

# Case Study: VGGNet

[Simonyan and Zisserman, 2014]

Small filters, Deeper networks

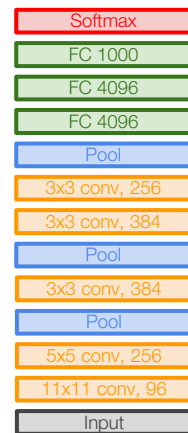
8 layers (AlexNet)

-> 16 - 19 layers (VGG16Net)

Only 3x3 CONV stride 1, pad 1  
and 2x2 MAX POOL stride 2

11.7% top 5 error in ILSVRC'13  
(ZFNet)

-> 7.3% top 5 error in ILSVRC'14



AlexNet



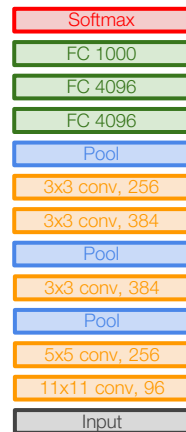
VGG16

VGG19

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Q: Why use smaller filters? (3x3 conv)



AlexNet



VGG16

VGG19

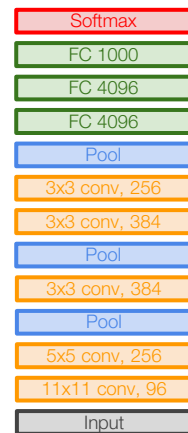
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[Simonyan and Zisserman, 2014]

Q: Why use smaller filters? (3x3 conv)

Stack of three 3x3 conv (stride 1) layers has same **effective receptive field** as one 7x7 conv layer

Q: What is the effective receptive field of three 3x3 conv (stride 1) layers?



AlexNet



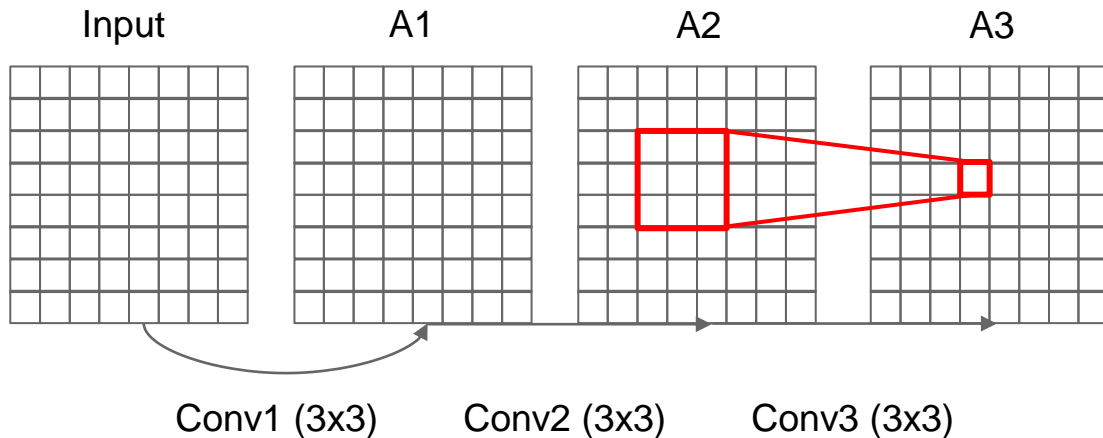
VGG16

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[Simonyan and Zisserman, 2014]

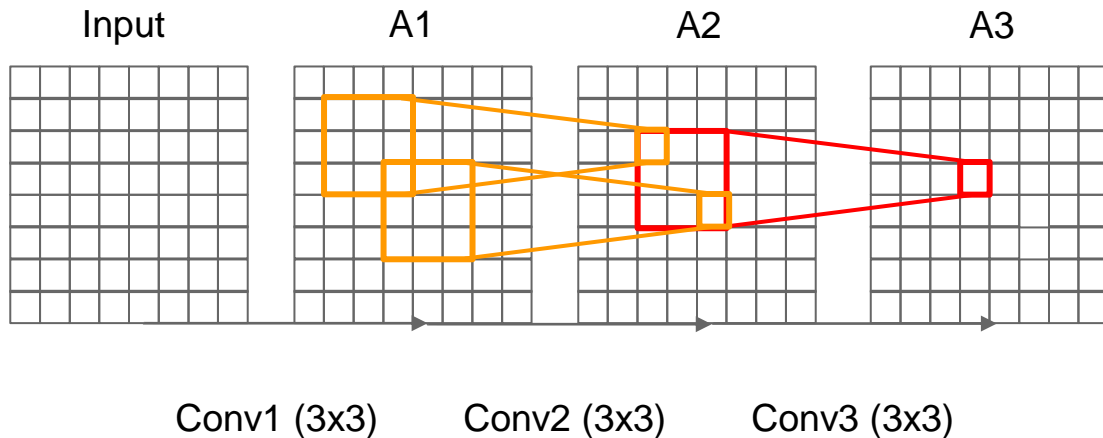
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*[Simonyan and Zisserman, 2014]*

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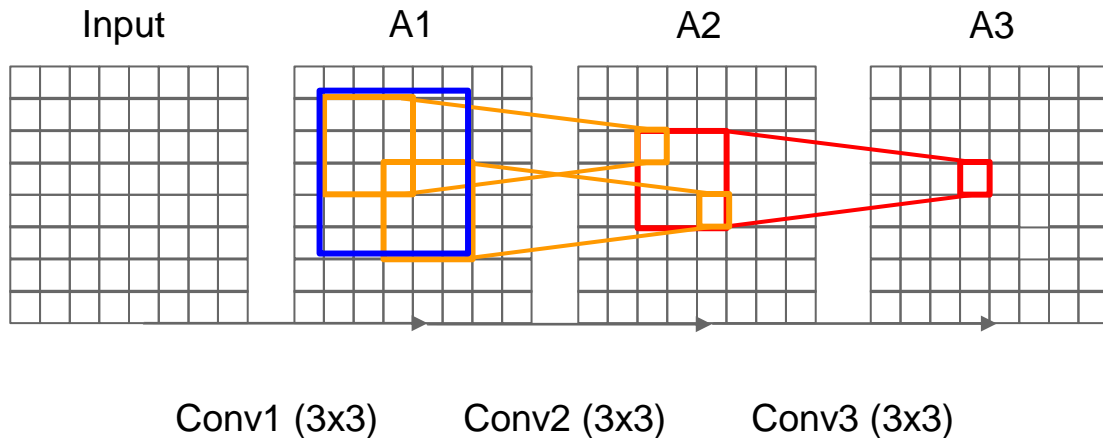
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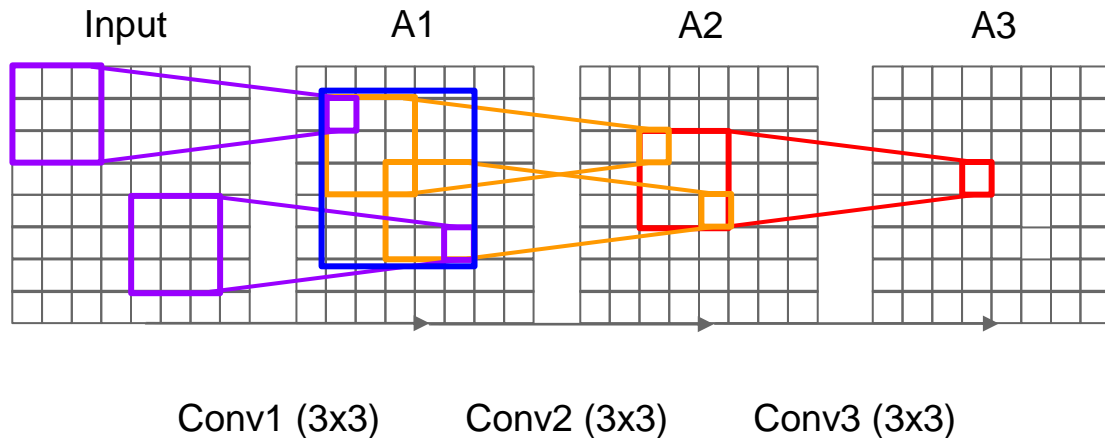
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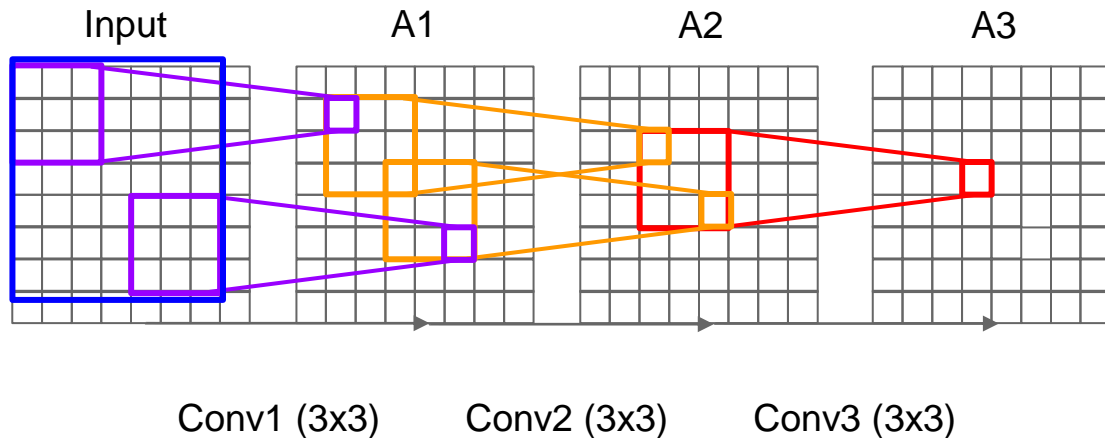
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# Case Study: VGGNet

[Simonyan and Zisserman, 2014]

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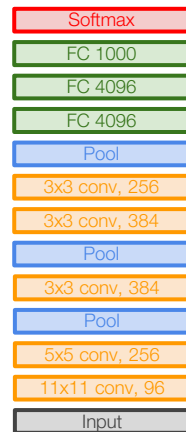
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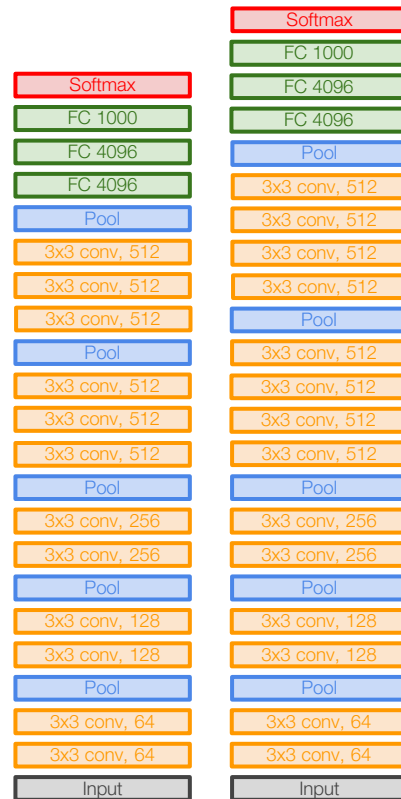
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Stack of three 3x3 conv (stride 1) layers has same **effective receptive field** as one 7x7 conv layer

[7x7]



AlexNet



VGG16

VGG19

# Case Study: VGGNet

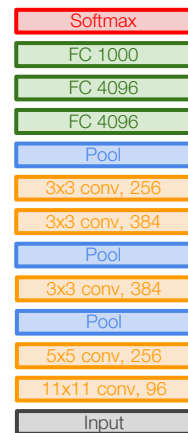
[Simonyan and Zisserman, 2014]

Q: Why use smaller filters? (3x3 conv)

Stack of three 3x3 conv (stride 1) layers has same **effective receptive field** as one 7x7 conv layer

But deeper, more non-linearities

And fewer parameters:  $3 * (3^2 C^2)$  vs.  $7^2 C^2$  for C channels per layer



AlexNet



VGG16

VGG19

INPUT: [224x224x3] memory: 224\*224\*3=150K params: 0 (not counting biases)

CONV3-64: [224x224x64] memory: 224\*224\*64=3.2M params:  $(3*3*3)*64 = 1,728$

CONV3-64: [224x224x64] memory: 224\*224\*64=3.2M params:  $(3*3*64)*64 = 36,864$

POOL2: [112x112x64] memory: 112\*112\*64=800K params: 0

CONV3-128: [112x112x128] memory: 112\*112\*128=1.6M params:  $(3*3*64)*128 = 73,728$

CONV3-128: [112x112x128] memory: 112\*112\*128=1.6M params:  $(3*3*128)*128 = 147,456$

POOL2: [56x56x128] memory: 56\*56\*128=400K params: 0

CONV3-256: [56x56x256] memory: 56\*56\*256=800K params:  $(3*3*128)*256 = 294,912$

CONV3-256: [56x56x256] memory: 56\*56\*256=800K params:  $(3*3*256)*256 = 589,824$

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POOL2: [28x28x256] memory: 28\*28\*256=200K params: 0

CONV3-512: [28x28x512] memory: 28\*28\*512=400K params:  $(3*3*256)*512 = 1,179,648$

CONV3-512: [28x28x512] memory: 28\*28\*512=400K params:  $(3*3*512)*512 = 2,359,296$

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POOL2: [14x14x512] memory: 14\*14\*512=100K params: 0

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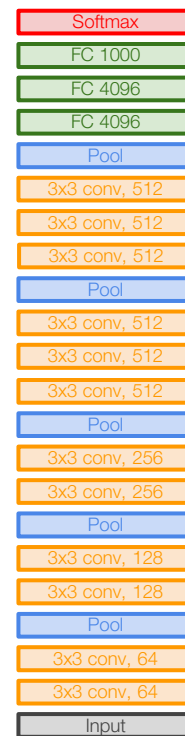
CONV3-512: [14x14x512] memory: 14\*14\*512=100K params:  $(3*3*512)*512 = 2,359,296$

POOL2: [7x7x512] memory: 7\*7\*512=25K params: 0

FC: [1x1x4096] memory: 4096 params:  $7*7*512*4096 = 102,760,448$

FC: [1x1x4096] memory: 4096 params:  $4096*4096 = 16,777,216$

FC: [1x1x1000] memory: 1000 params:  $4096*1000 = 4,096,000$



VGG16

INPUT: [224x224x3] memory:  $224*224*3=150\text{K}$  params: 0 (not counting biases)

CONV3-64: [224x224x64] memory:  $224*224*64=3.2\text{M}$  params:  $(3*3*3)*64 = 1,728$

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POOL2: [112x112x64] memory:  $112*112*64=800\text{K}$  params: 0

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POOL2: [7x7x512] memory:  $7*7*512=25\text{K}$  params: 0

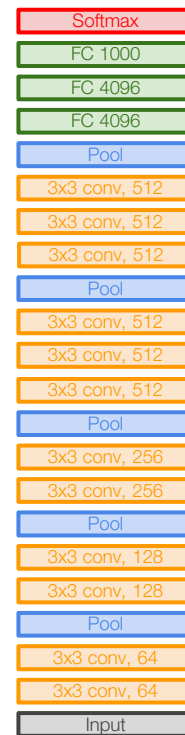
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FC: [1x1x1000] memory: 1000 params:  $4096*1000 = 4,096,000$

TOTAL memory:  $24\text{M} * 4 \text{ bytes} \sim 96\text{MB}$  / image (for a forward pass)

TOTAL params: 138M parameters



VGG16

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TOTAL memory:  $24\text{M} * 4 \text{ bytes} \sim 96\text{MB} / \text{image}$  (only forward!  $\sim 2$  for bwd)

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Note:

Most memory is in  
early CONV

Most params are  
in late FC

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VGG16

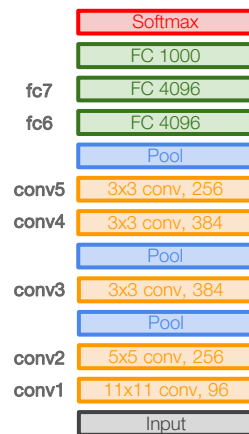
Common names

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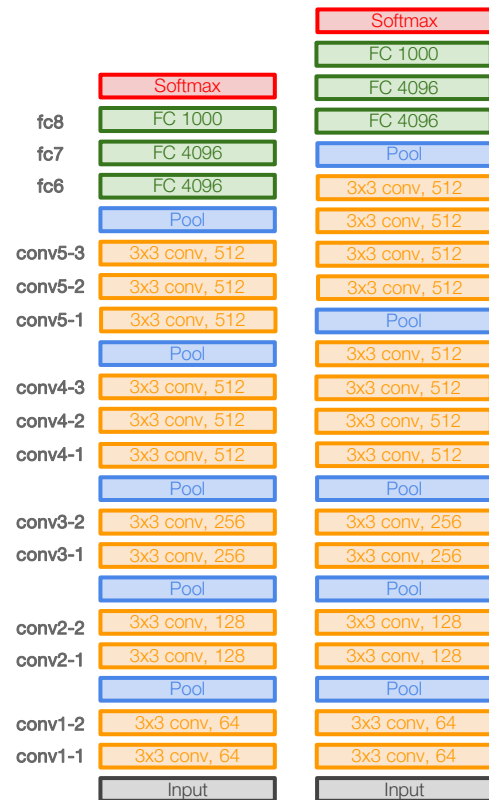
[Simonyan and Zisserman, 2014]

## Details:

- ILSVRC'14 2nd in classification, 1st in localization
- Similar training procedure as Krizhevsky 2012
- No Local Response Normalisation (LRN)
- Use VGG16 or VGG19 (VGG19 only slightly better, more memory)
- Use ensembles for best results
- FC7 features generalize well to other tasks



AlexNet



VGG16

VGG19

# ImageNet Large Scale Visual Recognition Challenge (ILSVRC) winners

