Package 'DescriptiveRepresentationCalculator'

October 19, 2023

Title Descriptive Representation Calculator: Characterizing Observed

and Expected Representation

Version 1.0.0
Description Calculates descriptive representation measures for comparing the composition of a political body to the population it represents. Allows users to compute the expected degree of representation for a body under a random sampling model, the expected degree of representation variability, as well as representation scores from observed political bodies. Package based on Gerring, Jerzak, and Oncel (2023) <doi:10.1017 s0003055423000680="">.</doi:10.1017>
URL https://github.com/cjerzak/DescriptiveRepresentationCalculator-software/
BugReports https: //github.com/cjerzak/DescriptiveRepresentationCalculator-software/issues
Depends R (>= $3.3.3$)
License GPL-3
Encoding UTF-8
Imports stats
RoxygenNote 7.2.3
NeedsCompilation no
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ExpectedRepresentation

Compute the expected degree of representation for any group in a political body

Description

Finds the degree of expected representation for any group in a political body under a random sampling model as described in Gerring, Jerzak and Oncel (2023).

Usage

```
ExpectedRepresentation(PopShares, BodyN, a = -0.5, b = 1)
```

Arguments

PopShares A numeric vector containing the group-level population proportions.

BodyN A positive integer denoting the size of the political body in question.

a, b The a and b parameters control the affine transformation for how th

The a and b parameters control the affine transformation for how the representation measure is summarized. That is, a and b control how the expected L1 deviation of the population shares from the body shares is re-weighted. The expected L1 deviation is the average value of the absolute deviation of the population from body shares under a random sampling model. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a*E[L1]+b. By default, a=-0.5 and b=1 so that the expected Rose Index of Proportionality is

returned.

Value

The expected degree of representation (a scalar).

References

• John Gerring, Connor T. Jerzak, Erzen Oncel. (2023), The Composition of Descriptive Representation, *American Political Science Review*, p. 1-18. doi:10.1017/S0003055423000680

Examples

```
ExpectedRep <- ExpectedRepresentation(PopShares = c(1/3, 2/3, 1/3),

BodyN = 50)

print( ExpectedRep )
```

ObservedRepresentation

Compute the observed degree of representation for any group in a political body

Description

Finds the degree of observed representation for any group in a political body.

Usage

ObservedRepresentation(BodyMemberCharacteristics, PopShares, BodyShares, a = -0.5, b = 1)

Arguments

BodyMemberCharacteristics

A vector specifying the characteristics for members of a political body.

PopShares A numeric vector specifying population shares of identities specified in the

body-member characteristics input. The names of the entries in PopShares should correspond to identities in that body-member characteristics input (see

Example).

BodyShares (optional) A numeric vector with same structure as PopShares specifying group

population shares of a given body. If specified, used by default instead of

BodyMemberCharacteristics.

a, b Parameters controlling the affine transformation for how the representation mea-

sure is summarized. That is, a and b control how the L1 deviation of the population shares from the body shares is re-weighted. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a*L1+b. By default, a=-0.5

and b=1 so that the Rose Index of Proportionality is returned.

Value

The observed degree of representation (a scalar). By default, this quantity is the Rose Index of Proportionality.

Examples

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•	ompute the amount of representation left unexplained by a random mpling model.
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Description

Finds the residual standard deviation when using the expected representation for any group in a political body to predict observed representation as described in Gerring, Jerzak and Oncel, 2023.

Usage

```
SDRepresentation(PopShares, BodyN, a = -0.5, b = 1, nMonte = 10000)
```

Arguments

,	
PopShares	A numeric vector containing the group-level population proportions.
BodyN	A positive integer denoting the size of the political body in question.
a, b	Parameters controlling the affine transformation for how the representation measure is summarized. That is, a and b control how the expected L1 deviation of the population shares from the body shares is re-weighted. The expected L1 deviation is the average value of the absolute deviation of the population from body shares under a random sampling model. This expected L1 deviation is multiplied by a; b is as an additive re-scaling term: a*E[L1]+b. By default, a=-0.5 and b=1 so that the expected Rose Index of Proportionality is used in the calculation.
nMonte	A positive integer denoting number of Monte Carlo iterations used to approxi-

Value

A scalar summary of the amount of representation not explained by a random sampling model. More precisely, this function returns the the residual standard deviation when using the expected degree of representation to predict observed representation under a random sampling model.

mate the variance of representation under a random sampling model.

References

• John Gerring, Connor T. Jerzak, Erzen Oncel. (2023), The Composition of Descriptive Representation, *American Political Science Review*, p. 1-18. doi:10.1017/S0003055423000680

Examples

```
SDRep <- SDRepresentation(PopShares = c(1/3, 2/3, 1/3), BodyN = 50)

print( SDRep )
```

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