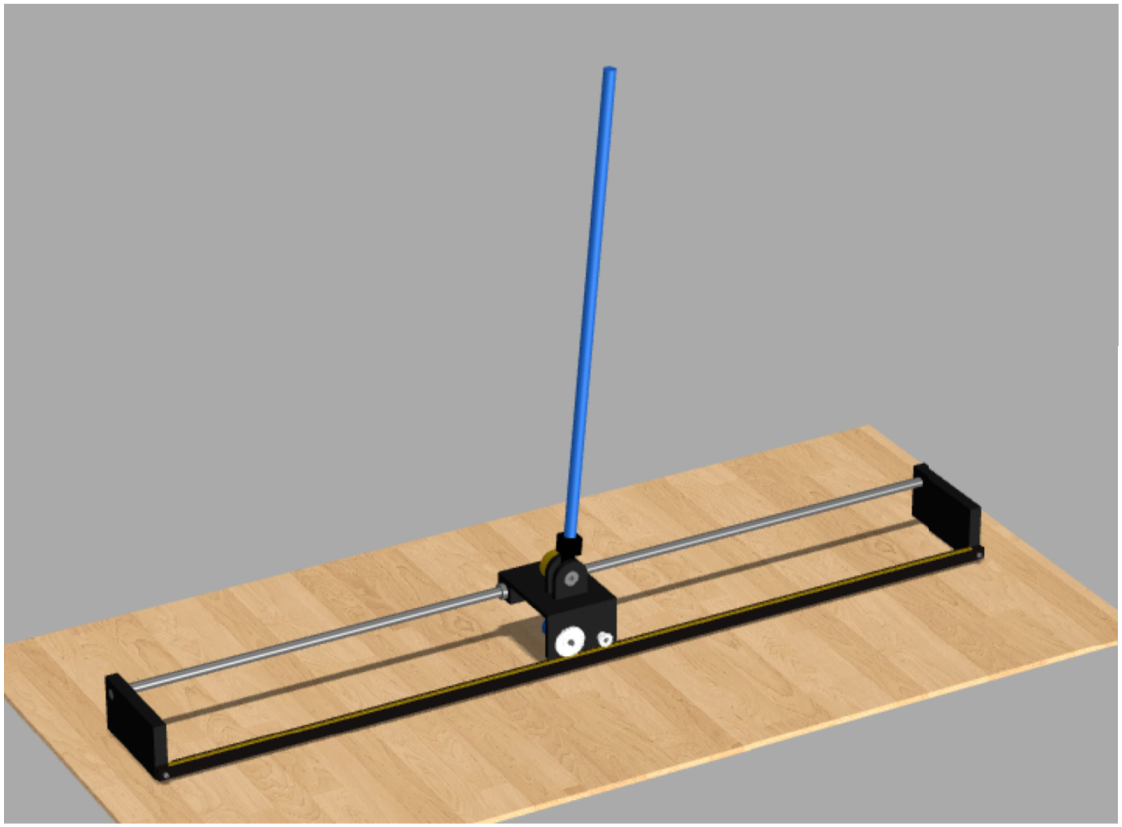
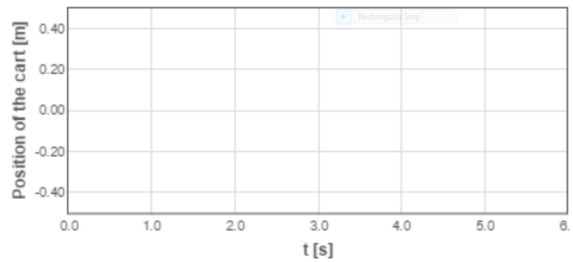
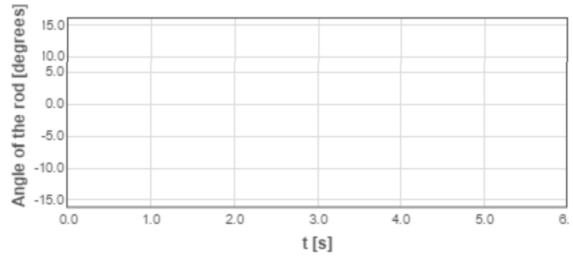
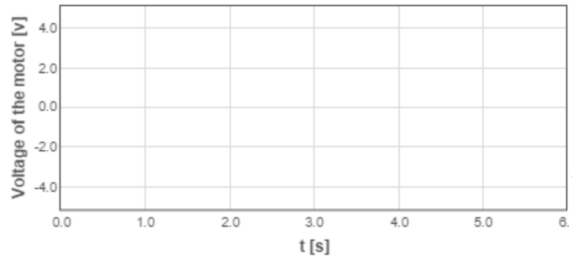
# Outline

**Virtual Lab: Inverted Pendulum**






| Simulation | Setpoint of the cart [m] | Disturbance | Initial conditions | Camera view | Controller u(t) = -K(x(t)-xd(t)) |
|---|---|---|---|---|---|
| Start Stop Reset | Random Steps / Manual : 0 | Push ⇐ Push ⇒ | Cart position [m]: 0 / Rod angle [deg]: 5 | Default Front Top | k1: -9.1287 k2: -52.4975 k3: -14.9912 k4: -6.3533 Default |

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