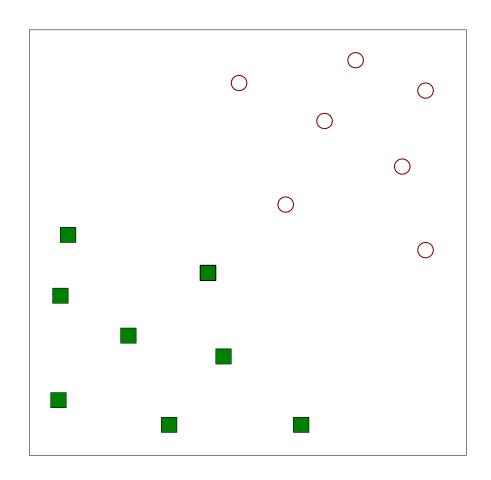
# **Data Mining**

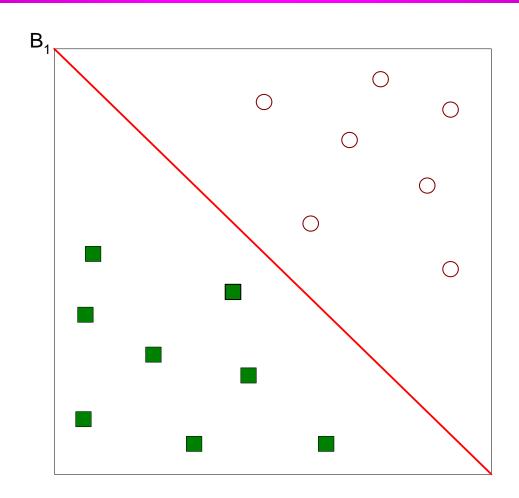
# **Support Vector Machines**

Introduction to Data Mining, 2<sup>nd</sup> Edition by

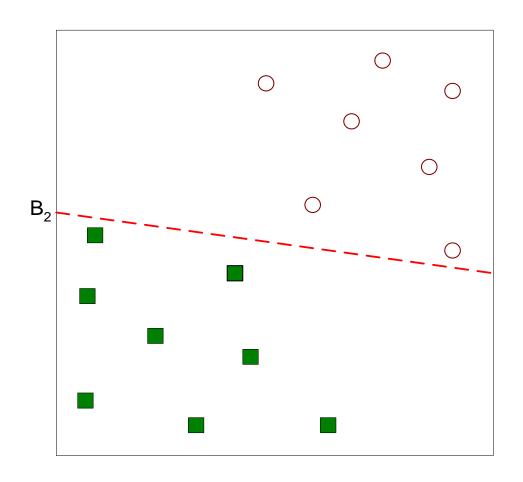
Tan, Steinbach, Karpatne, Kumar



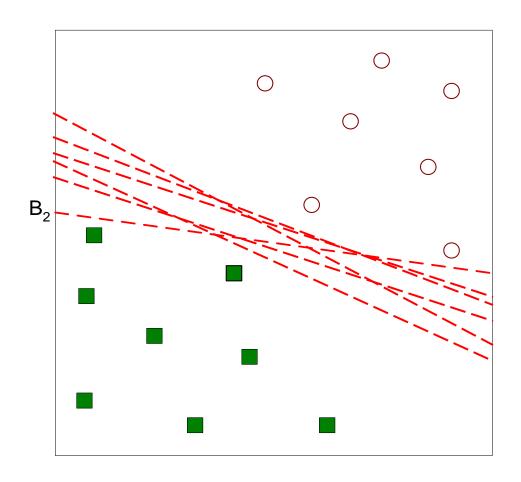
Find a linear hyperplane (decision boundary) that will separate the data



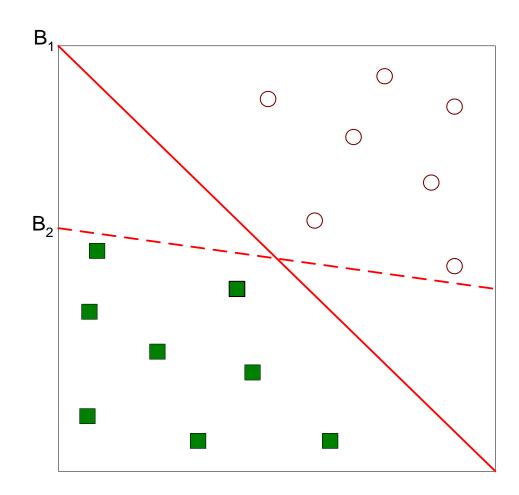
One Possible Solution



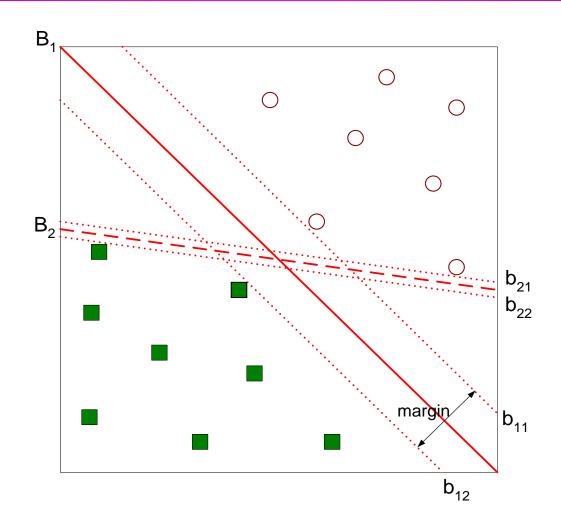
Another possible solution



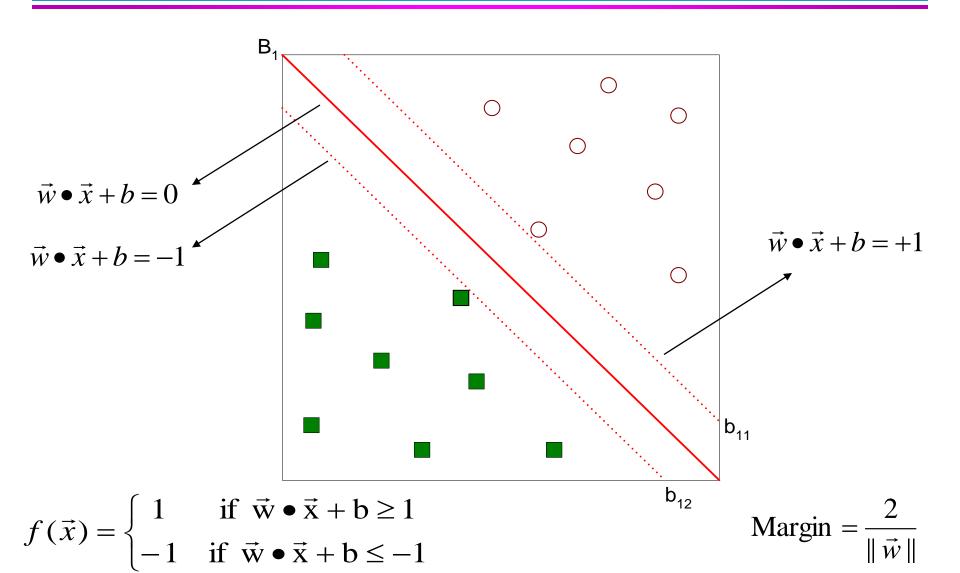
Other possible solutions



- Which one is better? B1 or B2?
- How do you define better?



Find hyperplane maximizes the margin => B1 is better than B2



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Introduction to Data Mining, 2<sup>nd</sup> Edition

#### **Linear SVM**

Linear model:

$$f(\vec{x}) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x} + b \ge 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x} + b \le -1 \end{cases}$$

- Learning the model is equivalent to determining the values of  $\vec{w}$  and b
  - How to find  $\vec{w}$  and  $\vec{b}$  from training data?

# **Learning Linear SVM**

- Objective is to maximize: Margin =  $\frac{2}{\|\vec{w}\|}$ 
  - Which is equivalent to minimizing:  $L(\vec{w}) = \frac{\|\vec{w}\|^2}{2}$
  - Subject to the following constraints:

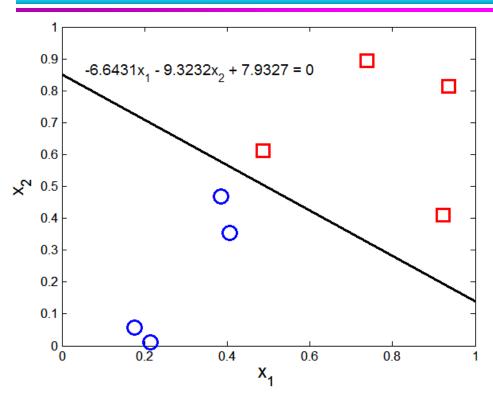
$$y_i = \begin{cases} 1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \ge 1 \\ -1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \le -1 \end{cases}$$

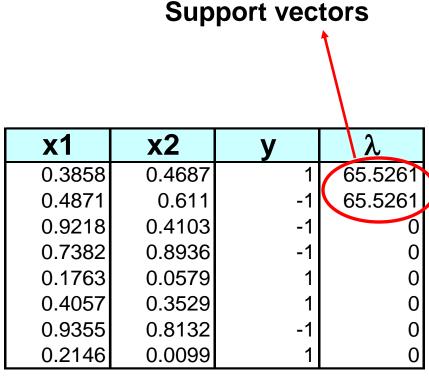
or

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \ge 1, \qquad i = 1, 2, \dots, N$$

- This is a constrained optimization problem
  - Solve it using Lagrange multiplier method

# **Example of Linear SVM**



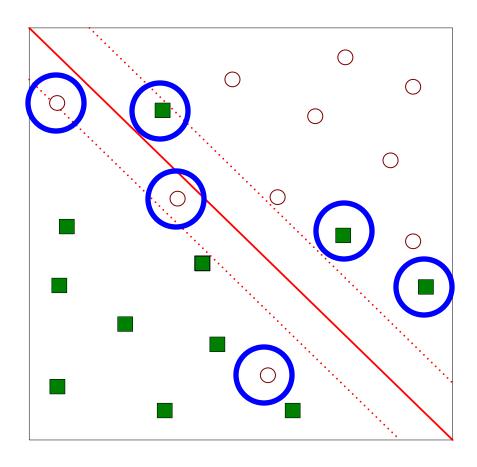


# **Learning Linear SVM**

- Decision boundary depends only on support vectors
  - If you have data set with same support vectors, decision boundary will not change
  - How to classify using SVM once w and b are found? Given a test record, x<sub>i</sub>

$$f(\vec{x}_i) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \ge 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \le -1 \end{cases}$$

What if the problem is not linearly separable?



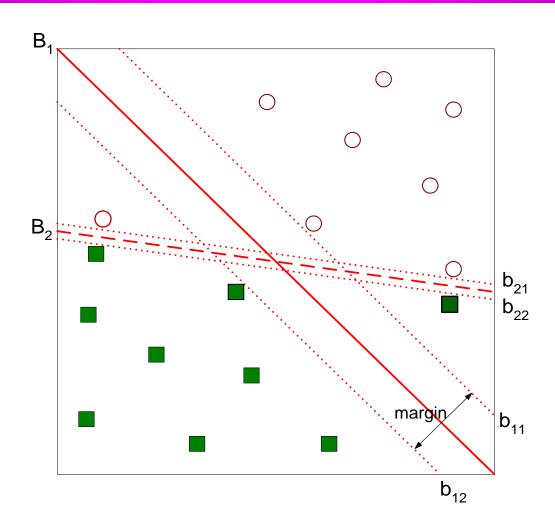
- What if the problem is not linearly separable?
  - Introduce slack variables
    - Need to minimize:

$$L(w) = \frac{\|\vec{w}\|^2}{2} + C\left(\sum_{i=1}^{N} \xi_i^k\right)$$

Subject to:

$$y_i = \begin{cases} 1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + \mathbf{b} \ge 1 - \xi_i \\ -1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + \mathbf{b} \le -1 + \xi_i \end{cases}$$

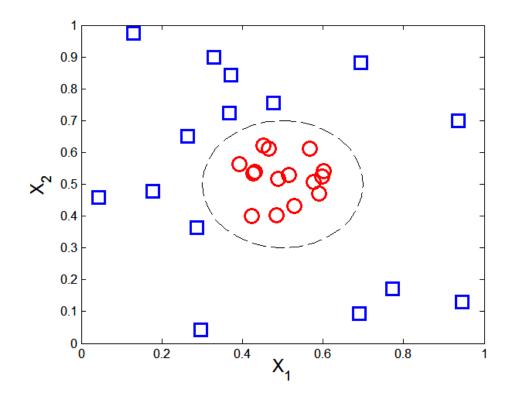
◆ If k is 1 or 2, this leads to similar objective function as linear SVM but with different constraints (see textbook)



Find the hyperplane that optimizes both factors

#### **Nonlinear Support Vector Machines**

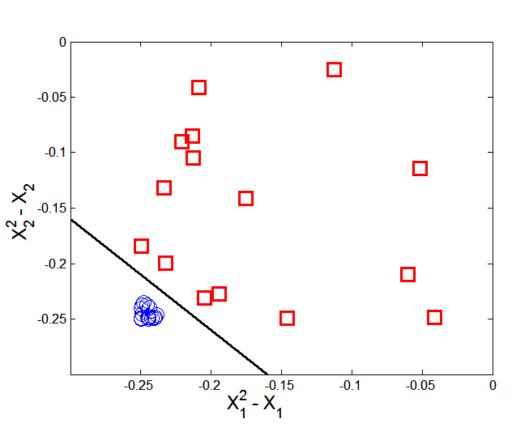
What if decision boundary is not linear?



$$y(x_1, x_2) = \begin{cases} 1 & \text{if } \sqrt{(x_1 - 0.5)^2 + (x_2 - 0.5)^2} > 0.2 \\ -1 & \text{otherwise} \end{cases}$$

#### **Nonlinear Support Vector Machines**

Transform data into higher dimensional space



$$x_1^2 - x_1 + x_2^2 - x_2 = -0.46.$$

$$\Phi:(x_1,x_2) \longrightarrow (x_1^2,x_2^2,\sqrt{2}x_1,\sqrt{2}x_2,1).$$

$$w_4x_1^2 + w_3x_2^2 + w_2\sqrt{2}x_1 + w_1\sqrt{2}x_2 + w_0 = 0.$$

**Decision boundary:** 

$$\vec{w} \bullet \Phi(\vec{x}) + b = 0$$

#### **Learning Nonlinear SVM**

Optimization problem:

$$\min_{\mathbf{w}} \frac{\|\mathbf{w}\|^2}{2}$$
subject to  $y_i(\mathbf{w} \cdot \Phi(\mathbf{x}_i) + b) \ge 1, \ \forall \{(\mathbf{x}_i, y_i)\}$ 

 Which leads to the same set of equations (but involve Φ(x) instead of x)

$$\begin{split} L_D &= \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j) \qquad \mathbf{w} = \sum_i \lambda_i y_i \Phi(\mathbf{x}_i) \\ & \lambda_i \{ y_i (\sum_j \lambda_j y_j \Phi(\mathbf{x}_j) \cdot \Phi(\mathbf{x}_i) + b) - 1 \} = 0, \end{split}$$

$$f(\mathbf{z}) = sign(\mathbf{w} \cdot \Phi(\mathbf{z}) + b) = sign(\sum_{i=1}^{n} \lambda_i y_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{z}) + b).$$

#### **Learning NonLinear SVM**

Issues:

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- used?
- How to do the computation in high dimensional space?
  - Most computations involve dot product Φ(x<sub>i</sub>) Φ(x<sub>i</sub>)
  - Curse of dimensionality?

# **Learning Nonlinear SVM**

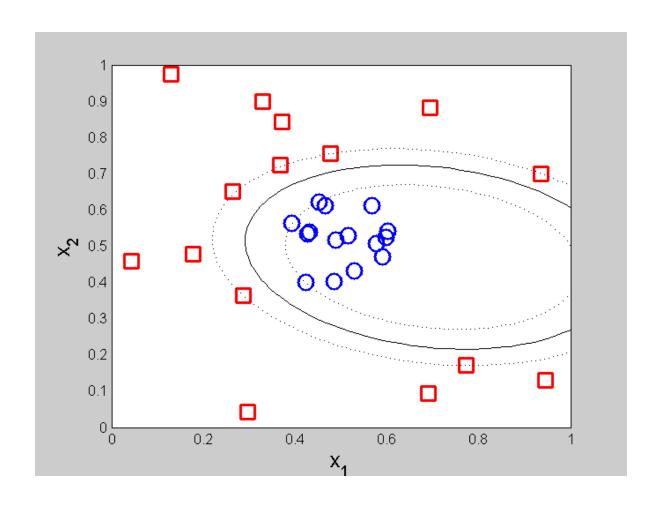
- Kernel Trick:
  - $\Phi(x_i) \bullet \Phi(x_j) = K(x_i, x_j)$
  - K(x<sub>i</sub>, x<sub>j</sub>) is a kernel function (expressed in terms of the coordinates in the original space)
    - Examples:

$$K(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y} + 1)^{p}$$

$$K(\mathbf{x}, \mathbf{y}) = e^{-\|\mathbf{x} - \mathbf{y}\|^{2}/(2\sigma^{2})}$$

$$K(\mathbf{x}, \mathbf{y}) = \tanh(k\mathbf{x} \cdot \mathbf{y} - \delta)$$

### **Example of Nonlinear SVM**



**SVM** with polynomial degree 2 kernel

# **Learning Nonlinear SVM**

- Advantages of using kernel:
  - Don't have to know the mapping function Φ
  - Computing dot product  $\Phi(x_i) \bullet \Phi(x_j)$  in the original space avoids curse of dimensionality
- Not all functions can be kernels
  - Must make sure there is a corresponding Φ in some high-dimensional space
  - Mercer's theorem (see textbook)

#### **Characteristics of SVM**

- The learning problem is formulated as a convex optimization problem
  - Efficient algorithms are available to find the global minima
  - Many of the other methods use greedy approaches and find locally optimal solutions
  - High computational complexity for building the model
- Robust to noise
- Overfitting is handled by maximizing the margin of the decision boundary,
- SVM can handle irrelevant and redundant attributes better than many other techniques
- The user needs to provide the type of kernel function and cost function
- Difficult to handle missing values
- What about categorical variables?