

Propositional Logic - Syntactic Sugar

$\varphi \Leftrightarrow \psi := (\neg\varphi \vee \psi) \wedge (\neg\psi \vee \varphi)$ $\varphi \rightarrow \psi := \neg\varphi \vee \psi$

$\varphi \oplus \psi := (\varphi \wedge \neg\psi) \vee (\psi \wedge \neg\varphi)$ $\varphi \bar{\wedge} \psi := \neg(\varphi \wedge \psi)$

$(\alpha \Rightarrow \beta | \gamma) := (\neg\alpha \vee \beta) \wedge (\alpha \vee \gamma)$ $\varphi \bar{\vee} \psi := \neg(\varphi \vee \psi)$

Satisfiability, Validity and Equivalence

$\text{SAT}(\varphi) := \neg \text{VALID}(\neg\varphi)$ $\varphi \Leftrightarrow \psi := \text{VALID}(\varphi \leftrightarrow \psi)$

$\text{VALID}(\varphi) := (\varphi \Leftrightarrow 1)$ $\text{SAT}(\varphi) := \neg(\varphi \Leftrightarrow 0)$.

Conjunctive Normal Form: from truth table, take minterms that are 0. Each minterm is built as an OR of the negated variables. E.g.,

$(0, 0, 1) \rightarrow (x \vee y \vee \neg z)$.

Distributivity: $a \wedge (b \vee c) = (a \wedge b) \vee (a \wedge c)$

$a \vee (b \wedge c) = (a \vee b) \wedge (a \vee c)$

Sequent Calculus:

1. Prove validity of ϕ : start with $\{\} \vdash \phi$; ϕ is valid iff $\Gamma \cap \Delta \neq \{\}$ for all leaves; else, counterexample: var is true, if $x \in \Gamma$; false otherwise; "don't care", if variable doesn't appear.
2. Prove satisfiability of ϕ : start with $\{\phi\} \vdash \{\}$; ϕ is satisfiable iff $\Gamma \cap \Delta = \{\}$ for at least one leaf. Satisfying interpretation: same as counterexample.

OPER.	LEFT	RIGHT
NOT	$\neg\phi, \Gamma \vdash \Delta$ $\Gamma \vdash \phi, \Delta$	$\Gamma \vdash \neg\phi, \Delta$ $\neg\phi, \Gamma \vdash \Delta$
AND	$\phi \wedge \psi, \Gamma \vdash \Delta$ $\phi, \psi, \Gamma \vdash \Delta$	$\Gamma \vdash \phi \wedge \psi, \Delta$ $\Gamma \vdash \phi, \Delta$ $\Gamma \vdash \psi, \Delta$
OR	$\phi, \Gamma \vdash \Delta$ $\psi, \Gamma \vdash \Delta$	$\Gamma \vdash \phi \vee \psi, \Delta$ $\Gamma \vdash \phi, \psi, \Delta$

Resolution Calculus

$\frac{\{ \neg x \} \cup C_1 \quad \{ x \} \cup C_2}{C_1 \cup C_2}$
To prove unsatisfiability of given clauses in CNF: If we reach $\{\}$, the formula is unsatisfiable. E.g., $\{\{a\}, \{\neg a, b\}, \{\neg b\}\}$, we get:

$\{a\} + \{\neg a, b\} \rightarrow \{b\}$; $\{b\} + \{\neg b\} \rightarrow \{\}$ (unsatisfiable).

To prove validity, prove UNSAT of negated formula.

Linear Clause Forms (Computes CNF)

Bottom up in the syntax tree: convert "operators and variables" into new variable. E.g., $\neg a \vee b$ becomes $x_1 \leftrightarrow \neg a$; $x_2 \leftrightarrow x_1 \vee b$. Use rules below to find CNF.

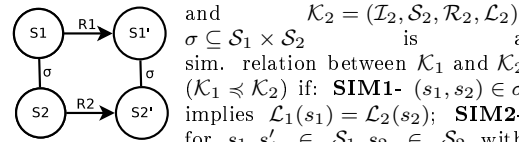
$$\begin{aligned} x &\leftrightarrow \neg y \Leftrightarrow (\neg x \vee \neg y) \wedge (x \vee y) \\ x &\leftrightarrow y_1 \wedge y_2 \Leftrightarrow (\neg x \vee y_1) \wedge (\neg x \vee y_2) \wedge (x \vee \neg y_1 \vee \neg y_2) \\ x &\leftrightarrow y_1 \vee y_2 \Leftrightarrow (\neg x \vee y_1 \vee y_2) \wedge (x \vee \neg y_1) \wedge (x \vee \neg y_2) \\ x &\leftrightarrow y_1 \rightarrow y_2 \Leftrightarrow (x \vee y_1) \wedge (x \vee \neg y_1 \vee \neg y_2) \wedge (\neg x \vee \neg y_1 \vee y_2) \\ x &\leftrightarrow (y_1 \leftrightarrow y_2) \Leftrightarrow (x \vee y_1 \vee y_2) \wedge (x \vee \neg y_1 \vee \neg y_2) \wedge (\neg x \vee y_1 \vee \neg y_2) \wedge (\neg x \vee \neg y_1 \vee y_2) \\ x &\leftrightarrow y_1 \oplus y_2 \Leftrightarrow (x \vee \neg y_1 \vee y_2) \wedge (x \vee y_1 \vee \neg y_2) \wedge (\neg x \vee y_1 \vee y_2) \wedge (\neg x \vee \neg y_1 \vee \neg y_2) \end{aligned}$$

Davis Putnam Procedure - proves SAT; To prove validity: prove unsatisfiability of negated formula. **(1)** Compute Linear Clause Form *(Don't forget to create the last clause $\{x_n\}$)* **(2)** Last variable has to be \perp (true) \rightarrow find implied variables. **(3)** For remaining variables: assume values and

compute newly implied variables. **(4)** If contradiction reached: backtrack.

<pre> Apply(⊙, BddNode a, b) int m; BddNode h, l; if isLeaf(a)&isLeaf(b) then return Eval(⊙, label(a), label(b)); else m=max(label(a),label(b)) (a0,a1):=Ops(a,m); (b0,b1):=Ops(b,m); h:=Apply(⊙,a1,b1); l:=Apply(⊙,a0,b0); return CreateNode(m,h,l) end; </pre>	<pre> Compose(int x, BddNode ψ, α) int m; BddNode h, l; if x>label(ψ) then return ψ; elseif x=label(ψ) then return ITE(α,high(ψ), low(ψ)); else m=max{label(ψ),label(α)}; (α0,α1):=Ops(α, m); (ψ0,ψ1):=Ops(ψ, m); h:=Compose(x,ψ1,α1); l:=Compose(x,ψ0,α0); return CreateNode(m,h,l) endif; end </pre>
<pre> ITE(BddNode i, j, k) int m; BddNode h, l; if i = 0 then return k elseif i=1 then return j elseif j=k then return k else m = max{label(i), label(j),label(k)} (i0,i1):=Ops(i,m); (j0,j1):=Ops(j,m); (k0,k1):=Ops(k,m); l:=ITE(i0,j0,k0); h:=ITE(i1,j1,k1); return CreateNode(m,h,l) end; end </pre>	<pre> Constrain(Φ, β) if β=0 then ret 0 elseif Φ ∈ {0,1} (β = 1) ret Φ else m=max{label(β),label(Φ)} (Φ0,Φ1):=Ops(Φ,m); (β0,β1):=Ops(β,m); if β0=0 ret Constrain(Φ1,β1) elseif β1=0 then ret Constrain(Φ0,β0) else l:=Constrain(Φ0,β0); h:=Constrain(Φ1,β1); ret CreateNode(m,h,l) endif; endif; end </pre>
<pre> Restrict(Φ, β) if β=0 return 0 elseif Φ ∈ {0,1} ∨ (β = 1) return Φ else m=max{label(β),label(Φ)} (Φ0,Φ1):=Ops(Φ,m); (β0,β1):=Ops(β,m) if β0=0 return Restrict(Φ1,β1) elseif β1=0 return Restrict(Φ0,β0) elseif m=label(Φ) return CreateNode(m, Restrict(Φ1,β1), Restrict(Φ0,β0)) else return Restrict(Φ, Apply(v,β0,β1)) endif; endif; end </pre>	<pre> Ops(v,m) x:=label(v); if m=degree(x) return (low(v),high(v)) else return(v, v) end; end </pre> <p>Other Diagrams: TODD ZDD FDD</p> <p>----</p>

Simulation:



$(s_1, s_2) \in \sigma$ and $(s_1, s'_1) \in \mathcal{R}_1$, there must be $s'_2 \in \mathcal{S}_2$ with $(s'_1, s'_2) \in \sigma$ (s_2, s'_2) $\in \mathcal{R}_2$; **SIM3-** for all $s_1 \in \mathcal{I}_1$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$.

Greatest Simulation Relation

$(s_1, s_2) \in \mathcal{H}_0 \Leftrightarrow \mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$

$(s_1, s_2) \in \mathcal{H}_{i+1} \Leftrightarrow$

$\left(\begin{aligned} &(s_1, s_2) \in \mathcal{H}_i \wedge \\ &\forall s'_1 \in \mathcal{S}_1. \exists s'_2 \in \mathcal{S}_2. \\ &(s_1, s'_1) \in \mathcal{R}_1 \rightarrow (s_2, s'_2) \in \mathcal{R}_2 \wedge (s'_1, s'_2) \in \mathcal{H}_i \end{aligned} \right)$

\mathcal{H}_* is the greatest simulation relation if **SIM3:**

$\mathcal{I}_1 \subseteq \{s_1 \in \mathcal{S}_1 | \exists s_2 \in \mathcal{I}_2. (s_1, s_2) \in \mathcal{H}_*\}$

Bisimulation: $\sigma \subseteq \mathcal{S}_1 \times \mathcal{S}_2$ is a bisim. relation

between \mathcal{K}_1 and \mathcal{K}_2 ($\mathcal{K}_1 \approx \mathcal{K}_2$) if: **BISIM1-**

$(s_1, s_2) \in \sigma$ implies $\mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$; **BISIM2a-**

$(s_1, s'_1) \in \mathcal{S}_1, s_2 \in \mathcal{S}_2, (s_1, s_2) \in \sigma, (s_1, s'_1) \in \mathcal{R}_1$, imply that there is $s'_2 \in \mathcal{S}_2$ with $(s'_1, s'_2) \in \sigma$ and $(s_2, s'_2) \in \mathcal{R}_2$; **BISIM2b-** $s_2, s'_2 \in \mathcal{S}_2, s_1 \in \mathcal{S}_1, (s_1, s_2) \in \sigma, (s_2, s'_2) \in \mathcal{R}_2$, imply that there is $s'_1 \in \mathcal{S}_1$ with $(s'_1, s'_2) \in \sigma$ and $(s_1, s'_1) \in \mathcal{R}_1$; **BISIM3a-** for all $s_1 \in \mathcal{I}_1$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$; **BISIM3b-** for all $s_1 \in \mathcal{I}_2$, there is a $s_2 \in \mathcal{I}_2$ with $(s_1, s_2) \in \sigma$.

Greatest Bisimulation Relation (Equivalence)

$(s_1, s_2) \in \mathcal{B}_0 \Leftrightarrow \mathcal{L}_1(s_1) = \mathcal{L}_2(s_2)$

$(s_1, s_2) \in \mathcal{B}_{i+1} \Leftrightarrow$

$\left(\begin{aligned} &(s_1, s_2) \in \mathcal{B}_i \wedge \\ &\forall s'_1 \in \mathcal{S}_1. \exists s'_2 \in \mathcal{S}_2. \\ &(s_1, s'_1) \in \mathcal{R}_1 \rightarrow (s_2, s'_2) \in \mathcal{R}_2 \wedge (s'_1, s'_2) \in \mathcal{B}_i \\ &\forall s'_2 \in \mathcal{S}_2. \exists s'_1 \in \mathcal{S}_1. \\ &(s_2, s'_2) \in \mathcal{R}_2 \rightarrow (s_1, s'_1) \in \mathcal{R}_1 \wedge (s'_1, s'_2) \in \mathcal{B}_i \end{aligned} \right)$

\mathcal{B}_* is the greatest simulation relation if

$\mathcal{I}_1 \subseteq \{s_1 \in \mathcal{S}_1 | \exists s_2 \in \mathcal{I}_2. (s_1, s_2) \in \mathcal{B}_*\}$

$\mathcal{I}_2 \subseteq \{s_2 \in \mathcal{S}_2 | \exists s_1 \in \mathcal{I}_1. (s_1, s_2) \in \mathcal{B}_*\}$

Quotient: given $\mathcal{K} = (\mathcal{I}, \mathcal{S}, \mathcal{R}, \mathcal{L})$ and the

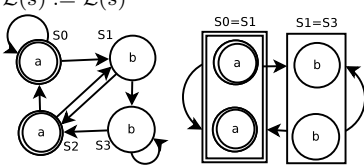
equivalence relation $\sigma \subseteq \mathcal{S} \times \mathcal{S}$; Quotient structure

$\mathcal{K}_{/\sigma} = (\tilde{\mathcal{I}}, \tilde{\mathcal{S}}, \tilde{\mathcal{R}}, \tilde{\mathcal{L}})$: $\tilde{\mathcal{I}} := \{\{s' \in \mathcal{S} | (s, s') \in \sigma\} | s \in \mathcal{I}\}$

$\tilde{\mathcal{S}} := \{\{s' \in \mathcal{S} | (s, s') \in \sigma\} | s \in \mathcal{S}\}$

$(\tilde{s}_1, \tilde{s}_2) \in \tilde{\mathcal{R}} : \Leftrightarrow \exists s'_1 \in \tilde{s}_1. \exists s'_2 \in \tilde{s}_2. (s'_1, s'_2) \in \mathcal{R}$

$\tilde{\mathcal{L}}(\tilde{s}) := \mathcal{L}(s)$



Symbolic Product Computation - given

$\mathcal{K}_1 = (\mathcal{V}_1, \varphi_{\mathcal{I}}, \varphi_{\mathcal{R}})$ and $\mathcal{K}_2 = (\mathcal{V}_2, \psi_{\mathcal{I}}, \psi_{\mathcal{R}})$, the

product is: $\mathcal{K}_1 \times \mathcal{K}_2 = (\mathcal{V}_1 \cup \mathcal{V}_2, \varphi_{\mathcal{I}} \wedge \psi_{\mathcal{I}}, \varphi_{\mathcal{R}} \wedge \psi_{\mathcal{R}})$

Quantif. $\exists x. \varphi := [\varphi]_x^1 \vee [\varphi]_x^0 \quad \forall x. \varphi := [\varphi]_x^1 \wedge [\varphi]_x^0$

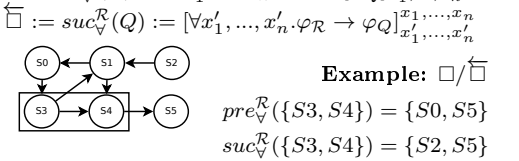
Predecessor and Successor

$\diamond := \text{pre}_{\mathcal{S}}^{\mathcal{R}}(Q) := \exists x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \wedge [\varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$

$\bar{\diamond} := \text{suc}_{\mathcal{S}}^{\mathcal{R}}(Q) := \exists x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \wedge \varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$

$\square := \text{pre}_{\mathcal{V}}^{\mathcal{R}}(Q) := \forall x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \rightarrow [\varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$

$\bar{\square} := \text{suc}_{\mathcal{V}}^{\mathcal{R}}(Q) := \forall x'_1, \dots, x'_n. \varphi_{\mathcal{R}} \rightarrow \varphi_Q]_{x'_1, \dots, x'_n}^{x_1, \dots, x_n}$



Example: $\square / \bar{\square}$

$\text{pre}_{\mathcal{V}}^{\mathcal{R}}(\{S3, S4\}) = \{S0, S5\}$

$\text{suc}_{\mathcal{V}}^{\mathcal{R}}(\{S3, S4\}) = \{S2, S5\}$

$\text{pre}_{\mathcal{S}}^{\mathcal{R}}(Q = \{S_1, \dots, S_n\})$ for each node n in \mathcal{K} : if n points to a node that is not in Q n $\notin \text{pre}_{\mathcal{S}}^{\mathcal{R}}(Q)$ else n $\in \text{pre}_{\mathcal{S}}^{\mathcal{R}}(Q)$	$\text{suc}_{\mathcal{S}}^{\mathcal{R}}(Q = \{S_1, \dots, S_n\})$ for each node n in \mathcal{K} : if (n is pointed by a node that is not in Q) n $\notin \text{suc}_{\mathcal{S}}^{\mathcal{R}}(Q)$ else n $\in \text{suc}_{\mathcal{S}}^{\mathcal{R}}(Q)$
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Tarski-Knaster Theorem: $\mu :=$ starts $\perp \rightarrow$

least fixpoint $\spadesuit \nu :=$ starts $\top \rightarrow$ greatest fixpoint *

Rabin-Scott Subset Construction 1. Initial

state is a set of states containing all the initial

states. **2.** For all transitions of a set of states,

compute the successors and create a set of states

containing all the possible reachable states when

performing that transition. **3.** Acceptance condition

are set of states containing acceptance states.

Local Model Checking

$\frac{\text{st} \vdash \varphi \wedge \psi}{\{ \text{st} \vdash \varphi \} \quad \{ \text{st} \vdash \psi \}} \wedge$	$\frac{\text{st} \vdash \varphi \vee \psi}{\{ \text{st} \vdash \varphi \} \quad \{ \text{st} \vdash \psi \}} \vee$
$\frac{\text{st} \vdash \varphi \sqsubseteq \psi}{\{ \text{st}_1 \vdash \varphi \} \dots \{ \text{st}_n \vdash \varphi \}} \wedge$	$\frac{\text{st} \vdash \varphi \supseteq \psi}{\{ \text{st}_1 \vdash \varphi \} \dots \{ \text{st}_n \vdash \varphi \}} \vee$
$\frac{\text{st} \vdash \varphi \sqsubseteq \psi}{\{ \text{st}'_1 \vdash \varphi \} \dots \{ \text{st}'_n \vdash \varphi \}} \wedge$	$\frac{\text{st} \vdash \varphi \supseteq \psi}{\{ \text{st}'_1 \vdash \varphi \} \dots \{ \text{st}'_n \vdash \varphi \}} \vee$
$\frac{\text{st} \vdash \varphi \mu x. \varphi}{\text{st} \vdash \varphi} \quad \frac{\text{st} \vdash \varphi \nu x. \varphi}{\text{st} \vdash \varphi}$	$\frac{\text{st} \vdash \varphi}{\text{st} \vdash \varphi} \quad \frac{\mathcal{D} \varphi (\text{replace w. initial form.})}{\text{st} \vdash \varphi}$
$\{s_1 \dots s_n\} = \text{suc}_{\mathcal{S}}^{\mathcal{R}}(s)$ and $\{s'_1 \dots s'_n\} = \text{pre}_{\mathcal{S}}^{\mathcal{R}}(s)$	

Approximations and Ranks

If $(s, \mu x. \varphi)$ repeats \rightarrow return 1	$\text{apx}_0(\mu x. \varphi) := 0$
If $(s, \nu x. \varphi)$ repeats \rightarrow return 0	$\text{apx}_0(\nu x. \varphi) := 1$
$\text{apx}_{n+1}(\mu x. \varphi) := \lfloor \varphi \rfloor_x^{\text{apx}_n(\mu x. \varphi)}$	
$\text{apx}_{n+1}(\nu x. \varphi) := \lfloor \varphi \rfloor_x^{\text{apx}_n(\nu x. \varphi)}$	

Automata types: G \rightarrow Safety; F \rightarrow Liveness;

FG \rightarrow Persistence/Co-Buchi; GF \rightarrow Fairness/Buchi.

Automaton Determinization

NDet_G \rightarrow Det_G: 1. Remove all states/edges that do

not satisfy acceptance condition; 2. Use Subset

construction (Rabin-Scott); 3. Acceptance condition

will be the states where $\{\}$ is never reached.

{NDet_F(partial) or NDet_{prefix}} \rightarrow Det_{FG}:

Breakpoint Construction.

NDet_F(total) \rightarrow Det_F: Subset Construction.

NDet_{FG} \rightarrow Det_{FG}: Breakpoint Construction.

NDet_{GF} \rightarrow {Det_{Rabin} or Det_{Streett}}: Safra

Algorithm.

* **Breakpoint Construction 1.** Each state is

composed by two components **2.** Initial state first

component is a set of all initial states, and second

component is the empty set. Ex.: $(\mathcal{I}, \{\})$. **3.** a

successor for a state (Q, Q_f) is generated as follows:

$\left\{ \begin{aligned} &\text{If } Q_f = \{\} \quad (\text{suc}_{\mathcal{S}}^{\mathcal{R}a}(Q), (\text{suc}_{\mathcal{S}}^{\mathcal{R}a}(Q) \cap \mathcal{F})) \\ &\text{Otherwise} \quad (\text{suc}_{\mathcal{S}}^{\mathcal{R}a}(Q), (\text{suc}_{\mathcal{S}}^{\mathcal{R}a}(Q_f) \cap \mathcal{F})) \end{aligned} \right.$

4. Acceptance states are states where $Q_f \neq \{\}$.

Boolean Operations on ω -Automata

Complement

$\neg \mathcal{A}_{\forall}(Q, \mathcal{I}, \mathcal{R}, \mathcal{F}) = \mathcal{A}_{\exists}(Q, \mathcal{I}, \mathcal{R}, \neg \mathcal{F})$

$\neg \mathcal{A}_{\exists}(Q, \mathcal{I}, \mathcal{R}, \mathcal{F}) = \mathcal{A}_{\forall}(Q, \mathcal{I}, \mathcal{R}, \neg \mathcal{F})$

Conjunction

$(\mathcal{A}_{\exists}(Q_1, \mathcal{I}_1, \mathcal{R}_1, \mathcal{F}_1) \wedge \mathcal{A}_{\exists}(Q_2, \mathcal{I}_2, \mathcal{R}_2, \mathcal{F}_2)) =$

$\mathcal{A}_{\exists}(Q_1 \cup Q_2, \mathcal{I}_1 \wedge \mathcal{I}_2, \mathcal{R}_1 \wedge \mathcal{R}_2, \mathcal{F}_1 \wedge \mathcal{F}_2)$

Disjunction

$(\mathcal{A}_{\exists}(Q_1, \mathcal{I}_1, \mathcal{R}_1, \mathcal{F}_1) \vee \mathcal{A}_{\exists}(Q_2, \mathcal{I}_2, \mathcal{R}_2, \mathcal{F}_2)) =$

$\mathcal{A}_{\exists} \left(\begin{aligned} &Q_1 \cup Q_2 \cup \{q\}, \\ &(\neg q \wedge \mathcal{I}_1) \vee (q \wedge \mathcal{I}_2), \\ &(\neg q \wedge \mathcal{R}_1 \wedge \neg q') \vee (q \wedge \mathcal{R}_2 \wedge q'), \\ &(\neg q \wedge \mathcal{F}_1) \vee (q \wedge \mathcal{F}_2) \end{aligned} \right)$

If both automata are totally defined,

$(\mathcal{A}_{\exists}(Q_1, \mathcal{I}_1, \mathcal{R}_1, \mathcal{F}_1) \vee \mathcal{A}_{\exists}(Q_2, \mathcal{I}_2, \mathcal{R}_2, \mathcal{F}_2)) =$

$\mathcal{A}_{\exists}(Q_1 \cup Q_2, \mathcal{I}_1 \wedge \mathcal{I}_2, \mathcal{R}_1 \wedge \mathcal{R}_2, \mathcal{F}_1 \vee \mathcal{F}_2)$

Eliminate Nesting - Acceptance condition **must** be

an automata of the same type

$\mathcal{A}_{\exists}(Q^1, \mathcal{I}_1^1, \mathcal{R}_1^1, \mathcal{A}_{\exists}(Q^2, \mathcal{I}_2^1, \mathcal{R}_2^1, \mathcal{F}_1))$

$= \mathcal{A}_{\exists}(Q^1 \cup Q^2, \mathcal{I}_1^1 \wedge \mathcal{I}_2^1, \mathcal{R}_1^1 \wedge \mathcal{R}_2^1, \math$

Boolean Operations of F	
(1) $\neg F\varphi = G\neg\varphi$	(2) $F\varphi \vee F\psi = F[\varphi \vee \psi]$
(3) $F\varphi \wedge F\psi = A_{\exists}(\{p, q\}, \neg p \wedge \neg q, [p' \leftrightarrow p \vee \varphi] \wedge [q' \leftrightarrow q \vee \psi], F[p \wedge q])$	
Boolean Operations of FG	
(1) $\neg FG\varphi = GF\neg\varphi$	(2) $FG\varphi \wedge FG\psi = FG[\varphi \wedge \psi]$
(3) $FG\varphi \vee FG\psi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow (q \Rightarrow \psi) \neg \varphi), FG[\neg q \vee \psi])$	

Boolean Operations of GF	
(1) $\neg GF\varphi = FG\neg\varphi$	(2) $GF\varphi \vee GF\psi = GF[\varphi \vee \psi]$
(3) $GF\varphi \wedge GF\psi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow (q \Rightarrow \neg\psi) \varphi), GF[q \wedge \psi])$	

Transformation of Acceptance Conditions

Reduction of G
$G\varphi = A_{\exists}(\{q\}, q, \varphi \wedge q \wedge q', Fq))$
$G\varphi = A_{\exists}(\{q\}, q, q' \leftrightarrow q \wedge \varphi, FGq)$
$G\varphi = A_{\exists}(\{q\}, q, q' \leftrightarrow q \wedge \varphi, GFq)$

Reduction of F
$F\varphi$ can not be expressed by $NDet_G$
$F\varphi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow q \vee \varphi, FGq)$
$F\varphi = A_{\exists}(\{q\}, \neg q, q' \leftrightarrow q \vee \varphi, GFq)$

Reduction of FG
$FG\varphi$ can not be expressed by $NDet_G$
$FG\varphi = A_{\exists}(\{q\}, \neg q, q \rightarrow \varphi \wedge q', Fq)$
$FG\varphi = A_{\exists} \left(\begin{bmatrix} \{p, q\}, & \neg p \wedge \neg q, \\ (p \rightarrow p') \wedge (p' \rightarrow p \vee \neg q) \wedge \\ (q' \leftrightarrow (p \wedge \neg q \vee \neg \varphi) \vee (p \wedge q)) \end{bmatrix}, \begin{matrix} G\neg q \wedge Fp \end{matrix} \right),$
$FG\varphi = A_{\exists} \left(\begin{bmatrix} \{p, q\}, & \neg p \wedge \neg q, \\ (p \rightarrow p') \wedge (p' \rightarrow p \vee \neg q) \wedge \\ (q' \leftrightarrow (p \wedge \neg q \vee \neg \varphi) \vee (p \wedge q)) \end{bmatrix}, \begin{matrix} GF[p \wedge \neg q] \end{matrix} \right),$

Temporal Logics *Beware of Finite Paths*
E and A quantify over infinite paths.
A φ holds on every state that has no infinite path;
E φ is false on every state that has no infinite path;
A0 holds on states with only finite paths;
E1 is false on state with only finite paths;
□0 holds on states with no successor states;
◇1 holds on states with successor states.

$F\varphi = \varphi \vee XF\varphi$	$G\varphi = \varphi \wedge XG\varphi$
$[\varphi \ U \ \psi] = \psi \vee (\varphi \wedge X[\varphi \ U \ \psi])$	
$[\varphi \ B \ \psi] = \neg\psi \wedge (\varphi \vee X[\varphi \ B \ \psi])$	
$[\varphi \ W \ \psi] = (\psi \wedge \varphi) \vee (\neg\psi \wedge X[\varphi \ W \ \psi])$	

Negation Normal Form

$\neg(\varphi \wedge \psi) = \neg\varphi \vee \neg\psi$	$\neg(\varphi \vee \psi) = \neg\varphi \wedge \neg\psi$
$\neg\neg\varphi = \varphi$	$\neg X\varphi = X\neg\varphi$
$\neg G\varphi = F\neg\varphi$	$\neg F\varphi = G\neg\varphi$
$\neg[\varphi \ U \ \psi] = [(\neg\varphi) \ \underline{B} \ \psi]$	$\neg[\varphi \ \underline{U} \ \psi] = [(\neg\varphi) \ B \ \psi]$
$\neg[\varphi \ B \ \psi] = [(\neg\varphi) \ \underline{U} \ \psi]$	$\neg[\varphi \ U \ \psi] = [(\neg\varphi) \ U \ \psi]$
$\neg A\varphi = E\neg\varphi$	$\neg E\varphi = A\neg\varphi$
$\neg \widetilde{X}\varphi = \widetilde{X}\neg\varphi$	$\neg \widetilde{X}\varphi = \widetilde{X}\neg\varphi$
$\neg \widetilde{G}\varphi = \widetilde{F}\neg\varphi$	$\neg \widetilde{F}\varphi = \widetilde{G}\neg\varphi$
$\neg[\varphi \ \widetilde{U} \ \psi] = [(\neg\varphi) \ \widetilde{\underline{B}} \ \psi]$	$\neg[\varphi \ \widetilde{\underline{U}} \ \psi] = [(\neg\varphi) \ \widetilde{B} \ \psi]$
$\neg[\varphi \ \widetilde{B} \ \psi] = [(\neg\varphi) \ \widetilde{\underline{U}} \ \psi]$	$\neg[\varphi \ \widetilde{\underline{B}} \ \psi] = [(\neg\varphi) \ \widetilde{U} \ \psi]$

LTL Syntactic Sugar: analog for past operators

$G\varphi = \neg[1 \ U \ (\neg\varphi)]$	$F\varphi = [1 \ U \ \varphi]$
$[\varphi \ W \ \psi] = \neg[(\neg\varphi \vee \neg\psi) \ \underline{U} \ (\neg\varphi \wedge \psi)]$	
$[\varphi \ \underline{W} \ \psi] = [(\neg\psi) \ \underline{U} \ (\varphi \wedge \psi)]$ <small>$(\neg\psi \text{ holds until } \varphi \wedge \psi)$</small>	
$[\varphi \ B \ \psi] = \neg[(\neg\varphi) \ \underline{U} \ \psi]$	
$[\varphi \ \underline{B} \ \psi] = [(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)]$ <small>$(\psi \text{ can't hold when } \varphi \text{ holds})$</small>	
$[U \ \psi] = \neg[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)]$	
$[\varphi \ U \ \psi] = [\varphi \ \underline{U} \ \psi] \vee G\varphi$	

$[\varphi \ \underline{U} \ \psi] = \neg[(\neg\psi) \ U \ (\neg\varphi \wedge \neg\psi)]$	
$[\varphi \ \underline{U} \ \psi] = \neg[(\neg\psi) \ W \ (\varphi \rightarrow \psi)]$	
$[\varphi \ \underline{U} \ \psi] = [\psi \ \underline{W} \ (\varphi \rightarrow \psi)]$	
$[\varphi \ \underline{U} \ \psi] = \neg[(\neg\varphi) \ B \ \psi]$ <small>$(\varphi \text{ doesn't matter when } \psi \text{ holds})$</small>	
$[\varphi \ \underline{U} \ \psi] = [\psi \ \underline{B} \ (\neg\varphi \wedge \neg\psi)]$	

CTL Syntactic Sugar: analog for past operators

Existential Operators
$EF\varphi = E[1 \ \underline{U} \ \varphi]$
$EG\varphi = E[\varphi \ U \ 0]$
$E[\varphi \ U \ \psi] = E[\varphi \ \underline{U} \ \psi] \vee EG\varphi$
$E[\varphi \ B \ \psi] = E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)] \vee EG\neg\psi$
$E[\varphi \ B \ \psi] = E[(\neg\psi) \ U \ (\varphi \wedge \neg\psi)]$
$E[\varphi \ \underline{B} \ \psi] = E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \neg\psi)]$
$E[\varphi \ \underline{B} \ \psi] = E[(\neg\psi \ \underline{U} \ (\varphi \wedge \neg\psi)) \vee EG\neg\psi$
$E[\varphi \ W \ \psi] = E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \psi)]$
$E[\varphi \ W \ \psi] = E[(\neg\psi) \ U \ (\varphi \wedge \psi)]$
$E[\varphi \ \underline{W} \ \psi] = E[(\neg\psi) \ \underline{U} \ (\varphi \wedge \psi)]$

Universal Operators
$AX\varphi = \neg EX\neg\varphi$
$AG\varphi = \neg E[1 \ \underline{U} \ \neg\varphi]$
$AF\varphi = \neg EG\neg\varphi$
$AF\varphi = \neg E[(\neg\varphi) \ U \ 0]$
$A[\varphi \ U \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)]$
$A[\varphi \ \underline{U} \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \neg\psi)] \wedge \neg EG\neg\psi$
$A[\varphi \ U \ \psi] = \neg E[(\neg\psi) \ U \ (\neg\varphi \wedge \neg\psi)]$
$A[\varphi \ B \ \psi] = \neg E[(\neg\varphi) \ \underline{U} \ \psi]$
$A[\varphi \ \underline{B} \ \psi] = \neg E[(\neg\varphi) \ U \ \psi]$
$A[\varphi \ \underline{B} \ \psi] = \neg E[(\neg\varphi \vee \psi) \ \underline{U} \ \psi] \wedge \neg EG(\neg\varphi \vee \psi)$
$A[\varphi \ W \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \psi)]$
$A[\varphi \ \underline{W} \ \psi] = \neg E[(\neg\psi) \ \underline{U} \ (\neg\varphi \wedge \psi)] \wedge \neg EG\neg\psi$
$A[\varphi \ \underline{W} \ \psi] = \neg E[(\neg\psi) \ U \ (\neg\varphi \wedge \psi)]$

CTL to μ – Calculus ($\Phi_{inf} = \nu y. \Diamond y$)
$EX\varphi = \Diamond(\Phi_{inf} \wedge \varphi)$
$EG\varphi = \nu x. \varphi \wedge \Diamond x$
$EF\varphi = \mu x. \Phi_{inf} \wedge \varphi \vee \Diamond x$
$E[\varphi \underline{U} \psi] = \mu x. (\Phi_{inf} \wedge \psi) \vee \varphi \wedge \Diamond x$
$E[\varphi \underline{U} \psi] = \nu x. (\Phi_{inf} \wedge \psi) \vee \varphi \wedge \Diamond x$
$E[\varphi \underline{B} \psi] = \mu x. \neg\psi \wedge (\Phi_{inf} \wedge \varphi \vee \Diamond x)$
$E[\varphi B \psi] = \nu x. \neg\psi \wedge (\Phi_{inf} \wedge \varphi \vee \Diamond x)$
$AX\varphi = \Box(\Phi_{inf} \rightarrow \varphi)$
$AG\varphi = \nu x. (\Phi_{inf} \rightarrow \varphi) \wedge \Box x$
$AF\varphi = \mu x. \varphi \vee \Box x$
$A[\varphi \underline{U} \psi] = \mu x. \psi \vee (\Phi_{inf} \rightarrow \varphi) \wedge \Box x$
$A[\varphi \underline{U} \psi] = \nu x. \psi \vee (\Phi_{inf} \rightarrow \varphi) \wedge \Box x$
$A[\varphi \underline{B} \psi] = \mu x. (\Phi_{inf} \rightarrow \neg\psi) \wedge (\varphi \vee \Box x)$
$A[\varphi B \psi] = \nu x. (\Phi_{inf} \rightarrow \neg\psi) \wedge (\varphi \vee \Box x)$

CTL* to CTL - Existential Operators

$EX\varphi = EXE\varphi$	
$EF\varphi = EF EF\varphi$	$EF G\varphi \equiv EF EG\varphi$
$E[\varphi \ W \ \psi] = E[(E\varphi) \ W \ \psi]$	
$E[\varphi \ \underline{W} \ \psi] = E[(E\varphi) \ \underline{W} \ \psi]$	
$E[\psi \ U \ \varphi] = E[\psi \ U \ E(\varphi)]$	
$E[\psi \ \underline{U} \ \varphi] = E[\psi \ \underline{U} \ E(\varphi)]$	
$E[\varphi \ B \ \psi] = E[(E\varphi) \ B \ \psi]$	
$E[\varphi \ \underline{B} \ \psi] = E[(E\varphi) \ \underline{B} \ \psi]$	

obs. $EGF\varphi \neq EGEF\varphi \rightarrow$ can't be converted

CTL* to CTL - Universal Operators

$AX\varphi = AX A\varphi$
$AG\varphi = AG A\varphi$
$A[\varphi \ W \ \psi] = A[(A\varphi) \ W \ \psi]$
$A[\varphi \ \underline{W} \ \psi] = A[(A\varphi) \ \underline{W} \ \psi]$
$A[\varphi \ U \ \psi] = A[A(\varphi) \ U \ \psi]$
$A[\varphi \ \underline{U} \ \psi] = A[A(\varphi) \ \underline{U} \ \psi]$

$A[\psi \ B \ \varphi] = A[\psi \ B \ (E(\varphi))]$
$A[\psi \ B \ \varphi] = A[\psi \ B \ (E(\varphi))]$
Eliminate boolean op. after path quantify
$[\varphi_1 \ \underline{U} \ \psi_1] \wedge [\varphi_2 \ \underline{U} \ \psi_2] =$

$$\left[(\varphi_1 \wedge \varphi_2) \ \underline{U} \ \left(\psi_1 \wedge [\varphi_2 \ \underline{U} \ \psi_2] \vee \right. \right. \\ \left. \left. \psi_2 \wedge [\varphi_1 \ \underline{U} \ \psi_1] \right) \right]$$

$$[\varphi_1 \ \underline{U} \ \psi_1] \wedge [\varphi_2 \ U \ \psi_2] =$$

$$\left[(\varphi_1 \wedge \varphi_2) \ \underline{U} \ \left(\psi_1 \wedge [\varphi_2 \ U \ \psi_2] \vee \right. \right. \\ \left. \left. \psi_2 \wedge [\varphi_1 \ \underline{U} \ \psi_1] \right) \right]$$

$$[\varphi_1 \ U \ \psi_1] \wedge [\varphi_2 \ U \ \psi_2] =$$

$$\left[(\varphi_1 \wedge \varphi_2) \ \underline{U} \ \left(\psi_1 \wedge [\varphi_2 \ U \ \psi_2] \vee \right. \right. \\ \left. \left. \psi_2 \wedge [\varphi_1 \ U \ \psi_1] \right) \right]$$

CTL* Modelchecking to LTL model checking

Let's φ_i be a pure path formula (without path quantifiers), Ψ be a propositional formula, abbreviate subformulas $E\varphi$ and $A\psi$ working bottom-up the syntax tree to obtain the following

$$\text{normal form: } \phi = \text{let } \begin{bmatrix} x_1 = A\varphi_1 \\ \vdots \\ x_n = A\varphi_n \end{bmatrix} \text{ in } \Psi \text{ end}$$

Use LTL model checking to compute

$Q_i := \llbracket A\varphi_i \rrbracket_{\mathcal{K}_i-1}$, where $\mathcal{K}_0 := \mathcal{K}$ and \mathcal{K}_{i+1} is obtained from \mathcal{K}_i by labelling the states Q_i with x_i .

Finally compute $\llbracket \Psi \rrbracket_{\mathcal{K}_n}$

LTL to ω -automata

$\phi \langle X\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow X\varphi, \phi \langle q \rangle_x)$
$\phi \langle X\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q_0, q_1\}, 1,$

$$(q_0 \leftrightarrow \varphi) \wedge (q_1 \leftrightarrow Xq_0), \phi \langle q_1 \rangle_x) \\ \phi \langle G\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \varphi \wedge Xq,$$

$$\phi \langle F\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \varphi \wedge Xq, \\ \phi \langle q \rangle_x \wedge GF[q \rightarrow \varphi])$$

$$\phi \langle [\varphi \ U \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \psi \vee \varphi \wedge Xq, \\ \phi \langle q \rangle_x \wedge GF[\varphi \rightarrow q])$$

$$\phi \langle [\varphi \ \underline{U} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \psi \vee \varphi \wedge Xq, \\ \phi \langle q \rangle_x \wedge GF[q \rightarrow \psi])$$

$$\phi \langle [\varphi \ B \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \neg\psi \wedge (\varphi \vee Xq), \\ \phi \langle q \rangle_x \wedge GF[q \vee \psi])$$

$$\phi \langle [\varphi \ \underline{B} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, 1, q \leftrightarrow \neg\psi \wedge (\varphi \vee Xq), \\ \phi \langle q \rangle_x \wedge GF[q \rightarrow \varphi])$$

$$\phi \langle \widetilde{X}\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \varphi, \phi \langle q \rangle_x)$$

$$\phi \langle \widetilde{X}\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \varphi, \phi \langle q \rangle_x)$$

$$\phi \langle \widetilde{G}\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \varphi \wedge q, \phi \langle \varphi \wedge q \rangle_x)$$

$$\phi \langle \widetilde{F}\varphi \rangle_x \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \varphi \vee q, \phi \langle \varphi \vee q \rangle_x)$$

$$\phi \langle [\varphi \ \widetilde{U} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \psi \vee \varphi \wedge q, \\ \phi \langle \psi \vee \varphi \wedge q \rangle_x)$$

$$\phi \langle [\varphi \ \widetilde{\underline{U}} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \psi \vee \varphi \wedge q, \\ \phi \langle \psi \vee \varphi \wedge q \rangle_x)$$

$$\phi \langle [\varphi \ \widetilde{B} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, q, Xq \leftrightarrow \neg\psi \wedge (\varphi \vee q), \\ \phi \langle \neg\psi \wedge (\varphi \vee q) \rangle_x)$$

$$\phi \langle [\varphi \ \widetilde{\underline{B}} \ \psi] \rangle_x \Leftrightarrow A_{\exists}(\{q\}, \neg q, Xq \leftrightarrow \neg\psi \wedge (\varphi \vee q), \\ \phi \langle \neg\psi \wedge (\varphi \vee q) \rangle_x)$$

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