

Computer Graphics

ECSE-4750 FALL 2015

CLASS 8

Class

- Term Project
- Polygons, geometry, and should I draw them
- Textures and Coordinates
- Homework 4

Term Project

You will think of, implement, and document a program relating to graphics. It must demonstrate both graphics input and output; other than that it must only be legal and ethical.

This may be done by a team, and may be combined with another course's project if you get the approval of everyone involved.

You need to work in teams of 4-5 people

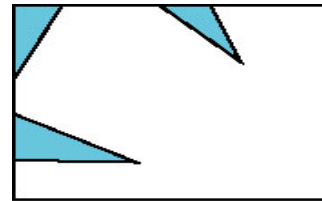
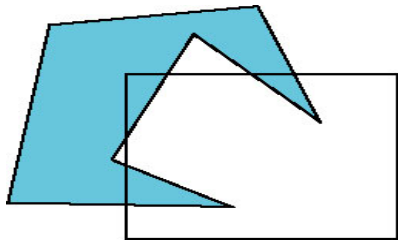
This is on purpose, businesses need you to work well in teams.

Polygons, geometry, and clipping

Polygon Clipping

Not as simple as line segment clipping

- Clipping a line segment yields at most one line segment
- Clipping a polygon can yield multiple polygons



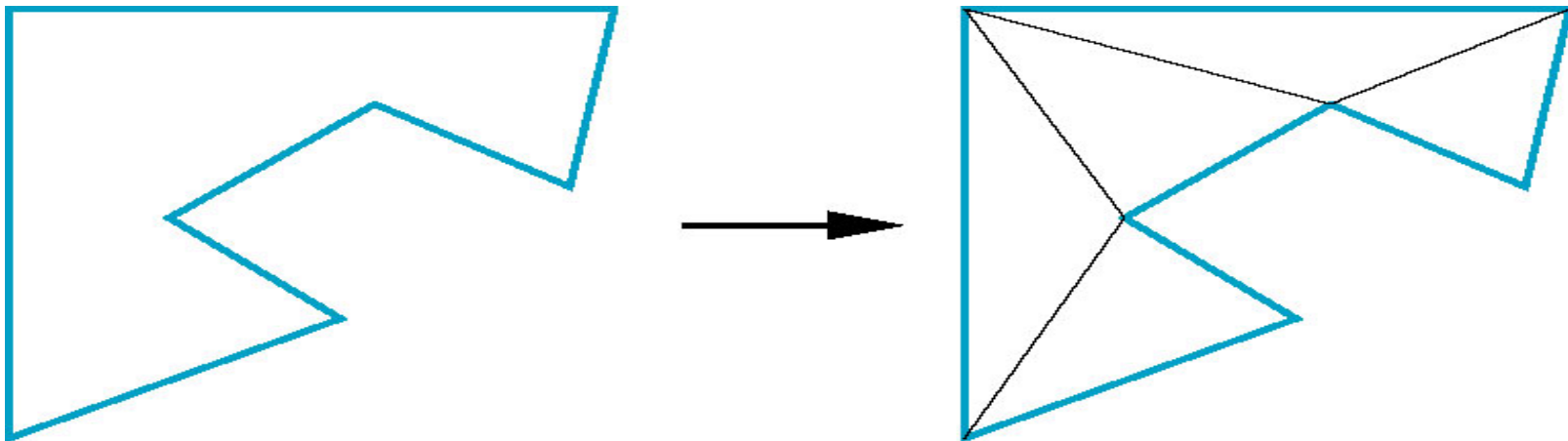
However, clipping a convex polygon can yield at most one other polygon

Tessellation and Convexity

One strategy is to replace nonconvex (*concave*) polygons with a set of triangular polygons (a *tessellation*)

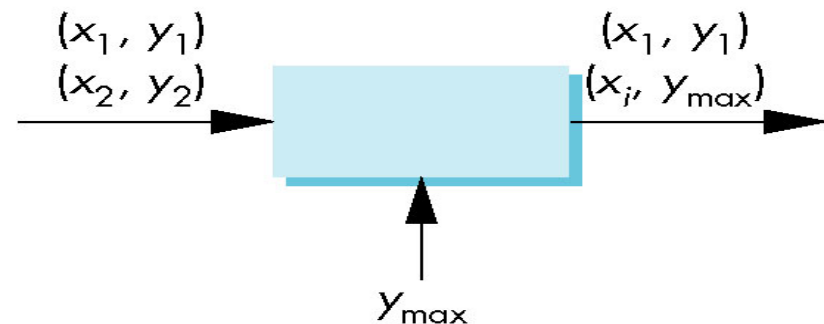
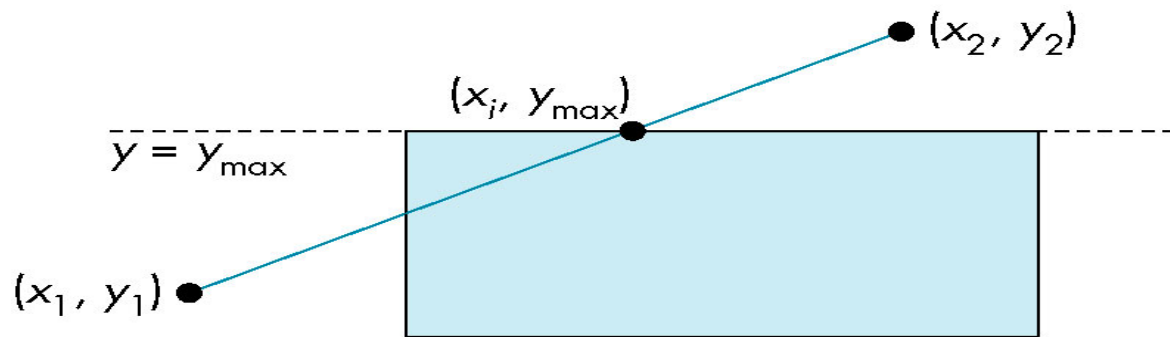
Also makes fill easier

Tessellation through tessellation shaders



Clipping as a Black Box

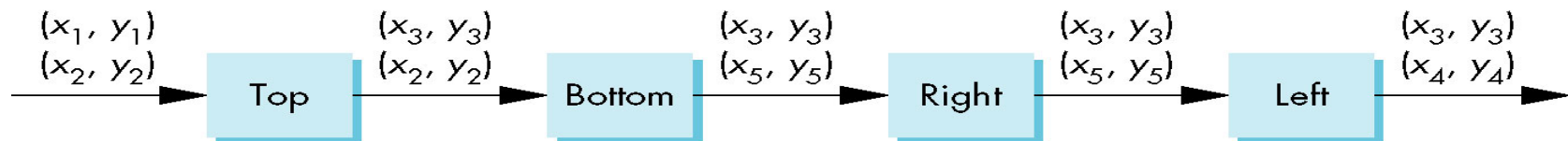
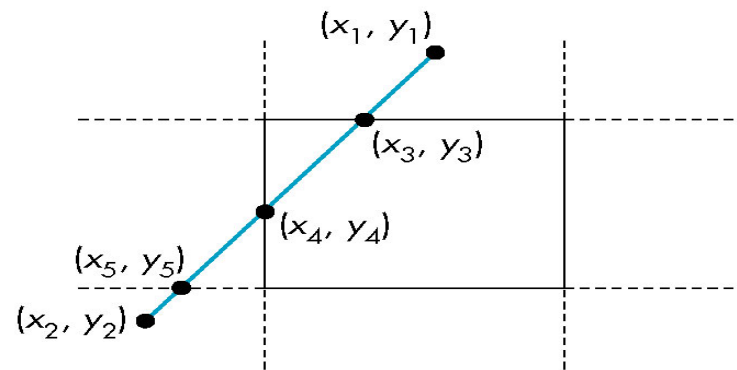
Can consider line segment clipping as a process that takes in two vertices and produces either no vertices or the vertices of a clipped line segment



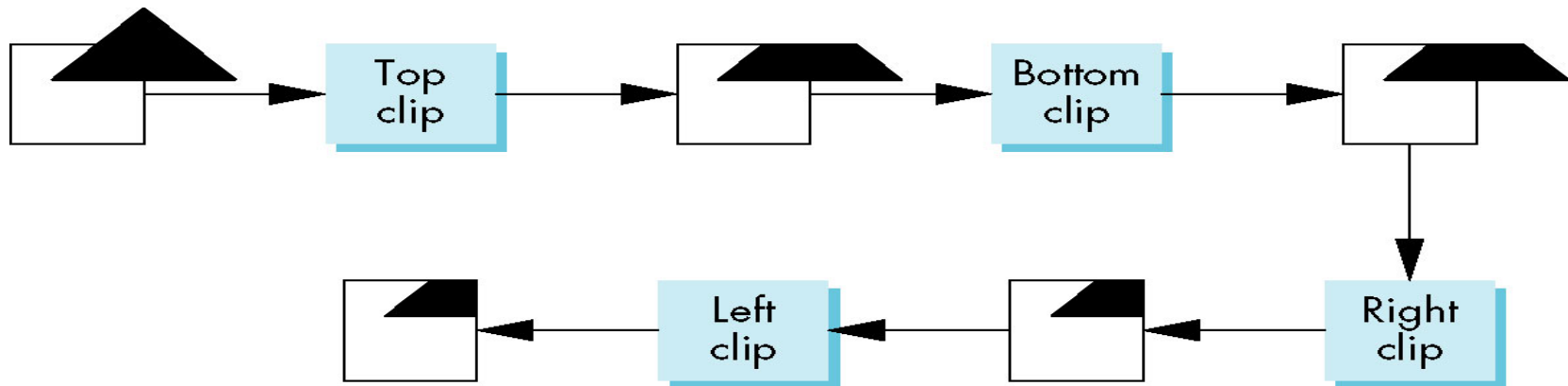
Pipeline Clipping of Line Segments

Clipping against each side of window is independent of other sides

- Can use four independent clippers in a pipeline



Pipeline Clipping of Polygons



Three dimensions: add front and back clippers

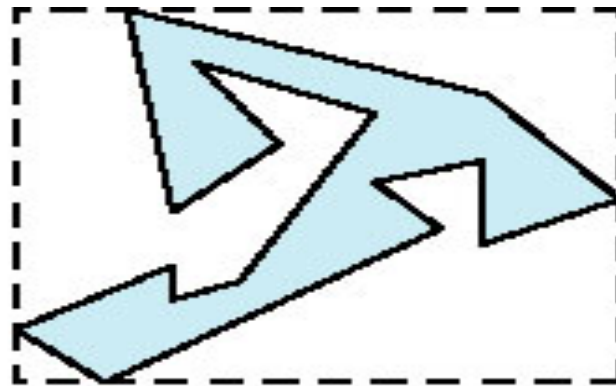
Strategy used in SGI Geometry Engine

Small increase in latency

Bounding Boxes

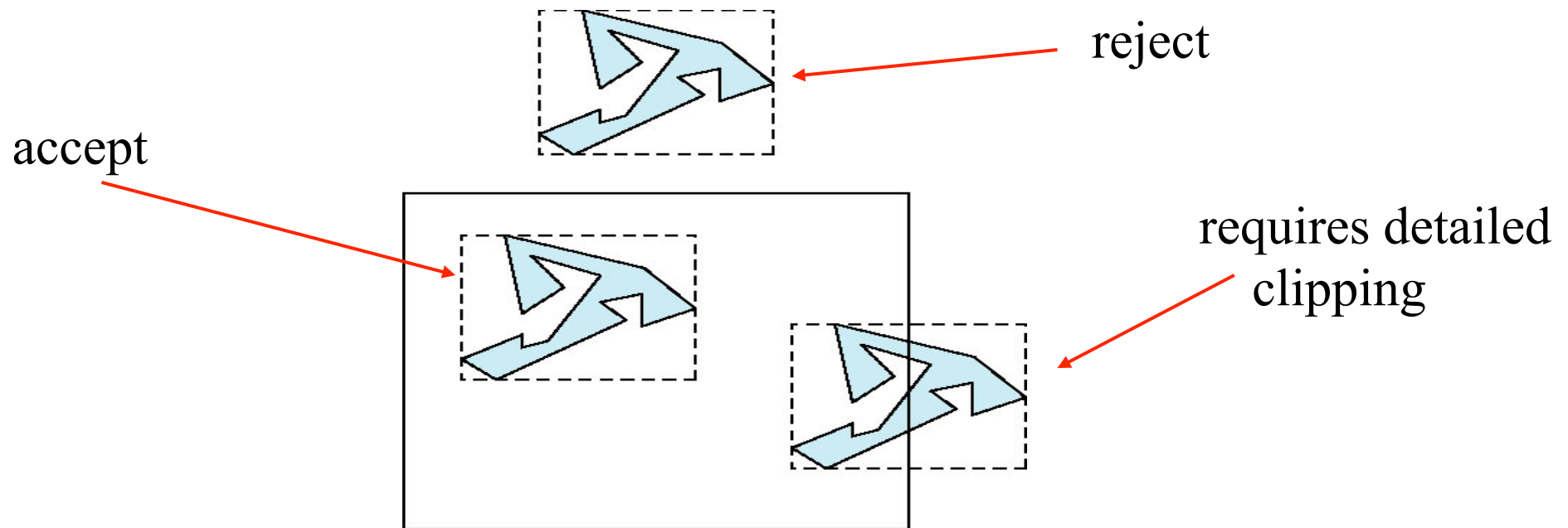
Rather than doing clipping on a complex polygon, we can use an *axis-aligned bounding box* or *extent*

- Smallest rectangle aligned with axes that encloses the polygon
- Simple to compute: max and min of x and y



Bounding boxes

Can usually determine accept/reject based only on bounding box



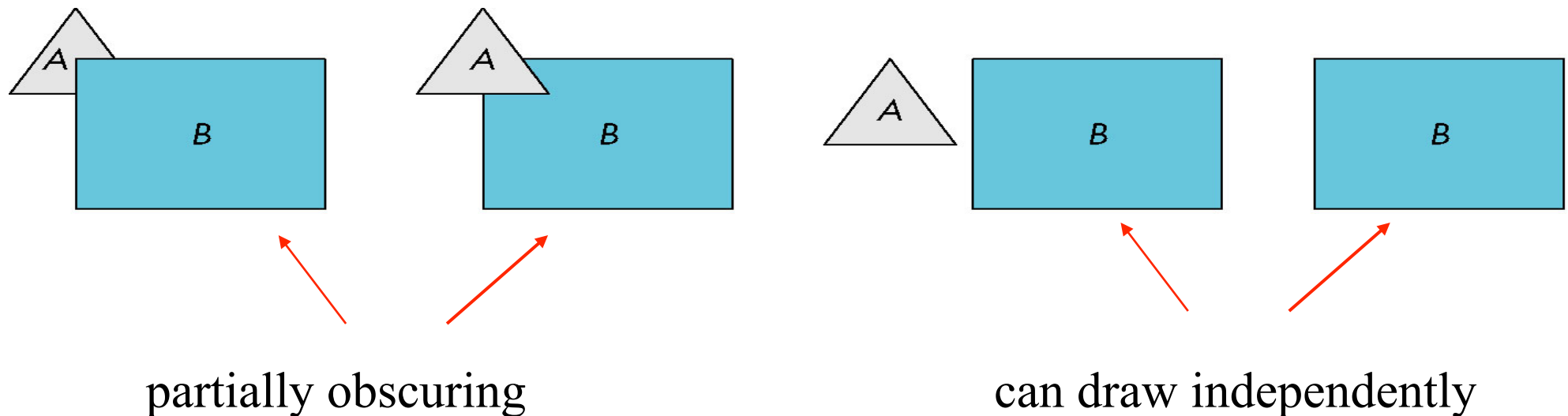
Clipping and Visibility

Clipping has much in common with hidden-surface removal
In both cases, we are trying to remove objects that are not visible to the camera

Often we can use visibility or occlusion testing early in the process to eliminate as many polygons as possible before going through the entire pipeline

Hidden Surface Removal

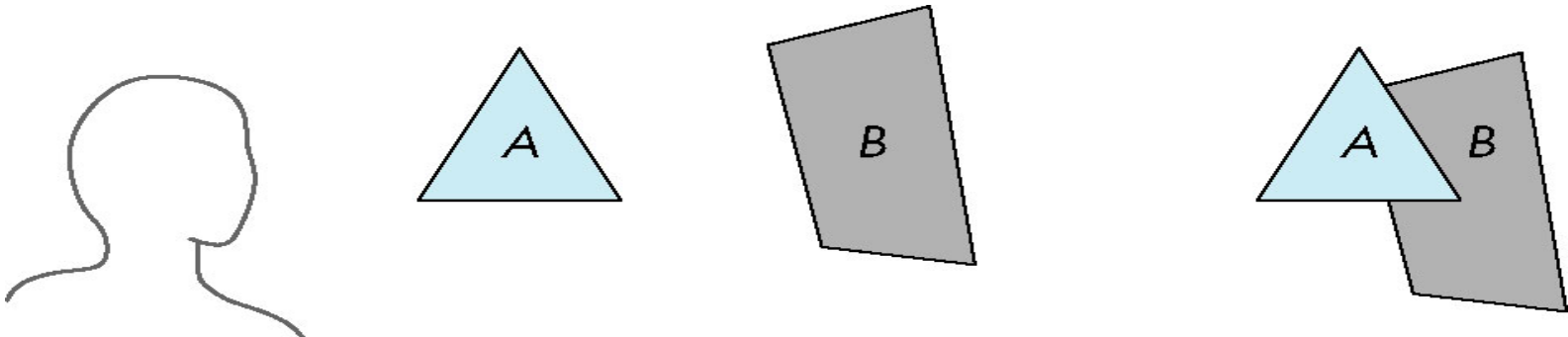
- Object-space approach: use pairwise testing between polygons (objects)



- Worst case complexity $O(n^2)$ for n polygons

Painter's Algorithm

Render polygons a back to front order so that polygons behind others are simply painted over



B behind A as seen by viewer

Fill B then A

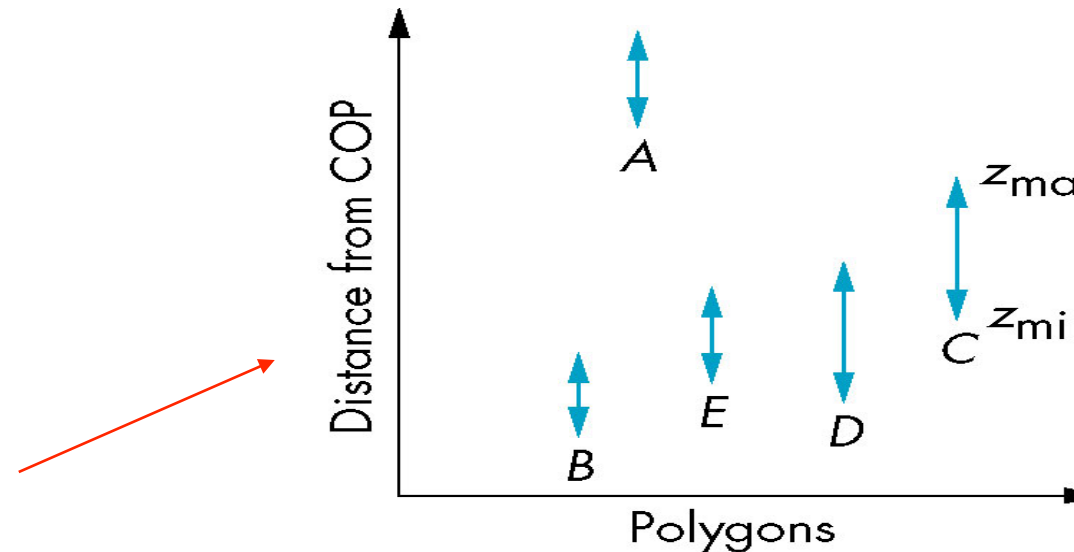
Depth Sort

Requires ordering of polygons first

- $O(n \log n)$ calculation for ordering
- Not every polygon is either in front or behind all other polygons

Order polygons and deal with
easy cases first, harder later

Polygons sorted by
distance from COP



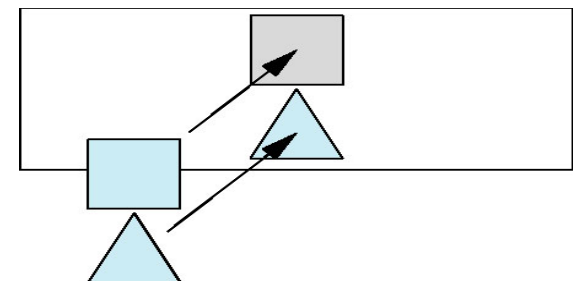
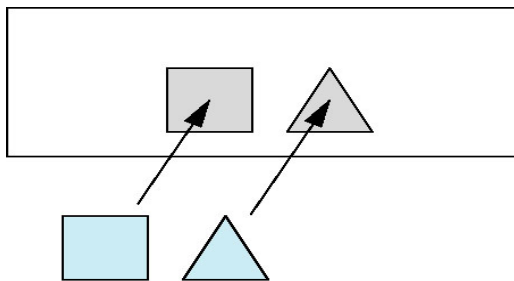
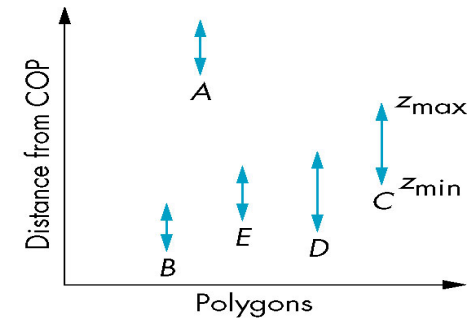
Easy Cases

A lies behind all other polygons

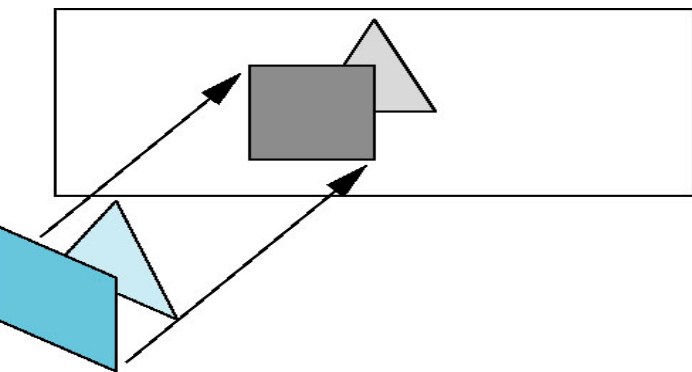
- Can render

Polygons overlap in z but not in either x or y

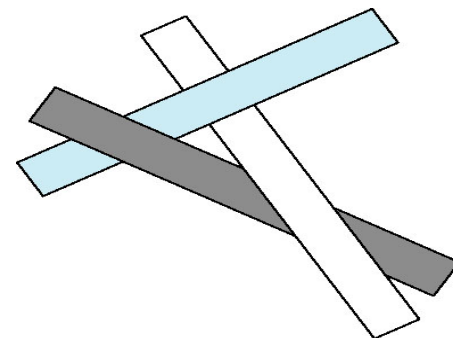
- Can render independently



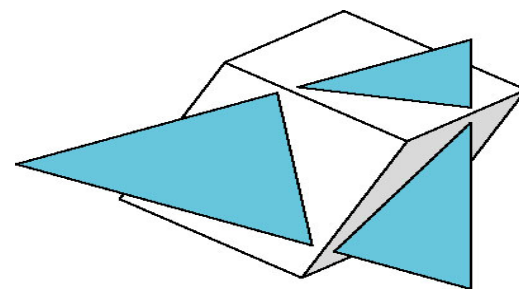
Hard Cases



overlap in all directions
can one is fully on
side of the other



cyclic overlap



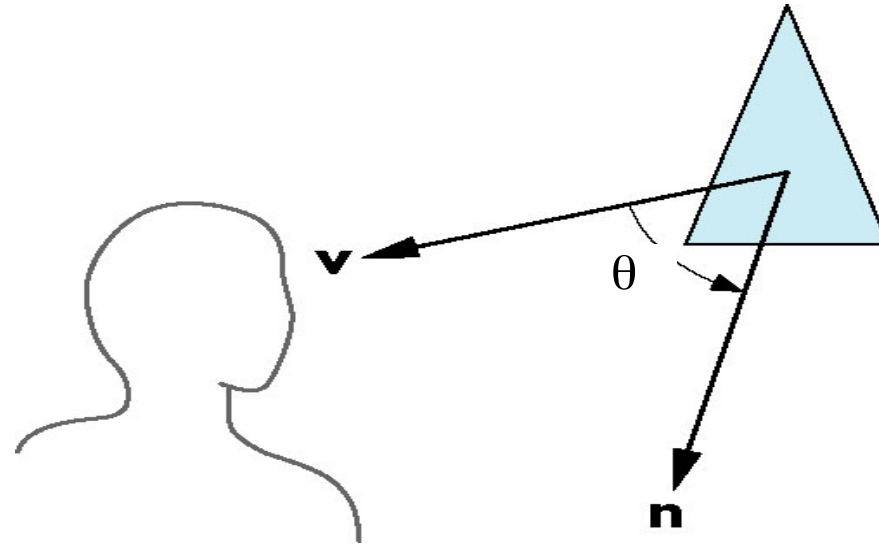
penetration

Back-Face Removal (Culling)

Face is visible iff $90 \geq \theta \geq -90$

Equivalently $\cos \theta \geq 0$

$\mathbf{v} \cdot \mathbf{n} \geq 0$



Equation of face has form $ax + by + cz + d = 0$

after normalization $\mathbf{n} = (0 \ 0 \ 1 \ 0)^T$

We only need to test the sign of c

In OpenGL we can simply enable culling

but may not work correctly if we have nonconvex objects

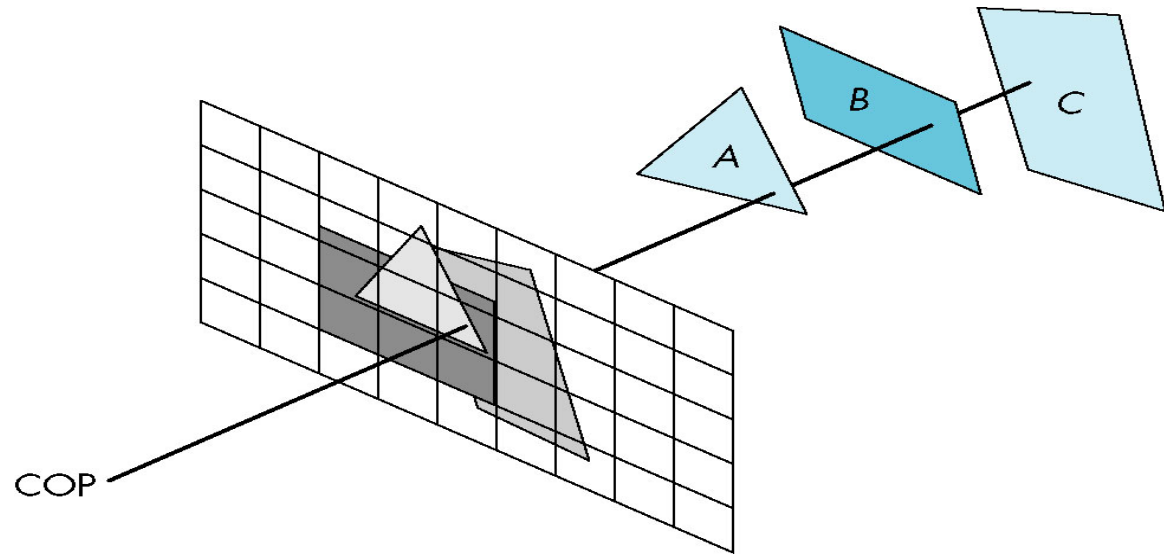
Image Space Approach

Look at each projector (nm for an $n \times m$ frame buffer) and find closest of k polygons

Complexity $O(nmk)$

Ray tracing

z-buffer

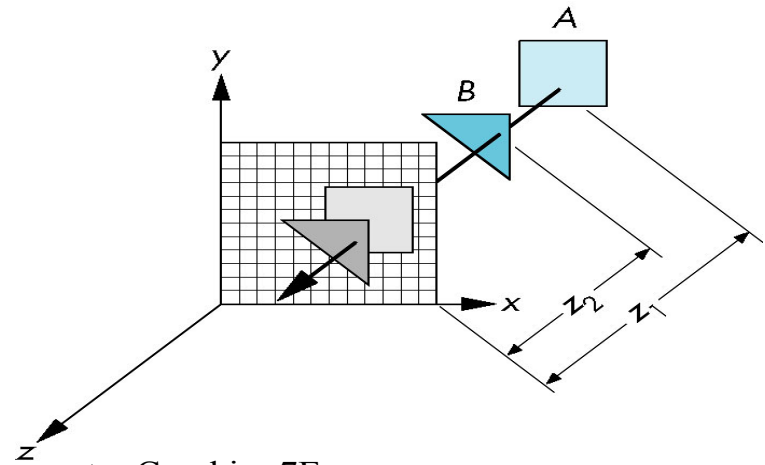


z-Buffer Algorithm

Use a buffer called the z or depth buffer to store the depth of the closest object at each pixel found so far

As we render each polygon, compare the depth of each pixel to depth in z buffer

If less, place shade of pixel in color buffer and update z buffer



Textures

Textures

Texture coordinates are specified at each vertex of a given geometry

We are drawing polygons

These need to be tessellated

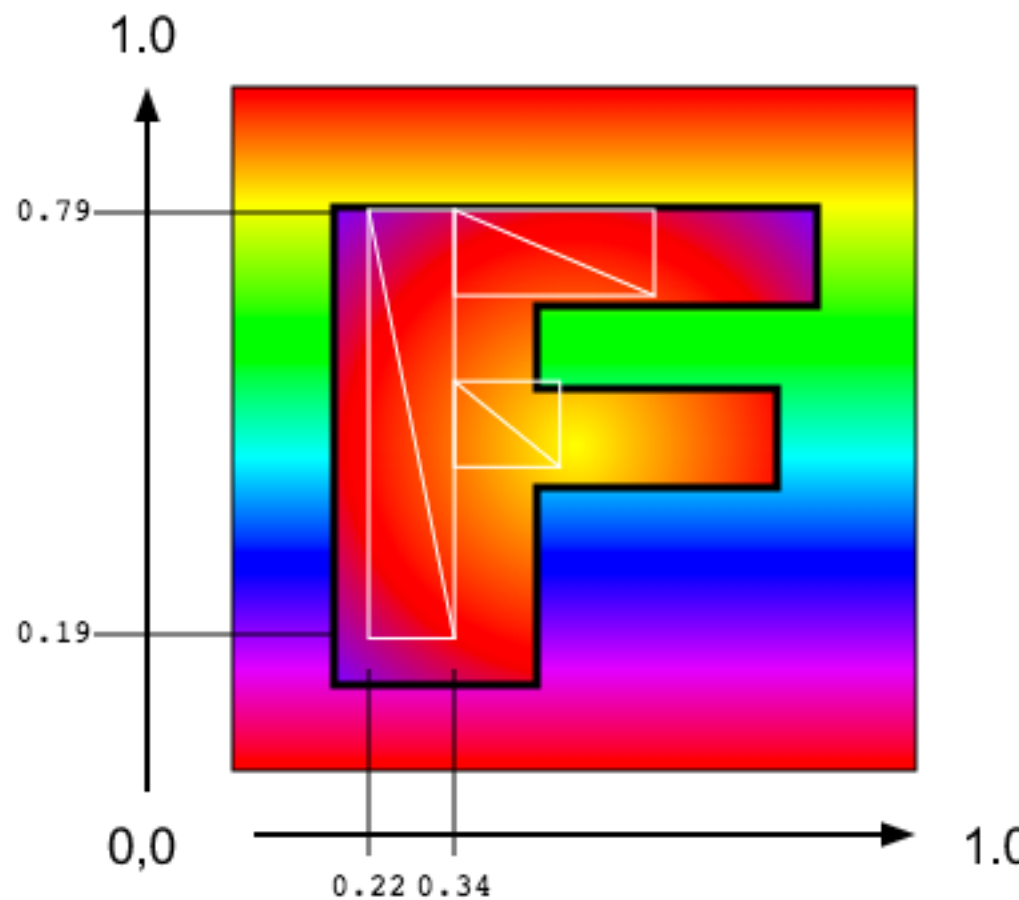
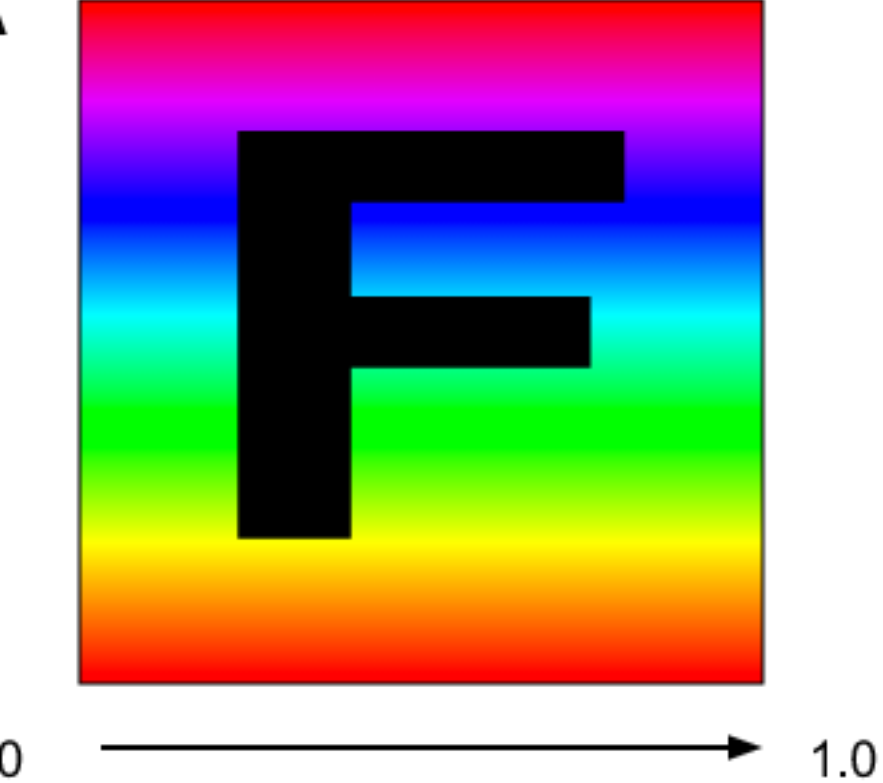
Topology and geometry saves us

Only need to redefine the triangle end points

Geometry stays the same

Textures

0



Texture coordinate generation

Previous example nice for simple translation

How to map to real world



Pixel: (84, 111)
Coord: (-120, 45)

Pixel: (611, 417)
Coord: (-75, 20)

Interpolate on the geometries
world coordinates and find the
appropriate texture coordinate

Homework 4

Textures are very good, use your code from the in class challenge and textures to the Hw4 code.

Add code to interpolate texture coordinates for each state

Add one texture and reuse across all the geometries

Each state will “cut” themselves out of the entire image.

Try turning off some states

Hint: To open local files you can turn off Chrome file security with the command line option:
`--args --disable-web-security`, just remember to close the browser when finished)
Or use Firefox ;)