

# Feasibility of Using Behavioral Marker via Mobile Sensors in Measuring Physical Activity: A Pilot Study

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# **♦** Background

- Direct observation of behaviors is the main assessment method of behavior analysis(Pierce & Cheney, 2013). However, data collection is limited due to practical difficulties of collecting vast amount of information with accuracy(Gardner, 2000).
- Recently, mobile sensors have emerged as an effective and efficient way to measure passive data for behaviors (Rohani et al., 2018), as mobile sensors allow the collection of data as they occur, thus minimizing the loss of data.
- However, the use of passive data in behavioral research has not been fully investigated in terms of reliability and validity, calling for further research to confirm the consistency between the collected passive data and the participant's self-reports. (Singh & Agarwal, 2016).

## **♦** Purpose

 The purpose of this study was to test the feasibility of using passive data collected via mobile sensors in explaining self-report regarding physical activity.

#### **♦** Method

## **Participants**

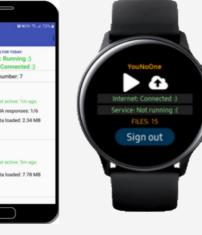
• 15 college students (Age mean=28.4; male N=9, female N=6)

## **Procedure**

- For 15 days
- YouNoOne, mobile sensing software, on smartphone and smartwatch(Samsung Galaxy Gear S3, Active)
- Data collection

Passive data	Self-report (EMA*)
<ul><li>Heart rate(HRM)</li><li>Step counts</li><li>Significant motion counts</li></ul>	<ul> <li>Q. Your status in last 10 minutes?</li> <li>1. Status (study, rest, exercise, eat, on transportation, talk)</li> <li>2. Intensity (1~5)</li> <li>3. Location (home, study place, workplace, outside)</li> <li>4. Ability to move (yes or no)</li> </ul>
- 24 hours / 7days	- 6 times a day





YouNoOne

## **Data Analysis**

 Hierarchical linear regressions were conducted to examine explanation power of passive sensing data on self-reported physical activity in SPSS 25.

\* Ecological Momentary Assessment

## **♦** Results

 After controlling for the location and ability to move, passive data significantly and uniquely accounted for the self-reported status of physical activity(F(5,63) = 27.046, p<0.01,  $\Delta R^2$  = 0.067), but not the intensity.

Table 1. Effect of passive sensing data on self-reported status of physical activity

•	. ,		,		•
redictor	В	SE	β	t	Predictor
Block 1					Block 1
onstant	.03	.04		.65	Constant
oummy1_location	03	.11	02	24	Dummy1_location
oummy3_location	03	.12	02	22	Dummy3_location
oummy4_location	.67	.09	.70	7.72	Dummy4_location
oummy5_location	03	.11	02	22	Dummy5_location
ummy6 location	22	13	16	1 73	Dummy6 location

Dummy3_location	03	.12	02	22
Dummy4_location	.67	.09	.70	7.72
Dummy5_location	03	.11	02	22
Dummy6_location	22	.13	.16	1.73
$R^2 = .511$				
Block 2				
Constant	.06	.10		.56
Dummy1_location	02	.11 -	.02 -	20
Dummy3_location	03	.12 -	.02 -	24
Dummy4_location	.67	.09	.70	7.67
Dummy5_location	05	.14 -	.04 -	35
Dummy6_location	.23	.13	.16	1.74
Dummy_ability	03	.10 -	.03	32
$\Delta R^2 = .512$				
$R^2 = .001$				
Block 3				
Constant	.60	.26	4	2.29
Dummy1_location	05	.11 -	.04 -	47
Dummy3_location	08	.11 -	.06	.73
Dummy4_location	.71	.10	.73	7.76
Dummy5_location	12	.14 -	.10 -	88
Dummy6_location	.22	.13	.15	1.78
Dummy_ability	14	.11 -	.14 -	-1.26
HRM	01	.00	.26 -	-2.17
Step_counts	.00	.00 -	.03 -	21
SigMotion_counts	.01	.00 -	.25	2.58

 $\Delta R^2 = .580$ 

 $R^2 = .067^*$ 

Table 2. Effect of passive sensing data on self-reported intensity of physical activity

SE

Constant       .03       .04       .59         Dummy1_location      03       .12      02      22         Dummy3_location      03       .13      01      20         Dummy4_location      03       .13      01      20         Dummy6_location      22       .14       .11       1.58         R2 = .682       Block 2         Constant       .01       .11      04         Dummy1_location      03       .12      02      24         Dummy3_location      02       .13      01      17         Dummy4_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001       .01       .23       .15       .05         Dummy1_location      04       .13      03       .33         Dummy4_location      04       .13      03       .33         Dummy5_location      04       .13      01      14         Dummy6_location       .02       .16	Block 1				
Dummy3_location        03         .13        01        20           Dummy4_location         1.07         .10         .82         9.19           Dummy5_location        03         .13        01        20           Dummy6_location        22         .14         .11         1.58           R2 = .682         Block 2         Block 2         Block 2           Constant         .01         .11        04         Dummy1_location        02        24           Dummy1_location        02         .13        01        17           Dummy4_location        00         .15        01        02           Dummy6_location         .22         .14         .11         1.54           Dummyability        03         .11        03        30           AR2 = .683         R2 = .001         R2 = .001         R3         R3         R3         R3           Dummy1_location        04         .12        03        33         R3           Dummy3_location        04         .12        03        33           Dummy4_location         .94         .10         .85         10.32	Constant	.03	.04		.59
Dummy4_location       1.07       .10       .82       9.19         Dummy5_location      03       .13      01      20         Dummy6_location      22       .14       .11       1.58         R2 = .682       .682         Block 2       .00       .01       .11      04         Dummy1_location      03       .12      02      24         Dummy3_location      02       .13      01      17         Dummy4_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001       .055       .055         Dummy1_location      04       .12      03      33         Dummy1_location      04       .12      03      33         Dummy4_location       .94       .10       .85       10.32         Dummy6_location      02       .16      01      14         Dummy6_location      02       .16      01      14         Dummy6_location       .23       .1	Dummy1_location	03	.12	02	22
Dummy5_location      03       .13      01      20         Dummy6_location      22       .14       .11       1.58         R2 = .682       .682         Block 2       .01       .11      04         Dummy1_location      03       .12      02      24         Dummy3_location      02       .13      01      17         Dummy4_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001       .04       .12      03      33         Dummy1_location      04       .12      03      33         Dummy1_location      04       .13      03       .33         Dummy4_location      94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy6_location       .00	Dummy3_location	03	.13	01	20
Dummy6_location      22      14      11       1.58         R² = .682       Block 2       Constant      01      11      04         Dummy1_location      03      12      02      24         Dummy3_location      02      13      01      17         Dummy5_location      00      15      01      02         Dummy6_location      22      14      11       154         Dummy_ability      03      11      03      30         AR² = .683       R² = .001       Block 3       Block 3       Block 3         Constant      17      31       055       033         Dummy1_location      04      12      03      33         Dummy4_location      04      13      03      33         Dummy4_location      04      13      03      33         Dummy6_location      02      16      01      14         Dummy6_location      23      15      12       1.53         Dummy6_location      20      21      21      21 <tr< th=""><th>Dummy4_location</th><th>1.07</th><th>.10</th><th>.82</th><th>9.19</th></tr<>	Dummy4_location	1.07	.10	.82	9.19
R2 = .682   Slock 2   Slock 3   Sl	Dummy5_location	03	.13	01	20
Constant	Dummy6_location	22	.14	.11	1.58
Constant       .01       .11      04         Dummy1_location      03       .12      02      24         Dummy3_location      02       .13      01      17         Dummy4_location       1.1       .10       .82       9.58         Dummy5_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001         Block 3       3       0.55         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .01       .00      06      55 <t< th=""><th><math>R^2 = .682</math></th><th></th><th></th><th></th><th></th></t<>	$R^2 = .682$				
Dummy1_location        03         .12        02        24           Dummy3_location        02         .13        01        17           Dummy4_location         1.1         .10         .82         9.58           Dummy5_location        00         .15        01        02           Dummy6_location         .22         .14         .11         1.54           Dummy_ability        03         .11        03        30           AR2 = .683         R2 = .001         .04         .12        03        33           Block 3         .00         .04         .12        03        33           Dummy1_location        04         .12        03        33           Dummy3_location        04         .13        03         .33           Dummy4_location         .94         .10         .85         10.32           Dummy6_location         .23         .15         .12         1.53           Dummy_ability        02         .13        01        14           Dummy_ability        02         .13        01        049           Step_counts         .01         .00 <th></th> <th></th> <th></th> <th></th> <th></th>					
Dummy3_location      02       .13      01      17         Dummy4_location       1.1       .10       .82       9.58         Dummy5_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683      001         Block 3      001       .12      03      33         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .01       .00      06      55         AR2 = .688	Constant	.01	.11		04
Dummy4_location       1.1       .10       .82       9.58         Dummy5_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001         Block 3       3       3       3         Constant       .17       .31       0.55         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      06      55         AR2 = .688	Dummy1_location	03	.12	02	24
Dummy5_location      00       .15      01      02         Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001         Block 3       .00       .01       .055         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      05      55         AR2 = .688	Dummy3_location	02	.13	01	17
Dummy6_location       .22       .14       .11       1.54         Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001         Block 3       .17       .31       0.55         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      05      55         AR2 = .688	Dummy4_location	1.1	.10	.82	9.58
Dummy_ability      03       .11      03      30         AR2 = .683       R2 = .001         Block 3       Constant       .17       .31       0.55         Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      06      55         AR2 = .688	Dummy5_location	00	.15	01	02
AR <sup>2</sup> = .683  R <sup>2</sup> = .001  Block 3  Constant	Dummy6_location	.22	.14	.11	1.54
R <sup>2</sup> = .001  Block 3  Constant	Dummy_ability	03	.11	03	30
Constant .17 .31 0.55  Commy1_location04 .120333  Cummy3_location04 .1303 .33  Cummy4_location .94 .10 .85 10.32  Cummy5_location02 .160114  Cummy6_location .23 .15 .12 1.53  Cummy_ability02 .1301 -0.13  Clark	$\Delta R^2 = .683$				
Constant       .17 .31       0.55         Cummy1_location      04 .120333         Cummy3_location      04 .1303 .33         Cummy4_location       .94 .10 .85 10.32         Cummy5_location      02 .160114         Cummy6_location       .23 .15 .12 1.53         Cummy_ability      02 .1301 -0.13         HRM      00 .00 .05 -0.49         Step_counts       .00 .000780         SigMotion_counts       .01 .000655         AR2 = .688	$R^2 = .001$				
Dummy1_location      04       .12      03      33         Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR2 = .688	Block 3				
Dummy3_location      04       .13      03       .33         Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR2 = .688	Constant	.17	.31		0.55
Dummy4_location       .94       .10       .85       10.32         Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR2 = .688	Dummy1_location	04	.12	03	33
Dummy5_location      02       .16      01      14         Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR² = .688	Dummy3_location	04	.13	03	.33
Dummy6_location       .23       .15       .12       1.53         Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR² = .688	Dummy4_location	.94	.10	.85	10.32
Dummy_ability      02       .13      01       -0.13         HRM      00       .00       .05       -0.49         Step_counts       .00       .00      07      80         SigMotion_counts       .01       .00      06      55         AR² = .688	Dummy5_location	02	.16	01	14
00 .00 .05 -0.49  Step_counts .00 .000780  SigMotion_counts .01 .000655  AR <sup>2</sup> = .688	Dummy6_location	.23	.15	.12	1.53
Step_counts       .00 .000780         SigMotion_counts       .01 .000655         AR² = .688	Dummy_ability	02	.13	01	-0.13
SigMotion_counts .01 .000655 $AR^2 = .688$	HRM	00	.00	.05	-0.49
$\Delta R^2 = .688$	Step_counts	.00	.00	07	80
	SigMotion_counts	.01	.00	06	55
$R^2 = .005$	$\Delta R^2 = .688$				
	$R^2 = .005$				

#### Discussion

- The significant R<sup>2</sup> suggests that passive data accounts for 6.7% of the self-reported status of physical activity, and thus suggests that passive data is feasible in measuring physical activity.
- However, passive data did not significantly explain the selfreported intensity of physical activity. A possible reason may be that there is less variation possible in intensity, compared to status. This further suggests that passive data may not be sensitive enough to detect subtle changes in the intensity of physical activity.
- The results indicate that passive data collected via mobile sensing can partially explain the self-reported status of physical activity and has the potential to be used to measuring behaviors in the context of physical activity.
- However, further studies should include various sensors to measure physical activity and should use more reliable selfreport questionnaires to enhance the explanation power of passive data on self-reported physical activity data.

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