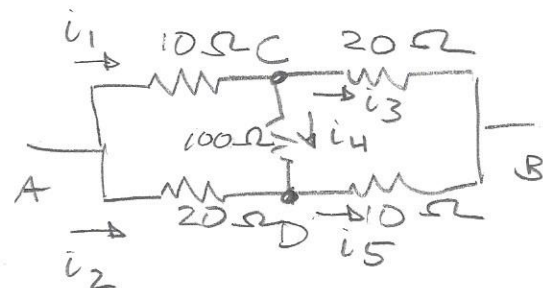
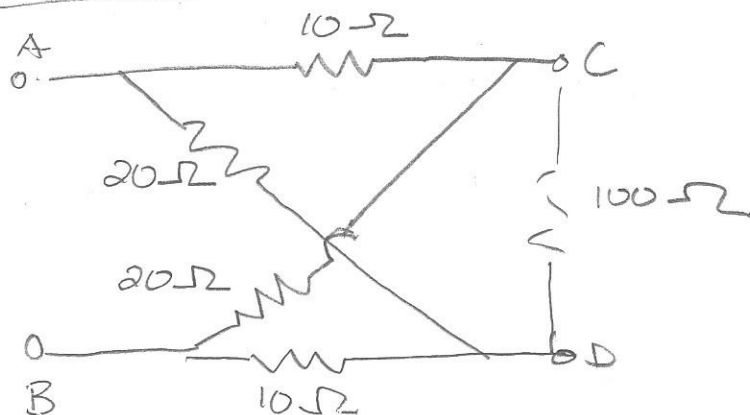


PROBLEM SET 4

SOLUTIONS

Problem 1 : B-6-2



$$e_{AB} = R_{AB} \cdot (i_1 + i_2)$$

$$\left. \begin{array}{l} @ C: i_1 = i_3 + i_4 \rightarrow i_3 = i_1 - i_4 \\ @ D: i_5 = i_4 + i_2 \end{array} \right\} \begin{array}{l} \text{variables: } i_1, i_2, i_4 \\ \therefore \text{need 3 equations} \end{array}$$

Path ACB : $e_{AC} + e_{CB} = e_{AB}$

$$10i_1 + 20i_3 = e_{AB}$$

$$10i_1 + 20(i_1 - i_4) = e_{AB}$$

①

Path ADB : $e_{AD} + e_{DB} = e_{AB}$

$$20i_2 + 10i_5 = e_{AB}$$

$$20i_2 + 10(i_4 + i_2) = e_{AB}$$

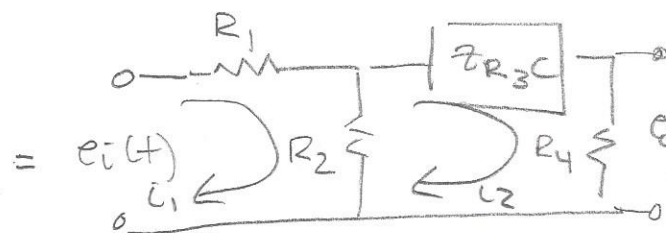
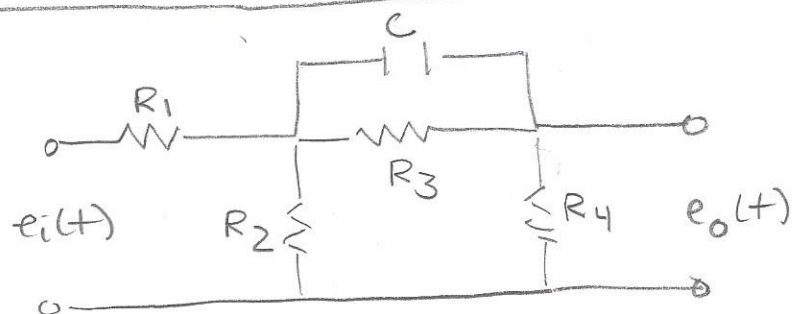
②

Path AC-D = Path AD $\Rightarrow e_{AC} + e_{CD} = e_{AD}$

$$10i_1 + 100i_4 = 20i_2$$

③

$$e_{AB} = R_{AB}(i_1 + i_2) \Rightarrow R_{AB} = \frac{e_{AB}}{i_1 + i_2} \Rightarrow \boxed{R_{AB} = 14.8 \Omega}$$

Problem 2: B-6-7

$$e_o(t) = e_{R_4}(t)$$

$$z_{R_3C}(s) = \frac{\frac{1}{Cs} \cdot R_3}{\frac{1}{Cs} + R_3} = \frac{R_3}{R_3Cs + 1}$$

$$G(s) = \frac{E_o(s)}{E_i(s)} = \frac{R_4 I_2(s)}{E_i(s)}$$

$$\text{Loop } i_1: E_i(s) - R_1 I_1(s) - R_2 [I_1(s) - I_2(s)] = 0 \quad (1)$$

$$\text{Loop } i_2: -z_{R_3C}(s) I_2(s) - R_4 I_2(s) - R_2 [I_2(s) - I_1(s)] = 0 \quad (2)$$

$$(1) [R_1 + R_2] I_1(s) + [-R_2] I_2(s) = E_i(s)$$

$$[-R_2] I_1(s) + [z_{R_3C}(s) + R_4 + R_2] I_2(s) = 0$$

$$\therefore I_2(s) = \frac{\begin{vmatrix} R_1 + R_2 & E_i(s) \\ -R_2 & 0 \end{vmatrix}}{\begin{vmatrix} R_1 + R_2 & -R_2 \\ -R_2 & z_{R_3C}(s) + R_4 + R_2 \end{vmatrix}}$$

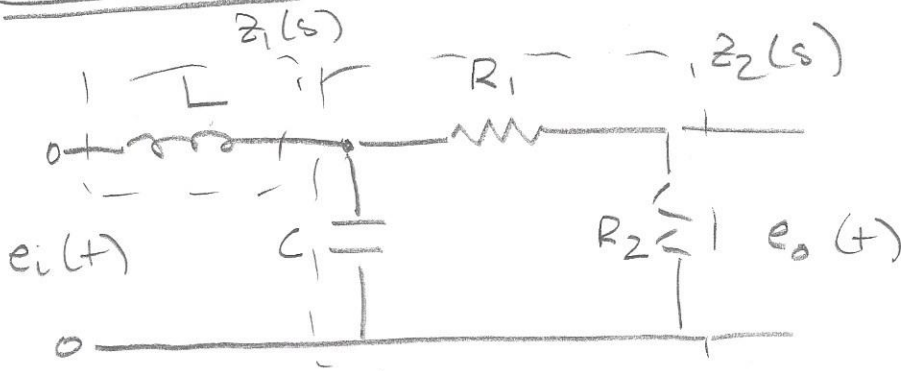
$$\begin{aligned} &= \frac{R_2 E_i(s)}{(R_1 + R_2)[z_{R_3C}(s) + R_4 + R_2] - R_2^2} \\ &= \frac{R_2 (R_3Cs + 1) E_i(s)}{(R_1 + R_2)[R_3 + (R_4 + R_2)(R_3Cs + 1)] - R_2^2 (R_3Cs + 1)} \end{aligned}$$

Problem 2: (cont'd)

$$G(s) = \frac{E_o(s)}{E_i(s)} = \frac{R_4 I_2(s)}{E_i(s)}$$

$$= \frac{R_4}{E_i(s)} \cdot \frac{R_2 (R_3(s+1)) \cancel{E_i(s)}}{(R_1+R_2) [R_3 + (R_4+R_2)(R_3(s+1))] - R_2^2 (R_3(s+1))}$$

$$\boxed{\frac{E_o(s)}{E_i(s)} = \frac{R_2 R_4 (R_3(s+1))}{(R_1+R_2) [R_3 + R_4 (R_3(s+1))] + R_1 R_2 (R_3(s+1))}}$$

Problem 3: B-6-8

$$E_c(s) = E_{R_1}(s) + E_{R_2}(s)$$

$$\frac{E_o(s)}{E_i(s)} = \frac{E_c(s)}{E_i(s)} \cdot \frac{E_o(s)}{E_c(s)}$$

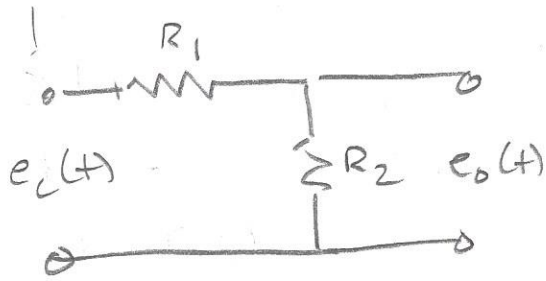
$$\frac{E_c(s)}{E_i(s)} = \frac{z_2(s)}{z_1(s) + z_2(s)}$$

$$z_1(s) = z_L(s) = Ls$$

$$z_2(s) = \frac{z_c(s) \cdot [z_{R_1}(s) + z_{R_2}(s)]}{z_c(s) + [z_{R_1}(s) + z_{R_2}(s)]}$$

$$= \frac{\frac{1}{Cs} \cdot (R_1 + R_2)}{\frac{1}{Cs} + R_1 + R_2} = \frac{R_1 + R_2}{(R_1 + R_2)Cs + 1}$$

$$\frac{E_c(s)}{E_i(s)} = \frac{\frac{R_1 + R_2}{(R_1 + R_2)Cs + 1}}{Ls + \frac{R_1 + R_2}{(R_1 + R_2)Cs + 1}} = \frac{R_1 + R_2}{Ls[(R_1 + R_2)Cs + 1] + R_1 + R_2}$$

Problem 3: Cont'd

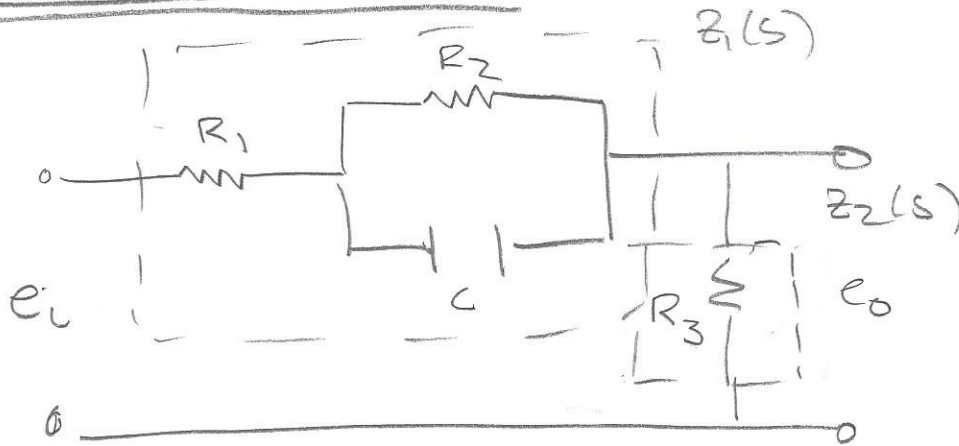
$$\frac{E_o(s)}{E_i(s)} = \frac{Z_{R_2}(s)}{Z_{R_1}(s) + Z_{R_2}(s)}$$

$$= \frac{R_2}{R_1 + R_2}$$

$$\frac{E_o(s)}{E_i(s)} = \frac{E_c(s)}{E_i(s)} \cdot \frac{E_o(s)}{E_c(s)}$$

$$= \frac{\cancel{R_1 + R_2}}{Ls[(R_1 + R_2)Cs + 1] + R_1 + R_2} \cdot \frac{R_2}{\cancel{R_1 + R_2}}$$

$$\boxed{\frac{E_o(s)}{E_i(s)} = \frac{R_2}{Ls[(R_1 + R_2)Cs + 1] + R_1 + R_2}}$$

Problem 4: B-6-11

$$\frac{E_o(s)}{E_i(s)} = \frac{z_2(s)}{z_1(s) + z_2(s)}$$

$$z_2(s) = z_{R_3}(s) = R_3$$

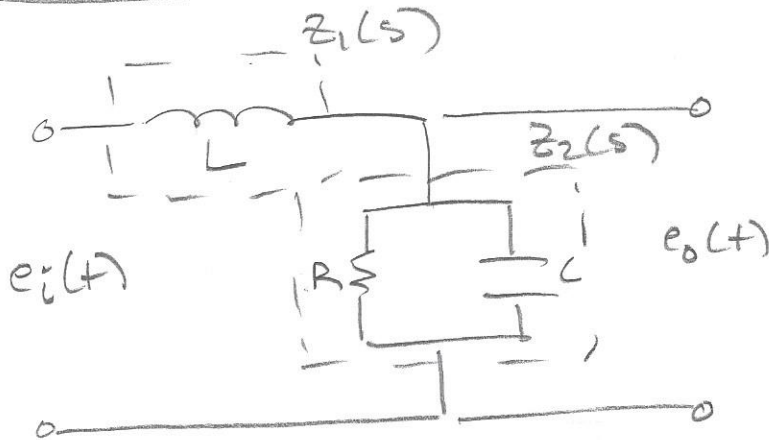
$$z_1(s) = z_{R_1}(s) + \frac{z_{R_2}(s) \cdot z_C(s)}{z_{R_2}(s) + z_C(s)}$$

$$= R_1 + \frac{R_2 \frac{1}{Cs}}{R_2 + \frac{1}{Cs}}$$

$$= R_1 + \frac{R_2}{R_2Cs + 1}$$

$$\frac{E_o(s)}{E_i(s)} = \frac{R_3}{R_1 + \frac{R_2}{R_2Cs + 1} + R_3}$$

$$\boxed{\frac{E_o(s)}{E_i(s)} = \frac{R_3(R_2Cs + 1)}{(R_1 + R_3)(R_2Cs + 1) + R_2}}$$

Problem 5 : B-6-12

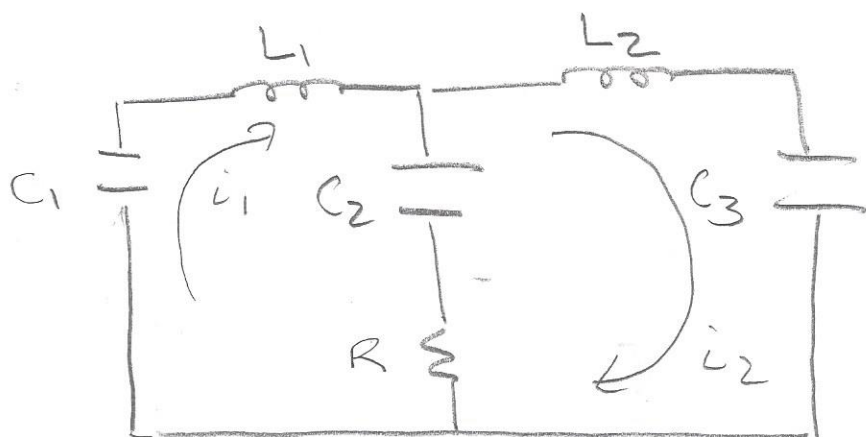
$$\frac{E_o(s)}{E_i(s)} = \frac{z_2(s)}{z_1(s) + z_2(s)}$$

$$z_1(s) = z_L(s) = Ls$$

$$z_2(s) = \frac{z_C(s) \cdot z_R(s)}{z_C(s) + z_R(s)} = \frac{\frac{1}{Cs} \cdot R}{\frac{1}{Cs} + R} = \frac{R}{RCs + 1}$$

$$\frac{E_o(s)}{E_i(s)} = \frac{\frac{R}{RCs + 1}}{Ls + \frac{R}{RCs + 1}}$$

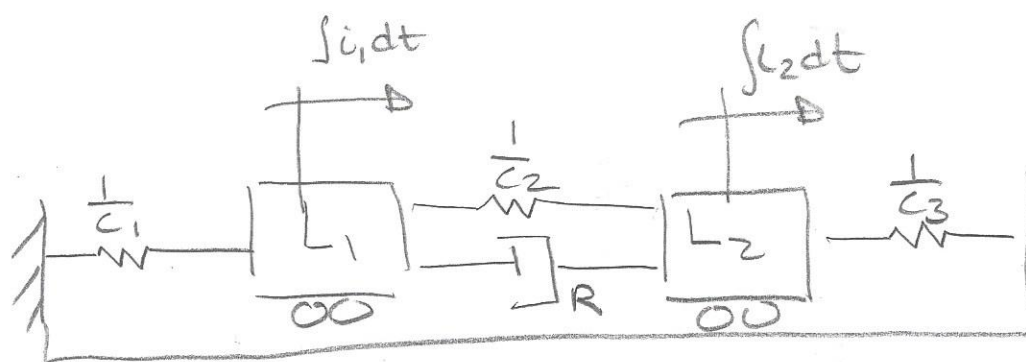
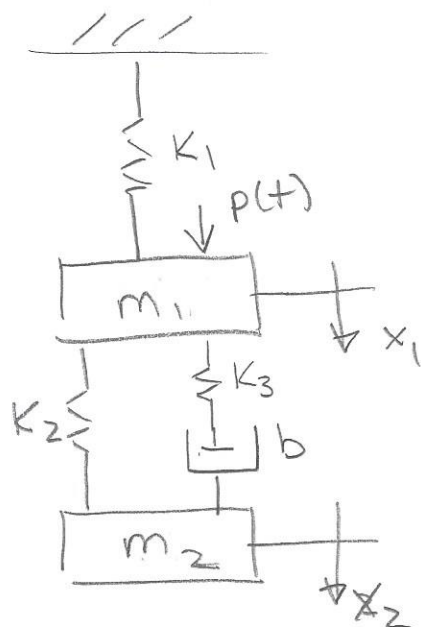
$$\Rightarrow \boxed{\frac{E_o(s)}{E_i(s)} = \frac{R}{Ls[RCs + 1] + R}}$$

Problem 6: B-6-17

$C_1, L_1 \Rightarrow$ share common velocity \dot{i}_1

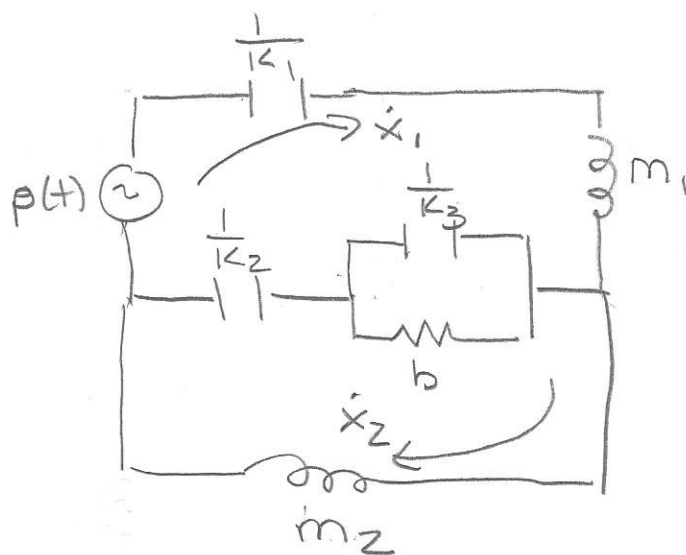
$L_2, C_3 \Rightarrow$ share common velocity \dot{i}_2

$C_2, R \Rightarrow$ relative velocity between \dot{i}_1 and \dot{i}_2

Problem 7: B-6-18

$K_2, (K_3 + b)$

\Rightarrow share relative current between \dot{x}_1 and \dot{x}_2

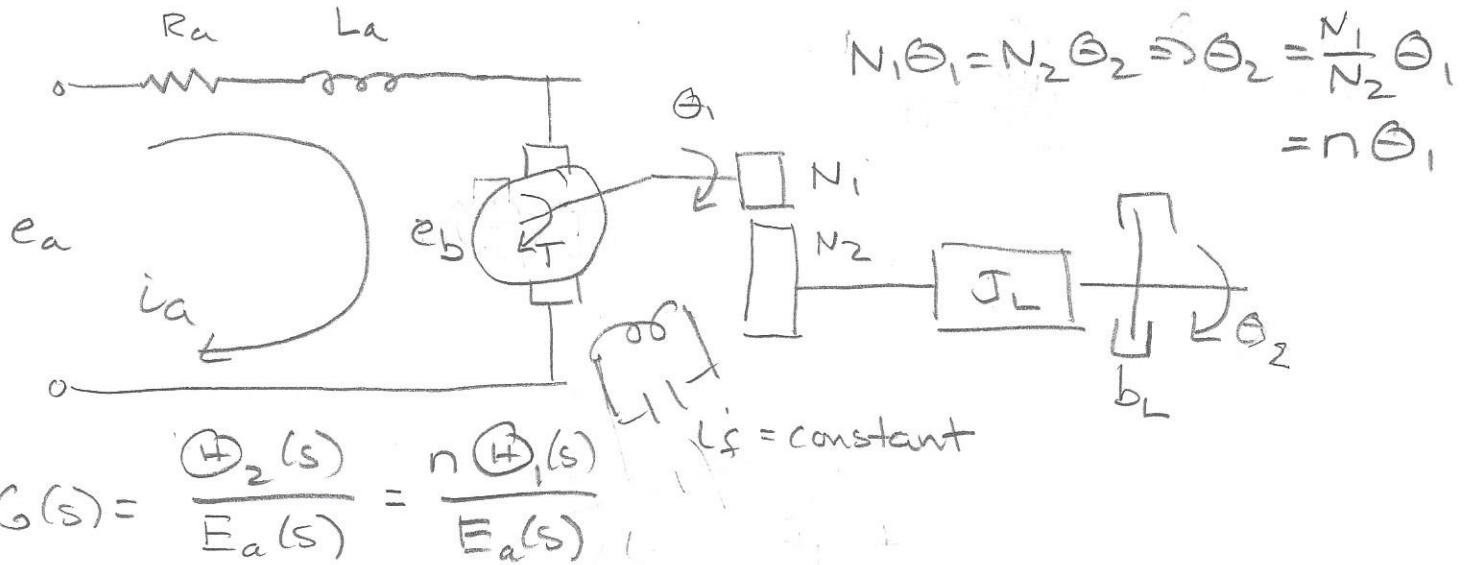


$K_1, m_1 \Rightarrow$ share common current \dot{x}_1 , with voltage source $p(t)$

$m_2 \Rightarrow$ has current \dot{x}_2

K_3 and $b \Rightarrow$ undergo same voltage

Problem 8 : B-6-19



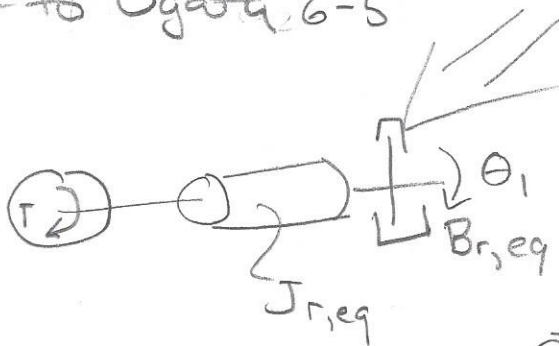
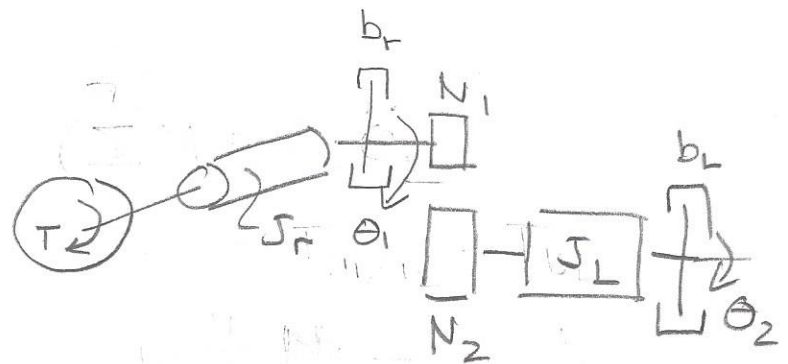
Electrical:

$$E_a(s) - R_a I_a(s) - L_a s I_a(s) - E_b(s) = 0$$

Mechanical

$$\begin{cases} J_{r,eq} = J_r + n^2 J_L \\ B_{r,eq} = b_r + n^2 b_L \end{cases}$$

→ Refer to Ogata 6-5



$$\sum M = J_{r,eq} \ddot{\theta}_1 = T - T_{B_{r,eq}} = T - B_{r,eq} \dot{\theta}_1$$

$$\Rightarrow J_{r,eq} \ddot{\theta}_1 + B_{r,eq} \dot{\theta}_1 = T = [J_{r,eq} s^2 + B_{r,eq} s] \Theta(s) = T(s)$$

Problem 8 (Cont'd)Electromechanical

$$(1) e_b = K_b \dot{\theta}_1 \Rightarrow \underline{E_b(s) = K_b s \Theta_1(s)}$$

$$(2) T = K \cdot i_a \Rightarrow \underline{T(s) = K I_a(s)}$$

$$\Rightarrow [K_b s] \Theta_1(s) + [R_a + L_a s] I_a(s) = E_a(s)$$

$$\Rightarrow [J_{r,eq} s^2 + B_{r,eq} s] \Theta_1(s) + [-K] I_a(s) = 0$$

$$\Theta_1(s) = \frac{\begin{vmatrix} E_a(s) & R_a + L_a s \\ 0 & -K \end{vmatrix}}{\begin{vmatrix} K_b s & R_a + L_a s \\ [J_{r,eq} s^2 + B_{r,eq} s] & -K \end{vmatrix}}$$

$$= \frac{-K E_a(s)}{[J_{r,eq} s^2 + B_{r,eq} s][R_a + L_a s] + K K_b s}$$

$$\therefore \frac{\Theta_2(s)}{E_a(s)} = \frac{n \Theta_1(s)}{E_a(s)} = \frac{K n}{[J_{r,eq} s^2 + B_{r,eq} s][R_a + L_a s] + K K_b s}$$

$$L_a = 0$$

$$\boxed{\frac{\Theta_2(s)}{E_a(s)} = \frac{0.072}{s(0.1296s + 1)}}$$