Kanhaiya Lal Chaurasiya

CONTACT Information

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RESEARCH INTERESTS Shape memory alloy, Actuators and control, Bio-inspired system design, Structural health monitoring, System engineering and New product development (NPD)

EDUCATION

Indian Institute of Technology (IIT) Kanpur, Kanpur, India

• Master of Technology (M.Tech.) in Mechanical Engineering, CPI of 9.0/10

• Bachelor of Technology (B.Tech.) in Mechanical Engineering, CPI of 7.1/10 (2015) (5-years Integrated Dual Degree Programme)

St. John's School, CISCE Board, Varanasi, India

• 12th Grade (Higher Secondary), Scored 90.3%; Secured **100/100** marks in Mathematics (2010)

• 10^{th} Grade (Secondary), Scored 92.0%

(2008)

(2016)

PUBLICATIONS

Peer-reviewed Journals

- [1] Chaurasiya, K. L., Harsha, A., Sinha, Y., & Bhattacharya, B. (2022). Design and development of non-magnetic hierarchical actuator powered by shape memory alloy based bipennate muscle. *Scientific Reports*, 12(1), 1-15. https://doi.org/10.1038/s41598-022-14848-w
- [2] Sampath, S., Chaurasiya, K. L., Aryan, P., & Bhattacharya, B. (2021). An innovative approach towards defect detection and localization in gas pipelines using integrated in-line inspection methods. *Journal of Natural Gas Science and Engineering*, 90, 103933. https://doi.org/10.1016/j.jngse.2021.103933
- [3] Chaurasiya, K. L., Bhattacharya, B., Varma, A. K., & Rastogi, S. (2020). Dynamic modeling of a cabin pressure control system. Proceedings of Institution of Mechanical Engineers, *Part G: Journal of Aerospace Engineering*, 234, 401-415. https://doi.org/10.1177/0954410019867578

International Conferences

- [1] Chaurasiya, K. L., Gupta, N., Javeed, F., Kumar, V., & Bhattacharya, B. (2024, May). Enhancing actuation frequency of shape memory alloy-based system with a novel evaporative cooling technique for fast cyclic applications. *In Active and Passive Smart Structures and Integrated Systems XVIII* (Vol. 12946, pp. 458-467). SPIE.
- [2] Pandey, A., Haneef, J., Sinha, Y., Chaurasiya, K. L., & Bhattacharya, B. (2024, May). Design and development of a shape memory alloy-powered rotary variable stiffness actuator embedded with an agonist-antagonist mechanism. In Active and Passive Smart Structures and Integrated Systems XVIII (Vol. 12946, pp. 468-477). SPIE.
- [3] Chaurasiya, K. L., Pawar, V., & Bhattacharya, B. (2023, April). An innovative method and apparatus for speed control of pipe health monitoring robot during gas pipeline inspection. *In Health Monitoring of Structural and Biological Systems XVII* (Vol. 12488, pp. 372-379) SPIE.
- [4] Sinha, Y., Chaurasiya, K. L., Patel, Y. A. K., Gupta, T., & Bhattacharya, B. (2023, April). Design and development of novel rotary actuation system based on shape memory alloy springs driven mechanism arranged in bipennate muscle architecture. *In Active and Passive Smart Structures and Integrated Systems XVII* (Vol. 12483, pp. 498-510). SPIE.

Patents
(2 Granted &
4 Pending)

- [1] [Appl. No. 202411043335] (Country: India) "A Shape Memory Alloy-Based Device with Enhanced Rotational Motion", 2024 (Pending)
- [2] [Appl. No. 202311068306] (Country: India) "Air-Levitation based Hyperloop Transporting System with Robot Vehicle for Transporting Goods", 2023 (Pending)
- [3] [Appl. No. PCT/US2022/041899] (Countries: United States & European Region) "Actuator for a Valve", Pub. No. WO/2023/034215, IPC F16K 31/02 2006.1, 2022 (Pending)
- [4] [Appl. No. 202211077045] (Country: India) "Hyperloop Transporting System with Robot Vehicle for Transporting Goods", Pub. No. 43/2023, IPC G06Q, 2022 (Pending)

- [5] [Patent No. 414106] (Country: India) "Bipennate Muscle Architecture-based Shape Memory Alloy Embedded Hierarchical Actuator", IPC F03G; B25J, 2021 (Granted)
- [6] [Patent No. 517151] (Country: India) "Speed Control System for Pipe Health Monitoring Robot", Pub. No. 36/2020, IPC H01M; G11B, 2020 (Granted)

Invited Reviewer

- Proceedings of the IMechE, Part E: Journal of Process Mechanical Engineering
- Journal of Smart Materials and Structures

Honors and Awards

2022	National	ISSS Technology Award - 2022 for Bio-inspired Muscle Actuator
2022	IIT Kanpur	Honoured for Coordinator role in 44 th & 45 th HAL Training Program
2017	Tata Motors	"Outstanding" assessment in annual performance appraisal
2016	IIT Kanpur	Runner-up for Best M.Tech. Thesis among all engineering disciplines.
2014	$1^{\rm st}/21$	Best Engineering Summer Project Award, Whirlpool India
2014	Top $21/2500$	Whirlpool Young Leaders Program Fellow
2013	$2^{\rm nd}/200$	National level case study competition Manthan by CAG
2013	IIT Bombay	Certificate of Engineering Excellence, Inter-College Robowar Event
2012	IIT Kanpur	Recipient of Merit-cum-Means Scholarship
2012	$1^{\rm st}$ prize	Inter-College Combat Robot Tournament, Techkriti, IIT Kanpur
2012	IIT Kanpur	Certificate of Appreciation for a project in Manufacturing Science
2011	National	Secured IIT-JEE All India Rank – 1802 (99.62 percentile)
2010	National	Merit Certificate by UP State Govt. for 100/100 in Maths (12 th Grade)

Professional Experience (7.5+ years) Indian Institute of Technology (IIT) Kanpur, Mechanical Engineering, Kanpur, India
Senior Project Scientist (Apr'19-Present)

- Conducting R&D activities leading to translation of research for end-users via industrial partners.
- Drafting research proposals to various sponsoring agencies and securing a grant of \$274,700.
- Delivering strong project leadership skills via project initiation, planning, & execution phases.
- Applying and validating analytical & numerical methods to solve dynamic models and applied mechanics problems related to product performance and processes.
- Led design team and collaborated with research associates and technologists. Identification of failures and improvement in processes based on Design failure mode and effects analysis (DFMEA).
- Designed & fabricated robot components and performed experiments; gained hands-on experience in additive manufacturing. Prepared and presented reports to cross-functional technical teams.

Tata Motors Ltd., Engineering Research Centre, Pune, India

Senior Manager (Sep'16 - Mar'19)

- Performed multibody modeling and vehicle dynamics simulation of Futuristic Infantry Combat Vehicle (FICV) in LMS Virtual.Lab motion solver environment.
- Analyzed infield failures and resolve issues by designing Interior Trim components across commercial vehicle platforms range. Collaborated with Noise, Vibration & Harshness (NVH) and Engine teams to propose optimal acoustic and thermal packages based on testing & CFD analysis.
- Prepared and processed DFMEAs, drafted benchmark reports, and ensure all quality standards are met by analyzing and efficiently responding to customer feedback.
- Formulated product innovation strategies; Co-led team of 12 to implement new technology development projects across multiple vehicle platforms. Strong expertise in managing project gateways, design, estimation, resource allocation, risk management & interfacing with stakeholders.

Whirlpool of India Ltd., Global Technology and Engineering Centre, Pune, India

Summer Intern (Mav'14 - Jun'14)

- Studied Gyroscopic Effect in end spinning of drum-type washing machine and performed dynamic modeling of washer in MATLAB Simulink.
- Proposed a novel design having an increment in maximum end-spin velocity by 250 RPM leading to a decrease in drying time compared to benchmarked products.

INVITED TALK & SUMMITS

- [1] Future of Work: Industry 4.0, Innovation and 21st Century Skills., Presented at Y20 Summit G20 Youth Consultation Forum (Apr'23), IIT Kanpur, India.
- [2] Sustainability Transformation to a Resilient Society, Invited Speaker at YNU International Symposium (Dec'22), Yokohama National University, Japan.

[3] Adaptive Intelligent Pipe Health Monitoring Robot, Exhibited among 75 National Projects at IInvenTiv (23 IITs R&D Fair) under Ministry of Education, Govt. of India (Oct'22).

RESEARCH PROJECTS

Bio-inspired shape memory alloy-based artificial muscle (Bipennate) actuation system

 ${\tt SPONSORED} \ R\&D \ {\tt PROJECT} \ | \ {\sf PI:} \ {\sf Prof.} \ {\tt Bishakh} \ {\tt Bhattacharya}, \ {\sf IIT} \ {\sf Kanpur} \ ({\tt Jun'21-Ongoing})$

- Integrated bio-inspired design principles in developing bipennate muscle configured shape memory alloy powered actuators for valve control and prosthetic applications.
- Led a team of 4 to develop and experimentally validate an analytical model for a high-force actuator (257 N with 15 V input). Benchmarked the system against industry-developed actuator, achieved 67% reduction in weight, 32% in cost and 19% energy savings with SMA driven system.

Compressed Air-based Cargo Hyperloop (CABCH) mobility system

Pls: Prof. B. Bhattacharya, Prof. G. Biswas, & Prof. A. K. Varma, IIT Kanpur (Dec'22-Ongoing)

- Developing a CAD and mathematical model for a pipe-following modular robotic system carrying a series of cargo modules used for transporting powered by the drag force of the compressed-air flow with a designed target velocity of 180 km/hr.
- Demonstrated a scaled-down working model showcasing system levitation using air lubrication theory at G20 Youth Consultation Summit (Y20) Future of Work: Industry 4.0 & Innovation.

Passive speed control system for Pipeline Health Monitoring Robot (PHMR)

SPONSORED R&D PROJECT | PI: Prof. Bishakh Bhattacharya, IIT Kanpur (Apr'19 - Apr'21)

- Designed, modeled, and experimentally validated the speed control system for an 8-inch pipeline diameter for a PHMR to improve the effectiveness of inspection tool during pipeline pigging.
- Led a team of 15 and tested the system at 3.2 bar pressure and reported to passively regulate any undesirable high-speed spikes maximum by 51% within the acceptable range. Novel system design with dual integration of bypass leakage flow and hydro-mechanical brake mechanisms.

A novel and robust Cabin Pressure Control System (CPCS) for combat aircraft using active smart valve system (Supported by: Hindustan Aeronautics Limited, Lucknow)

MASTER'S THESIS | Advisors: Dr. B. Bhattacharya & Dr. A. K. Varma, IIT Kanpur (Jun'15 - May'16)

- Developed and validated mathematical model for design and performance analysis of pneumatically operated CPCS for multirole light combat aircraft.
- Proposed a piezostack-based active smart valve system for infusing robustness into existing CPCS in terms of reliability, accuracy & easy adaptability to any given cabin pressurization law.
- Created a MATLAB program by incorporating isentropic flow theory through convergent-divergent nozzle and gradient descent algorithm to cover steady-state and transient flight conditions for cabin control volume depicting a standard CPCV architecture as per SAE 2000–ARP 1270.

MENTORING EXPERIENCE

- Mentoring 4 **UG** students as a part of undergraduate projects at IIT Kanpur projects ranging from Variable stiffness actuator, Bionic arm, SMA rotary system, and Cargo hyperloop system.
- Mentor for **Summer Interns** (2022 & '23), SMSS Lab IIT Kanpur delivered tutorials on shape memory alloy models & 3D printing techniques and conducted brainstorming sessions.
- Mentor for MS by Research & M.Tech. Students, IIT Kanpur delivered tutorials on Shape Memory Alloy modeling, interacted with student during doubt-clearing sessions.
- Teaching Assistant for Theory of Mechanisms Lab & Smart Material and Structures.

Computer Skills

- Programming Languages: C, C++, Java, Go, Python
- Simulation Softwares: LMS Virtual.Lab, ABAQUS, MATLAB, modeFRONTIER
- Design Environments: CATIA V5, SolidWorks, AutoCAD, Inventor
- Familiar: MS Office, HPC, PLM, IATEX Origin, Tecplot, LabVIEW, 3D Printing slicing software

Relevant Courses

- Smart Materials & Structures
- Introduction to Robotics
- Data Structures & Algorithms

- Computer Aided Engg. Design
- Vibration & Control
- Finite Element Methods

EXTRA-CURRICULAR ACTIVITIES

- Active member of IITK Rock Climbing Club outdoor wall climbing & bouldering sessions.
- Developed and maintaining website for Smart Materials and Systems Lab, IIT Kanpur.
- Volunteered in Tata Motors Community Service Initiatives educational guidance to tribal children, health awareness camp in rural schools and tree plantation drive.
- Won first prize in national level combat robot event held in Techkriti-2012 at IIT Kanpur.