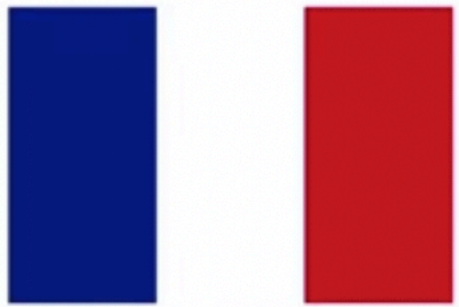
Traditional Language Models



J'ai vu le match de foot

Sequence	$P(\text{Sequence})$
I saw the game of soccer	4.5 e-5
I saw the soccer game	6.0 e-5
I saw the soccer match	4.6 e-5
Saw I the game of soccer	2.6 e-9

N-grams

$$P(w_2|w_1) = \frac{\text{count}(w_1, w_2)}{\text{count}(w_1)} \longrightarrow \text{Bigrams}$$

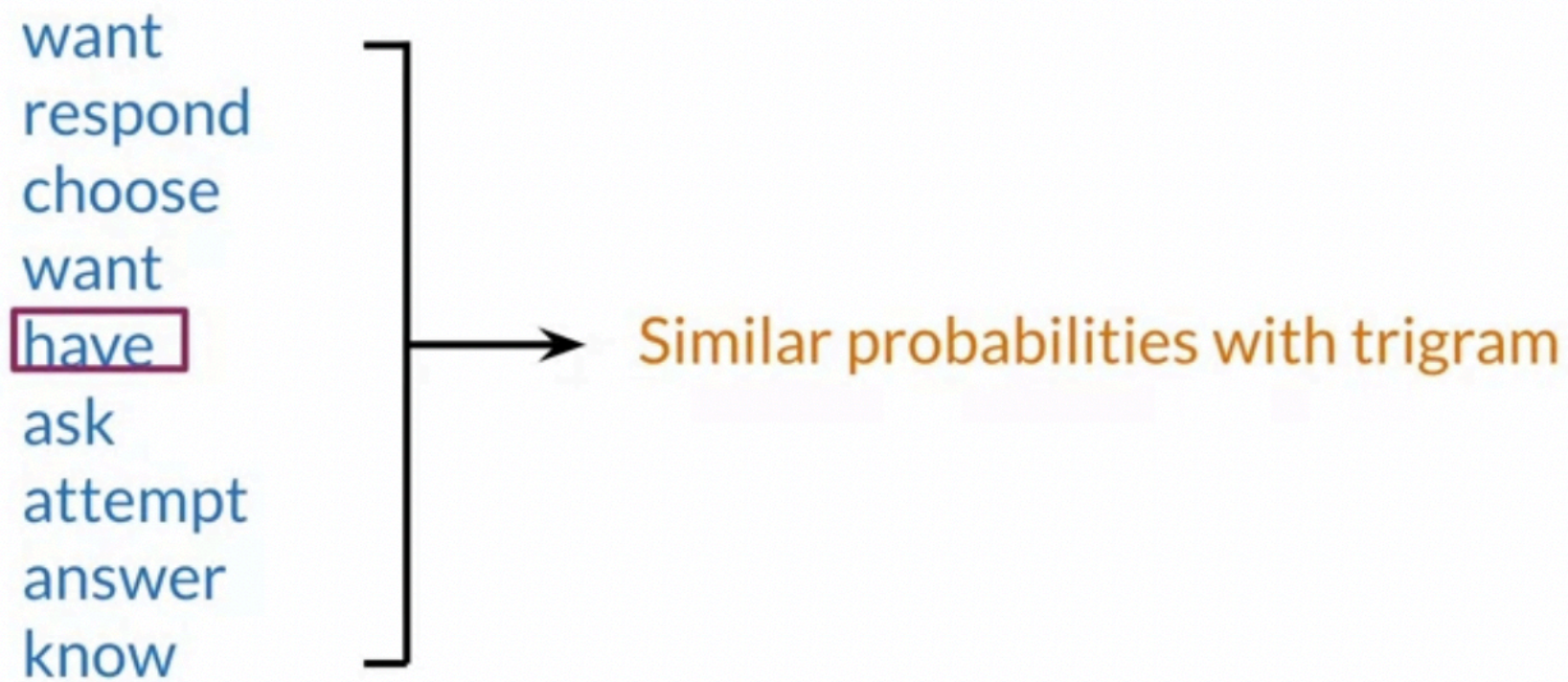
$$P(w_3|w_1, w_2) = \frac{\text{count}(w_1, w_2, w_3)}{\text{count}(w_1, w_2)} \longrightarrow \text{Trigrams}$$

$$P(w_1, w_2, w_3) = P(w_1) \times P(w_2|w_1) \times P(w_3|w_2)$$

- Large N-grams to capture dependencies between distant words
- Need a lot of space and RAM

Advantages of RNNs

Nour was supposed to study with me. I called her but she did not ___have___



Advantages of RNNs

Nour was supposed to study with me. I called her but she did not answer

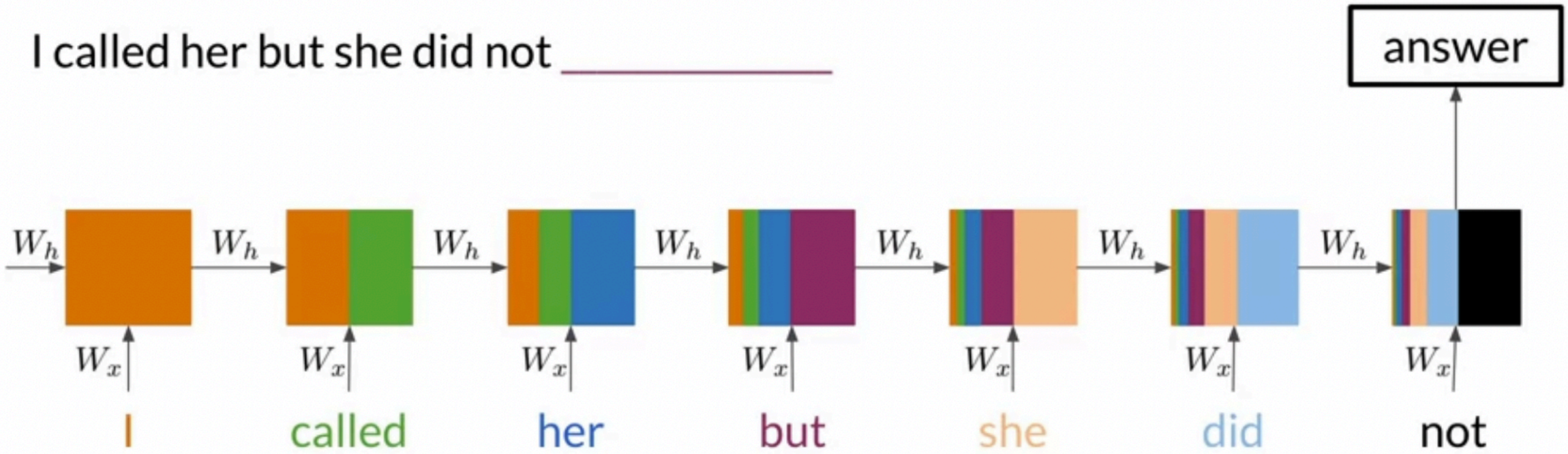
want
respond
choose
want
have
ask
attempt
answer
know

RNNs look at every previous word

Similar probabilities with trigram

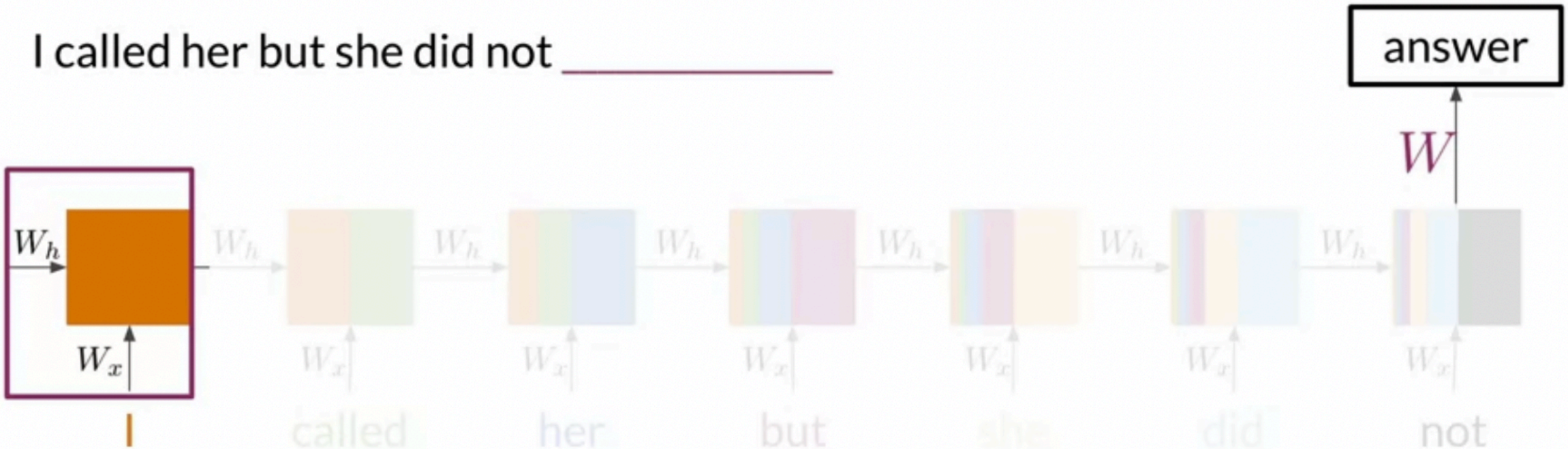
RNNs Basic Structure

I called her but she did not _____



RNNs Basic Structure

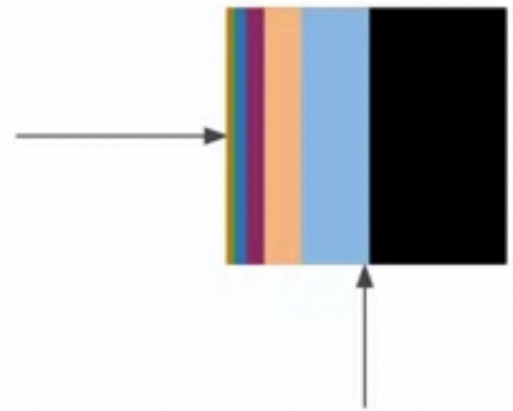
I called her but she did not _____



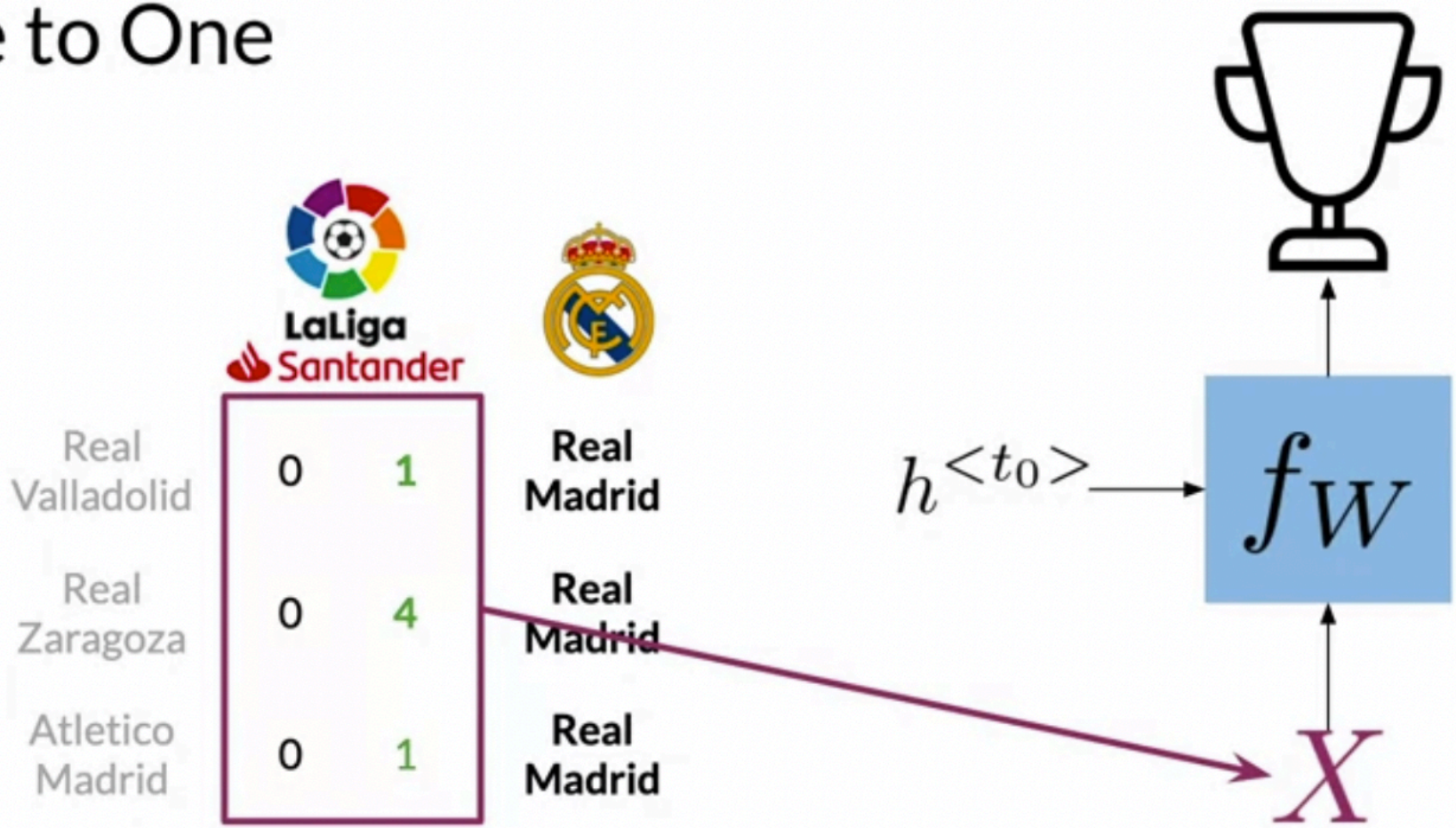
Learnable parameters

Summary

- RNNs model relationships among distant words
- In RNNs a lot of computations share parameters

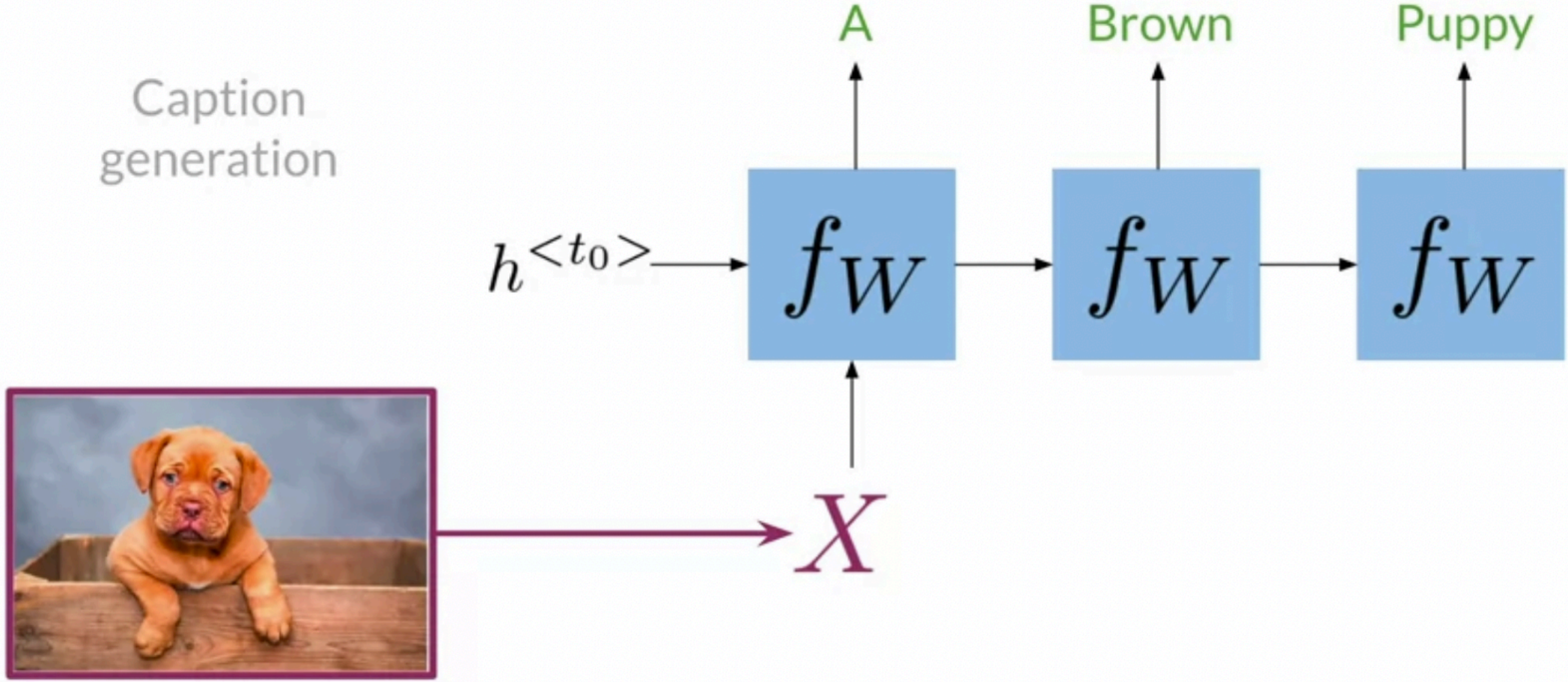


One to One

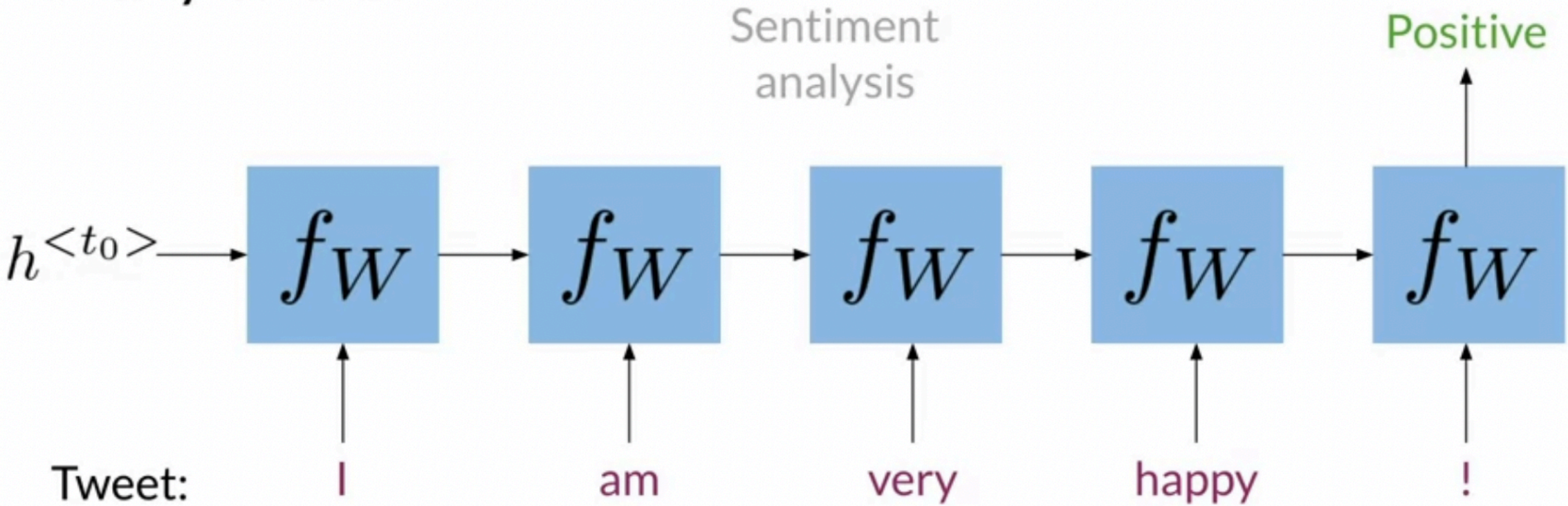

LaLiga
Santander
Real Valladolid
0
1
Real Madrid
Real Zaragoza
0
4
Real Madrid
Atletico Madrid
0
1
Real Madrid
$h^{<t_0>}$
f_W
X

One to Many

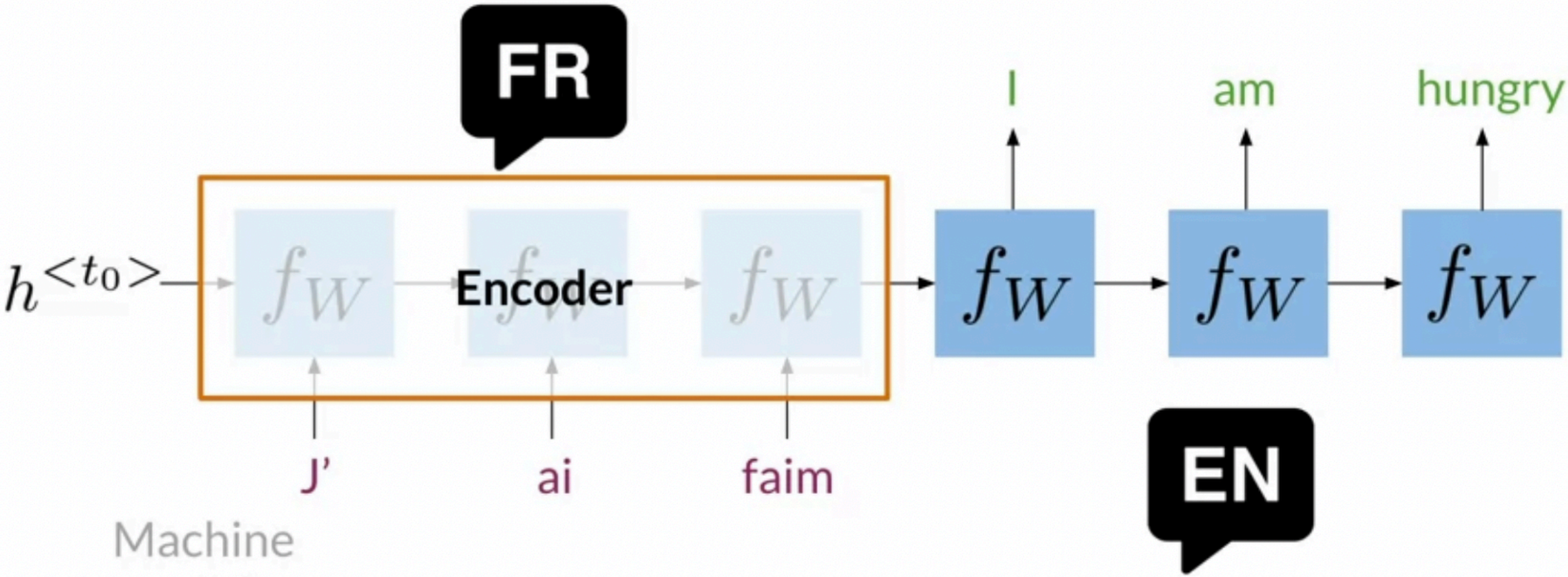
Caption generation



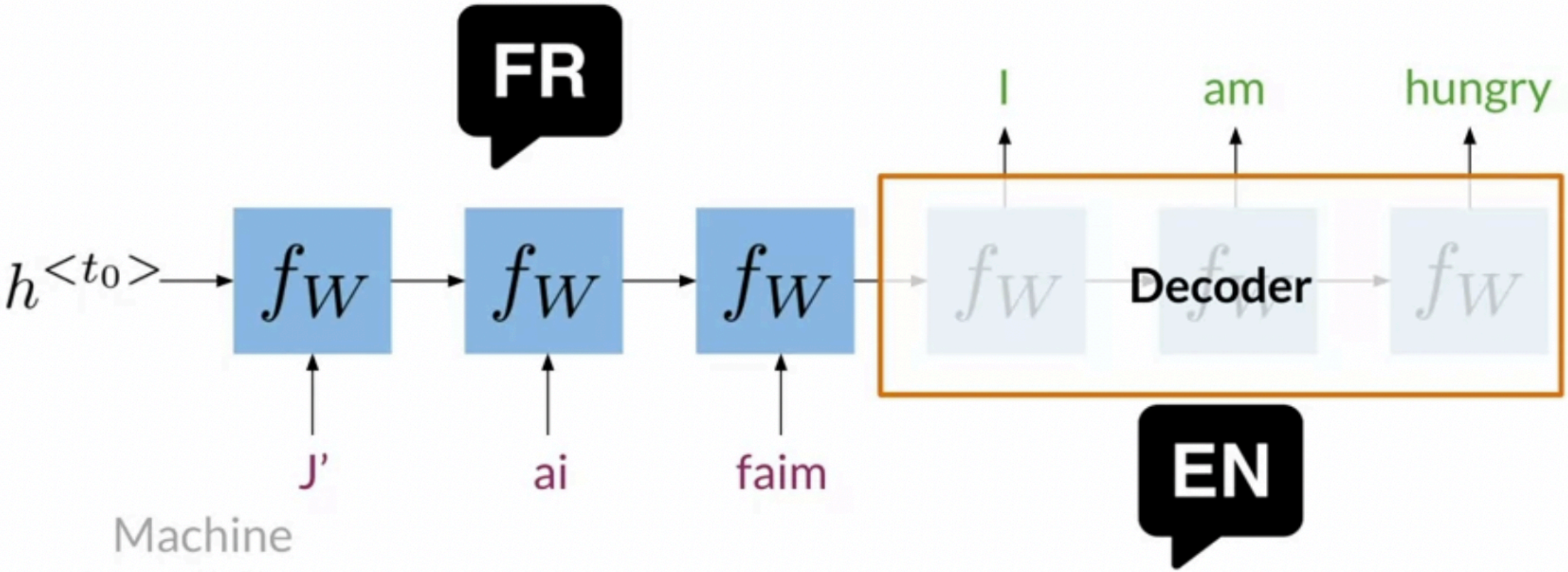
Many to One


Sentiment analysis
Positive
$h^{<t_0>}$
fw
fw
fw
fw
fw
Tweet:
I
am
very
happy
!

Many to Many


FR
I
am
hungry
$h^{<t_0>}$
fw
Encoder
fw
fw
fw
fw
fw
J'
ai
faim
EN
Machine
Translation

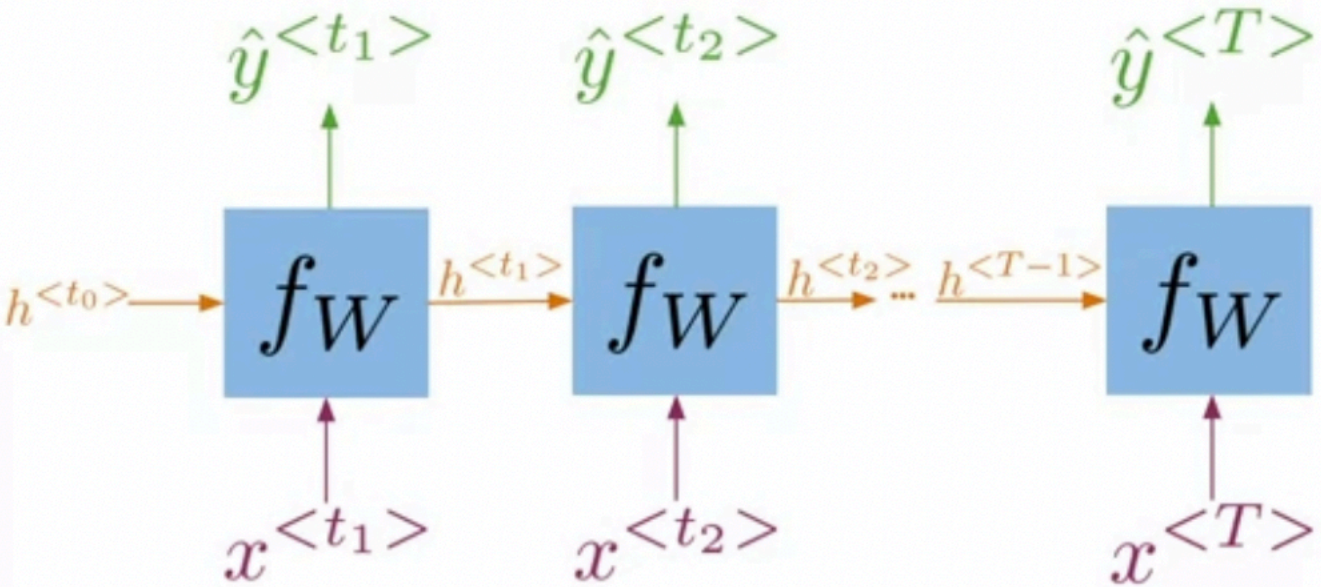
Many to Many


FR
I
am
hungry
$h^{<t_0>}$
fw
fw
fw
fw
Decoder
fw
J'
ai
faim
EN
Machine Translation

Summary

- RNNs can be implemented for a variety of NLP tasks
- Applications include Machine translation and caption generation

A Vanilla RNN

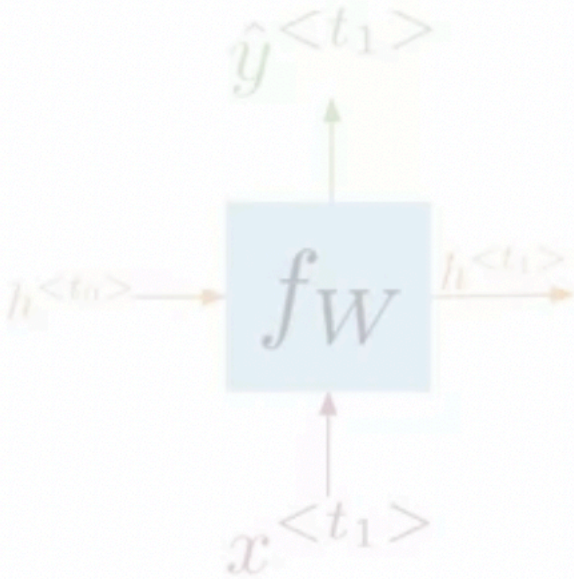


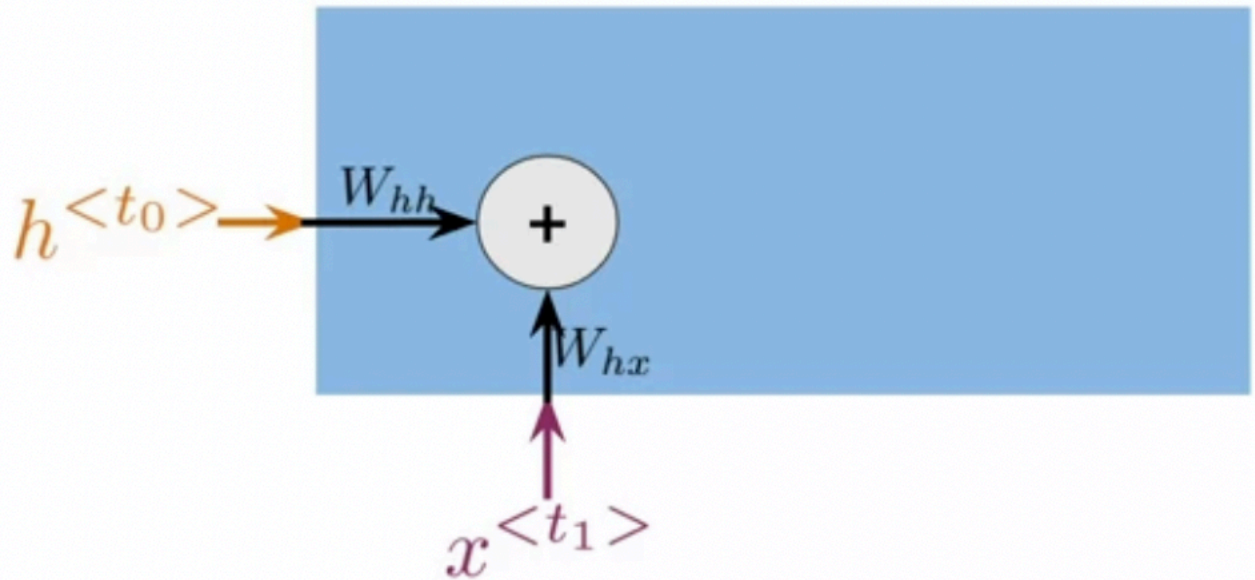
$$h^{<t>} = g(W_h[h^{<t-1>}, x^{<t>}] + b_h)$$

$$\hat{y}^{<t>} = g(W_{yh}h^{<t>} + b_y)$$

$$h^{<t>} = g(W_{hh}h^{<t-1>} \oplus W_{hx}x^{<t>} + b_h)$$

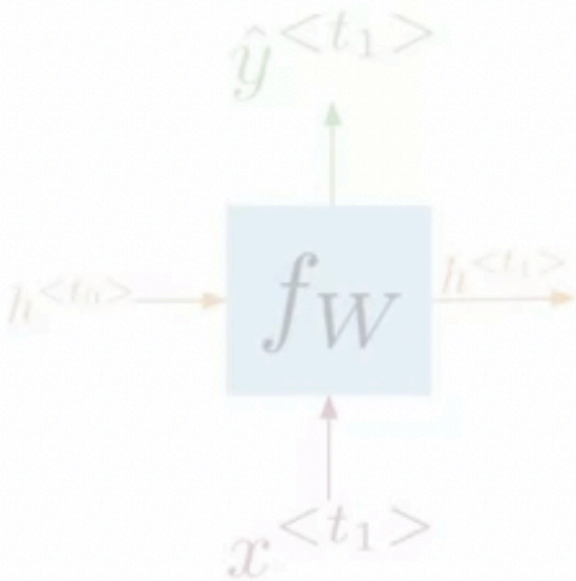
A Vanilla RNN

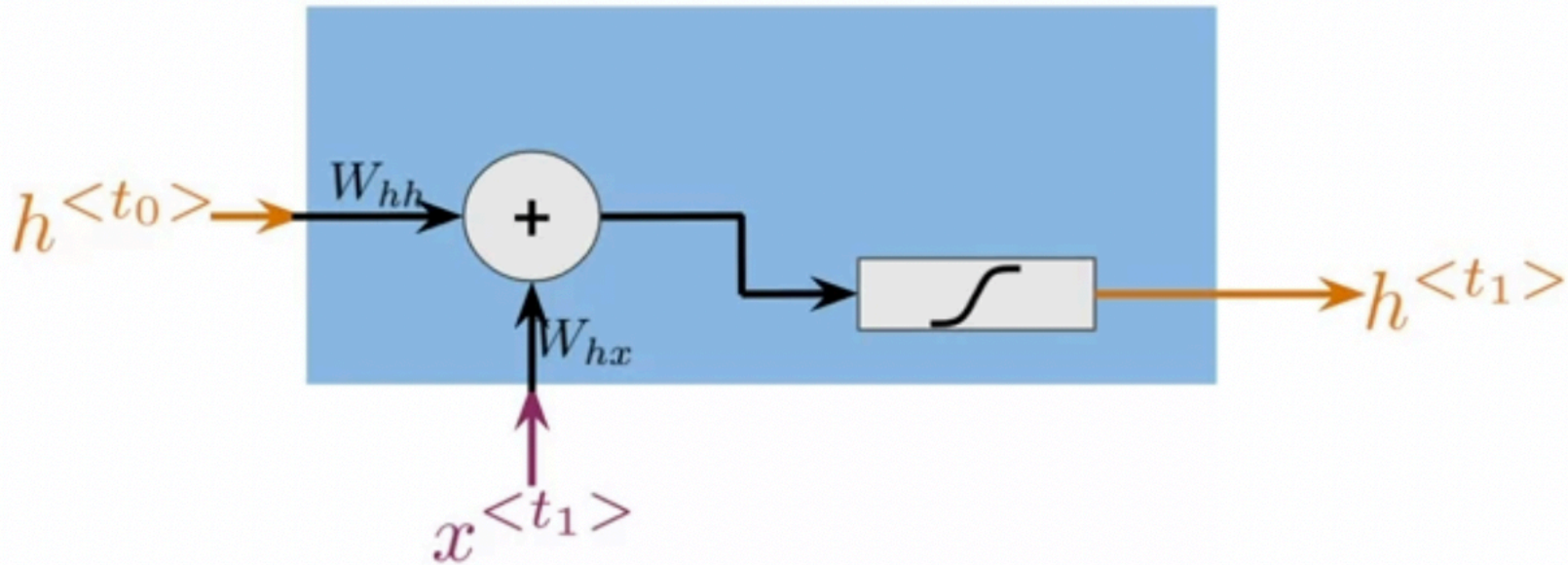




$$h^{<t>} = g(W_{hh}h^{<t-1>} \oplus W_{hx}x^{<t>} + b_h)$$

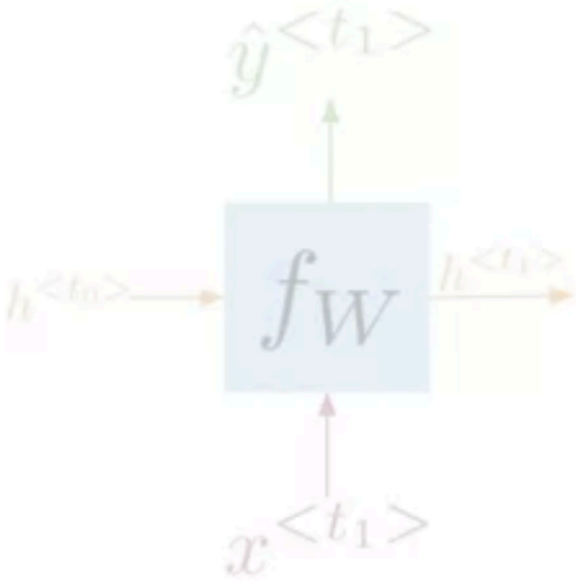
A Vanilla RNN

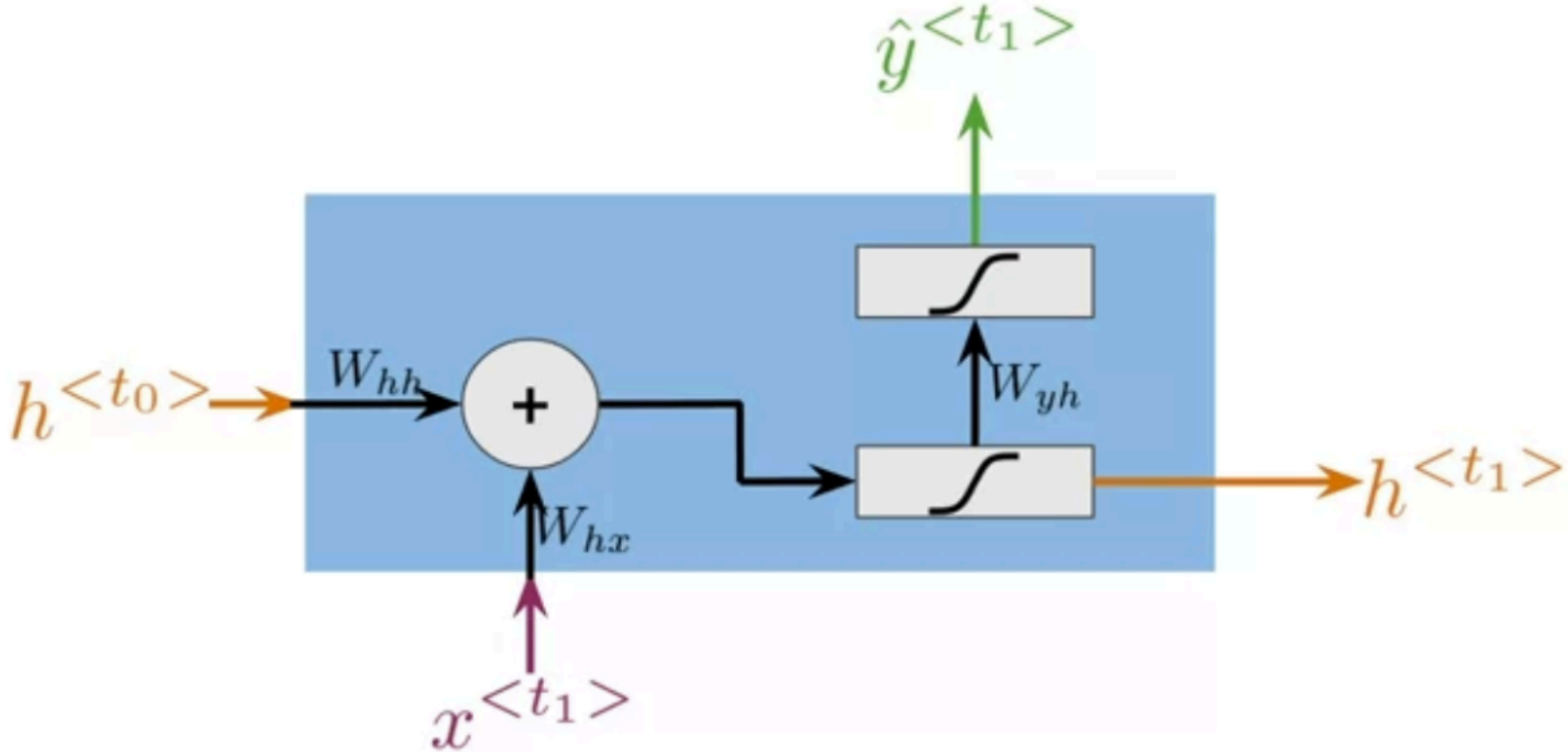




$$h^{<t>} = g(W_{hh}h^{<t-1>} \oplus W_{hx}x^{<t>} + b_h)$$

A Vanilla RNN





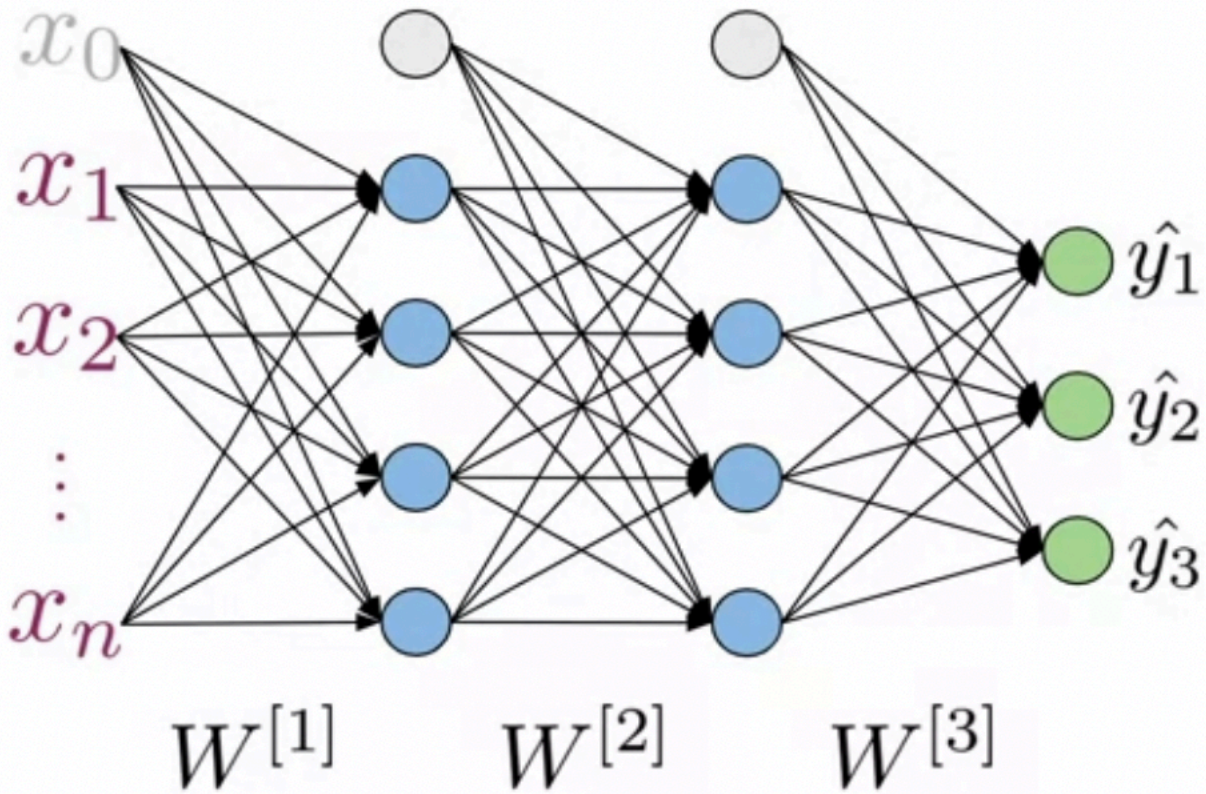
$$h^{<t>} = g(W_{hh}h^{<t-1>} \oplus W_{hx}x^{<t>} + b_h)$$

$$\hat{y}^{<t>} = g(W_{yh}h^{<t>} + b_y)$$

Summary

- Hidden states propagate information through time
- Basic recurrent units have two inputs at each time: $h^{<t-1>}$, $x^{<t>}$

Cross Entropy Loss



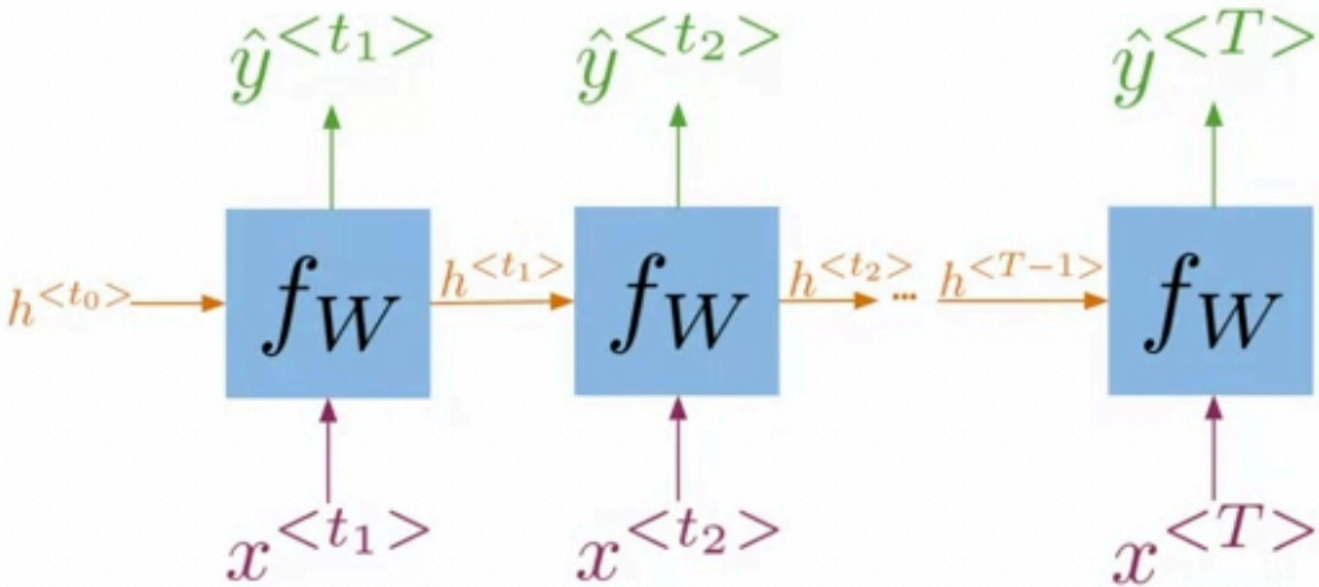
K - classes or possibilities

Either 0 or 1

$$J = -\sum_{j=1}^{K} y_j \log \hat{y}_j$$

Looking at a single example (x, y)

Cross Entropy Loss



$$h^{<t>} = g(W_h[h^{<t-1>}, x^{<t>}] + b_h)$$

$$\hat{y}^{<t>} = g(W_{yh}h^{<t>} + b_y)$$

$$J = -\frac{1}{T}\sum_{t=1}^{T}\sum_{j=1}^{K} y_j^{<t>} \log \hat{y}_j^{<t>}$$

Average with respect to time

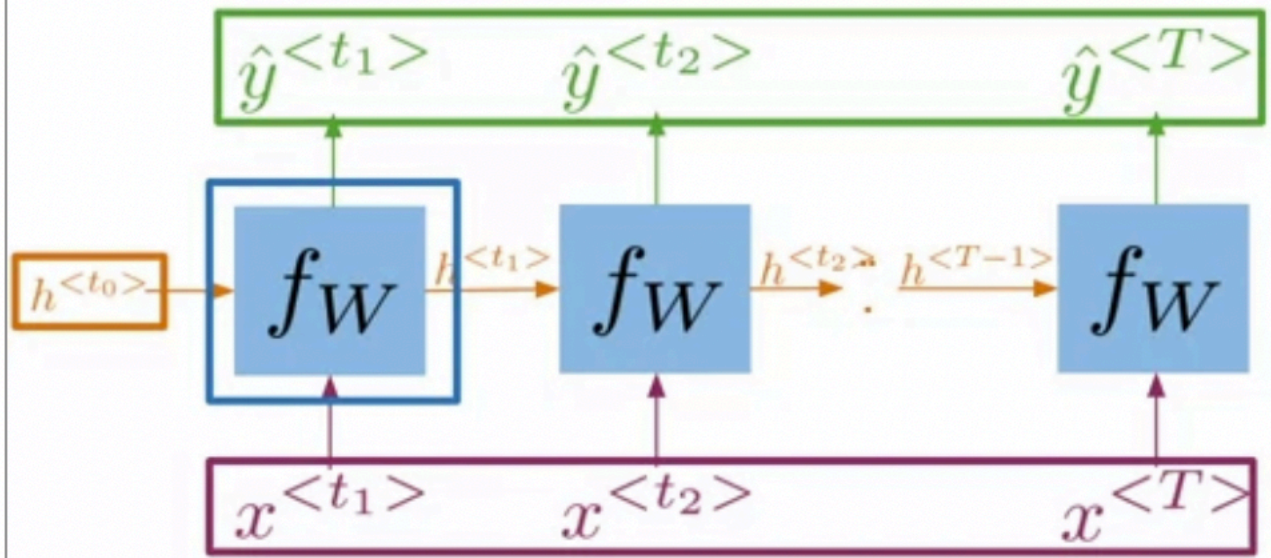
Summary

For RNNs the loss function is just an average through time!

Outline

- scan() function in tensorflow
- Computation of forward propagation using abstractions

tf.scan() function



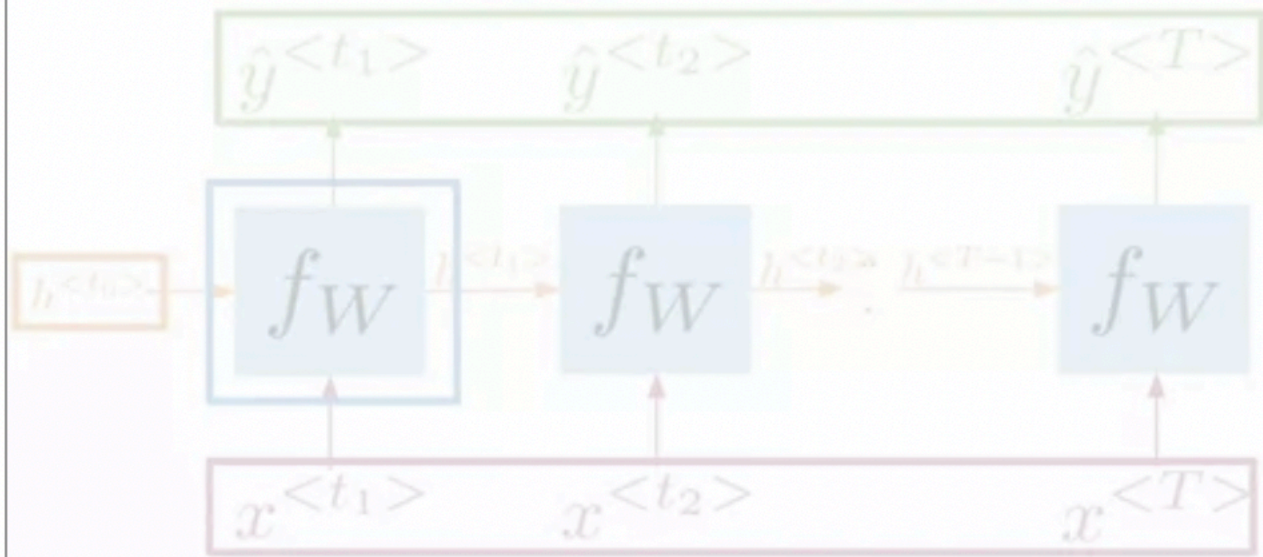

```
def scan(fn, elems, initializer=None, ...):

    cur_value = initializer
    ys = []

    for x in elems:
        y, cur_value = fn(x, cur_value)
        ys.append(y)

    return ys, cur_value
```

tf.scan() function

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        y, cur_value = fn(x, cur_value)
        ys.append(y)

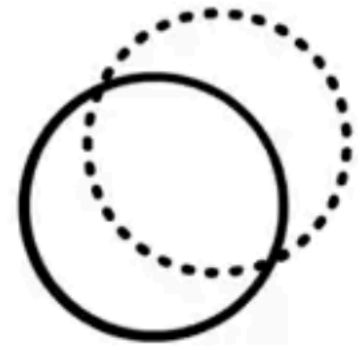
    return ys, cur_value
```

Frameworks like Tensorflow need this type of abstraction

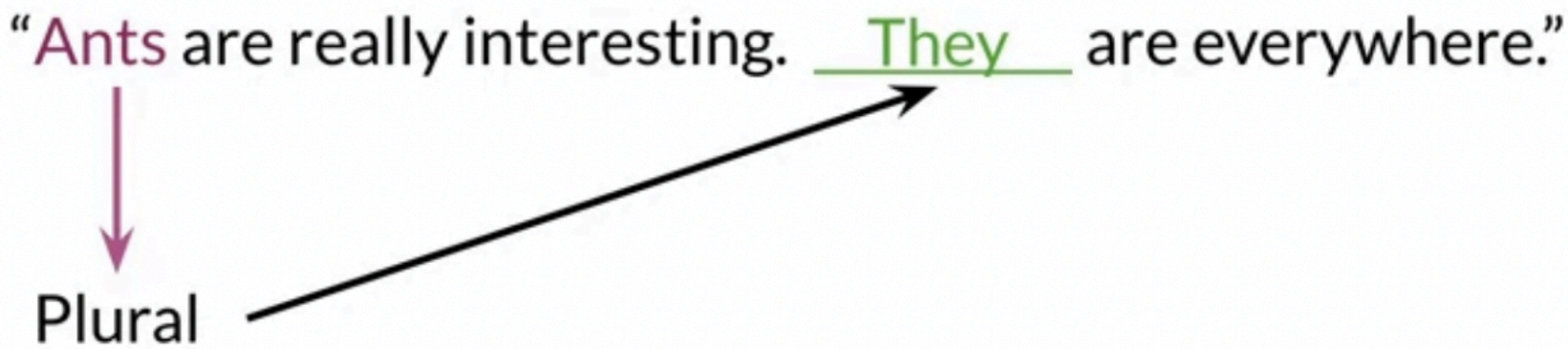
Parallel computations and GPU usage

Summary

- Frameworks require abstractions
- tf.scan() mimics RNNs

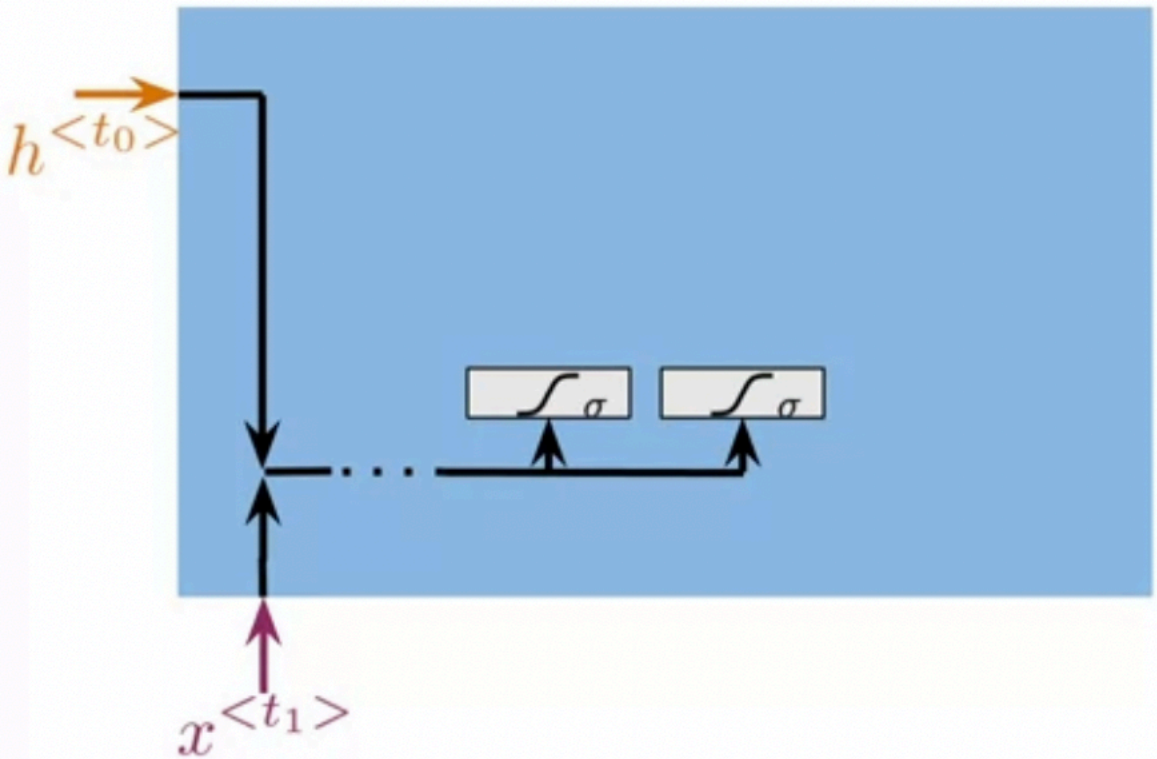


Gated Recurrent Units



Relevance and update gates to remember important prior information

Gated Recurrent Unit

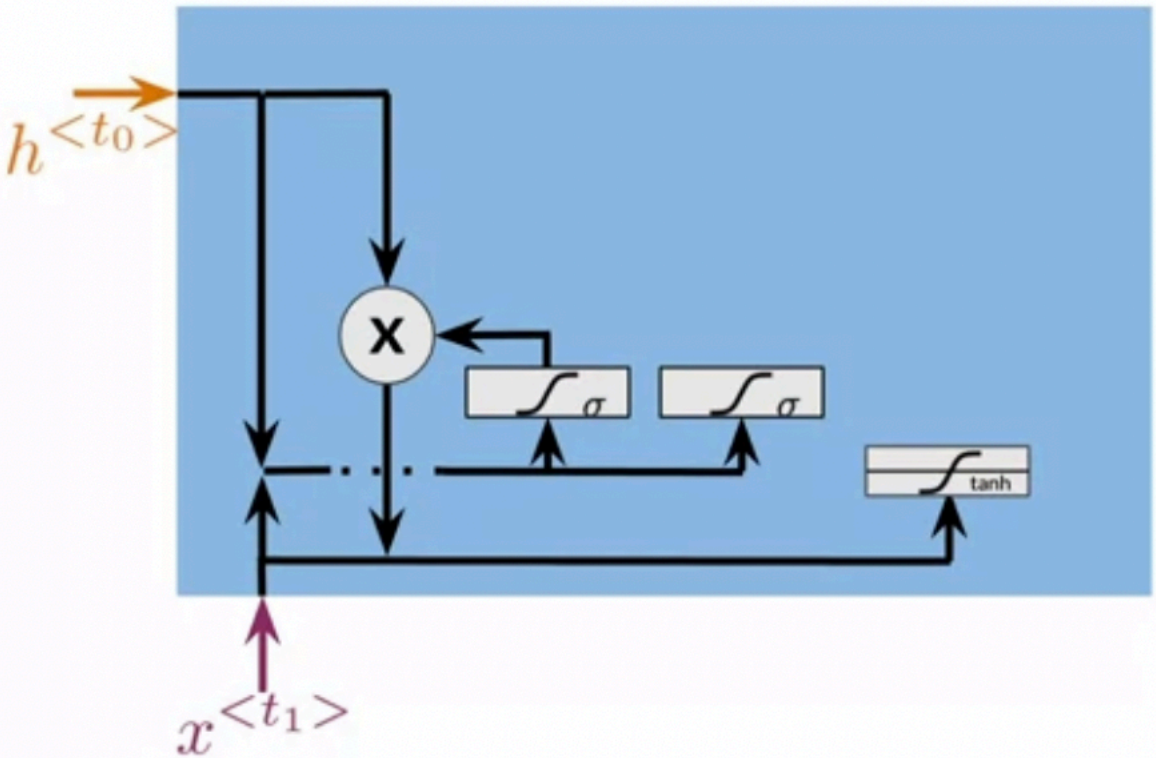


Gates to keep/update relevant information in the hidden state

$$\Gamma_r = \sigma(W_r[h^{<t_0>}, x^{<t_1>}] + b_r)$$

$$\Gamma_u = \sigma(W_u[h^{<t_0>}, x^{<t_1>}] + b_u)$$

Gated Recurrent Unit



Gates to keep/update relevant information in the hidden state

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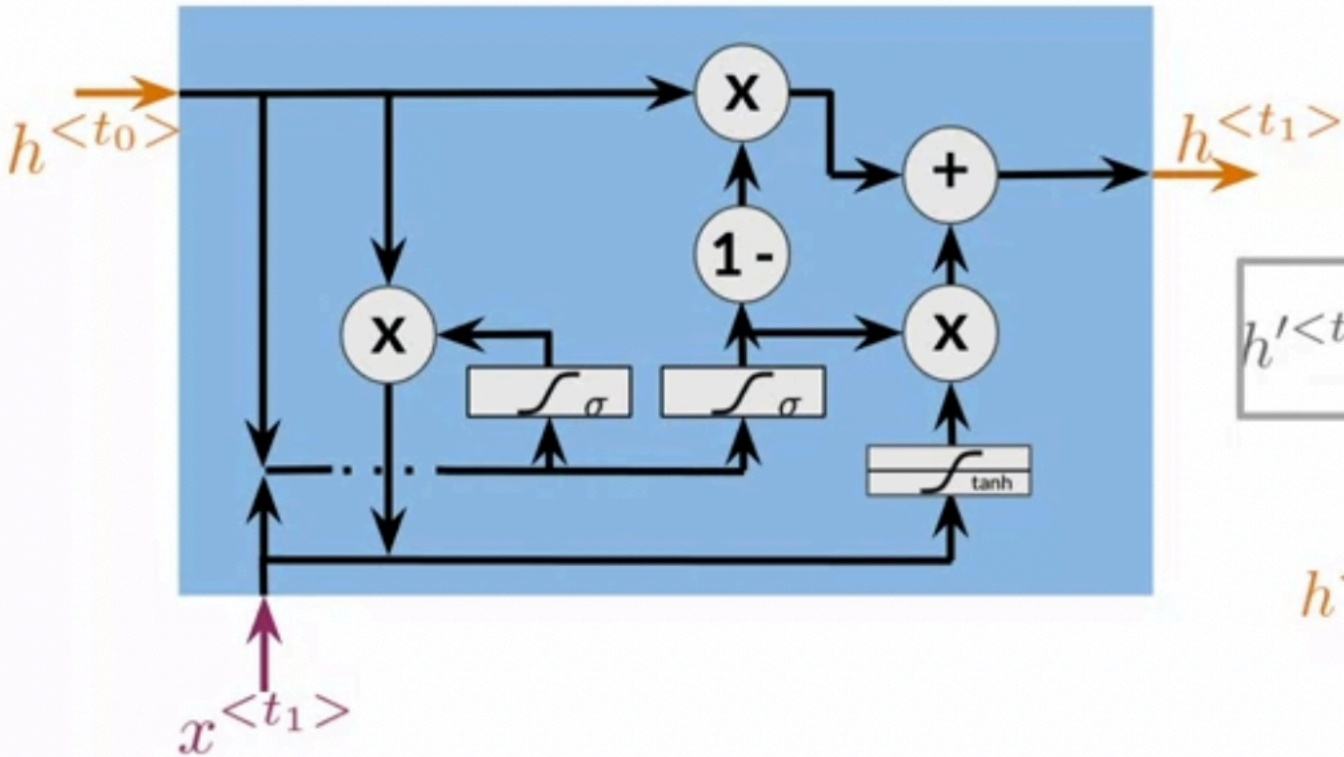
$$\Gamma_u = \sigma(W_u[h^{<t_0>}, x^{<t_1>}] + b_u)$$

$$h'^{<t_1>} = \tanh(W_h[\Gamma_r * h^{<t_0>}, x^{<t_1>}] + b_h)$$

Hidden state candidate

Gated Recurrent Unit



Gates to keep/update relevant information in the hidden state

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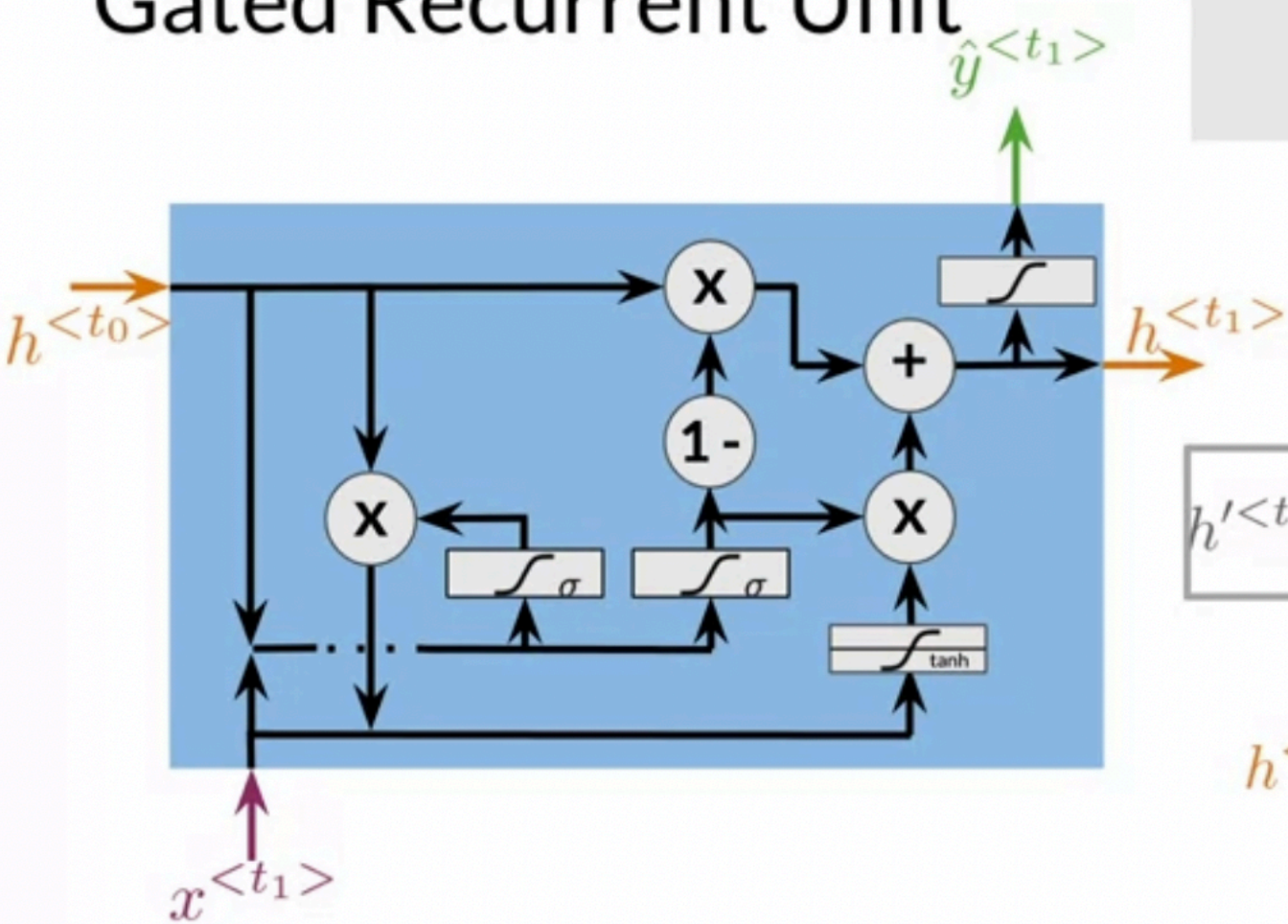
Hidden state candidate

$$h^{<t_1>} = \Gamma_u * h^{<t_0>} + (1 - \Gamma_u) * h'^{<t_1>}$$

Gated Recurrent Unit



Gates to keep/update relevant information in the hidden state

$$\Gamma_r = \sigma(W_r[h^{<t_0>}, x^{<t_1>}] + b_r)$$

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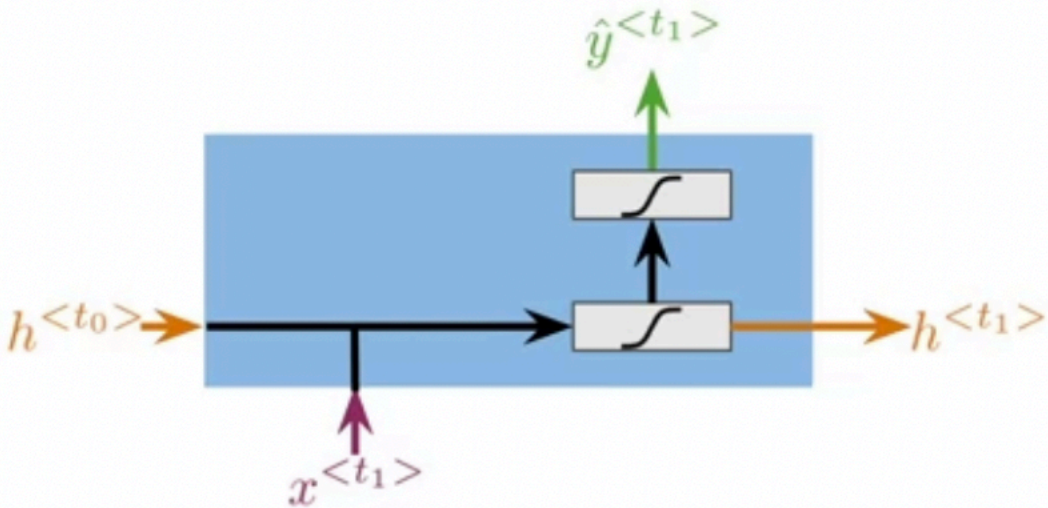
$$h'^{<t_1>} = \tanh(W_h[\Gamma_r * h^{<t_0>}, x^{<t_1>}] + b_h)$$

Hidden state candidate

$$h^{<t_1>} = \Gamma_u * h^{<t_0>} + (1 - \Gamma_u) * h'^{<t_1>}$$

$$\hat{y}^{<t_1>} = g(W_y h^{<t_1>} + b_y)$$

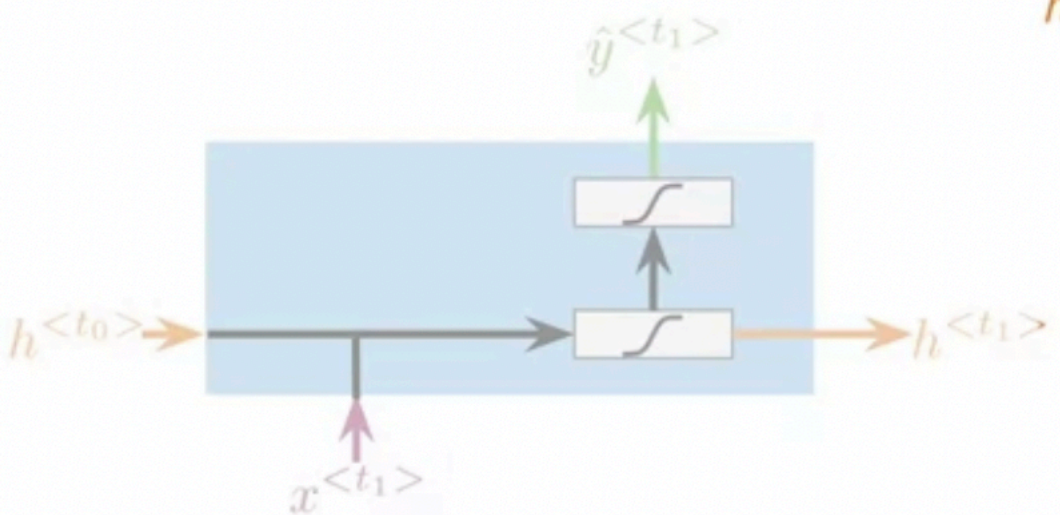
Vanilla RNN vs GRUs



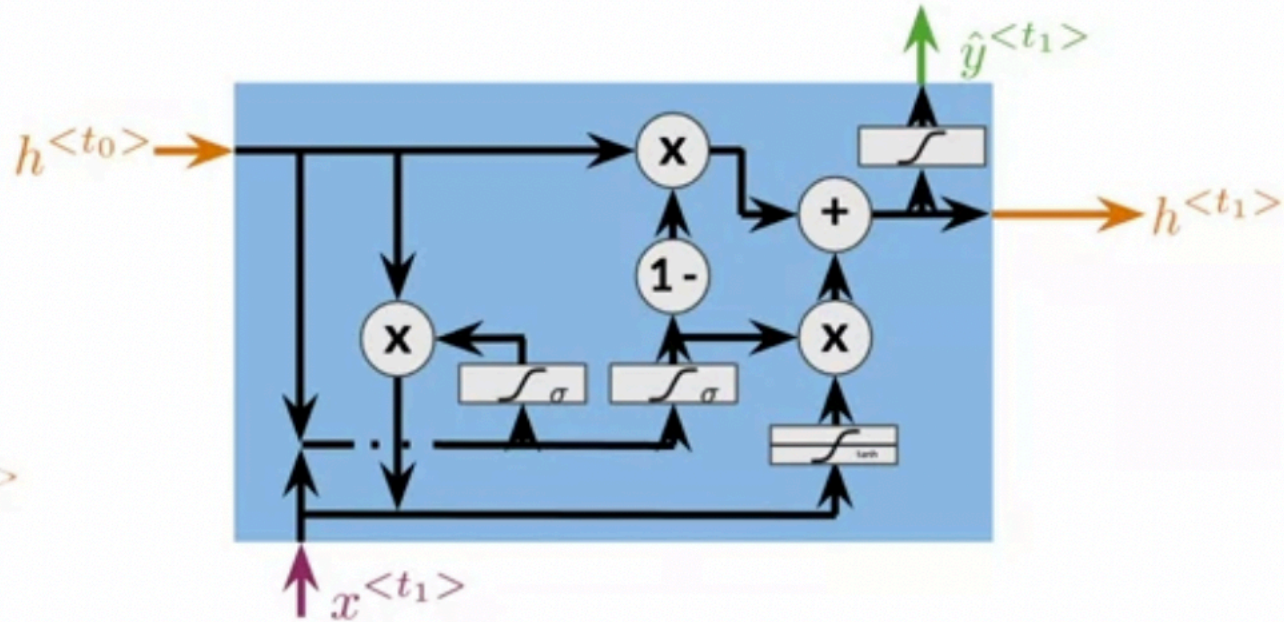
$$h^{<t>} = g(W_h[h^{<t-1>}, x^{<t>}] + b_h)$$

$$\hat{y}^{<t>} = g(W_{yh}h^{<t>} + b_y)$$

Vanilla RNN vs GRUs



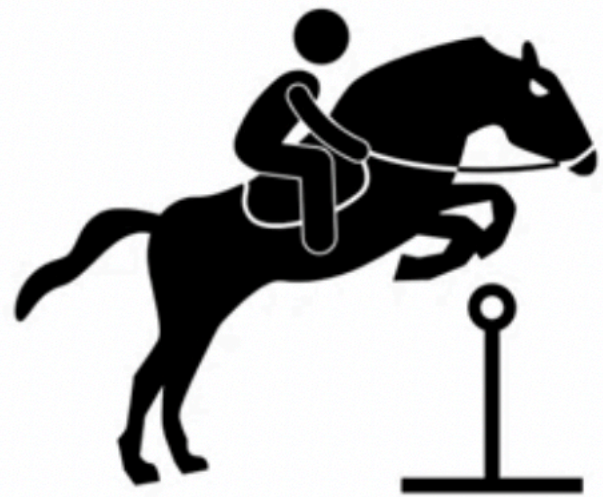
$$h^{<t>} = g(W_h[h^{<t-1>}, x^{<t>}] + b_h)$$
$$\hat{y}^{<t>} = g(W_{yh}h^{<t>} + b_y)$$



$$\Gamma_u = \sigma(W_u[h^{<t_0>}, x^{<t_1>}] + b_u)$$
$$\Gamma_r = \sigma(W_r[h^{<t_0>}, x^{<t_1>}] + b_r)$$
$$h'^{<t_1>} = \tanh(W_h[\Gamma_r * h^{<t_0>}, x^{<t_1>}] + b_h)$$
$$h^{<t_1>} = \Gamma_u * h^{<t_0>} + (1 - \Gamma_u) * h'^{<t_1>}$$
$$\hat{y}^{<t_1>} = g(W_y h^{<t_1>} + b_y)$$

Summary

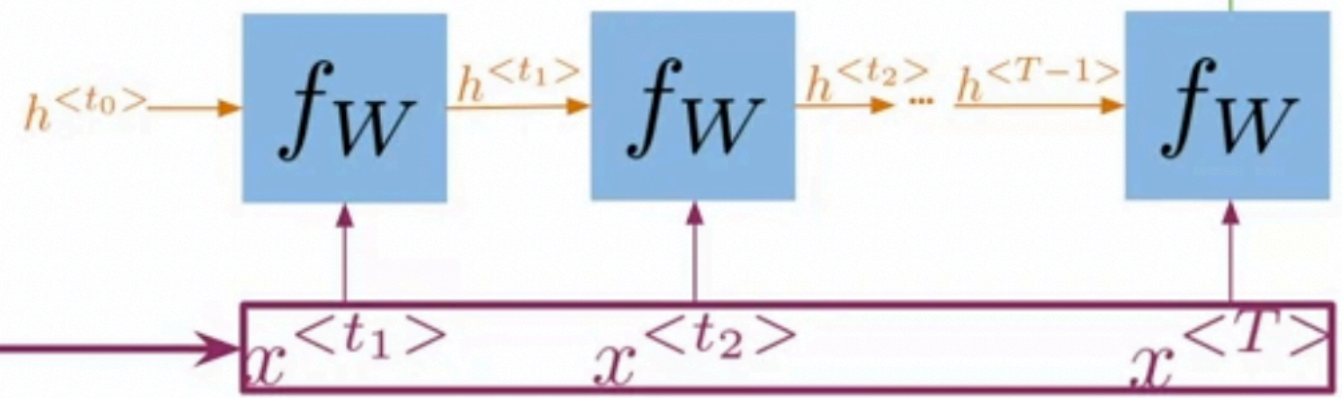
- GRUs “decide” how to update the hidden state
- GRUs help preserve important information



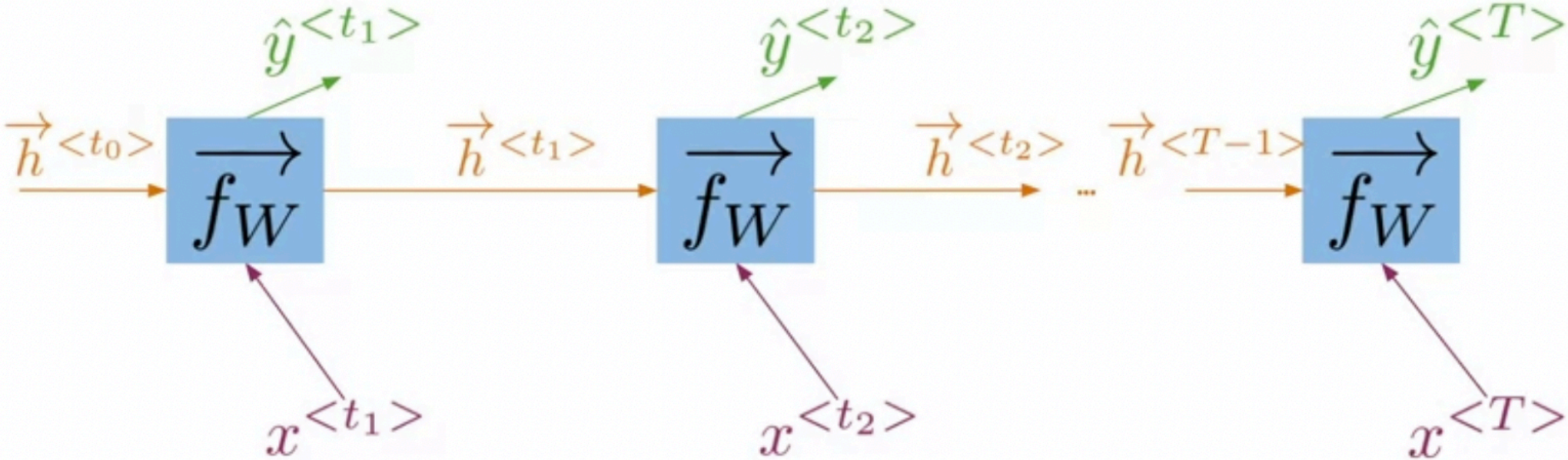
Bi-directional RNNs

I was trying really hard to get a hold of _____. **Louise,** finally answered when I was about to give up.

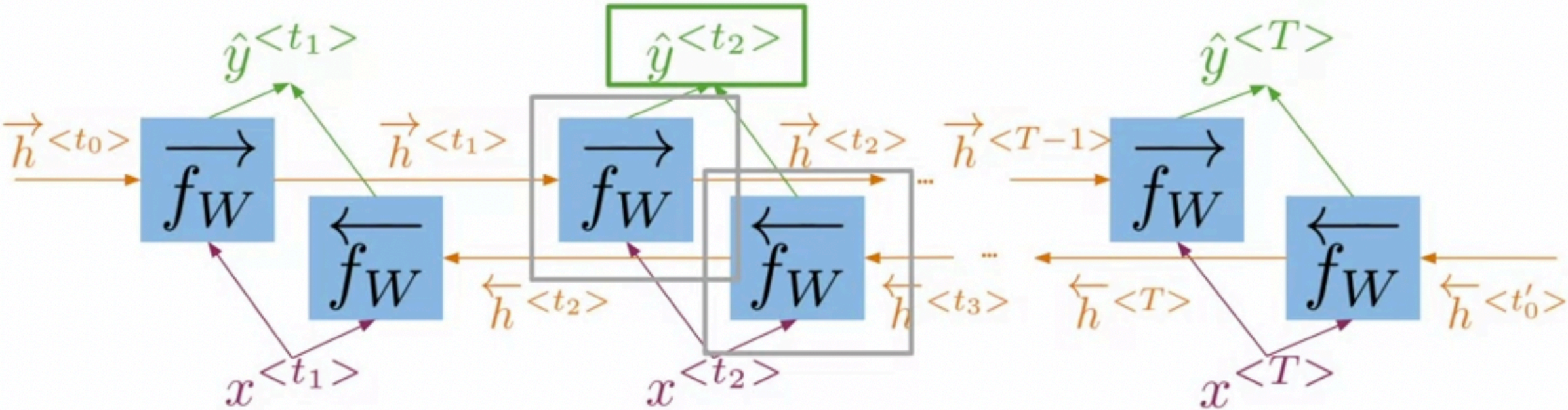
her him them



Bi-directional RNNs

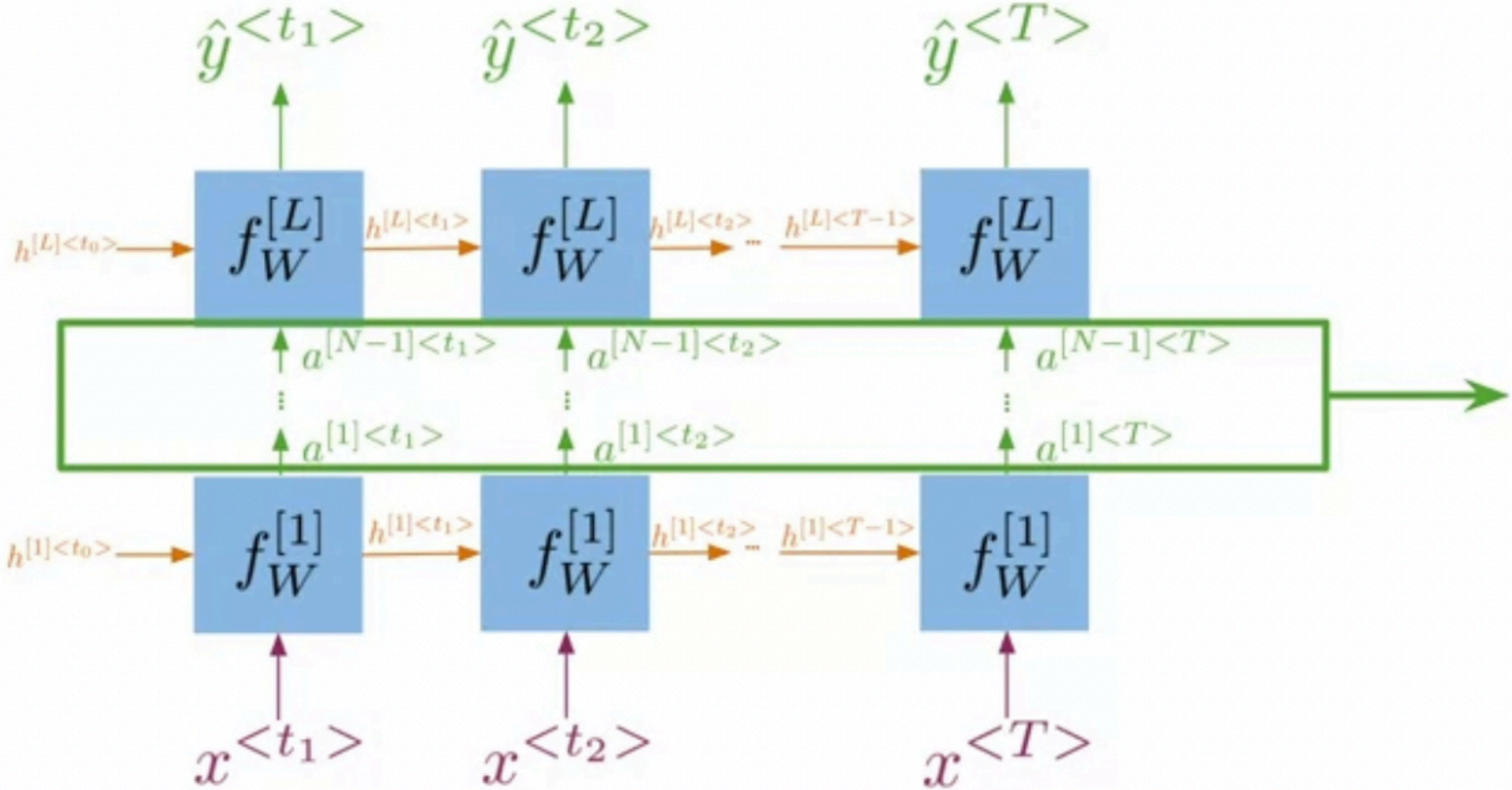


Bi-directional RNNs



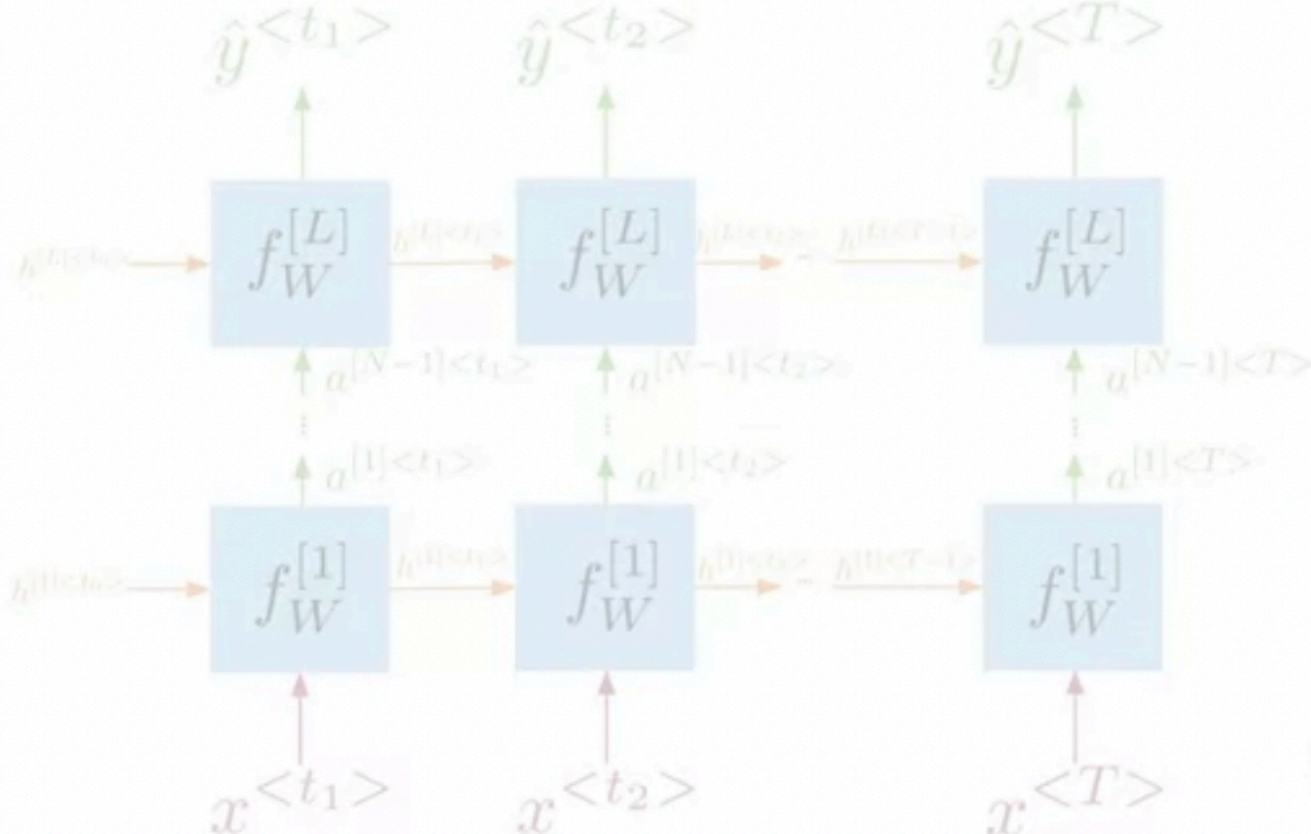
Information flows from the past and from the future **independently**

Deep RNNs



Intermediate layers and activations

Deep RNNs



$$h^{[l]<t>} = f^{[l]}(W_h^{[l]}[h^{[l]<t-1>}, a^{[l-1]<t>}] + b_h^{[l]})$$

$$a^{[l]<t>} = f^{[l]}(W_a^{[l]} h^{[l]<t>} + b_a^{[l]})$$

1. Get hidden states for current layer
2. Pass the activations to the next layer

Summary

- In bidirectional RNNs, the outputs take information from the past and the future
- Deep RNNs have more than one layer, which helps in complex tasks