

Week 1

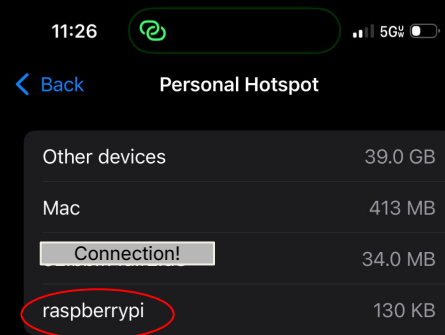
Progress



Raspberry Pi Swap Out Camera Cable



Raspberry Pi Headless Boot



Raspberry Pi Headless Boot

```
The programs included with the Debian GNU/Linux system are free software;  
the exact distribution terms for each program are described in the  
individual files in /usr/share/doc/*/copyright.
```

```
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.
```

```
Last login: Mon May 12 20:24:45 2025
```

```
[smplasketch@raspberrypi:~ $ ls
```

```
Bookshelf  Documents  Music      Public     Videos
```

```
Desktop    Downloads  Pictures   Templates
```

```
smplasketch@raspberrypi:~ $
```

Raspberry Pi Headless Boot

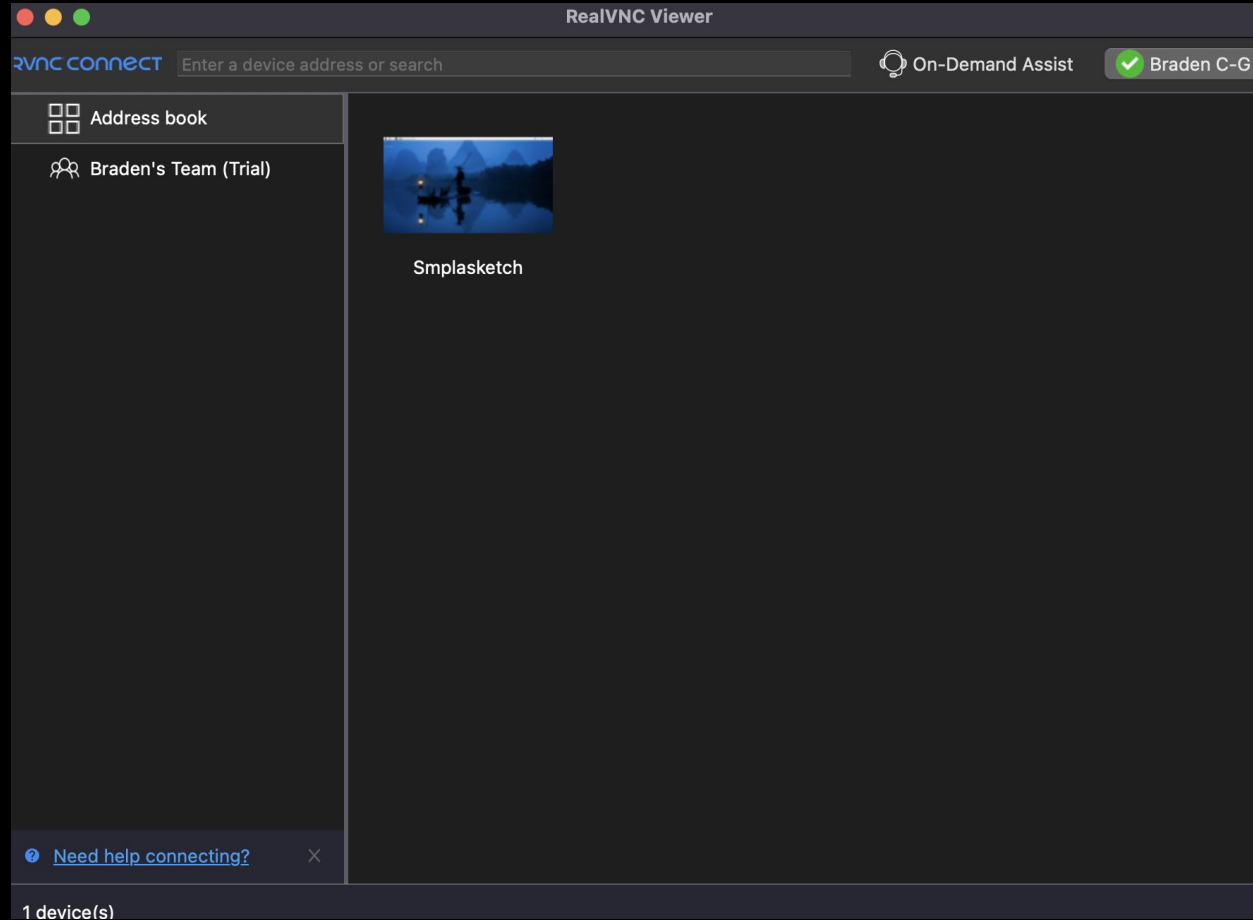
```
bradencantor-goldner — smplasketch@raspberrypi: ~ — ssh smplasketch@raspberrypi.local — 105x34
raspberrypi Pi Zero W Rev 1.1, 512MB

Raspberry Pi Software Configuration Tool (raspi-config)

1 System Options      Configure system settings
2 Display Options     Configure display settings
3 Interface Options   Configure connections to peripherals
4 Performance Options Configure performance settings
5 Localisation Options Configure language and regional settings
6 Advanced Options    Configure advanced settings
8 Update              Update this tool to the latest version
9 About raspi-config  Information about this configuration tool

<Select>              <Finish>
```

Raspberry Pi Headless Boot



Raspberry Pi Headless Boot

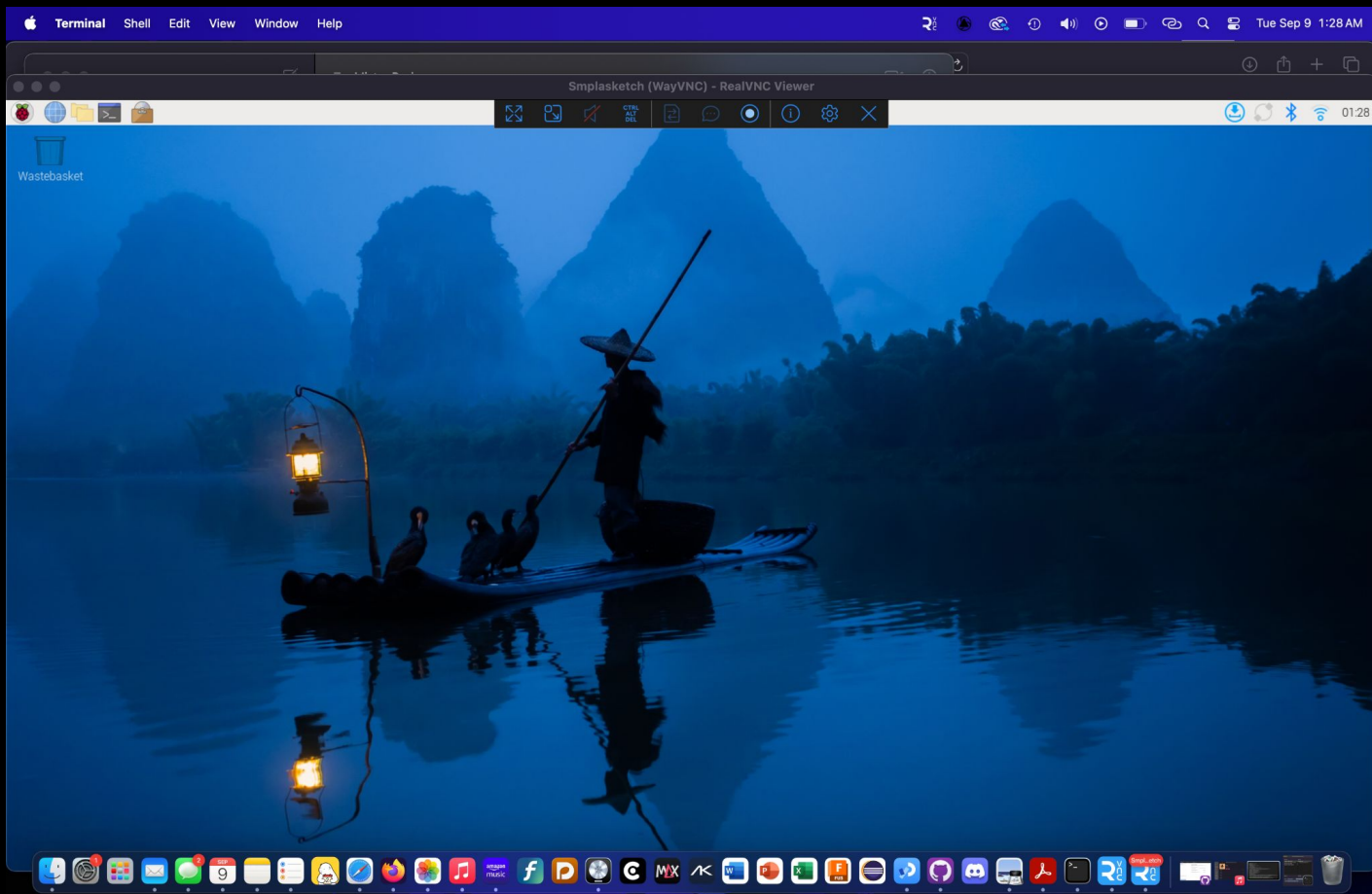


Image Processing Function

```
void processImage() {
    modImg.loadPixels(); //load display pixels
    img.loadPixels(); //load images pixels

    for (int x = 0; x < width; x++) {
        ArrayList<Integer> readRedPix = new ArrayList<Integer>(); // create list to hold y values for a single x point
        for (int y = 0; y < height; y++) {
            int loc = x + y*width; //calculate pixel location

            // Pull out the 3 color components from pixel
            float r = red(img.pixels[loc]);
            float g = green(img.pixels[loc]);
            float b = blue(img.pixels[loc]);

            // Change red pixels to green to show that it was read
            if (r > 200 && b < 250 && g < 250) {
                r=0;
                b=0;
                g=255;
                readRedPix.add(y); //add the y value to the list
            }

            // Change displayed pixel to represent coordinates counted
            modImg.pixels[loc] = color(r, g, b);
        }
        int avg = findAvgY(readRedPix);
        float avgFl = map(avg, 0, height, -1, 1);
        wav[x] = avg;
    }
    modImg.updatePixels();
}
```


Demo

