

Optimization - 4

Agenda :-

- ① Recap
- ② Constrained Optimization
- ③ GD \rightarrow code
- ④ Computing gradients of function

① Recap :-

$$\min_{\vec{w}, w_0} \left[- \sum y_i * \left(\frac{w^T x + w_0}{\|\vec{w}\|} \right) \right]$$

↓

① Gradient Descent

$$w_i^{t+1} = w_i^t - \eta * \frac{\partial f}{\partial w_i^t}$$

$$f(w_0, w_1, w_2, \dots, w_n) = - \sum y_i * \left(\frac{w^T x_i + w_0}{\|\vec{w}\|} \right)$$

$$\frac{\partial f}{\partial w_1} = \frac{f(w_1 + \Delta, w_2, w_3, \dots, w_n) - f(w_1, w_2, \dots, w_n)}{\Delta}$$

$$f(w_0, w_1, \dots, w_n) = \left[- \sum y_i * \left(\frac{w^T x + w_0}{\|\vec{w}\|} \right) \right]$$

$$= - \sum y_i * \left(\frac{w_1 x_1 + w_2 x_2 + \dots + w_n x_n + w_0}{\|\vec{w}\|} \right)$$

$$= - \sum y_i * \left(\frac{w_1 x_1 + w_2 x_2 + \dots + w_n x_n + w_0}{\sqrt{w_1^2 + w_2^2 + \dots + w_n^2}} \right)$$

$$f = - \sum y_i * \left[\frac{h(w_i)}{g(w_i)} \right]$$

$\textcircled{h/g}$

Idea

→ Computationally expensive.

Soln :-

eq:-

$$\frac{\overset{w_1}{3x} + \overset{w_2}{4y} + \overset{w_0}{4}}{\|w\|}$$

$$\begin{aligned}\|w\| &= \sqrt{w_1^2 + w_2^2} \\ &= \sqrt{3^2 + 4^2} = \boxed{5}\end{aligned}$$

$$\Rightarrow \frac{3x + 4y + 4}{\|w\|}$$

$$= \frac{3x + 4y + 4}{5}$$

$$= \left(\frac{3}{5}\right)x + \left(\frac{4}{5}\right)y + \left(\frac{4}{5}\right)$$

\swarrow \swarrow \swarrow
 w_1 w_2 w_0

$$= \boxed{w_1' x + w_2' y + w_0'} \quad \checkmark$$

$$w_1' = \frac{w_1}{\|w\|} \quad , \quad w_2' = \frac{w_2}{\|w\|} \quad w_0' = \frac{w_0}{\|w\|}$$

$$h/g \rightarrow 1 \Rightarrow$$

$$\min_{\vec{w}, w_0} - \sum y_i \left(\frac{w^T x + w_0}{\| \vec{w} \|} \right)$$

(1)

$$\min_{\vec{w}, w_0} = - \sum y_i (w^T x + w_0)$$

such that $\| \vec{w} \| = 1$ \rightarrow condition

Constrained Optimization

$$f = -\sum y_i * (w^T x_i + w_0)$$

$$f = -\sum y_i * (w_1 x_1 + w_2 x_2 + \dots + w_n x_n + w_0)$$

$$\frac{\partial f}{\partial w_1} = -\sum y_i * x_1$$

$$\frac{\partial f}{\partial w_2} = -\sum y_i * x_2$$

...

$$\frac{\partial f}{\partial w_j} = -\sum y_i * x_j$$

$$w_j^{t+1} = w_j^t - \eta * \frac{\partial f}{\partial w_j^t}$$

$$w_j^{t+1} = w_j^t - \eta * (-\sum y_i * x_j^i)$$

$j \neq 0$ ①

$$f = -\sum y_i * (\cancel{w_1 x_1} + \cancel{w_2 x_2} + \cancel{w_n x_n} + \cancel{w_0})$$

↓

$$\frac{\partial f}{\partial w_0} = -\sum y_i$$

$$w_0^{t+1} = w_0^t - \eta * \left(\frac{\partial f}{\partial w_0^t} \right)$$

$$w_0^{t+1} = w_0^t - \eta * (-\sum y_i)$$

②

* Computing gradients of a function

(Q) $f(x_1, x_2, x_3) = a_1 x_1 + a_2 x_2 + a_3 x_3$

where, $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$, $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$

$$\nabla_{\vec{x}} f(\vec{x}) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \end{bmatrix}$$

$$f = a_1 \underline{x_1} + \cancel{a_2 x_2} + \cancel{a_3 x_3}$$

$$\boxed{\frac{\partial f}{\partial x_1} = a_1}$$

$$\frac{\partial f}{\partial x_2} = a_2$$

$$\frac{\partial f}{\partial x_3} = a_3$$

$$\nabla_{\vec{x}} f = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \vec{a}$$

* general

$$f = \vec{a} \cdot \vec{x}$$

$$\nabla_{\vec{x}} f = \vec{a}$$

$$f = a \cdot x$$

$$\frac{df}{dx} = \textcircled{a}$$

eq 2 :

$$f(x_1, x_2, \dots, x_d) = \vec{x}^T * \vec{x}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix}$$

$$\nabla_{\vec{x}} f = ?$$

Soln $\therefore f = \vec{x}^T * \vec{x}$

$$= [x_1 \ x_2 \ \dots \ x_d]^T \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix}$$

$$= x_1 * x_1 + x_2 * x_2 + \dots + x_d * x_d$$

$$f = \underbrace{x_1^2 + x_2^2 + \dots + x_d^2}$$

$$\nabla_{\vec{x}} f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_d} \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \\ \vdots \\ 2x_d \end{bmatrix}$$

$$= 2 * \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix}$$

$$\nabla_x f = 2 * \vec{x} \quad \checkmark$$

general :

$$f = x * x = x^2$$

$$\frac{df}{dx} = 2x$$

✓

⊛ general form of optimization problem.

optimize \rightarrow $f(\theta)$

such that

$\left. \begin{array}{l} g_1(\theta) \\ g_2(\theta) \\ \vdots \end{array} \right\}$

$\|w\| = 1$

eg:- $\min_{\vec{w}, w_0} - \sum y_i * (w^T x_i + w_0)$

such that

$\|w\| = 1$

(8) Can above problem be solved
using Gradient Descent?

→ NO

$$w_{\text{new}} = w_{\text{old}} - \eta * \Delta_w f$$

↳ Iterative process

Initially, $\|w\| = 1$

eg: $w_1 = 3/5$ ✓

$w_2 = 4/5$ ✓

unconstrained



Constrained



unconstrained'

* Lagrange's Multiplier

eg:- Constrained prob

$$\|w\| = 1$$

$$\|w\| - 1 = 0$$

$$\begin{array}{l} \min_{\theta} \quad \underline{f(\theta)} \\ \text{st, } \left. \begin{array}{l} g_1(\theta) = 0 \\ g_2(\theta) = 0 \\ g_3(\theta) = 0 \\ \vdots \end{array} \right\} \end{array}$$

$$\min_{\theta} \left\{ \underline{f(\theta)} + \lambda_1 * g_1(\theta) + \lambda_2 * g_2(\theta) + \lambda_3 * g_3(\theta) \right\}$$

Lagrange's Multiplier

(eg) ::

$$L = \min_{x, y} \underline{\underline{(x^2 + y^2)}}$$

Such that $\underline{\underline{x + 2y - 1 = 0}}$

$$L = \min_{x, y, \lambda} \left(\underline{\underline{x^2 + y^2 + \lambda(x + 2y - 1)}} \right)$$

$$\frac{\partial L}{\partial x} = 2x + \lambda = 0$$

$$\boxed{\lambda = -2x} \rightarrow \textcircled{1}$$

,

$$\frac{\partial L}{\partial y} = 2y + 2\lambda = 0$$

$$\boxed{\lambda = -y} \rightarrow \textcircled{2}$$

$$\frac{\partial L}{\partial \lambda} = x + 2y - 1 = 0 \rightarrow \textcircled{3}$$

using ① & ② in ③

$$\lambda = -2x$$

$$x = -\frac{\lambda}{2}$$

$$\lambda = -y$$

$$y = -\lambda$$

$$x + 2y - 1 = 0$$

$$-\frac{\lambda}{2} + 2(-\lambda) - 1 = 0$$

$$-\lambda \left(\frac{1}{2} + 2 \right) - 1 = 0$$

$$\lambda \left(\frac{1}{2} + 2 \right) = -1$$

$$\lambda \left(\frac{5}{2} \right) = -1$$

$$\boxed{\lambda = -2/5}$$

using this in eqn (1)

$$y = -1$$

$$\boxed{y = 2/5} \quad \checkmark$$

$$x = -1/2$$

$$= -(-2/5) \times \frac{1}{2}$$

$$\boxed{x = 1/5} \quad \checkmark$$

$$\underline{(Q)} \quad f(x_1, x_2, x_3) = \vec{x}^T * (\vec{x} + \vec{b})$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$$

value of gradient of $f(\vec{x})$
w.r.t \vec{x} ?

$$\nabla_{\vec{x}} f(\vec{x}) = ?$$

$$f = \underline{\vec{x}^T} * (\vec{a} + \vec{b})$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \vec{x}^T = [x_1 \quad x_2 \quad x_3]$$

$$\vec{a} + \vec{b} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$$

$$\vec{a} + \vec{b} = \begin{bmatrix} x_1 + 1 \\ x_2 + 3 \\ x_3 + 5 \end{bmatrix}$$

$$f = \vec{x}^T * (\vec{a} + \vec{b})$$

$$= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} * \begin{bmatrix} x_1 + 1 \\ x_2 + 3 \\ x_3 + 5 \end{bmatrix}$$

$$= x_1 * (x_1 + 1) + x_2 * (x_2 + 3) + x_3 * (x_3 + 5)$$

$$f = \left[x_1^2 + x_1 + x_2^2 + 3x_2 + x_3^2 + 5x_3 \right]$$

$$\nabla_{\vec{x}} f =$$

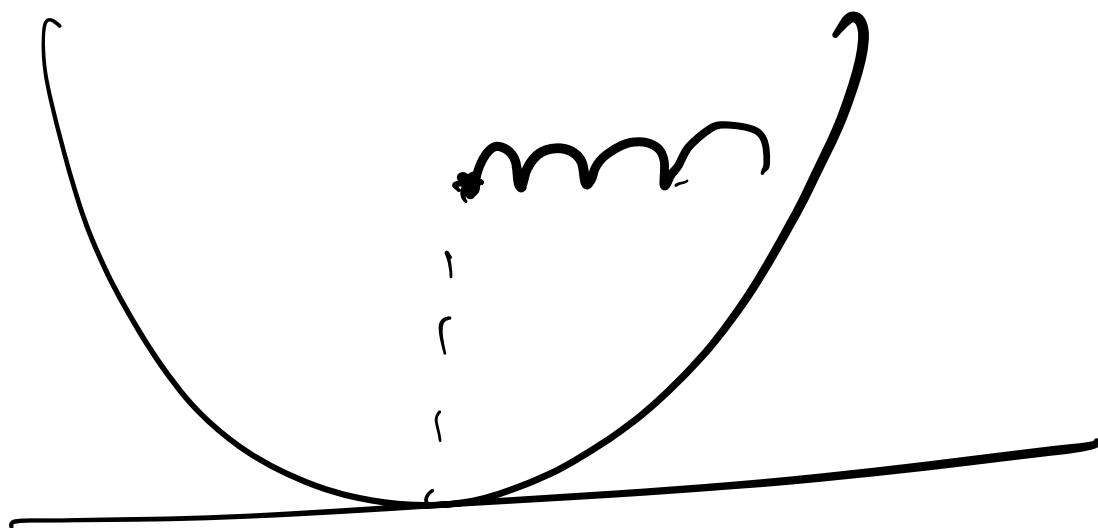
$$\begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \end{bmatrix} = \begin{bmatrix} 2x_1 + 1 \\ 2x_2 + 3 \\ 2x_3 + 5 \end{bmatrix}$$

$$= 2\vec{x} + \vec{b}$$

general : $f = a(a+b)$

$$f = a^2 + ba$$

$$\boxed{\frac{df}{da} = 2a + b}$$



Geiz : $f = \underbrace{w_1 x_1 + w_2 x_2 + w_3 x_3}$

$$\nabla_{\vec{x}} f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \end{bmatrix}$$

$$= \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \quad \left(\vec{w} \right)$$