

CS 97SI: INTRODUCTION TO PROGRAMMING CONTESTS

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Today's Lecture

- Stack/Queue
- Heap and Priority Queue
- Union-Find Structure
- Binary Search Tree (BST)
- Binary Indexed Tree (BIT)
- Lowest Common Ancestor (LCA)

Typical Quarter at Stanford

```
void quarter() {  
    while(true) { // no break  
        task x = GetNextTask(tasks);  
        process(x);  
        // new tasks may enter  
    }  
}
```

- `GetNextTask()` decides the order of the tasks

GetNextTask()

- Possible behaviors of `GetNextTask()`:
 - ▣ Returns the newest task (stack)
 - ▣ Returns the oldest task (queue)
 - ▣ Returns the most urgent task (priority queue)
 - ▣ Returns the easiest task (priority queue)
- We want `GetNextTask()` to run quickly
 - ▣ ... by organizing the tasks in a clever way

Stack

- Last in, first out (LIFO)
- Supports three constant-time operations
 - ▣ `Push(x)`: inserts x into the stack
 - ▣ `Pop()`: removes the newest item
 - ▣ `Top()`: returns the newest item
- Very easy implementation using arrays

Stack Implementation

- Have a large enough array `s[]` and a counter `k`, which starts at zero
 - ▣ `Push(x)`: set `s[k] = x` and increment `k` by 1
 - ▣ `Pop()`: decrement `k` by 1
 - ▣ `Top()`: returns `s[k - 1]` (error if `k` is zero)
- C++ and Java have implementations of stack
 - ▣ `stack` (C++), `Stack` (Java)
- But you should be able to implement it from scratch

Queue

- First in, first out (FIFO)
- Supports three constant-time operations
 - ▣ `Enqueue(x)`: inserts x into the queue
 - ▣ `Dequeue()`: removes the oldest item
 - ▣ `Front()`: returns the oldest item
- Implementation is similar to that of stack
 - ▣ Just slightly trickier

Queue Implementation

- In many cases, you know the total number of elements that enter a queue
 - ▣ ... which allows you to use an array for implementation
- Maintain two indices `head` and `tail`
 - ▣ `Dequeue()` increments `head`
 - ▣ `Enqueue()` increments `tail`
 - ▣ Use the value of `tail - head` to check emptiness
- You can use `queue` (C++) and `Queue` (Java)

Priority Queue

- Each element in a PQ has a priority value
- Three operations:
 - ▣ `Insert(x, p)`: inserts `x` into the PQ, whose priority is `p`
 - ▣ `RemoveTop()`: removes the element with the highest priority
 - ▣ `Top()`: returns the element with the highest priority
- All operations can be done quickly if implemented using a heap
- `priority_queue` (C++), `PriorityQueue` (Java)

Heap

- Complete binary tree with the heap property:
 - ▣ The value of a node \geq values of its children
- The root node has the maximum value
 - ▣ Constant-time `top()` operation
- Inserting/removing a node can be done in $O(\log n)$ time without breaking the heap property
 - ▣ May need rearrangement of some nodes

Heap Example

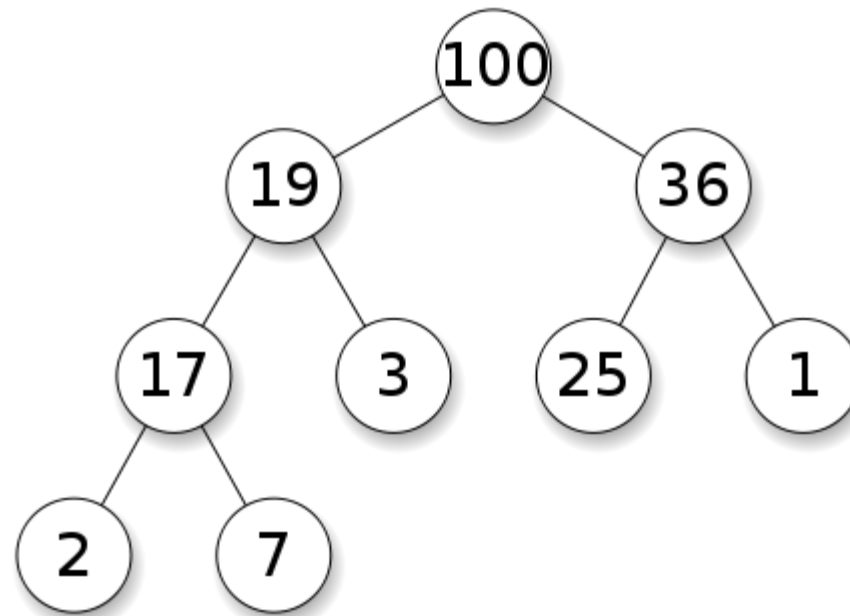
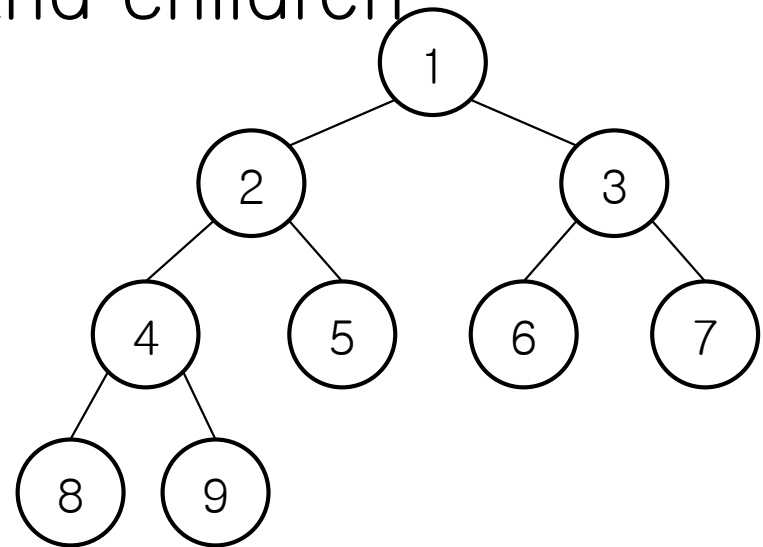


Figure from Wikipedia

Numbering the Nodes

- Start from the root, number the nodes 1, 2, ... from left to right
- Given a node k , easy to compute the indices of its parent and children
 - ▣ Parent node: $\lfloor k/2 \rfloor$
 - ▣ Children: $2k$, $2k + 1$



Inserting a Node

- 1. Make a new node in the last level, as far left as possible
 - ▣ If the last level is full, make a new one
- 2. If the new node breaks the heap property, swap with its parent node
 - ▣ The new node moves up the tree, which may introduce another conflict
- 3. Repeat 2 until all conflicts are resolved
- Running time = tree height = $O(\log n)$

Implementation: Node Insertion

- Inserting a new node with value v into a heap H

```
void InsertNode(int v) {  
    H[++n] = v;  
    for(int k = n; k > 1; k /= 2) {  
        if(H[k] > H[k / 2])  
            swap(H[k], H[k / 2]);  
        else break;  
    }  
}
```

Deleting the Root Node

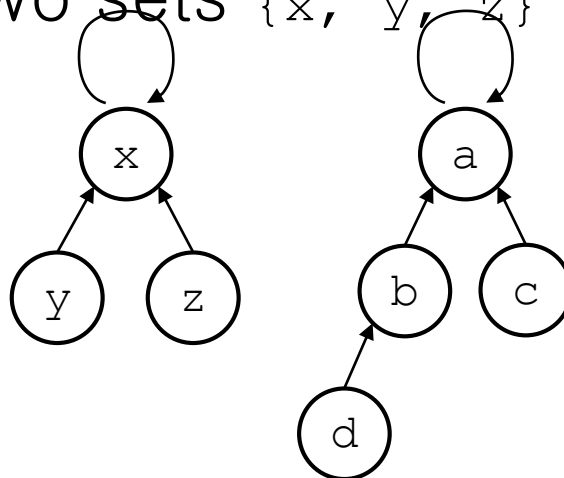
- 1. Remove the root, and bring the last node (rightmost node in the last level) to the root
- 2. If the root breaks the heap property, look at its children and swap it with the larger one
 - ▣ Swapping can introduce another conflict
- 3. Repeat 2 until all conflicts are resolved
- Running time = $O(\log n)$
- Exercise: implementation
 - ▣ Just a few edge cases to consider

Union-Find Structure

- Can support two types of operations efficiently
 - ▣ `Find(x)`: returns the “representative” of the set that x belongs
 - ▣ `Union(x, y)`: merges two sets that contain x and y
- Both operations can be done in (essentially) constant time
- Super-short implementation!

Union-Find Structure

- Main idea: represent each set by a rooted tree
 - ▣ Every node maintains a link to its parent
 - ▣ A root node is the “representative” of the corresponding set
 - ▣ Example: two sets $\{x, y, z\}$ and $\{a, b, c, d\}$



Implementation Idea

- `Find(x)`: follow the links from `x` until a node points itself
 - ▣ This can take $O(n)$ time but we will make it faster
- `Union(x, y)`: run `Find(x)` and `Find(y)` to find corresponding root nodes and direct one to the other

Implementation

- We will assume that the links are stored in $L[]$

```
int Find(int x) {  
    while(x != L[x]) x = L[x];  
    return x;  
}  
  
void Union(int x, int y) {  
    L[Find(x)] = Find(y);  
}
```

Path Compression

- In a bad case, the trees can become too deep
 - ▣ Which slows down the operations
- Path compression makes the trees shallower every time `Find()` is called
- We don't care how a tree looks like as long as the root stays the same
 - ▣ After `Find(x)` returns the root, backtrack to `x` and reroute all the links to the root

Path Compression Implementations

```
int Find(int x) {  
    if(x == L[x]) return x;  
    int root = Find(L[x]);  
    L[x] = root;  
    return root;  
}
```

```
int Find(int x) {  
    return x == L[x] ? x : L[x] = Find(L[x]);  
}
```

Binary Search Tree (BST)

- A binary tree with the following property: for each node v ,
 - ▣ value of $v \geq$ values in v 's left subtree
 - ▣ value of $v \leq$ values in v 's right subtree

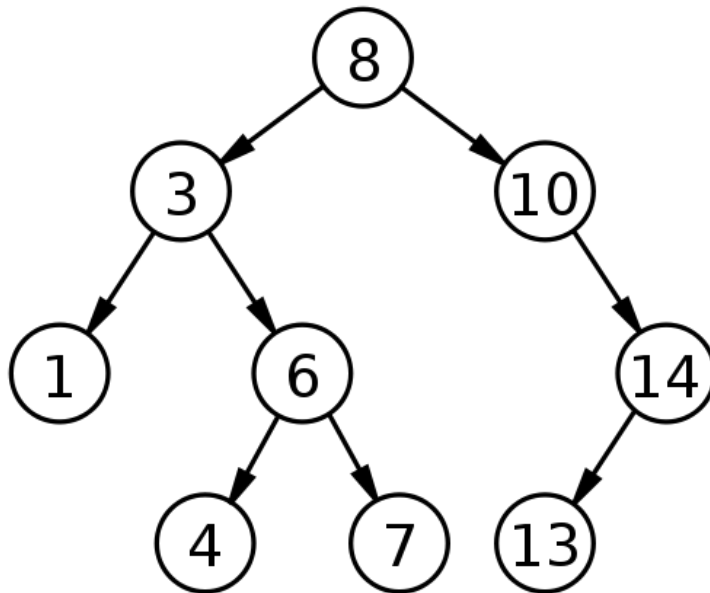


Figure from Wikipedia

What BSTs can do

- Supports three operations
 - ▣ `Insert(x)`: inserts a node with value x
 - ▣ `Delete(x)`: deletes a node with value x , if there is any
 - ▣ `Find(x)`: returns the node with value x , if there is any
- Many extensions are possible
 - ▣ `Count(x)`: counts the number of nodes with value less than or equal to x
 - ▣ `GetNext(x)`: returns the smallest node with value $\geq x$

BSTs in Programming Contests

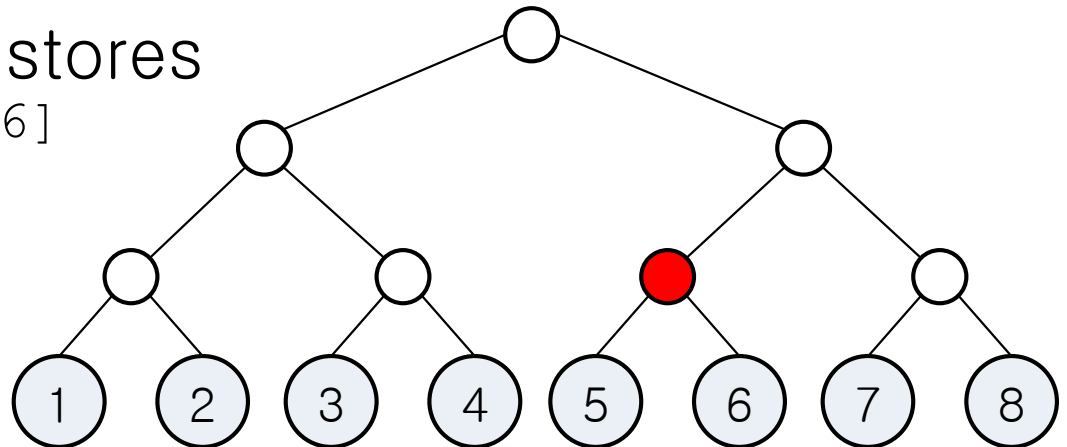
- Simple implementation cannot guarantee efficiency
 - ▣ In worst case, tree height becomes n (which makes BST useless)
 - ▣ Guaranteeing $O(\log n)$ running time per operation requires balancing of the tree (hard to implement)
 - ▣ We will skip the implementation details
- Use the standard library implementations
 - ▣ `set`, `map` (C++)
 - ▣ `TreeSet`, `TreeMap` (Java)

Binary Indexed Tree (BIT)

- A variant of segment trees
- Supports very useful interval operations
 - ▣ $\text{Set}(k, x)$: sets the value of k th item equal to x
 - ▣ $\text{Sum}(k)$: computes the sum of items $1 \dots k$
 - Note: sum of items $i \dots j = \text{Sum}(j) - \text{Sum}(i - 1)$
- Both operations can be done in $O(\log n)$ time using $O(n)$ space

BIT Structure

- Full binary tree with at least n leaf nodes
 - ▣ We will use $n = 8$ for our example
- k th leaf node stores the value of item k
- Each internal node stores the sum of values of its children
 - ▣ e.g. Red node stores $\text{item}[5] + \text{item}[6]$

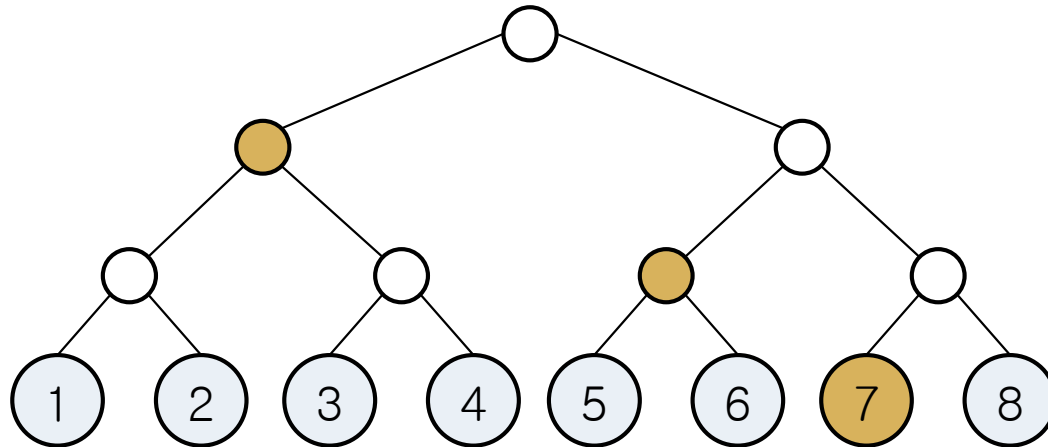


Summing Consecutive Values

- Main idea: choose the minimal set of nodes whose sum gives the desired value
- We will see that
 - ▣ at most 1 node is chosen at each level so that the total number of nodes we look at is $\log_2 n$
 - ▣ and this can be done in $O(\log n)$ time
- Let's start with some examples

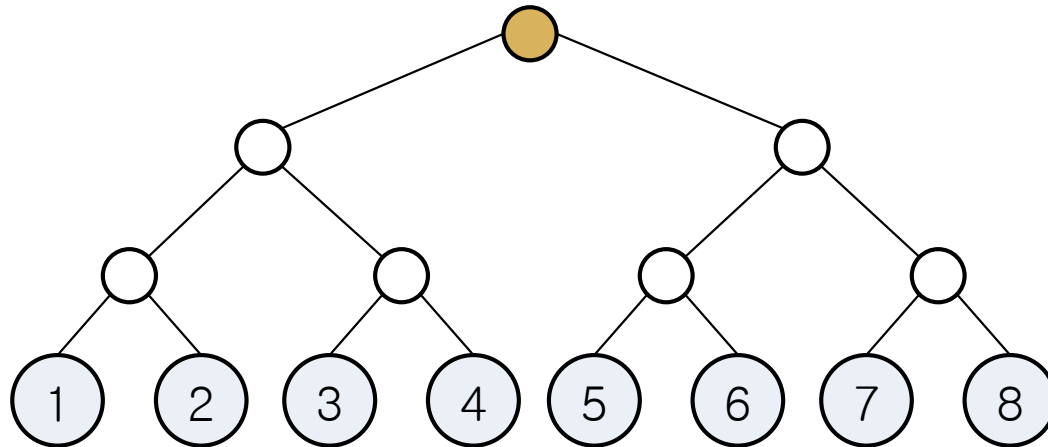
Summing: Example 1

- $\text{Sum}(7)$ = sum of the values of gold-colored nodes



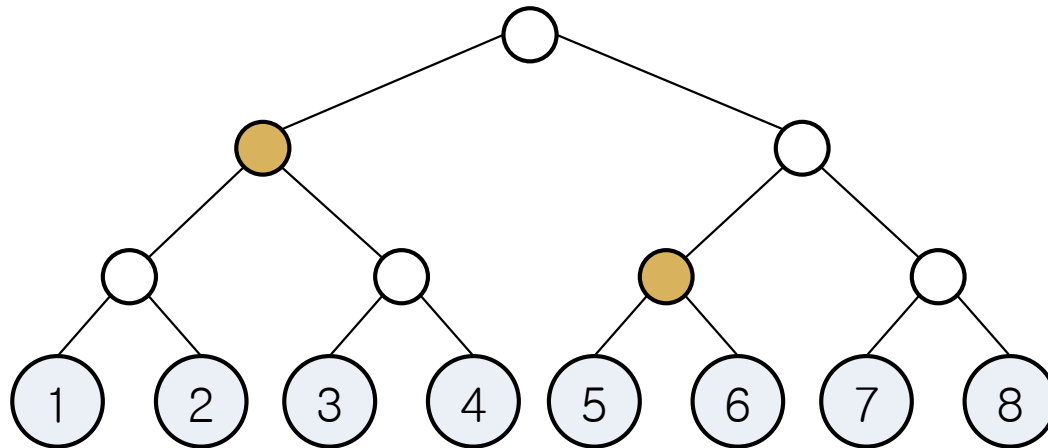
Summing: Example 2

□ Sum (8)



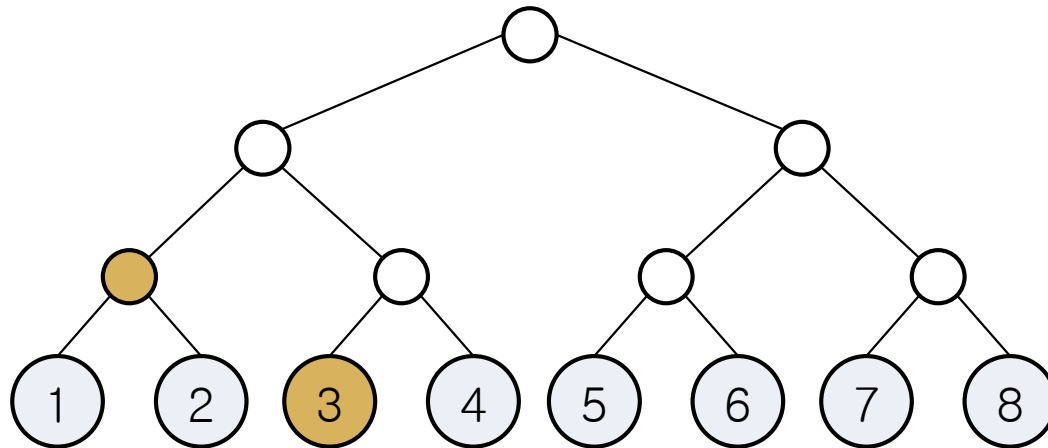
Summing: Example 3

□ Sum (6)



Summing: Last Example

□ Sum (3)



Implementing $\text{Sum}(k)$

- Maintain a pointer P which initially points at leaf k
- Climb the tree using the following procedure:
 - ▣ If P is pointing to a left child of some node:
 - Add the value of P
 - Set P to the parent node of P 's left neighbor
 - If P has no left neighbor, terminate
 - ▣ Otherwise:
 - Set P to the parent node of P
- Use an array to implement (review the heap section)

Updating a Value: $\text{Set}(k, x)$

- This part is a lot easier
- Only the values of leaf k and its ancestors change
- 1. Start at leaf k , change its value to x
- 2. Go to its parent, and recompute its value
- 3. Repeat 2 until the root

Extension

- Make the `Sum()` function work for any interval
 - ▣ ... not just ones that start from item 1
- Can support more operations with the new `Sum()` function
 - ▣ `Min(i, j)`: Minimum element among items $i...j$
 - ▣ `Max(i, j)`: Maximum element among items $i...j$

Lowest Common Ancestor (LCA)

- Input: a rooted tree and a bunch of node pairs
- Output: lowest (deepest) common ancestors of the given pairs of nodes
- Goal: preprocessing the tree in $O(n \log n)$ time in order to answer each LCA query in $O(\log n)$ time

Preprocessing

- Each node stores its depth, as well as the links to every 2^k th ancestor
 - ▣ $O(\log n)$ additional storage per node
 - ▣ We will use $\text{Anc}[x][k]$ to denote the 2^k th ancestor of node x
- Computing $\text{Anc}[x][k]$
 - ▣ $\text{Anc}[x][0] = x$'s parent
 - ▣ $\text{Anc}[x][k] = \text{Anc}[\text{Anc}[x][k-1]][k-1]$

Answering a Query

- Given two node indices x and y
 - ▣ Without loss of generality, assume $\text{depth}(x) \leq \text{depth}(y)$
- Maintain two pointers p and q , initially pointing at x and y
- If $\text{depth}(p) < \text{depth}(q)$, bring q to the same depth as p
 - ▣ using Anc that we computed before
- Now we will assume that $\text{depth}(p) = \text{depth}(q)$

Answering a Query

- If p and q are the same, return p
- Otherwise, initialize k as $\lfloor \log_2 n \rfloor$ and repeat:
 - ▣ If k is 0, return p 's parent node
 - ▣ If $\text{Anc}[p][k]$ is undefined, or if $\text{Anc}[p][k]$ and $\text{Anc}[q][k]$ point to the same node:
 - Decrease k by 1
 - ▣ Otherwise:
 - Set $p = \text{Anc}[p][k]$ and $q = \text{Anc}[q][k]$ to bring p and q up by 2^k levels

Conclusion

- We covered LOTS of stuff today
 - ▣ Try many small examples with pencil and paper to completely internalize the material
 - ▣ Review and solve relevant problems
- Discussion and collaboration are strongly recommended!