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Facet nanoarchitectonics of visible-light driven Ag₃PO₄ photocatalytic micromotors: Tuning motion for biofilm eradication

Daniel Rojas¹, Michaela Kuthanova², Kristyna Dolezelikova² and Martin Pumera 6,34,5

Abstract

The customized design of micro-/nanomotors represents one of the main research topics in the field of micro-/nanomotors; however, the effects of different crystal facets on micromotor movement are often neglected. In this work, self-propelled amorphous, cubic, and tetrahedral Ag₃PO₄ particles were synthetized using a scalable precipitation method. Their programmable morphologies exhibited different motion properties under fuel-free and surfactant-free conditions and visible light irradiation. Differences in these motion properties were observed according to morphology and correlated with photocatalytic activity. Moreover, Ag₃PO₄ micromotors are inherently fluorescent, which allows fluorescence-based tracking. Furthermore, bacterial biofilms represent a major concern in modern society since most of them are antibiotic resistant. The as-prepared self-propelled particles exhibited morphologically dependent antibiofilm activities toward gram-positive and gram-negative bacteria. The enhanced diffusion of the particles promoted biofilm removal in comparison with static control experiments, realizing the possibility of a new class of light-driven biofilm-eradicating micromotors that do not require the use of both H₂O₂ and UV light.

Introduction

Light-driven nano-/micromotors have received great attention in recent years due to their interesting advantages compared to catalytic micromotors. The use of light to drive motion allows remote action in their movements, reversible on/off motion and the tuning of active wavelengths by tuning the micromotor composition, which are difficult to obtain in chemically driven micromotors. Hence, there is increasing interest in the synthesis and characterization of light-active materials as nano-/micromotors. For instance, TiO₂^{2,3}, ZnO⁴, and AgCl^{5,6} have been used as photoactive materials under UV irradiation. However, there is growing interest in developing new nanomaterials that are capable of producing motion

under visible light irradiation, such as Cu₂O⁷, SiO₂/Au/ PEN⁸, and BiVO₄⁹, sulfur- and nitrogen-containing porous donor-acceptor polymers $(SNPs)^{10}$ or $C_3N_4^{11}$. Ag₃PO₄ is a promising photocatalytic material due to its high separation of photogenerated electron/hole pairs facilitated by the absorption of visible light. This enables the degradation of organic pollutants and the production of oxygen from water splitting. Different strategies for improving Ag₃PO₄ photoactivity have been reported, such as its combination with other materials to form composites or heterostructures and in crystal facet engineering ¹². Despite its promising capabilities as a visible-light driven photocatalyst, it has been scarcely used for the development of micromotors. Ag₃PO₄ micromotors have been proposed as active colloids using UV light¹³ or chemical¹⁴ stimuli in their spherical form containing mixed facets and as visible light-driven micromotors in their cubic form¹⁵. The controllable synthesis of light-driven micromotors is still a relevant area of research in the field of improving micromotor capabilities. In recent years,

Correspondence: Martin Pumera (pumera.research@gmail.com)

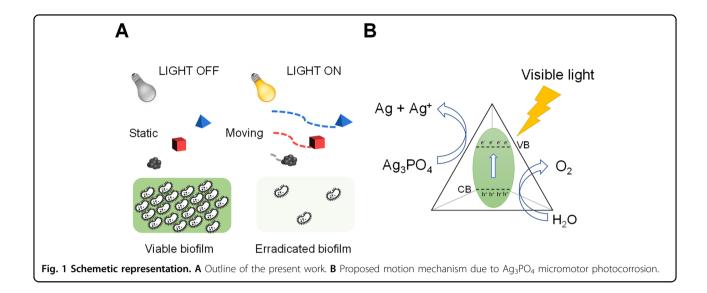
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¹Future Energy and Innovation Laboratory, Central European Institute of Technology, Brno University of Technology (CEITEC-BUT), Purkyňova 123, 61200 Brno, Czech Republic

²Department of Chemistry and Biochemistry, Mendel University in Brno, Zemedelska 1, CZ-613 00 Brno, Czech Republic



different structures, such as microtubes 11,16 and Janus spheres $^{17-19}$, have been successfully implemented in micro-/nanorobots using different catalytic materials. However, even considering the critical role that facets have in the photocatalytic performance of a semiconductor, it remains unexplored in the micromotor field except for a very recent paper by Liu et al. 20 , which studied the effects of facets on Cu_2O micromotor motion.

Many studies are conducted with interest in the application of micromotors in combatting bacterial contamination. The abilities to produce motion and carry potential antibacterial compounds are promising tools for the combination of mechanical eradication and biochemical interactions between micromotors and bacterial biofilms^{21–25}.

The ability of bacteria to form biofilms is a dangerous kind of virulence that causes threats in the surgery field (risk of gram-positive methicillin-resistant *Staphylococcus aureus* (MRSA) presence) and in the food industry, such as the dairy and meat industries (risk of gram-negative *Pseudomonas aeruginosa* (*P. aeruginosa*) presence)²⁶. The removal of biofilms by commonly used sanitary compounds is impossible to conduct in hard-to-reach places. By combining the mechanical eradication of biofilms by micromotors with the cell death of biofilm bacteria, a modern and sophisticated method is facilitated for application in biofouling clean-up processes in many industries²⁷.

Therefore, in this work, the effects of the presence of different exposed facets on the motion of visible-light driven Ag₃PO₄ photocatalytic micromotors was evaluated. In addition, taking advantage of the antibacterial properties of Ag₃PO₄, their ability to eliminate the bacterial biofilms of *P. aeruginosa* and MRSA bacteria was observed in the absence of H₂O₂ and UV light.

Results and discussion

Preparation and characterization of Ag_3PO_4 photocatalytic micromotors

The effects of different crystal facets on the photocatalytic properties of Ag₃PO₄ have been studied in recent years to improve its performance in the photo-degradation of pollutants 28,29 , water splitting 12,30,31 and biofilm eradication^{32–34}. Even if some reports in the literature were conducted with regard to the motion of Ag₃PO₄-based particles, only cubic and amorphous particles have been separately studied. However, the effects of different shapes and facets of different Ag₃PO₄ particles remain unexplored. Therefore, the main objective of this work was to explore the effects of crystal facet engineering on Ag₃PO₄-based micromotor motion and antibiofilm properties (Fig. 1A). To investigate the relationships between facets and motion, different shapes of Ag₃PO₄ micromotors were synthetized using a cheap and scalable precipitation method. Amorphous Ag₃PO₄ (am-Ag₃PO₄) containing mixed facets, cubic Ag₃PO₄ (c-Ag₃PO₄) with dominating {100} facets and tetrahedral Ag₃PO₄ (t-Ag₃PO₄) with dominating {111} facets were synthesized. Am-Ag₃PO₄ was synthetized by the direct precipitation of AgNO3 with NaH₂PO₄, while in the case of c-Ag₃PO₄, a silver/ammonia complex was formed before the addition of NaH₂PO₄. The motion mechanism for light-powered Ag₃PO₄-based nanocarriers is schematically illustrated in Fig. 1B. Visible light photons having energies equal to or higher than the Ag₃PO₄ bandgap are absorbed, promoting electrons (e⁻) from the valence band (VB) to the conduction band (CB) and leaving holes in the VB. The energy of the holes created by visible light is sufficiently high to oxidize water, producing oxygen. However, the energy of the electrons is lower than that of H⁺/H₂; hence, without the addition of

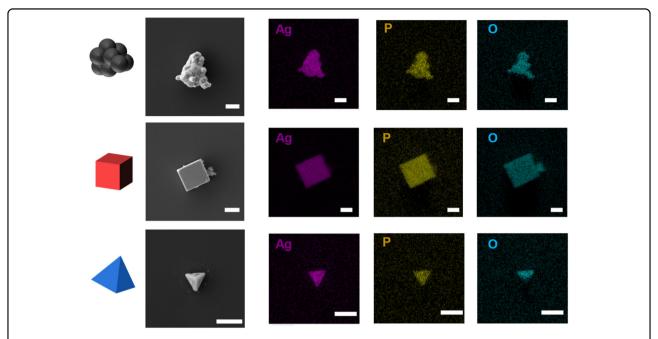


Fig. 2 SEM micrographs and EDX elemental mapping images of Ag_3PO_4 micromotors. From top to bottom, the rows correspond to am- Ag_3PO_4 , c- Ag_3PO_4 and t- Ag_3PO_4 . Scale bar: 1 μ m.

an electron scavenger, Ag_3PO_4 itself will decompose during water photooxidation, producing Ag on the surface and realizing the formation of Ag^+ ions^{13,35}. The asymmetric generation of chemical species on the surface of the Ag_3PO_4 micromotors is mainly responsible for their motion¹⁵. Since the photogenerated ions diffuse at different rates, a local electric field is generated due to the asymmetric charge distribution around the motor, moving the particles forward due to a self-diffusiophoretic mechanism^{9,36}. Due to the high activity of this reaction, Ag_3PO_4 is able to display self-propulsion in fuel-free conditions in deionized water.

As seen in the micrographs shown in Fig. 2, the successful syntheses of am-Ag₃PO₄, c-Ag₃PO₄ and t-Ag₃PO₄ were accomplished. Additionally, the EDS mapping confirmed the presence of the constituent elements Ag, P and O, confirming the particle composition. However, a larger cluster of particles retaining the shape and exposed facets were also observed, as shown in Fig. S1.

To confirm the dominating facets in the prepared samples, their XRD spectra were recorded and investigated. The X-ray diffraction patterns shown in Fig. 3A clearly indicate a full phase match with the body-centered cubic crystalline structure of Ag_3PO_4 (6.004 Å, BCC, JCPDS no. 06-0505). No additional peaks were found in the XRD signals, indicating well-crystallized pure-phase compounds for all the structures and the absence of impurities. The c- Ag_3PO_4 showed an intensity ratio of 0.35 between the peaks of the {110} and {200} planes,

which is weaker than that in the am-Ag₃PO₄ (0.65) and t-Ag₃PO₄ (0.63) planes. This indicates the preferential exposure of {100} facets in c-Ag₃PO₄. In addition, the ratio between the {222} and {200} planes is higher in the case of t-Ag₃PO₄ (1.20) than in the cases of am-Ag₃PO₄ (1.01) and c-Ag₃PO₄ (0.43). These ratios indicate the preferential exposure of {111} facets in t-Ag₃PO₄ 30,37 . The UV-vis spectra (UV-VIS) of the different particles are presented in Fig. 3B. All samples showed an absorption edge at approximately 500 nm, confirming their visible light absorption.

Motion behavior of Ag₃PO₄ photocatalytic micromotors

The motion of the different synthesized Ag₃PO₄ micromotors can be observed in Videos S1 to S3 for t-Ag₃PO₄, c-Ag₃PO₄ and am-Ag₃PO₄, respectively. The particles were tracked using Trackmate, and the resulting trajectories were extracted and plotted from the coordinate origin of each particle (Fig. 4A). Particle movement was tracked over 10 s under dark and illuminated conditions using a visible light microscope source, and the track length was dramatically increased from the dark to the illuminated conditions, confirming the visible lightpowered motion mechanism of the particles. The Ag₃PO₄ micromotor trajectories were studied by performing mean-squared displacement (MSD) analysis under different dark and visible light irradiation conditions in deionized water. The MSD (µm²) for a given time interval (Δt) is defined as follows, where <> indicates an

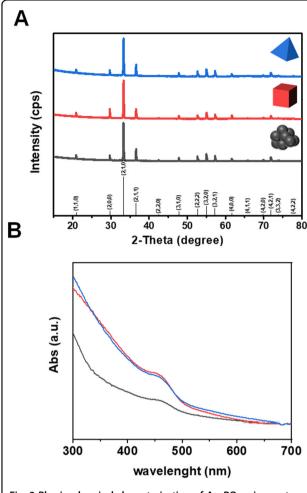


Fig. 3 Physicochemical characterization of Ag₃PO₄ micromotors. A XRD patterns of the different morphologies of Ag₃PO₄ micromotors. **B** UV–Vis spectra of Ag₃PO₄ micromotors. a-Ag₃PO₄ (gray), c-Ag₃PO₄ (red) and t-Ag₃PO₄ (blue).

assembly of n particles:

$$\langle MSD \rangle = (x(\Delta t) - x_0)^2 + (y(\Delta t) - y_0)^2 \tag{1}$$

In the case of pure Brownian motion, the MSD obeys the following relationship:

$$\langle MSD \rangle = 4D\Delta t \tag{2}$$

where D $(\mu m^2 s^{-1})$ is the diffusion coefficient of the particles.

In the case of ballistic motion, the MSD obeys the following relationship:

$$\langle MSD \rangle = 4D\Delta t + \nu^2 \Delta t^2 \tag{3}$$

The time interval or frame rate used (50 FPS) was set below the rotational diffusion (τ_R), where ballistic motion dominates over rotational motion. τ_R was calculated using the following equation:

$$\tau_R = \frac{8\pi\eta R^3}{k_B T} \tag{4}$$

where η is the viscosity (0.89 mPa), k_B is the Boltzmann constant, T is the temperature (25 °C) and R is the particle radius. τ_R was estimated to be 13 s, and hence, the MSD was studied for t < 1 s ($t < \tau_R$). Under these conditions, the motion mechanisms of the Ag₃PO₄-based micromotors containing different facets were studied through their MSD analyses. Under dark conditions, the MSD values of all three structures increased linearly over time, indicating Brownian motion, whereas under visible light irradiation, increased parabolically, indicating ballistic motion (Fig. 4B). From the MSD fitting, the diffusion coefficients of the micromotors were calculated and are plotted in Fig. 4C. The mixed potential of a semiconductor under dark and light conditions provides information about the corresponding catalytic process. As seen in Fig. 4D, the mixed potential values of the different Ag₃PO₄ micromotors were shifted toward more anodic potentials following the order of $\Delta E_{Ag3PO4Light:dark} = 73$, 51, and 29 mV for t-Ag₃PO₄, c-Ag₃PO₄ and a-Ag₃PO₄, respectively. The positive shift in the mixed potential under irradiation indicates the tendency of the material to be reduced, which is associated with the photocorrosion of Ag₃PO₄ into Ag, which is related to micromotor motion and O2 generation. Interestingly, these differences in the mixed potentials were correlated with the diffusion coefficients (D) of the Ag₃PO₄ micromotors. Therefore, the trend found in the motion capability is in agreement with previous reports wherein {111} facets exhibited a higher photocatalytic activity than the {100} facets, confirming that we can tune the motion of Ag₃PO₄ micromotors using faceting nanoarchitectonics ^{30,37}. Figure 5 shows the strong fluorescence exhibited by the Ag₃PO₄-based micromotors under 488 nm excitation. By taking advantage of their inherent fluorescence, the motors can also be tracked by fluorescence microscopy.

Biofilm eradication using Ag₃PO₄ photocatalytic micromotors

Our group's previous work studied the application of micromotors in targeting gram-positive and gramnegative biofilms. The motion of micromotors was induced by the presence of both 1 wt% $\rm H_2O_2$ and UV light exposure²⁰. Despite the excellent eradication effect, $\rm H_2O_2$ at high concentrations and UV exposure are still

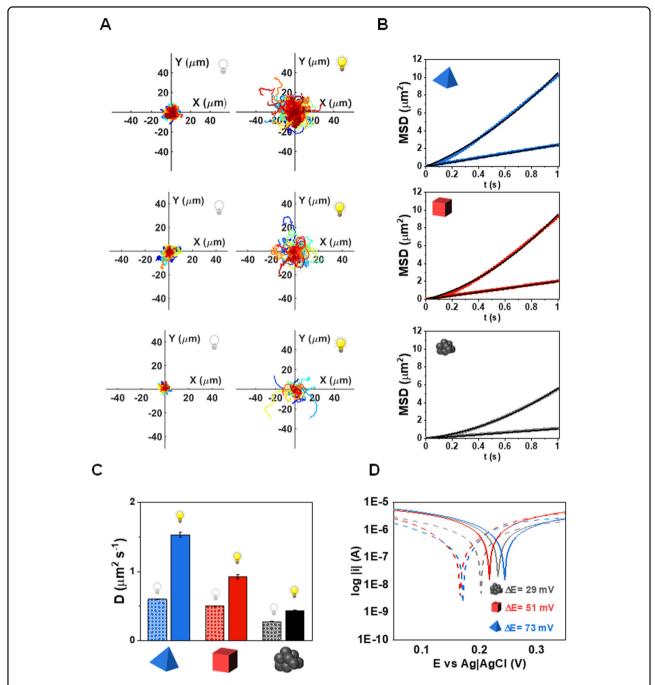


Fig. 4 Motion characteriztion of Ag₃PO₄ micromotors. A Groupings of the analyzed trajectories of Ag₃PO₄ micromotors over 10 s plotted from a single origin under dark (lightbulb OFF) and visible illumination (lightbulb ON). **B** MSD values of Ag₃PO₄ micromotors under dark conditions (squares) and visible light illumination (circles). Each row corresponds to a micromotor shape; from top to bottom: $t-Ag_3PO_4$, $c-Ag_3PO_4$ and $a-Ag_3PO_4$. (blue), $c-Ag_3PO_4$ (fred) and $a-Ag_3PO_4$ (black). **D** Tafel plots of $t-Ag_3PO_4$ (blue), $t-Ag_3PO_4$ (fred) and $t-Ag_3PO_4$ (black).

invasive for nontargeted bacteria and other surrounding organisms. In this study of micromotors, motion is induced by visible light along without the need for H_2O_2 . The am- Ag_3PO_4 , c- Ag_3PO_4 , and t- Ag_3PO_4 micromotors were tested on two different bacterial monospecies

biofilms. The bacterial strains used for the biofilm eradication tests were gram-positive in the case of methicillin-resistant *Staphylococcus aureus* (MRSA) and gram-negative in the case of *Pseudomonas aeruginosa* (*P. aeruginosa*).

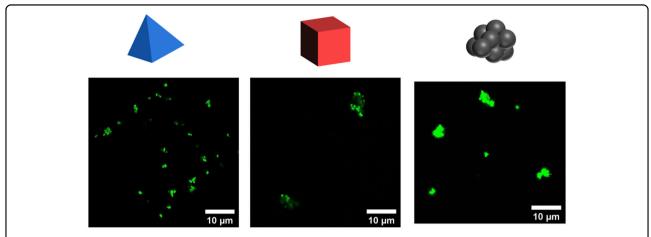


Fig. 5 Fluorescence microscopy images of t-Ag₃PO₄, c-Ag₃PO₄ and a-Ag₃PO₄ (from left to right) micromotors in pure water under light excitation (λ_{exc} = 488 nm). The light emitted by the particles was recorded at λ_{em} = 500–550 nm.

Viability assays were performed under three different conditions: control (indicated as C, bacteria under light exposure), in the presence of static micromotors (1 µg/ mL) under dark conditions (S) and using the same amount of moving micromotors under light irradiation (M). As shown in Fig. 6A, the presence of micromotors dramatically affected biofilm viability, which was highly decreased in the presence of static micromotors (66%, 74% and 45% for am-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄, respectively) and decreased to a greater extent under moving conditions (17%, 57% and 15% for am-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄, respectively). In addition to biofilm viability, the influences of the micromotors on biofilm thickness were evaluated with positive results. The treatment of gram-negative Pseudomonas aeruginosa with all micromotor shapes resulted in significant decreases in biofilm thickness, from 77 µm in the control to 45, 38, and 18% with respect to the control values for am-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄, respectively (Fig. 6B). Additionally, the confocal microscope images of the biofilm shown in Fig. S4 indicate a sparser and weaker biofilm after treatment.

The treatment of the biofilm of methicillin-resistant *S. aureus* (MRSA) by micromotors was significantly more effective in comparison with that of *P. aeruginosa* biofilm. In this case, the viability assay, as shown in oltzmann constant, T is the tem Fig. 7A, showed that in the presence of static micromotors, lower viability was recorded in comparison to that of *P. aeruginosa* (1%, 32% and 18% for am-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄, respectively), which decreased to a greater extent under moving conditions (0.5%, 4% and 4% for am-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄, respectively). The thickness of the biofilm also decreased in comparison to that of the control, from 19 μm for the control to 9, 8 and 13 μm for am-Ag₃PO₄,

c-Ag₃PO₄, and t-Ag₃PO₄, respectively. The biofilm again appeared sparser than the control (Fig. S5).

Differences in the effects on MRSA and *P. aeruginosa* are caused by the arrangement and composition of the biofilm matrix and by the molecular composition of the bacterial gram-positive and gram-negative cell walls. Previous reports, such as those in the study performed by Choi et al., mentioned that the pathogen autoaggregation ability of *S. aureus* is 2 times higher than that of *P. aeruginosa*. The reason for this may be the significantly higher ability of *P. aeruginosa* to produce proteins, carbohydrates, and eDNA in its biofilms compared to that of MRSA, which could explain the different efficiencies of biofilm eradication observed in this work³⁸.

Conclusions

In this work, we developed fuel-free Ag₃PO₄ micromotors powered by visible light irradiation. The Ag₃PO₄based micromotors were synthetized with different exposed facets to study the corresponding effects on their motion. t-Ag₃PO₄ exhibited the highest motion capability, which is in accordance with its more active facets. Moreover, the Ag₃PO₄-based micromotors exhibited high inherent fluorescence, which can be advantageous for their tracking. Furthermore, the proposed Ag₃PO₄-based micromotors were employed for the biofilm eradication of gram-positive and gram-negative bacterial biofilms, demonstrating enhanced biofilm eradication under motion conditions compared with that under static conditions. These results show the potential of crystal facet engineering in the design of new micromotors for tuning their motion and also demonstrate the use of low-cost visible light-driven fuel-free photocatalytic-based micromotors as alternatives to other previously reported antibiofilm micromotors requiring the use of both UV light and H₂O₂.

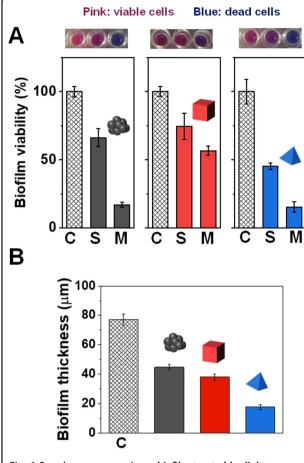


Fig. 6 Pseudomonas aeruginosa biofilm treated by light-propelled Ag₃PO₄ micromotors under dark and visible-light irradiation conditions for 60 min. A control without the presence of particles and light irradiation was added. A Determination of the biofilm viability of *P. aeruginosa* after treatment with a-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄ micromotors. B Measurement of *P. aeruginosa* biofilm thickness after exposure to light-propelled micromotors. C (control): without the presence of motors or light, S (static): in the presence of micromotors and M (moving): in the presence of micromotors and light.

Material and methods Synthesis

Different Ag_3PO_4 shapes were synthetized by a simple and scalable precipitation method as follows. For t- Ag_3PO_4 , 43 mg $AgNO_3$ was added to a beaker containing 2 mL of ethanol to form a homogeneous solution. The solution was added dropwise to a reaction flask containing 10 mL of 0.1 M H_3PO_4 ethanol solution at 60 °C, forming a precipitate. In the case of c- Ag_3PO_4 , the formation of the $[Ag(NH_3)_2]^+$ complex was required prior to Ag_3PO_4 . To achieve this, 100 mg $AgNO_3$ was added to 10 mL deionized water, and 0.1 M ammonia solution was added dropwise. First, a dark precipitate of silver oxides appeared, which was further dissolved by adding an excess of NH_3 to form the $[Ag(NH_3)_2]^+$ complex. Then, 0.15 M

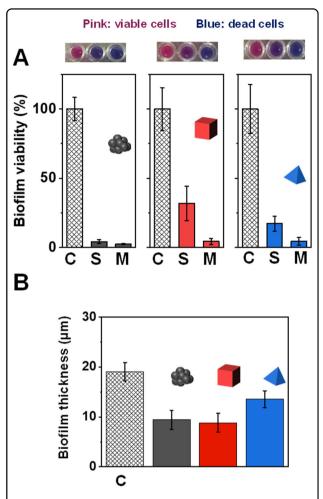


Fig. 7 Effect of light-propelled Ag₃PO₄ micromotors on the biofilm of methicillin-resistant *S. aureus* (MRSA) under dark and visible-light irradiation conditions for 60 min. A control without the presence of particles and light irradiation was added.

A Determination of the biofilm viability of MRSA after treatment with a-Ag₃PO₄, c-Ag₃PO₄, and t-Ag₃PO₄. B Measurement of MRSA biofilm thickness after exposure to light-propelled micromotors. C (control): without the presence of motors or light, S (static): in the presence of micromotors and M (moving): in the presence of micromotors and light.

 Na_2HPO_4 solution was added dropwise to the $[Ag(NH_3)_2]^+$ solution to form a precipitate. For a-Ag₃PO₄, 10 mL of 0.15 M Na_2HPO_4 was added dropwise to 30 mL of 0.15 M $AgNO_3$ to obtain a precipitate. The obtained yellow precipitates were collected by centrifugation and washed with deionized water and ethanol four times. Finally, the obtained powders were dried in an oven at 60 °C for 12 h^{37,39}.

Physicochemical characterization

A Tescan MIRA 3 XMU SEM equipped with an EDX detector (Oxford Instruments) was used for morphology characterization and elemental mapping. The crystallinity

was studied by X-ray diffraction (XRD) using an X-ray diffractometer (Rigaku SmartLab 3 kW) with a Brag Brentano geometry and Cu K α radiation. UV–Vis spectra were recorded using a Jasco V-750 UV–Vis spectrophotometer.

Electrochemical measurements

Prior to Tafel experiments, $5 \,\mu L$ of a Ag_3PO_4 suspension (1 mg mL $^{-1}$) was dropcast onto a screen-printed electrode to produce a working electrode. An $Ag/AgCl/0.1 \, M$ KCl electrode was used as a reference electrode, and a Pt wire was used as a counter electrode. Deionized water was used as an electrolyte to mimic the conditions of the movement experiments. Tafel plot measurements were carried out with an Autolab potentiostat (PGSTAT 204, Metrohm) with NOVA software 2.1 at a scan rate of $5 \, \text{mV s}^{-1}$. The irradiation source was a customized setup consisting of light-emitting diodes (LZ4-40B208, LedEngin Inc.) with a wavelength of $460 \, \text{nm}$.

Movement characterization

For the movement characterization, a-Ag₃PO₄, c-Ag₃PO₄ and t-Ag₃PO₄ dispersions at concentrations of 0.05 mg were placed on glass slides that were then observed using 40x and 60x objectives (Nikon ECLIPSE TS2R inverted microscope). Videos were recorded using a Hamamatsu digital C13440-20CU camera at a frame rate of 50 FPS. The light flux (160 mW/cm^2) was determined by measuring the light power passing through the sample position (Optical power meter S305C, Thorlabs, USA). The recorded videos were tracked using the Trackmate plugin for Imagel⁴⁰, and MSD values were calculated using the msdanalyzer⁴¹.

Biofilm eradication experiments

a-Ag₃PO₄, c-Ag₃PO₄ and t-Ag₃PO₄ were used for the elimination of monospecies bacterial biofilms. Grampositive methicillin-resistant S. aureus (CCM 7110) and gram-negative Pseudomonas aeruginosa (CCM 3955) bacteria obtained from the Czech Collection of Microorganisms (CCM, Brno, Czech Republic) were tested for biofilm eradication in 96-well plates using the following protocol: Fresh bacterial culture was diluted in brain heart infusion broth (BHI) to an optical density of 0.1 (OD600), and 200 µL of bacterial inoculum was pipetted into 96well U-shaped plates for 7 days of incubation at 37 °C. The BHI medium was changed regularly every day. After incubation, the biofilm plates were washed three times with phosphate-buffered saline (PBS). Micromotors were used at a concentration of $1 \mu g \, mL^{-1}$. The experiments were performed in four replicates, and error bars are expressed as the standard deviation. Plates with biofilm and micromotor samples were irradiated using an LED lamp (Fig. S3 for emission spectra) to enhance biofilm eradication ability, and the controls were prepared at the same time. Measurements of biofilm viability were performed at 60 min, and then the biofilms were washed three times with PBS. Biofilm viability was determined by Alamar Blue staining (Thermo Fisher Scientific, Waltham, MA, USA) according to the manufacturer's instructions. The fluorescence of each well was evaluated (560/590 nm, excitation/emission). 3D biofilm images and thicknesses were collected using confocal scanning microscopy as described in our previous study²⁰.

Acknowledgements

This work was supported by the project Advanced Functional Nanorobots (reg. No. CZ.02.1.01/0.0/0.0/15_003/0000444 financed by the EFRR). M.P. was also supported by Ministry of Education, Youth and Sports (Czech Republic) grant LL2002 under ERC CZ program. K.D. and M.K. acknowledge financial support from ERDF "Multidisciplinary research to increase application potential of nanomaterials in agricultural practice" (No. CZ.02.1.01/0.0/0.0/16_025/0007314).

Author details

¹Future Energy and Innovation Laboratory, Central European Institute of Technology, Brno University of Technology (CEITEC-BUT), Purkyňova 123, 61200 Brno, Czech Republic. ²Department of Chemistry and Biochemistry, Mendel University in Brno, Zemedelska 1, CZ-613 00 Brno, Czech Republic. ³Department of Chemical and Biomolecular Engineering, Yonsei University, 50 Yonsei-ro, Seodaemun-Gu, Seoul 03722, South Korea. ⁴Department of Medical Research, China Medical University Hospital, China Medical University, No. 91 Hsueh-Shih Road, Taichung 40402, Taiwan. ⁵Center for Advanced Functional Nanorobots, Department of Inorganic Chemistry, University of Chemistry and Technology Prague, Technicka 5, 166 28 Prague, Czech Republic

Author contributions

D.R. designed the experiments, synthesized the ${\rm Ag_3PO_4}$ micromotors, and performed SEM-EDX, XRD, UV–Vis, electrochemical measurements, and motion analysis. M.K. participated in biofilm preparation, treatment optimization, and the determination of biofilm viability. K.D. prepared and treated the biofilms for confocal microscopy and biofilm thickness measurements, supervised the design of the microbiological analyses and contributed to writing of the manuscript. M.P. conceptualized the research and supervised the micromotor-based work.

Competing interests

The authors declare no competing interests

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Supplementary information The online version contains supplementary material available at https://doi.org/10.1038/s41427-022-00409-0.

Received: 27 February 2022 Revised: 12 May 2022 Accepted: 1 June 2022. Published online: 29 July 2022

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