Gauss-Jordan Forward Followed by backward Sub

```
>> M=[1 0 5 -2 9;1 -2 9 -2 -5;-2 2 -14 -2 20;-1 -2 -1 0 -15];
>> M
M =
    1 0 5 -2 9
1 -2 9 -2 -5
    >> %E21(-1) E31(2) E41(1)
 >> M(2,:)=M(2,:)+-1*M(1,:);
 >> M(3,:)=M(3,:)+2*M(1,:);
 >> M(4,:)=M(4,:)+1*M(1,:)
    1 0 5 -2 9
0 -2 4 0 -14
0 2 -4 -6 38
0 -2 4 -2 -6
>> %E32(1) E34(-1)
>> %E32(1) E42(-1)
>> M(3,:)=M(3,:)+1*M(2,:);
>> M(4,:)=M(4,:)+-1*M(2,:)
M =
                     -2 9
     1
          0
              5
        -2 4 0 -14
0 0 -6 24
     0
     0
              0
     0
        0
                   -2 8
```

>> %E43(-1/3)

1

0

0

0

M =

>> M(4,:)=M(4,:)+-1/3*M(3,:)

5

4 0 0 -6 24

0

-2 9 0 -14

0 0

0

-2

0

```
>> %Backwards Elimination
>> %E3(-1/6)
>> M(3,:) = (-1/6)*M(3,:)
M =
           5 –2 9
    1
       0
    0 -2 4 0 -14
0 0 0 1 -4
0 0 0 0 0
   0
>> %E13(2)
>> M(1,:)=M(1,:)+ 2*M(3,:)
M =
    1 0 5 0 1
    0 -2 4 0 -14
0 0 0 1 -4
0 0 0 0 0 0
      0
>> %E2(-1/2)
>> M(2,:)=-1/2*M(2,:)
            5
                 0
                     1
7
       0
   1
    0
        1
            -2
                  0
   0 0 0 1 -4
   0
       0 0 0
                     0
```

```
b.)
rref (M)
>> rref(M)
ans =
    1 0 5 0 1
0 1 -2 0 7
   1 0
    c.)
Rank [M] = 3
Rank [A] = 3
matlab
>> rank(A)
ans =
>> rank(M)
   3
>> 'rank (A)
```

ans =

d.) The system is consistent and as a result of rank[A] <n, the system is not unique and has infinitely many solutions.

consistent or non consistent / unique or not unique

a.)

The system is consistent and due to the fact rank[A]<n, the system is not unique and due to the last row being all zero, has infinitely many solutions. This is under the assumption rank[A] will have the same definition as question 2 and n being the count of columns in a coefficient matrix.

If we consider the variables a,b,c,d with the corresponding columns we can say the following about a:

a = -3

```
b.)
```

```
>> M= [-2 -8 1 2 -11 -9;-2 -8 0 1 -12 -6;3 12 3 -1 26 -1;-5 -20 2 -5 -9 -57;-5 -20 3 3 -22 -32;2 8 -2 -2 8 14]
      -8 1 2 -11
       -8
12
           0 1 -12
3 -1 26
                           -6
   -2
                           -1
            2 -5 -9 -57
            3 3 -22 -32
-2 -2 8 14
   -5 -20
>> rref(M)
ans =
            0 0
            1 0
      0 0 1 -2 0
0 0 0 0 1
0 0 0 0 0
    0
```

The system is inconsistent and has no solutions.

c.)

```
>> M = [-3 2 -4 3 3 -47;-1 2 1 -2 -1 14;-1 -2 2 -1 2 -24;5 0 -1 -1 5 -17;1 1 4 3 3 -29
M =
                3 -47
  -3
          -4 3
         1 -2 -1 14
  -1
      2
  -1
      -2
         2 -1 2 -24
     0 -1 -1 5 -17
1 4 3 3 -29
   5
>> rref(M)
ans =
     0 0 0 0
                    2
      1 0 0 0
     0 1 0 0 0
   0 0 0 1 0 -3
     0 0 0 1
                     -9
```

The system in consistent. There is exactly one solution for every variable, meaning that they system is unique (Rank[A]=n). The answers to the variables are shown below:

c=0

Distributive Clause w/ Random Matrix

```
>> A=randi([-5 5],2,3)
                                     >> %c(A+B)=cA+cB
                                     >> c* (A+B)
                                     ans =
    3 -5 -3
    4 -1 3
                                       1.7386 -6.9543 -6.0850
                                       7.8236 -3.4772 -0.8693
>> B=randi([-5 5],2,3)
                                     >> c*A+c*B
B =
                                     ans =
   -1 -3 -4
      -3 -4
                                        1.7386 -6.9543 -6.0850
                                        7.8236 -3.4772 -0.8693
>> c=rand()
   0.8693
```

The above concretely shows that the distributive law for scalar multiplication holds true

```
b.)
```

```
D=c(A+B)
E=cA+cB
Dij=(c(A+B))ij
Eij=cAij+cBij

(c(A+B))ij=cAij+cBij
-->by definition of +

=cAij+cBij
-->distribution of + over matrices
|
=(c(A+B))ij
-->by definiion of +

for all i,j so c(A+B)=cA+cB
Dij=Eij
```