

benchmarking

June 4, 2020

1 Benchmarking numpy / scikit-image / scipy vs clesperanto

```
In [1]: import clesperanto as cle
import numpy as np
import time
import matplotlib.pyplot as plt

num_iterations = 10

# measure execution time of a given method
def benchmark(function, kwargs):
    times = []
    for i in range(0, num_iterations):
        start_time = time.time()
        function(**kwargs)
        delta_time = time.time() - start_time
        times = times + [delta_time]
        # print(delta_time)

# return median of measurements to ignore warmup-effects
    return np.median(times)

def benchmark_size(method_np, method_cle, method_cle_alloc):
    times_ref = []
    times_cle = []
    times_cle_alloc = []
    sizes = []
    for size in [1, 2, 4, 8, 16, 32, 64]:

        input1 = np.zeros((1024, 1024, size))
        cl_input1 = cle.push(input1)
        cl_input2 = cle.create(cl_input1.shape)

        time_ref = benchmark(method_np, {"image":input1})
        time_cle = benchmark(method_cle, {"image":cl_input1, "output":cl_input2})
```

```

time_cle_alloc = benchmark(method_cle_alloc, {"image":cl_input1})

times_ref = times_ref + [time_ref]
times_cle = times_cle + [time_cle]
times_cle_alloc = times_cle_alloc + [time_cle_alloc]
sizes = sizes + [size]

plt.plot(sizes, times_ref, 'r--', sizes, times_cle, 'g--', sizes, times_cle_alloc)
plt.ylabel('Time / ms')
plt.xlabel('Image size / MB')
plt.legend(("ref", "cle", "cle+alloc"));
plt.show()

print("\nSizes (MB)           " + str(sizes))
print("Times ref (s)           " + str(np.round(times_ref, 4)))
print("Times cle (s)            " + str(np.round(times_cle, 4)))
print("Times cle+alloc (s)      " + str(np.round(times_cle_alloc, 4)))

```

1.1 Thresholding

```

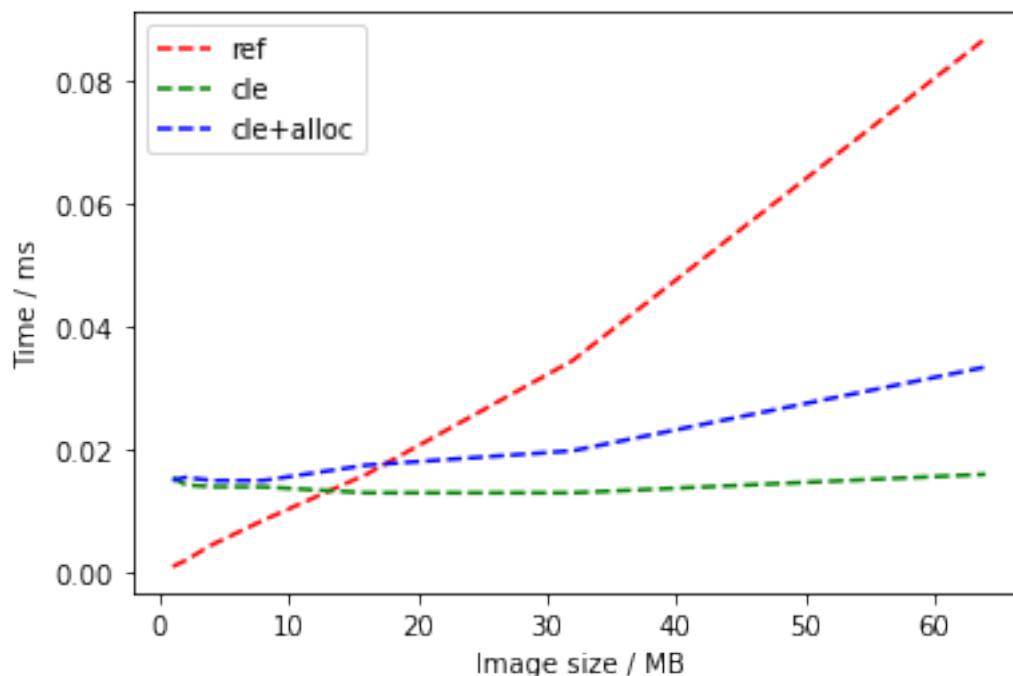
In [2]: # RED: thresholding of a numpy array
def threshold_ref(image):
    thresholded = image > 100
    return thresholded

# GREEN: thresholding of a pre-existing opencv array (no push, pull or alloc)
def threshold_cle(image, output):
    cle.greater_constant(image, output, 100)

# BLUE: allocate result memory + thresholding
def threshold_cle_alloc(image):
    thresholded = cle.create(image.shape)
    cle.greater_constant(image, thresholded, 100)

benchmark_size(threshold_ref, threshold_cle, threshold_cle_alloc)

```



```
Sizes (MB)          [1, 2, 4, 8, 16, 32, 64]
Times ref (s)       [0.001 0.002 0.0045 0.0085 0.016 0.0345 0.0868]
Times cle (s)       [0.0155 0.0143 0.014 0.0139 0.013 0.013 0.016 ]
Times cle+alloc (s) [0.015 0.0155 0.015 0.015 0.0175 0.0198 0.0334]
```

1.2 Gaussian blur radius 2

```
In [3]: from skimage.filters import gaussian
```

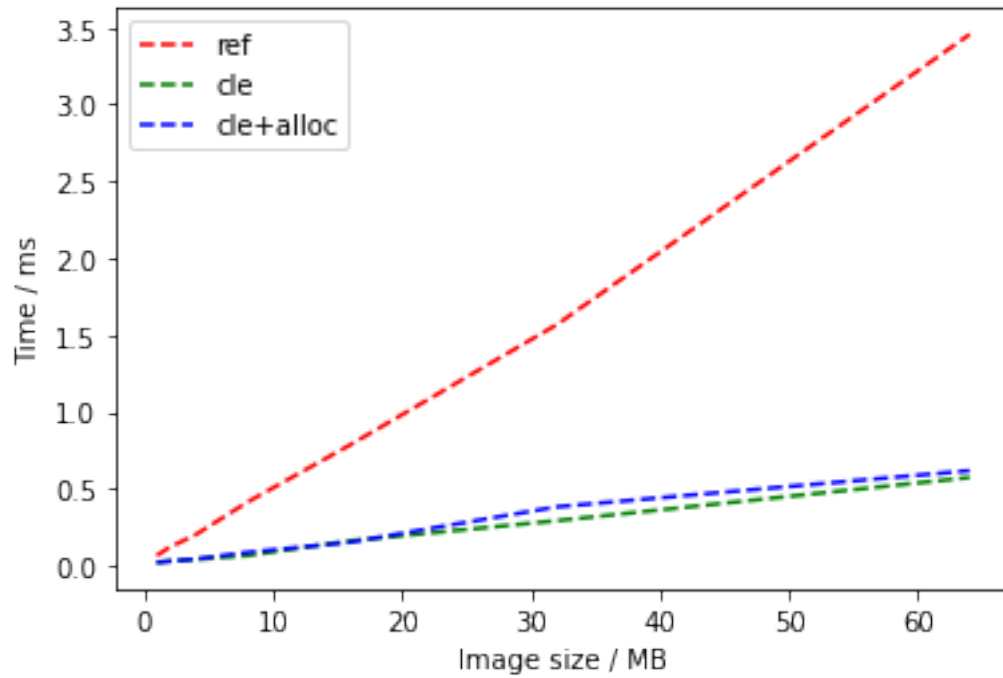
```
radius = 2
```

```
def gaussian_blur_filter_ref(image):
    filtered = gaussian(image, sigma=radius)
    return filtered
```

```
def gaussian_blur_filter_cle(image, output):
    cle.gaussian_blur(image, output, radius, radius, radius)
```

```
def gaussian_blur_filter_cle_alloc(image):
    filtered = cle.create(image.shape)
    cle.gaussian_blur(image, filtered, radius, radius, radius)
```

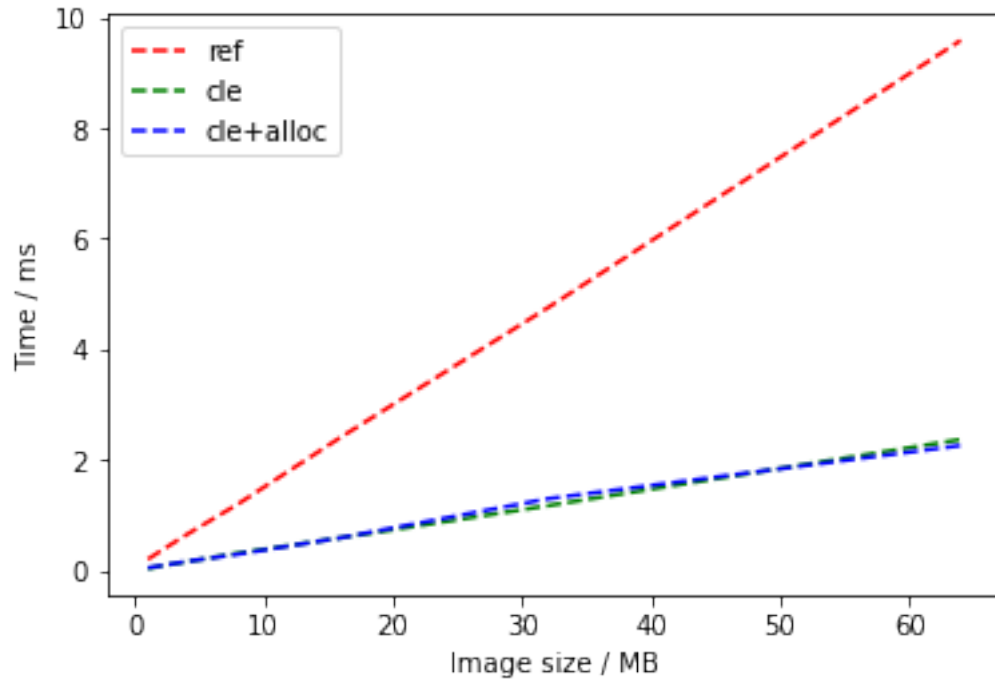
```
benchmark_size(gaussian_blur_filter_ref, gaussian_blur_filter_cle, gaussian_blur_filter_cle_alloc)
```



```
Sizes (MB)          [1, 2, 4, 8, 16, 32, 64]
Times ref (s)       [0.0653 0.1192 0.1999 0.4114 0.7856 1.5673 3.4555]
Times cle (s)       [0.0199 0.0294 0.0399 0.0648 0.1616 0.292 0.5732]
Times cle+alloc (s) [0.0214 0.0289 0.0424 0.0853 0.1521 0.3822 0.6174]
```

1.3 Gaussian blur radius 10

```
In [4]: radius = 10
        benchmark_size(gaussian_blur_filter_ref, gaussian_blur_filter_cle, gaussian_blur_filter_cle+alloc)
```



Sizes (MB)	[1, 2, 4, 8, 16, 32, 64]
Times ref (s)	[0.2077 0.3602 0.6532 1.2087 2.4212 4.7539 9.585]
Times cle (s)	[0.0399 0.0851 0.162 0.3166 0.5969 1.1758 2.3712]
Times cle+alloc (s)	[0.0524 0.0905 0.168 0.3005 0.5974 1.3004 2.2642]

1.4 Binary erosion

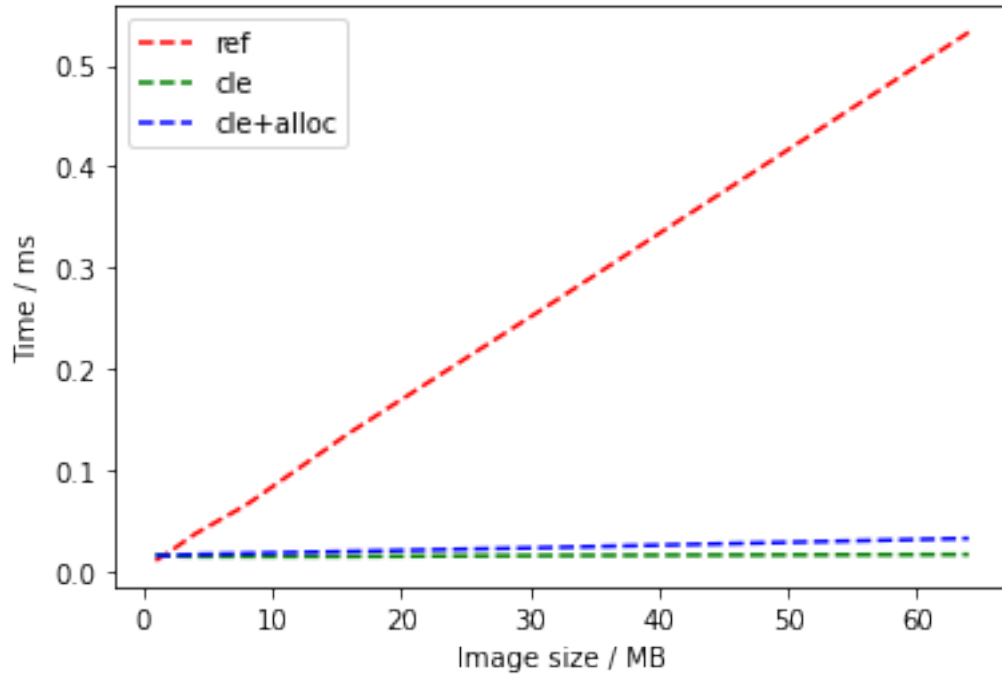
```
In [5]: from skimage.morphology import binary_erosion
```

```
def binary_erosion_ref(image):
    filtered = binary_erosion(image)
    return filtered

def binary_erosion_cle(image, output):
    cle.erode_box(image, output)

def binary_erosion_cle_alloc(image):
    filtered = cle.create(image.shape)
    cle.erode_box(image, filtered)

benchmark_size(binary_erosion_ref, binary_erosion_cle, binary_erosion_cle_alloc)
```



Sizes (MB)	[1, 2, 4, 8, 16, 32, 64]
Times ref (s)	[0.01 0.018 0.0359 0.0648 0.1362 0.2673 0.5328]
Times cle (s)	[0.016 0.0145 0.014 0.014 0.014 0.015 0.016]
Times cle+alloc (s)	[0.015 0.015 0.016 0.017 0.019 0.0229 0.0319]

1.5 Mean filter radius=2

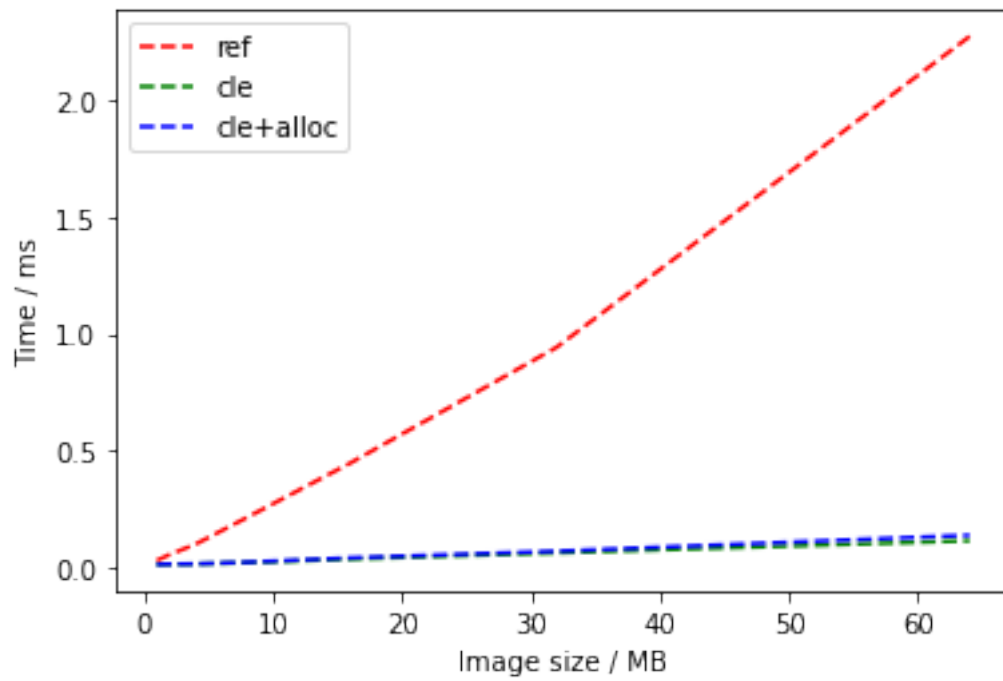
In [6]: `import scipy.ndimage.filters as spf`

```
radius = 2
def mean_filter_ref(image):
    # todo: not sure if size is a radius or a diameter. Check documentation
    # https://docs.scipy.org/doc/scipy/reference/generated/scipy.ndimage.uniform_filter
    filtered = spf.uniform_filter(image, size=radius)
    return filtered

def mean_filter_cle(image, output):
    cle.mean_box(image, output, radius, radius, radius)

def mean_filter_cle_alloc(image):
    filtered = cle.create(image.shape)
    cle.mean_box(image, filtered, radius, radius, radius)
```

```
benchmark_size(mean_filter_ref, mean_filter_cle, mean_filter_cle_alloc)
```



```
Sizes (MB)      [1, 2, 4, 8, 16, 32, 64]
Times ref (s)    [0.0339 0.0593 0.1032 0.2174 0.4493 0.9431 2.2677]
Times cle (s)    [0.017  0.018  0.0194 0.0249 0.0404 0.067  0.1185]
Times cle+alloc (s) [0.0175 0.0189 0.0199 0.0269 0.0455 0.0738 0.1417]
```

```
In [ ]:
```