

### **Table of Contents**

- NumPy Array
- Array Creation
- Array Shapes
- Array Arithmetic
- Array Broadcasting and Broadcasting Rules



## The NumPy Library



- NumPy is a Python library for scientific computing
- It is pre-installed in Anaconda and Google Colab
- The NumPy library provides a lot of useful functions for numerical computations
- For example, to calculate the mean:

```
import numpy as np
```

```
x = [1,2,3]
print('The mean is:',np.mean(x))
The mean is: 2.0
```

(1+2+3)/3



## NumPy Array

- Large amount of data are processed in machine learning
- Data are represented in computer as n-d arrays, aka tensors
- NumPy provides a special data structure called NumPy array to represent tensors

#### You see an image like this

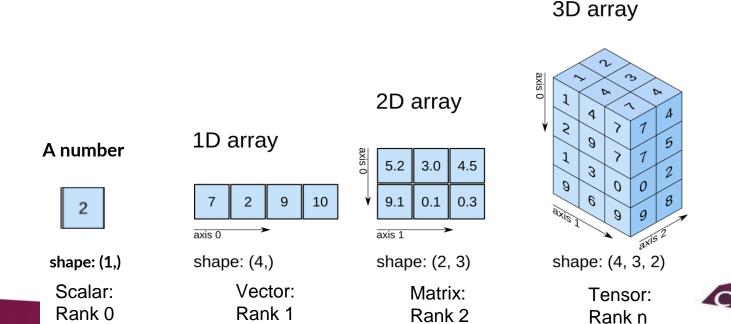


#### Your computer sees an image like this



## NumPy Array

- NumPy allows users to declare N dimensional (nd) arrays (Tensors)
- Using the function np.array()

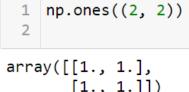


### **Array Creation**

- There are different ways to create NumPy arrays:
- np.array()
  - Create an array with from a list or tuple
  - > Example:

```
1 np.array([1,2,3])
array([1, 2, 3])
```

- 2. np.zeros(shape), np.ones(shape)
  - Create an array full of zeros/ones with the specified shape
  - > Example:





### Array Creation

- 3. np.arange(start, stop, step)
  - Similar usage as range() function, but return an array instead
  - > Example:

- 4. np.linspace(start, stop, num)
  - Create an array of num evenly spaced samples
  - Over the interval [start, stop]
  - > Example:

```
1    np.linspace(0,0.5,5)
2    array([0. , 0.125, 0.25 , 0.375, 0.5 ])
```



### **Array Creation**

- 5. np.identity(*n*)
  - Create an identity array of size n
  - i.e. a square array with ones on the main diagonal
  - > Example:



### Exercise 1

NumPy array indexing and slicing work similar as list, try the codes below:

```
a_list = [0,1,2,3,4,5]
b_list = a_list[1:4] #b is some elements of a
print('a before:',a_list)
print('b before:', b_list)
b_list[0] = 1000 #change an element of b
print('a after:', a_list)
print('b after:',b_list)
```

```
a_array = np.array([0,1,2,3,4,5])
b_array = a_array[1:4] #b is some elements of a
print('a before:', a_array)
print('b before:', b_array)
b_array[0] = 1000 #change an element of b
print('a after:',a_array)
print('b after:',b_array)
```

- Does a\_list change after changing an element of b\_list? How about a\_array?
- Can you propose a way where a\_array won't be changed after changing b\_array?



### Array Shapes

The shape of an array can be accessed by array.shape attribute

```
1  x = np.array([[1,2],[3,4]])
2  print('Array x: \n', x)
3  print('Shape of x:', x.shape)
4
5
6  y = np.array([[1],[2],[3]])
7  print('Array y: \n', y)
8  print('Shape of y:', y.shape)
```

```
Array x:
[[1 2]
[3 4]]
Shape of x: (2, 2)
Array y:
[[1]
[2]
[3]]
Shape of y: (3, 1)
```



### Array Shapes

- NumPy arrays can be reshaped by array.reshape() method
- Equivalent to the previous slide:

```
1  x = np.arange(1,5)
2  x = x.reshape(2,2)
3  print('Array x: \n', x)
4  print('Shape of x:', x.shape)
5
6
7  y = np.arange(1,4)
8  y = y.reshape(3,1)
9  print('Array y: \n', y)
10  print('Shape of y:', y.shape)
```

```
Array x:
  [[1 2]
  [3 4]]
Shape of x: (2, 2)
Array y:
  [[1]
  [2]
  [3]]
Shape of y: (3, 1)
```



### Exercise 2

- Try the code below, what is the output?
- What does -1 in x.reshape(-1,2) mean?
- Can you try reshape(-1,2) on the arrays returned by np.arange(1,n) with different values of n, where n is an integer?
- What is the condition for n which no error is returned?

```
1  x = np.arange(1,7)
2  x = x.reshape(-1,2)
3  print('Array x: \n', x)
4  print('Shape of x:', x.shape)
5
```



- NumPy provides a linear algebra module for matrices and vectors computations:
- np.transpose(a) or a.transpose() or a.T
  - Compute the transpose of the matrix a
  - > Example:

```
1 a = np.arange(6).reshape(2,3)
2 a
array([[0, 1, 2],
[3, 4, 5]])
```



- 2. np.dot(a, b)
  - > Compute the dot product of the vectors a and b

$$\mathbf{a} \cdot \mathbf{b} = \sum_{i} a_{i} b_{i}$$

> Example:

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \cdot \begin{bmatrix} 4 & 5 & 6 \end{bmatrix}$$
$$= 1 \times 4 + 2 \times 5 + 3 \times 6$$
$$= 32$$

```
1  a = np.array([1,2,3])
2  b = np.array([4,5,6])
3
4  print('The dot prodcut of a and b is:', np.dot(a,b))
```

The dot prodcut of a and b is: 32



- 3. np.linalg.norm(x, ord)
  - Compute the norm of the vector/matrix x
  - It computes the Frobenius norm if ord=None (default value)

$$||\mathbf{x}||_F = \sqrt{\sum_i \sum_j |x_{ij}|^2}$$

Example:

```
1 a = np.array([3,4])
2 np.linalg.norm(a)
1 a = np.array([[1,2],[3,4]])
2 np.linalg.norm(a)
5.477225575051661
```

5.0



- 4. np.matmul(a, b)
  - Multiply matrix a and matrix b
  - > Example:



- 5. np.linalg.inv(A)
  - $\triangleright$  Compute the inverse  $A^{-1}$  of matrix A, such that  $AA^{-1} = 1$
  - > Example:



- 6. np.linalg.solve(a,b)
  - > Solve a linear matrix equation, or system of linear scalar equations

> Example, solving 
$$\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
:

```
1 A = np.array([[1,2],[3,5]]) Solution:  x = \begin{bmatrix} -1 \\ 1 \end{bmatrix} 
2 b = np.array([1,2])  x = \begin{bmatrix} -1 \\ 1 \end{bmatrix}
```

array([-1., 1.])

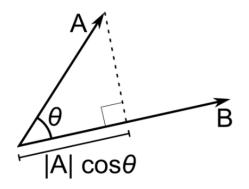


### Exercise 3

Recall the geometric interpretation of the dot product:

$$\frac{\mathbf{A} \cdot \mathbf{B}}{|A||B|} = \cos \theta$$

- Verify that the angle between the vectors A = [0,1,2] and B=[3,0,0] is  $\pi/2$  (90 degree)
- Hints:
  - > Use np.arccos(x) to calculate  $cos^{-1} x$
  - $\triangleright$  Use np.pi to get the value of  $\pi$





- Broadcasting refer to how NumPy treats arrays with different shapes during arithmetic operations
- If two arrays have the same shape, the operations will be performed elementwise
- If two arrays have different shapes, the smaller array will be broadcasted across the larger array



Consider the scalar multiplication, ie multiplying the whole array by 2:

$$2\mathbf{x} = 2 \cdot \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix} = \begin{bmatrix} 2x_1 & 2x_2 & \cdots & 2x_n \end{bmatrix}$$

• Is it necessary to declare an array of numbers 2 with the same shape as x to perform the multiplication, like below?

```
a = np.repeat(2,5)
a

x = np.arange(5)
x

array([2, 2, 2, 2, 2])
array([0, 1, 2, 3, 4])

array([0, 2, 4, 6, 8])
```



- Indeed, we can just multiply the array with an integer 2
- The integer 2 is broadcasted and multiplied with all elements of array x
- It yields the same result as the previous slide:

```
x = np.arange(5)
x

a = 2
a*x

array([0, 1, 2, 3, 4])
array([0, 2, 4, 6, 8])
```



- Similar behavior when multiplying a 2x1 array with 2x4 array
- Array a is broadcasted along axis 1 of array x
- Don't confuse it with matrix multiplication!

1. If the arrays do not have the same rank, prepend the shape of the lower rank array with 1 until both arrays have the same rank.

```
Image (3d array): 256 x 256 x 3
Scale (1d array): 3
Result (3d array): 256 x 256 x 3
Result (3d array): 256 x 256 x 3
Image (3d array): 256 x 256 x 3
Result (3d array): 256 x 256 x 3
```

Examples are taken from documentation:

https://docs.scipy.org/doc/numpy/user/basics.broadcasting.html



2. The two arrays are said to be compatible in a dimension if they have the same size in the dimension, or if one of the arrays has size 1 in that dimension.

#### Compatible in all dimensions

```
A (3d array): 15 x 3 x 5
B (3d array): 15 x 1 x 5
Result (3d array): 15 x 3 x 5
```

#### Incompatible in dimension 1

```
A (2d array): 2 x 1
B (3d array): 8 x 4 x 3
```



3. The arrays can be broadcast together if they are compatible in all dimensions.

Compatible in all dimensions

```
A = np.arange(15*3*5).reshape(15,3,5)
B = np.arange(15*5).reshape(15,1,5)
(A*B).shape
```

```
(15, 3, 5)
```

Incompatible in dimension 1



4. After broadcasting, each array behaves as if it had shape equal to the elementwise maximum of shapes of the two input arrays.

```
A (4d array): 8 x 1 x 6 x 1

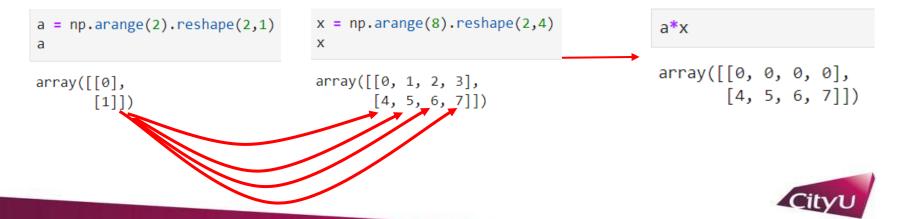
B (3d array): 7 x 1 x 5

Result (4d array): 8 x 7 x 6 x 5

Maximum of dimensions of A or B
```



5. In any dimension where one array had size 1 and the other array had size greater than 1, the first array behaves as if it were copied along that dimension



### Exercise 4

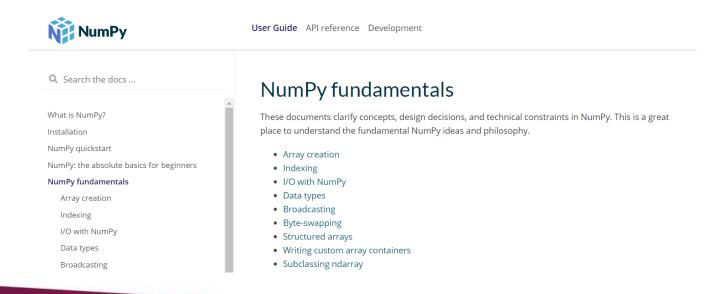
- Optimization problems are common in machine learning, one of the algorithms to solve optimization problems is the Newton-Raphson algorithm.
- Refer to your Jupyter notebook, implement the Newton-Raphson algorithm for linear regression using NumPy.



### More on the NumPy Library

More on the NumPy library:

https://docs.scipy.org/doc/numpy/user/basics.html



### Next Lesson...

### Advanced Python

#### **Pandas**

- Series and DataFrame
- Descriptive statistics in Pandas
- Group By: split-apply-combine
- Data visualization



專業 創新 胸懷全球 Professional·Creative For The World

