A Bayesian View on the Hilbert Transform and the Kramers-

Kronig Transform of Electrochemical Impedance Data:

Probabilistic Estimates and Quality Scores

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Abstract

Electrochemical impedance spectroscopy (EIS) is one of the most widely used experimental tools in electrochemistry and has applications ranging from energy storage and power generation to medicine. Considering the broad applicability of the EIS technique, it is critical to validate the EIS data against the Hilbert transform (HT) or, equivalently, the Kramers–Kronig relations. These mathematical relations allow one to assess the self-consistency of obtained spectra. However, the use of validation tests is still uncommon. In the present article, we aim at bridging this gap by reformulating the HT under a Bayesian framework. In particular, we developed the Bayesian Hilbert transform (BHT) method that interprets the HT probabilistically. Leveraging the BHT, we proposed several scores that provide quick metrics for the evaluation of the EIS data quality.

<u>Keywords</u>: Electrochemical Impedance Spectroscopy, Hilbert Transform, Kramers-Kronig Relations, Bayesian Methods, Quality scores

1 Introduction

Electrochemical impedance spectroscopy (EIS) is one of the most important and versatile techniques of electrochemistry.[1] EIS has been used widely in the fields of energy storage, [2, 3] solid-state ionics,[4, 5] fuel cells,[6, 7] electrolyzers,[8] solar cells,[9, 10] porous media,[11] sensors,[12] biology,[13] virological diagnostics,[14] and medicine.[15, 16] The EIS technique is particularly appreciated because it can be carried out for frequencies spanning several orders of magnitude, typically from 1 mHz to 10 MHz. Obtaining information across such a broad range of timescales allows one to gain insights from many disparate physicochemical phenomena.[17]

The impedance measured by the EIS technique is a transfer function, and, as such, it needs to satisfy linearity, time-invariance, and causality.[1, 18] Compliance with these properties can be evaluated experimentally, for example, by varying the EIS measurement settings systematically[19] or by broadband excitation.[20] However, these testing procedures are not practically possible or may take an unnecessarily long time. Alternatively, one can assess whether the measured EIS spectrum satisfies the criteria mentioned above using the Kramers-Kronig (KK) relations.[21, 22] Such relations, which can be obtained by manipulating the Hilbert transform (HT) of suitable even and odd functions, link the real and imaginary parts of the impedance to one another through integrals over frequencies from 0 Hz to ∞. While the exact implementation of KK relations needs impedance data for all possible frequencies, the EIS spectra, in reality, are only discretely sampled over a finite interval of frequencies. Methods, including direct integration and regression of generalized circuit models,[18, 23-30] have been developed to overcome this limitation. Consequently, the KK relations have been available as a tool to assess the validity of the EIS spectra. For an overview of the use of KK relations on

EIS, the reader is referred to the textbook of Orazem and Tribollet[1] and the monograph by Lasia.[31] We should remark that the EIS spectra are rarely benchmarked against the KK relations and therefore tested for their validity.

In this article, we aim at overcoming this significant gap by taking a slightly different starting point compared to the KK relations that are typically used in the EIS analysis.[1] Instead, we are going to focus on the HT, which, in the context of the transfer functions, is equivalent to the KK relations.[32] The HT is used in many applications, including fluid mechanics,[33] aerodynamics, [34] optics, [35] and geophysics. [36] Relative to the KK relations, the HT has far richer mathematical literature, with the availability of fast HT methods[37, 38] and many theoretical results.[32, 39, 40] In the context of analyzing the consistency of EIS data, we will set up a new framework, which is named as Bayesian Hilbert transform (BHT). As a first step, the BHT approach uses a linear approximation of the impedance, $Z(\omega)$, with respect to a given basis. In other words, we will write $Z(\omega) = \sum_n x_n \psi_n(\omega)$, where the $\psi_n(\omega)$'s are transfer functions and x_n 's are random variables (RVs) endowed with a certain probability distribution function (pdf) that will need to be determined. Here, we will use the $\psi_n(\omega)$'s originating from the distribution of relaxation times (DRT) and take the x_n 's to be normally distributed. After having regressed the x_n 's, we will be able to compute $Z_H(\omega)$, i.e., the HT of $Z(\omega)$ using a simple matrix multiplication. An important point to note is that both $Z(\omega)$ and $Z_H(\omega)$ will be understood as normally distributed RVs. Doing so will allow us to use analytical formulas and define a number of scores that quantify consistency of the real and imaginary parts of the regressed $Z(\omega)$ against experimental data and with themselves.

The scientific contribution of the paper is twofold. First, we reframed the HT of the EIS data in a general Bayesian context, where we leverage analytical matrix expressions. This allowed us to determine the hyperparameters used in the regression by maximizing the evidence rather than by an $ad\ hoc$ guess. Second, we proposed new ways to score the compliance of $Z(\omega)$ with the HT. These scores are based on residual plots, mean discrepancies, and "distances" between the pdfs of $Z(\omega)$ and $Z_H(\omega)$. We have also shared our code and included some of the developed metrics in DRTtools.[41] We expect that doing so will promote the inclusion of the HT or KK test of EIS data in existing software packages. Lastly, we must point out that, despite their importance, the KK relations are not widely used in the electrochemistry field. This is perhaps due to the difficulty in understanding the theory and the availability of modern software. We hope that our contribution will be instrumental in overcoming these two challenges.

2 Theory

2.1 Hilbert Transform

In this section, we briefly define the HT and recall how to link HT to KK relations. For an authoritative review of the topic, interested readers are invited to consult King's two-volume book.[32] The HT on the real line is defined as the operator that transforms a function $f(\omega)$ into another function $Hf(\omega)$ via the following integral:

$$Hf(\omega) = \frac{1}{\pi} P \int_{-\infty}^{\infty} \frac{f(\widehat{\omega})}{\omega - \widehat{\omega}} d\widehat{\omega}$$
 (1)

where the symbol $P \int (\cdot) d\hat{\omega}$ denotes the Cauchy principal value, which is formally defined as

$$P \int_{-\infty}^{\infty} \frac{f(\widehat{\omega})}{\omega - \widehat{\omega}} d\widehat{\omega} = \lim_{\varepsilon \downarrow 0} \int_{|\omega - \widehat{\omega}| > \varepsilon} \frac{f(\widehat{\omega})}{\omega - \widehat{\omega}} d\widehat{\omega}$$
 (2)

Other variants of the HT exist, including the HT on the circle, the finite HT, the multidimensional HT, and the discrete HT.[32] In this article, we will only use (1). Let us recall a few fundamental properties of the HT applied to the EIS. If f(z) is an EIS transfer function with $f(z) \to 0$ as $z \to \infty$, then

$$f_{\rm re}(\omega) = -H f_{\rm im}(\omega)$$
 (3a)

$$f_{\rm im}(\omega) = H f_{\rm re}(\omega)$$
 (3b)

where $f_{\rm re}(\omega) = {\rm Re}(f(\omega))$ and $f_{\rm im}(\omega) = {\rm Im}(f(\omega))$ are the real and imaginary parts of $f(\omega)$, respectively. We also note that, in the context of EIS, $f_{\rm re}(\omega)$ and $f_{\rm im}(\omega)$ are even and odd, respectively.[1] Enforcing one of the two equations in (3) implies that the other is satisfied.[32] Therefore, meeting (3) is equivalent to fulfilling the KK relations, which are the even and odd HTs.[1, 32]

Lastly, we wish to stress on a notational point. When we have a function $g(\omega, \theta)$ depending on multiple variables and want to take the HT of $g(\omega, \theta)$ with respect to ω , we will explicitly indicate the variable used in the transformation by adding a subscript under the H symbol. For example, for $g(\omega, \theta)$, we will designate with $H_{\omega}g(\omega, \theta)$ the following:

$$H_{\omega}g(\omega,\boldsymbol{\theta}) = \frac{1}{\pi}P \int_{-\infty}^{\infty} \frac{g(\widehat{\omega},\boldsymbol{\theta})}{\omega - \widehat{\omega}} d\widehat{\omega}$$
(4)

2.2 The Bayesian Hilbert Transform of Impedance Data

In this section, we describe how the BHT of EIS data is formulated. The BHT methodology is schematically illustrated in Figure 1. The cornerstone of the method is to approximate the impedance using a finite expansion over a latent vector \mathbf{x} . Then, from \mathbf{x} , we compute the HT by matrix multiplication. Throughout, we will use Bayesian statistics. That is, we will attach a

Gaussian probability distribution to the regressed impedance and the predicted HT by assuming that the latent x follows some prior pdf. Most importantly, we provide a set of scores that gauge how experimental, regressed, and HT EIS spectra compare to one another.

2.2.1 Approximation

As outlined in the introduction, we will leverage an expansion of the impedance on some basis set $\{\psi(\omega,\lambda)\}$, where the $\psi(\omega,\lambda)$'s are complex-valued transfer functions dependent on a parameter λ such that $\lim_{\omega\to\infty}\psi(\omega,\lambda)=0$. Explicitly, we will model the impedance to be

$$Z(\omega) = i\omega L_0 + R_\infty + \int_{\mathbb{R}} \psi(\omega, \lambda) \gamma(\lambda) d\lambda$$
 (5)

where $\gamma(\lambda)$ is some latent function to be determined. Here, we will take $\psi(\omega, \tau) = \frac{1}{1+i\omega\tau}$ and $\lambda = \log \tau$ to obtain a DRT-like approximation of the following type: [42]

$$Z(\omega) = i\omega L_0 + R_{\infty} + \int_{-\infty}^{\infty} \psi(\omega, \tau) \, \gamma(\log \tau) d\log \tau$$
 (6)

If the term $i\omega L_0$ is discarded, the HTs of the real or imaginary parts of the impedance can be obtained using $H_\omega \psi(\omega, \tau) = i \psi(\omega, \tau)$:

$$HZ(\omega) = \int_{-\infty}^{\infty} H_{\omega}(\psi(\omega, \tau)) \gamma(\log \tau) d\log \tau$$

$$= i \int_{-\infty}^{\infty} \psi(\omega, \tau) \gamma(\log \tau) d\log \tau$$
(7)

Explicitly, if we define $\psi_{\rm re}(\omega,\tau)={\rm Re}\big(\psi(\omega,\tau)\big)=\frac{1}{1+(\omega\tau)^2}$ and $\psi_{\rm im}(\omega,\tau)={\rm Im}\big(\psi(\omega,\tau)\big)=-\frac{\omega\tau}{1+(\omega\tau)^2}$, we can write that

$$Z_{\rm re}(\omega) = HZ_{\rm im}(\omega) = \int_{-\infty}^{\infty} \psi_{\rm re}(\omega, \tau) \, \gamma(\log \tau) d\log \tau \tag{8a}$$

$$Z_{\rm im}(\omega) = -HZ_{\rm re}(\omega) = \int_{-\infty}^{\infty} \psi_{\rm im}(\omega, \tau) \, \gamma(\log \tau) d\log \tau \tag{8b}$$

Therefore, if we can estimate $\gamma(\log \tau)$ from either $Z_{\rm re}(\omega)$ or $Z_{\rm im}(\omega)$, then we will be able to obtain $Z_{\rm im}(\omega)$ or $Z_{\rm re}(\omega)$, respectively, thanks to (8). We must stress that, in the context of this article, we will not aim to assign any physical meaning to the (latent) function $\gamma(\log \tau)$. Also, if we choose $\gamma(\log \tau) = \sum_{n=1}^{N} R_n \tau \, \delta(\tau - \tau_n)$, where R_n is some parameter and $\delta(\tau - \tau_n)$ is a Dirac distribution centered at τ_n , we will retrieve the Voigt expansion used elsewhere in the context of the KK tests.[23, 25, 29]

To approximate $\gamma(\log \tau)$ numerically, we expand it over a finite set of functions $\mathcal{B} = \{\phi_1(\log \tau), \phi_2(\log \tau), ..., \phi_N(\log \tau)\}$ as

$$\gamma(\log \tau) = \sum_{n=1}^{N} \gamma_n \phi_n(\log \tau)$$
(9)

where the γ_n 's are scalars. By plugging (9) into (6), we can write the following two vector equations

$$\mathbf{Z}_{\rm re} = R_{\infty} \mathbf{1} + \mathbf{A}_{\gamma, \rm re} \boldsymbol{\gamma} \tag{10a}$$

$$\mathbf{Z}_{\rm im} = L_0 \boldsymbol{\omega} + \mathbf{A}_{\gamma, \rm im} \boldsymbol{\gamma} \tag{10b}$$

where $\boldsymbol{\gamma} = (\gamma_1, \gamma_2, ..., \gamma_N)^{\top} \in \mathbb{R}^N$ and the $\boldsymbol{Z}_{\mathrm{re}}, \boldsymbol{Z}_{\mathrm{im}}, \boldsymbol{1}, \boldsymbol{\omega} \in \mathbb{R}^M$ are vectors such that, for $1 \leq m \leq M$, $(\boldsymbol{Z}_{\mathrm{re}})_m = Z_{\mathrm{re}}(\omega_m)$, $(\boldsymbol{Z}_{\mathrm{im}})_m = Z_{\mathrm{im}}(\omega_m)$, $(\boldsymbol{1})_m = 1$, and $(\boldsymbol{\omega})_m = \omega_m$. Explicitly, the entries of the matrices $\boldsymbol{A}_{\gamma,\mathrm{re}}, \boldsymbol{A}_{\gamma,\mathrm{im}} \in \mathbb{R}^{M \times N}$ are defined as

We note that these two matrices may be obtained with any of the methods described elsewhere.[41, 43]

For notational convenience, we will define the following two matrices:

$$A_{\rm re} = (\mathbf{1}, A_{\gamma, \rm re}) \tag{12a}$$

$$\mathbf{A}_{\mathrm{im}} = (\boldsymbol{\omega}, \mathbf{A}_{\gamma, \mathrm{im}}) \tag{12b}$$

which allow us to rewrite (10) more compactly in the form

$$\mathbf{Z}_{\text{re}} = \mathbf{A}_{\text{re}} \mathbf{x}_{\text{re}} \tag{13a}$$

$$\mathbf{Z}_{\mathrm{im}} = \mathbf{A}_{\mathrm{im}} \mathbf{x}_{\mathrm{im}} \tag{13b}$$

where $\mathbf{x}_{\text{re}} = (R_{\infty} \quad \mathbf{\gamma}^{\mathsf{T}})^{\mathsf{T}}$ for (13a), and $\mathbf{x}_{\text{im}} = (L_0 \quad \mathbf{\gamma}^{\mathsf{T}})^{\mathsf{T}}$ for (13b).

We will suppose that a given EIS experiment is a realization of the following stochastic process:

$$\mathbf{Z}_{\text{exp,re}} = \mathbf{A}_{\text{re}} \mathbf{x}_{\text{re}} + \boldsymbol{\varepsilon}_{\text{re}} \tag{14a}$$

$$\mathbf{Z}_{\text{exp,im}} = \mathbf{A}_{\text{im}} \mathbf{x}_{\text{im}} + \boldsymbol{\varepsilon}_{\text{im}} \tag{14b}$$

where the "errors", $\varepsilon_{\rm re}$ and $\varepsilon_{\rm im}$, are two independent Gaussian RVs, such that $\varepsilon_{\rm re}$, $\varepsilon_{\rm im} \sim \mathcal{N}(\mathbf{0}, \sigma_n^2 \mathbf{I})$ with \mathbf{I} being the $M \times M$ identity matrix. In the ensuing derivation, we will drop the subscripts "re" and "im" from (14) as the two are notationally identical.

2.2.2 Bayesian Hilbert Transform

Bayesian methods leverage conditional probabilities. In particular, we can write that [44-46]

$$p(x|\boldsymbol{\omega}, \boldsymbol{Z}_{\exp})p(\boldsymbol{Z}_{\exp}|\boldsymbol{\omega}) = p(x)p(\boldsymbol{Z}_{\exp}|\boldsymbol{\omega}, x)$$
(15)

where $p(\cdot)$ is the pdf of the RV in the brackets, the symbol "|" indicates "conditioned to", and, again, \mathbf{Z}_{exp} is the experimentally measured real or imaginary part of the impedance. The $p(\mathbf{Z}_{\text{exp}}|\boldsymbol{\omega}, \boldsymbol{x})$ can be obtained from (14) as

$$p(\mathbf{Z}_{\exp}|\boldsymbol{\omega}, \mathbf{x}) = p(\boldsymbol{\varepsilon}) \propto \exp\left(-\frac{1}{2\sigma_n^2} \|\mathbf{A}\mathbf{x} - \mathbf{Z}_{\exp}\|^2\right)$$
 (16)

If we specify a prior on x (*i.e.* we assume p(x)), then we can obtain $p(x|\omega, \mathbf{Z}_{\exp})$. We will take $x \sim \mathcal{N}(0, \mathbf{W}^{-1})$, *i.e.*,

$$p(\mathbf{x}) \propto \exp\left(-\frac{1}{2}\mathbf{x}^{\mathsf{T}}\mathbf{W}\mathbf{x}\right) \tag{17}$$

with the matrix \boldsymbol{W} defined as

$$\boldsymbol{W} = \frac{1}{\sigma_{\beta}^{2}} \boldsymbol{I} + \frac{1}{\sigma_{\lambda}^{2}} \begin{pmatrix} 0 & 0 \\ 0 & \boldsymbol{p}_{q}^{\mathsf{T}} \boldsymbol{D}_{q} \end{pmatrix}$$
(18)

where σ_{β}^2 and σ_{λ}^2 are two real numbers and \boldsymbol{D}_q is the q^{th} order differentiation matrix.[41, 43]

Plugging (16) and (17) into (15) gives the posterior

$$p(\mathbf{x}|\boldsymbol{\omega}, \mathbf{Z}_{\text{exp}}) \propto \exp\left(-\frac{1}{2\sigma_n^2} \|\mathbf{A}\mathbf{x} - \mathbf{Z}_{\text{exp}}\|^2 - \frac{1}{2}\mathbf{x}^{\mathsf{T}}\mathbf{W}\mathbf{x}\right)$$
 (19)

From the latter, it follows that

$$x|\omega, Z_{\exp} \sim \mathcal{N}(\mu_x, \Sigma_x)$$
 (20)

where

$$\boldsymbol{\mu}_{x} = \frac{1}{\sigma_{n}^{2}} \boldsymbol{\Sigma}_{x} \boldsymbol{A}^{\mathsf{T}} \boldsymbol{Z} \tag{21a}$$

$$\mathbf{\Sigma}_{x} = \left(\frac{1}{\sigma_{n}^{2}} \mathbf{A}^{\mathsf{T}} \mathbf{A} + \mathbf{W}\right)^{-1} \tag{21b}$$

We note that $\boldsymbol{\mu}_{x}$ and $\boldsymbol{\Sigma}_{x}$ are functions of the scalars σ_{n}^{2} , σ_{β}^{2} , and σ_{λ}^{2} , which we will collect in the vector $\boldsymbol{\theta} = \left(\sigma_{n}^{2}, \sigma_{\beta}^{2}, \sigma_{\lambda}^{2}\right)^{\mathsf{T}}$.

Once the $x|Z_{\rm exp}$ is estimated, we can use (8) to compute $Z_{\rm H}(\omega_{\star})$, either $-HZ_{\rm im}(\omega_{\star})$ or $HZ_{\rm re}(\omega_{\star})$, at a new angular frequency ω_{\star} as

$$Z_{\mathrm{H}}(\omega_{\star}) = \boldsymbol{h} \, \boldsymbol{x} \sim \mathcal{N}(\boldsymbol{h} \, \boldsymbol{\mu}_{x}, \, \boldsymbol{h} \, \boldsymbol{\Sigma}_{x} \boldsymbol{h}^{\mathsf{T}})$$
(22)

where the column vector $\mathbf{h} \in \mathbb{R}^{N+1}$ is either \mathbf{h}_{re} or \mathbf{h}_{im} defined next. We note that $(\mathbf{h}_{re})_1 = (\mathbf{h}_{im})_1 = 0$, while all other entries (for n = 1, 2, 3, ..., N) are

$$(\mathbf{h}_{re})_{n+1} = \int_{-\infty}^{\infty} \psi_{re}(\omega_{\star}, \tau) \phi_n(\log \tau) d\log \tau$$
(23a)

$$(\mathbf{h}_{\text{im}})_{n+1} = \int_{-\infty}^{\infty} \psi_{\text{im}}(\omega_{\star}, \tau) \phi_n(\log \tau) \, d\log \tau \tag{23b}$$

More precisely, for the HT of the imaginary part of the data ($Z_{\rm exp} = Z_{\rm exp,im} \& Z_{\rm H} = Z_{\rm H,re}$) we need to take $h = h_{\rm re}$. Instead, for the HT of the real part of the data ($Z_{\rm exp} = Z_{\rm exp,re} \& Z_{\rm H} = Z_{\rm H,im}$) we need to set $h = h_{\rm im}$.

We can rewrite (22) in matrix form as

$$Z_{H}(\omega_{\star}) = Hx \sim \mathcal{N}(\mu_{H}, \Sigma_{H})$$
(24)

where the angular frequency vector is defined as $\boldsymbol{\omega}_{\star} = \left(\omega_{\star,1}, \omega_{\star,2}, \dots, \omega_{\star,K}\right)^{\mathsf{T}} \in \mathbb{R}^{K}$ and the $\boldsymbol{Z}_{\mathsf{H}}(\boldsymbol{\omega}_{\star}) = \left(Z_{\mathsf{H}}(\omega_{\star,1}), Z_{\mathsf{H}}(\omega_{\star,2}), \dots, Z_{\mathsf{H}}(\omega_{\star,K})\right)^{\mathsf{T}} \in \mathbb{R}^{K}$. Further to that,

$$\mu_H = H\mu_{\chi} \tag{25a}$$

$$\Sigma_{\mathrm{H}} = \boldsymbol{H} \, \boldsymbol{\Sigma}_{\boldsymbol{\chi}} \boldsymbol{H}^{\mathsf{T}} \tag{25b}$$

with the following definition of the matrix $\mathbf{H} \in \mathbb{R}^{K \times (N+1)}$

$$H(\boldsymbol{\omega}_{\star}) = \begin{pmatrix} \boldsymbol{h}(\omega_{\star,1}) \\ \boldsymbol{h}(\omega_{\star,2}) \\ \vdots \\ \boldsymbol{h}(\omega_{\star,K}) \end{pmatrix}$$
(26)

The DRT-only part of the EIS spectrum, i.e., $Z_{\rm DRT}$, for which the resistance and inductance contributions are not considered, can be obtained at ω_{\star} using

$$\mathbf{Z}_{\mathrm{DRT}}(\boldsymbol{\omega}_{\star}) = \mathbf{A}_{\mathrm{DRT}} \, \boldsymbol{x} \tag{27}$$

where the $A_{DRT} \in \mathbb{R}^{K \times (N+1)}$ is defined following analogous reasoning and notation behind (23) and (26). In particular, we will define the entries of $A_{DRT,re}$ or $A_{DRT,im}$ to be 0 in the first column, *i.e.* $(A_{DRT,re})_{k,1} = (A_{DRT,im})_{k,1} = 0$, and

$$(\mathbf{A}_{\mathrm{DRT,re}})_{k,n+1} = \int_{-\infty}^{\infty} \psi_{\mathrm{re}}((\boldsymbol{\omega}_{\star})_{k}, \tau) \, \phi_{n}(\log \tau) d\log \tau$$
 (28a)

for k = 1, 2, ..., K and n = 1, 2, ..., N. As above $\mathbf{Z}_{DRT}(\boldsymbol{\omega}_{\star})$ is a multivariate normal, *i.e.*,

$$\mathbf{Z}_{\mathrm{DRT}}(\boldsymbol{\omega}_{\star}) \sim \mathcal{N}(\boldsymbol{\mu}_{\mathrm{DRT}}, \boldsymbol{\Sigma}_{\mathrm{DRT}})$$
 (29)

where μ_{DRT} and Σ_{DRT} are defined as

$$\mu_{\text{DRT}} = A_{\text{DRT}} \, \mu_x \tag{30a}$$

$$\Sigma_{\text{DRT}} = A_{\text{DRT}} \, \Sigma_{x} \, A_{\text{DRT}}^{\mathsf{T}} \tag{29b}$$

2.2.3 Choosing the Hyperparameters

The analysis described in the previous subsection can be carried out only if the hyperparameter vector $\boldsymbol{\theta} = \left(\sigma_n^2, \sigma_\beta^2, \sigma_\lambda^2\right)^{\mathsf{T}}$ is set.[44, 45] To determine it, we will maximize the marginal likelihood (or evidence),[47] obtained by integrating (or marginalizing) the likelihood, (16), with respect to the prior:

$$p(\mathbf{Z}_{\exp}|\boldsymbol{\omega},\boldsymbol{\theta}) = \int_{\mathbb{R}^{N+1}} p(\mathbf{Z}_{\exp}|\mathbf{x},\sigma_n^2) p(\mathbf{x}|\sigma_{\beta}^2,\sigma_{\lambda}^2) d\mathbf{x}$$
(31)

As the prior is Gaussian, we can follow classical manipulations (see Section S.1 in Supplementary Information) and obtain[46]

$$\log p(\mathbf{Z}_{\exp}|\boldsymbol{\omega},\boldsymbol{\theta}) = \frac{1}{2}\log|\boldsymbol{W}| - \frac{1}{2}\log|\boldsymbol{\Sigma}_{x}^{-1}| - \frac{M}{2}\log(\sigma_{n}^{2}) - E(\boldsymbol{\mu}_{x}) - \frac{M}{2}\log(2\pi)$$
(32)

In the implementation of the BHT method, the θ maximizing the experimental evidence is found by minimizing the negative marginal log-likelihood defined as

$$\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\omega}, \boldsymbol{Z}_{\exp}) = -\log p(\boldsymbol{Z}_{\exp}|\boldsymbol{\omega}, \boldsymbol{\theta})$$
(33)

in other words

$$\boldsymbol{\theta} = \underset{\boldsymbol{\theta}'}{\operatorname{argmin}} \mathcal{L}(\boldsymbol{\theta}', \boldsymbol{\omega}, \boldsymbol{Z}_{\exp})$$
(34)

2.3 Scoring the EIS Data

In the scientific literature, there are no metrics that can be used to score the compliance of the EIS data with the KK relations. Therefore, we developed four new metrics based on residuals, mean predictions, and distances between estimated distributions. All the scores were defined so that their outcomes are real numbers between 0 and 1 (or equivalently 0 and 100%). An HT-consistent EIS spectrum will score near 1. Instead, an HT-inconsistent EIS spectrum will score close to 0.

In the literature about KK relations applied to EIS, the quality of the impedance data is typically assessed by examining the residuals. Such residuals are obtained by subtracting (up to a constant or a linear function of the angular frequency) the experimental real/imaginary data from the HT estimate obtained using the imaginary/real part of the EIS data. One metric could leverage the residuals by computing the number of experimental points that lie within k standard deviations of the HT prediction. Such a score can be formally defined as

$$s_{k\sigma,re} = \frac{1}{M} \sum_{m=1}^{M} 1(|R_{\infty} + Z_{H,re}(\omega_m) - Z_{\exp,re}(\omega_m)| \le k \sigma(\omega_m))$$
(35a)

$$s_{k\sigma,\text{im}} = \frac{1}{M} \sum_{m=1}^{M} 1(\left|\omega_m L_0 + Z_{\text{H,re}}(\omega_m) - Z_{\text{exp,im}}(\omega_m)\right| \le k \,\sigma(\omega_m))$$
(35b)

where $1(\cdot)$ is the indicator function, which is 1 if its argument is true and 0 otherwise, $\sigma(\omega_m)$ is the standard deviation of the HT at ω_m , and R_{∞} and L_0 are obtained by Bayesian regression

from $Z_{\rm exp,re}$ and $Z_{\rm exp,im}$, respectively. We note that $0 \le s_{k\sigma} \le 1$ and $s_{k\sigma} \le s_{(k+1)\sigma}$ and that the smaller the residual, the closer the score will be to 1.

The $s_{k\sigma,re}$ and $s_{k\sigma,im}$ metrics compare data, the realization of an RV, and predictions, other RVs. However, other useful scores could compare the two *de facto* analogous RVs, that can be obtained from different parts of the data, namely $Z_H(\omega) \sim \mathcal{N}(\mu_H, \Sigma_H)$ and $Z_{DRT}(\omega) \sim \mathcal{N}(\mu_{DRT}, \Sigma_{DRT})$. One proposed score, which we call s_μ , consists in summing 1 to the negative of the relative distance between the mean vectors μ_{DRT} and μ_H :

$$s_{\mu,\text{re}} = 1 - \frac{\|\boldsymbol{\mu}_{\text{DRT,re}} - \boldsymbol{\mu}_{\text{H,re}}\|}{\|\boldsymbol{\mu}_{\text{DRT,re}}\| + \|\boldsymbol{\mu}_{\text{H,re}}\|}$$
 (36a)

$$s_{\mu,im} = 1 - \frac{\|\mu_{\text{DRT,im}} - \mu_{\text{H,im}}\|}{\|\mu_{\text{DRT,im}}\| + \|\mu_{\text{H,im}}\|}$$
(36b)

From these last two formulas, it follows that $0 \le s_{\mu} \le 1$ and that the closer is s_{μ} to 1, the more similar the two means μ_{DRT} and μ_{H} will be.

Another sensible approach entails comparing the pdf's of $\mathbf{Z}_{H}(\boldsymbol{\omega})$ and $\mathbf{Z}_{DRT}(\boldsymbol{\omega})$. This comparison can be done using some metrics. One particularly convenient one is called the Hellinger distance (HD).[48] The square of the HD, $\left(\mathrm{HD}(f,g)\right)^2$, between two pdfs f(x) and g(x) can be defined as

$$\left(\mathrm{HD}(f,g)\right)^2 = 1 - \int \sqrt{f(x)g(x)} \, dx \tag{37}$$

where $0 \le HD(f,g) \le 1$ and HD(f,g) = 0 if and only if f(x) = g(x). Therefore, a viable score could use[48]

$$\left(\mathrm{HD}(p_{Z_{\mathrm{DRT}}}, p_{Z_{\mathrm{H}}})(\omega_{\star})\right)^{2} = 1 - \sqrt{\frac{2\sigma_{\mathrm{DRT}}\sigma_{\mathrm{H}}}{\sigma_{\mathrm{DRT}}^{2} + \sigma_{\mathrm{H}}^{2}}} e^{-\frac{1(\mu_{\mathrm{DRT}} - \mu_{\mathrm{H}})^{2}}{4\sigma_{\mathrm{DRT}}^{2} + \sigma_{\mathrm{H}}^{2}}}$$
(38)

where $p_{Z_{\mathrm{DRT}}}$ and $p_{Z_{\mathrm{H}}}$ are the pdfs of $Z_{\mathrm{DRT}}(\omega_{\star})$ and $Z_{\mathrm{H}}(\omega_{\star})$ at the scalar angular frequency ω_{\star} . We must point out that in (38) the dependence of μ_{DRT} , σ_{DRT} , μ_{H} , and σ_{H} on ω_{\star} has been omitted for the sake of keeping the equation compact. Similar to what we did for the residuals, we can define an average HD as follows

$$\overline{HD} = \frac{1}{M} \sum_{m=1}^{M} HD(p_{Z_{DRT}}, p_{Z_{H}})(\omega_{m})$$
(39)

which allows us to compute two HD scores, $s_{\rm HD,re}$ and $s_{\rm HD,im}$

$$s_{\rm HD,re} = 1 - \overline{\rm HD}_{\rm re}$$
 (40a)

$$s_{\rm HD,im} = 1 - \overline{\rm HD}_{\rm im} \tag{40b}$$

where $\overline{\text{HD}}_{re}$ is the average Hellinger distance between $Z_{\text{DRT,re}}$ and $Z_{\text{H,re}}$ over ω_{\star} and $\overline{\text{HD}}_{\text{im}}$ is the average Hellinger distance between $Z_{\text{DRT,im}}$ and $Z_{\text{H,im}}$ over ω_{\star} . We should stress that while $Z_{\text{DRT,re}}$ and $Z_{\text{H,im}}$ are obtained from the sole real part of the EIS spectrum, $Z_{\text{DRT,im}}$ and $Z_{\text{H,re}}$ are calculated using only the imaginary portion of the EIS. Therefore, both $\overline{\text{HD}}_{\text{re}}$ and $\overline{\text{HD}}_{\text{im}}$ compare the real part with the imaginary part of the EIS data.

A final metric leverages the Kullback-Leibler (KL) discrepancy or relative entropy, $d_{KL}(\cdot || \cdot)$, which is often used to measure the degree of similarity between the two pdfs.[46] Unfortunately, we were not able to produce a consistent score using the KL divergence alone, because $d_{KL}(\cdot || \cdot)$ is neither symmetric nor bounded. Instead, we will use the Jensen-Shannon

divergence (JSD), which is based on the KL but is symmetric and bounded between 0 and log 2.[49] If we define

$$Z_{\rm M}(\omega_{\star}) = \frac{1}{2} \left(Z_{\rm DRT}(\omega_{\star}) + Z_{\rm H}(\omega_{\star}) \right) \tag{41a}$$

the JSD between $Z_{DRT}(\omega_{\star})$ and $Z_{H}(\omega_{\star})$ is the following symmetrized KL divergence:

$$JSD(Z_{DRT}(\omega_{\star}), Z_{H}(\omega_{\star}))$$

$$= \frac{1}{2} \left(d_{KL}(Z_{DRT}(\omega_{\star})||Z_{M}(\omega_{\star})) + d_{KL}(Z_{H}(\omega_{\star})||Z_{M}(\omega_{\star})) \right)$$
(42a)

As we did above for residuals and HD, the average JSD will be averaged over the experiment as follows:

 $\overline{\text{JSD}}(Z_{\text{DRT}}, Z_{\text{H}})$

$$= \frac{1}{2M} \sum_{m=1}^{M} \left(d_{KL} \left(Z_{DRT}(\omega_m) || Z_{M}(\omega_m) \right) + d_{KL} \left(Z_{H}(\omega_m) || Z_{M}(\omega_m) \right) \right)$$
(43a)

Therefore, we can develop two JSD scores

$$s_{\rm JSD,re} = \frac{\log 2 - \overline{\rm JSD}_{\rm re}}{\log 2} \tag{44a}$$

$$s_{\rm JSD,im} = \frac{\log 2 - \overline{\rm JSD}_{\rm im}}{\log 2} \tag{44b}$$

where \overline{JSD}_{re} is the average JSD between $Z_{DRT,re}$ and $Z_{H,re}$ and \overline{JSD}_{im} is the average JSD between $Z_{DRT,im}$ and $Z_{H,im}$. Consistently with what we did for other scores, the s_{JSD} 's are bounded between 0 and 1 and a s_{JSD} close to 1 implies that Z_{DRT} and Z_{H} are consistent, while

if the s_{JSD} nears 0, the two are inconsistent. We must note that no close formula is known for the JSD, therefore the \overline{JSD} was obtained by Monte Carlo sampling.

3 Results

3.1 Synthetic Experiments

To benchmark the performance of the BHT method, we tested it systematically against controlled synthetic experiments with known standard circuits. In this section, we will illustrate the BHT framework and the EIS data scoring. The BHT method follows the logical path shown in Figure 1. All circuits studied are reported in Table 1 with their parameters listed in Table 2. Consistently with our earlier articles, the frequency range of analysis was selected to be between 10^{-4} and 10^4 Hz with a resolution of 10 points per decade.[50, 51] We must stress that the experimental impedance was generated by adding white noise to the real and the imaginary parts of the exact impedance, consistently with (14) and (16). That is, given the exact circuit impedance, $Z_{\text{exact}}(\omega)$, the experimental data $Z_{\text{exp}}(\omega)$ is obtained as follows:

$$Z_{\rm exp}(\omega) = Z_{\rm exact}(\omega) + \varepsilon_{\rm re} + i \, \varepsilon_{\rm im}$$
 (45)

where $\varepsilon_{\rm re}$ and $\varepsilon_{\rm im}$ are independent and identically distributed RVs with a Gaussian distribution with a mean of 0 and standard deviation $\sigma_{n,\rm exp}$, *i.e.*, $\varepsilon_{\rm re}$, $\varepsilon_{\rm im} \sim \mathcal{N} \left(0, \sigma_{n,\rm exp}^2 \right)$. We note that $\sigma_{n,\rm exp}$ is conceptually different from σ_n . While $\sigma_{n,\rm exp}$ is a parameter used to draw the synthetic experimental data, σ_n is one of the hyperparameters optimized by maximizing the evidence. In all synthetic experiments, we set $\sigma_{n,\rm exp} = 0.8~\Omega$, a relatively high value for the given circuit parameters.

As a first step, we investigated how the BHT performs for a resistor in series with a ZARC element. The corresponding synthetic impedance spectrum obtained using (45) is shown in Figure 2. The real and imaginary parts can be separated and regressed separately using (20) to obtain the latent x. In turn, x can be used to obtain 1) the regressed and smoothed impedance, Z; 2) the R_0 - and L_0 -subtracted impedance, Z_{DRT} ; and 3) the HT impedance, Z_H . The real and imaginary parts of the experimental EIS are shown in Figure 2 (b) and (c). In these two panels, the mean impedance (black line) and the 3σ credible intervals (solid grey shading) are reported. By visual inspection, it appears that the artificial experiments fall within the credible bands. As already outlined above, the hyperparameter vector $\boldsymbol{\theta} = \left(\sigma_n^2, \sigma_\beta^2, \sigma_\lambda^2\right)^\mathsf{T}$ used to find these estimates was obtained by evidence maximization, which was achieved by finding the minimum of $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\omega}, \boldsymbol{Z}_{\text{exp}})$ with respect to $\boldsymbol{\theta}$. We plotted in Figure 3 the $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\omega}, \boldsymbol{Z}_{\text{exp,re}})$, panel (a), and $\mathcal{L}(\theta, \omega, Z_{\mathrm{exp,im}})$ as a function of σ_{β} and σ_{λ} , where in both cases the σ_n was fixed, i.e., $\sigma_n = \sigma_{n,\text{exp}}$. We can see that the minimum is rather sharp and elongated along the σ_{λ} direction, indicating a small penalty on the derivative. Interestingly, for both real and imaginary data, the minima are obtained for relatively small values of $\frac{1}{\sigma_B^2}$ and $\frac{1}{\sigma_A^2} (\frac{1}{\sigma_B^2} = 2.93 \times 10^{-3})$ and 7.36×10^{-3} and $\frac{1}{\sigma_1^2}=1.36\times10^{-3}$ and 1.36×10^{-3} for the real and imaginary parts, respectively), which correspond to a small smoothing penalty, as realized by the matrix W, on the prior-less term $\frac{1}{\sigma_n^2} \mathbf{A}^T \mathbf{A}$. After conducting the Bayesian regression, $Z_{\rm H}$ and $Z_{\rm DRT}$ can be predicted. In particular, upon adding the R_{∞} or ωL_0 , the $Z_{\rm H}$ can be compared to the experiments. The comparison is reported in Figure 4 (a) and (b) for the real and imaginary parts of the EIS, respectively. It is apparent that $Z_{\rm H}$ as obtained from the imaginary (real) part can well recover the real (imaginary) part of the synthetic experiment. This is further confirmed by the s_{μ} values,

which are in the range of 95%-98%, see Table 3. An alternative view is given by the residuals, which are obtained by subtracting the experimental data from the mean HT's impedance, $\mu_{\rm H}$, plus the offset R_{∞} or ωL_0 . Figure 4 (c) and (d) report the real and imaginary residuals, respectively, together with their 3σ bands (solid gray region). We can observe that all points fall within the grey region, indicating that $s_{3\sigma,\rm re}=s_{3\sigma,\rm im}=100\%$. From the scores reported in Table 3, the residual scores are high, suggesting that the EIS spectrum is HT- (or KK-) consistent. However, we note that a visual inspection of the residuals does not yield any direct information about the distribution of the residuals. Therefore, we also reported the kernel-estimated densities of the residuals in Figure 4 (e) and (f). There, we observe that the densities are centered around 0 and endowed with a high degree of symmetry. Further, as one can see from Table 3, the s_{μ} , $s_{\rm HD}$, and $s_{\rm JSD}$ are closer to 100% rather than 0, suggesting that the estimated distributions of $Z_{\rm H}$ and $Z_{\rm DRT}$ also match one another.

We then analyzed two sets of synthetic experiments based on two ZARCs (indicated as $2\times ZARC$) in series, see Table 1 and Table 2 for the exact impedance and parameters used, respectively. For these circuits, it is well known that the latent γ cannot be obtained easily, especially if the smoothing (i.e. $\frac{1}{\sigma_{\lambda}^2}$) is too strong and the characteristic timescales are partially or fully overlapping. [44, 45] Figure 5 (a) and (b) report the exact and synthetic EIS spectra of the two cases. Figure 5 (c) and (d) correspond to the regressed imaginary parts. We note that similar regression was also done for the real part, see Table 3, but is not shown for the sake of brevity. Before discussing Figure 6, we must point out that the panels (a) & (c) and (b) & (d) of Figure 5 correspond to (a), (c) & (e) and (b), (d) & (f) in Figure 6. The obtained HT's impedances, Z_H , are plotted in Figure 6 (a) and (b). Both Z_H match well the synthetic experiment, leading to $s_{\mu} \approx 100\%$. Similarly, we plotted residuals and their distributions in

Figure 6 (c) & (e) and (d) & (f). Unsurprisingly, the results are consistent with expectations that the residuals should fall within the 3σ bands with rather symmetric distributions. As shown in Table 3, all scores confirm the built-in consistency of the EIS spectrum.

We also applied the BHT method to the piecewise constant (PWC) element. This element is somewhat pathological because the exact γ is discontinuous and therefore requires *ad hoc* regularization.[44, 45] We report in Figure 7 (a) the exact and synthetic EIS of the PWC element and in Figure 7 (b) the regressed imaginary part. The $Z_{H,im}$, reported in Figure 7 (c), which was obtained with the data of Figure 7 (b), matches the experiment well. Furthermore, the residuals, shown in Figure 7 (d), appear to be well within the 3σ credible interval with the underlying distribution being characterized by some degree of symmetry. The scores, see Table 3, are also consistent with the visual analysis and indicate, as expected, that the data comply with the HT.

The synthetic experiments illustrated above assumed that there was only one resistor in the series being connected to the main elements. However, inductive features could also be present in the EIS data. These inductances could be modeled by adding a ωL_0 term to the imaginary part of the impedance, see (5). While the HT of a constant is formally 0, the HT of ωL_0 is infinite.[32] Therefore, the inductance component needs to be subtracted from the impedance data at the regression stage and added later. This is a delicate issue that the BHT method can handle. We show that in Figure 8 (a), where an inductor is added to the circuit of Figure 2 (a), see Table 2 for the parameter values. Not only could our framework recover the imaginary part of the impedance, as shown in Figure 8 (b), but it also reliably retrieved an HT of the data that matched the experiments well. This consistency is shown in the prediction and residual plots in Figure 8 (c) and (d), respectively, and in all computed scores, see Table 3. One may also

wonder how well the BHT would do in retrieving the mean values of the circuit parameters, i.e., R_{∞} and L_0 , and the $\sigma_{n, \exp}$ from $\boldsymbol{\theta}$. We tested that by carrying out 2000 artificial experiments, for which the $\boldsymbol{\theta}$'s were obtained by maximizing the evidence. The resulting mean values of R_{∞} and L_0 and the corresponding $\sigma_n = (\boldsymbol{\theta})_1$ are shown in Figure 9 as a joint distribution plot. The values obtained deviate little from their externally assigned values, see Table 2, showing little correlation to one another. One important point to note is that, while these point estimates did not comply with the Bayesian philosophy, we think it is important to highlight that the BHT methodology developed here consistently retrieves the ground truth of the studied synthetic experiments.

Furthermore, we wished to determine if the BHT could detect inconsistent impedance data. As a first example, we used a circuit composed of two slightly different transfer functions for the real and the imaginary parts. The actual model is shown in the last row of Table 1, and the parameters can be found in Table 2. The Nyquist plot of such an artificial impedance is shown in Figure S1 (a). In this specific case, the exact impedance is not a transfer function, and therefore, the HT is expected to detect that. In other words, if we performed HT on $Z_{re}(\omega)$, we would not be able to obtain $Z_{im}(\omega)$ and vice versa. The inconsistency of the data is not apparent if the real and the imaginary parts of the EIS are regressed using the BHT, see Figure S1 (a) and (b). On the other hand, the HTs in Figure S2 (a) and (b) show a significant deviation from the experimental data. This discrepancy is even more evident if one looks at the residuals, which are bimodally distributed, see Figure S2 (c) and (d). Further, all scores in Table 3 are lower than that of the previous synthetic experiments, indicating a decreased reliability and inconsistency in the data.

As a second example, we used frequency-dependent drift on a given EIS parameter to model deviations from an ideal transfer function. We showed the BHT and corresponding scores were able to detect that the EIS data is inconsistent as a consequence of the drift. To generate the EIS spectra, we employed the same baseline $2\times ZARCs$ impedance model illustrated above (see the second lines of Table 1 and Table 2). The low-frequency drift function, $\zeta(\omega,\rho) = \frac{1}{\log \frac{\omega_{\max}}{\omega_{\min}}} \log \left(\frac{\omega_{\max}^{\rho} \omega^{1-\rho}}{\omega_{\min}} \right)$, multiplied $R_{ct,2}$ as follows

$$R_{\rm ct,2}(\omega) = R_{\rm ct,2} \, \zeta(\omega, \rho) \tag{46}$$

where ω_{\max} and ω_{\min} are the highest and the lowest angular frequencies, respectively, and ρ is a number between 1 and 1.5; $\rho=1$ indicates no drift, *i.e.*, no deviation from ideality. The real and imaginary parts of the exact impedance are shown in Figure 10 (a) and (b). Figure S3 (a), (b), and (c) show the Nyquist plot and real and imaginary parts of select synthetic EIS spectra, respectively. Using 1000 synthetic experiments for each ρ , we computed the average $\bar{s} = \frac{s_{re} + s_{lm}}{2}$ of the scores described in Section 2.3. As shown in Figure 10 (c), all the scores, except for \bar{s}_{μ} , decrease as ρ increases. This trend is consistent with the intuition that increasing the drift will increase the inconsistency in the impedance data and therefore decrease \bar{s} . Additionally, we report regression and prediction results as well as the residuals for $\rho=1.5$ and $\sigma_{n,\exp}=0.1,0.8$, and $1.6~\Omega$ in Figure S4, S5, S6. Inconsistency between the real and imaginary part of the synthetic data can be observed by comparing with the BHT prediction with the real part shown in the panels (c). The residual plots in the (d) panels of these figures correctly indicate severe non-stationarity at low frequencies, with the credible bands increasing as $\sigma_{n,\exp}$ increases.

As a third example, we used the model of Murer and co-workers,{Murer, 2020 #60} which is inspired by corrosion and consists of the following RC impedance with time-drifting polarization resistance:

$$Z(\omega) = R_{\Omega} + \frac{R_{\rm p}(t)}{1 + i \,\omega \,R_{\rm p}(t)C_{\rm dl}} \tag{47}$$

where $R_{\Omega} = 50 \,\Omega$, $R_{\rm p}(0) = 500 \,\Omega$, $t(f_n) = \sum_{k=1}^{n} \frac{1}{f_k}$, $C_{\rm dl} = 2 \times 10^{-2} \,\rm F$, and $R_{\rm p}(t) = R_{\rm p}(0) - k_-\sqrt{t}$ with $k_- = 1.5 \,\frac{\Omega}{\sqrt{s}}$ or $R_{\rm p}(t) = R_{\rm p}(0) + k_+t^2$ with $k_+ = 5 \times 10^{-6} \,\frac{\Omega}{\rm s^2}$ for time decreasing or increasing polarization resistence, respectively. The corresponding Nyquist plots are shown in Figure 11 (a) (decreasing) and (b) (increasing) where the reference spectrum with $R_{\rm p}(t) = R_{\rm p}(0)$, the drifting noiseless impedance, and stochastic experiments with $\sigma_{n,\rm exp} = 3 \,\Omega$ are presented. After regressing real and imaginary parts of the spectra, see panels (a) and (b) of Figure S7 and Figure S8, we computed the HT and compared that to the imaginary and real parts of the spectra as shown in panels (c) and (d) of Figure S7 and Figure S8. The deviations, as present in the residuals in panels (c) to (f) of Figure 11, indicate that the BHT method can correctly capture the time drifting in the underlying EIS data.

As a last set of synthetic experiments, We also studied if the BHT approach developed could be used to test if EIS data from batteries and supercapacitors are HT-compliant. To be consistent with the theory above, we applied the BHT to the admittance defined as $Y(\omega) = 1/Z(\omega)$. More details can be found in Section S.2 of the SI. We first evaluated the synthetic data obtained using the DDT (distribution of diffusion times) model,[52, 53] see Section S.3 for details. The admittance of the real part and the imaginary part as obtained by BHT are shown in Figure S9 (c) and (d); both match well the synthetic experiments. Additionally, the residual points and their distributions are shown in Figure S9 (e) and (f). All residuals center

near 0 with a seemingly unimodal distribution, suggesting that the EIS data are consistent. The scores listed in Table 3 also support this conclusion. As a second example, we generated the synthetic impedance of a Li₃N battery[56] with the frequencies selected in the range from 18 Hz to 4×10^5 Hz. The Nyquist plots of the impedance and corresponding admittance are shown in Figure S10 (a) and (b), respectively. The admittance predicted by the BHT is reported in Figure S10 (c) and (d). While a good match can be observed for $f \le 7\times10^4$ Hz, above that threshold, a small discrepancy appears. The residuals shown in Figure S10 (e) and (f) also reflect this deviation.

3.2 Real Experiments

The analysis of the BHT method would be incomplete if real experiments were not analyzed. For this reason, we examined two sets of experimental data that had been used in our prior publications.[43-45] First, we tested the BHT against the data obtained from a commercial battery.[43, 45] The EIS spectrum was collected from a LiCoO₂ battery (Ansmann 18650) at a 25% state of charge from 5 mHz to 600 Hz with 10 points per decade. The impedance spectrum is drawn in Figure S11 (a). We first estimated the imaginary part of the spectrum using Bayesian regression. The estimated impedance data shows little deviation from the experimental measurement and falls within an extremely narrow credible band, see Figure S11 (b). For the obtained $Z_{\rm H,re}$, the credible band only slightly enlarges to be observable and the deviations are still small, see Figure S11 (c). We further plotted the discrepancy between $Z_{\rm H}$ and $Z_{\rm exp}$ in Figure S11 (d), where clear deviations appear only at low frequencies for $f \leq 10^{-2}$ Hz. The distribution of residuals reflects this insight and is centered at the origin with small dissymmetric fringes around it. The scores in Table 3 also support the above assessment and

suggest that the quality of the imaginary part of the spectrum is likely to be better than that of the real part.

We also analyzed an EIS spectrum obtained from a symmetrical solid oxide fuel cell (SOFC) with 15% Sm-doped CeO₂ (SDC) as the electrolyte and Ba_{0.95}La_{0.05}Fe_{0.95}P_{0.05}O_{3.8} (BLFP) as the electrode.[54] The impedance data were obtained at 700 °C under a synthetic air atmosphere (a mixture of N₂ and O₂ in a 0.79:0.21 ratio) and a total pressure of 1 atm. The EIS measurement was conducted in a frequency ranging from 0.1 Hz to 2.47×10^4 Hz with 15 points per decade, as reported in Figure 12 (a). While we performed BHT regression for both the real and the imaginary part of the experimental data, we only show the analysis of $Z_{\rm exp,im}$. As shown in Figure 12 (b), Bayesian regression is capable of capturing the imaginary part well with no notable discrepancy and a credible band too narrow to be observable. The high quality of the data is evident from Figure 12 (d), where a remarkably good match is observed between the $R_{\infty} + Z_{\rm H,re}$ and the $Z_{\rm exp,im}$. We further show the residual between these two terms in Figure 12 (d). One can notice that the residuals are unimodally distributed with the center of the distribution placed near the origin. The high quality of the impedance data is further confirmed by the scores listed in Table 3, which indicate strong compliance with the HT.

We also tested the validity of the BHT approach developed against experimental battery data, where, as above, the analysis was done on the admittance. As a first example, we used data taken from a MoS₂-based battery.[55] The Nyquist plot of the EIS spectrum is shown in Figure 13 (a) with the corresponding admittance in Figure 13 (b). As shown in Figure 13 (c) and (d), the BHT can retrieve the experimental data reliably, suggesting consistency. This is further confirmed by the residual plots, see Figure 13 (e) and (f), which are unimodally distributed and centered around the origin. The obtained scores, see Table 3, also support the conclusion that

the admittance of the MoS₂ is HT-consistent. Another example is that of a silicon-nanowire-based lithium-ion battery.[57] Figure S12 (a) and (b) show the Nyquist plot of the impedance and corresponding admittance. One can observe that the BHT'd admittance matches the experimental data well, see Figure S12 (c) and (d). The residuals have unskewed distributions with their means located near the origin. The scores are also HT-consistent and indicate good data quality.

4 Conclusions

Compliance with the HT or the KK relations is a cornerstone of EIS analysis. While this is an important and generally appreciated fact, practitioners rarely test their data for that. In this article, we aim at bridging this gap by putting forward two innovations. First, we reframed the HT in a probabilistic Bayesian framework. Doing so allowed us to identify the credibility of the HT'd EIS data and, in turn, use that credibility to compare predictions. Second, we established several criteria to score the impedance data. We assigned a score value between 0 and 1, where the higher the score, the better the experimental impedance $Z(\omega)$ compliance with the HT. The scores were developed by leveraging residuals, distances between the means, and probabilistic discrepancies between predictions. By applying the BHT to the admittance, we established that it could be used to analyze unbounded EIS spectra typical of batteries and supercapacitors.

Various research topics could expand on this work. The basis set used here could be further extended to include spectral and pseudo-spectral elements, *e.g.*, radial-basis functions, to improve accuracy. Also, more metrics may be developed to score the quality of EIS against the KK relation or HT. Furthermore, new standardized test cases and procedures may be proposed to benchmark algorithms that assess the compliance of EIS data with the HT or KK relations.

Sharing our source code may prove to be useful to researchers and speed up innovations in this area. We also added related functionalities to the DRTtools with the intent of releasing an easy-to-use HT package to the entire electrochemical community. Lastly, we wish to emphasize that by formalizing a BHT method, this article may revive research in the area and promote the benchmarking of the EIS data consistency by HT or KK relations.

Code availability

The implementation of the method can be found at https://github.com/ciuccislab/BHT and https://github.com/site/drttools/

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List of abbreviations and symbols

BHT Bayesian Hilbert transform DRT Distribution of relaxation times **EIS** Electrochemical impedance spectroscopy HT Hilbert transform HD Hellinger distance JSD Jensen-Shannon divergence KK Kramers-Kronig KL Kullback-Leibler Probability distribution function pdf RV Random variable **SOFC** Solid oxide fuel cell A Matrix used to regress the experimental data, \mathbf{Z}_{exp} Matrix used to calculate Z_{DRT} A_{DRT} Differentiation matrix (q^{th} order) \boldsymbol{D}_a f Frequency h Column vector used to compute $Z_{\rm H}$ H Matrix used to compute Z_H I **Identity** matrix Inductance L_0 $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\omega}, \boldsymbol{Z}_{\text{exp}})$ Negative log-likelihood $p(\cdot)$ Probability distribution function Ohmic resistance R_{∞} Score based on the residuals $S_{k\sigma}$ Score based on the estimated means S_{μ}

Score based on the Hellinger distance score

Score based on the Jensen-Shannon divergence

 s_{HD}

 $S_{\rm ISD}$

W Inverse of the covariance matrix of the prior on x

x Latent vector

 $\mathbf{Z}_{\mathrm{exp}}$ Vector of experimental EIS data

Z_H Vector of HT'd impedance

 $\mathbf{Z}_{\mathrm{DRT}}$ Vector of impedance (DRT part only - i.e., R_{∞} and $i\omega L_0$ terms excluded)

 $\gamma(\log \tau)$ Latent function

 γ Vector of $\gamma(\log \tau)$'s

 ε Experimental error

θ Vector of hyper-parameters, *i.e.*, $\boldsymbol{\theta} = (\sigma_n^2, \sigma_\beta^2, \sigma_\lambda^2)^{\mathsf{T}}$

 μ_x Mean of x

 $\mu_{\rm H}$ Mean of $Z_{\rm H}$

 μ_{DRT} Mean of $\mathbf{Z}_{\mathrm{DRT}}$

 $\sigma_{n, \text{exp}}$ Standard deviation of the synthetic impedance error

 σ_n Hyperparameter (standard deviation of the experimental error)

 σ_{β} Hyperparameter (norm penalty)

 σ_{λ} Hyperparameter (norm of the derivative penalty)

 Σ_x Covariance of x

 $\Sigma_{\rm H}$ Covariance of $Z_{\rm H}$

 Σ_{DRT} Covariance of Z_{DRT}

 $\phi_n(\log \tau)$ Basis function

 $\psi(\omega, \log \tau)$ Complex transfer function

 ω Angular frequency ($\omega = 2\pi f$)

 ω_{\star} Angular frequency at which one predicts $Z_{\rm H}$

 ω Vector of angular frequencies

 $\boldsymbol{\omega}_{\star}$ Vector of $\boldsymbol{\omega}_{\star}$'s

Algorithm

 $Z_{\mathrm{exp,re}}$ and $Z_{\mathrm{exp,im}}$ Input:

Output: Z_{re} , Z_{im} , $Z_{H,re}$, $Z_{H,im}$, $Z_{DRT,re}$, and $Z_{DRT,im}$

for $\mathbf{Z}_{\mathrm{exp}}$ in $\{\mathbf{Z}_{\mathrm{exp,re}}, \mathbf{Z}_{\mathrm{exp,im}}\}$:

- Compute optimal θ = (σ_n², σ_β², σ_λ²)^T using (33)
 Estimate μ_x and Σ_x using (21)
 Compute μ_H and Σ_H using (25), μ_{DRT} and Σ_{DRT} using (29)

end

compute the scores $s_{k\sigma}$, s_{μ} , s_{HD} , and s_{ISD} .

a. $Z_{\rm H,re}$ + R_{∞} and $Z_{\rm H,im}$ + $i\omega L_0$ against $Z_{\rm exp,re}$ and $Z_{\rm exp,im}$, respectively

b. residuals and density distribution

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Table 1 – Exact EIS responses used for the synthetic experiments.

Model	Z(f)	Reference	Ref.
			Figures
ZARC	$R_{\infty} + \frac{R_{\rm ct}}{1 + (i2\pi f \tau_0)^{\phi}}$	[31]	2-4
2×ZARC	$R_{\infty} + \frac{R_{\text{ct},1}}{1 + (i2\pi f \tau_1)^{\phi_1}} + \frac{R_{\text{ct},2}}{1 + (i2\pi f \tau_2)^{\phi_2}}$	[31]	5-6
Piecewise Constant (PWC)	$R_{\infty} + \frac{R_{\rm ct}}{\ln \frac{\tau_2}{\tau_1}} \left(\ln \left(1 - \frac{i}{2\pi f \tau_1} \right) - \ln \left(1 - \frac{i}{2\pi f \tau_2} \right) \right)$	[44]	7
L ₀ +ZARC	$i\omega L_0 + R_\infty + \frac{R_{\rm ct}}{1 + (i2\pi f \tau_0)^\phi}$		8-9
Failed experiment	$R_{\infty} + \text{Re}\left(\frac{R_{\text{ct}}}{1 + (i2\pi f \tau_0)^{\phi_1}}\right) + \text{Im}\left(\frac{R_{\text{ct}}}{1 + (i2\pi f \tau_0)^{\phi_2}}\right)$		S1-S2

Table 2 – Values of the circuit parameters utilized in the synthetic experiments.

Model	$R_{\infty}(\Omega)$	$R_{\mathrm{ct}}\left(\Omega\right)$	τ_0 (s)	φ	L ₀ (H)	Ref. Figures
ZARC	10	50	1.0	0.8		2-4
2×ZARC	20	[50, 50]	[0.1, 10]	[0.8, 0.8]		5&6 LHS
2×ZARC	20	[50, 50]	[0.1, 1.0]	[0.8, 0.8]		5&6 RHS
PWC	10	50	[10, 0.1]			7
L ₀ +ZARC	10	50	1.0	0.8	5.0×10 ⁻⁴	8
L ₀ +ZARC	10	50	1.0	[0.8, 1.0]	5.0×10 ⁻⁴	S1-S2

Table 3 – Scores obtained for synthetic and real experiments.

	Residual						Mean		Hellinger Distance		Jensen-Shannon Discrepancy		Ref.
Element	$s_{1\sigma,\mathrm{re}}$	$s_{2\sigma,\mathrm{re}}$	$s_{3\sigma,\mathrm{re}}$	$s_{1\sigma,\mathrm{im}}$	$s_{2\sigma,\mathrm{im}}$	$s_{3\sigma,\mathrm{im}}$	S _{μ,re}	$s_{\mu, \mathrm{im}}$	s _{HD,re}	S _{HD,im}	S _{JSD,re}	S _{JSD,im}	Figures
ZARC	87.7%	100.0%	100.0%	60.5%	91.4%	100.0%	99.1%	97.6%	57.1%	63.6%	76.8%	79.6%	2-4
2×ZARC	74.1%	100.0%	100.0%	66.7%	95.1%	100.0%	99.5%	97.2%	62.6%	60.6%	79.3%	74.4%	5&6 LHS
2×ZARC	76.5%	100.0%	100.0%	61.7%	93.8%	100.0%	99.6%	97.6%	61.9%	57.3%	78.8%	71.1%	5&6 RHS
PWC	71.6%	100.0%	100.0%	64.2%	93.8%	100.0%	99.1%	96.2%	59.1%	56.2%	77.1%	70.5%	7
L ₀ +ZARC	87.7%	100.0%	100.0%	60.5%	91.4%	100.0%	99.1%	97.6%	57.1%	63.6%	76.8%	79.6%	8
Failed exp	54.3%	77.8%	86.4%	39.5%	75.3%	85.2%	95.9%	87.3%	35.1%	31.6%	48.0%	42.2%	S1-S2
DDT-model	88.9%	97.5%	100.0%	75.3%	81.5%	87.7%	99.4%	97.0%	60.5%	55.5%	78.6%	72.0%	S9
Li ₃ N	44.4%	92.6%	96.3%	75.3%	84.0%	86.4%	98.8%	97.7%	20.9%	55.6%	29.1%	67.4%	S10
LIB	94.1%	98.0%	100.0%	47.1%	80.4%	100.0%	99.3%	95.2%	81.0%	36.2%	93.1%	46.0%	<mark>S11</mark>
SOFC	100.0%	100.0%	100.0%	84.0%	98.8%	100.0%	99.7%	98.9%	67.4%	52.2%	86.5%	67.3%	11
2H MoS ₂	91.5%	97.9%	100.0%	76.6%	85.1%	93.6%	99.7%	99.0%	82.7%	68.3%	92.4%	80.0%	12
Si NC	92.6%	98.1%	98.1%	40.7%	63.0%	79.6%	99.5%	98.7%	57.6%	29.6%	77.3%	38.2%	S12

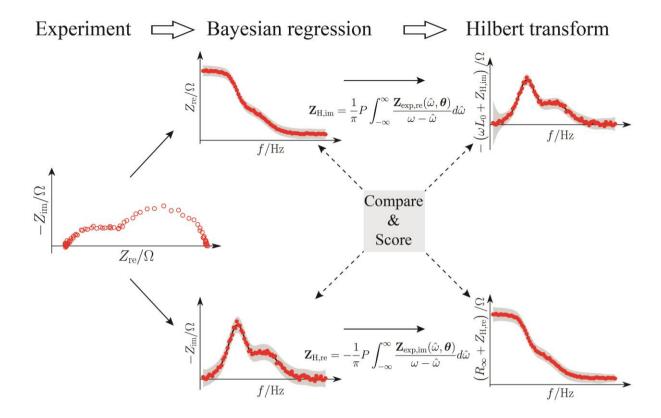


Figure 1 - Schematic illustration of the Bayesian Hilbert transform method as applied to electrochemical impedance spectroscopy data.

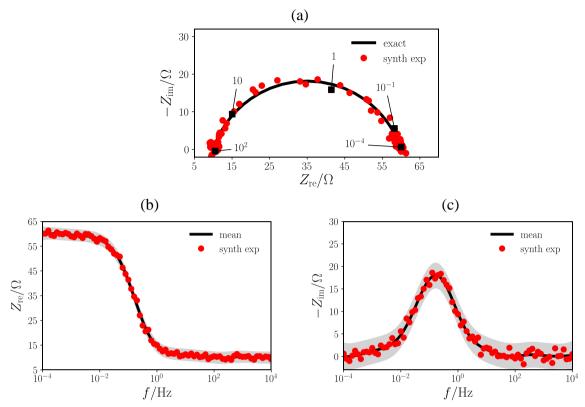


Figure 2 – (a) Nyquist plot of the synthetic experimental and exact impedance; the reported numbers indicate frequencies in Hz. (a) real and (b) imaginary parts of the impedance and Bayesian regression. Mean and 3σ credible intervals are shown as a black line and a solid grey region, respectively.

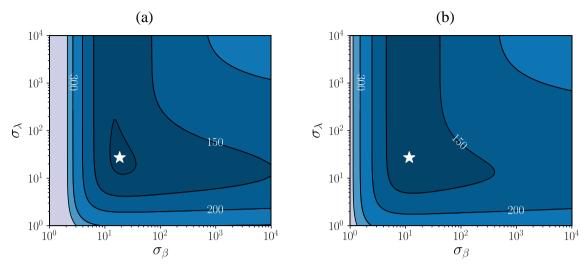


Figure 3 – Negative of the log-likelihood, $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\omega}, \boldsymbol{Z}_{\text{exp}}) = -\log p(\boldsymbol{Z}_{\text{exp}}|\boldsymbol{\omega}, \boldsymbol{\theta})$, computed for the (a) real and (b) imaginary of the impedance data of Figure 2. The σ_n was set to be equal to $\sigma_{n,\text{exp}}$ and the minimum is indicated with the star symbol.

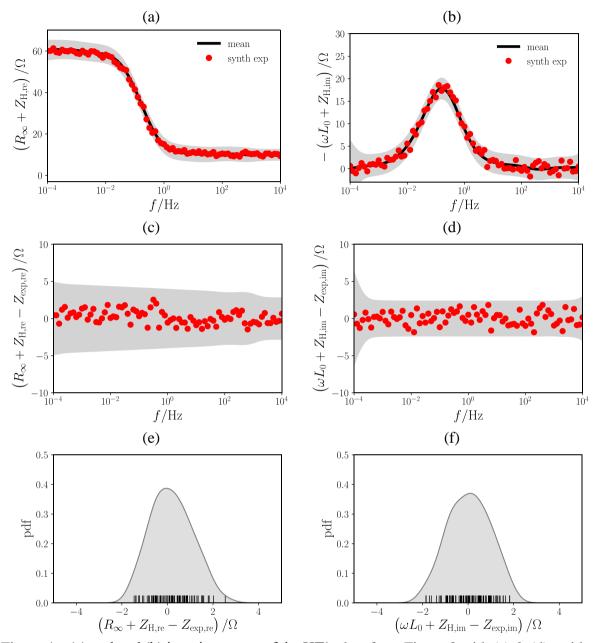


Figure 4 - (a) real and (b) imaginary part of the HT's data from Figure 2 with (c) & (d) residuals and (e) & (f) their distributions also shown.

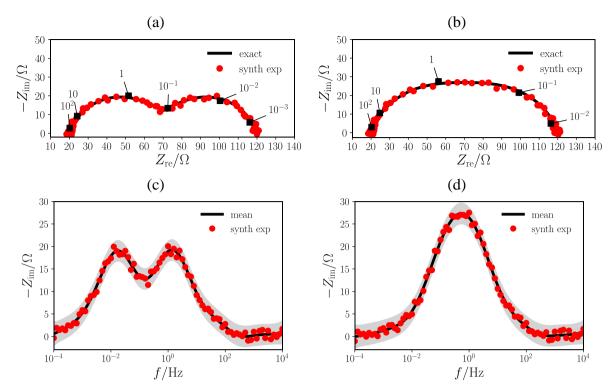


Figure 5 – Nyquist plot of the impedance response of two ZARC elements in series with (a) partially and (b) fully overlapping features; the reported numbers indicate frequencies in Hz. (c) and (d) imaginary part of the EIS spectrum as a function of the frequency and corresponding to the Nyquist plots in panels (a) and (b), respectively.

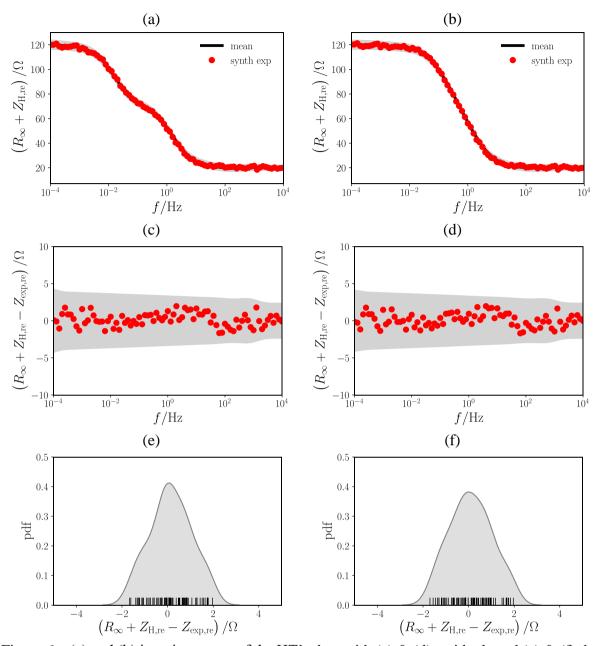


Figure 6 - (a) and (b) imaginary part of the HT's data with (c) & (d) residuals and (e) & (f) their distributions also shown. The left-hand and right-hand sides in this Figure correspond to the left-hand and right-hand sides of Figure 5.

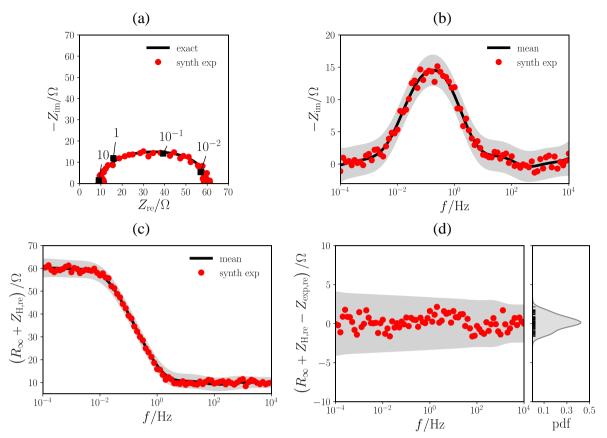


Figure 7 – (a) Nyquist plot of the EIS response of a PWC element; the reported numbers indicate frequencies in Hz. (b) The imaginary part of the EIS spectrum with Bayesian regression. (c) BHT of the $Z_{\rm exp,im}$ and (d) corresponding residuals vs. frequency.

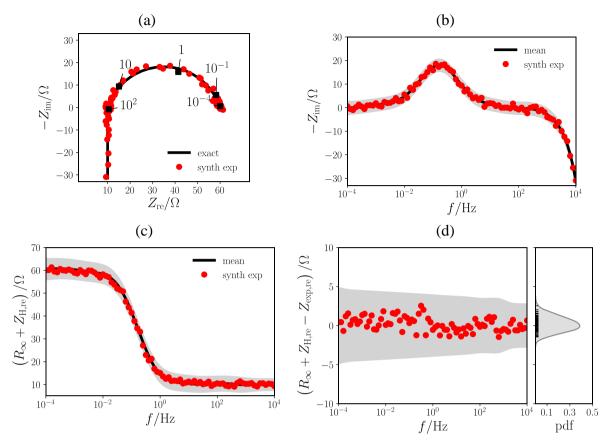


Figure 8 – (a) Nyquist plot of the EIS response of a ZARC element in series with a resistor and an inductor; the reported numbers indicate frequencies in Hz. (b) The imaginary part of the EIS spectrum with Bayesian regression. (c) BHT of the $Z_{\rm exp,im}$ and (d) corresponding residuals vs. frequency.

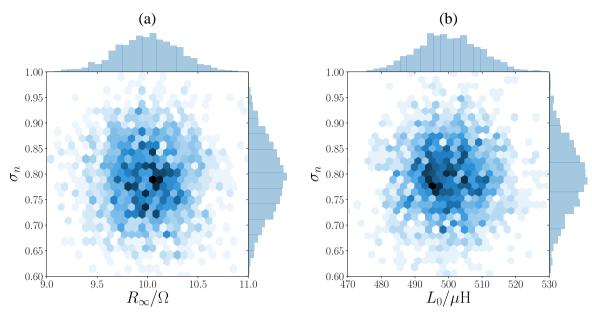


Figure 9 – Distribution of the optimal σ_n as obtained by evidence maximization and regressed R_{∞} and L_0 , the (a) imaginary and (b) real parts of the EIS spectrum were used to obtain these plots.

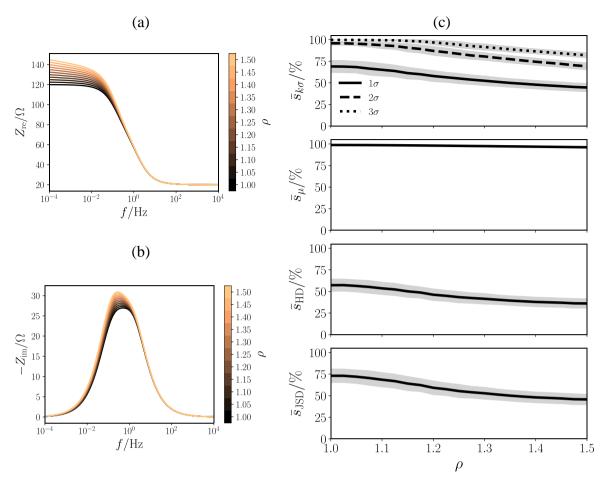


Figure 10 – (a) Real and (b) imaginary parts of the impedance of 2×ZARCs model with a ρ -dependent drift on $R_{\rm ct,2}$. (c) Re-im averaged scores, *i.e.*, $\bar{s} = \frac{s_{\rm re} + s_{\rm im}}{2}$. The lines and grey bands indicate the average and 1σ intervals as obtained from 1000 synthetic experiments.

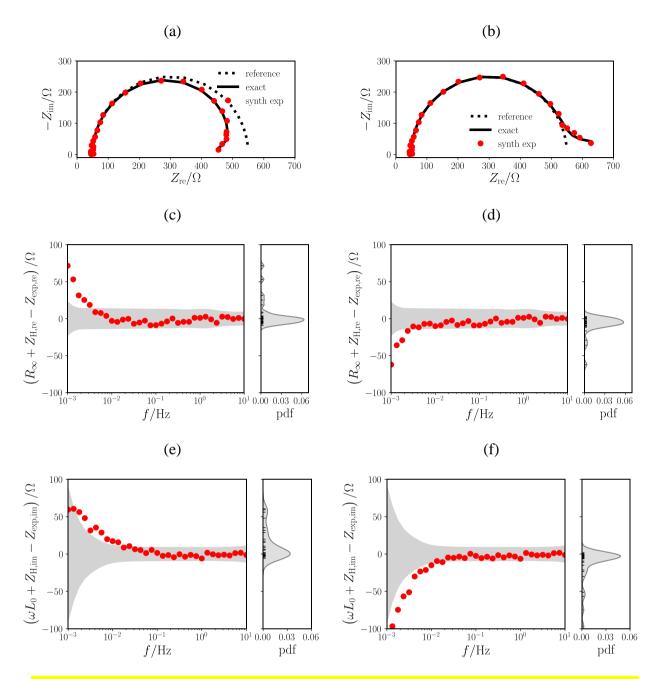


Figure 11 – (a) and (b) Nyquist plots of the time-drifting impedance. BHT residuals computed using the (c) & (d) real and (e) & (f) imaginary parts of the impedance data. The left- and right-hand-side panels correspond to time-decreasing and time-increasing polarization resistence, respectively.

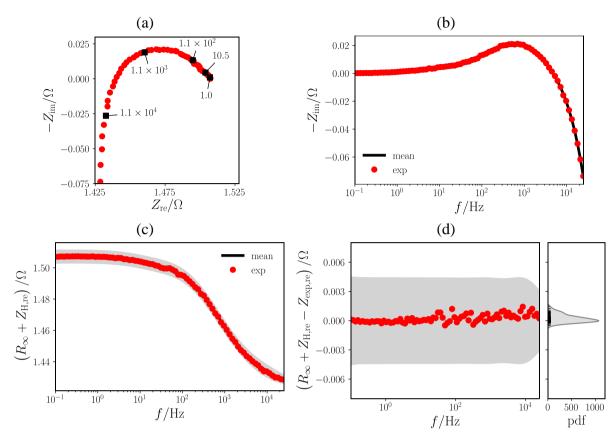


Figure 12 – (a) Nyquist plot of the BLFP|SDC|BLFP SOFC and (b) its regressed imaginary part; the reported numbers in (a) indicate frequencies in Hz. (c) BHT of $Z_{\rm exp,im}$ and (d) corresponding residuals vs. frequency and their distribution.

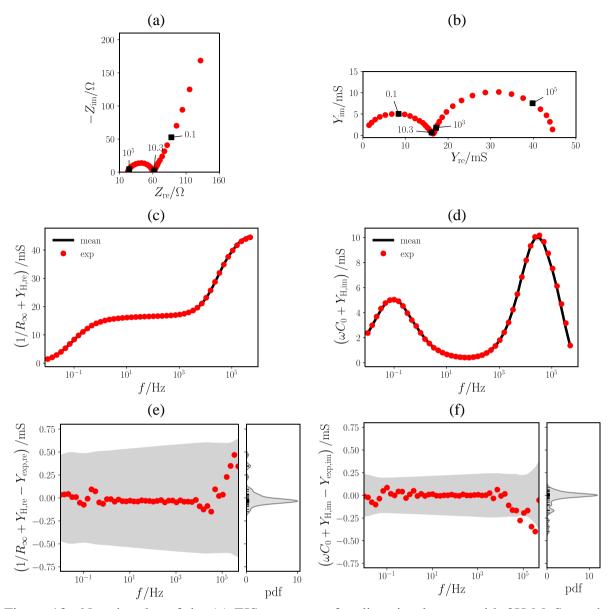


Figure 13 –Nyquist plot of the (a) EIS response of sodium-ion battery with 2H-MoS₂ as the anode[55] and (b) corresponding admittance; the reported numbers indicate frequencies in Hz. BHT of (c) $Y_{\text{exp,im}}$ and (d) $Y_{\text{exp,re}}$ shown vs. frequency and compared with experimental data (c) $Y_{\text{exp,re}}$ and (d) $Y_{\text{exp,im}}$, respectively. (e) and (f) residuals and their distributions.