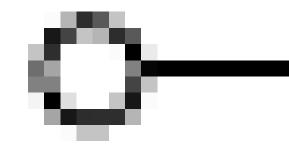
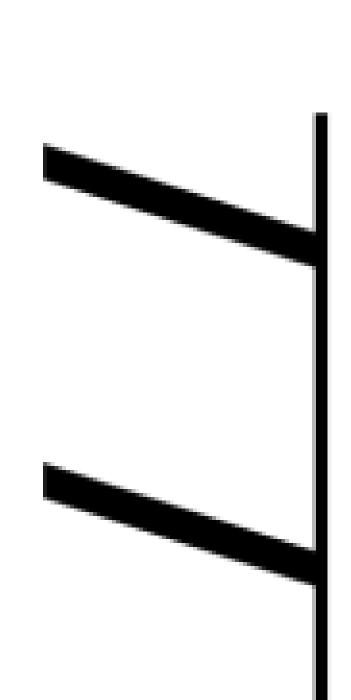
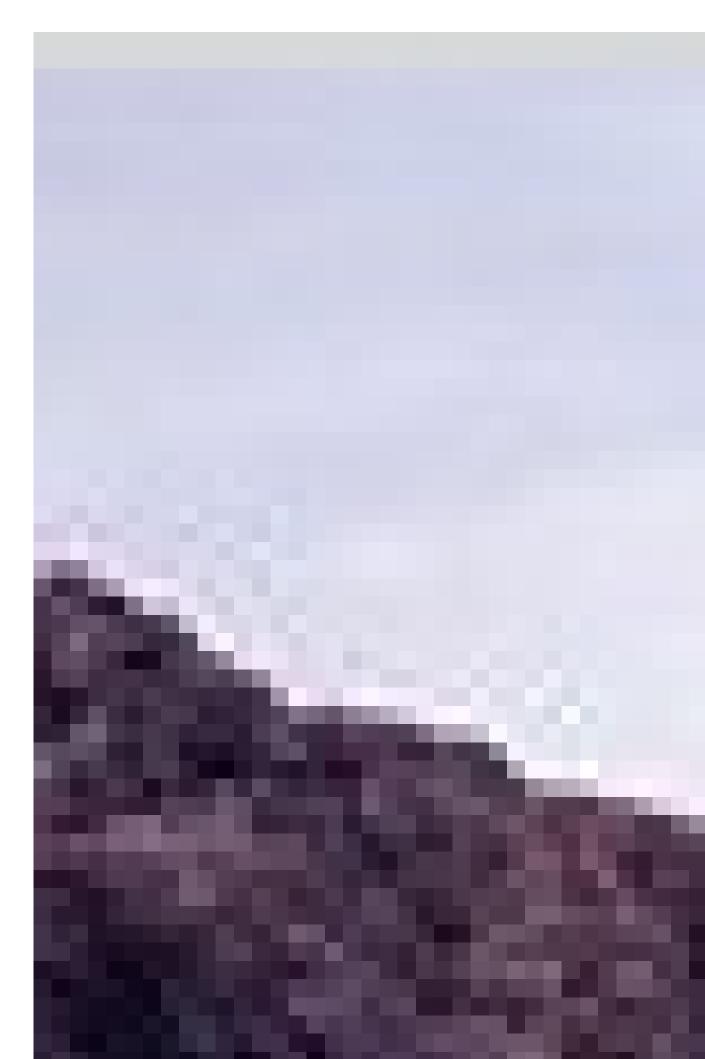


two ways







 $\begin{array}{l} y(t) = c_2 \cdot h(t) \\ \dot{x}(t) = u(t) - y(t) = u(t) - c_2 \cdot h(t) \\ \textbf{State Space Representation} c \triangleq \frac{c_2}{c_1} \end{array}$



