
- Programming: change switches and jump wires
- Data: enter numbers using punch cards

30 tons
30 x 50 x 8.5 ft
17,468 vacuum
tubes
300 multiply/sec
15,000 watts



John Mauchly (left) and J. Presper Eckert (right)
http://cs.swau.edu/~durkin/articles/history_computing.html



ENIAC, Ester Gerston (left), Gloria Gordon (right)
US Army photo: <http://ftp.arl.mil/ftp/historic-computers>

Basic Characteristics of TOY Machine

TOY is a general-purpose computer

- Sufficient power to perform any computation.
- Limited only by amount of memory and time.

Stored-program computer [von Neumann, 1944]

- Data and program encoded in binary.
- Data and program stored in same memory.
- Can change program without rewiring.

Outgrowth of Alan Turing's work

All modern computers are general-purpose computers and have same (von Neumann) architecture.



John von Neumann



Maurice Wilkes (left)
EDSAC (right)

TOY Reference Card

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Format 1	opcode				dest d				source s				source t			
Format 2	opcode				dest d				addr							

#	Operation	Fmt	Pseudocode
0:	halt	1	<code>exit(0)</code>
1:	add	1	<code>R[d] ← R[s] + R[t]</code>
2:	subtract	1	<code>R[d] ← R[s] - R[t]</code>
3:	and	1	<code>R[d] ← R[s] & R[t]</code>
4:	xor	1	<code>R[d] ← R[s] ^ R[t]</code>
5:	shift left	1	<code>R[d] ← R[s] << R[t]</code>
6:	shift right	1	<code>R[d] ← R[s] >> R[t]</code>
7:	load addr	2	<code>R[d] ← addr</code>
8:	load	2	<code>R[d] ← mem[addr]</code>
9:	store	2	<code>mem[addr] ← R[d]</code>
A:	load indirect	1	<code>R[d] ← mem[R[t]]</code>
B:	store indirect	1	<code>mem[R[t]] ← R[d]</code>
C:	branch zero	2	<code>if (R[d] == 0) pc ← addr</code>
D:	branch positive	2	<code>if (R[d] > 0) pc ← addr</code>
E:	jump register	2	<code>pc ← R[d]</code>
F:	jump and link	2	<code>R[d] ← pc; pc ← addr</code>

Register 0 always reads 0.
Loads from `mem[FF]` from `stdin`.
Stores to `mem[FF]` to `stdout`.

16-bit registers.
16-bit memory.
8-bit program counter.