# Interpolation

MATH-151: Mathematical Algorithms in Matlab

September 18, 2023

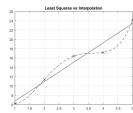


### FITTING THE DATA

 Sometimes we are given some information and want to find a function that agrees with the data. This is a process called interpolation

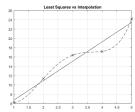
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 Most often we use polynomials as our interpolants, but different sets of functions can also be used!

## When is Interpolation Used?

- Interpolation is useful in many purposes when we are interested in representing data with a smooth function that captures changes in slope.
   For example
  - Plotting a smooth curve through data
  - Reading between entries of a data table
  - Differentiation or integration of function data
  - Approximating a complicated function with a simpler one
  - Using trigonometric functions to interpolate uniformly-spaced data points is called the Discrete Fourier Transform (or DFT) and commonly used in signal processing.

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- Let's start with the second part, how do we make our term be 0, when our x is any of our other points? We multiply by  $(x-x_j)$  for all the  $j \neq i$

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This gives us 
$$f(x_i) \frac{\prod_{j=1, j \neq i}^{N} (x - x_j)}{\prod_{j=1, j \neq i}^{N} (x_i - x_j)}$$

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This gives us 
$$f(x_i) \frac{\prod_{j=1, j \neq i}^{N} (x - x_j)}{\prod_{i=1}^{N} \prod_{j \neq i}^{N} (x_i - x_j)}$$

• We repeat this for each of our points and add them together

$$p(x) = \sum_{i=1}^{N} f(x_i) \frac{\prod_{j=1, j \neq i}^{N} (x - x_j)}{\prod_{j=1, j \neq i}^{N} (x_i - x_j)}$$

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- Suppose we have 3 points. (2,5), (7,0), and (8,11).
- We start with  $x_1 = 2$ ,  $f(x_1) = 5$ . Our term to make sure this works is

$$f(x_1)\frac{(x-x_2)(x-x_3)}{(x_1-x_2)(x_1-x_3)} = 5\frac{(x-7)(x-8)}{(2-7)(2-8)}$$

• Repeating this process for  $x_2=7$  and  $x_3=8$  we can find our interpolating polynomial

$$p(x) = 5\frac{(x-7)(x-8)}{(2-7)(2-8)} + 0\frac{(x-2)(x-8)}{(7-2)(7-8)} + 11\frac{(x-2)(x-7)}{(8-2)(8-7)}$$

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• We can simplify this, but we don't have to. The computer loves to grind through arithmetic!

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$$f[x_1, x_2, \dots, x_n] = \frac{f[x_2, \dots, x_n] - f[x_1, \dots, x_{n-1}]}{x_n - x_1}$$

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And we use these to build our polynomial as follows

$$p(x) = f[x_1] + f[x_1, x_2](x - x_1) + \dots + f[x_1, \dots, x_n](x - x_1) \times \dots \times (x - x_{n-1})$$

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 Just like Lagrange's method, this looks much more complicated when writing it abstractly than when performing it in practice, so lets see an example again.

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$$5 f[x_1, x_2] = \frac{0-5}{7-2} = 1$$

$$6 f[x_2] = 0$$

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#### Newton Divided Differences in Practice

 Using our points from earlier we can compute our interpolating polynomial using our divided differences.

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$$f[x_2, x_3] = \frac{11-0}{8-7} = 11$$

$$f[x_1, x_2, x_3] = \frac{11-(-1)}{8-2} = 2$$

$$8 f[x_3] = 11$$

Putting it all together we can find our interpolating polynomial is

$$f(x) = 5 + (-1)(x-2) + 2(x-2)(x-7)$$
 or, if we want to be fancy, 
$$f(x) = 5 + (x-2)\bigg(-1 + (x-7)(2)\bigg)$$

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 If we want to do the work, we can see this is the same answer that Lagrange's method gave us!

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  - Lagrange's method is easier to understand and more straightfoward.
     But it is less flexible to new data, and often less computationally efficient
  - Newton's divided differences are easier to add new data points to and can be written to be very fast, however it is harder to understand and implement