

HW 7

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(2)

a) Let $k_1(x, x') = \psi_1(x)^T \psi_1(x')$, $k_2(x, x') = \psi_2(x)^T \psi_2(x')$.

Then $k_3(x, x') = k_1(x, x') + k_2(x, x')$

$$= \psi_1(x)^T \psi_1(x') + \psi_2(x)^T \psi_2(x')$$

$$= \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \end{pmatrix}^T \begin{pmatrix} \psi_1(x') \\ \psi_2(x') \end{pmatrix}$$

$$= \psi_3(x)^T \psi_3(x')$$

$$\left[\text{substitution } \psi_3(x) = \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \end{pmatrix} \right]$$

Feature map is therefore $\psi_3(x) = \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \end{pmatrix}$. \square

b)

Let $k_1(x, x') = \psi_1(x)^T \psi_1(x')$, $k_2(x, x') = \psi_2(x)^T \psi_2(x')$

Then, $k_p(x, x') = k_1(x, x') k_2(x, x')$

$$= \psi_1(x)^T \psi_1(x') \psi_2(x)^T \psi_2(x')$$

Now assume $\psi_1(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_d(x) \end{pmatrix}$, $\psi_2(x) = \begin{pmatrix} g_1(x) \\ g_2(x) \\ \vdots \\ g_{d'}(x) \end{pmatrix}$

Then,

$$k_p(x, x') = \sum_{i=1}^d f_i(x) f_i(x') \sum_{j=1}^{d'} g_j(x) g_j(x')$$

$$= \sum_{i=1}^d \sum_{j=1}^{d'} f_i(x) g_j(x) f_i(x') g_j(x')$$

$$= \sum_{i=1}^d \sum_{j=1}^{d'} h_{ij}(x) h_{ij}(x')$$

$$= \psi_p(x)^T \psi_p(x'), \quad \text{where}$$

$$\psi_p(x) = \begin{pmatrix} h_{1,1}(x) \\ h_{2,1}(x) \\ \vdots \\ h_{d,d'}(x) \end{pmatrix} = \begin{pmatrix} f_1(x) g_1(x) \\ f_2(x) g_1(x) \\ \vdots \\ f_d(x) g_{d'}(x) \end{pmatrix}$$

Q

①

$$2) J(w) = \frac{1}{N} \sum_{i=1}^N \mathcal{L}(y^{(i)}, t^{(i)}) + \frac{\lambda}{2} \|w\|^2$$

Let $S =$ row space of $\Phi = \text{span} \{ \psi(x^{(i)})^T, i = 1, 2, \dots, N \}$.

Then, $w = w_S + w_{\perp}$, where w_S is the projection of w onto S and w_{\perp} is orthogonal to S (Hint).

Let w^* be a minimizer for $J(w)$.

Then,

$$\begin{aligned} J(w^*) &= \frac{1}{N} \sum_{i=1}^N \mathcal{L}(g(w^{*T} \psi(x)), t^{(i)}) + \frac{\lambda}{2} \|w^*\|^2 \\ &= \frac{1}{N} \sum_{i=1}^N \mathcal{L}(g(w_S^{*T} \psi(x)), t^{(i)}) + \frac{\lambda}{2} \|w_S^*\|^2 + \frac{\lambda}{2} \|w_{\perp}^*\|^2 \\ &\geq \frac{1}{N} \sum_{i=1}^N \mathcal{L}(g(w_S^{*T} \psi(x)), t^{(i)}) + \frac{\lambda}{2} \|w_S^*\|^2 \\ &= J(w_S^*). \end{aligned}$$

This means that for every minimizer w^* , the projection of w^* onto S is actually the real global minimum.

In other words, the optimal weights lie in $\text{span} \{ \psi(x^{(i)})^T \}, i = 0, 1, \dots, N$

□

$$b) \quad J(w) = \frac{1}{2N} \|t - \Psi w\|^2 + \frac{\lambda}{2} \|w\|^2$$

$$J(\alpha) = \frac{1}{2N} \|t - \Psi \Psi^T \alpha\|^2 + \frac{\lambda}{2} \|\Psi^T \alpha\|^2 \quad \left[\begin{array}{l} \text{Substitution} \\ w = \Psi^T \alpha \end{array} \right]$$

$$= \frac{1}{2N} \|t - K \alpha\|^2 + \frac{\lambda}{2} \|\Psi \cdot \alpha\|^2$$

dot-product

In order to find a candidate for minimizing this function, we can set its gradient equal to zero:

$$\nabla J(\alpha) = \frac{1}{2N} \cdot 2 \cdot (-K) \cdot (t - K\alpha) + \frac{\lambda}{2} \cdot 2 \cdot \Psi \cdot (\Psi \cdot \alpha)$$

$$= -\frac{1}{N} K (t - K\alpha) + \lambda \underbrace{\Psi \Psi^T}_K \alpha$$

$$= \frac{1}{N} K^2 \alpha - \frac{1}{N} K t + \lambda K \alpha = 0$$

$$\Rightarrow \left(\frac{1}{N} K - \lambda I \right) \alpha = \frac{1}{N} t$$

[First multiply both sides by K^{-1}
then move $\frac{1}{N} t$ to RHS]

[Note: I = identity matrix of the same size as K].

$$\Rightarrow \alpha = \frac{1}{N} \left(\frac{1}{N} K - \lambda I \right)^{-1} t$$

The only candidate is therefore $\alpha_0 = \frac{1}{N} \left(\frac{1}{N} K - \lambda I \right)^{-1} t$.

To check that this is a real (global) minimum, we need to

verify that $HJ(\alpha_0) > 0$ [the Hessian of J evaluated at α_0 is positive-definite]

$$HJ(\alpha_0) = HJ(\alpha) \Big|_{\alpha=\alpha_0} = \frac{1}{N} K^2 + \lambda K \Big|_{\alpha=\alpha_0} = \frac{1}{N} K^2 + \lambda K.$$

Since K is positive-definite by assumption and N, λ are both greater than zero, we can conclude that $HJ(\alpha_0) > 0$.

$\therefore \alpha_0 = \frac{1}{N} \left(\frac{1}{N} K - \lambda I \right)^{-1} t$ is the only global minimum

□