

22. By Green's Theorem, $\frac{1}{2A} \oint_C x^2 dy = \frac{1}{2A} \iint_D 2x dA = \frac{1}{A} \iint_D x dA = \bar{x}$ and
 $-\frac{1}{2A} \oint_C y^2 dx = -\frac{1}{2A} \iint_D (-2y) dA = \frac{1}{A} \iint_D y dA = \bar{y}$.

23. We orient the quarter-circular region as shown in the figure.

$$A = \frac{1}{4}\pi a^2 \text{ so } \bar{x} = \frac{1}{\pi a^2/2} \oint_C x^2 dy \text{ and } \bar{y} = -\frac{1}{\pi a^2/2} \oint_C y^2 dx.$$

Here $C = C_1 + C_2 + C_3$ where $C_1: x = t, y = 0, 0 \leq t \leq a$;

$C_2: x = a \cos t, y = a \sin t, 0 \leq t \leq \frac{\pi}{2}$; and

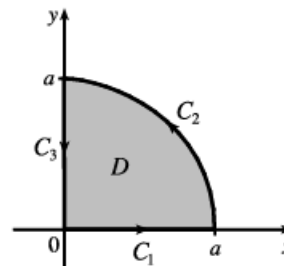
$C_3: x = 0, y = a - t, 0 \leq t \leq a$. Then

$$\begin{aligned} \oint_C x^2 dy &= \int_{C_1} x^2 dy + \int_{C_2} x^2 dy + \int_{C_3} x^2 dy = \int_0^a 0 dt + \int_0^{\pi/2} (a \cos t)^2 (a \cos t) dt + \int_0^a 0 dt \\ &= \int_0^{\pi/2} a^3 \cos^3 t dt = a^3 \int_0^{\pi/2} (1 - \sin^2 t) \cos t dt = a^3 \left[\sin t - \frac{1}{3} \sin^3 t \right]_0^{\pi/2} = \frac{2}{3} a^3 \end{aligned}$$

$$\text{so } \bar{x} = \frac{1}{\pi a^2/2} \oint_C x^2 dy = \frac{4a}{3\pi}.$$

$$\begin{aligned} \oint_C y^2 dx &= \int_{C_1} y^2 dx + \int_{C_2} y^2 dx + \int_{C_3} y^2 dx = \int_0^a 0 dt + \int_0^{\pi/2} (a \sin t)^2 (-a \sin t) dt + \int_0^a 0 dt \\ &= \int_0^{\pi/2} (-a^3 \sin^3 t) dt = -a^3 \int_0^{\pi/2} (1 - \cos^2 t) \sin t dt = -a^3 \left[\frac{1}{3} \cos^3 t - \cos t \right]_0^{\pi/2} = -\frac{2}{3} a^3, \end{aligned}$$

$$\text{so } \bar{y} = -\frac{1}{\pi a^2/2} \oint_C y^2 dx = \frac{4a}{3\pi}. \text{ Thus } (\bar{x}, \bar{y}) = \left(\frac{4a}{3\pi}, \frac{4a}{3\pi} \right).$$



20. No. Assume there is such a \mathbf{G} . Then $\operatorname{div}(\operatorname{curl} \mathbf{G}) = yz - 2yz + 2yz = yz \neq 0$ which contradicts Theorem 11.

For Exercises 23–29, let $\mathbf{F}(x, y, z) = P_1 \mathbf{i} + Q_1 \mathbf{j} + R_1 \mathbf{k}$ and $\mathbf{G}(x, y, z) = P_2 \mathbf{i} + Q_2 \mathbf{j} + R_2 \mathbf{k}$.

$$\begin{aligned} 25. \operatorname{div}(f\mathbf{F}) &= \operatorname{div}(f \langle P_1, Q_1, R_1 \rangle) = \operatorname{div} \langle fP_1, fQ_1, fR_1 \rangle = \frac{\partial(fP_1)}{\partial x} + \frac{\partial(fQ_1)}{\partial y} + \frac{\partial(fR_1)}{\partial z} \\ &= \left(f \frac{\partial P_1}{\partial x} + P_1 \frac{\partial f}{\partial x} \right) + \left(f \frac{\partial Q_1}{\partial y} + Q_1 \frac{\partial f}{\partial y} \right) + \left(f \frac{\partial R_1}{\partial z} + R_1 \frac{\partial f}{\partial z} \right) \\ &= f \left(\frac{\partial P_1}{\partial x} + \frac{\partial Q_1}{\partial y} + \frac{\partial R_1}{\partial z} \right) + \langle P_1, Q_1, R_1 \rangle \cdot \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle = f \operatorname{div} \mathbf{F} + \mathbf{F} \cdot \nabla f \end{aligned}$$

For Exercises 23–29, let $\mathbf{F}(x, y, z) = P_1 \mathbf{i} + Q_1 \mathbf{j} + R_1 \mathbf{k}$ and $\mathbf{G}(x, y, z) = P_2 \mathbf{i} + Q_2 \mathbf{j} + R_2 \mathbf{k}$.

$$\begin{aligned} 26. \operatorname{curl}(f\mathbf{F}) &= \left[\frac{\partial(fR_1)}{\partial y} - \frac{\partial(fQ_1)}{\partial z} \right] \mathbf{i} + \left[\frac{\partial(fP_1)}{\partial z} - \frac{\partial(fR_1)}{\partial x} \right] \mathbf{j} + \left[\frac{\partial(fQ_1)}{\partial x} - \frac{\partial(fP_1)}{\partial y} \right] \mathbf{k} \\ &= \left[f \frac{\partial R_1}{\partial y} + R_1 \frac{\partial f}{\partial y} - f \frac{\partial Q_1}{\partial z} - Q_1 \frac{\partial f}{\partial z} \right] \mathbf{i} + \left[f \frac{\partial P_1}{\partial z} + P_1 \frac{\partial f}{\partial z} - f \frac{\partial R_1}{\partial x} - R_1 \frac{\partial f}{\partial x} \right] \mathbf{j} \\ &\quad + \left[f \frac{\partial Q_1}{\partial x} + Q_1 \frac{\partial f}{\partial x} - f \frac{\partial P_1}{\partial y} - P_1 \frac{\partial f}{\partial y} \right] \mathbf{k} \\ &= f \left[\frac{\partial R_1}{\partial y} - \frac{\partial Q_1}{\partial z} \right] \mathbf{i} + f \left[\frac{\partial P_1}{\partial z} - \frac{\partial R_1}{\partial x} \right] \mathbf{j} + f \left[\frac{\partial Q_1}{\partial x} - \frac{\partial P_1}{\partial y} \right] \mathbf{k} \\ &\quad + \left[R_1 \frac{\partial f}{\partial y} - Q_1 \frac{\partial f}{\partial z} \right] \mathbf{i} + \left[P_1 \frac{\partial f}{\partial z} - R_1 \frac{\partial f}{\partial x} \right] \mathbf{j} + \left[Q_1 \frac{\partial f}{\partial x} - P_1 \frac{\partial f}{\partial y} \right] \mathbf{k} \\ &= f \operatorname{curl} \mathbf{F} + (\nabla f) \times \mathbf{F} \end{aligned}$$

For Exercises 23–29, let $\mathbf{F}(x, y, z) = P_1 \mathbf{i} + Q_1 \mathbf{j} + R_1 \mathbf{k}$ and $\mathbf{G}(x, y, z) = P_2 \mathbf{i} + Q_2 \mathbf{j} + R_2 \mathbf{k}$.

$$\begin{aligned}
 29. \operatorname{curl}(\operatorname{curl} \mathbf{F}) &= \nabla \times (\nabla \times \mathbf{F}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ \partial R_1/\partial y - \partial Q_1/\partial z & \partial P_1/\partial z - \partial R_1/\partial x & \partial Q_1/\partial x - \partial P_1/\partial y \end{vmatrix} \\
 &= \left(\frac{\partial^2 Q_1}{\partial y \partial x} - \frac{\partial^2 P_1}{\partial y^2} - \frac{\partial^2 P_1}{\partial z^2} + \frac{\partial^2 R_1}{\partial z \partial x} \right) \mathbf{i} + \left(\frac{\partial^2 R_1}{\partial z \partial y} - \frac{\partial^2 Q_1}{\partial z^2} - \frac{\partial^2 Q_1}{\partial x^2} + \frac{\partial^2 P_1}{\partial x \partial y} \right) \mathbf{j} \\
 &\quad + \left(\frac{\partial^2 P_1}{\partial x \partial z} - \frac{\partial^2 R_1}{\partial x^2} - \frac{\partial^2 R_1}{\partial y^2} + \frac{\partial^2 Q_1}{\partial y \partial z} \right) \mathbf{k}
 \end{aligned}$$

Now let's consider $\operatorname{grad}(\operatorname{div} \mathbf{F}) - \nabla^2 \mathbf{F}$ and compare with the above.

(Note that $\nabla^2 \mathbf{F}$ is defined on page 1119 [ET 1095].)

$$\begin{aligned}
 \operatorname{grad}(\operatorname{div} \mathbf{F}) - \nabla^2 \mathbf{F} &= \left[\left(\frac{\partial^2 P_1}{\partial x^2} + \frac{\partial^2 Q_1}{\partial x \partial y} + \frac{\partial^2 R_1}{\partial x \partial z} \right) \mathbf{i} + \left(\frac{\partial^2 P_1}{\partial y \partial x} + \frac{\partial^2 Q_1}{\partial y^2} + \frac{\partial^2 R_1}{\partial y \partial z} \right) \mathbf{j} + \left(\frac{\partial^2 P_1}{\partial z \partial x} + \frac{\partial^2 Q_1}{\partial z \partial y} + \frac{\partial^2 R_1}{\partial z^2} \right) \mathbf{k} \right] \\
 &\quad - \left[\left(\frac{\partial^2 P_1}{\partial x^2} + \frac{\partial^2 P_1}{\partial y^2} + \frac{\partial^2 P_1}{\partial z^2} \right) \mathbf{i} + \left(\frac{\partial^2 Q_1}{\partial x^2} + \frac{\partial^2 Q_1}{\partial y^2} + \frac{\partial^2 Q_1}{\partial z^2} \right) \mathbf{j} \right. \\
 &\quad \left. + \left(\frac{\partial^2 R_1}{\partial x^2} + \frac{\partial^2 R_1}{\partial y^2} + \frac{\partial^2 R_1}{\partial z^2} \right) \mathbf{k} \right] \\
 &= \left(\frac{\partial^2 Q_1}{\partial x \partial y} + \frac{\partial^2 R_1}{\partial x \partial z} - \frac{\partial^2 P_1}{\partial y^2} - \frac{\partial^2 P_1}{\partial z^2} \right) \mathbf{i} + \left(\frac{\partial^2 P_1}{\partial y \partial x} + \frac{\partial^2 R_1}{\partial y \partial z} - \frac{\partial^2 Q_1}{\partial x^2} - \frac{\partial^2 Q_1}{\partial z^2} \right) \mathbf{j} \\
 &\quad + \left(\frac{\partial^2 P_1}{\partial z \partial x} + \frac{\partial^2 Q_1}{\partial z \partial y} - \frac{\partial^2 R_1}{\partial x^2} - \frac{\partial^2 R_1}{\partial y^2} \right) \mathbf{k}
 \end{aligned}$$

Then applying Clairaut's Theorem to reverse the order of differentiation in the second partial derivatives as needed and comparing, we have $\operatorname{curl} \operatorname{curl} \mathbf{F} = \operatorname{grad} \operatorname{div} \mathbf{F} - \nabla^2 \mathbf{F}$ as desired.

38.

Let $\mathbf{H} = \langle h_1, h_2, h_3 \rangle$ and $\mathbf{E} = \langle E_1, E_2, E_3 \rangle$.

$$\begin{aligned}
 \text{(a) } \nabla \times (\nabla \times \mathbf{E}) &= \nabla \times (\text{curl } \mathbf{E}) = \nabla \times \left(-\frac{1}{c} \frac{\partial \mathbf{H}}{\partial t} \right) = -\frac{1}{c} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ \partial h_1/\partial t & \partial h_2/\partial t & \partial h_3/\partial t \end{vmatrix} \\
 &= -\frac{1}{c} \left[\left(\frac{\partial^2 h_3}{\partial y \partial t} - \frac{\partial^2 h_2}{\partial z \partial t} \right) \mathbf{i} + \left(\frac{\partial^2 h_1}{\partial z \partial t} - \frac{\partial^2 h_3}{\partial x \partial t} \right) \mathbf{j} + \left(\frac{\partial^2 h_2}{\partial x \partial t} - \frac{\partial^2 h_1}{\partial y \partial t} \right) \mathbf{k} \right] \\
 &= -\frac{1}{c} \frac{\partial}{\partial t} \left[\left(\frac{\partial h_3}{\partial y} - \frac{\partial h_2}{\partial z} \right) \mathbf{i} + \left(\frac{\partial h_1}{\partial z} - \frac{\partial h_3}{\partial x} \right) \mathbf{j} + \left(\frac{\partial h_2}{\partial x} - \frac{\partial h_1}{\partial y} \right) \mathbf{k} \right] \quad [\text{assuming that the partial derivatives} \\
 &\quad \text{are continuous so that the order of} \\
 &\quad \text{differentiation does not matter}] \\
 &= -\frac{1}{c} \frac{\partial}{\partial t} \text{curl } \mathbf{H} = -\frac{1}{c} \frac{\partial}{\partial t} \left(\frac{1}{c} \frac{\partial \mathbf{E}}{\partial t} \right) = -\frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2}
 \end{aligned}$$

$$\begin{aligned}
 \text{(b) } \nabla \times (\nabla \times \mathbf{H}) &= \nabla \times (\text{curl } \mathbf{H}) = \nabla \times \left(\frac{1}{c} \frac{\partial \mathbf{E}}{\partial t} \right) = \frac{1}{c} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ \partial E_1/\partial t & \partial E_2/\partial t & \partial E_3/\partial t \end{vmatrix} \\
 &= \frac{1}{c} \left[\left(\frac{\partial^2 E_3}{\partial y \partial t} - \frac{\partial^2 E_2}{\partial z \partial t} \right) \mathbf{i} + \left(\frac{\partial^2 E_1}{\partial z \partial t} - \frac{\partial^2 E_3}{\partial x \partial t} \right) \mathbf{j} + \left(\frac{\partial^2 E_2}{\partial x \partial t} - \frac{\partial^2 E_1}{\partial y \partial t} \right) \mathbf{k} \right] \\
 &= \frac{1}{c} \frac{\partial}{\partial t} \left[\left(\frac{\partial E_3}{\partial y} - \frac{\partial E_2}{\partial z} \right) \mathbf{i} + \left(\frac{\partial E_1}{\partial z} - \frac{\partial E_3}{\partial x} \right) \mathbf{j} + \left(\frac{\partial E_2}{\partial x} - \frac{\partial E_1}{\partial y} \right) \mathbf{k} \right] \quad [\text{assuming that the partial derivatives} \\
 &\quad \text{are continuous so that the order of} \\
 &\quad \text{differentiation does not matter}] \\
 &= \frac{1}{c} \frac{\partial}{\partial t} \text{curl } \mathbf{E} = \frac{1}{c} \frac{\partial}{\partial t} \left(-\frac{1}{c} \frac{\partial \mathbf{H}}{\partial t} \right) = -\frac{1}{c^2} \frac{\partial^2 \mathbf{H}}{\partial t^2}
 \end{aligned}$$

(c) Using Exercise 29, we have that $\text{curl curl } \mathbf{E} = \text{grad div } \mathbf{E} - \nabla^2 \mathbf{E} \Rightarrow$

$$\nabla^2 \mathbf{E} = \text{grad div } \mathbf{E} - \text{curl curl } \mathbf{E} = \text{grad } 0 + \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} \quad [\text{from part (a)}] = \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2}.$$

(d) As in part (c), $\nabla^2 \mathbf{H} = \text{grad div } \mathbf{H} - \text{curl curl } \mathbf{H} = \text{grad } 0 + \frac{1}{c^2} \frac{\partial^2 \mathbf{H}}{\partial t^2} \quad [\text{using part (b)}] = \frac{1}{c^2} \frac{\partial^2 \mathbf{H}}{\partial t^2}.$

60.

$$(a) \ x = a \cosh u \cos v, \ y = b \cosh u \sin v, \ z = c \sinh u \Rightarrow$$

$$\begin{aligned} \frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} &= \cosh^2 u \cos^2 v + \cosh^2 u \sin^2 v - \sinh^2 u \\ &= \cosh^2 u - \sinh^2 u = 1 \end{aligned}$$

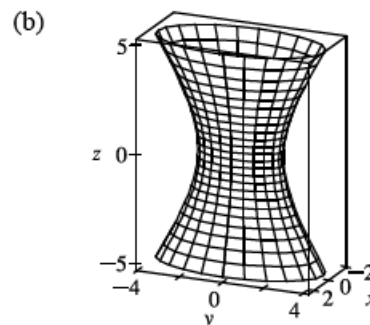
and the parametric equations represent a hyperboloid of one sheet.

$$(c) \ \mathbf{r}_u = \sinh u \cos v \mathbf{i} + 2 \sinh u \sin v \mathbf{j} + 3 \cosh u \mathbf{k} \text{ and}$$

$$\mathbf{r}_v = -\cosh u \sin v \mathbf{i} + 2 \cosh u \cos v \mathbf{j}, \text{ so } \mathbf{r}_u \times \mathbf{r}_v = -6 \cosh^2 u \cos v \mathbf{i} - 3 \cosh^2 u \sin v \mathbf{j} + 2 \cosh u \sinh u \mathbf{k}.$$

We integrate between $u = \sinh^{-1}(-1) = -\ln(1 + \sqrt{2})$ and $u = \sinh^{-1} 1 = \ln(1 + \sqrt{2})$, since then z varies between -3 and 3 , as desired. So the surface area is

$$\begin{aligned} A(S) &= \int_0^{2\pi} \int_{-\ln(1+\sqrt{2})}^{\ln(1+\sqrt{2})} |\mathbf{r}_u \times \mathbf{r}_v| \, du \, dv \\ &= \int_0^{2\pi} \int_{-\ln(1+\sqrt{2})}^{\ln(1+\sqrt{2})} \sqrt{36 \cosh^4 u \cos^2 v + 9 \cosh^4 u \sin^2 v + 4 \cosh^2 u \sinh^2 u} \, du \, dv \end{aligned}$$



64. (a) Here $z = a \sin \alpha$, $y = |AB|$, and $x = |OA|$. But

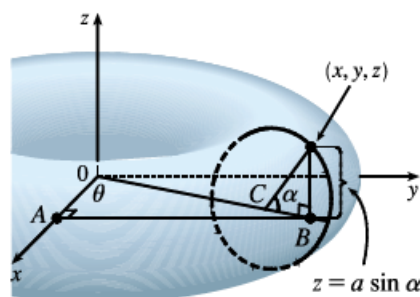
$$|OB| = |OC| + |CB| = b + a \cos \alpha \text{ and } \sin \theta = \frac{|AB|}{|OB|} \text{ so that}$$

$$y = |OB| \sin \theta = (b + a \cos \alpha) \sin \theta. \text{ Similarly } \cos \theta = \frac{|OA|}{|OB|} \text{ so}$$

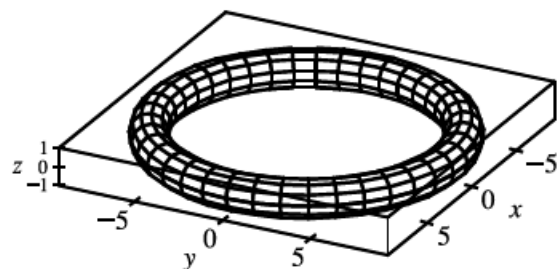
$$x = (b + a \cos \alpha) \cos \theta. \text{ Hence a parametric representation for the}$$

$$\text{torus is } x = b \cos \theta + a \cos \alpha \cos \theta, y = b \sin \theta + a \cos \alpha \sin \theta,$$

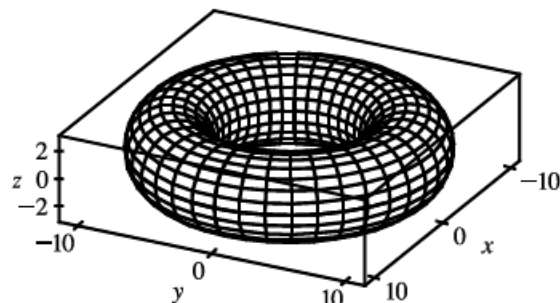
$$z = a \sin \alpha, \text{ where } 0 \leq \alpha \leq 2\pi, 0 \leq \theta \leq 2\pi.$$



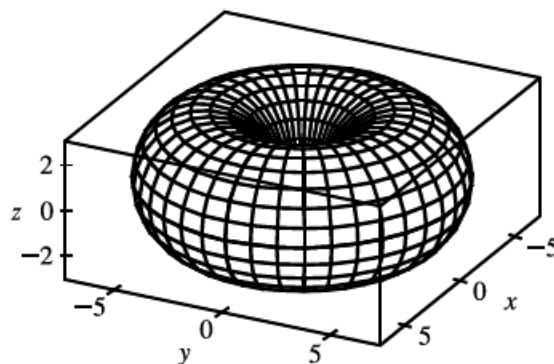
(b)



$$a = 1, b = 8$$



$$a = 3, b = 8$$



$$a = 3, b = 4$$

(c) $x = b \cos \theta + a \cos \alpha \cos \theta$, $y = b \sin \theta + a \cos \alpha \sin \theta$, $z = a \sin \alpha$, so $\mathbf{r}_\alpha = \langle -a \sin \alpha \cos \theta, -a \sin \alpha \sin \theta, a \cos \alpha \rangle$,

$$\mathbf{r}_\theta = \langle -(b + a \cos \alpha) \sin \theta, (b + a \cos \alpha) \cos \theta, 0 \rangle \text{ and}$$

$$\begin{aligned} \mathbf{r}_\alpha \times \mathbf{r}_\theta &= (-ab \cos \alpha \cos \theta - a^2 \cos \alpha \cos^2 \theta) \mathbf{i} + (-ab \sin \alpha \cos \theta - a^2 \sin \alpha \cos^2 \theta) \mathbf{j} \\ &\quad + (-ab \cos^2 \alpha \sin \theta - a^2 \cos^2 \alpha \sin \theta \cos \theta - ab \sin^2 \alpha \sin \theta - a^2 \sin^2 \alpha \sin \theta \cos \theta) \mathbf{k} \\ &= -a(b + a \cos \alpha) [(\cos \theta \cos \alpha) \mathbf{i} + (\sin \theta \cos \alpha) \mathbf{j} + (\sin \alpha) \mathbf{k}] \end{aligned}$$

$$\text{Then } |\mathbf{r}_\alpha \times \mathbf{r}_\theta| = a(b + a \cos \alpha) \sqrt{\cos^2 \theta \cos^2 \alpha + \sin^2 \theta \cos^2 \alpha + \sin^2 \alpha} = a(b + a \cos \alpha).$$

Note: $b > a$, $-1 \leq \cos \alpha \leq 1$ so $|b + a \cos \alpha| = b + a \cos \alpha$. Hence

$$A(S) = \int_0^{2\pi} \int_0^{2\pi} a(b + a \cos \alpha) d\alpha d\theta = 2\pi [ab\alpha + a^2 \sin \alpha]_0^{2\pi} = 4\pi^2 ab.$$