

CE 290 I Lecture Notes, C. Kirsch

Control and Information Management

Computer Science for Non-Computer Scientists

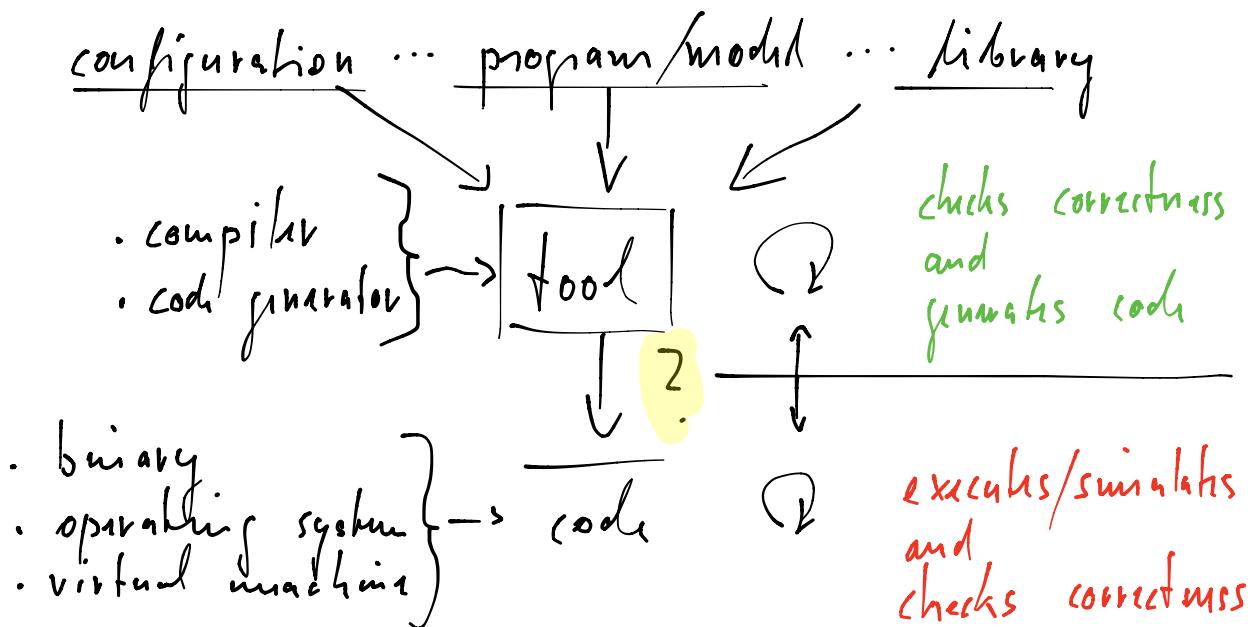
- Introduction
- Architecture
- Algorithms
- Computability & Complexity
- Languages
- Syntax & Semantics
- Compilers
- Data Structures
- Memory Management
- Concurrency
- Kernels & Virtual Machines
- Real Time & Model-driven Development

Software and Systems

- Target: learn how to construct complex software systems, in the cloud and on the ground
- Audience: everyone who does not care about computer science but needs it to solve a problem that involves computation (which is basically everyone)
- Approach: we explain all fundamental principles of computer science in one semester, accompanied by weekly programming assignments
- Prerequisite: basic programming experience

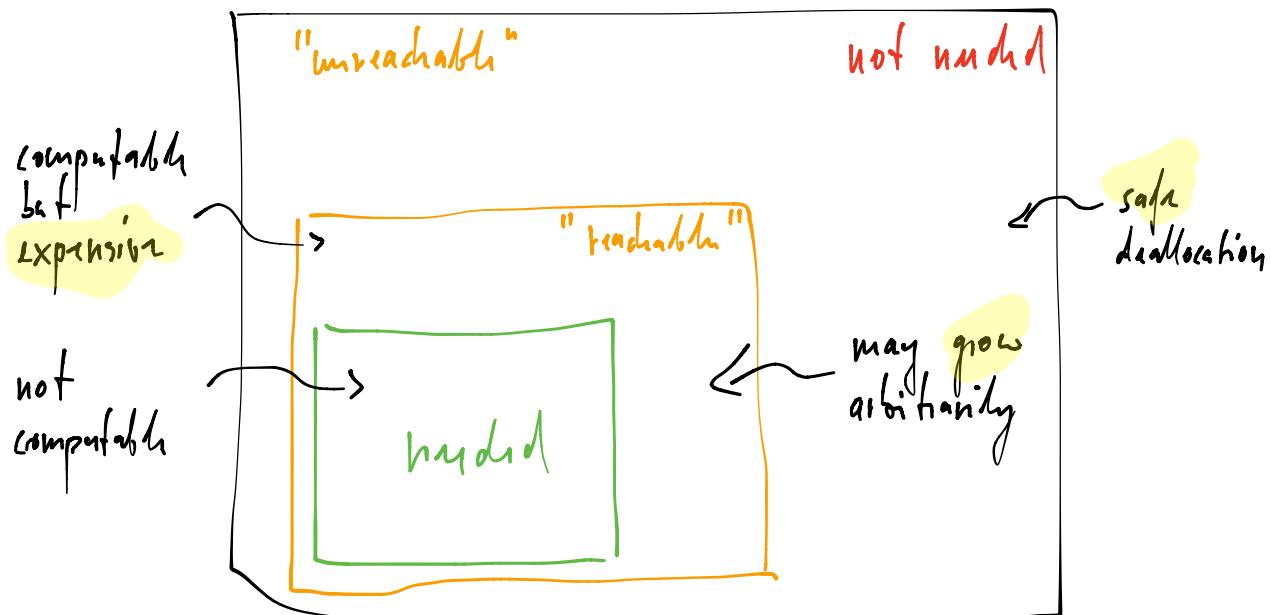
Myth Busting

- I prefer programming language X because it makes it more convenient to implement my app: wrong!
 - the fundamental problem of programming is to establish **functional correctness** and **adequate performance**.
 - different languages provide different levels of **automating** the process of establishing correctness and performance and should therefore be chosen based on that insight.



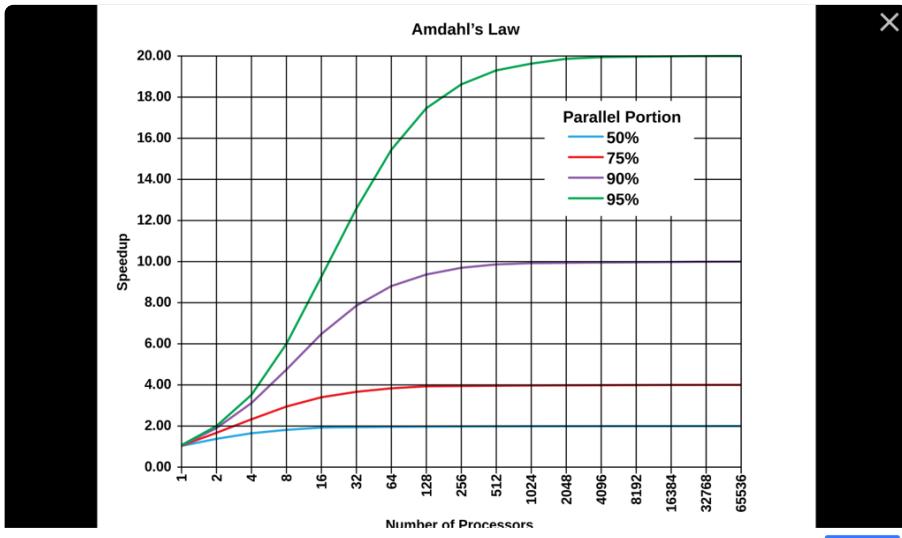
Myth Busting

- I like garbage-collected languages because they free me from memory management: wrong!
 - garbage collectors provide safe deallocation of unneeded memory but the programmer still needs to say what is unneeded, otherwise the system will run out of memory
 - programmers need to determine when memory is not needed anymore (which is a difficult, highly app-dependent property)



Myth Busting

- Let's buy a 100-core machine, create 100 threads of our app, and then be 100 times faster: wrong!



The speedup of a program using multiple processors in parallel computing is limited by the sequential fraction of the program. For example, if 95% of the program can be parallelized, the theoretical maximum speedup using parallel computing would be 20x as shown in the diagram, no matter how many processors are used.

[Details](#)

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$$\text{speedup} \rightarrow S(N) = \frac{1}{(1-P) + \frac{P}{N}} \quad \begin{matrix} \text{parallel portion} \\ \text{if } P=1 \end{matrix} \quad i.e. \quad S(N) = N \quad \text{but} \quad S(\infty) = \frac{1}{1-P}$$

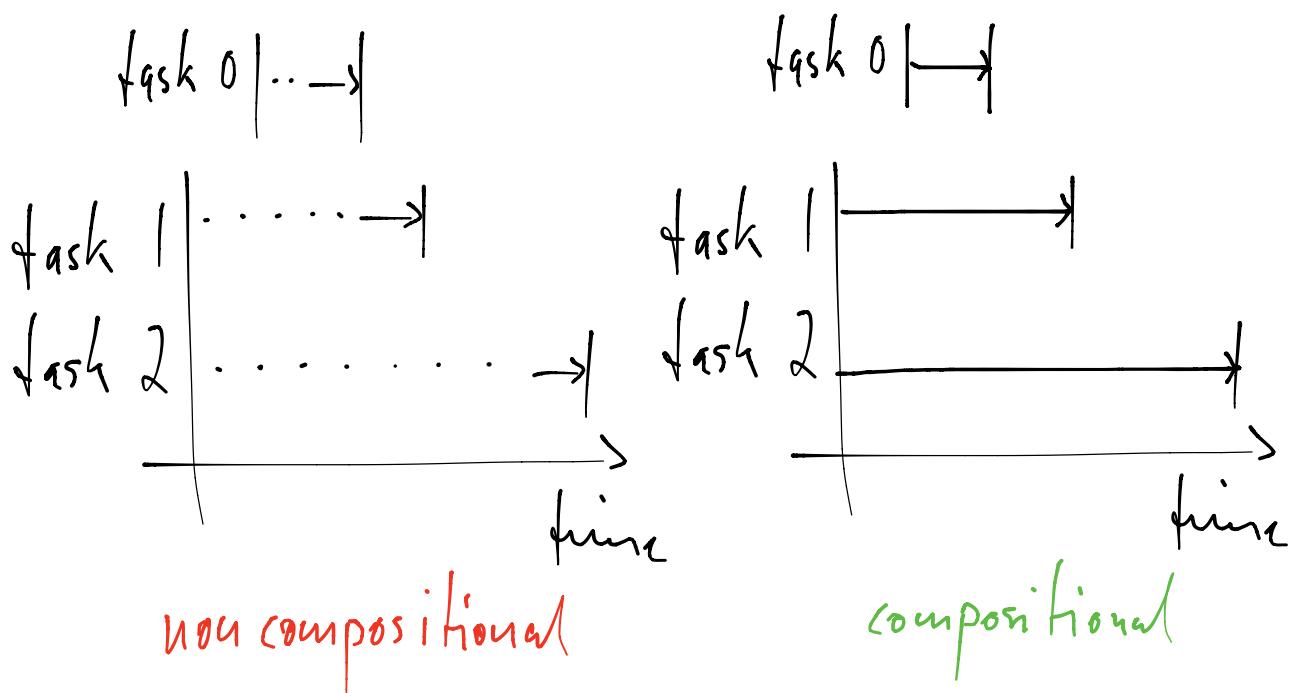
processors

- Sequentiality is not a property of a program but a property of program execution!

- processor architecture
- memory hierarchy
- communication infrastructure

Myth Busting

- I need some real-time performance but my system is too slow, let's just get a faster machine and be done with it: *wrong!*
 - program execution time is a global, highly **non-linear** property that depends on all aspects of a system / hardware and all software
 - real-time programming needs **predictability**, not speed!



Bad Habits

- Let's use this fancy **library** without understanding any of its implementation details : bad !
- I have been using all these **compilers**, who cares what they do and how : bad !
 - **operating systems**
 - **mechanisms**
- I like **virtualization**, no idea how it works, but who cares, let's use it anyway : bad !

....

Problem Definition:

Software systems typically involve nontrivial functional and nonfunctional (performance) characteristics implemented by a possibly large number of interacting software and hardware components

The challenge is to fully understand that interaction and not just how to develop code (this is not a software engineering class)

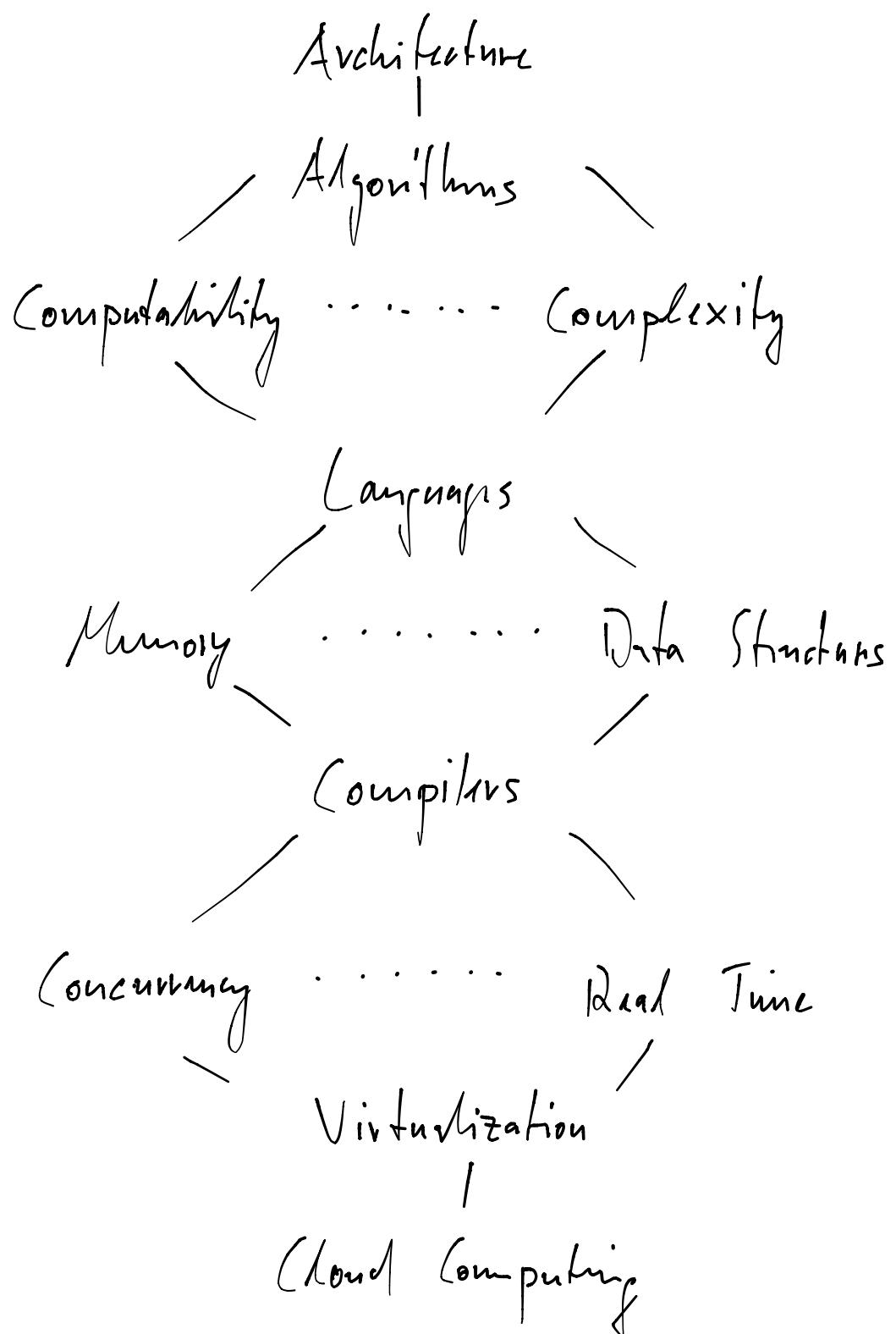
Software systems development is nevertheless mostly done by non-computer scientists with domain-specific backgrounds (our target)

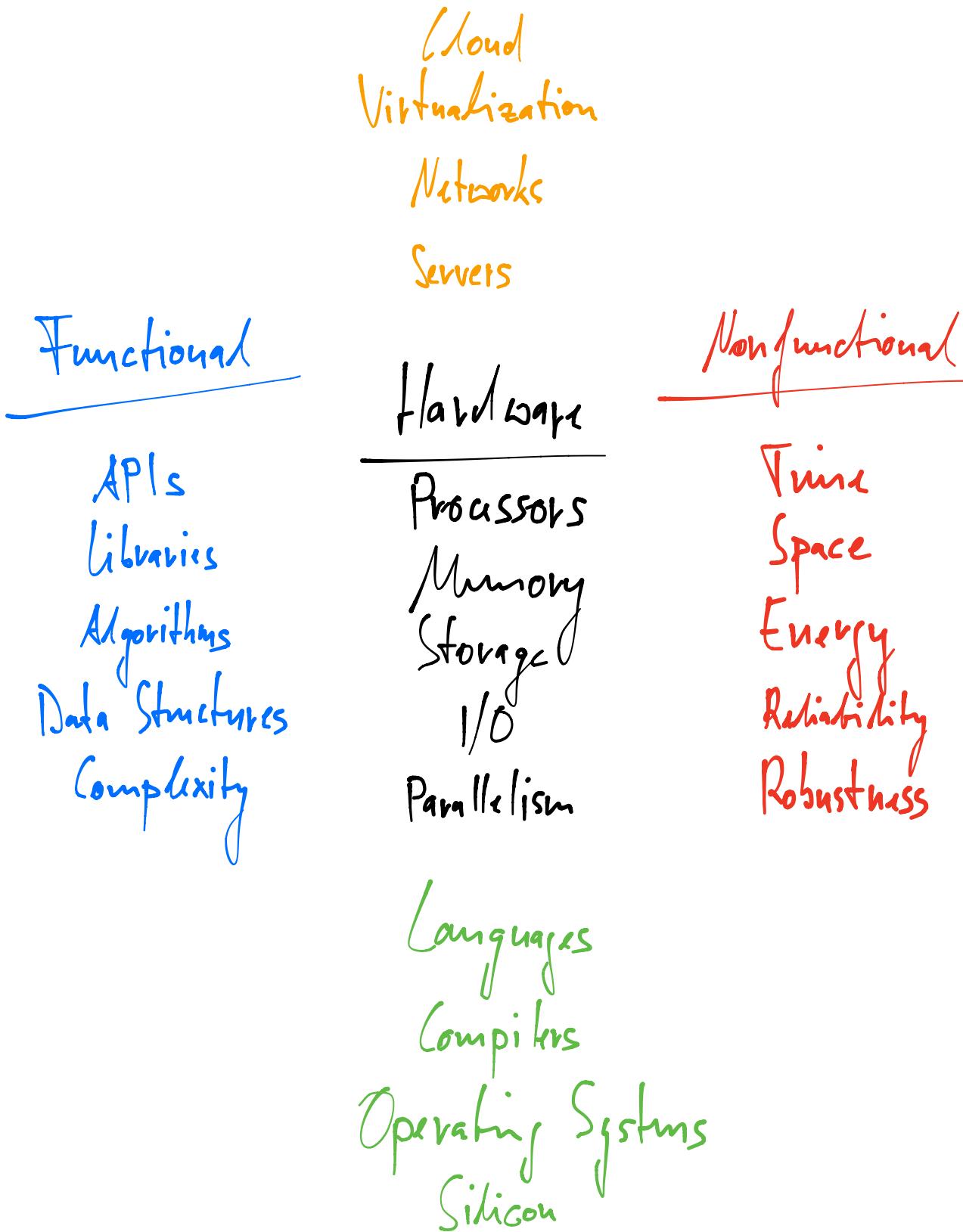
Solution:

We develop the background necessary for comprehensively understanding system behavior:

- Architecture and Algorithms
- Computability and Complexity
- Languages and Compilers
- Memory and Data Structures
- Concurrency and Real Time
- Virtualization and Cloud Computing

The key is to find the correct abstractions for modeling the relevant aspects of a solution to a given problem in system design.





Syllabus

<u>area</u>	<u>content</u>	<u>motivation</u>
architecture	DLX machine <ul style="list-style-type: none">• registers• memory• I/O	foundation
algorithms	DLX programs <ul style="list-style-type: none">• arithmetic• memory- branching• subroutines	completeness
complexity	DLX execution <ul style="list-style-type: none">• size of input• # instructions• asymptotic behavior	performance
languages	C subset <ul style="list-style-type: none">• arithmetic• assignment• while loops• functions	correctness
semantics	C compiler <ul style="list-style-type: none">• EBNF• recursive-descent parsing• straight cash generation	automation

complexity	C Execution • C code vs. DLX instructions	performance
architecture	DLX modes • index vs. address • fix vs. spry • fragmentation	performance
data structures	composite types • arrays • records • lists • trees • hashtables	abstraction
Memory	memory management • heap vs. stack • dynamic memory allocation • garbage collection	spatial isolation
concurrency	models & implementations • threads vs. processes • virtual memory • shared memory vs. message passing • synchronization	abstraction performance

communication models & implementations interaction

- programmed vs.
interrupt-driven I/O
- I/O instructions vs.
memory-mapped I/O
- asynchronous I/O

concurrency

scheduling

temporal
isolation

- throughput, latency
- fairness
- algorithms (lists)
- real time

model-driven
development

DSLs

abstraction

- ZET, BET, LET
- SR, LET programming

cloud computing

virtualization

scalability

- virtual machines
(system vs. process)
- migration
- load balancing