

Propositional Logic - Syntactic Sugar

$\varphi \Leftrightarrow \psi := (\neg\varphi \vee \psi) \wedge (\neg\psi \vee \varphi)$ $\varphi \rightarrow \psi := \neg\varphi \vee \psi$

$\varphi \oplus \psi := (\varphi \wedge \neg\psi) \vee (\psi \wedge \neg\varphi)$ $\varphi \bar{\wedge} \psi := \neg(\varphi \wedge \psi)$

$(\alpha \Rightarrow \beta | \gamma) := (\neg\alpha \vee \beta) \wedge (\alpha \vee \gamma)$ $\varphi \bar{\vee} \psi := \neg(\varphi \vee \psi)$

Satisfiability, Validity and Equivalence

$\text{SAT}(\varphi) := \neg \text{VALID}(\neg\varphi)$ $\varphi \Leftrightarrow \psi := \text{VALID}(\varphi \leftrightarrow \psi)$

$\text{VALID}(\varphi) := (\varphi \Leftrightarrow 1)$ $\text{SAT}(\varphi) := \neg(\varphi \Leftrightarrow 0)$.

Conjunctive Normal Form: from truth table, take minterms that are 0. Each minterm is built as an OR of the negated variables. E.g.,

$(0, 0, 1) \rightarrow (x \vee y \vee \neg z)$.

Distributivity: $a \wedge (b \vee c) = (a \wedge b) \vee (a \wedge c)$

$a \vee (b \wedge c) = (a \vee b) \wedge (a \vee c)$

Sequent Calculus:

1. Prove validity of ϕ : start with $\{\} \vdash \phi$; ϕ is valid iff $\Gamma \cap \Delta \neq \{\}$ for all leaves; else, counterexample: var is true, if $x \in \Gamma$; false otherwise; "don't care", if variable doesn't appear.
2. Prove satisfiability of ϕ : start with $\{\phi\} \vdash \{\}$; ϕ is satisfiable iff $\Gamma \cap \Delta = \{\}$ for at least one leaf. Satisfying interpretation: same as counterexample.

OPER.	LEFT	RIGHT
NOT	$\neg\phi, \Gamma \vdash \Delta$ $\Gamma \vdash \phi, \Delta$	$\Gamma \vdash \neg\phi, \Delta$ $\neg\phi, \Gamma \vdash \Delta$
AND	$\phi \wedge \psi, \Gamma \vdash \Delta$ $\phi, \psi, \Gamma \vdash \Delta$	$\Gamma \vdash \phi \wedge \psi, \Delta$ $\Gamma \vdash \phi, \Delta \quad \Gamma \vdash \psi, \Delta$
OR	$\phi \vee \psi, \Gamma \vdash \Delta$ $\phi, \Gamma \vdash \Delta \quad \psi, \Gamma \vdash \Delta$	$\Gamma \vdash \phi \vee \psi, \Delta$ $\Gamma \vdash \phi, \psi, \Delta$

Resolution Calculus $\frac{\{ \neg x \} \cup C_1 \quad \{ x \} \cup C_2}{C_1 \cup C_2}$

To prove unsatisfiability of given clauses in CNF: If we reach $\{\}$, the formula is unsatisfiable. E.g., $\{\{a\}, \{\neg a, b\}, \{\neg b\}\}$, we get:

$\{a\} + \{\neg a, b\} \rightarrow \{b\}$; $\{b\} + \{\neg b\} \rightarrow \{\}$ (unsatisfiable).

To prove validity, prove UNSAT of negated formula.

Linear Clause Forms (Computes CNF)

Bottom up in the syntax tree: convert "operators and variables" into new variable. E.g., $\neg a \vee b$ becomes $x_1 \leftrightarrow \neg a$; $x_2 \leftrightarrow x_1 \vee b$. Use rules below to find CNF.

$$x \leftrightarrow \neg y \Leftrightarrow (\neg x \vee \neg y) \wedge (x \vee y)$$

$$x \leftrightarrow y_1 \wedge y_2 \Leftrightarrow (\neg x \vee y_1) \wedge (\neg x \vee y_2) \wedge (x \vee \neg y_1 \vee \neg y_2)$$

$$(x \vee \neg y_1 \vee \neg y_2)$$

$$x \leftrightarrow y_1 \vee y_2 \Leftrightarrow (\neg x \vee y_1 \vee y_2) \wedge (x \vee \neg y_1) \wedge (x \vee \neg y_2)$$

$$(x \vee \neg y_1) \wedge (x \vee \neg y_2)$$

$$x \leftrightarrow y_1 \rightarrow y_2 \Leftrightarrow (x \vee y_1) \wedge (x \vee \neg y_1 \vee \neg y_2) \wedge (\neg x \vee \neg y_1 \vee y_2)$$

$$(\neg x \vee \neg y_1 \vee y_2)$$

$$x \leftrightarrow (y_1 \leftrightarrow y_2) \Leftrightarrow (x \vee y_1 \vee y_2) \wedge (x \vee \neg y_1 \vee \neg y_2) \wedge (\neg x \vee y_1 \vee \neg y_2) \wedge (\neg x \vee \neg y_1 \vee y_2)$$

$$(\neg x \vee y_1 \vee \neg y_2) \wedge (\neg x \vee \neg y_1 \vee y_2)$$

$$x \leftrightarrow y_1 \oplus y_2 \Leftrightarrow (x \vee \neg y_1 \vee y_2) \wedge (x \vee y_1 \vee \neg y_2) \wedge (\neg x \vee y_1 \vee y_2) \wedge (\neg x \vee \neg y_1 \vee \neg y_2)$$

$$(\neg x \vee y_1 \vee y_2) \wedge (\neg x \vee \neg y_1 \vee \neg y_2)$$

Davis Putnam Procedure - proves SAT; To prove validity: prove unsatisfiability of negated formula. **(1)** Compute Linear Clause Form

(Don't forget to create the last clause $\{x_n\}$) **(2)** Last

variable has to be \perp (true) \rightarrow find implied variables.

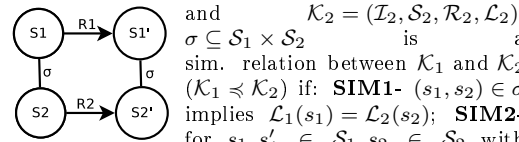
(3) For remaining variables: assume values and

compute newly implied variables. **(4)** If

contradiction reached: backtrack.

<pre> Apply(⊙, BddNode a, b) int m; BddNode h, l; if isLeaf(a)&isLeaf(b) then return Eval(⊙, label(a), label(b)); else m=max(label(a),label(b)) (a0,a1):=Ops(a,m); (b0,b1):=Ops(b,m); h:=Apply(⊙,a1,b1); l:=Apply(⊙,a0,b0); return CreateNode(m,h,l) end; </pre>	<pre> Compose(int x, BddNode ψ, α) int m; BddNode h, l; if x>label(ψ) then return ψ; elseif x=label(ψ) then return ITE(α,high(ψ), low(ψ)); else m=max{label(ψ),label(α)}; (α0,α1):=Ops(α, m); (ψ0,ψ1):=Ops(ψ, m); h:=Compose(x,ψ1,α1); l:=Compose(x,ψ0,α0); return CreateNode(m,h,l) endif; end </pre>
<pre> ITE(BddNode i, j, k) int m; BddNode h, l; if i = 0 then return k elseif i=1 then return j elseif j=k then return k else m = max{label(i), label(j),label(k)} (i0,i1):=Ops(i,m); (j0,j1):=Ops(j,m); (k0,k1):=Ops(k,m); l:=ITE(i0,j0,k0); h:=ITE(i1,j1,k1); return CreateNode(m,h,l) end; end </pre>	<pre> Constrain(Φ, β) if β=0 then ret 0 elseif Φ ∈ {0,1} (β = 1) ret Φ else m=max{label(β),label(Φ)} (Φ0,Φ1):=Ops(Φ,m); (β0,β1):=Ops(β,m); if β0=0 ret Constrain(Φ1,β1) elseif β1=0 then ret Constrain(Φ0,β0) else l:=Constrain(Φ0,β0); h:=Constrain(Φ1,β1); ret CreateNode(m,h,l) endif; endif; end </pre>
<pre> Restrict(Φ, β) if β=0 return 0 elseif Φ ∈ {0,1} ∨ (β = 1) return Φ else m=max{label(β),label(Φ)} (Φ0,Φ1):=Ops(Φ,m); (β0,β1):=Ops(β,m) if β0=0 return Restrict(Φ1,β1) elseif β1=0 return Restrict(Φ0,β0) elseif m=label(Φ) return CreateNode(m, Restrict(Φ1,β1), Restrict(Φ0,β0)) else return Restrict(Φ, Apply(v,β0,β1)) endif; endif; end </pre>	<pre> Ops(v,m) x:=label(v); if m=degree(x) return (low(v),high(v)) else return(v, v) end; end </pre> <p>Other Diagrams: TDDD ZDD FDD</p> <p>-----</p>

Simulation:



given $K_1 = (\mathcal{I}_1, \mathcal{S}_1, \mathcal{R}_1, \mathcal{L}_1)$ and $K_2 = (\mathcal{I}_2, \mathcal{S}_2, \mathcal{R}_2, \mathcal{L}_2)$; $\sigma \subseteq \mathcal{S}_1 \times \mathcal{S}_2$ is a sim. relation between K_1 and K_2 ($K_1 \preceq K_2$) if: **SIM1-** $(s_1, s_2) \in \sigma$ implies $\mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$; **SIM2-** for $s_1, s'_1 \in \mathcal{S}_1, s_2 \in \mathcal{S}_2$ with $(s_1, s_2) \in \sigma$ and $(s_1, s'_1) \in \mathcal{R}_1$, there must be $s'_2 \in \mathcal{S}_2$ with $(s'_1, s'_2) \in \sigma$ ($s_2, s'_2 \in \mathcal{S}_2$); **SIM3-** for all $s_1 \in \mathcal{I}_1$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$.

Greatest Simulation Relation

$(s_1, s_2) \in \mathcal{H}_0 \Leftrightarrow \mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$

$(s_1, s_2) \in \mathcal{H}_{i+1} \Leftrightarrow$

$\left(\begin{array}{l} (s_1, s_2) \in \mathcal{H}_i \wedge \\ \forall s'_1 \in \mathcal{S}_1. \exists s'_2 \in \mathcal{S}_2. \\ (s_1, s'_1) \in \mathcal{R}_1 \rightarrow (s_2, s'_2) \in \mathcal{R}_2 \wedge (s'_1, s'_2) \in \mathcal{H}_i \end{array} \right)$

\mathcal{H}_* is the greatest simulation relation if **SIM3:**

$\mathcal{I}_1 \subseteq \{s_1 \in \mathcal{S}_1 | \exists s_2 \in \mathcal{I}_2. (s_1, s_2) \in \mathcal{H}_*\}$

Bisimulation: $\sigma \subseteq \mathcal{S}_1 \times \mathcal{S}_2$ is a bisim. relation

between K_1 and K_2 ($K_1 \approx K_2$) if: **BISIM1-**

$(s_1, s_2) \in \sigma$ implies $\mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$; **BISIM2a-**

$(s_1, s'_1 \in \mathcal{S}_1, s_2 \in \mathcal{S}_2, (s_1, s_2) \in \sigma, (s_1, s'_1) \in \mathcal{R}_1$, imply that there is $s'_2 \in \mathcal{S}_2$ with $(s'_1, s'_2) \in \sigma$ and $(s_2, s'_2) \in \mathcal{R}_2$; **BISIM2b-** $s_2, s'_2 \in \mathcal{S}_2, s_1 \in \mathcal{S}_1, (s_1, s_2) \in \sigma, (s_2, s'_2) \in \mathcal{R}_2$, imply that there is $s'_1 \in \mathcal{S}_1$ with $(s'_1, s'_2) \in \sigma$ and $(s_1, s'_1) \in \mathcal{R}_1$; **BISIM3a-** for all $s_1 \in \mathcal{I}_1$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$; **BISIM3b-** for all $s_1 \in \mathcal{I}_2$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$.

Greatest Bisimulation Relation (Equivalence)

$(s_1, s_2) \in \mathcal{B}_0 \Leftrightarrow \mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$

$(s_1, s_2) \in \mathcal{B}_{i+1} \Leftrightarrow$

$\left(\begin{array}{l} (s_1, s_2) \in \mathcal{B}_i \wedge \\ \forall s'_1 \in \mathcal{S}_1. \exists s'_2 \in \mathcal{S}_2. \\ (s_1, s'_1) \in \mathcal{R}_1 \rightarrow (s_2, s'_2) \in \mathcal{R}_2 \wedge (s'_1, s'_2) \in \mathcal{B}_i \\ \forall s'_2 \in \mathcal{S}_2. \exists s'_1 \in \mathcal{S}_1. \\ (s_2, s'_2) \in \mathcal{R}_2 \rightarrow (s_1, s'_1) \in \mathcal{R}_1 \wedge (s'_1, s'_2) \in \mathcal{B}_i \end{array} \right)$

\mathcal{B}_* is the greatest simulation relation if

$\mathcal{I}_1 \subseteq \{s_1 \in \mathcal{S}_1 | \exists s_2 \in \mathcal{I}_2. (s_1, s_2) \in \mathcal{B}_*\}$

$\mathcal{I}_2 \subseteq \{s_2 \in \mathcal{S}_2 | \exists s_1 \in \mathcal{I}_1. (s_1, s_2) \in \mathcal{B}_*\}$

Quotient: given $\mathcal{K} = (\mathcal{I}, \mathcal{S}, \mathcal{R}, \mathcal{L})$ and the

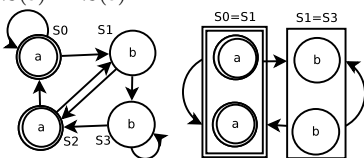
equivalence relation $\sigma \subseteq \mathcal{S} \times \mathcal{S}$; Quotient structure

$\mathcal{K}_{/\sigma} = (\tilde{\mathcal{I}}, \tilde{\mathcal{S}}, \tilde{\mathcal{R}}, \tilde{\mathcal{L}})$: $\tilde{\mathcal{I}} := \{\{s' \in \mathcal{S} | (s, s') \in \sigma\} | s \in \mathcal{I}\}$

$\tilde{\mathcal{S}} := \{\{s' \in \mathcal{S} | (s, s') \in \sigma\} | s \in \mathcal{S}\}$

$(\tilde{s}_1, \tilde{s}_2) \in \tilde{\mathcal{R}} : \Leftrightarrow \exists s'_1 \in \tilde{s}_1. \exists s'_2 \in \tilde{s}_2. (s'_1, s'_2) \in \mathcal{R}$

$\tilde{\mathcal{L}}(\tilde{s}) := \mathcal{L}(s)$



Symbolic Product Computation - given

$\mathcal{K}_1 = (\mathcal{V}_1, \varphi_{\mathcal{I}}, \varphi_{\mathcal{R}})$ and $\mathcal{K}_2 = (\mathcal{V}_2, \psi_{\mathcal{I}}, \psi_{\mathcal{R}})$, the

product is: $\mathcal{K}_1 \times \mathcal{K}_2 = (\mathcal{V}_1 \cup \mathcal{V}_2, \varphi_{\mathcal{I}} \wedge \psi_{\mathcal{I}}, \varphi_{\mathcal{R}} \wedge \psi_{\mathcal{R}})$

Quantif. $\exists x. \varphi := [\varphi]_x^1 \vee [\varphi]_x^0 \quad \forall x. \varphi := [\varphi]_x^1 \wedge [\varphi]_x^0$

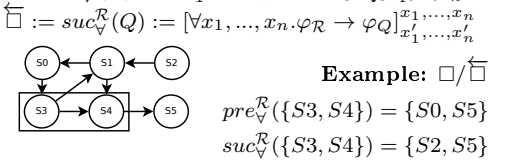
Predecessor and Successor

$\diamond := \text{pre}_{\mathcal{R}}^{\mathcal{R}}(Q) := \exists x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \wedge [\varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$

$\diamondsuit := \text{suc}_{\mathcal{R}}^{\mathcal{R}}(Q) := \exists x_1, \dots, x_n. \varphi_{\mathcal{R}} \wedge \varphi_Q]_{x_1, \dots, x_n}^{x'_1, \dots, x'_n}$

$\square := \text{pre}_{\mathcal{V}}^{\mathcal{R}}(Q) := \forall x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \rightarrow [\varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$

$\square \vdash := \text{suc}_{\mathcal{V}}^{\mathcal{R}}(Q) := \forall x_1, \dots, x_n. \varphi_{\mathcal{R}} \rightarrow \varphi_Q]_{x_1, \dots, x_n}^{x'_1, \dots, x'_n}$



Example: \square / \square

$\text{pre}_{\mathcal{R}}^{\mathcal{R}}(\{S3, S4\}) = \{S0, S5\}$

$\text{suc}_{\mathcal{R}}^{\mathcal{R}}(\{S3, S4\}) = \{S2, S5\}$

$\text{pre}_{\mathcal{V}}^{\mathcal{R}}(Q = \{S_1, \dots, S_n\})$ for each node n in \mathcal{K} : if n points to a node that is not in Q n $\notin \text{pre}_{\mathcal{V}}^{\mathcal{R}}(Q)$ else n $\in \text{pre}_{\mathcal{V}}^{\mathcal{R}}(Q)$	$\text{suc}_{\mathcal{V}}^{\mathcal{R}}(Q = \{S_1, \dots, S_n\})$ for each node n in \mathcal{K} : if (n is pointed by a node that is not in Q) n $\notin \text{suc}_{\mathcal{V}}^{\mathcal{R}}(Q)$ else n $\in \text{suc}_{\mathcal{V}}^{\mathcal{R}}(Q)$
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Tarski-Knaster Theorem: $\mu :=$ starts $\perp \rightarrow$

least fixpoint $\spadesuit \nu :=$ starts $\top \rightarrow$ greatest fixpoint *

Rabin-Scott Subset Construction 1. Initial

state is a set of states containing all the initial

states. **2.** For all transitions of a set of states,

compute the successors and create a set of states

containing all the possible reachable states when

performing that transition. **3.** Acceptance condition

are set of states containing acceptance states.

Local Model Checking

$\frac{\text{st} \vdash \varphi \wedge \psi}{\{ \text{st} \vdash \varphi \} \quad \{ \text{st} \vdash \psi \}} \wedge$	$\frac{\text{st} \vdash \varphi \vee \psi}{\{ \text{st} \vdash \varphi \} \quad \{ \text{st} \vdash \psi \}} \vee$
$\frac{\text{st} \vdash \varphi \sqsubseteq \psi}{\{ \text{st}_1 \vdash \varphi \} \dots \{ \text{st}_n \vdash \varphi \}} \wedge$	$\frac{\text{st} \vdash \varphi \supset \psi}{\{ \text{st}_1 \vdash \varphi \} \dots \{ \text{st}_n \vdash \varphi \}} \vee$
$\frac{\text{st} \vdash \varphi \sqsubseteq \psi}{\{ \text{st}'_1 \vdash \varphi \} \dots \{ \text{st}'_n \vdash \varphi \}} \wedge$	$\frac{\text{st} \vdash \varphi \supset \psi}{\{ \text{st}'_1 \vdash \varphi \} \dots \{ \text{st}'_n \vdash \varphi \}} \vee$
$\frac{\text{st} \vdash \varphi \mu x. \varphi}{\text{st} \vdash \varphi} \quad \frac{\text{st} \vdash \nu x. \varphi}{\text{st} \vdash \varphi}$	$\frac{\text{st} \vdash \varphi}{\text{st} \vdash \varphi} \quad \frac{\mathcal{Q} \vdash \text{replace w. initial form.}}{\mathcal{Q} \vdash \text{replace w. initial form.}}$
$\{s_1 \dots s_n\} = \text{suc}_{\mathcal{R}}^{\mathcal{R}}(s)$ and $\{s'_1 \dots s'_n\} = \text{pre}_{\mathcal{R}}^{\mathcal{R}}(s)$	

Approximations and Ranks

If $(s, \mu x. \varphi)$ repeats \rightarrow return 0	$\text{apx}_0(\mu x. \varphi) := 0$
If $(s, \nu x. \varphi)$ repeats \rightarrow return 1	$\text{apx}_0(\nu x. \varphi) := 1$
$\text{apx}_{n+1}(\mu x. \varphi) := \lfloor \varphi \rfloor_x^{\text{apx}_n(\mu x. \varphi)}$	
$\text{apx}_{n+1}(\nu x. \varphi) := \lfloor \varphi \rfloor_x^{\text{apx}_n(\nu x. \varphi)}$	

Automata types: G \rightarrow Safety; F \rightarrow Liveness;

FG \rightarrow Persistence/Co-Buchi; GF \rightarrow Fairness/Buchi.

Automaton Determinization

NDet_G \rightarrow Det_G: 1. Remove all states/edges that do

not satisfy acceptance condition; 2. Use Subset

construction (Rabin-Scott); 3. Acceptance condition

will be the states where $\{\}$ is never reached.

{NDet_F(partial) or NDet_{prefix}} \rightarrow Det_{FG}:

Breakpoint Construction.

NDet_F(total) \rightarrow Det_F: Subset Construction.

NDet_{FG} \rightarrow Det_{FG}: Breakpoint Construction.

NDet_{GF} \rightarrow {Det_{Rabin} or Det_{Streett}}: Safra

Algorithm.

* **Breakpoint Construction 1.** Each state is

composed by two components **2.** Initial state first

component is a set of all initial states, and second

component is the empty set. Ex.: $(\mathcal{I}, \{\})$. **3.** a

successor for a state (Q, Q_f) is generated as follows:

$\left\{ \begin{array}{l} \text{If } Q_f = \{\} \quad (\text{suc}_{\mathcal{R}}^{\mathcal{R}a}(Q), (\text{suc}_{\mathcal{R}}^{\mathcal{R}a}(Q) \cap \mathcal{F})) \\ \text{Otherwise} \quad (\text{suc}_{\mathcal{R}}^{\mathcal{R}a}(Q), (\text{suc}_{\mathcal{R}}^{\mathcal{R}a}(Q_f) \cap \mathcal{F})) \end{array} \right.$

4. Acceptance states are states where $Q_f \neq \{\}$.

Boolean Operations on ω -Automata

Complement

$\neg \mathcal{A}_{\forall}(Q, \mathcal{I}, \mathcal{R}, \mathcal{F}) = \mathcal{A}_{\exists}(Q, \mathcal{I}, \mathcal{R}, \neg \mathcal{F})$

$\neg \mathcal{A}_{\exists}(Q, \mathcal{I}, \mathcal{R}, \mathcal{F}) = \mathcal{A}_{\forall}(Q, \mathcal{I}, \mathcal{R}, \neg \mathcal{F})$

Conjunction

$(\mathcal{A}_{\exists}(Q_1, \mathcal{I}_1, \mathcal{R}_1, \mathcal{F}_1) \wedge \mathcal{A}_{\exists}(Q_2, \mathcal{I}_2, \mathcal{R}_2, \mathcal{F}_2)) =$

$\mathcal{A}_{\exists}(Q_1 \cup Q_2, \mathcal{I}_1 \wedge \mathcal{I}_2, \mathcal{R}_1 \wedge \mathcal{R}_2, \mathcal{F}_1 \wedge \mathcal{F}_2)$

$$\begin{array}{ll} (1) \neg F\varphi = G\neg\varphi & (2) F\varphi \vee F\psi = F[\varphi \vee \psi] \\ (3) F\varphi \wedge F\psi = \mathcal{A}_{\exists}(\{p, q\}, \neg p \wedge \neg q, & \\ & [p' \leftrightarrow p \vee \varphi] \wedge [q' \leftrightarrow q \vee \psi], F[p \wedge q]) \end{array}$$
$$\begin{array}{l} (1) \neg FG\varphi = GF\neg\varphi \quad (2) FG\varphi \wedge FG\psi = FG[\varphi \wedge \psi] \\ (3) FG\varphi \vee FG\psi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow (q \Rightarrow \psi | \neg\varphi), \\ \quad FG[\neg q \vee \psi]) \end{array}$$
$$\begin{array}{l} (1) \neg GF\varphi = FG\neg\varphi \quad (2) GF\varphi \vee GF\psi = GF[\varphi \vee \psi] \\ (3) GF\varphi \wedge GF\psi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow (q \Rightarrow \neg\psi|\varphi), \\ \quad GF[q \wedge \psi]) \end{array}$$

Reduction of G
 $G\varphi = \mathcal{A}_{\exists}(\{q\}, q, \varphi \wedge q \wedge q', Fq)$
 $G\varphi = \mathcal{A}_{\exists}(\{q\}, q, q' \leftrightarrow q \wedge \varphi, FGq)$
 $G\varphi = \mathcal{A}_{\exists}(\{q\}, q, q' \leftrightarrow q \wedge \varphi, GFq)$
Reduction of F

$$\begin{array}{l} F\varphi = \mathcal{A}_\exists(\{q\}, \neg q, q' \leftrightarrow q \vee \varphi, FGq) \\ F\varphi = \mathcal{A}_\exists(\{q\}, \neg q, q' \leftrightarrow q \vee \varphi, GFq) \\ \text{Reduction of FG} \end{array}$$
$$FG\varphi = \mathcal{A}_{\exists}(\{q\}, \neg q, q \rightarrow \varphi \wedge q', Fq) \\ FG\varphi = \mathcal{A}_{\exists}\left(\begin{array}{c} \{p, q\}, \quad \neg p \wedge \neg q, \\ [(p \rightarrow p') \wedge (p' \rightarrow p \vee \neg q) \wedge \\ (q' \leftrightarrow (p \wedge \neg q \vee \neg \varphi) \vee (p \wedge q))] \\ G\neg q \wedge Fp \end{array}\right), \\ FG\varphi = \mathcal{A}_{\exists}\left(\begin{array}{c} \{p, q\}, \quad \neg p \wedge \neg q, \\ [(p \rightarrow p') \wedge (p' \rightarrow p \vee \neg q) \wedge \\ (q' \leftrightarrow (p \wedge \neg q \vee \neg \varphi) \vee (p \wedge q))] \\ GF[p \wedge \neg q] \end{array}\right)$$

E and A quantify over infinite paths.
 $A\varphi$ holds on every state that has no infinite path;
 $E\varphi$ is false on every state that has no infinite path;
 $A0$ holds on states with only finite paths;
 $E1$ is false on state with only finite paths;
 $\Box 0$ holds on states with no successor states;
 $\Diamond 1$ holds on states with successor states.

$$\begin{aligned} [\varphi U \psi] &= \psi \vee (\varphi \wedge X[\varphi U \psi]) \\ [\varphi B \psi] &= \neg\psi \wedge (\varphi \vee X[\varphi B \psi]) \\ [\varphi W \psi] &= (\psi \wedge \varphi) \vee (\neg\psi \wedge X[\varphi W \psi]) \end{aligned}$$

$\neg(\varphi \wedge \psi) = \neg\varphi \vee \neg\psi$	$\neg(\varphi \vee \psi) = \neg\varphi \wedge \neg\psi$
$\neg\neg\varphi = \varphi$	$\neg X\varphi = X\neg\varphi$
$\neg G\varphi = F\neg\varphi$	$\neg F\varphi = G\neg\varphi$
$\neg[\varphi \ U \ \psi] = [(\neg\varphi) \ \underline{B} \ \psi]$	$\neg[\varphi \ \underline{U} \ \psi] = [(\neg\varphi) \ B \ \psi]$
$\neg[\varphi \ B \ \psi] = [(\neg\varphi) \ \underline{U} \ \psi]$	$\neg[\varphi \ \underline{B} \ \psi] = [(\neg\varphi) \ U \ \psi]$
$\neg A\varphi = E\neg\varphi$	$\neg E\varphi = A\neg\varphi$
$\neg \overline{X}\varphi = \overline{X}\neg\varphi$	$\neg \overline{X}\varphi = \overline{X}\neg\varphi$
$\neg \overline{G}\varphi = \overline{F}\neg\varphi$	$\neg \overline{F}\varphi = \overline{G}\neg\varphi$

LTl Syntactic Sugar: analog for past operators

$G\varphi = \neg[1 \ U \ (\neg\varphi)]$	$F\varphi = [1 \ \underline{U} \ \varphi]$
$[\varphi \ W \ \psi] = \neg[(\neg\varphi \vee \neg\psi) \ \underline{U} \ (\neg\varphi \wedge \psi)]$	
$[\varphi \ \underline{W} \ \psi] = [(\neg\psi) \ \underline{U} \ (\varphi \wedge \psi)]$	$(\neg\psi \text{ holds until } \varphi \wedge \psi)$
$[\varphi \ B \ \psi] = \neg[(\neg\varphi) \ \underline{U} \ \psi]$	
$[\varphi \ \underline{B} \ \psi] = [(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)]$	$(\psi \text{ can't hold when } \varphi \text{ holds})$
$[\varphi \ U \ \psi] = \neg[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)]$	
$[\varphi \ U \ \psi] = [\varphi \ U \ \psi] \vee G\varphi$	

$$\begin{aligned} [\varphi \underline{U} \psi] &= \neg[(\neg\psi) \text{ } U \text{ } (\neg\varphi \wedge \neg\psi)] \\ [\varphi \underline{U} \psi] &= \neg[(\neg\psi) \text{ } W \text{ } (\varphi \rightarrow \psi)] \\ [\varphi \underline{U} \psi] &= [\psi \text{ } W \text{ } (\varphi \rightarrow \psi)] \\ [\varphi \underline{U} \psi] &= \neg[(\neg\varphi) \text{ } B \text{ } \psi] \text{ (}\varphi \text{ doesn't matter when } \psi \text{ holds)} \\ [\varphi \underline{U} \psi] &= [\psi \text{ } B \text{ } (\neg\varphi \wedge \neg\psi)] \end{aligned}$$

Existential Operators	
$EF\varphi = E[1 \ \underline{U} \ \varphi]$	
$EG\varphi = E[\varphi \ U \ 0]$	

$$\begin{aligned} E[\varphi \ B \ \psi] &= E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)] \vee EG\neg\psi \\ E[\varphi \ B \ \psi] &= E[(\neg\psi) \ U \ (\varphi \wedge \neg\psi)] \\ E[\varphi \ \underline{B} \ \psi] &= E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)] \\ E[\varphi \ W \ \psi] &= E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \psi)] \vee EG\neg\psi \\ E[\varphi \ W \ \psi] &= E[(\neg\psi) \ U \ (\varphi \wedge \psi)] \\ E[\varphi \ W \ \psi] &= E[(\neg\psi) \ U \ (\varphi \wedge \psi)] \end{aligned}$$
$$\begin{array}{l}
\overline{AX\varphi = \neg EX\neg\varphi} \\
AG\varphi = \neg E[1 \ \underline{U} \neg\varphi] \\
AF\varphi = \neg EG\neg\varphi \\
AF\varphi = \neg E[(\neg\varphi) \ U \ 0] \\
A[\varphi \ U \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)] \\
A[\varphi \ U \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)] \wedge \neg EG\neg\psi \\
A[\varphi \ \underline{U} \ \psi] = \neg E[(\neg\psi) \ U \ (\neg\varphi \wedge \neg\psi)] \\
A[\varphi \ B \ \psi] = \neg E[(\neg\varphi) \ \underline{U} \ \psi] \\
A[\varphi \ \underline{B} \ \psi] = \neg E[(\neg\varphi) \ U \ \psi] \\
A[\varphi \ \underline{B} \ \psi] = \neg E[(\neg\varphi \vee \psi) \ \underline{U} \ \psi] \wedge \neg EG(\neg\varphi \vee \psi) \\
A[\varphi \ W \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)] \\
A[\varphi \ \underline{W} \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)] \wedge \neg EG\neg\psi \\
A[\varphi \ W \ \psi] = \neg E[(\neg\psi) \ U \ (\neg\varphi \wedge \neg\psi)]
\end{array}$$
$$\begin{aligned}
EX\varphi &= \Diamond(\Phi_{inf} \wedge \varphi) \\
EG\varphi &= \nu x. \varphi \wedge \Diamond x \\
EF\varphi &= \mu x. \Phi_{inf} \wedge \varphi \vee \Diamond x \\
E[\varphi \underline{U} \psi] &= \mu x. (\Phi_{inf} \wedge \psi) \vee \varphi \wedge \Diamond x \\
E[\varphi \underline{U} \psi] &= \nu x. (\Phi_{inf} \wedge \psi) \vee \varphi \wedge \Diamond x \\
E[\varphi \underline{B} \psi] &= \mu x. \neg \psi \wedge (\Phi_{inf} \wedge \varphi \vee \Diamond x) \\
E[\varphi \underline{B} \psi] &= \nu x. \neg \psi \wedge (\Phi_{inf} \wedge \varphi \vee \Diamond x) \\
AX\varphi &= \Box(\Phi_{inf} \rightarrow \varphi) \\
AG\varphi &= \nu x. (\Phi_{inf} \rightarrow \varphi) \wedge \Box x \\
AF\varphi &= \mu x. \varphi \vee \Box x \\
A[\varphi \underline{U} \psi] &= \mu x. \psi \vee (\Phi_{inf} \rightarrow \varphi) \wedge \Box x \\
A[\varphi \underline{U} \psi] &= \nu x. \psi \vee (\Phi_{inf} \rightarrow \varphi) \wedge \Box x \\
A[\varphi \underline{B} \psi] &= \mu x. (\Phi_{inf} \rightarrow \neg \psi) \wedge (\varphi \vee \Box x) \\
A[\varphi \underline{B} \psi] &= \nu x. (\Phi_{inf} \rightarrow \neg \psi) \wedge (\varphi \vee \Box x)
\end{aligned}$$
$$\begin{array}{l} EX\varphi = EXE\varphi \\ EF\varphi = EFE\varphi \\ E[\varphi \ W \ \psi] = E[(E\varphi) \ W \ \psi] \\ E[\varphi \ \underline{W} \ \psi] = E[(E\varphi) \ \underline{W} \ \psi] \\ E[\psi \ U \ \varphi] = E[\psi \ U \ E(\varphi)] \\ E[\psi \ \underline{U} \ \varphi] = E[\psi \ \underline{U} \ E(\varphi)] \\ E[\varphi \ B \ \psi] = E[(E\varphi) \ B \ \psi] \\ E[\varphi \ \underline{B} \ \psi] = E[(E\varphi) \ \underline{B} \ \psi] \end{array} \quad \begin{array}{l} \\ \\ EF\mathcal{G}\varphi \equiv EFEG\varphi \\ \\ \\ \\ \end{array}$$
$$\begin{aligned} & \text{CTL* to CTL} - \underline{\text{Universal Operators}} \\ & AX\varphi = AXA\varphi \\ & AG\varphi = AGA\varphi \\ & A[\varphi \ W \ \psi] = A[(A\varphi) \ W \ \psi] \\ & A[\varphi \ \underline{W} \ \psi] = A[(A\varphi) \ \underline{W} \ \psi] \\ & A[\varphi \ U \ \psi] = A[(A\varphi) \ U \ \psi] \\ & A[\varphi \ \underline{U} \ \psi] = A[(A\varphi) \ \underline{U} \ \psi] \\ & A[\psi \ B \ \varphi] = A[\psi \ B \ (E[\varphi])] \end{aligned}$$
$$A[\psi \ \underline{B} \ \varphi] = A[\psi \ \underline{B} \ (E(\varphi))]$$

Eliminate boolean op. after path quantify

$$[\varphi_1 \ \underline{U} \ \psi_1] \wedge [\varphi_2 \ \underline{U} \ \psi_2] =$$
$$\begin{aligned} [\varphi_1 \underline{U} \psi_1] \wedge [\varphi_2 U \psi_2] &= \left[(\varphi_1 \wedge \varphi_2) \underline{U} \left(\begin{array}{l} \psi_1 \wedge [\varphi_2 \underline{U} \psi_2]^\vee \\ \psi_2 \wedge [\varphi_1 \underline{U} \psi_1] \end{array} \right) \right] \\ [\varphi_1 U \psi_1] \wedge [\varphi_2 U \psi_2] &= \left[(\varphi_1 \wedge \varphi_2) \underline{U} \left(\begin{array}{l} \psi_1 \wedge [\varphi_2 U \psi_2]^\vee \\ \psi_2 \wedge [\varphi_1 \underline{U} \psi_1] \end{array} \right) \right] \\ [\varphi_1 U \psi_1] \wedge [\varphi_2 U \psi_2] &= \left[(\varphi_1 \wedge \varphi_2) U \left(\begin{array}{l} \psi_1 \wedge [\varphi_2 U \psi_2]^\vee \\ \psi_2 \wedge [\varphi_1 U \psi_1] \end{array} \right) \right] \end{aligned}$$

Let's φ_i be a pure path formula (without path quantifiers), Ψ be a propositional formula, abbreviate subformulas $E\varphi$ and $A\psi$ working bottom-up the syntax tree to obtain the following

normal form: $\phi = \text{let } \begin{bmatrix} x_1 = A\varphi_1 \\ \vdots \\ x_n = A\varphi_n \end{bmatrix} \text{ in } \Psi \text{ end}$

Use LTL model checking to compute $Q_i := \llbracket A\varphi_i \rrbracket_{\mathcal{K}_{i-1}}$, where $\mathcal{K}_0 := \mathcal{K}$ and \mathcal{K}_{i+1} is obtained from \mathcal{K}_i by labelling the states Q_i with x_i . Finally compute $\llbracket \Psi \rrbracket_{\mathcal{K}}$.

$\Phi \equiv A\varphi$, translate $\neg\varphi$ to an ω -automaton $\mathfrak{A}_{\neg\varphi} = A_3(Q, \varphi_I, \varphi_R, \varphi_F)$. Thus:
 $\mathcal{K} \models A\varphi \Leftrightarrow \mathcal{K} \models \neg E\neg\varphi \Leftrightarrow \mathcal{K} \models \mathfrak{A}_{\neg\varphi} \Leftrightarrow \mathcal{K} \times \mathcal{K}_{\mathfrak{A}} \models \neg E\varphi_F$
Reduction to ω -automaton emptiness.

$$\begin{aligned}
\phi\langle X\varphi\rangle_x &\Leftrightarrow \mathcal{A}_{\exists}(\{q\}, 1, q \leftrightarrow X\varphi, \phi\langle q\rangle_x) \\
\phi\langle X\varphi\rangle_x &\Leftrightarrow \\
&\mathcal{A}_{\exists}(\{q_0, q_1\}, 1, (q_0 \leftrightarrow \varphi) \wedge (q_1 \leftrightarrow Xq_0), \phi\langle q_1\rangle_x) \\
\phi\langle G\varphi\rangle_x &\Leftrightarrow \\
&\mathcal{A}_{\exists}(\{q\}, 1, q \leftrightarrow \varphi \wedge Xq, \phi\langle q\rangle_x \wedge GF[\varphi \rightarrow q]) \\
\phi\langle F\varphi\rangle_x &\Leftrightarrow \\
&\mathcal{A}_{\exists}(\{q\}, 1, q \leftrightarrow \varphi \vee Xq, \phi\langle q\rangle_x \wedge GF[q \rightarrow \varphi]) \\
\phi\langle[\varphi \, U \, \psi]\rangle_x &\Leftrightarrow \\
&\mathcal{A}_{\exists}(\{q\}, 1, q \leftrightarrow \psi \vee \varphi \wedge Xq, \phi\langle q\rangle_x \wedge GF[\varphi \rightarrow q]) \\
\phi\langle[\varphi \, \underline{U} \, \psi]\rangle_x &\Leftrightarrow \\
&\mathcal{A}_{\exists}(\{q\}, 1, q \leftrightarrow \psi \vee \varphi \wedge Xq, \phi\langle q\rangle_x \wedge GF[q \rightarrow \psi]) \\
\phi\langle[\varphi \, B \, \psi]\rangle_x &\Leftrightarrow
\end{aligned}$$
$$\begin{aligned}
& A_{\exists}(\{q\}, 1, q \leftrightarrow \neg\psi \wedge (\varphi \vee Xq), \Phi(q)_x \wedge GF[q \vee \psi]) \\
& \Phi([\varphi \underline{B} \psi])_x \Leftrightarrow \\
& A_{\exists}(\{q\}, 1, q \leftrightarrow \neg\psi \wedge (\varphi \vee Xq), \Phi(q)_x \wedge GF[q \rightarrow \varphi]) \\
& \Phi([\overline{X} \varphi]_x) \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \varphi, \Phi(q)_x) \\
& \Phi([\overline{X} \varphi]_x) \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \varphi, \Phi(q)_x) \\
& \Phi([\overline{G} \varphi]_x) \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \varphi \wedge q, \Phi(\varphi \wedge q)_x) \\
& \Phi([\overline{F} \varphi]_x) \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \varphi \vee q, \Phi(\varphi \vee q)_x) \\
& \Phi([\varphi \underline{U} \psi])_x \Leftrightarrow \\
& A_{\exists}(\{q\}, q, Xq \leftrightarrow \psi \vee \varphi \wedge q, \Phi(\psi \vee \varphi \wedge q)_x) \\
& \Phi([\varphi \underline{U} \psi])_x \Leftrightarrow \\
& A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \psi \vee \varphi \wedge q, \Phi(\psi \vee \varphi \wedge q)_x) \\
& \Phi([\varphi \underline{B} \psi])_x \Leftrightarrow \\
& A_{\exists}(\{q\}, q, Xq \leftrightarrow \neg\psi \wedge (\varphi \vee q), \Phi(\neg\psi \wedge (\varphi \vee q))_x) \\
& \Phi([\varphi \underline{B} \psi])_x \Leftrightarrow \\
& A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \neg\psi \wedge (\varphi \vee q), \Phi(\neg\psi \wedge (\varphi \vee q))_x)
\end{aligned}$$

First order terms are defined as follows:
 $-0 \in Term_{\leq}^{S1S}$

$$\begin{aligned} -t \in V_\Sigma | \text{typ}_\Sigma(t) = \mathbb{N} &\subseteq \text{Term}_\Sigma^{S1S} \\ -SUC(\tau) \in \text{Term}_\Sigma^{S1S} &\text{ if } \tau \in \text{Term}_\Sigma^{S1S} \end{aligned}$$

Formulas $\hat{\varphi}_i$ are defined as:

Formulas ζ_{S1S} are defined as:

- $\neg p^{(t)} \in L_{S1S}$ (predicate p at time t)
- $\neg \varphi, \varphi \wedge \psi \in L_{S1S}$
- $\neg \exists t. \varphi \in L_{S1S}$
- $\neg \exists p. \varphi \in L_{S1S}$

where:

- $\neg \tau \in Term_{\Sigma}^{S1S}$
- $\neg \varphi, \psi \in \zeta_{S1S}$
- $\neg t \in V_{\Sigma}$ with $typ_{\Sigma}(t) = \mathbb{N}$
- $\neg p \in V_{\Sigma}$ with $typ_{\Sigma}(p) = \mathbb{N} \rightarrow \mathbb{B}$

LO2

first order terms are defined as:
 $-t \in V_{\Sigma} | typ_{\Sigma}(t) = \mathbb{N} \subseteq Term_{\Sigma}^{LO2}$
formulas LO2 are defined as:
 $-t1 < t2 \in L_{LO2}$
 $-p^{(t)} \in L_{LO2}$
 $-\neg\varphi, \varphi \wedge \psi \in L_{LO2}$
 $-\exists t. \varphi \in L_{LO2}$
 $-\exists p. \varphi \in L_{LO2}$
where:

```

 $-t, t_1, t_2 \tau \in V_\Sigma$  with  $typ_\Sigma(t) = typ_\Sigma(t_1) = typ_\Sigma(t_2) = \mathbb{N}$ 
 $-\varphi, \psi \in \zeta_{LO2}$ 
 $-t \in V_\Sigma$  with  $typ_\Sigma(t) = \mathbb{N}$ 
 $-p \in V_\Sigma$  with  $typ_\Sigma(p) = \mathbb{N} \rightarrow \mathbb{B}$ 
function  $LO2\_S1S(\Phi)$ 
  case  $\Phi$  of
     $t_1 < t_2$  : return  $\exists p. [\forall t. p^{(t)} \rightarrow p^{(SUC(t))}] \wedge \neg p^{(t_1)} \wedge p^{(t_2)}$  ;
     $p^{(t)}$  : return  $p^{(t)}$  ;
     $\neg\varphi$  : return  $\neg LO2\_S1S(\varphi)$  ;
     $\varphi \wedge \psi$  : return  $LO2\_S1S(\varphi) \wedge LO2\_S1S(\psi)$  ;
     $\exists t. \varphi$  : return  $\exists t. LO2\_S1S(\varphi)$  ;
     $\exists p. \varphi$  : return  $\exists p. LO2\_S1S(\varphi)$  ;
  end
end
function  $S1S\_LO2(\Phi)$ 
  case  $\Phi$  of
     $p^{(n)}$  :
      return  $\exists t_0 \dots tn. p^{(tn)} \wedge zero(t_0) \wedge \bigwedge_{i=0}^{n-1} succ(ti, ti+1)$  ;
     $p^{(t_0+n)}$  :

```

```

return  $\exists t1...tn.p^{(tn)} \wedge \bigwedge_{i=0}^{n-1} succ(ti, ti + 1);$ 
 $\neg \varphi$  : return  $\neg S1\bar{S\_}LO2(\varphi);$ 
 $\varphi \wedge \psi$  : return  $S1\bar{S\_}LO2(\varphi) \wedge S1\bar{S\_}LO2(\psi);$ 
 $\exists t.\varphi$  : return  $\exists t.S1\bar{S\_}LO2(\varphi);$ 
 $\exists p.\varphi$  : return  $\exists p.S1\bar{S\_}LO2(\varphi);$ 
end

```

end

LO2' Consider the following set $\zeta_{LO2'}$ of formulas:

- $-Subset(p, q), Sing(p), and PSUC(p, q) belong to \zeta_{LO2'}$
- $-\neg \varphi, \varphi \wedge \psi$
- $-\exists p.\varphi$

where $-\varphi, \psi \in \zeta_{LO2'}$
 $-p \in V_{\Sigma}$ with $typ_{\Sigma}(p) = \mathbb{N} \rightarrow \mathbb{B}$
 $\zeta_{LO2'}$ has nonnumeric variables
 numeric variable t is replaced by a singleton set p_t
 $\zeta_{LO2'}$ is as expressive as LO2 and S1S
function **ElimFO**(Φ) (LO2 TO LO2')
case Φ **of**
 $t1 = t2 : \text{return } Subset(q_{t1}, q_{t2}) \wedge Subset(q_{t2}, q_{t1})$

```

t1 < t2 :  $\Psi := \forall q1. \forall q2. PSUC(q1, q2) \rightarrow$ 
[Subset(q1, p)  $\rightarrow$  Subset(q2, p)];
  return  $\exists p. \Psi \wedge \neg Subset(qt1, p) \wedge Subset(qt2, p)$ ;
p(t) : return Subset(qt, p)
 $\neg\varphi$  : return  $\neg ElimFO(\varphi)$ ;
 $\varphi \wedge \psi$  : return  $ElimFO(\varphi) \wedge ElimFO(\psi)$ ;
 $\varphi \vee \psi$  : return  $ElimFO(\varphi) \vee ElimFO(\psi)$ ;
 $\exists t. \varphi$  : return  $\exists qt. Sing(qt) \wedge ElimFO(\varphi)$ ;
 $\exists p. \varphi$  : return  $\exists p. ElimFO(\varphi)$ ;
end
end
function Tp2Od(t0,  $\Phi$ ) temporal to LO1
case  $\Phi$  of
  is_var( $\Phi$ ) :  $\Psi^{(t0)}$ ;
   $\neg\varphi$  : return  $\neg Tp2Od(\varphi)$ ;
   $\varphi \wedge \psi$  : return  $Tp2Od(\varphi) \wedge Tp2Od(\psi)$ ;
   $\varphi \vee \psi$  : return  $Tp2Od(\varphi) \vee Tp2Od(\psi)$ ;
   $X\varphi$  :  $\Psi := \exists t1. (t0 < t1) \wedge (\forall t2. t0 < t2 \rightarrow t1 \leq$ 
t2)  $\wedge Tp2Od(t1, \varphi)$ ;
   $[\varphi \underline{U} \psi]$  :  $\Psi := \exists t1. t0 \leq$ 
t1  $\wedge Tp2Od(t1, \psi) \wedge interval((t0, 1, t1, 0), \varphi)$ ;
   $[\varphi B \psi]$  :  $\Psi := \forall t1. t0 \leq$ 
t1  $\wedge interval((t0, 1, t1, 0), \neg\varphi) \rightarrow Tp2Od(t1, \neg\psi)$ ;
   $\overleftarrow{X}\varphi$  :  $\Psi := \forall t1. (t1 < t0) \wedge (\forall t2. t2 < t0 \rightarrow t2 \leq$ 
t1)  $\rightarrow Tp2Od(t1, \varphi)$ ;
   $\overleftarrow{X}\varphi$  :  $\Psi := \exists t1. (t1 < t0) \wedge (\forall t2. t2 < t0 \rightarrow t2 \leq$ 
t1)  $\wedge Tp2Od(t1, \varphi)$ ;
   $[\varphi \underline{U} \psi]$  :  $\Psi := \exists t1. t1 \leq$ 
t0  $\wedge Tp2Od(t1, \psi) \wedge interval((t1, 0, t0, 1), \varphi)$ ;
   $[\varphi \overleftarrow{B} \psi]$  :  $\Psi := \forall t1. t1 \leq$ 
t0  $\wedge interval((t1, 0, t0, 1), \neg\varphi) \rightarrow Tp2Od(t1, \neg\psi)$ ;
end
return  $\Psi$ 
end
function interval(l,  $\varphi$ )
case  $\Phi$  of
  (t0, 0, t1, 0) :
    return  $\forall t2. t0 < t2 \wedge t2 < t1 \rightarrow Tp2Od(t2, \varphi)$ ;

```

```

(t0, 0, t1, 1) :
  return  $\forall t2. t0 < t2 \wedge t2 \leq t1 \rightarrow Tp2Od(t2, \varphi)$ ;
(t0, 1, t1, 0) :
  return  $\forall t2. t0 \leq t2 \wedge t2 < t1 \rightarrow Tp2Od(t2, \varphi)$ ;
(t0, 1, t1, 1) :
  return  $\forall t2. t0 \leq t2 \wedge t2 \leq 3t1 \rightarrow Tp2Od(t2, \varphi)$ ;
end
end
Temporal Logic Equivalences and Tips
 $[\varphi \underline{U} \psi] \equiv \varphi$  don't matter when  $\psi$  hold
 $[\varphi B \psi] \equiv \psi$  can't hold when  $\varphi$  hold
 $[\varphi W \psi] \equiv \neg\psi$  hold until  $\varphi \wedge \psi$ 
 $[\varphi \underline{U} \psi] \equiv [\varphi \underline{U} \psi] \vee G\varphi$ 
 $[a \underline{U} Fb] \equiv Fb$ 
 $F[a \underline{U} b] \equiv Fb \equiv [Fa \underline{U} Fb]$ 
 $[\varphi B \psi] \equiv [\varphi B \psi] \vee G\neg\psi$ 
 $F[a B b] \equiv F[a \wedge \neg b]$ 
 $[\varphi W \psi] \equiv \neg[\neg\varphi \underline{W} \psi]$ 
 $E(\varphi \wedge \psi) \equiv E\varphi \wedge E\psi$  (in general)
AEA  $\equiv A$ 
GF(x  $\vee$  y)  $\equiv GFx \vee GFy$ 
FF $\varphi \equiv F\varphi$ 
GG $\varphi \equiv G\varphi$ 
GF $\varphi \equiv XGF\varphi \equiv FGF\varphi \equiv GGF\varphi \equiv GFGF\varphi \equiv$ 
FGGF $\varphi$ 
FG $\varphi \equiv XFG\varphi \equiv FFG\varphi \equiv GFG\varphi \equiv GFFG\varphi \equiv$ 
FGFG $\varphi$ 
 $\Rightarrow$  Rules from F apply to E and rules from G to A.
LTL formulas that can't be translated for CTL
* E[(a1 SU b1) | a2 SU b2] SU c
* E[(a | b SU c) SU d]
* E[[a SU b] SU c] SU d
* EG[(a1 SU b1) | a2 SU b2] SU c
* EG(a | X a)
* EG(a | b SU c)
* EG[[a SU b] SU c]
* EG[a SU b SU c]
G and  $\mu$ -calculus (safety property)

```

```

- $[\nu x. \varphi \wedge \Diamond x]_K$ 
-Contains states s where an infinite path  $\pi$  starts
  with  $\forall t. \pi^{(t)} \in [\varphi]_K$ 
- $\varphi$  holds always on  $\pi$ 
F and  $\mu$ -calculus (liveness property)
- $[\mu x. \varphi \vee \Diamond x]_K$ 
-Contains states s where a (possibly finite) path  $\pi$ 
  starts with  $\exists t. \pi^{(t)} \in [\varphi]_K$ 
- $\varphi$  holds at least once on  $\pi$ 
FG and  $\mu$ -calculus (persistence property)
- $[\mu y. [\nu x. \varphi \wedge \Diamond x] \vee \Diamond y]_K$ 
-Contains states s where an infinite path  $\pi$  starts
  with  $\exists t1. \forall t2. \pi^{(t1+t2)} \in [\varphi]_K$ 
- $\varphi$  holds after some point on  $\pi$ 
GF and  $\mu$ -calculus (fairness property)
- $[\nu y. [\mu x. (y \wedge \varphi) \vee \Diamond x]]_K$ 
-Contains states s where an infinite path  $\pi$  starts
  with
 $\forall t1. \exists t2. \pi^{(t1+t2)} \in [\varphi]_K$ 
- $\varphi$  holds infinitely often on  $\pi$ 
 $\omega$ -Automaton to LO2
A $\exists(q1, ..., qn, \psi I, \psi R, \psi F)$  (input automaton)
 $\exists q1..qn. \Theta LO2(0, \psi I) \wedge (\forall t. \Theta LO2(t, \psi R)) \wedge$ 
 $(\forall t1 \exists t2. t1 < t2 \wedge \Theta LO2(t2, \psi F))$ 
Where  $\Theta LO2(t, \Phi)$  is:
- $\Theta LO2(t, p) := p(t)$  for variable p
- $\Theta LO2(t, X\psi) := \Theta LO2(t+1, \psi)$ 
- $\Theta LO2(t, \neg\psi) := \neg \Theta LO2(t, \psi)$ 
- $\Theta LO2(t, \varphi \wedge \psi) := \Theta LO2(t, \varphi) \wedge \Theta LO2(t, \psi)$ 
- $\Theta LO2(t, \varphi \vee \psi) := \Theta LO2(t, \varphi) \vee \Theta LO2(t, \psi)$ 
Temporal logic set examples
-Pure LTL: AFGa
-Pure CTL: AGEFa
-LTL + CTL: AFa
-CTL*: AFGa  $\vee$  AGEFa
Extra Equations G
AG $[\varphi U \psi] = AG(\varphi \vee \psi)$ 
AG $[\varphi B \psi] = AG(\neg\psi)$ 
AG $[\varphi W \psi] = AG(\psi \rightarrow \varphi)$ 

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AG $[\varphi \underline{U} \psi] = A(G(\varphi \vee \psi) \wedge GF\psi)$ 
AG $[\varphi B \psi] = A(G(\neg\psi) \wedge GF\varphi)$ 
AG $[\varphi \overleftarrow{W} \psi] = A(G(\psi \rightarrow \varphi) \wedge GF\psi)$ 
// note that the following are only initially, but not
generally valid
AG $\overleftarrow{X}\varphi = AG\varphi$ 
AG $\overleftarrow{X}\varphi = A(\text{false})$ 
AG $\overleftarrow{G}\varphi = AG\varphi$ 
AG $\overleftarrow{F}\varphi = A\varphi$ 
AG $[\varphi \overleftarrow{U} \psi] = AG(\varphi \vee \psi)$ 
AG $[\varphi \overleftarrow{B} \psi] = AG(\neg\psi)$ 
AG $[\varphi \overleftarrow{W} \psi] = AG(\psi \rightarrow \varphi)$ 
AG $[\varphi \overleftarrow{U} \psi] = A(\psi \wedge G(\varphi \vee \psi))$ 
AG $[\varphi \overleftarrow{B} \psi] = A(\varphi \wedge G(\neg\psi))$ 
AG $[\varphi \overleftarrow{W} \psi] = A(\psi \wedge G(\psi \rightarrow \varphi))$ 
Extra Equations F
AFF $\psi = AF\psi$ 
AF $[\varphi \underline{U} \psi] = AF\psi$ 
AF $[\varphi \overleftarrow{B} \psi] = AF(\varphi \wedge \neg\psi)$ 
AF $[\varphi \overleftarrow{W} \psi] = AF(\varphi \wedge \psi)$ 
AF $[\varphi \underline{U} \psi] = A(F(\psi) \vee FG\varphi)$ 
AF $[\varphi B \psi] = A(F(\varphi \wedge \neg\psi) \vee FG(\neg\varphi \wedge \neg\psi))$ 
AF $[\varphi W \psi] = A(F(\varphi \wedge \psi) \vee FG\neg\psi)$ 
// note that the following are only initially, but not
generally valid
AF $\overleftarrow{X}\varphi = A(\text{true})$ 
AF $\overleftarrow{X}\varphi = AF\varphi$ 
AF $\overleftarrow{G}\varphi = A\varphi$ 
AF $\overleftarrow{F}\varphi = AF\varphi$ 
AF $[\varphi \overleftarrow{U} \psi] = AF\psi$ 
AF $[\varphi \overleftarrow{B} \psi] = AF(\varphi \wedge \neg\psi)$ 
AF $[\varphi \overleftarrow{W} \psi] = AF(\varphi \wedge \psi)$ 
AF $[\varphi \overleftarrow{U} \psi] = A(F\psi \vee F\overleftarrow{G}\varphi)$ 
AF $[\varphi \overleftarrow{B} \psi] = A(F(\varphi \wedge \neg\psi) \vee F\overleftarrow{G}(\neg\varphi \wedge \neg\psi))$ 
AF $[\varphi \overleftarrow{W} \psi] = A(F(\varphi \wedge \psi) \vee F\overleftarrow{G}\neg\psi)$ 

```