Package 'causalimages'

July 20, 2025

Title Causal Inference with Earth Observation, Bio-medical,
and Social Science Images

Version 0.1

Description Provides a system for performing causal inference with earth observation,
bio-medical, and social science images and image sequences (videos). The package
uses a 'JAX' backend for GPU/TPU acceleration. Key functionalities include building
conda-based backends (e.g., via 'BuildBackend'), implementing image-based confounder
and heterogeneity analyses (e.g., 'AnalyzeImageConfounding', 'AnalyzeImageHeterogeneity'),
and writing/reading large image corpora as '.tfrecord' files for use in training
(via 'WriteTfRecord' and 'GetElementFromTfRecordAtIndices'). This allows researchers
to scale causal inference to modern large-scale imagery data, bridging R with
hardware-accelerated Python libraries. The package is partly based on Jerzak
and Daoud (2023) <doi:10.48550/arXiv.2310.00233>.

URL https://github.com/cjerzak/causalimages-software

BugReports https://github.com/cjerzak/causalimages-software/issues

Depends R (>= 3.3.3)

License GPL-3

Encoding UTF-8

LazyData false

Imports tensorflow,
reticulate,
geosphere,
raster,
rrapply,
glmnet,
sf,
data.table,
pROC

Suggests knitr,
rmarkdown

VignetteBuilder knitr

RoxygenNote 7.3.2

Contents

AnalyzeImageConfounding

Perform causal estimation under image confounding

Description

Perform causal estimation under image confounding

Usage

```
AnalyzeImageConfounding(
  obsW,
  obsY,
  X = NULL,
  file = NULL,
  imageKeysOfUnits = NULL,
  fileTransport = NULL,
  imageKeysOfUnitsTransport = NULL,
  nBoot = 10L,
  inputAvePoolingSize = 1L,
  useTrainingPertubations = T,
  useScalePertubations = F,
  orthogonalize = F,
  transportabilityMat = NULL,
  latTransport = NULL,
  longTransport = NULL,
  lat = NULL,
  long = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  Sys.setenv_text = NULL,
  figuresTag = NULL,
```

```
        figuresPath = "./",
        plotBands = 1L,
        plotResults = T,
        XCrossModal = T,
        optimizeImageRep = T,
        nonLinearScaler = NULL,
        nWidth_ImageRep = 64L,
        nDepth_ImageRep = 1L,
        kernelSize = 5L,
        nWidth_Dense = 64L,
        nDepth_Dense = 1L,
        imageModelClass = "VisionTransformer",
        pretrainedModel = NULL,
        strides = 2L,
        nDepth_TemporalRep = 3L,
        patchEmbedDim = 16L,
        dropoutRate = 0.1,
        batchSize = 16L,
        nSGD = 400L,
        testFrac = 0.05,
        TfRecords_BufferScaler = 4L,
        learningRateMax = 0.001,
        TFRecordControl = NULL,
        dataType = "image",
        image_dtype = "float16",
        atError = "stop",
        seed = NULL
)
```

Arguments

`obsW`	A numeric vector where `0`'s correspond to control units and `1`'s to treated units.
`obsY`	A numeric vector containing observed outcomes.
`X`	An optional numeric matrix containing tabular information used if `orthogonalize = T`. `X` is normalized internally and salience maps with respect to `X` are transformed back to the original scale.
`file`	Path to a tfrecord file generated by `WriteTfRecord`.
`imageKeysOfUnits`	
	A vector of length `length(obsY)` specifying the unique image ID associated with each unit. Samples of `imageKeysOfUnits` are fed into the package to call images into memory.
`nBoot`	Number of bootstrap iterations for uncertainty estimation.
`useTrainingPertubations`	
	Boolean specifying whether to randomly perturb the image axes during training to reduce overfitting.
`transportabilityMat`	
	Optional matrix with a column named `imageKeysOfUnits` specifying keys to be used by the package for generating treatment effect predictions for out-of-sample points.
`long, lat`	Optional vectors specifying longitude and latitude coordinates for units. Used only for describing highest and lowest probability neighborhood units if specified.

conda_env	A conda environment where computational environment lives, usually created via causalimages::BuildBackend(). Default = "CausalImagesEnv".
conda_env_required	A Boolean stating whether use of the specified conda environment is required.
figuresTag	A string specifying an identifier that is appended to all figure names.
figuresPath	A string specifying file path for saved figures made in the analysis.
plotBands	An integer or vector specifying which band position (from the image representation) should be plotted in the visual results. If a vector, plotBands should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be used in RGB plotting).
plotResults	(default = T) Should analysis results be plotted?
optimizeImageRep	Boolean specifying whether to optimize over the image model representation (or only over downstream parameters).
nWidth_ImageRep	Integer specifying width of image model representation.
nDepth_ImageRep	Integer specifying depth of image model representation.
kernelSize	Dimensions used in spatial convolutions.
nWidth_Dense	Integer specifying width of image model representation.
nDepth_Dense	Integer specifying depth of dense model representation.
strides	(default = 2L) Integer specifying the strides used in the convolutional layers.
dropoutRate	Dropout rate used in training to prevent overfitting (dropoutRate = 0 corresponds to no dropout).
batchSize	Batch size used in SGD optimization. Default = 50L.
nSGD	Number of stochastic gradient descent (SGD) iterations. Default = 400L
testFrac	Default = 0.1. Fraction of observations held out as a test set to evaluate out-of-sample loss values.
TfRecords_BufferScaler	The buffer size used in tfrecords mode is batchSize*TfRecords_BufferScaler. Lower TfRecords_BufferScaler towards 1 if out-of-memory problems.
dataType	(default = "image") String specifying whether to assume "image" or "video" data types.

Value

Returns a list consisting of

- ATE_est ATE estimate.

- ATE_se Standard error estimate for the ATE.

- plotResults If set to TRUE, causal salience plots are saved to disk, characterizing the image confounding structure. See references for details.

References

- Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Integrating Earth Observation Data into Causal Inference: Challenges and Opportunities. *ArXiv Preprint*, 2023.

Examples

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

AnalyzeImageHeterogeneity

Decompose treatment effect heterogeneity by image or image sequence

---

Description

Implements the image heterogeneity decomposition analysis of Jerzak, Johansson, and Daoud (2023). Users input in treatment and outcome data, along with a function specifying how to load in images using keys referenced to each unit (since loading in all image data will usually not be possible due to memory limitations). This function by default performs estimation, constructs salience maps, and can optionally perform estimation for new areas outside the original study sites in a transportability analysis.

Usage

```
AnalyzeImageHeterogeneity(
  obsW,
  obsY,
  X = NULL,
  orthogonalize = F,
  imageKeysOfUnits = 1:length(obsY),
  kClust_est = 2,
  file = NULL,
  transportabilityMat = NULL,
  lat = NULL,
  long = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  figuresTag = "",
  figuresPath = "./",
  plotBands = 1L,
  heterogeneityModelType = "variational_minimal",
  plotResults = F,
  optimizeImageRep = T,
  nWidth_ImageRep = 64L,
  nDepth_ImageRep = 1L,
  nWidth_Dense = 64L,
  nDepth_Dense = 1L,
  nDepth_TemporalRep = 1L,
  useTrainingPertubations = T,
  strides = 2L,
  nonLinearScaler = NULL,
  pretrainedModel = NULL,
  testFrac = 0.1,
  kernelSize = 5L,
  learningRateMax = 0.001,
```

```
    TFRecordControl = NULL,
    patchEmbedDim = 16L,
    nSGD = 500L,
    batchSize = 16L,
    seed = NULL,
    Sys.setenv_text = NULL,
    imageModelClass = "VisionTransformer",
    nMonte_predictive = 10L,
    nMonte_salience = 10L,
    nMonte_variational = 2L,
    TfRecords_BufferScaler = 4L,
    temperature = 1,
    inputAvePoolingSize = 1L,
    dataType = "image"
)
```

Arguments

obsW	A numeric vector where 0's correspond to control units and 1's to treated units.
obsY	A numeric vector containing observed outcomes.
X	Optional numeric matrix containing tabular information used if `orthogonalize = T`.
orthogonalize	A Boolean specifying whether to perform the image decomposition after orthogonalizing with respect to tabular covariates specified in X.
imageKeysOfUnits	
	A vector of length `length(obsY)` specifying the unique image ID associated with each unit. Samples of `imageKeysOfUnits` are fed into the package to call images into memory.
kClust_est	Integer specifying the number of clusters used in estimation. Default is 2L.
file	Path to a tfrecord file generated by `WriteTfRecord`.
transportabilityMat	
	An optional matrix with a column named key specifying keys to be used for generating treatment effect predictions for out-of-sample points in earth observation data settings.
long, lat	Optional vectors specifying longitude and latitude coordinates for units. Used only for describing highest and lowest probability neighborhood units if specified.
conda_env	A conda environment where computational environment lives, usually created via `causalimages::BuildBackend()`. Default = "CausalImagesEnv".
conda_env_required	
	A Boolean stating whether use of the specified conda environment is required.
figuresTag	A string specifying an identifier that is appended to all figure names.
figuresPath	A string specifying file path for saved figures made in the analysis.
plotBands	An integer or vector specifying which band position (from the acquired image representation) should be plotted in the visual results. If a vector, `plotBands` should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be used in RGB plotting).
plotResults	Should analysis results be plotted?

optimizeImageRep

        Boolean specifying whether to optimize over the image model representation (or only over downstream parameters).

nWidth_ImageRep

        Integer specifying width of image model representation.

nDepth_ImageRep

        Integer specifying depth of image model representation.

nWidth_Dense   Integer specifying width of image model representation.

nDepth_Dense   Integer specifying depth of dense model representation.

strides   Integer specifying the strides used in the convolutional layers.

kernelSize   Dimensions used in spatial convolutions.

nSGD   Number of stochastic gradient descent (SGD) iterations.

batchSize   Batch size used in SGD optimization.

nMonte_predictive

        An integer specifying how many Monte Carlo iterations to use in the calculation of posterior means (e.g., mean cluster probabilities).

nMonte_salience

        An integer specifying how many Monte Carlo iterations to use in the calculation of the salience maps (e.g., image gradients of expected cluster probabilities).

nMonte_variational

        An integer specifying how many Monte Carlo iterations to use in the calculation of the expected likelihood in each training step.

TfRecords_BufferScaler

        The buffer size used in tfrecords mode is batchSize*TfRecords_BufferScaler. Lower TfRecords_BufferScaler towards 1 if out-of-memory problems.

dataType   String specifying whether to assume "image" or "video" data types.

Value

Returns a list consisting of

- clusterTaus_mean default
- clusterProbs_mean. Estimated mean image effect cluster probabilities.
- clusterTaus_sigma. Estimated cluster standard deviations.
- clusterProbs_lowerConf. Estimated lower confidence for effect cluster probabilities.
- impliedATE. Implied ATE.
- individualTau_est. Estimated individual-level image-based treatment effects.
- transportabilityMat. Transportability matrix with estimated cluster information.
- plottedCoordinates. List containing coordinates plotted in salience maps.
- whichNA_dropped. A vector containing observations dropped due to missingness.

References

- Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Image-based Treatment Effect Heterogeneity. Forthcoming in *Proceedings of the Second Conference on Causal Learning and Reasoning (CLeaR), Proceedings of Machine Learning Research (PMLR)*, 2023.

Examples

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

BuildBackend	*Build the environment for CausalImages models. Builds a conda environment in which jax, tensorflow, tensorflow-probability optax, equinox, and jmp are installed.*

Description

Build the environment for CausalImages models. Builds a conda environment in which jax, tensorflow, tensorflow-probability optax, equinox, and jmp are installed.

Usage

```
BuildBackend(conda_env = "CausalImagesEnv", conda = "auto")
```

Arguments

conda_env	(default = "CausalImagesEnv") Name of the conda environment in which to place the backends.
conda	(default = auto) The path to a conda executable. Using "auto" allows reticulate to attempt to automatically find an appropriate conda binary.

Value

Builds the computational environment for causalimages. This function requires an Internet connection. You may find out a list of conda Python paths via: system("which python")

Examples

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

GetAndSaveGeolocatedImages	
	Getting and saving geo-located images from a pool of .tif's

Description

A function that finds the image slice associated with the `long` and `lat` values, saves images by band (if `save_as = "csv"`) in save_folder.

Usage

```
GetAndSaveGeolocatedImages(
  long,
  lat,
  keys,
  tif_pool,
  image_pixel_width = 256L,
  save_folder = ".",
  save_as = "csv",
  lyrs = NULL
)
```

Arguments

`long`	Vector of numeric longitudes.
`lat`	Vector of numeric latitudes.
`keys`	The image keys associated with the long/lat coordinates.
`tif_pool`	A character vector specifying the fully qualified path to a corpus of .tif files.
`image_pixel_width`	
	An even integer specifying the pixel width (and height) of the saved images.
`save_folder`	(default = `"."`) What folder should be used to save the output? Example: `"~/Downloads"`
`save_as`	(default = `".csv"`) What format should the output be saved as? Only one option currently (`.csv`)
`lyrs`	(default = NULL) Integer (vector) specifying the layers to be extracted. Default is for all layers to be extracted.

Value

Finds the image slice associated with the `long` and `lat` values, saves images by band (if `save_as` = `"csv"`) in save_folder. The save format is: `sprintf("%s/Key%s_BAND%s.csv", save_folder, keys[i], band_)`

Examples

```
# Example use (not run):
#MASTER_IMAGE_POOL_FULL_DIR <- c("./LargeTifs/tif1.tif","./LargeTifs/tif2.tif")
#GetAndSaveGeolocatedImages(
                    #long = GeoKeyMat$geo_long,
                    #lat = GeoKeyMat$geo_lat,
                    #image_pixel_width = 500L,
                    #keys = row.names(GeoKeyMat),
                    #tif_pool = MASTER_IMAGE_POOL_FULL_DIR,
                    #save_folder = "./Data/Uganda2000_processed",
                    #save_as = "csv",
                    #lyrs = NULL)
```

```
GetElementFromTfRecordAtIndices
```
Reads unique key indices from a `.tfrecord` *file.*

Description

Reads unique key indices from a `.tfrecord` file saved via a call to `causalimages::WriteTfRecord`.

Usage

```
GetElementFromTfRecordAtIndices(uniqueKeyIndices, file,
    conda_env, conda_env_required)
```

Arguments

uniqueKeyIndices

(integer vector) Unique image indices to be retrieved from a `.tfrecord`

conda_env   (Default = NULL) A conda environment where tensorflow v2 lives. Used only if a version of tensorflow is not already active.

conda_env_required

(default = F) A Boolean stating whether use of the specified conda environment is required.

file   (character string) A character string stating the path to a `.tfrecord`

Value

Returns content from a `.tfrecord` associated with `uniqueKeyIndices`

Examples

```
# Example usage (not run):
#GetElementFromTfRecordAtIndices(
  #uniqueKeyIndices = 1:10,
  #file = "./NigeriaConfoundApp.tfrecord")
```

```
GetImageRepresentations
```
Generates image and video representations useful in earth observation tasks for casual inference.

Description

Generates image and video representations useful in earth observation tasks for casual inference.

Usage

```
GetImageRepresentations(
  X = NULL,
  imageKeysOfUnits = NULL,
  file = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  returnContents = T,
  getRepresentations = T,
  imageModelClass = "VisionTransformer",
  NORM_MEAN = NULL,
  NORM_SD = NULL,
  Sys.setenv_text = NULL,
  InitImageProcess = NULL,
  pretrainedModel = NULL,
  lat = NULL,
  long = NULL,
  image_dtype = NULL,
  image_dtype_tf = NULL,
  XCrossModal = T,
  nWidth_ImageRep = 64L,
  nDepth_ImageRep = 1L,
  nDepth_TemporalRep = 1L,
  batchSize = 16L,
  nonLinearScaler = NULL,
  optimizeImageRep = T,
  strides = 1L,
  kernelSize = 3L,
  patchEmbedDim = 16L,
  TfRecords_BufferScaler = 10L,
  dropoutRate,
  dataType = "image",
  bn_momentum = 0.99,
  inputAvePoolingSize = 1L,
  CleanupEnv = FALSE,
  initializingFxns = FALSE,
  seed = NULL
)
```

Arguments

imageKeysOfUnits

> A vector of length `length(imageKeysOfUnits)` specifying the unique image ID associated with each unit. Samples of `imageKeysOfUnits` are fed into the package to call images into memory.

file Path to a tfrecord file generated by `causalimages::WriteTfRecord`.

conda_env A conda environment where computational environment lives, usually created via `causalimages::BuildBackend()`. Default = `"CausalImagesEnv"`

conda_env_required

> A Boolean stating whether use of the specified conda environment is required.

InitImageProcess

> (default = `NULL`) Initial image processing function. Usually left `NULL`.

nWidth_ImageRep	
	Number of embedding features output.
batchSize	Integer specifying batch size in obtaining representations.
strides	Integer specifying the strides used in the convolutional layers.
kernelSize	Dimensions used in the convolution kernels.
TfRecords_BufferScaler	
	The buffer size used in `tfrecords` mode is `batchSize*TfRecords_BufferScaler`. Lower `TfRecords_BufferScaler` towards 1 if out-of-memory problems.
dataType	String specifying whether to assume `"image"` or `"video"` data types. Default is `"image"`.

Value

A list containing two items:

- `Representations` (matrix) A matrix containing image/video representations, with rows corresponding to observations.
- `ImageRepArm_OneObs`, `ImageRepArm_batch_R`, `ImageRepArm_batch` (functions) Image modeling functions.
- `ImageModel_And_State_And_MPPolicy_List` List containing image model parameters fed into functions.

References

- Rolf, Esther, et al. "A generalizable and accessible approach to machine learning with global satellite imagery." *Nature Communications* 12.1 (2021): 4392.

Examples

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

GetMoments   *Get moments for normalization (internal function)*

Description

An internal function function for obtaining moments for channel normalization.

Usage

```
GetMoments(iterator, dataType, image_dtype, momentCalIters = 34L)
```

Arguments

iterator	An iterator
dataType	A string denoting data type
momentCalIters	Number of minibatches with which to estimate moments

Value

Returns mean/sd arrays for normalization.

Examples

```
# (Not run)
# GetMoments(iterator, dataType, image_dtype, momentCalIters = 34L)
```

---

image2   *Visualizing matrices as heatmaps with correct north-south-east-west*
                               orientation

Description

A function for generating a heatmap representation of a matrix with correct spatial orientation.

Usage

```
image2(
  x,
  xaxt = NULL,
  yaxt = NULL,
  xlab = "",
  ylab = "",
  main = NULL,
  cex.main = NULL,
  col.lab = "black",
  col.main = "black",
  cex.lab = 1.5,
  box = F
)
```

Arguments

x	The numeric matrix to be visualized.
xaxt	The x-axis tick labels.
yaxt	The y-axis tick labels.
xlab	The x-axis labels.
ylab	The y-axis labels.
main	The main figure label.
cex.main	The main figure label sizing factor.
col.lab	Axis label color.
col.main	Main label color.
cex.lab	Cex for the labels.
box	Draw a box around the image?

Value

Returns a heatmap representation of the matrix, x, with correct north/south/east/west orientation.

Examples

```
#set seed
set.seed(1)

#Geneate data
x <- matrix(rnorm(50*50), ncol = 50)
diag(x) <- 3

# create plot
image2(x, main = "Example Text", cex.main = 2)
```

LongLat2CRS   *Get the spatial point of long/lat coordinates*

Description

Convert longitude and latitude coordinates to a different coordinate reference system (CRS).

Usage

```
LongLat2CRS(long, lat, CRS_ref)
```

Arguments

long   Vector of numeric longitudes.

lat   Vector of numeric latitudes.

CRS_ref   A CRS into which the long-lat point should be projected.

Value

Numeric vector of length two giving the coordinates of the supplied location in the CRS defined by
CRS_ref.

Examples

```
# (Not run)
#spatialPt <- LongLat2CRS(long = 49.932,
#                 lat = 35.432,
#           CRS_ref = sf::st_crs("+proj=lcc +lat_1=48 +lat_2=33 +lon_0=-100 +ellps=WGS84"))
```

---

message2   *message2 message() with timestamps*

Description

A function that displays a message with date and time.

Usage

```
message2(text, quiet = FALSE)
```

Arguments

text   Character string to be displayed as message, with date and time.

quiet   Logical. If TRUE, suppresses the message output. Default is FALSE.

Value

Displays message with date and time to stderr.

Examples

```
message2("Hello world")
message2("Process completed", quiet = FALSE)
```

PredictiveRun   *Perform predictive modeling using images or videos*

Description

Perform predictive modeling using images or videos

Usage

```
PredictiveRun(
  obsY,
  imageKeysOfUnits = NULL,
  file = NULL,
  fileTransport = NULL,
  imageKeysOfUnitsTransport = NULL,
  nBoot = 10L,
  inputAvePoolingSize = 1L,
  useTrainingPertubations = T,
  useScalePertubations = F,
  X = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  Sys.setenv_text = NULL,
  figuresTag = NULL,
  figuresPath = "./",
```

```
    plotBands = 1L,
    plotResults = T,
    XCrossModal = T,
    optimizeImageRep = T,
    nWidth_ImageRep = 64L,
    nDepth_ImageRep = 1L,
    kernelSize = 5L,
    nWidth_Dense = 64L,
    nDepth_Dense = 1L,
    imageModelClass = "VisionTransformer",
    pretrainedModel = NULL,
    strides = 2L,
    nonLinearScaler = NULL,
    nDepth_TemporalRep = 3L,
    patchEmbedDim = 16L,
    dropoutRate = 0.1,
    batchSize = 16L,
    nSGD = 400L,
    testFrac = 0.05,
    TfRecords_BufferScaler = 4L,
    learningRateMax = 0.001,
    TFRecordControl = NULL,
    dataType = "image",
    image_dtype = "float16",
    atError = "stop",
    seed = NULL,
    modelPath = "./trained_model.eqx",
    metricsPath = "./evaluation_metrics.rds"
)
```

Arguments

`obsY`	A numeric vector containing observed outcomes to predict.
`imageKeysOfUnits`	
	A vector of length `length(obsY)` specifying the unique image ID associated with each unit. Samples of `imageKeysOfUnits` are fed into the package to call images into memory.
`file`	Path to a tfrecord file generated by `WriteTfRecord`.
`nBoot`	Number of bootstrap iterations for uncertainty estimation.
`useTrainingPertubations`	
	Boolean specifying whether to randomly perturb the image axes during training to reduce overfitting.
`X`	An optional numeric matrix containing tabular information. `X` is normalized internally.
`conda_env`	A conda environment where computational environment lives, usually created via `causalimages::BuildBackend()`. Default = `"CausalImagesEnv"`.
`conda_env_required`	
	A Boolean stating whether use of the specified conda environment is required.
`figuresTag`	A string specifying an identifier that is appended to all figure names.
`figuresPath`	A string specifying file path for saved figures made in the analysis.

plotBands	An integer or vector specifying which band position (from the image representation) should be plotted in the visual results. If a vector, plotBands should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be used in RGB plotting).
plotResults	(default = T) Should analysis results be plotted?
optimizeImageRep	Boolean specifying whether to optimize over the image model representation (or only over downstream parameters).
nWidth_ImageRep	Integer specifying width of image model representation.
nDepth_ImageRep	Integer specifying depth of image model representation.
kernelSize	Dimensions used in spatial convolutions.
nWidth_Dense	Integer specifying width of image model representation.
nDepth_Dense	Integer specifying depth of dense model representation.
strides	(default = 2L) Integer specifying the strides used in the convolutional layers.
dropoutRate	Dropout rate used in training to prevent overfitting (dropoutRate = 0 corresponds to no dropout).
batchSize	Batch size used in SGD optimization. Default = 50L.
nSGD	Number of stochastic gradient descent (SGD) iterations. Default = 400L
testFrac	Default = 0.1. Fraction of observations held out as a test set to evaluate out-of-sample loss values.
TfRecords_BufferScaler	The buffer size used in tfrecords mode is batchSize*TfRecords_BufferScaler. Lower TfRecords_BufferScaler towards 1 if out-of-memory problems.
dataType	(default = "image") String specifying whether to assume "image" or "video" data types.
modelPath	Path to save the trained model. Default = "./trained_model.eqx".
metricsPath	Path to save the evaluation metrics as a RDS file. Default = "./evaluation_metrics.rds".
transportabilityMat	Optional matrix with a column named imageKeysOfUnits specifying keys to be used by the package for generating predictions for out-of-sample points.

Value

Returns a list consisting of

- predictedY Predicted values for all units.
- ModelEvaluationMetrics Rigorous evaluation metrics (e.g., MSE, R2 for continuous; AUC, accuracy for binary).

References

- Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Integrating Earth Observation Data into Causal Inference: Challenges and Opportunities. *ArXiv Preprint*, 2023.

Examples

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

---

print2   *print2 print() with timestamps*

Description

A function prints a string with date and time.

Usage

```
print2(text, quiet = F)
```

Arguments

x   Character string to be printed, with date and time.

Value

Prints with date and time.

Examples

```
message("Hello world")
```

TrainDefine   *Defines an internal training routine (internal function)*

Description

Defines trainers defined in TrainDefine(). Internal function.

Usage

```
TrainDefine()
```

Arguments

.   No parameters.

Value

Internal function defining a training sequence.

TrainDo   *Runs a training routine (internal function)*

Description

Runs trainers defined in TrainDefine(). Internal function.

Usage

```
TrainDo()
```

Arguments

.   No parameters.

Value

Internal function performing model training.

WriteTfRecord   *Write an image corpus as a .tfrecord file*

Description

Writes an image corpus to a `.tfrecord` file for rapid reading of images into memory for fast ML training. Specifically, this function serializes an image or video corpus into a `.tfrecord` file, enabling efficient data loading for machine learning tasks, particularly for image-based causal inference training. It requires that users define an `acquireImageFxn` function that accepts keys and returns the corresponding image or video as an array of dimensions (length(keys), nSpatialDim1, nSpatialDim2, nC for images or (length(keys), nTimeSteps, nSpatialDim1, nSpatialDim2, nChannels) for video sequences.

Usage

```
WriteTfRecord(
  file,
  uniqueImageKeys,
  acquireImageFxn,
  writeVideo = F,
  image_dtype = "float16",
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  Sys.setenv_text = NULL
)
```

Arguments

`file`	A character string naming a file for writing.
`uniqueImageKeys`	
	A vector specifying the unique image keys of the corpus. A key grabs an image/video array via `acquireImageFxn(key)`.
`acquireImageFxn`	
	A function whose input is an observation keys and whose output is an array with dimensions `(length(keys), nSpatialDim1, nSpatialDim2, nChannels)` for images and `(length(keys), nTimeSteps, nSpatialDim1, nSpatialDim2, nChannels)` for image sequence data.
`writeVideo`	(default = `FALSE`) Should we assume we're writing image sequence data of form batch by time by height by width by channels?
`conda_env`	(default = `"CausalImagesEnv"`) A conda environment where computational environment lives, usually created via `causalimages::BuildBackend()`
`conda_env_required`	
	(default = `T`) A Boolean stating whether use of the specified conda environment is required.

Value

Writes a unique key-referenced `.tfrecord` from an image/video corpus for use in image-based causal inference training.

Examples

```
# Example usage (not run):
#WriteTfRecord(
#  file = "./NigeriaConfoundApp.tfrecord",
#  uniqueImageKeys = 1:n,
#  acquireImageFxn = acquireImageFxn)
```

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