Colin MJ. Jalbert

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EXPERIENCE

San Jose, CA **Made Robotics LLC**

Product Design Engineer

May 2019 - Present

- Collaborated in the co-founding of an LLC, developing walking robotic systems for the transportation, mobility augmentation and industrial applications sector, successfully generating patents, working prototypes and grant applications for the company.
- Responsibilities included but not limited to mechanical system and assembly design, component determination, geometric dimensioning and tolerancing, metals/plastic materials/force analysis and electro-mechanical prototyping.

United States Army USA. Kuwait. Iraq

Veteran, Engineer

Fall 2012 – Fall 2018

- Supported a multi-disciplinary team of engineers working in various locations to accomplish mechanical, hydraulic, and electrical engineering missions for the US Army Corps of Engineers.
- Developed familiarity with a wide range of electro-mechanical tools and skills, including using heavy machinery, wire braiding, crimping, soldering, connector attachment and troubleshooting.

YourStory International

Pont Morel, Haiti

Mechanical Engineering Associate

December 2013 – 2016

- Co-founded a non-profit organization to develop a holistic approach to reducing trash in Haiti by designing a machine system which converted throwaway polymers into lightweight building materials.
- Utilized 3D simulation programs (Solidworks + Fusion 360) to simulate load and conditional scenarios to aid in the rapid development of demolished areas leading to innovations within their structural architecture.

EDUCATION

University of Massachusetts, Amherst

Amherst, Massachusetts Bachelors; Mechanical Engineering Graduation Date: Spring 2019

PROJECT EXPERIENCE

Robot Quadruped

- Designed and built quadruped and hexapod robots to aid in home maintenance and improve quality of life for physically or mentally impaired individuals.
- Designed and assembled PCB, fabricated material, designed actuated-assembly systems, and prototyped various 3D printing techniques to test reliability and surface conditions.

Wireless Robotics Controller

Designed, fabricated and programmed a wireless robot controller equipped with numerous sensors and control modules including but not limited to encoders, 9-Axis IMUs, potentiometers, switches, buttons, capacitors and resistors.

KNOWLEDGE, SKILLS & ACKNOWLEDGEMENTS

Languages: Fluent in English and French, knowledge of Spanish.

Personal Patents: Single Passenger Vehicle For Adaptive Transportation.

Technical Skills: 10+ years 3D Modeling; SolidWorks, AutoDesk Fusion 360, SpaceClaim and MATLAB.

Programming Languages: C++, Arduino, HTML, CSS, Javascript.