Linear differential equations
Laplace transform
Solving LDEs with the Laplace transform
Properties of state-space representation
Transfer functions
Transient response analysis of first order and second order systems

Outline

- Linear differential equations
- 2 Laplace transform
- Solving LDEs with the Laplace transform
- Properties of state-space representation
- **5** Transfer functions
 - Impulse response and time constant
 - Relationship between state space and transfer functions
- Transient response analysis of first order and second order systems
 - First order systems
 - Second order systems

Solving LDEs with the Laplace transform 1/3

The Laplace transform can be used to solve LDEs with given initial conditions (the previous approach gave us the basis functions). This is done by using the following property (differentiation):

$$\mathcal{L}{f^{(1)}} = sF(s) - f(0),$$

 $\mathcal{L}{f^{(2)}} = s^2F(s) - sf(0) - f^{(1)}(0).$

Via induction, the Laplace transform of the *n*th order derivative:

$$\mathcal{L}\lbrace f^{(n)}\rbrace = s^n F(s) - \sum_{i=1}^n s^{n-i} f^{(n-i)}(0)$$

Solving LDEs with the Laplace transform 2/3

$$\mathcal{L}{f^{(n)}} = s^n F(s) - \sum_{i=1}^n s^{n-i} f^{(n-i)}(0)$$

We want to solve the following LDE:

$$\sum_{i=0}^{n} A_i y^{(n-i)}(t) = f(t),$$
$$y^{(i)}(0) = c_i \quad \forall i = 0 \dots n.$$

Via the linearity of the Laplace transform:

$$\sum_{i=0}^{n} A_i \mathcal{L}\{y^{(n-i)}(t)\} = \mathcal{L}\{f(t)\}$$

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$$\sum_{i=0}^{n} A_i \mathcal{L}\{y^{(n-i)}(t)\} = \mathcal{L}\{f(t)\}$$
(1)

$$\mathcal{L}\{f^{(n)}\} = s^n F(s) - \sum_{i=1}^n s^{n-i} f^{(n-i)}(0)$$
 (2)

Expanding Eq. (2) into (1) yields:

$$Y(s)\sum_{i=0}^{n}A_{i}s^{i}-\sum_{i=1}^{n}\sum_{j=1}^{i}A_{i}s^{i-j}y^{j-1}(0)=F(s)$$

The solution in the time domain is obtained via the inverse Laplace transform: $y(t) = \mathcal{L}^{-1}\{Y(s)\}.$