```c
1   /* File Name: cars3.c
2    *
3    * This has two Linkbot I cars drive at the same time
    where one is
4    * going forward 360^0 the the other is going 220^0.
5    */
6
7   #include <linkbot.h>
8
9   int main() {
10      CLinkbotI car1, car2;
11
12      car1.moveNB(360, NaN, -360);
13      car2.moveNB(220, NaN, -220);
14
15      car1.moveWait();
16      car2.moveWait();
17
18      return 0;
19  }
20
```