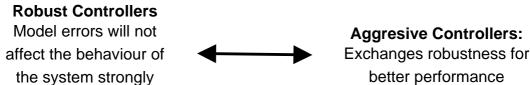
Good disturbance rejection Not sensitive to noise Fast tracking Small control inputs Robust Controllers Model errors will not **Aggresive Controllers:**

Fast Controllers



Slow Controllers