# Package 'causalimages'

August 17, 2025

**Title** Causal Inference with Earth Observation, Bio-medical, and Social Science Images

Version 0.1

Description Provides a system for performing causal inference with earth observation, bio-medical, and social science images and image sequences (videos). The package uses a 'JAX' backend for GPU/TPU acceleration. Key functionalities include building conda-based backends (e.g., via 'BuildBackend'), implementing image-based confounder and heterogeneity analyses (e.g., 'AnalyzeImageConfounding', 'AnalyzeImageHeterogeneity'), and writing/reading large image corpora as '.tfrecord' files for use in training (via 'WriteTfRecord' and 'GetElementFromTfRecordAtIndices'). This allows researchers to scale causal inference to modern large-scale imagery data, bridging R with hardware-accelerated Python libraries. The package is partly based on Jerzak and Daoud (2023) <doi:10.48550/arXiv.2310.00233>.

URL https://github.com/cjerzak/causalimages-software

```
BugReports https://github.com/cjerzak/causalimages-software/issues
Depends R (>= 3.3.3)
License GPL-3
Encoding UTF-8
LazyData false
Imports tensorflow,
     reticulate,
     geosphere,
     raster,
     rrapply,
     glmnet,
     sf,
     data.table,
     pROC
Suggests knitr,
     rmarkdown
VignetteBuilder knitr
RoxygenNote 7.3.2
```

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AnalyzeImageConfounding

Perform causal estimation under image confounding

# Description

Perform causal estimation under image confounding

```
AnalyzeImageConfounding(
  obsW,
  obsY,
  X = NULL
  file = NULL,
  imageKeysOfUnits = NULL,
  fileTransport = NULL,
  imageKeysOfUnitsTransport = NULL,
  nBoot = 10L,
  inputAvePoolingSize = 1L,
  useTrainingPertubations = T,
  useScalePertubations = F,
  crossFit = FALSE,
  augmented = FALSE,
  orthogonalize = F,
  transportabilityMat = NULL,
  latTransport = NULL,
  longTransport = NULL,
  lat = NULL,
  long = NULL,
  conda_env = "CausalImagesEnv",
```

```
conda_env_required = T,
  Sys.setenv_text = NULL,
  figuresTag = NULL,
  figuresPath = "./",
 plotBands = 1L,
 plotResults = T,
 XCrossModal = T,
 XForceModal = F,
  optimizeImageRep = T,
 nonLinearScaler = NULL,
 nWidth_ImageRep = 64L,
 nDepth_ImageRep = 1L,
 kernelSize = 5L,
 nWidth_Dense = 64L,
 nDepth_Dense = 1L,
  imageModelClass = "VisionTransformer",
  pretrainedModel = NULL,
  strides = 2L,
 nDepth_TemporalRep = 3L,
 patchEmbedDim = 16L,
 dropoutRate = 0.1,
 droppathRate = 0.1,
 batchSize = 16L,
 nSGD = 400L
  testFrac = 0.05,
 TfRecords_BufferScaler = 4L,
 learningRateMax = 0.001,
  TFRecordControl = NULL,
 dataType = "image",
  image_dtype = "float16",
 atError = "stop",
  seed = NULL
)
```

## **Arguments**

obsW A numeric vector where 0's correspond to control units and 1's to treated units.

obsY A numeric vector containing observed outcomes.

X An optional numeric matrix containing tabular information used if orthogonalize = T. X is normalized internally and salience maps with respect to X are trans-

formed back to the original scale.

file Path to a tfrecord file generated by WriteTfRecord.

imageKeysOfUnits

A vector of length length(obsY) specifying the unique image ID associated with each unit. Samples of imageKeysOfUnits are fed into the package to call images into memory.

nBoot Number of bootstrap iterations for uncertainty estimation.

useTrainingPertubations

Boolean specifying whether to randomly perturb the image axes during training to reduce overfitting.

transportabilityMat

Optional matrix with a column named imageKeysOfUnits specifying keys to be used by the package for generating treatment effect predictions for out-of-

sample points.

long, lat Optional vectors specifying longitude and latitude coordinates for units. Used

only for describing highest and lowest probability neighborhood units if speci-

fied.

A conda environment where computational environment lives, usually created conda\_env

via causalimages::BuildBackend(). Default = "CausalImagesEnv".

conda\_env\_required

A Boolean stating whether use of the specified conda environment is required.

figuresTag A string specifying an identifier that is appended to all figure names.

figuresPath A string specifying file path for saved figures made in the analysis.

plotBands An integer or vector specifying which band position (from the image represen-

> tation) should be plotted in the visual results. If a vector, plotBands should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be used

in RGB plotting).

plotResults (default = T) Should analysis results be plotted?

optimizeImageRep

Boolean specifying whether to optimize over the image model representation

(or only over downstream parameters).

nWidth\_ImageRep

Integer specifying width of image model representation.

nDepth\_ImageRep

Integer specifying depth of image model representation.

kernelSize Dimensions used in spatial convolutions.

nWidth\_Dense Integer specifying width of image model representation.

Integer specifying depth of dense model representation. nDepth\_Dense

strides (default = 2L) Integer specifying the strides used in the convolutional layers.

dropoutRate Dropout rate used in training to prevent overfitting (dropoutRate = 0 corre-

sponds to no dropout).

Droppath rate used in training to prevent overfitting (droppathRate = 0 corredroppathRate

sponds to no droppath).

Batch size used in SGD optimization. Default = 50L. batchSize

nSGD Number of stochastic gradient descent (SGD) iterations. Default = 400L

testFrac Default = 0.1. Fraction of observations held out as a test set to evaluate out-of-

sample loss values.

TfRecords\_BufferScaler

The buffer size used in tfrecords mode is batchSize\*TfRecords\_BufferScaler.

Lower TfRecords\_BufferScaler towards 1 if out-of-memory problems.

(default = "image") String specifying whether to assume "image" or "video" dataType

data types.

#### Value

Returns a list consisting of

- ATE\_est ATE estimate.
- ATE se Standard error estimate for the ATE.
- plotResults If set to TRUE, causal salience plots are saved to disk, characterizing the image confounding structure. See references for details.

# References

• Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Integrating Earth Observation Data into Causal Inference: Challenges and Opportunities. *ArXiv Preprint*, 2023.

#### **Examples**

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

AnalyzeImageHeterogeneity

Decompose treatment effect heterogeneity by image or image sequence

## **Description**

Implements the image heterogeneity decomposition analysis of Jerzak, Johansson, and Daoud (2023). Users input in treatment and outcome data, along with a function specifying how to load in images using keys referenced to each unit (since loading in all image data will usually not be possible due to memory limitations). This function by default performs estimation, constructs salience maps, and can optionally perform estimation for new areas outside the original study sites in a transportability analysis.

```
AnalyzeImageHeterogeneity(
  obsW,
  obsY,
  X = NULL,
  orthogonalize = F,
  imageKeysOfUnits = 1:length(obsY),
  kClust_est = 2,
  file = NULL,
  transportabilityMat = NULL,
  lat = NULL,
  long = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  figuresTag = "",
  figuresPath = "./",
  plotBands = 1L,
  heterogeneityModelType = "variational_minimal",
```

```
plotResults = F,
 optimizeImageRep = T,
 nWidth_ImageRep = 64L,
 nDepth_ImageRep = 1L,
 nWidth_Dense = 64L,
 nDepth_Dense = 1L,
 nDepth_TemporalRep = 1L,
  useTrainingPertubations = T,
  strides = 2L,
 nonLinearScaler = NULL,
 pretrainedModel = NULL,
  testFrac = 0.1,
  kernelSize = 5L,
  learningRateMax = 0.001,
  TFRecordControl = NULL,
  patchEmbedDim = 16L
 nSGD = 500L
 batchSize = 16L,
  seed = NULL,
  Sys.setenv_text = NULL,
  imageModelClass = "VisionTransformer",
  nMonte_predictive = 10L,
 nMonte_salience = 10L,
  nMonte_variational = 2L,
  TfRecords_BufferScaler = 4L,
  temperature = 1,
  inputAvePoolingSize = 1L,
  dataType = "image"
)
```

#### **Arguments**

obsW A numeric vector where 0's correspond to control units and 1's to treated units.

obsY A numeric vector containing observed outcomes.

X Optional numeric matrix containing tabular information used if orthogonalize

= T

orthogonalize A Boolean specifying whether to perform the image decomposition after orthog-

onalizing with respect to tabular covariates specified in X.

imageKeysOfUnits

A vector of length length(obsY) specifying the unique image ID associated with each unit. Samples of imageKeysOfUnits are fed into the package to call images into memory.

images into memory.

kClust\_est Integer specifying the number of clusters used in estimation. Default is 2L.

file Path to a tfrecord file generated by WriteTfRecord.

 $transportability {\tt Mat}$ 

An optional matrix with a column named key specifying keys to be used for generating treatment effect predictions for out-of-sample points in earth observation data settings.

long, lat

Optional vectors specifying longitude and latitude coordinates for units. Used only for describing highest and lowest probability neighborhood units if specified.

conda\_env A conda environment where computational environment lives, usually created

via causalimages::BuildBackend(). Default = "CausalImagesEnv".

conda\_env\_required

A Boolean stating whether use of the specified conda environment is required.

figuresTag A string specifying an identifier that is appended to all figure names.

figuresPath A string specifying file path for saved figures made in the analysis.

plotBands An integer or vector specifying which band position (from the acquired image

representation) should be plotted in the visual results. If a vector, plotBands should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be

used in RGB plotting).

plotResults Should analysis results be plotted?

optimize Image Rep

Boolean specifying whether to optimize over the image model representation

(or only over downstream parameters).

nWidth\_ImageRep

Integer specifying width of image model representation.

nDepth\_ImageRep

Integer specifying depth of image model representation.

nWidth\_Dense Integer specifying width of image model representation.

nDepth\_Dense Integer specifying depth of dense model representation.

strides Integer specifying the strides used in the convolutional layers.

kernelSize Dimensions used in spatial convolutions.

nSGD Number of stochastic gradient descent (SGD) iterations.

batchSize Batch size used in SGD optimization.

nMonte\_predictive

An integer specifying how many Monte Carlo iterations to use in the calculation

of posterior means (e.g., mean cluster probabilities).

nMonte\_salience

An integer specifying how many Monte Carlo iterations to use in the calculation of the salience maps (e.g., image gradients of expected cluster probabilities).

nMonte\_variational

An integer specifying how many Monte Carlo iterations to use in the calculation of the expected likelihood in each training step.

TfRecords\_BufferScaler

The buffer size used in tfrecords mode is batchSize\*TfRecords\_BufferScaler.

Lower TfRecords\_BufferScaler towards 1 if out-of-memory problems.

dataType String specifying whether to assume "image" or "video" data types.

# Value

Returns a list consisting of

- clusterTaus\_mean default
- clusterProbs\_mean. Estimated mean image effect cluster probabilities.
- clusterTaus\_sigma. Estimated cluster standard deviations.
- clusterProbs\_lowerConf. Estimated lower confidence for effect cluster probabilities.
- impliedATE. Implied ATE.

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- individualTau\_est. Estimated individual-level image-based treatment effects.
- transportabilityMat. Transportability matrix with estimated cluster information.
- plottedCoordinates. List containing coordinates plotted in salience maps.
- whichNA\_dropped. A vector containing observations dropped due to missingness.

#### References

Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Image-based Treatment Effect Heterogeneity. Forthcoming in *Proceedings of the Second Conference on Causal Learning and Reasoning (CLeaR)*, *Proceedings of Machine Learning Research (PMLR)*, 2023.

## **Examples**

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

BuildBackend Build the environment for CausalImages models. Builds a conda

environment in which jax, tensorflow, tensorflow-probability optax, equinox, and jmp are installed.

**Description** 

Build the environment for CausalImages models. Builds a conda environment in which jax, tensorflow, tensorflow-probability optax, equinox, and jmp are installed.

#### Usage

```
BuildBackend(conda_env = "CausalImagesEnv", conda = "auto")
```

## **Arguments**

conda\_env (default = "CausalImagesEnv") Name of the conda environment in which to

place the backends.

conda (default = auto) The path to a conda executable. Using "auto" allows reticulate

to attempt to automatically find an appropriate conda binary.

### Value

Builds the computational environment for causalimages. This function requires an Internet connection. You may find out a list of conda Python paths via: system("which python")

#### **Examples**

```
# For a tutorial, see
```

# github.com/cjerzak/causalimages-software/

GetAndSaveGeolocatedImages

Getting and saving geo-located images from a pool of .tif's

## **Description**

A function that finds the image slice associated with the long and lat values, saves images by band (if save\_as = "csv") in save\_folder.

#### Usage

```
GetAndSaveGeolocatedImages(
  long,
  lat,
  keys,
  tif_pool,
  image_pixel_width = 256L,
  save_folder = ".",
  save_as = "csv",
  lyrs = NULL
)
```

#### **Arguments**

long Vector of numeric longitudes.lat Vector of numeric latitudes.

keys The image keys associated with the long/lat coordinates.

tif\_pool A character vector specifying the fully qualified path to a corpus of .tif files.

image\_pixel\_width

An even integer specifying the pixel width (and height) of the saved images.

save\_folder (default = ".") What folder should be used to save the output? Example: "~/Downloads"

save\_as (default = ".csv") What format should the output be saved as? Only one option

currently (.csv)

lyrs (default = NULL) Integer (vector) specifying the layers to be extracted. Default

is for all layers to be extracted.

### Value

Finds the image slice associated with the long and lat values, saves images by band (if save\_as = "csv") in save\_folder. The save format is: sprintf("%s/Key%s\_BAND%s.csv", save\_folder, keys[i], band\_)

## **Examples**

```
#keys = row.names(GeoKeyMat),
#tif_pool = MASTER_IMAGE_POOL_FULL_DIR,
#save_folder = "./Data/Uganda2000_processed",
#save_as = "csv",
#lyrs = NULL)
```

 ${\tt GetElementFromTfRecordAtIndices}$ 

 $\it Reads \ unique \ key \ indices \ from \ a$  . tfrecord  $\it file.$ 

## **Description**

Reads unique key indices from a .tfrecord file saved via a call to causalimages::WriteTfRecord.

## Usage

#### **Arguments**

uniqueKeyIndices

(integer vector) Unique image indices to be retrieved from a .tfrecord

conda\_env

(Default = NULL) A conda environment where tensorflow v2 lives. Used only if

a version of tensorflow is not already active.

conda\_env\_required

(default = F) A Boolean stating whether use of the specified conda environment

is required.

file

(character string) A character string stating the path to a .tfrecord

## Value

Returns content from a .tfrecord associated with uniqueKeyIndices  $\,$ 

## **Examples**

```
# Example usage (not run):
#GetElementFromTfRecordAtIndices(
    #uniqueKeyIndices = 1:10,
    #file = "./NigeriaConfoundApp.tfrecord")
```

 ${\tt GetImageRepresentations}$ 

Generates image and video representations useful in earth observation tasks for casual inference.

## **Description**

Generates image and video representations useful in earth observation tasks for casual inference.

```
GetImageRepresentations(
  X = NULL
  imageKeysOfUnits = NULL,
  file = NULL,
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  returnContents = T,
  getRepresentations = T,
  imageModelClass = "VisionTransformer",
  NORM\_MEAN = NULL,
  NORM_SD = NULL
  Sys.setenv_text = NULL,
  InitImageProcess = NULL,
  pretrainedModel = NULL,
  lat = NULL,
  long = NULL,
  image_dtype = NULL,
  image_dtype_tf = NULL,
  XCrossModal = T,
  XForceModal = F,
  nWidth_ImageRep = 64L,
  nDepth_ImageRep = 1L,
  nDepth_TemporalRep = 1L,
  batchSize = 16L,
  nonLinearScaler = NULL,
  optimizeImageRep = T,
  strides = 1L,
  kernelSize = 3L,
  patchEmbedDim = 16L,
  TfRecords_BufferScaler = 10L,
  dropoutRate,
  droppathRate,
  dataType = "image",
  bn_momentum = 0.99,
  inputAvePoolingSize = 1L,
  CleanupEnv = FALSE,
  initializingFxns = FALSE,
  seed = NULL
)
```

## **Arguments**

imageKeysOfUnits

A vector of length length(imageKeysOfUnits) specifying the unique image ID associated with each unit. Samples of imageKeysOfUnits are fed into the package to call images into memory.

file Path to a tfrecord file generated by causalimages::WriteTfRecord.

conda\_env A conda environment where computational environment lives, usually created

via causalimages::BuildBackend(). Default = "CausalImagesEnv"

conda\_env\_required

A Boolean stating whether use of the specified conda environment is required.

InitImageProcess

(default = NULL) Initial image processing function. Usually left NULL.

nWidth\_ImageRep

Number of embedding features output.

batchSize Integer specifying batch size in obtaining representations.

strides Integer specifying the strides used in the convolutional layers.

kernelSize Dimensions used in the convolution kernels.

TfRecords\_BufferScaler

The buffer size used in tfrecords mode is batchSize\*TfRecords\_BufferScaler.

Lower TfRecords\_BufferScaler towards 1 if out-of-memory problems.

dataType String specifying whether to assume "image" or "video" data types. Default is

"image".

#### Value

A list containing two items:

- Representations (matrix) A matrix containing image/video representations, with rows corresponding to observations.
- ImageRepArm\_OneObs,ImageRepArm\_batch\_R, ImageRepArm\_batch (functions) Image modeling functions.
- ImageModel\_And\_State\_And\_MPPolicy\_List List containing image model parameters fed into functions.

#### References

• Rolf, Esther, et al. "A generalizable and accessible approach to machine learning with global satellite imagery." *Nature Communications* 12.1 (2021): 4392.

#### **Examples**

```
# For a tutorial, see
```

# github.com/cjerzak/causalimages-software/

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GetMoments

Get moments for normalization (internal function)

## **Description**

An internal function function for obtaining moments for channel normalization.

## Usage

```
GetMoments(iterator, dataType, image_dtype, momentCalIters = 34L)
```

#### **Arguments**

```
iterator An iterator

dataType A string denoting data type

momentCalIters Number of minibatches with which to estimate moments
```

#### Value

Returns mean/sd arrays for normalization.

# **Examples**

```
# (Not run)
# GetMoments(iterator, dataType, image_dtype, momentCalIters = 34L)
```

image2

Visualizing matrices as heatmaps with correct north-south-east-west orientation

# Description

A function for generating a heatmap representation of a matrix with correct spatial orientation.

```
image2(
   x,
   xaxt = NULL,
   yaxt = NULL,
   xlab = "",
   ylab = "",
   main = NULL,
   cex.main = NULL,
   col.lab = "black",
   col.main = "black",
   cex.lab = 1.5,
   box = F
)
```

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## **Arguments**

Х	The numeric matrix to be visualized.
xaxt	The x-axis tick labels.
yaxt	The y-axis tick labels.
xlab	The x-axis labels.
ylab	The y-axis labels.
main	The main figure label.
cex.main	The main figure label sizing factor.
col.lab	Axis label color.
col.main	Main label color.
cex.lab	Cex for the labels.
box	Draw a box around the image?

## Value

Returns a heatmap representation of the matrix, x, with correct north/south/east/west orientation.

# **Examples**

```
#set seed
set.seed(1)

#Geneate data
x <- matrix(rnorm(50*50), ncol = 50)
diag(x) <- 3

# create plot
image2(x, main = "Example Text", cex.main = 2)</pre>
```

LongLat2CRS

Get the spatial point of long/lat coordinates

# Description

Convert longitude and latitude coordinates to a different coordinate reference system (CRS).

# Usage

```
LongLat2CRS(long, lat, CRS_ref)
```

# **Arguments**

long	Vector of numeric longitudes.
lat	Vector of numeric latitudes.

CRS\_ref A CRS into which the long-lat point should be projected.

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#### Value

Numeric vector of length two giving the coordinates of the supplied location in the CRS defined by CRS\_ref.

# **Examples**

```
# (Not run)
#spatialPt <- LongLat2CRS(long = 49.932,
# lat = 35.432,
# CRS_ref = sf::st_crs("+proj=lcc +lat_1=48 +lat_2=33 +lon_0=-100 +ellps=WGS84"))</pre>
```

message2

message2 message() with timestamps

## **Description**

A function that displays a message with date and time.

# Usage

```
message2(text, quiet = FALSE)
```

# **Arguments**

text Character string to be displayed as message, with date and time.

quiet Logical. If TRUE, suppresses the message output. Default is FALSE.

# Value

Displays message with date and time to stderr.

# **Examples**

```
message2("Hello world")
message2("Process completed", quiet = FALSE)
```

PredictiveRun

Perform predictive modeling using images or videos

## **Description**

Perform predictive modeling using images or videos

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#### Usage

```
PredictiveRun(
  obsY,
  imageKeysOfUnits = NULL,
  file = NULL,
  fileTransport = NULL,
  imageKeysOfUnitsTransport = NULL,
  nBoot = 10L,
  inputAvePoolingSize = 1L,
  useTrainingPertubations = T,
  useScalePertubations = F,
  X = NULL
  conda_env = "CausalImagesEnv",
  conda_env_required = T,
  Sys.setenv_text = NULL,
  figuresTag = NULL,
  figuresPath = "./",
  plotBands = 1L,
  plotResults = T,
  XCrossModal = T,
  XForceModal = F,
  optimizeImageRep = T,
  nWidth_ImageRep = 64L,
  nDepth_ImageRep = 1L,
  kernelSize = 5L,
  nWidth_Dense = 64L,
  nDepth_Dense = 1L,
  imageModelClass = "VisionTransformer",
  pretrainedModel = NULL,
  strides = 2L,
  nonLinearScaler = NULL,
  nDepth_TemporalRep = 3L,
  patchEmbedDim = 16L,
  dropoutRate = 0.1,
  droppathRate = 0.1,
  batchSize = 16L,
  nSGD = 400L
  testFrac = 0.05,
  TfRecords_BufferScaler = 4L,
  learningRateMax = 0.001,
  TFRecordControl = NULL,
  dataType = "image",
  image_dtype = "float16",
  atError = "stop",
  seed = NULL,
  modelPath = "./trained_model.eqx",
  metricsPath = "./evaluation_metrics.rds"
)
```

# **Arguments**

obsY

A numeric vector containing observed outcomes to predict.

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imageKeysOfUnits

A vector of length length(obsY) specifying the unique image ID associated with each unit. Samples of imageKeysOfUnits are fed into the package to call

images into memory.

file Path to a tfrecord file generated by WriteTfRecord.

nBoot Number of bootstrap iterations for uncertainty estimation.

useTrainingPertubations

Boolean specifying whether to randomly perturb the image axes during training

to reduce overfitting.

X An optional numeric matrix containing tabular information. X is normalized

internally.

conda\_env A conda environment where computational environment lives, usually created

via causalimages::BuildBackend(). Default = "CausalImagesEnv".

conda\_env\_required

A Boolean stating whether use of the specified conda environment is required.

figuresTag A string specifying an identifier that is appended to all figure names. figuresPath A string specifying file path for saved figures made in the analysis.

plotBands An integer or vector specifying which band position (from the image represen-

tation) should be plotted in the visual results. If a vector, plotBands should have 3 (and only 3) dimensions (corresponding to the 3 dimensions to be used

in RGB plotting).

plotResults (default = T) Should analysis results be plotted?

optimizeImageRep

Boolean specifying whether to optimize over the image model representation

(or only over downstream parameters).

nWidth\_ImageRep

Integer specifying width of image model representation.

 $n {\tt Depth\_ImageRep}$ 

Integer specifying depth of image model representation.

kernelSize Dimensions used in spatial convolutions.

nWidth\_Dense Integer specifying width of image model representation.

nDepth\_Dense Integer specifying depth of dense model representation.

strides (default = 2L) Integer specifying the strides used in the convolutional layers.

dropoutRate Dropout rate used in training to prevent overfitting (dropoutRate = 0 corre-

sponds to no dropout).

droppathRate Droppath rate used in training to prevent overfitting (droppathRate = 0 corre-

sponds to no droppath).

batchSize Batch size used in SGD optimization. Default = 50L.

nSGD Number of stochastic gradient descent (SGD) iterations. Default = 400L

testFrac Default = 0.1. Fraction of observations held out as a test set to evaluate out-of-

sample loss values.

TfRecords\_BufferScaler

The buffer size used in tfrecords mode is batchSize\*TfRecords\_BufferScaler.

Lower TfRecords\_BufferScaler towards 1 if out-of-memory problems.

dataType (default = "image") String specifying whether to assume "image" or "video"

data types.

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 $\label{lem:model} \begin{tabular}{ll} model Path & Path to save the trained model. Default = "./trained_model.eqx". \\ \begin{tabular}{ll} metricsPath & Path to save the evaluation metrics as a RDS file. Default = "./evaluation_metrics.rds". \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. Default = "./evaluation_metrics.rds". \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to save the evaluation metrics as a RDS file. \\ \begin{tabular}{ll} transportabilityMat & Path to sav$ 

Optional matrix with a column named imageKeysOfUnits specifying keys to be used by the package for generating predictions for out-of-sample points.

#### Value

Returns a list consisting of

- predictedY Predicted values for all units.
- ModelEvaluationMetrics Rigorous evaluation metrics (e.g., MSE, R2 for continuous; AUC, accuracy for binary).

#### References

• Connor T. Jerzak, Fredrik Johansson, Adel Daoud. Integrating Earth Observation Data into Causal Inference: Challenges and Opportunities. *ArXiv Preprint*, 2023.

## **Examples**

```
# For a tutorial, see
# github.com/cjerzak/causalimages-software/
```

print2

print2 print() with timestamps

#### **Description**

A function prints a string with date and time.

#### Usage

```
print2(text, quiet = F)
```

## **Arguments**

Χ

Character string to be printed, with date and time.

#### Value

Prints with date and time.

## **Examples**

```
message("Hello world")
```

TFRecordManagement 19

TFRecordManagement

Defines an internal TFRecord management routine (internal function)

# Description

Defines management defined in TFRecordManagement(). Internal function.

# Usage

TFRecordManagement()

# **Arguments**

No parameters.

# Value

Internal function defining a tfrecord management sequence.

TrainDefine

Defines an internal training routine (internal function)

# Description

Defines trainers defined in TrainDefine(). Internal function.

# Usage

TrainDefine()

# Arguments

No parameters.

## Value

Internal function defining a training sequence.

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TrainDo

Runs a training routine (internal function)

# Description

Runs trainers defined in TrainDefine(). Internal function.

# Usage

TrainDo()

#### **Arguments**

No parameters.

#### Value

Internal function performing model training.

WriteTfRecord

Write an image corpus as a .tfrecord file

## **Description**

Writes an image corpus to a .tfrecord file for rapid reading of images into memory for fast ML training. Specifically, this function serializes an image or video corpus into a .tfrecord file, enabling efficient data loading for machine learning tasks, particularly for image-based causal inference training. It requires that users define an acquireImageFxn function that accepts keys and returns the corresponding image or video as an array of dimensions (length(keys), nSpatialDim1, nSpatialDim1, nSpatialDim2, nC for images or (length(keys), nTimeSteps, nSpatialDim1, nSpatialDim2, nChannels) for video sequences.

```
WriteTfRecord(
   file,
   uniqueImageKeys,
   acquireImageFxn,
   writeVideo = F,
   image_dtype = "float16",
   conda_env = "CausalImagesEnv",
   conda_env_required = T,
   Sys.setenv_text = NULL
)
```

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## **Arguments**

file A character string naming a file for writing.

uniqueImageKeys

A vector specifying the unique image keys of the corpus. A key grabs an image/video array via acquireImageFxn(key).

acquireImageFxn

A function whose input is an observation keys and whose output is an array with dimensions (length(keys), nSpatialDim1, nSpatialDim2, nChannels)

for images and (length(keys), nTimeSteps, nSpatialDim1, nSpatialDim2, nChannels)

for image sequence data.

writeVideo (default = FALSE) Should we assume we're writing image sequence data of form

batch by time by height by width by channels?

conda\_env (default = "CausalImagesEnv") A conda environment where computational en-

vironment lives, usually created via causalimages::BuildBackend()

conda\_env\_required

(default = T) A Boolean stating whether use of the specified conda environment

is required.

## Value

Writes a unique key-referenced .tfrecord from an image/video corpus for use in image-based causal inference training.

## **Examples**

```
# Example usage (not run):
#WriteTfRecord(
# file = "./NigeriaConfoundApp.tfrecord",
# uniqueImageKeys = 1:n,
# acquireImageFxn = acquireImageFxn)
```

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