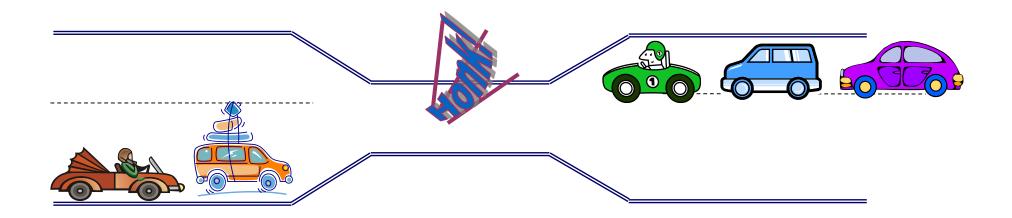


Deadlocks







Outline



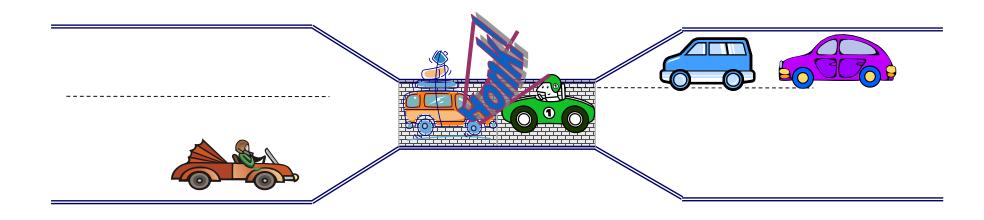
- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
 - Deadlock Prevention
 - Deadlock Avoidance
 - Deadlock Detection
 - Recovery From Deadlock



System Model



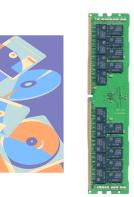
Bridge Crossing Example



Resources



- Resources passive entities needed by processes to do their work
 - CPU time, disk space, memory
- Two types of resources:
 - Preemptable can take it away
 - CPU, memory
 - Non-preemptable must leave it with the process
 - Disk space, printer, CD-writer
 - Mutual exclusion the right to enter a critical section







- Resources may require exclusive access or may be sharable
 - Read-only files are typically sharable
 - Printers are not sharable during time of printing
- One of the major tasks of an operating system is to manage resources

Resources



- Resource types R_1, R_2, \ldots, R_m
- Each resource type R_i has W_i instances.
- Each process utilizes a resource as follows:
 - request
 - use
 - release





- The Deadlock Problem
 - A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set.
- Deadlocks occur with multiple resources

Deadlock



- Deadlock not always deterministic Example 2 mutexes:
 - Deadlock won't always happen with this code
 - Have to have exactly the right timing ("wrong" timing?)
 - So you release a piece of software, and you tested it, and there it is, controlling a nuclear power plant

```
      Process A
      Process B

      (x.P();
      y.P();

      (y.P();
      x.P();

      y.V();
      x.V();

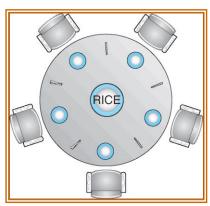
      x.V();
      y.V();
```



Dining-Philosophers Problem

- Five chopsticks/Five philosophers (really cheap restaurant)
 - Free-for all: Philosopher will grab any one they can
 - Need two chopsticks to eat
- What if all grab at same time?
 - Deadlock!



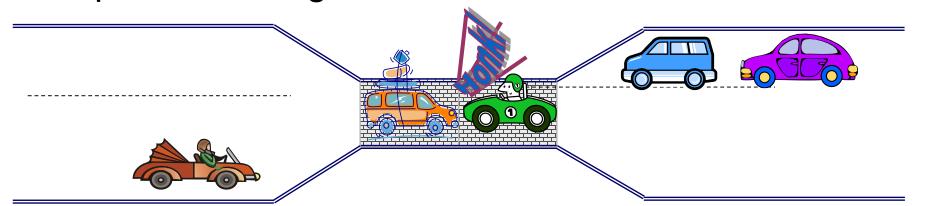




少,北京交通大學

Bridge Crossing Example

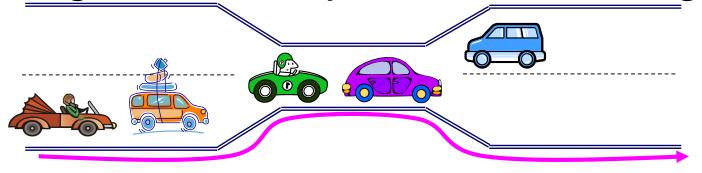
- Each segment of road can be viewed as a resource
 - Car must own the segment under them
 - Must acquire segment that they are moving into
- For bridge: must acquire both halves
 - Traffic only in one direction at a time
 - Problem occurs when two cars in opposite directions on bridge: each acquires one segment and needs next





Bridge Crossing Example

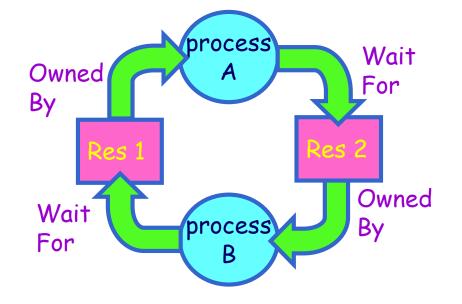
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback)
 - Several cars may have to be backed up
- Starvation is possible
 - East-going traffic really fast ⇒ no one goes west





Starvation vs Deadlock

- Starvation vs. Deadlock
 - Starvation: process waits indefinitely
 - Deadlock: circular waiting for resources
 - Deadlock ⇒ Starvation but not vice versa

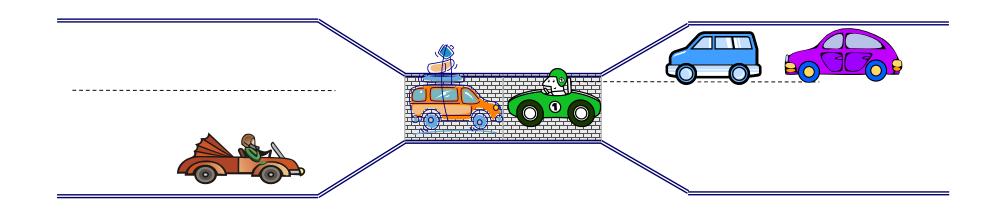




Deadlock Characterization



Deadlock Characterization



Four Requirements for Deadlock



Mutual exclusion

Only one process at a time can use a resource.

Hold and wait

 Process is holding at least one resource and is waiting to acquire additional resources held by other processes

No preemption

 Resources are released only voluntarily by the process holding the resource, after process is finished with it

Circular wait

- There exists a set $\{P_1, ..., P_n\}$ of waiting processes
 - P_1 is waiting for a resource that is held by P_2
 - P₂ is waiting for a resource that is held by P₃

 - P_n is waiting for a resource that is held by P_1



- When deadlock occurs, all four conditions hold
- Not sufficient conditions
- Not completely independently
 - "Circular wait" implies "Hold and wait"



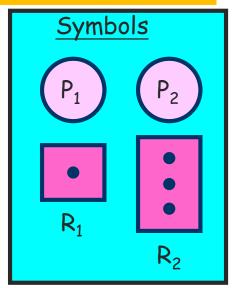
Resource-Allocation Graph

System Model

- A set of Processes $P_1, P_2, ..., P_n$
- Resource types $R_1, R_2, ..., R_m$
 - CPU cycles, memory space, I/O devices



- Each process utilizes a resource as follows:
 - •Request() / Use() / Release()





Resource-Allocation Graph

- A set of vertices V and a set of edges E.
- V is partitioned into two types:
 - $P = \{P_1, P_2, ..., P_n\}$, the set consisting of all the processes in the system.
 - $R = \{R_1, R_2, ..., R_m\}$, the set consisting of all resource types in the system.
- Request edge directed edge $P_i \rightarrow R_j$
- Assignment edge directed edge $R_j \rightarrow P_i$

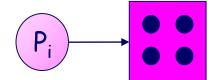


Resource-Allocation Graph

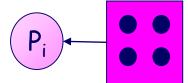
- Resource-Allocation Graph
 - Process
 - Resource Type with 4 instances



• P_i requests instance of R_j

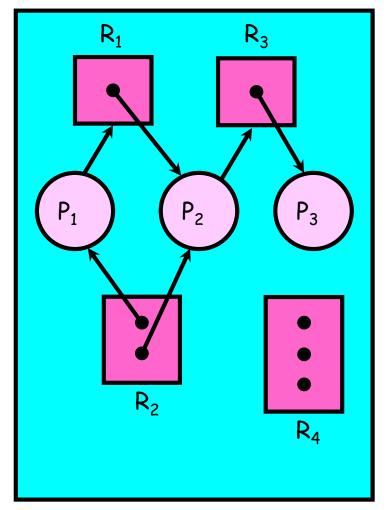


• P_i is holding an instance of R_j



Resource Allocation Graph Examples

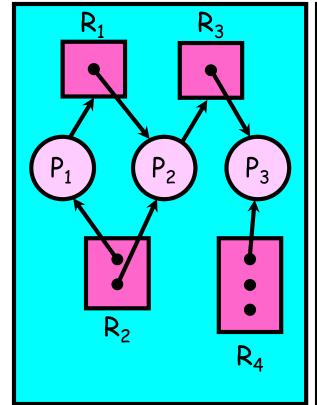
$$\begin{aligned} \bullet P &= \{ \, P_1, \, P_2, \, P_3 \, \} \\ \bullet R &= \{ \, R_1, \, R_2, \, R_3, \, R_4 \, \} \\ \bullet E &= \{ \, P_1 {\longrightarrow} R_1 \, , \, P_2 {\longrightarrow} R_3 \, , \\ R_2 {\longrightarrow} P_1, \, R_2 {\longrightarrow} P_2 \, , \\ R_1 {\longrightarrow} P_2, \, R_3 {\longrightarrow} P_3 \, \} \end{aligned}$$



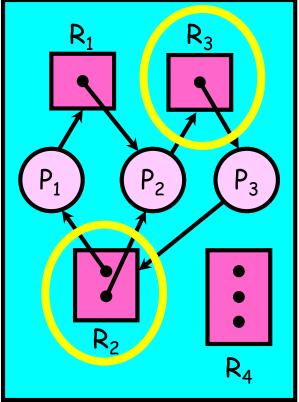
Simple Resource Allocation Graph

Resource Allocation Graph Examples

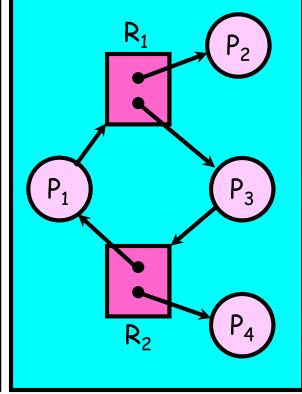
- request edge directed edge $P_i \rightarrow R_j$
- assignment edge directed edge $R_j o P_i$



Simple Resource Allocation Graph



Allocation Graph With Deadlock



Allocation Graph With Cycle, but No Deadlock

Deadlock Characterization



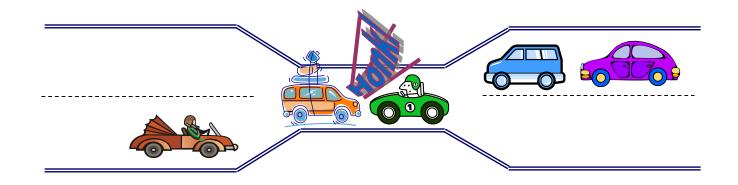
- Basic Facts
 - If graph contains no cycles ⇒ no deadlock
 - If graph contains a cycle ⇒
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock
 - In general, deadlock ⇒ cycle
 - cycle ⇒ may deadlock
 - no cycle ⇒ no deadlock
 - no deadlock ⇒ may have cycle
 - cycle + each resource in the cycle has only an instance



Methods for Handling Deadlocks

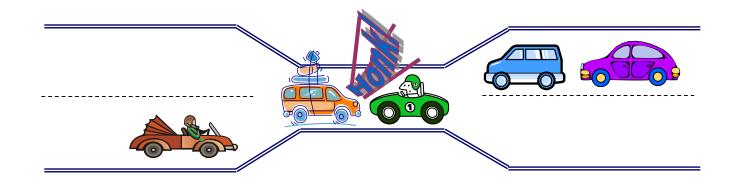
Methods for Handling Deadlocks Mixing

- Method 1
 - Left it unsolved



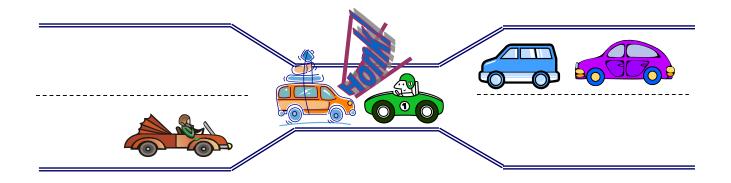
Methods for Handling Deadlocks Mixing

- Method 2
 - DELETE the two cars



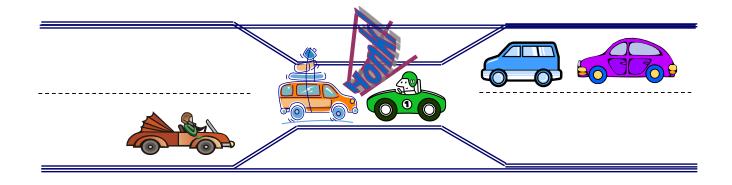
Methods for Handling Deadlocks ***

- Method 2
 - DELETE the two cars, or
 - Back the cars and restart



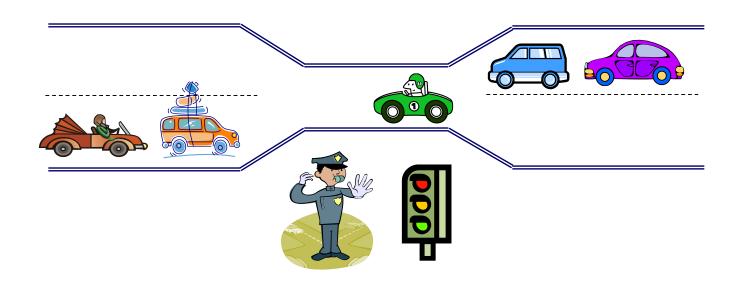
Methods for Handling Deadlocks Mixing

- Method 3
 - Widen the road



Methods for Handling Deadlocks Mixing

- Method 4
 - Ask for a police



Methods for Handling Deadlocks

- Method 1
 - Left it unsolved
- Method 2
 - DELETE the two cars, or
 - Back the cars and restart
- Method 3
 - Widen the road
- Method 4
 - Ask for a police

 Ignore the problem and pretend that deadlocks never occur in the system

 Allow system to enter deadlock and then recover

 Ensure that system will never enter a deadlock

Methods for Handling Deadlocks ***

- Ignore the problem and pretend that deadlocks never occur in the system
 - Used by most operating systems, including UNIX and Windows
- Ensure that the system will never enter a deadlock state
 - Deadlock prevention
 - Deadlock avoidance
- Allow the system to enter a deadlock state and then recover
 - Deadlock detection
 - Deadlock recovery



Deadlock Prevention





- Mutual exclusion
- Hold and wait
- No preemption
- Circular wait











Deadlock Prevention ①

- Mutual Exclusion not required for sharable resources; must hold for non-sharable resources.
 - Some resources are intrinsically non-sharable
 - Not very realistic

Deadlock Prevention ①



- Infinite resources
 - Examples:
 - Bay bridge with 12,000 lanes. Never wait!
 - Include enough resources so that no one ever runs out of resources.
 - Doesn't have to be infinite, just large
 - Give illusion of infinite resources (e.g. virtual memory)

Deadlock Prevention 2



Hold and Wait

- must guarantee that whenever a process requests a resource, it does not hold any other resources.
- Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none.
- Low resource utilization; starvation possible





No Preemption

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released.
- Only apply to resources whose state can be easily saved/restored (such as CPU, registers, memory)

Deadlock Prevention 4



Circular Wait

- 1. impose a total ordering of all resource types
- 2. require that each process requests resources in an increasing order of enumeration.
 - When request R_k , should release all R_i , $i \ge k$.
- Correctness (proof by contradiction)
- Force all processes to request resources in a particular order preventing any cyclic use of resources
 - Thus, preventing deadlock
 - Example (x.P, y.P, z.P, ...)

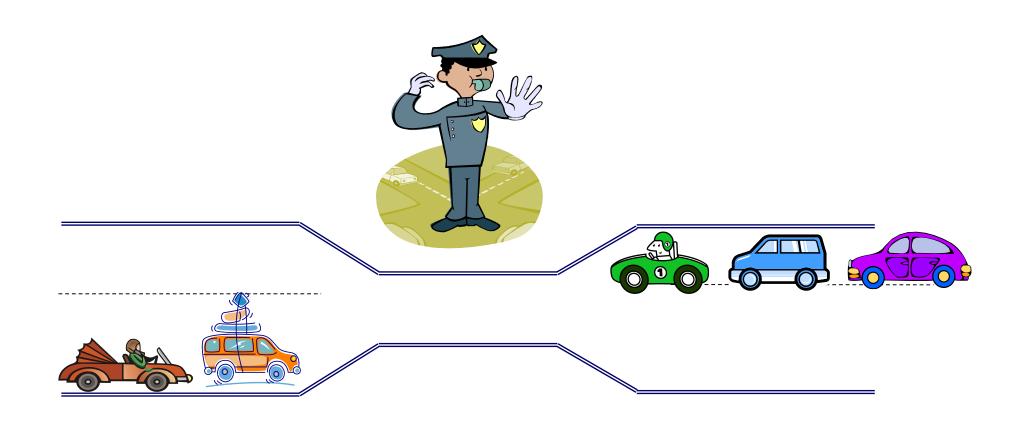


Deadlock Prevention

- Deadlock Prevention
 - 1. A set of methods for ensuring that at least one of the four necessary conditions cannot hold.
 - 2. These methods prevent deadlocks by constraining how requests for resources are made.













1 /4





3 /6











- Check for the given cases
- Require that the system has some additional a priori information available.



- Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need.
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition.
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes.



- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state.
- System is in safe state if there exists a safe sequence of all processes.



- Sequence $\langle P_1, P_2, ..., P_n \rangle$ is safe if for each P_i , the resources that P_i can still request, can be satisfied by currently available resources + resources held by all the P_j , with j < i.
- Formally, there is a safe sequence $\langle P_1, P_2, ..., P_n \rangle$ such that for all i = 1, 2, ..., n, $Available + \sum_{1 \leq j \leq i} (Allocated_j) \geq MaxNeed_i$



Available = 5

	allocated	needed	
P1	1	3	
P ₂	2	6	
P 3	0	8	
P4	5	1	
P5	4	2	
P6	7	3	



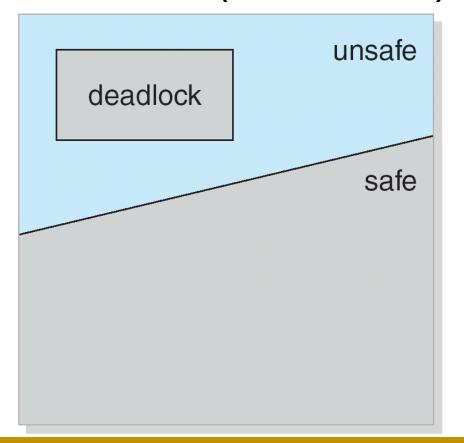
That is:

- If P_i resource needs are not immediately available, then P_i can wait until all P_j have finished (where j < i).
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate.
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on.



Unsafe State

- No safe sequence exists
- May lead to a deadlock (not must)





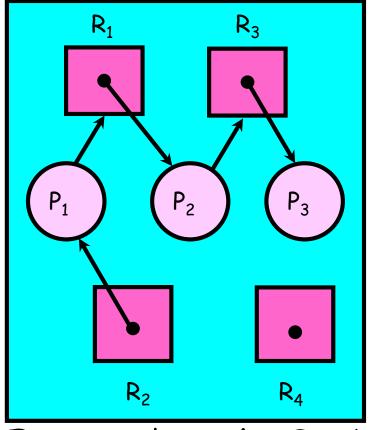


- If a system is in safe state ⇒ no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlocks
- Avoidance ⇒ ensure that a system will never enter an unsafe state



Avoidance algorithms

- Single instance of a resource type
 - Use a resource-allocation graph

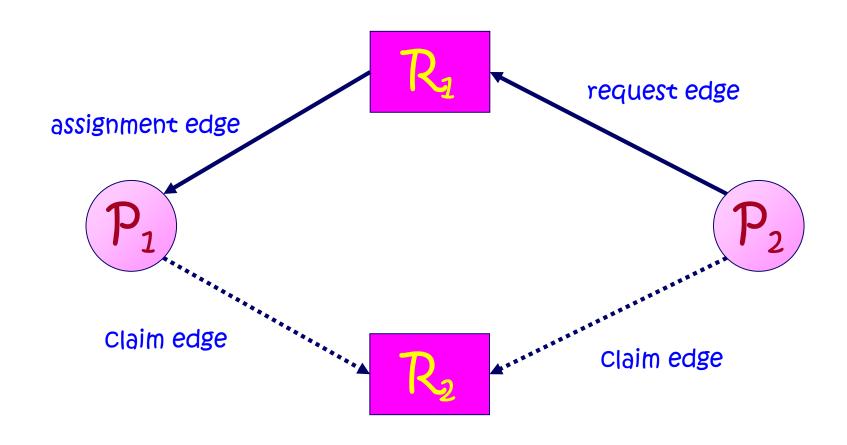


Resource Allocation Graph

Resource-Allocation Graph Scheme

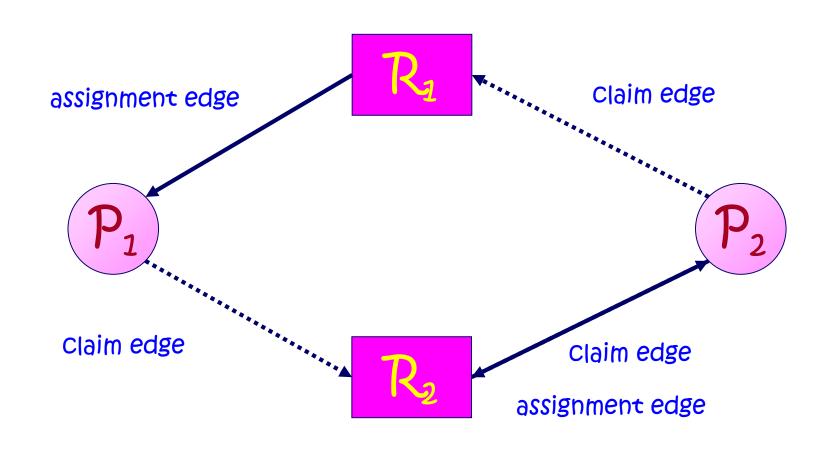
- Use a variant of resource-allocation graph
 - Claim edge $P_i \to R_j$ indicates that process P_i may request resource R_j ; represented by a dashed line.
 - Claim edge converts to request edge when a process requests a resource.
 - Request edge converted to assignment edge when the resource is allocated to the process.
 - When a resource is released by a process, assignment edge reconverts to a claim edge.
- Resources must be claimed a priori in the system.
- Check for safety using a cycle-detection algorithm.

Resource-Allocation Graph Scheme



Unsafe State in Resource-Allocation Graph



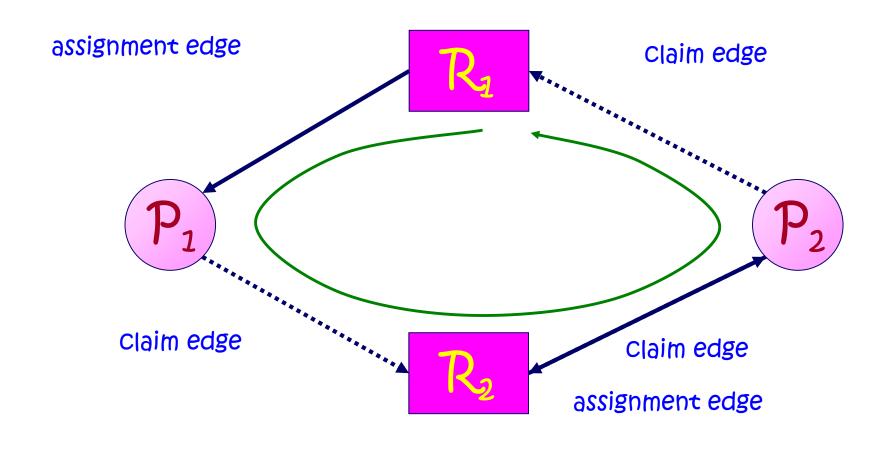


Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_j
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

Unsafe State in Resource-Allocation Graph



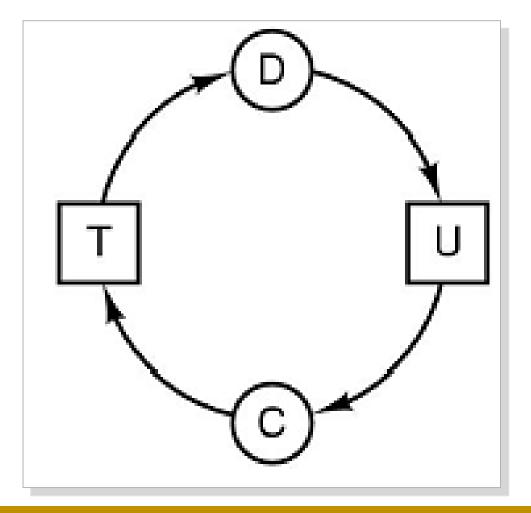




Cycle-Detection

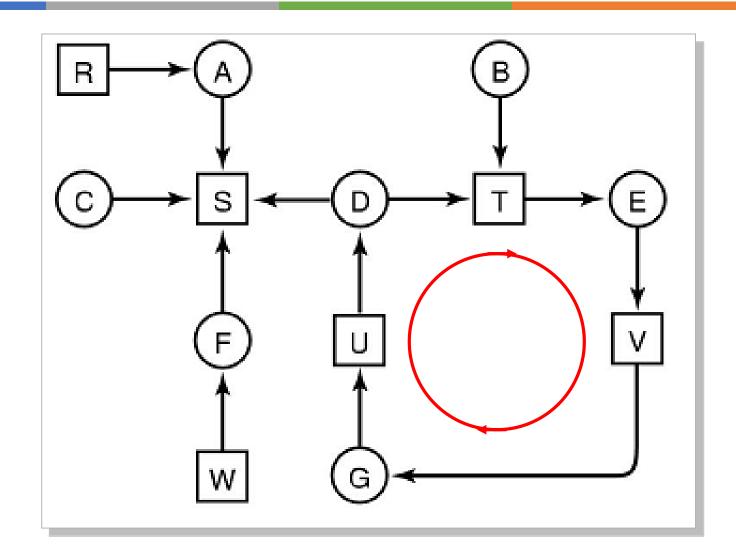
Only one of each type of resource ⇒ look for

loops





Cycle-Detection





Avoidance algorithms

- Single instance of a resource type
 - Use a resource-allocation graph
- Multiple instances of a resource type
 - Use the banker's algorithm



Banker's Algorithm

- Assumption
 - Each process must a priori claim maximum use
 - When a process requests a resource it may have to wait
 - When a process gets all its resources it must return them in a finite amount of time







1 /4

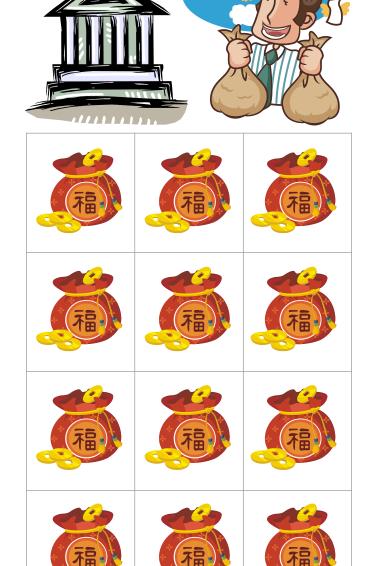




3 /6







Banker's Algorithm for Avoiding Deadlock

- Toward right idea:
 - State maximum resource needs in advance
 - Allow particular process to proceed if:
 - (available resources #requested) ≥ Max remaining that might be needed by any process

Banker's Algorithm for Avoiding Deadlock

- Banker's algorithm (less conservative):
 - Allocate resources dynamically
 - Evaluate each request and grant if some ordering of processes is still deadlock free afterward
 - Technique: pretend each request is granted, then run deadlock detection algorithm
 - Keeps system in a "SAFE" state

- Let
 - \cdot **n** = number of processes
 - \cdot m = number of resources types
 - Available: Vector of length m.



Available [j] = k —there are k instances of resource type R_j available.

- Let
 - n = number of processes
 - m = number of resources types
 - Max: n × m matrix.

Max					
1,1	•••	•••	1,j	•••	1,m
	•••	•••	•••	•••	•••
i,1	•••	•••	i,j_	•••	i,m

If Max[i,j] = k — then process P_i may request at most k instances of resource type R_j .

- Let
 - n = number of processes
 - \mathbf{m} = number of resources types
 - Allocation: n × m matrix

Allocation					
1,1	•••	•••	1,j	•••	1,m
•••	•••	•••	•••	•••	•••
i,1	•••	•••	i,j	•••	i,m

If Allocation[i,j] = k — then P_i is currently allocated k instances of R_j .

- Let
 - n = number of processes
 - \mathbf{m} = number of resources types
 - Need: n x m matrix

Need					
1,1	•••	•••	1,j	•••	1,m
•••	•••	•••	•••	•••	•••
i,1	•••	•••	ij	•••	i,m
i,1	•••	•••	i,j	•••	i,

If $Need[i,j] = k - then P_i$ may need k more instances of R_j to complete its task.

Need [i,j] = Max[i,j] - Allocation [i,j].

- Let $\mathbf{n} = \text{number of processes}$, and $\mathbf{m} = \text{number of resources types}$.
 - Available: Vector of length \mathbf{m} . If available $[\mathbf{j}] = \mathbf{k}$, there are \mathbf{k} instances of resource type $\mathbf{R}_{\mathbf{i}}$ available.
 - Max: $n \times m$ matrix. If Max [i,j] = k, then process P_i may request at most k instances of resource type R_i .
 - Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_i .
 - Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_i to complete its task.

Need [i,j] = Max[i,j] - Allocation [i,j].

Safety Algorithm



- 1. Let Work and Finish be vectors of length m and n, respectively. Initialize:
 - (a) Work = Available
 - (b) Finish [i] = false for i = 0, 1, ..., n-1.
- 2. Find an i such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$

If no such i exists, go to step 4.

- 3. Work = Work + Allocation_i
 Finish[i] = true
 go to step 2.
- 4. If Finish [i] == true for all i, then the system is in a safe state.

Resource-Request Algorithm for Process Pi

- $Request_i$ = request vector for process P_i .
- If $Request_i[j] = k$ then process P_i wants k instances of resource type R_j .
 - 1. If **Request_i ≤ Need_i** go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
 - 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available.
 - 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;
Allocation<sub>i</sub> = Allocation<sub>i</sub> + Request<sub>i</sub>;
Need<sub>i</sub> = Need<sub>i</sub> - Request<sub>i</sub>;
```

- If safe ⇒ the resources are allocated to P_i.
- If unsafe ⇒ P_i must wait, and the old resource-allocation state is restored



Example of Banker's Algorithm

Example

- Assuming that the system distinguishes between four types of resources, (A, B, C and D), the following is an example of how those resources could be distributed.
- Real systems, for example, would deal with much larger quantities of each resource.

												16224
		Alloca	ation			M	ax		Available			
	A	B	С	D	A	B	С	D	A	B	С	D
P1	0	0	1	4	0	6	5	6	1	5	2	0
P2	1	4	3	2	1	9	4	2				
P3	1	3	5	4	1	3	5	6				
P4	1	0	0	0	1	7	5	0				

		Ne	ed		=Max-Allocation	FINISH
	*	B	U	D		
P1	0	6	4	2		False
P2	0	5	1	0		False
P 3	0	0	0	2		False
P4	0	7	5	0		False

												16224
		Alloc	ation			M	ax		Available			
	A	B	С	D	A	B	С	D	A	B	С	D
P1	0	0	1	4	0	6	5	6	1	5	2	0
P2	1	4	3	2	1	9	4	2				
P3	1	3	5	4	1	3	5	6				
P4	1	0	0	0	1	7	5	0				

		Ne	ed		=Max-Allocation	FINISH
	A	B	С	D		
P1	0	6	4	2		False
P2	0	0	0	0		False 🛑
P 3	0	0	0	2		False
P4	0	7	5	0		False

		Alloc	ation			M	ax		Available			
	A	В	С	D	A	B	С	D	A	В	С	D
P1	0	0	1	4	0	6	5	6	1	5	2	0
P2	1	4	3	2		9	4	2				
P 3	1	3	5	4	1	3	5	6				
P4	1	0	0	0	1	7	5	0				

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	Ω		
P1	0	6	4	2		False
P2	0	0	0	0		True
Рз	0	0	0	2		False
P4	0	7	5	0		False

		Alloc	ation			M	ax		Available			
	A	B	С	D	A	B	С	D	A	B	С	D
P1	0	0	1	4	0	6	5	6	1	5	2	0
P2	0	0	0	0	1	9	4	2				
P3	1	3	5	4	1	3	5					
P4	1	0	0	0	1	7	5	0				

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	Ω		
P1	0	6	4	2		False
P2	0	0	0	0		True
Рз	0	0	0	2		False
P4	0	7	5	0		False

												14221	+1
		Alloc	ation			M	ax		Available				~
	A	В	С	D	A	B	С	D	A	B	С	D	
P1	0	0	1	4	0	6	5	6	1	5	2	0	
P2	0	0	0	0	1	9	4	2	1	4	3	2	
P3	1	3	5	4	1	3	5	6	2	9	5	2	
P4	1	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	U	Ω		
P1	0	6	4	2		False
P2	0	0	0	0		True
P 3	0	0	0	2		False
P4	0	7	5	0		False

												11224	土土海
		Alloc	ation			M	ax			Avai	lable		个字
	A	B	С	D	A	B	С	D	A	В	С	D	
P1	0	0	1	4	0	6	5	6	2	9	5	2	
P2	0	0	0	0	1	9	4	2					
P 3	1	3	5	4	1	3	5	6					
P4	1	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	Ω		
P1	0	6	4	2		False
P2	0	0	0	0		True
P 3	0	0	0	2		False
P4	0	7	5	0		False

												14251	4
		Alloc	ation		Max				Available				~
	A	В	С	D	A	B	С	D	A	B	С	D	
P1	0	0	1	4	0	6	5	6	2	9	5	2	
P2	0	0	0	0	1	9	4	2	1	3	5	4	
P3	0	0	0	0	1	3	5	6	3	12	10	6	
P4	1	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	Ω		
P1	0	6	4	2		False
P2	0	0	0	0		True
P 3	0	0	0	0		True
P4	0	7	5	0		False

												14224
		Alloc	ation			M	ax			Avai	lable	
	A	B	С	D	A	B	С	D	A	B	С	D
P1	0	0	1	4	0	6	5	6	3	12	10	6
P2	0	0	0	0	1	9	4	2				
P3	0	0	0	0	1	3	5	6				
P4	1	0	0	0	1	7	5	0				

		Ne	ed		=Max-Allocation	FINISH
	A	B	С	D		
P1	0	6	4	2		False
P2	0	0	0	0		True
P 3	0	0	0	0		True
P4	9	7	5	0		False

												14224	上十遍
		Alloc	ation			M	ax		Available				个字
	A	A B C D				B	C	D	A	B	С	D	
P1	0	0	1	4	0	6	5	6	4	12	10	6	
P2	0	0	0	0	1	9	4	2					Ī
P 3	0	0	0	0	1	3	5	6					
P4	0	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	D		
P1	0	6	4	2		False
P2	0	0	0	0		True
Рз	0	0	0	0		True
P4	0	0	0	0		True

												14221	上土滨
		Alloc	ation			M	ax		Available				个字
	A	B	С	D	A	B	С	D	A	B	С	D	
P1	0	0	0	0	0	6	5	6	4	12	11	10	
P2	0	0	0	0	1	9	4	2					
P3	0	0	0	0	1	3	5	6					
P4	0	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	C	D		
P1	0	0	0	0		True
P2	0	0	0	0		True
P 3	0	0	0	0		True
P4	0	0	0	0		True

												11221	ナ湾
		Alloc	ation			M	ax		Available				入字
	A	В	С	D	A	B	С	D	A	В	С	D	
P1	0	0	1	4	0	6	5	6	1	5	2	0	
P2	1	4	3	2	1	9	4	2					
P3	1	3	5	4	1	3	5	6					
P4	1	0	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	\$	B	U	D		
P1	0	6	4	2	Sare	False
P2	0	5	1	0	Ctate	False
P 3	0	0	0	2	P	False
P4	0	7	5	0		False

Safety Algorithm



- 1. Let Work and Finish be vectors of length m and n, respectively. Initialize:
 - (a) Work = Available
 - (b) Finish [i] = false for i = 0, 1, ..., n-1.
- 2. Find an i such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$

If no such i exists, go to step 4.

- 3. Work = Work + Allocation_i
 Finish[i] = true
 go to step 2.
- 4. If Finish [i] == true for all i, then the system is in a safe state.

												11221	上土滨
		Alloc	ation			M	ax		Available				个字
	A	A B C D				B	С	D	A	В	С	D	
P1	0	0	1	4	0	6	5	6	1	5	2	0	
P2	1	4	3	2	1	9	4	2					
P3	1	3	5	4	1	3	5	6					
P4	1	0	0	0	1	7	5	0					

		Ne	ed		process 4 requests 4 unit	FINISH
	\$	B	U	Ω	of resource B.	
P1	0	6	4	2	There are enough	False
P2	0	5	1	0	resources Assuming the	False
P 3	0	0	0	2	request is granted, the new	False
P4	0	7	5	0	state would be:	False

												11224	ナ湾
		Alloc	ation			M	ax			Avai	lable		个字
	A B C D 0 0 1 4				A	B	С	D	A	В	С	D	
P1	0	0	1	4	0	6	5	6	1	1	2	0	
P2	1	4	3	2	1	9	4	2					
P3	1	3	5	4	1	3	5	6					
P4	1	4	0	0	1	7	5	0					

		Ne	ed		=Max-Allocation	FINISH
	A	B	U	Ω	ath eafe	
P1	0	6	4	2	Ousare	False
P2	0	5	1	0	Ctate	False
P 3	0	0	0	2		False
P4	0	3	5	0		False

		Alloc	ation			M	ax			Avai	lable	14224
	A	B	С	D	A	B	С	D	A	В	С	D
P1	0	0	1	4	0	6	5	6	1	5	2	0
P2	1	4	3	2	1	9	4	2				
P3	1	3	5	4	1	3	5	6				
P4	1	0	0	0	1	7	5	0				

		Ne	ed		process 1	FINISH
	A	B	С	D	requests 2 unit of	
P1	0	6	4	2	resource B.	False
P2	0	5	1	0		False
P3	0	0	0	2		False
P4	0	7	5	0		False

Resource-Request Algorithm for Process Pi

- $Request_i$ = request vector for process P_i .
- If $Request_i[j] = k$ then process P_i wants k instances of resource type R_j .
 - 1. If Request_i ≤ Need_i go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
 - 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available.
 - 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;
Allocation<sub>i</sub> = Allocation<sub>i</sub> + Request<sub>i</sub>;
Need<sub>i</sub> = Need<sub>i</sub> - Request<sub>i</sub>;
```

- If safe \Rightarrow the resources are allocated to P_i .
- If unsafe ⇒ P_i must wait, and the old resource-allocation state is restored



Banker's Algorithm

- The Banker's algorithm is run by the operating system whenever a process requests resources.
- The algorithm avoids deadlock by denying or postponing the request if it determines that accepting the request could put the system in an unsafe state (one where deadlock could occur).



Banker's Algorithm

- For the Banker's algorithm to work, it needs to know three things:
 - How much of each resource each process could possibly request?
 - How much of each resource each process is currently holding?
 - How much of each resource the system has available?



Deadlock Detection



Deadlock Detection

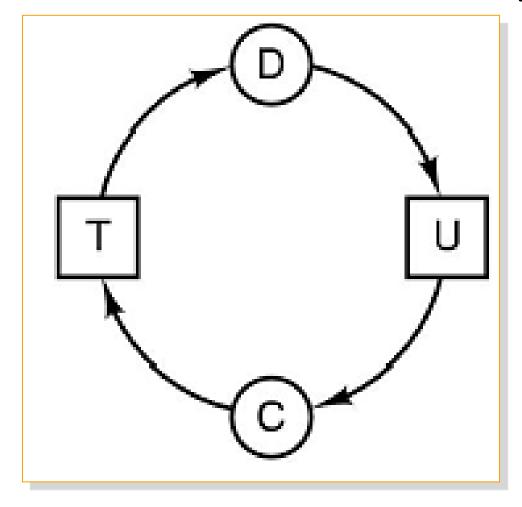
- Allow system to enter deadlock state
 - Detect whether deadlocks occur
 - If so, recover from the deadlock
- Detection algorithms
- Recovery scheme



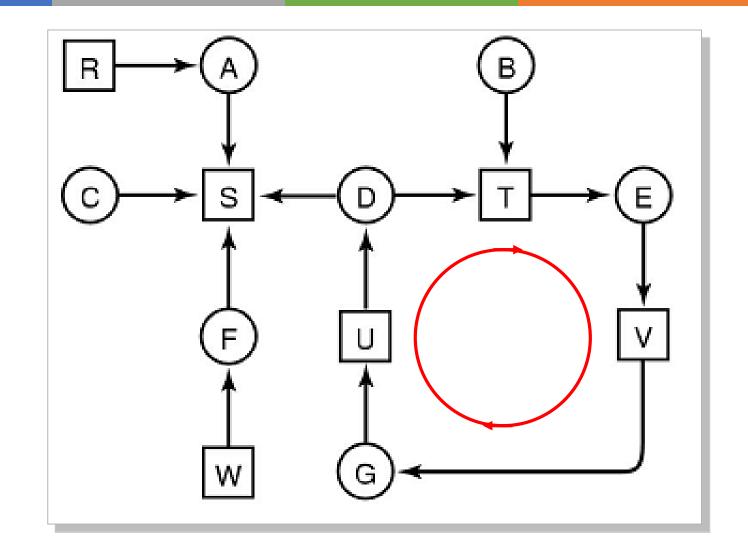
Deadlock Detection Algorithm

Single instance of each resource type ⇒ look

for loops



Single Instance of Each Resource Type

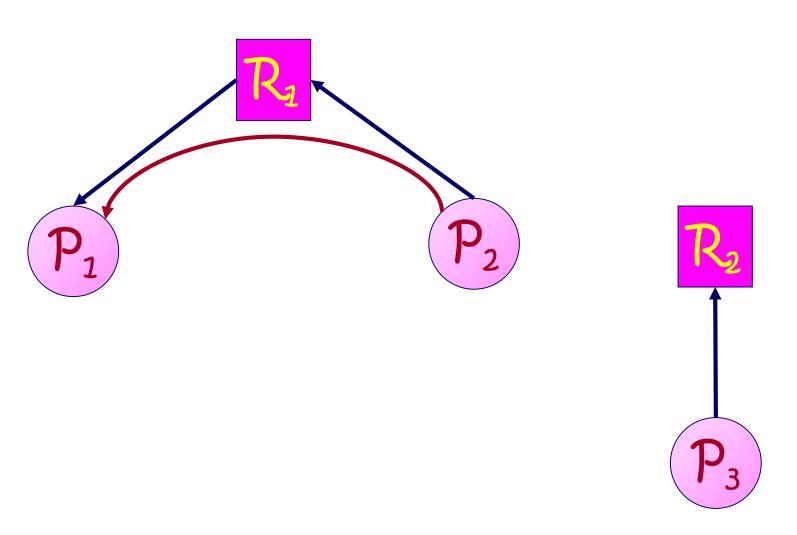


Single Instance of Each Resource Type

- Maintain wait-for graph
 - Nodes are processes
 - • $P_i \rightarrow P_j$ if P_i is waiting for P_j
- Periodically invoke an algorithm that searches for a cycle in the graph.

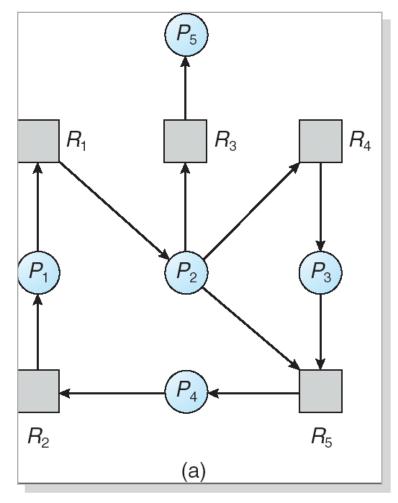


Wait-for Graph

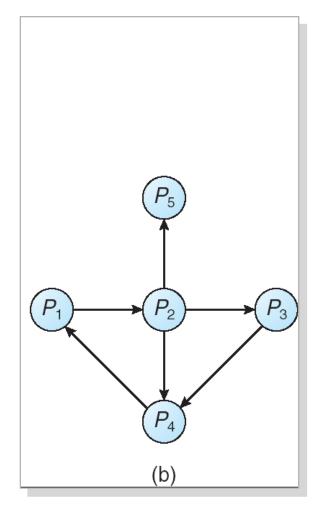


Resource-Allocation Graph & Wait-for Graph





Resource-Allocation Graph



Corresponding wait-for graph



Deadlock Detection Algorithm

- Single Instance of Each Resource Type
 - ⇒ look for loops
- Several Instances of a Resource Type
 - \Rightarrow ?

Several Instances of a Resource Type



- Available: Vector of length m indicates the number of available resources of each type.
- Allocation: $n \times m$ matrix defines the number of resources of each type currently allocated to each process.
- Request: $n \times m$ matrix indicates the current request of each process. If Request[i, j] = k, then process P_i is requesting k more instances of resource type R_i .

Detection Algorithm



- 1. Let Work and Finish be vectors of length m and n, respectively. Initialize:
 - (a) Work = Available
 - (b) For i = 1, 2, ..., n, if $Allocation_i \neq 0$, then Finish[i] = false; otherwise, Finish[i] = true.
- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$
 - If no such *i* exists, go to step 4.
- 3. $Work = Work + Allocation_i$ Finish[i] = truego to step 2.
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked.



Example of Detection Algorithm white the state of the control of t

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Alle	oca	<u>tion</u>	Re	que	<u>st</u>	<u>Available</u>		
	\$	B	С	A	B	С	*	B	U
\mathcal{P}_{o}	0	1	0	0	0	0	0	0	0
P_1	2	0	0	2	0	2			
P_2	3	0	3	0	0	0			
\mathcal{P}_3	2	1	1	1	0	0			
\overline{P}_{q}	0	0	2	0	0	2			



Example of Detection Algorithm white the state of the detection of the state of the

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Alle	oca	<u>tion</u>	Re	que	<u>st</u>	<u>Available</u>		
	A	B	С	A	B	С	A	B	C
Po	0	1	0	0	0	0	0	0	0
P_1	2	0	0	2	0	2			
P_2	3	0	3	0	0	0			
\mathcal{P}_3	2	1	1	1	0	0			
\mathcal{P}_{4}	0	0	2	0	0	2			



Example of Detection Algorithm white the state of the control of t

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Alle	oca	<u>tion</u>	Re	que	<u>est</u>	<u>Available</u>		
	A	B	С	A	B	С	A	B	C
Po							0	1	0
P_1	2	0	0	2	0	2			
P ₂	3	0	3	0	0	0			
\mathcal{P}_3	2	1	1	1	0	0			
\mathcal{P}_{4}	0	0	2	0	0	2			



Example of Detection Algorithm white the state of the control of t

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Alle	oca	<u>tion</u>	Re	que	<u>st</u>	<u>Available</u>		
	A B C 2 0 0			A	B	С	A	B	O
\mathcal{P}_{o}							3	1	3
P_1	2	0	0	2	0	2			
P_2									
P ₃	2	1	1	1	0	0			
\mathcal{P}_{4}	0	0	2	0	0	2			



Example of Detection Algorithm ***

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Alle	oca	tion	Re	que	<u>st</u>	<u>Available</u>		
	A B C 2 0 0		С	A	B	С	A	B	O
Po							5	2	4
P_1	2	0	0	2	0	2			
P ₂									
\mathcal{P}_3									
P4	0	0	2	0	0	2			



Example of Detection Algorithm white the state of the control of t

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

	Allocation ABC 2 0 0			Re	que	<u>st</u>	<u>Available</u>		
	A	B	С	A	B	С	A	B	O
Po							5	2	6
Pı	2	0	0	2	0	2			
P ₂									
\mathcal{P}_3									
\mathcal{P}_{4}									



Example of Detection Algorithm white the second sec

- Five processes P₀ through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

• Sequence $\langle P_0, P_2, P_3, P_4, P_1 \rangle$ will result in Finish[i] = true

for all i.

	Alle	oca	<u>tion</u>	Re	que	<u>st</u>	Ava	<u>le</u>	
	A	B	С	A	B	С	A	B	O
Po							7	2	6
P_1									
P_2									
\mathcal{P}_3									
\mathcal{P}_{4}									



Example of Detection Algorithm ***

- P₂ requests an additional instance of type C.
- State of system?
 - Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes; requests.
 - Deadlock exists, consisting of processes P₁, P₂, P₃, and P₄.

	Alle	oca	tion	Re	que	<u>st</u>	Ava	Availab A B O O	
	A	B	С	A	B	С	A	B	O
Po	0	1	0	0	0	0	0	0	0
P_1	2	0	0	2	0	2			
P_2	3	0	3	0	0	1			
P_3	2	1	1	1	0	0			
\mathcal{P}_{4}	0	0	2	0	0	2			

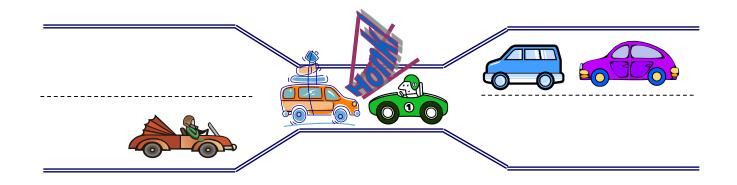


Recovery From Deadlock



Methods for Handling Deadlock

Method 1





Process Termination

- Terminate process, force it to give up resources
 - In Bridge example, Godzilla picks up a car, hurls it into the river. Deadlock solved!
 - But, not always possible killing a process holding a mutex leaves world inconsistent



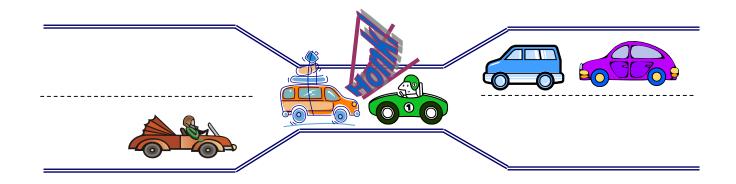
Process Termination

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
 - Priority of the process
 - How long process has computed, and how much longer to completion
 - Resources the process has used
 - Resources process needs to complete
 - How many processes will need to be terminated
 - Is process interactive or batch?



Methods for Handling Deadlock

Method 2



Roll Back

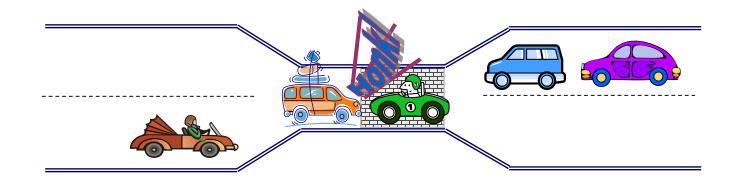


- Hit the rewind button on TiVo, pretend last few minutes never happened
- For bridge example, make one car roll backwards (may require others behind him)
- Return to some safe state, restart process for that state. (some resources are released)
 - totally rollback: simple but expensive
 - as far as necessary
 (OS should maintain "checkpoint" a recording of the state of a process to allow rollback)
- Of course, if you restart in exactly the same way, may reenter deadlock once again



Methods for Handling Deadlock

Method 3





Resource Preemption

- Preempt resources without killing off process
 - successively preempt some resources and give them to other processes until the deadlock cycle is broken.



Resource Preemption

- selecting a victim
 - How to minimize the cost?
 - what types and how many resources are held
 - how much time has run
 - how much time to end
 - •
 - starvation
 - same process may always be picked as victim, include number of rollback in cost factor.
 - not always select the same process for preemption

What to do when detect deadlock?

• Terminate process, force it to give up resources



Roll back actions of deadlocked processes



Many operating systems use other options



Summary

Summary



Starvation vs. Deadlock

- Starvation: processes waits indefinitely
- Deadlock: circular waiting for resources
- Deadlock ⇒ Starvation, but not other way around

Four conditions for deadlocks

- Mutual exclusion
 - Only one process at a time can use a resource
- Hold and wait
 - Process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption
 - Resources are released only voluntarily by the processes
- Circular wait
 - \exists set $\{T_1, ..., T_n\}$ of processes with a cyclic waiting pattern

少,北京交通大学

Summary

- Ensure that system will never enter a deadlock
 - deadlock prevention
 - deadlock avoidance
 - Banker's Algorithm
- Allow system to enter deadlock and then recover
 - deadlock detection
 - deadlock recovery
- Ignore the problem and pretend that deadlocks never occur in the system
 - Used by most operating systems, including UNIX and Windows



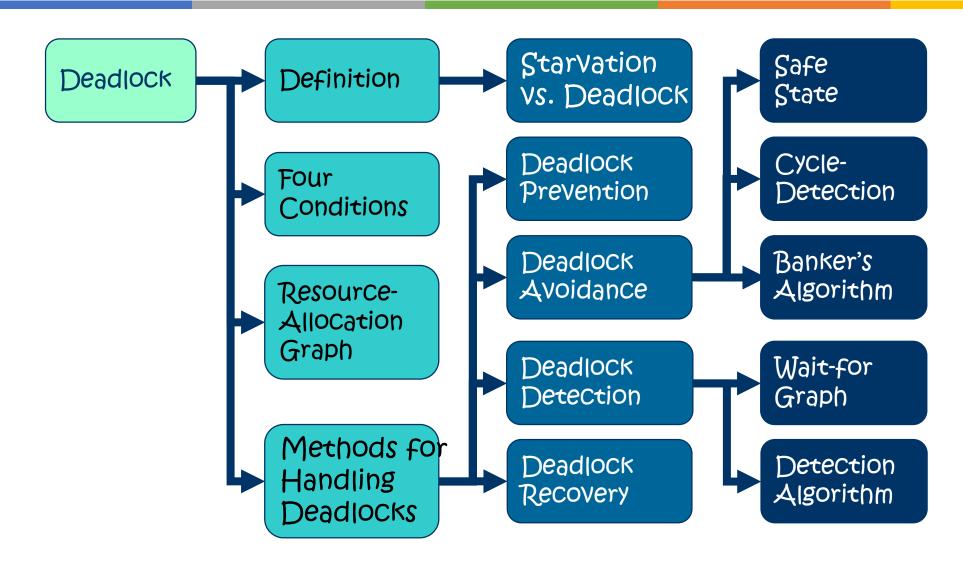
Summary

- Combine the three basic approaches
 - prevention
 - avoidance
 - detection

Allowing the use of the optimal approach for each of resources in the system.



Deadlock Handling





Thank you! Q&A

