PROBLEM SET 2 SOLUTIONS SOLUTIO

Problem 1

$$\frac{1}{4}f_{z}(t) = -K_{1}(x_{1} - K_{2}(x_{1} - X_{2})$$

$$= -K_{1}(x_{1} - Bx_{1} - K_{2}(x_{1} - X_{2})$$

$$+ C(t)$$

$$\Rightarrow [M, \times, + B \times, + (K, + k_2) \times, = K_2 \times_2 + f, (+)]$$

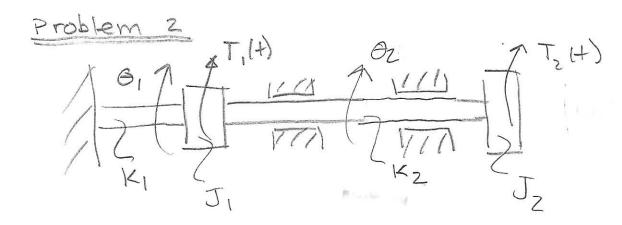
$$\frac{f_{K_2}}{f_{Z}F} = M_2 \dot{x}_2$$

$$= F_{K_2} + f_{Z}(+)$$

$$= K_2(x_1 - x_2) + f_{Z}(+)$$

$$= M_2 \dot{x}_2 + K_2 \dot{x}_2 = K_2 \dot{x}_1 + f_{Z}(+)$$

, .s



As the problem is given, Θ_z should be considered the relative angular displacement between J_z and J_z . That is $\Theta_z = \Theta_{J_z} + \Theta_{J_z}$

However, full points will be awarded if you interpretted Θ_z as the absolute angular displacement of J_z

$$\begin{array}{ll}
\Theta_{1} & T_{1}(t) \\
T_{1}(t) & = T_{1}(t) \\
T_{1}(t) & = -T_{1}(t) + T_{1}(t) + T_{1}(t) \\
T_{1}(t) & = -K_{1}(t) + T_{1}(t) + K_{2}(t) \\
T_{1}(t) & = K_{2}(t) + T_{1}(t)
\end{array}$$

$$\theta_{2} = \int_{Z} \theta_{2}$$

$$= -T_{K_{2}} + T_{2}(+)$$

$$= -K_{2} \theta_{2} + T_{2}(+)$$

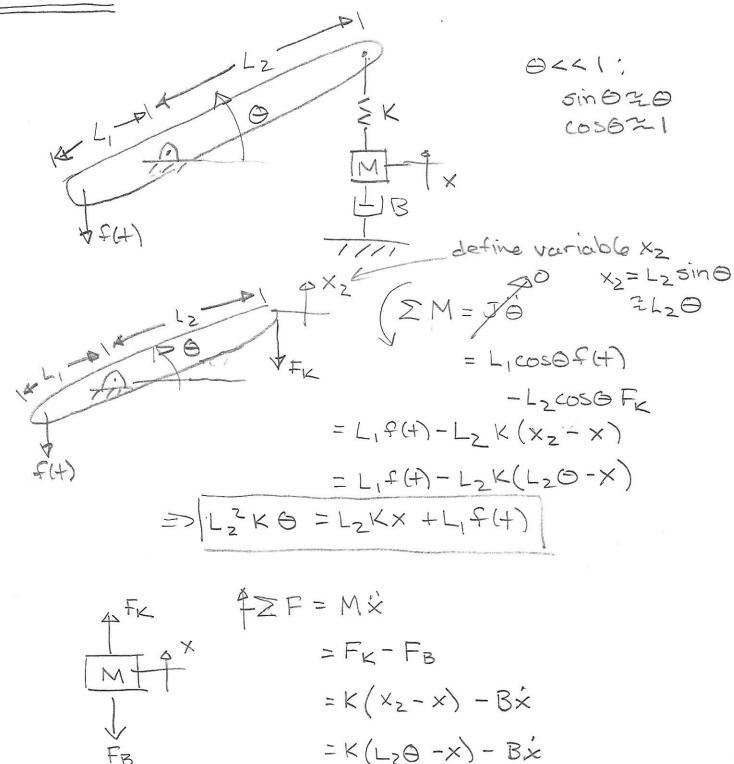
$$= -K_{2} \theta_{2} + T_{2}(+)$$

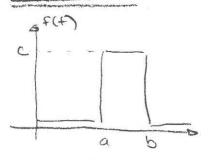
$$= \int_{Z} \theta_{2} + K_{2} \theta_{2} + T_{2}(+)$$

Problem 3

$$X_1$$
 X_2
 X_3
 X_4
 X_4
 X_5
 X_5

Problem 4





$$f(t) = c \cdot 1(t-a) - c \cdot 1(t-b)$$

$$J[f(t)] = c \cdot e^{-as} \cdot \frac{1}{s} - c \cdot e^{-bs} \cdot \frac{1}{s}$$

$$F(s) = \frac{c}{s} \left[e^{-as} - e^{-bs} \right]$$

$$f(t) = \frac{12/a^{2}}{a/2} + \frac{24}{6^{2}} \cdot 1(t - \frac{a}{2})$$

$$-\frac{12/a^{2}}{a/2} + 0 \cdot 1(t - a)$$

$$J[f(t)] = \frac{34}{0^{3}} \cdot \frac{1}{5^{2}} - \frac{24}{a^{2}} \cdot \frac{e^{-9/2}}{5} - \frac{24}{a^{3}} \cdot \frac{e^{-6}}{5^{2}}$$

$$F(s) = \frac{24}{a^{3}} \cdot \frac{1}{5^{2}} \left[1 - ase^{\frac{2}{2}s} - e^{-as} \right]$$

$$\frac{\lim_{\alpha \to 0} f(f(t))}{\int_{\alpha \to 0}^{2\pi} f(f(t))} = \frac{\lim_{\alpha \to 0}^{2\pi} f(f(t))}{\int_{\alpha \to 0}^{2\pi} f(f(t))} = \frac{\lim_{\alpha \to 0}^{2\pi}$$

Problem 7 B-2-10
$$2(s+2)$$
 $F(s) = s(s+1)(s+3)$

$$f(0^{\dagger}) = 0$$

(b) $f(\infty) = \frac{1}{5-00} = \frac{1}{5-00} = \frac{2(5+2)}{8(5+1)(5+3)}$
 $f(\infty) = \frac{4}{3}$

$$J[f(t)] = F(s)$$

$$J[f(t)] = SF(s) - f(o)$$

$$J[f(t)] = S^{2}F(s) - f(o) - f(o)$$

$$= s[s^{2}F(s)-sf(o)-f(o)] - f(o)$$

$$[J[f(+)]=s^{3}F(s)-s^{2}f(o)-f(o)]$$

=> 2nd order devicinivator:

In order, check

(3)
$$\frac{5}{\frac{5^2}{\omega_0^2} + \frac{235}{\omega_0} + 1}$$
) $\frac{(5^2 + \frac{235}{\omega_0^2} + 1)}{(\frac{5^2}{\omega_0^2} + \frac{235}{\omega_0} + 1)}$

check (5:

$$F(5) = \frac{5}{(5+1)^2 + 3^2}$$

$$= \frac{5+1}{(5+1)^2 + 3^2}$$

$$= \frac{1}{(5+1)^2 + 3^2}$$

$$= \frac{1}{(5+1)^2 + 3^2}$$

$$= \frac{1}{(5+1)^2 + 3^2}$$

$$= \frac{1}{(5+1)^2 + 3^2}$$

 $= \int f(t) = \frac{-2}{9}e^{-t} + \frac{8}{3}te^{-t} + \frac{2}{9}e^{-4t}$

Problem 10: 3-2-19

$$F(s) = \frac{2s+100}{(s+1)^2(s+u)} = \frac{4}{(s+1)} + \frac{8}{(s+1)^2} + \frac{6}{(s+1)^2}$$

$$A = \frac{d}{dt} \left(\frac{2s+10}{s+4} \right) \Big|_{s=-1} = \frac{(s+4)(s)-(2s+10)(s)}{(s+4)^2} \Big|_{s=-1} = \frac{-2}{9}$$

$$B = \frac{2s+100}{s+4} \Big|_{s=-1} = \frac{8}{3}$$

$$C = \frac{2s+100}{(s+1)^2} \Big|_{s=-4} = \frac{2}{9}$$

$$F(s) = \frac{-2}{9} \frac{1}{s+1} + \frac{8}{3} \frac{1}{(s+1)^2} + \frac{2}{9} \frac{1}{(s+4)}$$

Problem 11: B-2-22

$$\ddot{x} + Hx = 0$$
, $x(0) = 5$, $\dot{x}(0) = 0$

(a) $x(+) = x_c(+) + x_p(+)$
 $x_c(+) = x_c(+) + x_p(+)$
 $x_c(+) = x_c(+) + x_p(+)$
 $x_c(+) = x_c(+) = 0 \Rightarrow 0 = \pm 3i$
 $x_p(+) : f(+) = 0 \Rightarrow x_p(+) = 0$
 $x(+) = x_c(+) = c_1 \cos 2t + c_2 \sin 2t$
 $x_p(+) : f(+) = 0 \Rightarrow x_p(+) = 0$
 $x(+) = x_c(+) = c_1 \cos 2t + c_2 \sin 2t$
 $x_p(+) = x_c(+) = c_1 \cos 2t + c_2 \sin 2t$
 $x_p(+) = x_c(+) = c_1 \cos 2t + c_2 \sin 2t$
 $x_p(+) = x_c(+) = x_p(+) = 0$
 $x_p(+) = x_p(+) = x_p(+) = 0$

Problem 12: 8-2-24

$$2x + 2x + x = 1$$
; $x(0) = 0$, $x(0) = 2$

(6) $x(1) = x_{c}(1) + x_{p}(1)$
 $x_{c}(1) : D^{2} + 2D + 1 = 0$
 $x_{c}(1) : D^{2} + 2D + 1 = 0$
 $x_{c}(1) : D^{2} + 2D + 1 = 0$
 $x_{c}(1) : D^{2} + 2D + 1 = 0$
 $x_{c}(1) : D^{2} + 2D + 1 = 0$
 $x_{c}(1) : x(1) = e^{\frac{1}{2}t} \left[C_{1}\cos\frac{t}{2} + C_{2}\sin\frac{t}{2} \right]$
 $x_{p}(1) : f(1) = 1 = 0 : x_{p}(1) = A$
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 $x_{p}(1) : f(1) :$

Problem 8 ((ant'd) (b) (cont'd)

$$X(s) = \frac{1}{s} - \frac{s+1}{(s+\frac{1}{2})^2 + (\frac{1}{2})^2} + \frac{2}{(s+\frac{1}{2})^2 + (\frac{1}{2})^2}$$

$$= \frac{1}{s} - \frac{s+\frac{1}{2}}{(s+\frac{1}{2})^2 + (\frac{1}{2})^2} + 3\frac{\frac{1}{2}}{(s+\frac{1}{2})^2 + (\frac{1}{2})^2}$$

$$|x(t) = 1 - e^{-\frac{1}{2}}(os\frac{1}{2} + 3e^{-\frac{1}{2}}sin\frac{1}{2})$$