



Software Safety Requirements and Architecture Lane Assistance

Document Version: [Version]
Template Version 1.0, Released on 2017-06-21



Document history

Date	Version	Editor	Description
11/21/2018	1.0	Claris Li	Initial draft

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<u>Purpose</u>

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Purpose

Derive software safety requirements from technical software requirements to enable the system to maintain or reach a safe state.

Inputs to the Software Requirements and Architecture Document

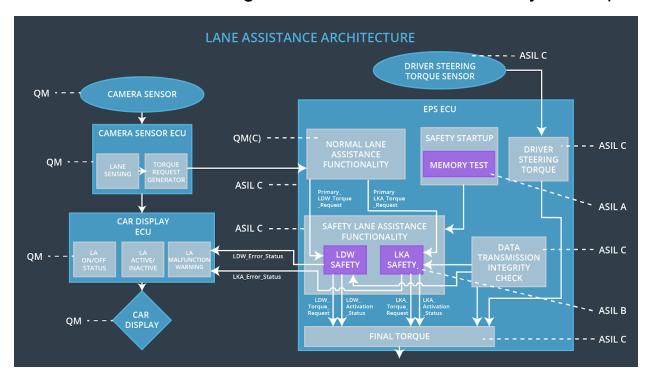
Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	С	50 ms	LDW Safety	LDW torque output is set to zero
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	С	50 ms	Data Transmission Integrity Check	N/A
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	С	50 ms	LDW Safety	LDW torque output is set to zero
Technical Safety	As soon as the LDW function deactivates the	С	50 ms	LDW Safety	LDW torque output is

Requirement 04	LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light				set to zero
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	С	Ignition Cycle	Memory Test	LDW torque output is set to zero

Refined Architecture Diagram from the Technical Safety Concept



Software Requirements

Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requireme nt 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	С	50 ms	LDW Safety	LDW torque output is set to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 01-01	The input signal "Primary_LDW_Torq_Req" shall be read and pre-processed to determine the torque request coming from the "Basic/Main LA Functionality" SW Component. Signal "processed_LDW_Torq_Re q" shall be generated at the end of the processing.	C	LDW_SAFETY_INPUT_ PROCESSING	N/A
Software Safety Requirement 01-02	In case the "processed_LDW_Torq_Re q" signal has a value greater than "Max_Torque_Amplitude_L DW" (maximum allowed safe torque), the torque signal "limited_LDW_Torq_Req"	С	TORQUE_LIMITER	"limited_LDW_ Torq_Req" = 0 (Nm=Newton- meter)

	shall be set to 0, else "limited_LDW_Torq_Req" shall take the value of "processed_LDW_Torq_Re q".			
Software Safety Requirement 01-03	The "limited_LDW_Torq_Req" shall be transformed into a signal "LDW_Torq_Req" which is suitable to be transmitted outside of the LDW Safety component ("LDW Safety") to the "Final EPS Torque"component. Also see SofSafReq02-01 and SofSafReq02-02	С	LDW_SAFETY_OUTP UT_GENERATOR	LDW_Torq_Re q= 0 (Nm)

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architectur e	Safe State
Technical Safety Requireme nt 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	С	50 ms	Data Transmissio n Integrity Check	N/A

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requireme nt 02-01	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see SofSafReq03-02) shall be protected by an End2End(E2E) protection mechanism	С	E2ECalc	LDW_Torq_R eq= 0 (Nm)
Software Safety Requireme nt 02-02	The E2E protection protocol shall contain and attach the control data: alive counter (SQC) and CRC to the data to be transmitted.	С	E2ECalc	LDW_Torq_R eq= 0 (Nm)

ID	Technical Safety Requirement	A S I L		Allocation to Architecture	Safe State
Technical Safety Requireme nt 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	С	50 ms	LDW Safety	LDW torque output is set to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 03-01	Each of the SW elements shall output a signal to indicate any error which is detected by the element. Error signal = error_status_input(LDW_S AFETY_INPUT_PROCESS ING), error_status_torque_limiter(TORQUE_LIMITER), error_status_output_gen(L DW_SAFETY_OUTPUT_G ENERATOR)	C	All	N/A
Software Safety Requirement 03-02	A software element shall evaluate the error status of all the other software elements and in case any 1 of them indicates an error, it shall deactivate the LDW feature ("activation_status"=0)	С	LDW_SAFET Y_ACTIVATI ON	Activation_status = 0 (LDW function deactivated)
Software Safety	In case of no errors from the software elements, the status of the LDW feature	С	LDW_SAFET Y_ACTIVATI ON	N/A

Requirement 03-03	shall be set to activated ("activation_status"=1)			
Software Safety Requirement 03-04	In case an error is detected by any of the software elements, it shall set the value of its corresponding torque to 0 so that "LDW_Torq_Req" is set to 0	С	All	LDW_Torq_Req = 0
Software Safety Requirement 03-05	Once the LDW functionality has been deactivated, it shall stay deactivated till the time the ignition is switched from off to on again.	С	LDW_SAFET Y_ACTIVATI ON	Activation_status = 0 (LDW function deactivated)

ID	Technical Safety Requirement	A S I L	Fault Toleran t Time Interval	Allocation to Architecture	Safe State
Technical Safety Requireme nt 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	С	50 ms	LDW Safety	LDW torque output is set to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requireme nt 04-01	When the LDW function is deactivated (activation_status set to 0), the activation_status shall be sent to the car display ECU.	С	LDW_SAFE TY_ACTIVA TION, CarDisplay ECU	N/A

ID	Technical Safety Requirement	A S I L	Fault Toleran t Time Interval	Allocation to Architecture	Safe State
Technical Safety Requireme nt 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	A	Ignition Cycle	Memory Test	LDW torque output is set to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requireme nt 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any corruption of content.	A	MEMORY TEST	Activation_status = 0
Software Safety Requireme nt 05-02	Standard RAM tests to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on (E.g.walking 1s test, RAM pattern test. Refer RAM and processor vendor recommendations)	A	MEMORY TEST	Activation_status = 0
Software Safety Requireme nt 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the "test_status" signal	A	MEMORY TEST	Activation_status = 0
Software Safety Requireme nt 05-04	In case any fault is indicated via the "test_status" signal the INPUT_LDW_PROCESSING shall set an error on	A	LDW_SAFE TY_INPUT_ PROCESSIN G	Activation_status = 0

ror_status_input (=1) so at the LDW functionality is		
eactivated and the DWTorque is set to 0		

Refined Architecture Diagram

