

Problem 3.2

Estimate from graph:

- Percent Overshoot: 56%
- Settling Time:
 - Textbook does not specify whether it is 2% or 5% settling time
 - 2%: 37 sec
 - 5%: 46 sec
- Rise Time: 4 sec

Problem 3.3

$$TF = \frac{Y(s)}{G(s)} = \frac{10}{s^3 + 3s^2 + 4s + 9}$$

Problem 3.8

$$U(s) = \frac{2}{s}$$

$$Y(s) = \frac{2}{s^2 + 3s + 2} \cdot \frac{2}{s} = \frac{2}{s} + \frac{2}{s+2} - \frac{4}{s+1}$$

$$y(t) = 2 + 2e^{-2t} - 4e^{-t}$$

Problem 3.12

Steady state value = 2

$$\tau = 5$$

$$G(s) = \frac{2}{5s + 1}$$

Problem 3.13

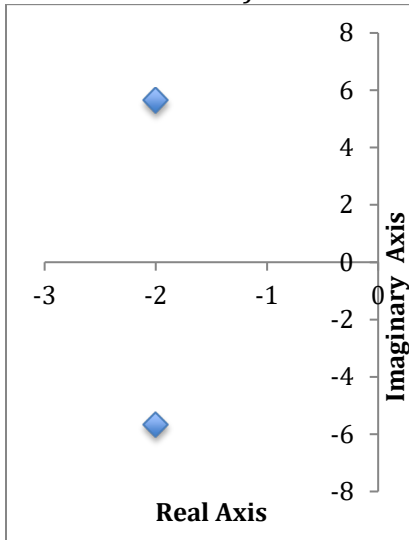
$$\omega_n \approx 6$$

$$\xi \approx 0.333$$

$$G(s) = \frac{36}{s^2 + 4s + 36}$$

Problem 3.14

$$\text{roots} = -2 \pm 4\sqrt{2}j$$



$$\text{zeta} = 0.3333$$

$$\text{natural frequency} = 6 \text{ rad/s}$$

Problem 3.18

$$\frac{Y(s)}{R(s)} = \frac{k1 + bs}{ms^2 + bs + (k1 + k2)}$$

Problem 3.22

From 2.29

$$\frac{dh_1}{dt} = \frac{Q_i - Q_b}{C_1}$$

$$\frac{dh_2}{dt} = \frac{Q_b - Q_o}{C_2}$$

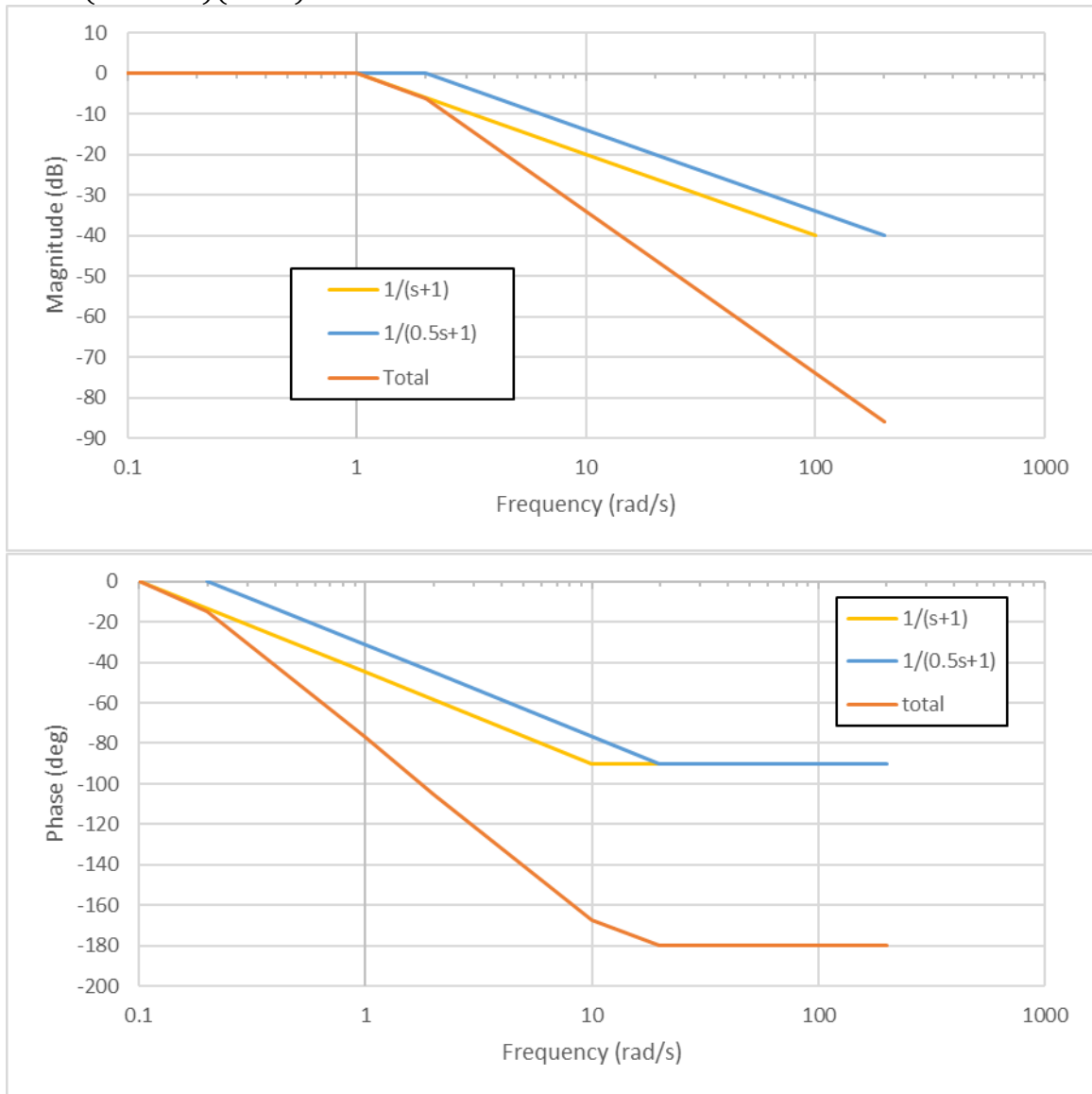
$$Q_b = \frac{h_1 - h_2}{R_1}$$

$$Q_o = \frac{h_2}{R_2}$$

$$\frac{H_2}{Q_i} = \frac{R_1}{\left[\frac{(R_1 R_2 C_2 s + R_2 + R_1)(R_1 C_1 s + 1)}{R_2} \right] - 1} \rightarrow \frac{R_2}{s^2 (R_1 R_2 C_1 C_2) + s (R_2 C_2 + R_1 C_1 + R_2 C_1) + 1}$$

Problem 3.25

$$TF = \frac{1}{(0.5s + 1)(s + 1)}$$



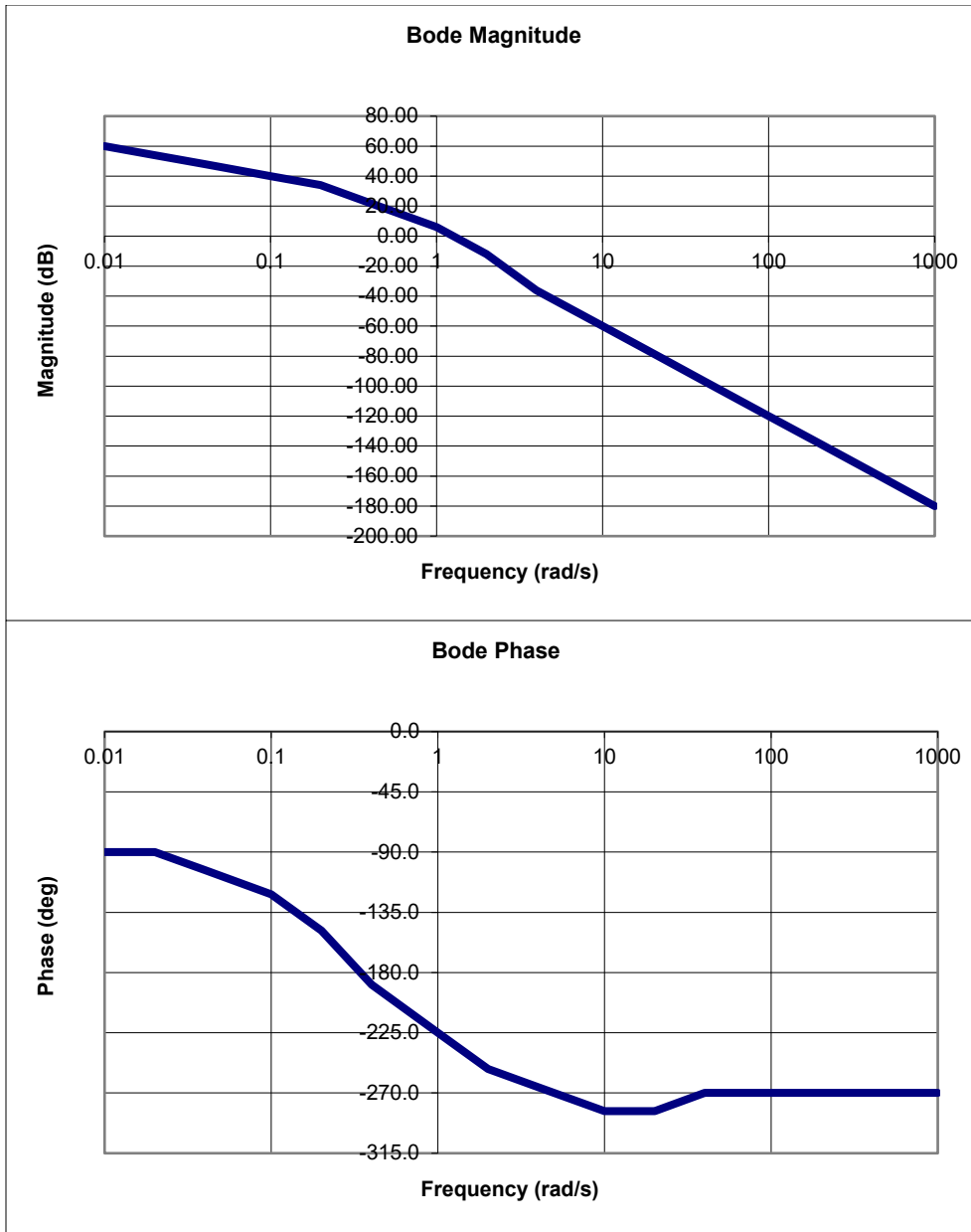
Problem 3.27

The plot is easiest using Excel, but it can be done by hand by creating a table.

$$G(s) = \frac{5(s+4)}{s(s+1)(s+2)(5s+1)} = \frac{10(0.25s+1)}{s(s+1)(0.5s+1)(5s+1)}$$

| Magnitude (dB) | | tau = 4 | tau = 1 | tau = 1 | tau = 2 | tau = 0.2 | |
|----------------|-------|---------|---------|---------|------------|-----------|---------|
| w (rad/s) | 10 | 0.25s+1 | 1/s | 1/(s+1) | 1/(0.5s+1) | 1/(5s+1) | total |
| 0.01 | 20.00 | 0.00 | 40.00 | 0.00 | 0.00 | 0.00 | 60.00 |
| 0.02 | 20.00 | 0.00 | 33.98 | 0.00 | 0.00 | 0.00 | 53.98 |
| 0.04 | 20.00 | 0.00 | 27.96 | 0.00 | 0.00 | 0.00 | 47.96 |
| 0.1 | 20.00 | 0.00 | 20.00 | 0.00 | 0.00 | 0.00 | 40.00 |
| 0.2 | 20.00 | 0.00 | 13.98 | 0.00 | 0.00 | 0.00 | 33.98 |
| 0.4 | 20.00 | 0.00 | 7.96 | 0.00 | 0.00 | -6.02 | 21.94 |
| 1 | 20.00 | 0.00 | 0.00 | 0.00 | 0.00 | -13.98 | 6.02 |
| 2 | 20.00 | 0.00 | -6.02 | -6.02 | 0.00 | -20.00 | -12.04 |
| 4 | 20.00 | 0.00 | -12.04 | -12.04 | -6.02 | -26.02 | -36.12 |
| 10 | 20.00 | 7.96 | -20.00 | -20.00 | -13.98 | -33.98 | -60.00 |
| 20 | 20.00 | 13.98 | -26.02 | -26.02 | -20.00 | -40.00 | -78.06 |
| 40 | 20.00 | 20.00 | -32.04 | -32.04 | -26.02 | -46.02 | -96.12 |
| 100 | 20.00 | 27.96 | -40.00 | -40.00 | -33.98 | -53.98 | -120.00 |
| 200 | 20.00 | 33.98 | -46.02 | -46.02 | -40.00 | -60.00 | -138.06 |
| 400 | 20.00 | 40.00 | -52.04 | -52.04 | -46.02 | -66.02 | -156.12 |
| 1000 | 20.00 | 47.96 | -60.00 | -60.00 | -53.98 | -73.98 | -180.00 |

| Phase (deg) | | tau = 4 | tau = 1 | tau = 1 | tau = 2 | tau = 0.2 | |
|-------------|----|---------|---------|---------|------------|-----------|--------|
| w (rad/s) | 10 | 0.25s+1 | 1/s | 1/(s+1) | 1/(0.5s+1) | 1/(5s+1) | total |
| 0.01 | 0 | 0.00 | -90.00 | 0.00 | 0.00 | 0.00 | -90.0 |
| 0.02 | 0 | 0.00 | -90.00 | 0.00 | 0.00 | 0.00 | -90.0 |
| 0.04 | 0 | 0.00 | -90.00 | 0.00 | 0.00 | -13.55 | -103.5 |
| 0.1 | 0 | 0.00 | -90.00 | 0.00 | 0.00 | -31.45 | -121.5 |
| 0.2 | 0 | 0.00 | -90.00 | -13.55 | 0.00 | -45.00 | -148.5 |
| 0.4 | 0 | 0.00 | -90.00 | -27.09 | -13.55 | -58.55 | -189.2 |
| 1 | 0 | 17.91 | -90.00 | -45.00 | -31.45 | -76.45 | -225.0 |
| 2 | 0 | 31.45 | -90.00 | -58.55 | -45.00 | -90.00 | -252.1 |
| 4 | 0 | 45.00 | -90.00 | -72.09 | -58.55 | -90.00 | -265.6 |
| 10 | 0 | 62.91 | -90.00 | -90.00 | -76.45 | -90.00 | -283.5 |
| 20 | 0 | 76.45 | -90.00 | -90.00 | -90.00 | -90.00 | -283.5 |
| 40 | 0 | 90.00 | -90.00 | -90.00 | -90.00 | -90.00 | -270.0 |
| 100 | 0 | 90.00 | -90.00 | -90.00 | -90.00 | -90.00 | -270.0 |
| 200 | 0 | 90.00 | -90.00 | -90.00 | -90.00 | -90.00 | -270.0 |
| 400 | 0 | 90.00 | -90.00 | -90.00 | -90.00 | -90.00 | -270.0 |
| 1000 | 0 | 90.00 | -90.00 | -90.00 | -90.00 | -90.00 | -270.0 |



A: Gain margin = -20 dB

B: Phase margin = -55°

C: Bandwidth = 1.3 rad/s

D: Steady state gain = infinite (because there is an integrator and the loop isn't closed)