# Package 'DescriptiveRepresentationCalculator'

January 9, 2025

**Title** Descriptive Representation Calculator: Characterizing Observed and Expected Representation **Version** 1.0.0

**Description** A system for analyzing descriptive representation, especially for comparing the composition of a political body to the population it represents. Users can compute the expected degree of representation for a body under a random sampling model, the expected degree of representation variability, as well as representation scores from observed political bodies. The package is based on Gerring, Jerzak, and Oncel (2024) <doi:10.1017/S0003055423000680>.

URL https://github.com/cjerzak/DescriptiveRepresentationCalculator-software/

# **BugReports https:**

//github.com/cjerzak/DescriptiveRepresentationCalculator-software/issues

**Depends** R (>= 3.3.3)

License GPL-3

**Encoding** UTF-8

LazyData false

Imports stats

RoxygenNote 7.3.2

# **Contents**

Index																														5
	SDRepresentation				•												 •													3
	ObservedRepresentation																													2
	ExpectedRepresentation	٠	٠	٠	•	٠	٠	•	•	 •	٠	٠	•	٠	٠	•	 •	•	٠	٠	٠	٠	٠	•	٠	•	 •	٠	٠	1

ExpectedRepresentation

Compute the expected degree of representation for any group in a political body

#### **Description**

Finds the degree of expected representation for any group in a political body under a random sampling model as described in Gerring, Jerzak and Oncel (2024).

#### Usage

```
ExpectedRepresentation(PopShares, BodyN, a = -0.5, b = 1)
```

### **Arguments**

PopShares A numeric vector containing the group-level population proportions.

BodyN A positive integer denoting the size of the political body in question.

a, b The a and b parameters control the affine transformation for how the represen-

tation measure is summarized. That is, a and b control how the expected L1 deviation of the population shares from the body shares is re-weighted. The expected L1 deviation is the average value of the absolute deviation of the population from body shares under a random sampling model. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a\*E[L1]+b. By default, a=-0.5 and b=1 so that the expected Rose Index of Proportionality is

returned.

#### Value

The expected degree of representation (a scalar).

#### References

• John Gerring, Connor T. Jerzak, Erzen Oncel. (2024), The Composition of Descriptive Representation, *American Political Science Review*, 118(2): 784-801. doi:10.1017/S0003055423000680

# Examples

 ${\tt Observed Representation}$ 

Compute the observed degree of representation for any group in a political body

# **Description**

Finds the degree of observed representation for any group in a political body.

# Usage

```
ObservedRepresentation(BodyMemberCharacteristics, PopShares, BodyShares, a = -0.5, b = 1)
```

SDRepresentation 3

#### **Arguments**

BodyMemberCharacteristics

A vector specifying the characteristics for members of a political body.

PopShares A numeric vector specifying population shares of identities specified in the

body-member characteristics input. The names of the entries in PopShares should correspond to identities in that body-member characteristics input (see

Example).

BodyShares (optional) A numeric vector with same structure as PopShares specifying group

population shares of a given body. If specified, used by default instead of

BodyMemberCharacteristics.

a, b Parameters controlling the affine transformation for how the representation mea-

sure is summarized. That is, a and b control how the L1 deviation of the population shares from the body shares is re-weighted. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a\*L1+b. By default, a=-0.5

and b=1 so that the Rose Index of Proportionality is returned.

#### Value

The observed degree of representation (a scalar). By default, this quantity is the Rose Index of Proportionality.

# **Examples**

SDRepresentation

Compute the amount of representation left unexplained by a random sampling model.

# Description

Finds the residual standard deviation when using the expected representation for any group in a political body to predict observed representation as described in Gerring, Jerzak and Oncel (2024).

# Usage

```
SDRepresentation(PopShares, BodyN, a = -0.5, b = 1, nMonte = 10000)
```

# **Arguments**

PopShares A numeric vector containing the group-level population proportions.

BodyN A positive integer denoting the size of the political body in question.

4 SDRepresentation

a, b

Parameters controlling the affine transformation for how the representation measure is summarized. That is, a and b control how the expected L1 deviation of the population shares from the body shares is re-weighted. The expected L1 deviation is the average value of the absolute deviation of the population from body shares under a random sampling model. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a\*E[L1]+b. By default, a=-0.5 and b=1 so that the expected Rose Index of Proportionality is used in the calculation.

nMonte

A positive integer denoting number of Monte Carlo iterations used to approximate the variance of representation under a random sampling model.

#### Value

A scalar summary of the amount of representation not explained by a random sampling model. More precisely, this function returns the the residual standard deviation when using the expected degree of representation to predict observed representation under a random sampling model.

#### References

• John Gerring, Connor T. Jerzak, Erzen Oncel. (2024), The Composition of Descriptive Representation, *American Political Science Review*, 118(2): 784-801. doi:10.1017/S0003055423000680

#### **Examples**

```
\label{eq:sdrep} \begin{split} \text{SDRep} &\leftarrow \text{SDRepresentation(PopShares} = c(1/3, \ 2/3, \ 1/3), \\ &\quad \text{BodyN} = 50) \\ \\ \text{print(SDRep)} \end{split}
```

# Index

 ${\it Expected Representation}, 1$ 

ObservedRepresentation, 2

 ${\tt SDRepresentation}, {\tt 3}$