Remarks

# Demo 1: Second Order Systems

No remarks, works fine

# Demo 2: First Order Systems

No remarks, works fine

# Demo 3: PID controllers

It is perhaps a little confusing fort the user what is happening. You have to give in a transfer function and the PID constants. It takes some times before you realize what influences what.

# Demo 4: Root Locus

No remarks, works fine

# Demo 5: Transfer Function and Bode Plot

Formulas of the output are still in Latex code, this needs to be fixed.

# Demo 6: From 3D-Plot to Magnitude Plot

Step 2 : The bode plot gives **us** , last sentence of 2 paragraph should be corrected, last sentence of 2 paragraph should be corrected, last part of last paragraph is missing.

# Demo 7: Time and frequency response of dynamical systems

Cursor for Nyquist Plot should be fixed (this is gonna take some rewriting of the code)

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