

U-Boot from Scratch

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FOSDEM - 2019

Jagan Teki

- → JagannadhaSutradharudu Teki
- → Enthusiastic Linux kernel hacker
- → U-Boot Maintainer for SPI, SPI-FLASH, Allwinner sunXi SoC
- → Buildroot, Yocto contributor
- → Heading to Amarula Solutions India

Agenda

- → U-Boot, In a NutShell
- → Image boot
- → Features
- → Port new hardware
- → Future plans



U-Boot, In a NutShell

- → History
- → Community
- → Hardware support
- → U-Boot
- → Source
- → Source tree
- → Build process
- → Boot Sequence
- → Loading sources
- → Debug
- → Tools
- → Testing

History

- → 8xxROM written by Magnus Damm
- → October 1999 Wolfgang Denk moved to sourceForge.net and as PPCBoot
- → PPCBoot-0.4.1 released in July 19, 2000
- → PPCBoot-2.0.0 became U-Boot-0.1.0 with x86
- → Since then added many architectures, boards, features etc.
- → Current name is termed as Das U-Boot
- → Flexible and opensource bootloader
- → Wolfgang Denk as head custodian for over 10 years
- → Tom Rini as head custodian since September 2012
- → Recent release v2019.01

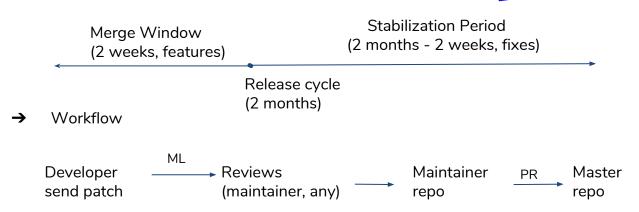
Community

- → On average over 25+ employers and 120+ developers contributing every release
- → Number of talks on various conferences

Development process:

- → 35+ Custodian/Maintainer for various subsystems
- → Release cycle

Note: RC now changed to 3 months, with 3 weeks MW



Hardware support

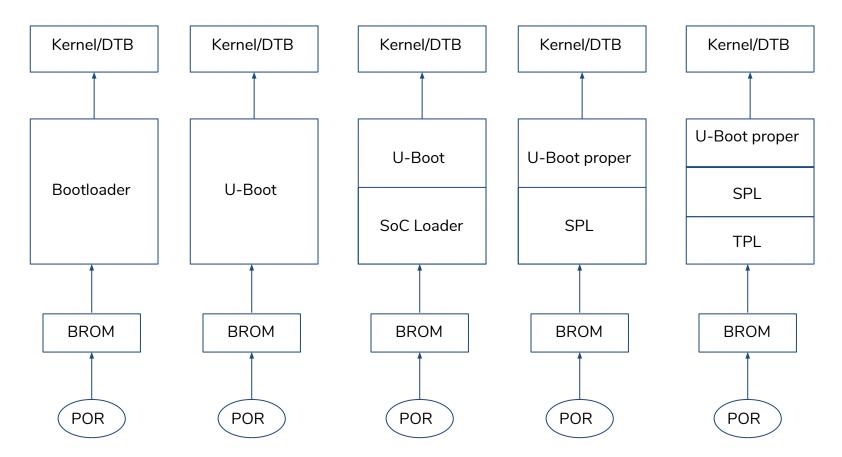
Architecture/SoC:

- → ARM
 - ♦ 32-bit: Aspeed, Altera, Allwinner, Atmel, Broadcom, Qemu, Qualcomm, Marvell, NXP, Rockchip, STM32, Tegra, Tl, UniPhier, Xilinx
 - 64-bit: Allwinner, Marvell, NXP, Rockchip, Tegra, UniPhier, Xilinx
- → X86 (Baytrail, Broadwell, Quark, etc)
- → ARC, M68K, MicroBlaze, MIPS, NDS32, NIOS2, PowerPC, RISCV, Sandbox, SuperH, Xtensa

Boards:

- → 186+ different board vendors
- → 1083+ different boards

U-Boot



U-Boot build

- → Git master or dev tree at http://qit.denx.de/?p=u-boot.qit;a=summary
- Custodian's or Maintainers tree at http://git.denx.de/?p=u-boot.git;a=forks

Example of building vyasa RK3288 board, which is ARM platform with arm-linux-gnueabi

- 1. \$ git clone git://git.denx.de/u-boot.git
- 2. \$ u-boot
- 3. \$ export ARCH=arm
- 4. \$ export CROSS_COMPILE=arm-linux-gnueabi-
- 5. \$ make vyasa-rk3288_defconfig
- 6. \$ make

U-Boot tree

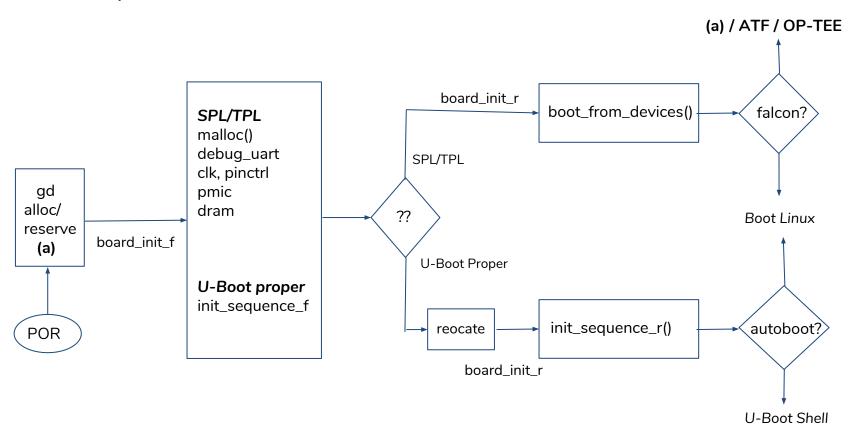
 \rightarrow Arch - Architecture specific code - foo CPU specific code arch/foo arch/foo/mach-joo - joo MACHINE specific code arch/foo/dts - foo devicetree code - board specific code board cmd - commands \rightarrow common - common code common/spl - SPL code configs - per board configuration \rightarrow disk - disk or partition \rightarrow - documentation doc \rightarrow drivers - drivers code - environment env \rightarrow fs - filesystems - Networking \rightarrow net - Kbuild scripts \rightarrow Kbuild - Global kconfig file \rightarrow Kconfig Makefile - Global makefile \rightarrow \rightarrow scripts, tools - build script, etc

Build process

| 1. | scripts/kconfig/confsyncconfig Kconfig | |
|-----|--|---|
| 2. | CHK | include/config.h |
| 3. | UPD | include/config.h |
| 4. | CFG | u-boot.cfg |
| 5. | GEN | include/autoconf.mk |
| 6. | GEN | include/autoconf.mk.dep |
| 7. | CFG | spl/u-boot.cfg |
| 8. | GEN | spl/include/autoconf.mk |
| 9. | CFG | tpl/u-boot.cfg |
| 10. | GEN | tpl/include/autoconf.mk |
| 11. | CHK | include/config/uboot.release |
| 12. | UPD | include/config/uboot.release |
| 13. | CHK | include/generated/version_autogenerated.h |
| 14. | UPD | include/generated/version_autogenerated.h |
| 15. | CHK | include/generated/timestamp_autogenerated.h |
| 16. | | |
| 17. | LD | arch/arm/cpu/built-in.o |
| 18. | CC | arch/arm/cpu/armv7/cache_v7.o |
| 19. | AS | arch/arm/cpu/armv7/cache_v7_asm.o |
| 20. | CC | arch/arm/cpu/armv7/cpu.o |
| 21. | CC | arch/arm/cpu/armv7/cp15.o |
| 22. | CC | arch/arm/cpu/armv7/syslib.o |
| 23. | AS | arch/arm/cpu/armv7/sctlr.o |
| 24. | AS | arch/arm/cpu/armv7/lowlevel_init.o |
| 25. | LD | arch/arm/cpu/armv7/built-in.o |
| 26. | AS | arch/arm/cpu/armv7/start.o |
| 27. | CC | arch/arm/lib/eabi_compat.o |
| 28. | AS | arch/arm/lib/crt0_arm_efi.o |
| 29. | CC | arch/arm/lib/reloc_arm_efi.o |
| 30. | CC | arch/arm/mach-rockchip/boot_mode.o |
| 31. | CC | arch/arm/mach-rockchip/rk3288-board.o |
| 32. | CC | arch/arm/mach-rockchip/sdram_common.o |
| 33. | CC | arch/arm/mach-rockchip/rk_timer.o |
| 34. | CC | arch/arm/mach-rockchip/rk3288/clk_rk3288.o |
| 35. | CC | arch/arm/mach-rockchip/rk3288/rk3288.o |
| 36. | CC | arch/arm/mach-rockchip/rk3288/syscon_rk3288.o |
| 37. | CC | board/amarula/vyasa-rk3288/vyasa-rk3288.o |

```
spl/arch/arm/mach-rockchip/sdram_common.o
 1.
         CC
 2.
         CC
                  spl/arch/arm/mach-rockchip/rk timer.o
         CC
                  spl/arch/arm/mach-rockchip/rk3288/clk_rk3288.o
 3.
 4.
         CC
                  spl/arch/arm/mach-rockchip/rk3288/rk3288.o
 5.
         CC
                  spl/arch/arm/mach-rockchip/rk3288/syscon_rk3288.o
 6.
         CC
                  spl/arch/arm/mach-rockchip/bootrom.o
         CC
                  spl/arch/arm/mach-rockchip/rk3288-board-spl.o
 7.
                  spl/arch/arm/cpu/armv7/cache_v7.o
 8.
         CC
         CC
                  spl/arch/arm/cpu/armv7/cpu.o
 9.
10.
         AS
                  spl/arch/arm/cpu/armv7/lowlevel_init.o
11.
                  spl/arch/arm/cpu/armv7/start.o
         AS
12.
         ΙD
                  spl/u-boot-spl
13.
         OBJCOPY spl/u-boot-spl-nodtb.bin
14.
         COPY
                  spl/u-boot-spl.dtb
15.
         CAT
                  spl/u-boot-spl-dtb.bin
16.
         COPY
                  spl/u-boot-spl.bin
17.
         CC
18.
                  tpl/arch/arm/mach-rockchip/sdram_common.o
         CC
19.
                  tpl/arch/arm/mach-rockchip/rk_timer.o
20.
         CC
                  tpl/arch/arm/mach-rockchip/rk3288/clk rk3288.o
         CC
21.
                  tpl/arch/arm/mach-rockchip/rk3288/rk3288.o
22.
         CC
                  tpl/arch/arm/mach-rockchip/rk3288/svscon_rk3288.o
         CC
                  tpl/arch/arm/mach-rockchip/bootrom.o
23.
24.
         CC
                  tpl/arch/arm/mach-rockchip/rk3288-board-tpl.o
25.
         CC
                  tpl/arch/arm/cpu/armv7/cache v7.o
                  tpl/arch/arm/cpu/armv7/cache_v7_asm.o
26.
         AS
         CC
                  tpl/arch/arm/cpu/armv7/cpu.o
27.
         CC
                  tpl/arch/arm/cpu/armv7/cp15.o
28.
29.
         CC
                  tpl/arch/arm/cpu/armv7/svslib.o
30.
         AS
                  tpl/arch/arm/cpu/armv7/lowlevel_init.o
31.
         AS
                  tpl/arch/arm/cpu/armv7/start.o
32.
         LDS
                  tpl/u-boot-spl.lds
33.
                  tpl/u-boot-tpl
         ΙD
34.
         OBJCOPY tpl/u-boot-tpl-nodtb.bin
35.
         COPY
                  tpl/u-boot-tpl.bin
36.
                  u-boot.dtb
         COPY
37.
         MKIMAGE u-boot-dtb.img
```

U-Boot Sequence



Loading sources

- → U-Boot can support variety of loading sources
- → RAM
- → Network: tftp, DHCP
- → Serial: Kermit
- → SPI Flash
- → MMC
- → Parallel NOR
- → NAND, UBI
- → USB
- → SATA
- → AHCI
- → NVME

Debug

- → printf
- → CONFIG_DEBUG
- → GDB
- → Early UART (CONFIG_DEBUG_UART)

```
#include <debug_uart.h>
static inline void _debug_uart_init(void)
    _mxc_serial_init(base);
static inline void _debug_uart_putc(int ch)
    while (!(readl(&base->ts) & UTS_TXEMPTY))
      WATCHDOG_RESET();
    writel(ch, &base->txd);
DEBUG_UART_FUNCS
debug_uart_init();
printch('T');
printch('P');
printch('L');
```

Tools

- → Patman
 - Manual patch creation, cover-letter, adding maintainers etc can be error-prone.
 - Patman make above automated
 - ◆ Create patch, insert cover-letter, add maintainer (via ~/.git-mailrc), run checkpatch.pl etc
 - How to use? tools/patman/README
- → Buildman
 - U-Boot builder for multiple commits, branches etc.
 - Replaced by legacy MAKEALL
 - Understandable output summary
 - Checking image sizes
 - ◆ tools/buildman/README
- → Binman
 - Packaging multiple image components

```
binman {
      filename = "u-boot-sunxi-with-spl.bin";
      pad-byte = <0xff>;
      blob {
            filename = "spl/sunxi-spl.bin";
      };
      u-boot-img {
            offset = <CONFIG SPL PAD TO>;
      };
    };
};
```

Testing

- → travis-ci.org
 - ◆ Automated build environment, with limited run-time, free to use
 - ◆ May take longer duration, if more jobs are initiated
 - travis.yml, u-boot travis build plugin
- → test.py
 - Pytest framework
 - ♦ Works for sandbox, qemu, some real hardware
 - Sanity tests for dm code
 - doc/README.trace
- → trace
 - ◆ Kind of Linux ftrace
 - ♦ Collect execution and sent to host for analysis
- → tbot
 - ♦ Execute test cases on boards
 - ♦ Heiko Schocher demo, https://www.youtube.com/watch?v=zfjpj3DLsx4

Image Boot

- → Legacy image
- → FIT
- → Verified image
- → ARM64 ATF
- → OP-TEE
- → Secure boot
- → Falcon mode
- → EFI boot
- → Distro boot

Legacy Image

- Fixed offset images standalone, \rightarrow zlmage binaries
- go addr [arg ...]
- u-boot Image format \rightarrow
- Single component ulmage
- Monolithic, combination of images
- bootm [addr [arg ...]] \rightarrow

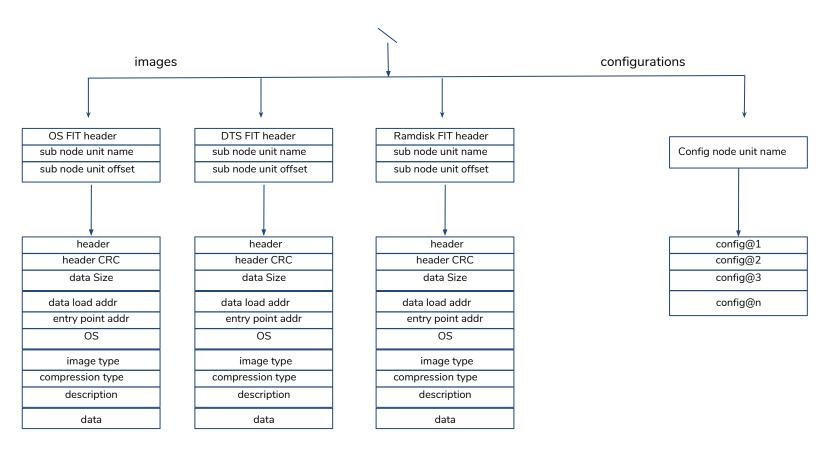
? Not flexible, indexing

? No hash integrity

? No scope of security addition

```
1 $ mkimage \
     > -A arm \
     > -0 linux \
     > -T kernel \
     > -a 0x10008000 \
     > -e 0x10008000 \
     > -n "Linux-4.19.0-rc2" \
     > -d zImage uImage
 9 Image Name:
                 Linux-4.19.0-rc2-next-20180905-0
10 Created:
                 Tue Sep 11 23:07:55 2018
11 Image Type: ARM Linux Kernel Image (uncompressed)
12 Data Size:
                 8372992 Bytes = 8176.75 kB = 7.99 MB
13 Load Address: 10008000
14 Entry Point: 10008000
16
17 $ mkimage
18 > - A arm \
19 > -0 linux \
20 > - T multi \
21 > -a 0 \times 10008000 
22 > -e 0x10008000 \
23 > -n 'Multi image' \
24 > -d vmlinux.bin.qz:ramdisk.image.qz:imx6q-icore-rqs.dtb uMulti
25 Image Name: Multi image
26 Created:
                 Tue Sep 11 23:07:55 2018
27 Image Type: ARM Linux Multi-File Image (gzip compressed)
28 Data Size:
                 82092755 Bytes = 80168.71 KiB = 78.29 MiB
29 Load Address: 10008000
30 Entry Point: 10008000
31 Contents:
      Image 0: 7609333 Bytes = 7430.99 KiB = 7.26 MiB
33
      Image 1: 74445331 Bytes = 72700.52 KiB = 71.00 MiB
34
35
      Image 2: 38071 Bytes = 37.18 KiB = 0.04 MiB
```

FIT (Flattened ulmage Tree)



FIT, contd

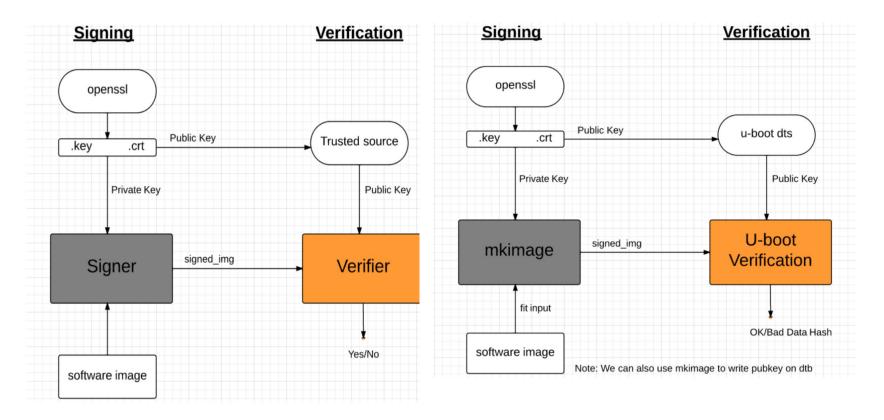
```
1/dts-v1/:
 2/{
        description = "FIT with single Linux kernel and FDT blob";
5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 11 12 22 23 24 25 6 27 28 29 30 1 32 33 34 40 44 45 47 44 45 };
        #address-cells = <1>:
        images {
             kernel@1 {
                  description = "i.MX6 Linux kernel";
                 data = /incbin/("./vmlinux.bin.qz");
                 type = "kernel";
                 arch = "arm";
                 os = "linux";
                 compression = "azip":
                 load = <0 \times 10008000>;
                 entrv = <0x10008000>;
                 hash@1 {
                      algo = "md5";
                 hash@2 {
                      algo = "sha1";
             1;
                  description = "Engicam i.CoreM6 Quad/Dual RQS Starter Kit Devicetree blob";
                  data = /incbin/("./imx6q-icore-rqs.dtb");
                 type = "flat dt";
                 arch = "arm";
                 compression = "none":
                 hash@1 {
                      algo = "md5";
                  hash@2 {
                      algo = "sha1";
                 };
            };
        };
        configurations {
             default = "conf@1";
             conf@1 {
                  description = "Boot Linux kernel with FDT blob":
                  kernel = "kernel@1";
                  fdt = "fdt@1";
```

```
1 icorem6qdl-rqs> fatload mmc 0:1 $loadaddr fit.itb
 2 reading fit.itb
 3 6167494 bytes read in 335 ms (17.6 MiB/s)
 4 icorem6qdl-rqs> bootm $loadaddr
 5 Booting FIT image from mmc ...
 6 ## Loading kernel from FIT Image at 12000000 ...
     Using 'conf@1' configuration
     Verifying Hash Integrity ... OK
     Trying 'kernel@1' kernel subimage
       Description: i.MX6 Linux kernel
11
       Type:
                     Kernel Image
12
       Compression: gzip compressed
13
       Data Start: 0x120000f0
14
                     6130148 Bytes = 5.8 MiB
       Data Size:
15
       Architecture: ARM
16
       05:
                     Linux
17
       Load Address: 0x10008000
       Entry Point: 0x10008000
       Hash algo:
                     md5
       Hash value:
                     b975a202ea2963c53c53f527329930cd
21
       Hash algo:
                     sha1
       Hash value: 78b93fe404b795de8c837af27d67f4df9b96083a
     Verifying Hash Integrity ... md5+ sha1+ OK
24 ## Loading fdt from FIT Image at 12000000 ...
     Using 'conf@1' configuration
26
     Trving 'fdt@l' fdt subimage
27
       Description: Engicam i.CoreM6 Quad/Dual RQS Starter Kit Devicetree blob
28
       Type:
                     Flat Device Tree
29
       Compression: uncompressed
                     0x125d8dbc
       Data Start:
31
32
       Data Size:
                     35298 Bytes = 34.5 KiB
       Architecture: ARM
       Hash algo:
34
       Hash value: 4371a4dfe55127c2fda8a9feb4d3b313
35
       Hash algo:
                     sha1
       Hash value: e34a9326b5e7fd43557753ef980fe67326f82ea1
     Verifying Hash Integrity ... md5+ sha1+ OK
     Booting using the fdt blob at 0x125d8dbc
     Uncompressing Kernel Image ... OK
     Using Device Tree in place at 125d8dbc, end 125e479d
42 Starting kernel ...
```

FIT Complexity?



Verified boot



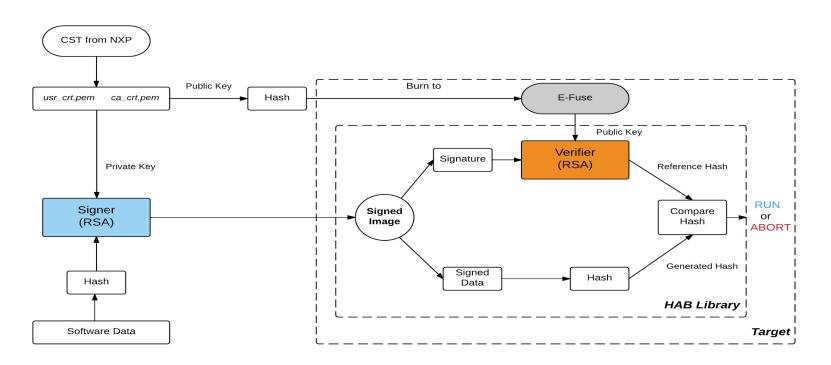
Secure boot, Signed

Signing

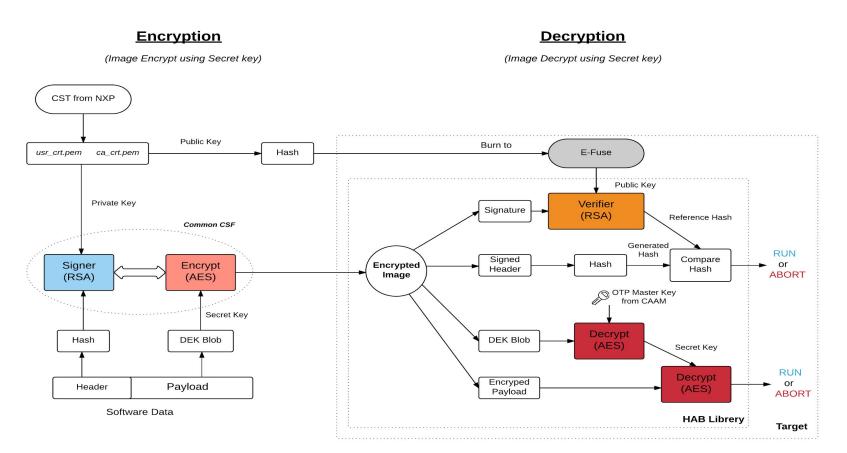
Verification

(Image Signing using Private key)

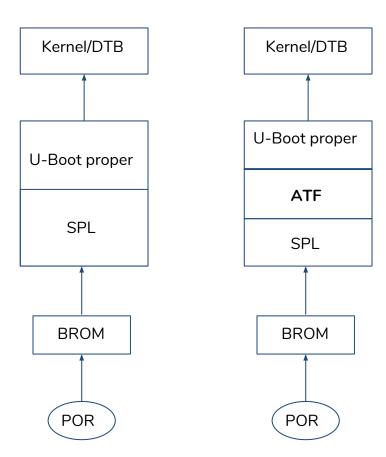
(Image Verify/authenticate using Public key)



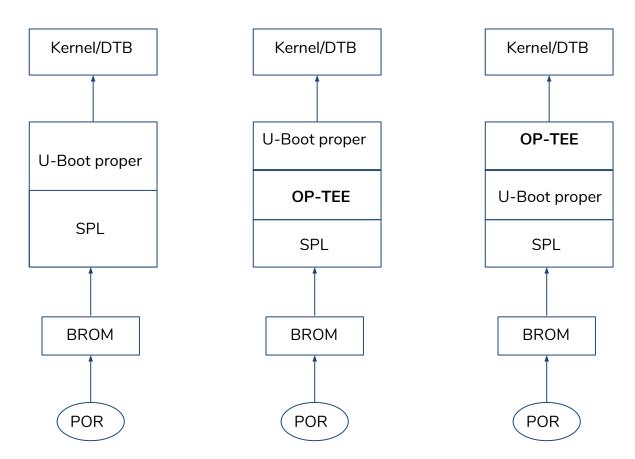
Secure boot, Encrypted



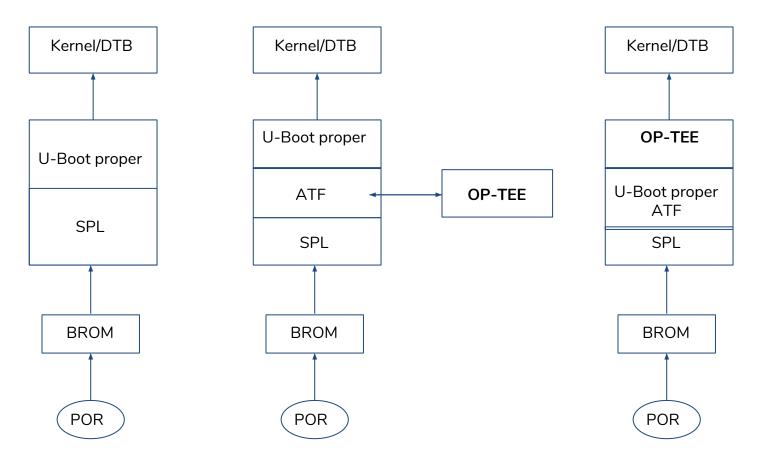
ATF



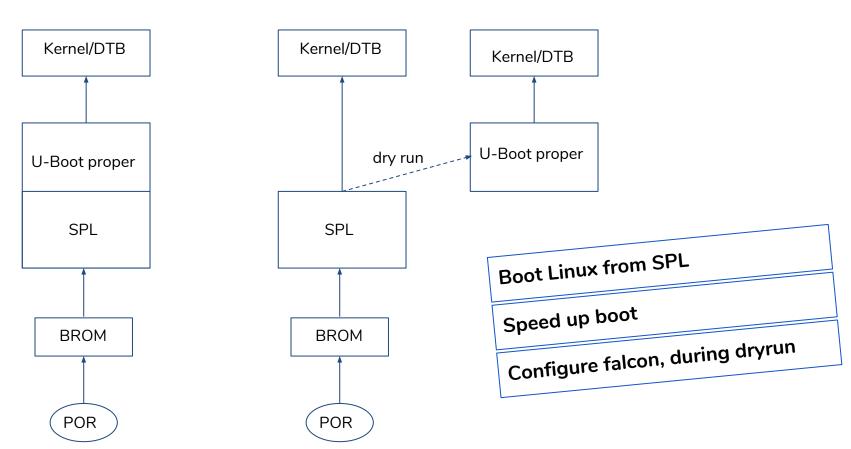
OP-TEE, ARMv7



OP-TEE, ARMv8



Falcon mode



Falcon, is useful?

[4.596400 2.968808] Starting logging: OK

[4.622379 0.012163] Starting network: OK

[4.748163 0.001834] Welcome to <u>VYASA</u> RK3288! [4.750725 0.002562] vyasa-rk3288 login:

[4.746329 0.123950]

[4.610216 0.013816] Initializing random number generator... done.

```
[0.001344 0.001342] U-Boot TPL 2017.09-rc2-13373-q2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.005975 0.004631] Trying to boot from BOOTROM
[0.008394 0.002419] Returning to boot ROM...
[0.216735 0.208341]
[0.217195 0.000460] U-Boot SPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.223097 0.005902] Trying to boot from MMC1[0.262093 0.038996] Expected Linux image is not found. Trying to start U-boot
[0.436129 0.174036]
[0.436416 0.000287]
[0.436696 0.000280] U-Boot 2017.09-rc2-13373-q2cffd0d-dirty (Aug 31 2017 - 20:41:14 +0530)
[0.442273 0.005577][0.442369 0.000096] Model: Amarula Vvasa-RK3288
                                                                                                [0.001135 0.001134] U-Boot TPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.444854 0.002485] DRAM: 2 GiB
[0.479422 0.034568] MMC: dwmmc@ff0c0000: 1
                                                                                                [0.005690 0.004555] Trying to boot from BOOTROM
[0.627295 0.147873] *** Warning - bad CRC, using default environment
[0.631527 0.004232]
                                                                                                [0.008221 0.002531] Returning to boot ROM...
[0.635980 0.004453] In:
                          serial@ff690000
[0.637982 0.002002] Out: serial@ff690000
[0.640004 0.002022] Err: serial@ff690000
                                                                                                [0.196488 0.188267]
[0.642244 0.002240] Model: Amarula Vvasa-RK3288
[0.644783 0.002539] Net: Net Initialization Skipped
                                                                                                [0.196704 0.000216] U-Boot SPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.647824 0.003041] No ethernet found.
[0.651954 0.004130] Hit any key to stop autoboot: 0
                                                                                                [0.202759 0.006055] Trying to boot from MMC1
[0.772503 0.120549] switch to partitions #0, OK
[0.774802 0.002299] mmcl is current device
[1.069762 0.294960] Scanning mmc 1:1...
                                                                                                [1.879613 1.676854] [ 0.090151] dmi: Firmware registration failed.
[1.312386 0.242624] Found /boot/extlinux/extlinux.conf
[1.315209 0.002823] Retrieving file: /boot/extlinux/extlinux.conf
                                                                                                [2.287880 0.408267] [ 0.645755] EXT4-fs (mmcblk0p1): couldn't mount as ext3 due to feature incompatibilities
[1.353460 0.038251] 145 bytes read in 28 ms (4.9 KiB/s)
[1.356412 0.002952] 1: Vyasa Linux-4.13
[1.358237 0.001825] Retrieving file: /boot/uImage
                                                                                                [2.301935 0.014055] [ 0.660209] EXT4-fs (mmcblk0p1): couldn't mount as ext2 due to feature incompatibilities
[1.740753 0.382516] 7836344 bytes read in 375 ms (19.9 MiB/s)
[1.744302 0.003549] append: console=ttvS2.115200n8 root=/dev/mmcblk0p1 rootwait guiet
                                                                                                [2.425052 0.123117] Starting logging: OK
[1.750086 0.005784] Retrieving file: /boot/rk3288-vyasa.dtb
[1.786952 0.036866] 36291 bytes read in 28 ms (1.2 MiB/s)
                                                                                                [2.440868 0.015816] Initializing random number generator... done.
[1.789950 0.002998] ## Booting kernel from Legacy Image at 02000000 ...
[1.794524 0.004574] Image Name: Linux-4.13.0-rc4-next-20170810-0
                                                                                                [2.452302 0.011434] Starting network: OK
[1.799040 0.004516]
                     Image Type: ARM Linux Kernel Image (uncompressed)
[1.803818 0.004778]
                     Data Size:
                                   7836280 Bytes = 7.5 MiB
[1.807426 0.003608]
                     Load Address: 02000000
                                                                                                [2.580451 0.128149]
[1.809776 0.002350]
                     Entry Point: 02000000
[1.812097 0.002321]
                     Verifying Checksum ... OK
                                                                                                [2.584354 0.003903] Welcome to VYASA RK3288!
[1.945372 0.133275] ## Flattened Device Tree blob at 01f00000
[1.948106 0.002734]
                     Booting using the fdt blob at 0x1f00000
                     Loading Kernel Image ... OK
                                                                                                [2.586697 0.002343] vyasa-rk3288 login:
[1.951715 0.003609]
[1.968363 0.016648]
                     Loading Device Tree to Offf4000, end Offffdc2 ... OK
[1.974709 0.006346]
[1.974911 0.000202] Starting kernel ...
[0.002243 0.002243]
[1.273396 1.271153] [
                       0.090111] dmi: Firmware registration failed.
```

0.581926| EXT4-fs (mmcblk0p1): couldn't mount as ext3 due to feature incompatibilities

[1.627592 0.009711] [0.592177] EXT4-fs (mmcblk0p1): couldn't mount as ext2 due to feature incompatibilities

EFI boot

- → Most of AArch64 and x86 UEFI is default booting system.
- → U-Boot support via EFI_LOADER, CMD_BOOTEFI configs.

```
=> load mmc 0:2 ${fdt_addr_r} boot/dtb
29830 bytes read in 14 ms (2 MiB/s)
=> load mmc 0:1 ${kernel_addr_r} efi/debian/grubaa64.efi
reading efi/debian/grubaa64.efi
120832 bytes read in 7 ms (16.5 MiB/s)
=> bootefi ${kernel_addr_r} ${fdt_addr_r}
```

doc/README.uefi

ELCE 2017: Marrying U-Boot, UEFI and grub, Alexander Graf

Distro boot

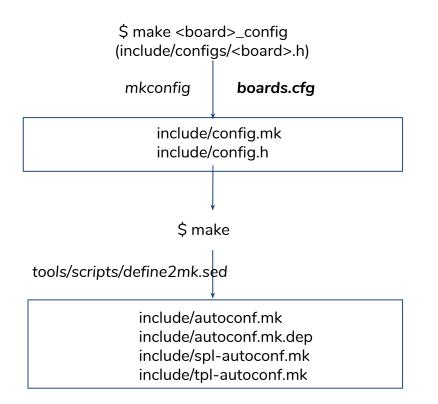
- → bootargs system boot environment commands
- → board-specific logic with respect to storage mechanism
- → DISTRO_DEFAULTS, generic distribution configuration

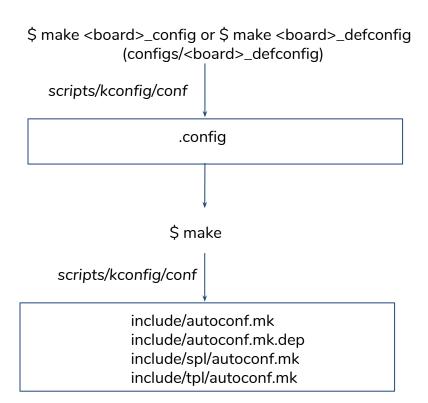
```
# u-boot, extlinux.conf
label linux-5.0.0-rc3
  kernel /Image
  devicetree /sun50i-a64-amarula-relic.dtb
  append console=ttyS0,115200 earlyprintk root=/dev/mmcblk0p2 rootwait rw
```

U-Boot Features

- → Kconfig
- → FDT
- → OF livetree
- → FDT Overlay
- → Driver model
- → OF platdata
- → DFU

Kconfig





FDT (Flat Device Tree)

- → Run-time hardware configuration
- → Single U-Boot binary for multiple boards (with board controlled dts)
- → Handle via libfdt
- → Enabled via CONFIG_OF_CONTROL
- → FDT supported U-Boot can build
 - ◆ with default dts, CONFIG_DEFAULT_DEVICE_TREE=<dts-file-name> in defconfig
 - \$ make
 - with user-specified dts
 - \$ make DEVICE_TREE=<dts-file-name>
- → Sample, UniPhier Pro4 reference, Pro4 Ace, Pro4 Sanji boards
 - \$ make uniphier_v7_defconfig (single configuration)
 - ♦ \$ make DEVICE_TREE=uniphier-pro4-ref
 - ♦ \$ make DEVICE_TREE=uniphier-pro4-ace
 - \$ make DEVICE_TREE=uniphier-pro4-sanji
- → DTB packing during build
 - ◆ CONFIG_OF_EMBED
 - ◆ CONFIG_OF_SEPARATE

FDT, u-boot

- → Maintain U-Boot specific node definitions in separate file
- → Useful for DT allocation in SPL
- → u-boot,dm-pre-alloc, u-boot,dm-spl

```
arch/arm/dts/imx6qdl-u-boot.dtsi */
     soc {
                 u-boot,dm-spl;
                 aips-bus@02000000 {
                      u-boot,dm-spl;
                 };
      };
};
&gpio1 {
     u-boot,dm-spl;
};
```

FDT, libfdt

```
1 int fdt delprop(void *fdt, int nodeoffset, const char *name)
2 {
3
          struct fdt property *prop;
          int len, proplen;
5
6
7
8
9
10
11
12
13
                                                                        ? add/update, copy large amount
          FDT RW CHECK HEADER(fdt);
          prop = fdt get property w(fdt, nodeoffset, name, &len);
          if (!prop)
                                                                          ? tree need to rebuilt
                  return len;
          proplen = sizeof(*prop) + FDT TAGALIGN(len);
                                                                           ? tree traversing is slow
          return fdt splice struct (fdt, prop, proplen, 0);
14 }
15
16 int ft board setup(void *blob, bd t *bd)
17 {
18
          int nodeoffset;
19
20
21
22
23 }
          nodeoffset = fdt path offset(blob, "/soc/aips-bus@02100000/usdhc@02198000");
          return fdt delprop(blob, nodeoffset, "no-1-8-v");
```

Livetree (Live Device Tree)

- → Pointer-based hierarchical structures
- → Support after relocation
- → ofnode, point to either flat tree or livetree
- → Enabled via CONFIG_OF_LIVE

```
static int zyng spi ofdata to platdata(struct udevice *bus)
     struct zynq spi platdata *plat = bus->platdata;
     plat->regs = (struct zynq_spi_regs *)devfdt_get_addr(bus);
     plat->frequency = fdtdec_get_int(blob, node, "spi-max-frequency",
250000000);
     /* new code */
     plat->regs = (struct zynq_spi_regs *)dev_read_addr(bus);
     plat->frequency = dev read u32 default(bus, "spi-max-frequency", 2500000000);
    return 0;
```

FDT Overlay

- → DTO, enable centralize DTB to be overlaid on the device tree.
- → Single image of multitude of similar boards and their expansion options
- → HAT Rasberry PI, Tinker board
- → DTO can load U-Boot via
 - ◆ FIT image
 - Manual load



```
/dts-v1/;
   images {
         kernel {
                 data = /incbin/("./zImage");
                 type = "kernel";
                 load = <0 \times 100800000>;
                 entry = <0x10080000>;
         fdt-1 {
                 data = /incbin/("./imx6q-icore.dtb");
                 type = "flat_dt";
         fdt-2 {
                 data = /incbin/("./imx6q-icore-mipi.dtb");
                 type = "flat_dt";
         configurations {
                 default = "imx6q-icore.dtb";
                 imx6q-icore.dtb {
                         kernel = "kernel";
                         fdt = "fdt-1";
                 imx6q-icore-mipi.dtb {
                         kernel = "kernel";
                         fdt = "fdt-2";
```

FDT Overlay, loading

```
/* via FIT */
=> bootm $loadaddr#imx6q-icore.dtb#imx6q-icore-mipi
/* Manual load */
=> setenv fdt addr 0x18000000
=> setenv fdt ovaddr 0x180c0000
=> load mmc 0:1 ${fdt addr} ${bootdir}/base.dtb
=> load mmc 0:1 ${fdt ovaddr} ${bootdir}/overlay.dtb
=> fdt resize 8192
=> fdt apply $fdt_ovaddr
=> bootm ${loadaddr} - ${fdt addr}
```

U-Boot Driver model

- → Driver model
- → DM, CPU
- → DM, Power
- → DM, Core
- → DM, Peripherals
- → Block layer
- → USB layer

Driver model

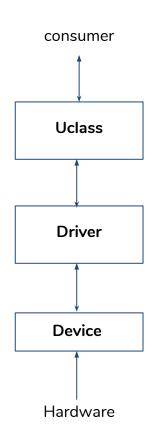
? ad-hoc model, direct functions call ? multiple controllers can't fit same driver

? not scalable, difficult to maintain

Simple, scalable, modular, homogeneous

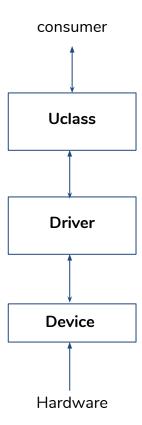
Lazy initialization, but bounded

Small overhead, SPL

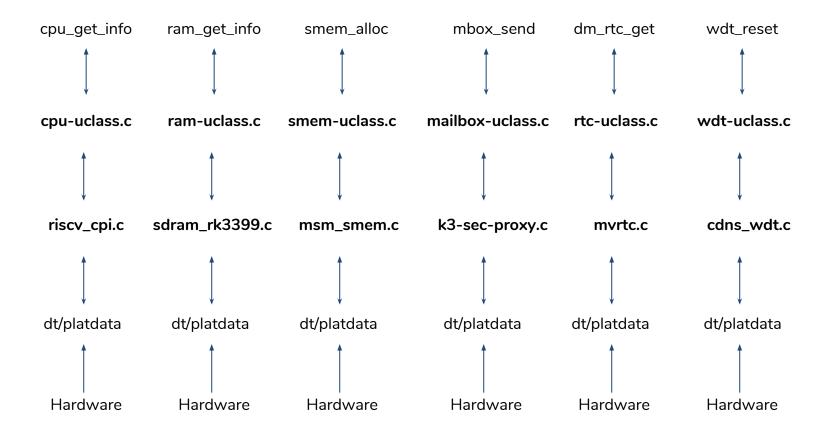


```
=> dm tree
Class
         index Probed Driver
                                   Name
root
            0 [ + ]
                      root drive root driver
clk
                      fixed rate |-- oscillator
                      rockchip r | -- dwmmc@ff0c0000
            0 [ + ]
mmc
blk
              _[ + ]
                      mmc blk
                                      `-- dwmmc@ff0c0000.blk
            1 [+]
                      rockchip_r |-- dwmmc@ff0f0000
mmc
blk
                      mmc blk
                                      `-- dwmmc@ff0f0000.blk
serial
            0 [ + ]
                      ns16550 se |-- serial@ff690000
eth
                      gmac rockc | -- ethernet@ff290000
usb
                      dwc2 usb
                                  |-- usb@ff540000
                      dwc2_usb | -- usb@ff580000
usb
                      rockchip_r |-- dmc@ff610000
ram
                      i2c rockch |-- i2c@ff650000
i2c
                      rk8xx pmic
                                      `-- pmic@1b
pmic
regulator
                      rk8xx buck
                                          -- DCDC REG1
                      rk8xx buck
regulator
                                          -- DCDC REG2
regulator
                      rk8xx buck
                                          |-- DCDC REG3
regulator
                      rk8xx buck
                                          |-- DCDC REG4
regulator
                      rk8xx ldo
                                          -- LDO REG1
```

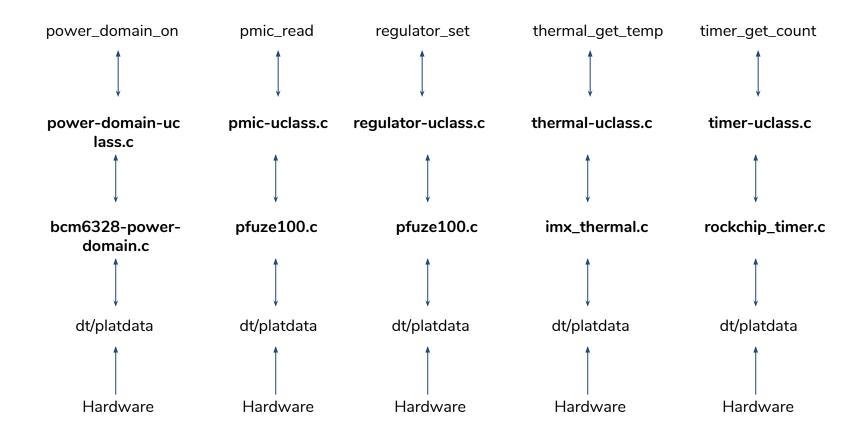
Driver model



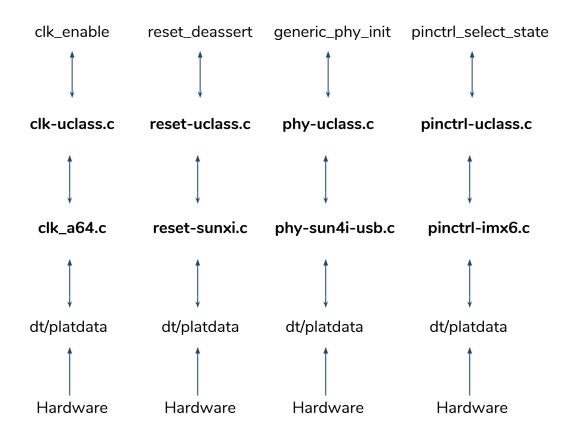
DM, CPU



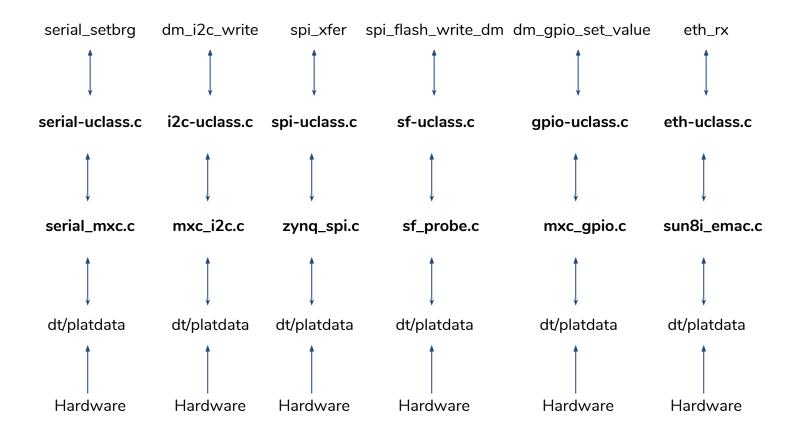
DM, Power



DM, Core



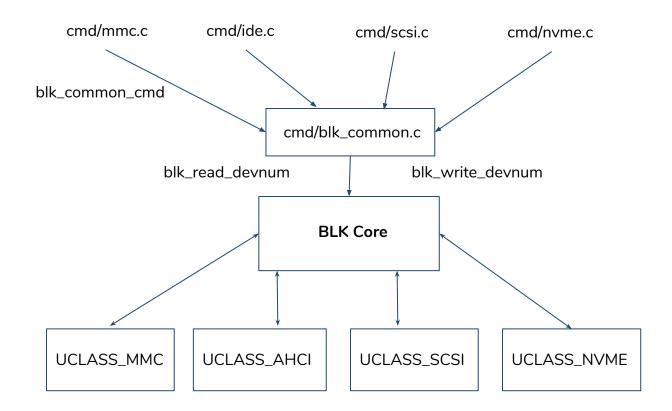
DM, Peripherals



```
UCLASS_DRIVER(spi) = {
     .id
         = UCLASS_SPI,
     .name
                    = "spi",
     .flags = DM_UC_FLAG_SEQ_ALIAS,
     .post bind = dm scan fdt dev,
     .post_probe = spi_post_probe,
     .child pre probe = spi child pre probe,
     .per device auto alloc size = sizeof(struct dm spi bus),
     .per child auto alloc size = sizeof(struct spi slave),
     .per child platdata_auto_alloc_size = sizeof(struct dm_spi_slave_platdata),
     .child post bind = spi child post bind,
};
U BOOT DRIVER(zyng qspi) = {
     .name = "zynq qspi",
     .id = UCLASS SPI,
     .of_match = zynq_qspi_ids,
     .ops = &zynq_qspi_ops,
     .ofdata to platdata = zynq_qspi_ofdata_to_platdata,
     .platdata auto alloc size = sizeof(struct zyng qspi platdata),
     .priv auto alloc_size = sizeof(struct zynq qspi_priv),
     .probe = zynq qspi probe,
};
```

```
static int sun4i_usb_phy_exit(struct phy *phy)
    clk_disable(&usb_phy->clocks);
    reset_assert(&usb_phy->resets);
static int sun4i_usb_phy_init(struct phy *phy)
    clk enable(&usb phy->clocks);
    reset deassert(&usb phy->resets);
static struct phy_ops sun4i_usb_phy_ops = {
    .init = sun4i usb phy init,
    .exit = sun4i usb phy exit,
};
static int sun4i usb phy probe(struct udevice *dev)
    clk_get_by_name(dev, "usb0_phy", &phy->clocks);
    reset get by name(dev, "usb0 reset", &phy->resets);
U_BOOT_DRIVER(sun4i_usb_phy) = {
    .id
           = UCLASS PHY,
    .ops = &sun4i_usb_phy_ops,
    .probe = sun4i usb phy probe,
};
```

Generic Block Layer



USB framework

- → via UCLASS_USB
- → uclass core: drivers/usb/host/usb-uclass.c
- → platform specific uboot driver: drivers/usb/host/ehci-generic.c
- → USB control, bulk, interrupt, create_int_queue etc via dm_usb_ops
- → include/usb.h
- → cmd/usb.c
- → USB Gadgets can probe via Gadget UCLASS
- → drivers/usb/gadget/ether.c, USB ETH Gadget
- → MUSB can operate Host and Peripheral
- → MUSB Host access via UCLASS USB
- → MUSB Peripheral access via
 - ◆ UCLASS_USB_DEV_GENERIC host devices
 - ◆ UCLASS_USB_GADGET_GENERIC gadget devices
- → drivers/usb/musb-new/sunxi.c, SunXi MUSB driver

OF Platdata

- → SPL size increases with FDT
- → Enabled via CONFIG_SPL_OF_PLATDATA
- → Explicitly define the device details Like legacy platform_device in Linux

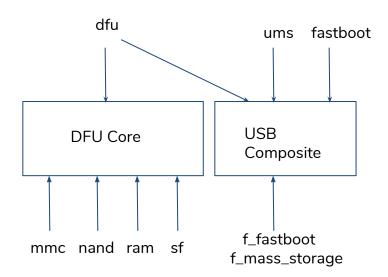
```
#include <dm/platform_data/spi_davinci.h>

static const struct davinci_spi_platdata davinci_spi_data = {
          .regs = (struct davinci_spi_regs *)0x01f0e000,
          .num_cs = 4,
};

U_BOOT_DEVICE(davinci_spi) = {
          .name = "davinci_spi",
          .platdata = &davinci_spi_data,
};
```

Firmware Upgrade

- → Upgrade firmware images on running U-Boot
- → DFU
- → DFU via tftp
- → UMS
- → Fastboot



Port new hardware

- → Prerequisite
- → Vyasa RK3288 port

Prerequisite

- → SRAM size restrictions
- → DDR configuration and timings
- → Start with Serial port, can be debuggable further

Vyasa RK3288 port

- → 3 stage bootloader
- → TPL
 - CPU, dram init, clocks, debug uart
 - ◆ SPL BOOTROM
- → SPL
 - ◆ SPL_OF_CONTROL, UART, falcon
 - ◆ SPL MMC
- → U-Boot proper
 - ◆ OF_CONTROL, UART, MMC, I2C,
 - ◆ CLK, Reset, commands etc



- → Add SoC support
 - arch/arm/mach-rockchip
 - arch/arm/mach-rockchip/rk3288
 - CPU clock, syscon, linker script etc
 - ◆ Add TARGET_VYASA_RK3288 in arch/arm/mach-rockchip/rk3288/Kconfig
- → Add DTS support
 - arch/arm/dts/rk3288-vyasa.dts
 - arch/arm/dts/rk3288-vyasa-u-boot.dtsi
- → Add Board support
 - board/amarula/vyasa-rk3288/
 - Board specific code
 - Board specific SPL code, if require
 - board/amarula/vyasa-rk3288/MAINTAINERS
- → Add header file
 - include/configs/vyasa-rk3288.h
 - Include common useful headers
 - Distro CONFIG definitions
 - ♦ CONFIG_ items which doesn't support Kconfig yet
- → Add defconfig file
 - ◆ CONFIG_ items which support Kconfig
- → Finally run buildman or travis to make sure all build fine
- → And use patman for sending patches to Mainline

ELCE 2017: Porting U-Boot and Linux on new ARM boards:a step-by-step guide, Quentin Schulz

```
U-Boot TPL 2018.09-00097-gd1e15041abf3 (Sep 13 2018 - 15:37:34 +0530)
Trying to boot from BOOTROM
Returning to boot ROM...
U-Boot SPL 2018.09-00097-gd1e15041abf3 (Sep 13 2018 - 15:37:34 +0530)
Trying to boot from MMC1
Expected Linux image is not found. Trying to start U-boot
U-Boot 2018.09-00097-gd1e15041abf3 (Sep 13 2018 - 15:37:34 +0530)
Model: Amarula Vyasa-RK3288
DRAM: 2 GiB
MMC: dwmmc@ff0c0000: 1, dwmmc@ff0f0000: 0
Loading Environment from MMC... *** Warning - bad CRC, using default environment
    serial
In:
Out: serial
Err: serial
Model: Amarula Vyasa-RK3288
Net: eth0: ethernet@ff290000
Hit any key to stop autoboot: 0
switch to partitions #0, OK
=>
```

Future plan

- → Kconfig migration
- → Driver model migrations
 - ♦ BLK, DM_MMC, DM_SCSI, DM_USB
 - ◆ DM_SPI, DM_SPI_FLASH, DM_VIDEO, DM_PCI
- → MTD driver model
- → Architecture CLK, RESET, Pinctrl Subsystems

Conclusion

- → Use DT and DM for new ports
- → Hands on with DM conversion
- → ML: u-boot@lists.denx.de
- → IRC: #u-boot
- → Lin: https://www.linkedin.com/in/jaganteki/
- → HABv4: https://openedev.amarulasolutions.com/display/ODWIKI/i.MX6+HABv4
- → OP-TEE case study: https://www.amarulasolutions.com/news/optee-case-study-on-imx6q/
- → Amarula Wiki: https://openedev.amarulasolutions.com

Questions??

Thank you

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