

## Chapter 5: Continuous-time systems

July 27, 2015

# Outline

- 1 Linear differential equations
- 2 Laplace transform
- 3 Solving LDEs with the Laplace transform
- 4 Properties of state-space representation
- 5 Transfer functions
  - Impulse response and time constant
  - Relationship between state space and transfer functions
- 6 Transient response analysis of first order and second order systems
  - First order systems
  - Second order systems

# Linear differential equations: definitions 1/2

Linear differential equations (LDE) are of the following form:

$$L[y(t)] = f(t),$$

where  $L$  is some linear operator.

The linear operator  $L$  is of the following form:

$$L_n(y) = \sum_{i=0}^n A_i(t) \frac{d^{n-i} y}{dt^{n-i}},$$

with given functions  $A_{1:n}$ .

The **order of a LDE** is the index of the highest derivative of  $y$ .

## Linear differential equations: definitions 2/2

$$L_n(y) = \sum_{i=0}^n A_i(t) \frac{d^{n-i} y}{dt^{n-i}} = f(t).$$

- $y$  is a scalar function  $\rightarrow$  **ordinary differential equation** (ODE);
- $y$  is a vector function  $\rightarrow$  **partial differential equation** (PDE);
- $f = 0 \rightarrow$  **homogeneous equation**  
 $\rightarrow$  solutions are called **complementary functions**;
- if  $A_{0:n}(t)$  are constants (i.e. not functions of time), the LDE is said to have **constant coefficients**.

## Example: radioactive decay 1/2

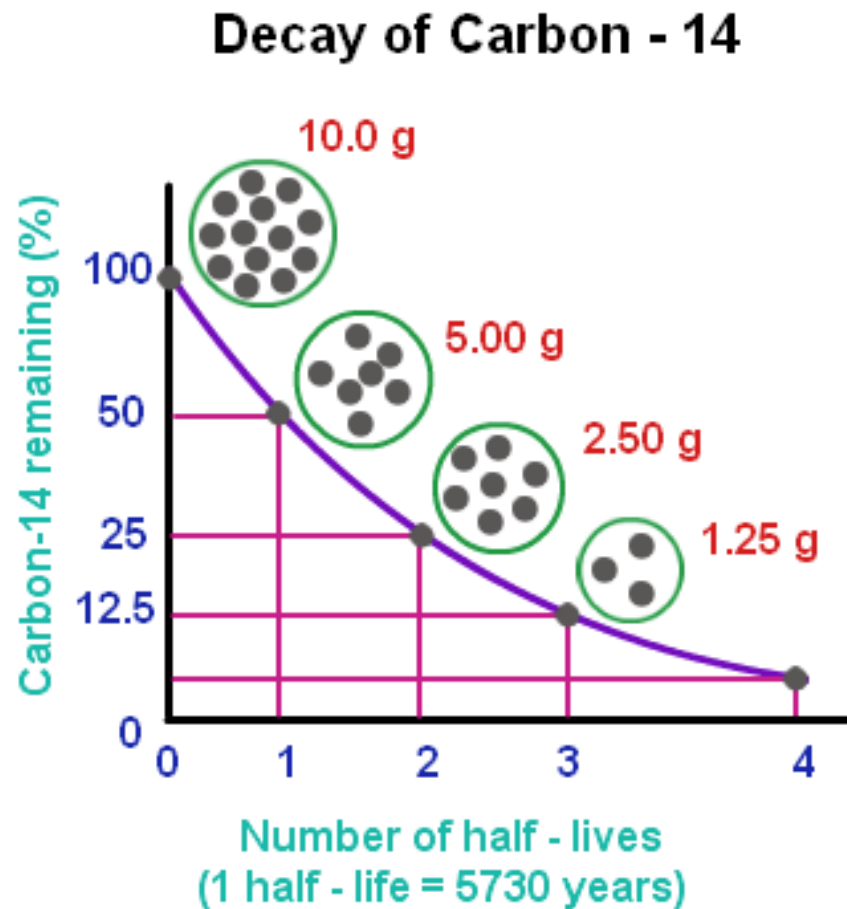
Let  $N(t)$  be the number of radioactive atoms at time  $t$ , then:

$$\frac{dN(t)}{dt} = -kN(t),$$

for some constant  $k > 0$ .

This is a first order homogeneous LDE with constant coefficients.

## Example: radioactive decay 2/2



# Solving homogeneous LDEs with constant coefficients 1/3

Solutions of LDEs must be of the form  $e^{zt}$  with  $z \in \mathbb{C}$ .

We assume an LDE with constant coefficients:

$$\sum_{i=0}^n A_i y^{(n-i)} = 0.$$

Replacing  $y = e^{zt}$  leads to:

$$\sum_{i=0}^n A_i z^{n-i} e^{zt} = 0$$

Dividing by  $e^{zt}$  yields the  $n$ th order **characteristic polynomial**:

$$F(z) = \sum_{i=0}^n A_i z^{n-i} = 0.$$

## Solving homogeneous LDEs with constant coefficients 2/3

Characteristic equation:

$$F(z) = \sum_{i=0}^n A_i z^{n-i} = 0.$$

- ① Solving the polynomial  $F(z)$  yields  $n$  zeros  $z_1$  to  $z_n$ ;
- ② Substituting a given zero  $z_i$  into  $e^{z t}$  gives a solution  $e^{z_i t}$ .

Homogeneous LDEs obey the superposition position:

→ any linear combination of solutions  $e^{z_1 t}, \dots, e^{z_n t}$  is a solution



## Solving homogeneous LDEs with constant coefficients 2/3

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Homogeneous LDEs obey the superposition position:

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→  $e^{z_1 t}, \dots, e^{z_n t}$  form a basis of the solution space of the LDE

The specific linear combination depends on initial conditions.

## Solving homogeneous LDEs with constant coefficients 3/3

### Example

$$y^{(4)}(t) - 2y^{(3)}(t) + 2y^{(2)}(t) - 2y^{(1)}(t) + y(t) = 0.$$

This is a 4th order homogeneous LDE with constant coefficients.  
The corresponding characteristic equation:

$$F(z) = z^4 - 2z^3 + 2z^2 - 2z + 1 = 0.$$

The zeros of  $F(z)$  are ( $j = \sqrt{-1}$ ):

$$z_1 = j, \quad z_2 = -j, \quad z_{3,4} = 1.$$

These zeros correspond to the following basis functions  $t$ :

$$e^{jt}, \quad e^{-jt}, \quad e^t, \quad te^t.$$

Linear differential equations

Laplace transform

Solving LDEs with the Laplace transform

Properties of state-space representation

Transfer functions

Transient response analysis of first order and second order systems

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# The Laplace transform

## Definition

The Laplace transform of  $f(t)$ , for all real numbers  $t \geq 0$ :

$$F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt.$$

The parameter  $s = \sigma + j\omega$  is the complex number frequency.

The initial value theorem states  $f(0^+) = \lim_{s \rightarrow \infty} sF(s)$ .

The final value theorem states  $f(\infty) = \lim_{s \rightarrow 0} sF(s)$ ,

if all poles of  $sF(s)$  are in the left half plane (i.e. real part  $< 0$ ).

# Important properties of the Laplace transform

property	time domain	s-domain
linearity	$af(t) + bg(t)$	$aF(s) + bG(s)$
differentiation	$f^{(1)}(t)$	$sF(s) - f(0)$
integration	$\int_0^t f(\tau)d\tau = (u * f)(t)$	$\frac{1}{s}F(s)$
convolution	$(f * g)(t) = \int_0^t f(\tau)g(t - \tau)d\tau$	$F(s) \cdot G(s)$
time scaling	$f(at)$	$\frac{1}{a}F\left(\frac{s}{a}\right)$
time shifting	$f(t - a)u(t - a)$	$e^{-as}F(s)$

# Inverse Laplace transform

## Definition

The inverse Laplace transform converts  $s$ -domain to time domain:

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = \frac{1}{j2\pi} \int_{\gamma-jT}^{\gamma+jT} e^{st} F(s) ds.$$

Practically, the inverse Laplace transform takes two steps:

- 1 write  $F(s)$  in terms of partial fractions
- 2 transform each term in the partial fraction  
based on tables of  $s/t$ -domain pairs  
(course notes p. 4.32-4.33)