

## exercise 2

env\_init(): 初始化envs数组, 构建env\_free\_list链表, 节点数为NENV, 注意envs[0]在头部

```
void
env_init(void)
{
    // Set up envs array
    // LAB 3: Your code here.

    env_free_list = NULL;
    for (int i = NENV - 1; i >= 0; i--) {    //链表前插法构建
        envs[i].env_id = 0;
        envs[i].env_link = env_free_list;
        env_free_list = &envs[i];
    }
    //panic("env_init not yet implemented");
    // Per-CPU part of the initialization
    env_init_percpu();
}
```

env\_setup\_vm(struct Env \*e): 传入ENV结构指针e, 为进程分配内存空间, 设置e->env\_pgdir字段

region\_alloc(struct Env \*e, void \*va, size\_t len): 为e 分配len byte大小的物理空间, 并将va虚拟地址开始的len长度大小的空间映射到该物理空间。操作e->env\_pgdir

load\_icode(struct Env \*e, uint8\_t \*binary): 为e加载binary地址开始处的ELF文件。

env\_create(uint8\_t \*binary, enum EnvType type): 从env\_free\_list链表选取一个Env结构, 加载从binary地址开始的ELF文件, 用户环境类型为 type。

```
void
env_create(uint8_t *binary, enum EnvType type)
{
    // LAB 3: Your code here.
    struct Env *e;
    int r;
    if ((r=env_alloc(&e,0)!=0)){            //创建新的env变量, 若失败则报告错误信息
        panic("create env failed\n");
    }
    load_icode(e,binary);    //加载ELF文件
    e->env_type = type;      //设置env_type
    //panic("env_create not yet implemented");
}
```

env\_run(struct Env \*e): 执行e指向的用户环境

```
// LAB 3: Your code here.
if (curenv && curenv->env_status == ENV_RUNNING) { //首先设置curenv
    curenv->env_status = ENV_RUNNABLE;
}
curenv = e;
e->env_status = ENV_RUNNING;
e->env_runs++;
lcr3(PADDR(e->env_pgdir)); //加载地址空间
env_pop_tf(&e->env_tf); //弹出env_tf结构到寄存器

//panic("env_run not yet implemented");
}
```

## exercise 4

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参考信息:

Table 5-1. Protected-Mode Exceptions and Interrupts

Vector No.	Mnemonic	Description	Type	Error Code	Source
0	#DE	Divide Error	Fault	No	DIV and IDIV instructions.
1	#DB	RESERVED	Fault/Trap	No	For Intel use only.
2	—	NMI Interrupt	Interrupt	No	Nonmaskable external interrupt.
3	#BP	Breakpoint	Trap	No	INT 3 instruction.
4	#OF	Overflow	Trap	No	INTO instruction.
5	#BR	BOUND Range Exceeded	Fault	No	BOUND instruction.
6	#UD	Invalid Opcode (Undefined Opcode)	Fault	No	UD2 instruction or reserved opcode. <sup>1</sup>
7	#NM	Device Not Available (No Math Coprocessor)	Fault	No	Floating-point or WAIT/FWAIT instruction.
8	#DF	Double Fault	Abort	Yes (zero)	Any instruction that can generate an exception, an NMI, or an INTR.
9		Coprocessor Segment Overrun (reserved)	Fault	No	Floating-point instruction. <sup>2</sup>
10	#TS	Invalid TSS	Fault	Yes	Task switch or TSS access.
11	#NP	Segment Not Present	Fault	Yes	Loading segment registers or accessing system segments.
12	#SS	Stack-Segment Fault	Fault	Yes	Stack operations and SS register loads.
13	#GP	General Protection	Fault	Yes	Any memory reference and other protection checks.
14	#PF	Page Fault	Fault	Yes	Any memory reference.
15	—	(Intel reserved. Do not use.)		No	
16	#MF	x87 FPU Floating-Point Error (Math Fault)	Fault	No	x87 FPU floating-point or WAIT/FWAIT instruction.
17	#AC	Alignment Check	Fault	Yes (Zero)	Any data reference in memory. <sup>3</sup>
18	#MC	Machine Check	Abort	No	Error codes (if any) and source are model dependent. <sup>4</sup>
19	#XF	SIMD Floating-Point Exception	Fault	No	SSE/SSE2/SSE3 floating-point instructions <sup>5</sup>
20-31	—	Intel reserved. Do not use.			
32-255	—	User Defined (Non-reserved) Interrupts	Interrupt		External interrupt or INT <i>n</i> instruction.

代码:

定义每个中断类型的中断处理函数

TRAPHANDLER\_NOEC表示不压入错误信息, TRAPHANDLER表示需要错误信息

每个都压入中断号, 再 jmp \_alltraps

\_alltraps的作用是把中断现场的上下文保存到内核栈中, 然后jmp到trap函数, 做真正的中断处理

```

/*
 * Lab 3: Your code here for generating entry points for the different traps.
 */
TRAPHANDLER_NOEC(th0, T_DIVIDE)

```

```

TRAPHANDLER_NOEC(th1, T_DEBUG)
TRAPHANDLER_NOEC(th2, T_NMI)
TRAPHANDLER_NOEC(th3, T_BRKPT)
TRAPHANDLER_NOEC(th4, T_OFLOW)
TRAPHANDLER_NOEC(th5, T_BOUND)
TRAPHANDLER_NOEC(th6, T_ILLOP)
TRAPHANDLER_NOEC(th7, T_DEVICE)
TRAPHANDLER(th8, T_DBLFLT)

TRAPHANDLER(th10, T_TSS)
TRAPHANDLER(th11, T_SEGNP)
TRAPHANDLER(th12, T_STACK)
TRAPHANDLER(th13, T_GPFLT)
TRAPHANDLER(th14, T_PGFLT)

TRAPHANDLER_NOEC(th16, T_FPERR)
TRAPHANDLER(th17, T_ALIGN)
TRAPHANDLER_NOEC(th18, T_MCHK)
TRAPHANDLER_NOEC(th19, T_SIMDERR)
TRAPHANDLER_NOEC(th48, T_SYSCALL)
TRAPHANDLER_NOEC(th_default, T_DEFAULT)

/*
 * Lab 3: Your code here for _alltraps
 */
.global _alltraps
_alltraps:
    # according to struct Trapframe, we need to push %ds and %es
    pushl %ds
    pushl %es
    pushal
    movw $GD_KD, %ax
    movw %ax, %ds
    movw %ax, %es
    pushl %esp
    call trap

```

补充trap\_init():

```

void
trap_init(void)
{
    extern struct Segdesc gdt[];

    // LAB 3: Your code here.
    void th0();
    void th1();
    void th2();
    void th3();
    void th4();
    void th5();
    void th6();
    void th7();

```

```

void th8();

void th10();
void th11();
void th12();
void th13();
void th14();

void th16();
void th17();
void th18();
void th19();
void th48();
void th_default();
SETGATE(idt[0], 0, GD_KT, th0, 0);      //SETGATE(gate, istrap, sel, off,
//dp1), 定义在inc/mmu.h中
SETGATE(idt[1], 0, GD_KT, th1, 0);      //设置idt[1], 段选择子为内核代码段, 段内偏
//移为th1
SETGATE(idt[2], 0, GD_KT, th2, 0);
SETGATE(idt[3], 0, GD_KT, th3, 3);
SETGATE(idt[4], 0, GD_KT, th4, 0);
SETGATE(idt[5], 0, GD_KT, th5, 0);
SETGATE(idt[6], 0, GD_KT, th6, 0);
SETGATE(idt[7], 0, GD_KT, th7, 0);
SETGATE(idt[8], 0, GD_KT, th8, 0);

SETGATE(idt[10], 0, GD_KT, th10, 0);
SETGATE(idt[11], 0, GD_KT, th11, 0);
SETGATE(idt[12], 0, GD_KT, th12, 0);
SETGATE(idt[13], 0, GD_KT, th13, 0);
SETGATE(idt[14], 0, GD_KT, th14, 0);

SETGATE(idt[16], 0, GD_KT, th16, 0);
SETGATE(idt[17], 0, GD_KT, th17, 0);
SETGATE(idt[18], 0, GD_KT, th18, 0);
SETGATE(idt[19], 0, GD_KT, th19, 0);
SETGATE(idt[48], 1, GD_KT, th48, 3);
SETGATE(idt[T_DEFAULT], 0, GD_KT, th_default, 0);

//panic("trap_init not yet implemented");
// Per-CPU setup
trap_init_percpu();
}

```

## 问题1

What is the purpose of having an individual handler function for each exception/interrupt? (i.e., if all exceptions/interrupts were delivered to the same handler, what feature that exists in the current implementation could not be provided?)

无法得知trap类型, 无法判断发生了什么中断。不同的中断需要的操作是不同的 (例如有的需要压入错误代码, 有的不需要), 同一个handler处理比较麻烦。

## 问题2

Did you have to do anything to make the `user/softint` program behave correctly? The grade script expects it to produce a general protection fault (trap 13), but `softint`'s code says `int $14`. Why should this produce interrupt vector 13? What happens if the kernel actually allows `softint`'s `int $14` instruction to invoke the kernel's page fault handler (which is interrupt vector 14)?

用户级只能调用T\_SYSCALL, 其他只能由内核调用。程序试图调用14号中断处理程序 (page fault), 检查发现特权级不够, 所以触发了一般保护错误。如果允许用户不经过内核调用page fault, 则可以不经内核就访问内存, 操作系统将会很容易被攻击。

## exercise 5

修改trap\_dispatch(), 将页错误分配给page\_fault\_handler()处理。

```
static void
trap_dispatch(struct Trapframe *tf)
{
    // Handle processor exceptions.
    // LAB 3: Your code here.
    if (tf->tf_trapno == T_PGFLT) {
        page_fault_handler(tf);
        return;
    }
}
```

## exercise 6

修改trap\_dispatch(), 当断点异常发生时调用内核的monitor。添加如下代码

```
if (tf->tf_trapno == T_BRKPT) {
    monitor(tf);
    return;
}
```

## Questions

1. The break point test case will either generate a break point exception or a general protection fault depending on how you initialized the break point entry in the IDT (i.e., your call to `SETGATE` from `trap_init`). Why? How do you need to set it up in order to get the breakpoint exception to work as specified above and what incorrect setup would cause it to trigger a general protection fault?
2. What do you think is the point of these mechanisms, particularly in light of what the `user/softint` test program does?

1. 设置SETGATE(idt[3], 0, GD\_KT, th3, 0)的时候, 最后一个参数如果为0, 那么从用户态触发中断就会触发一般保护错误; 如果为3, 就能正常触发。

2. 这些机制都是为了保护操作系统内核不受攻击，隔离用户代码与内核代码。

## exercise 7

总结需要做的：

1. 为中断号T\_SYSCALL添加一个handler
2. 在trap\_dispatch()中判断中断号如果是T\_SYSCALL，调用syscall()函数（defined in kern/syscall.c），并将syscall()保存的返回值保存到tf->tf\_regs.reg\_eax，再恢复到%eax寄存器中。
3. 修改syscall.c中的syscall()函数，使能处理定义在syscall.h中的所有系统调用。

trap\_init()中已有 `SETGATE(idt[48], 1, GD_KT, th48, 3);`

在trap\_dispatch()中添加：

```
if (tf->tf_trapno == T_SYSCALL) {
    // 系统调用，按照指定规则，从寄存器中取出系统调用号和五个参数，传给syscall.c中的
    // syscall()，并将返回值保存到tf->tf_regs.reg_eax
    tf->tf_regs.reg_eax = syscall(tf->tf_regs.reg_eax, tf->tf_regs.reg_edx,
    tf->tf_regs.reg_ecx,
    tf->tf_regs.reg_ebx, tf->tf_regs.reg_edi, tf->tf_regs.reg_esi);
    return;
}
```

修改syscall.c中的syscall()：

参照syscall.h中的：

```
/* system call numbers */
enum {
    SYS_cputs = 0,
    SYS_cgetc,
    SYS_getenvid,
    SYS_env_destroy,
    NSYSCALLS
};
```

syscall.c:

```
int32_t
syscall(uint32_t syscallno, uint32_t a1, uint32_t a2, uint32_t a3, uint32_t a4,
uint32_t a5)
{
    // Call the function corresponding to the 'syscallno' parameter.
    // Return any appropriate return value.
    // LAB 3: Your code here.
    //panic("syscall not implemented")

    switch (syscallno) {
```

```

        case SYS_cputs:
            sys_cputs((const char*)a1, (size_t)a2);
            return 0;
        case SYS_cgetc:
            return sys_cgetc();
        case SYS_getenv:
            return sys_getenv();
        case SYS_env_destroy:
            return sys_env_destroy((env_t)a1);
        case NSYScalls:
            return 0;
        default:
            return -E_INVAL;
    }
}

```

## exercise 8

---

完成lib/libmain.c中的libmain(), 初始化thisenv, 使其指向当前用户环境。即系统调用sys\_getenv获取env, 再得到相应env结构。

```

void
libmain(int argc, char **argv)
{
    // set thisenv to point at our Env structure in envs[].
    // LAB 3: Your code here.
    //thisenv = 0;
    env_t env = sys_getenv();
    thisenv = envs + ENVX(env);
}

```

## 结果

---



```
+ ld obj/user/faultwrite
+ cc[USER] user/faultwritekernel.c
+ ld obj/user/faultwritekernel
+ ld obj/kern/kernel
ld: warning: section `.bss' type changed to PROGBITS
+ as boot/boot.S
+ cc -Os boot/main.c
+ ld boot/boot
boot block is 412 bytes (max 510)
+ mk obj/kern/kernel.img
make[1]: Leaving directory '/home/jiahao/Documents/fduos2021'
divzero: OK (0.8s)
softint: OK (1.0s)
badsegment: OK (1.0s)
Part A score: 30/30

faultread: OK (1.0s)
faultreadkernel: OK (1.0s)
faultwrite: OK (1.0s)
faultwritekernel: OK (1.0s)
breakpoint: OK (1.0s)
    (Old jos.out.breakpoint failure log removed)
testbss: OK (1.0s)
    (Old jos.out.testbss failure log removed)
hello: OK (1.0s)
    (Old jos.out.hello failure log removed)
Part B score: 70/70

Score: 100/100
jiahao@jiahao-virtual-machine:~/Documents/fduos2021$
```

## 第二部分

---

优化代码

现有问题：

凡是涉及到各个中断号处理函数的代码都有许多结构上的重复，如图：

```

TRAPHANDLER_NOEC(th0, T_DIVIDE)
TRAPHANDLER_NOEC(th1, T_DEBUG)
TRAPHANDLER_NOEC(th2, T_NMI)
TRAPHANDLER_NOEC(th3, T_BRKPT)
TRAPHANDLER_NOEC(th4, T_OFLOW)
TRAPHANDLER_NOEC(th5, T_BOUND)
TRAPHANDLER_NOEC(th6, T_ILLOP)
TRAPHANDLER_NOEC(th7, T_DEVICE)
TRAPHANDLER(th8, T_DBLFLT)

TRAPHANDLER(th10, T_TSS)
TRAPHANDLER(th11, T_SEGNP)
TRAPHANDLER(th12, T_STACK)
TRAPHANDLER(th13, T_GPFLT)
TRAPHANDLER(th14, T_PGFLT)

TRAPHANDLER_NOEC(th16, T_FPERR)
TRAPHANDLER(th17, T_ALIGN)
TRAPHANDLER_NOEC(th18, T_MCHK)
TRAPHANDLER_NOEC(th19, T_SIMDERR)
TRAPHANDLER_NOEC(th48, T_SYSCALL)
TRAPHANDLER_NOEC(th_default, T_DEFAULT)
void th0();
void th1();
void th2();
void th3();
void th4();
void th5();
void th6();
void th7();
void th8();

void th10();
void th11();
void th12();
void th13();
void th14();

void th16();
void th17();
void th18();
void th19();
void th48();
void th_default();

```

## 解决方法：

对于这些重复性很大的代码，可以考虑将其单独提出到一个文件，在需要用到这些代码的地方引用并设置宏定义

创建文件kern/handler.txt

```
TH(0)
TH(1)
TH(2)
TH(3)
TH(4)
TH(5)
TH(6)
TH(7)
THE(8)
THE(10)
THE(11)
THE(12)
THE(13)
THE(14)
TH(16)
THE(17)
TH(18)
TH(19)
TH(48)
```

此即为以上部分代码的原型，接下来在原来的地方引用kern/handler.txt并设置不同宏定义，实现原来代码的功能

trapentry.S

```
/*
 * Lab 3: Your code here for generating entry points for the different traps.
 */

#define TH(n) \
TRAPHANDLER_NOEC(handler##n, n)

#define THE(n) \
TRAPHANDLER(handler##n, n)

#include "handler.txt"

#undef THE
#undef TH
```

这里最终为：

```
TRAPHANDLER_NOEC(handler0, 0)
TRAPHANDLER_NOEC(handler1, 1)
.....
TRAPHANDLER_NOEC(handler48, 48)
```

trap.c

```
void
trap_init(void)
{
```

```

extern struct Segdesc gdt[];

// LAB 3: Your code here.
#define TH(n) void handler##n();
#define THE(n) void handler##n();

#include "handler.txt"

#undef THE
#undef TH

#define TH(n) SETGATE(idt[n], 0, GD_KT, handler##n, 0);
#define THE(n) SETGATE(idt[n], 0, GD_KT, handler##n, 0);

#include "handler.txt"

#undef THE
#undef TH

SETGATE(idt[3], 0, GD_KT, handler3, 3);
SETGATE(idt[48], 0, GD_KT, handler48, 3);

//panic("trap_init not yet implemented");
// Per-CPU setup
trap_init_percpu();
}

```

优化后的代码在编译后与原来的代码一样：

```

// LAB 3: Your code here.
void th0();
void th1();
void th2();
void th3();
void th4();
void th5();
void th6();
void th7();
void th8();

void th10();
void th11();
void th12();
void th13();
void th14();

void th16();
void th17();
void th18();
void th19();
void th48();
void th_default();
SETGATE(idt[0], 0, GD_KT, th0, 0);
SETGATE(idt[1], 0, GD_KT, th1, 0);
SETGATE(idt[2], 0, GD_KT, th2, 0);

```

```

SETGATE(idt[3], 0, GD_KT, th3, 3);
SETGATE(idt[4], 0, GD_KT, th4, 0);
SETGATE(idt[5], 0, GD_KT, th5, 0);
SETGATE(idt[6], 0, GD_KT, th6, 0);
SETGATE(idt[7], 0, GD_KT, th7, 0);
SETGATE(idt[8], 0, GD_KT, th8, 0);

SETGATE(idt[10], 0, GD_KT, th10, 0);
SETGATE(idt[11], 0, GD_KT, th11, 0);
SETGATE(idt[12], 0, GD_KT, th12, 0);
SETGATE(idt[13], 0, GD_KT, th13, 0);
SETGATE(idt[14], 0, GD_KT, th14, 0);

SETGATE(idt[16], 0, GD_KT, th16, 0);
SETGATE(idt[17], 0, GD_KT, th17, 0);
SETGATE(idt[18], 0, GD_KT, th18, 0);
SETGATE(idt[19], 0, GD_KT, th19, 0);
SETGATE(idt[48], 1, GD_KT, th48, 3);
SETGATE(idt[T_DEFAULT], 0, GD_KT, th_default, 0);

```

## 结果

```

+ ld obj/kern/kernel
ld: warning: section '.bss' type changed to PROGBITS
+ as boot/boot.S
+ cc -Os boot/main.c
+ ld boot/boot
boot block is 412 bytes (max 510)
+ mk obj/kern/kernel.img
make[1]: Leaving directory '/home/jiahao/Documents/fduos2021'
divzero: OK (0.9s)
softint: OK (0.9s)
badsegment: OK (1.0s)
Part A score: 30/30

faultread: OK (1.0s)
faultreadkernel: OK (1.0s)
faultwrite: OK (1.0s)
faultwritekernel: OK (1.0s)
breakpoint: OK (1.1s)
testbss: OK (1.0s)
hello: OK (1.0s)
Part B score: 70/70

Score: 100/100
jiahao@jiahao-virtual-machine:~/Documents/fduos2021$

```

## 分析优点

这样优化代码，可以减少源程序的重复代码量，使程序更简洁易懂

