

3. Path Tracing

Physically Based Rendering

Shinyoung Yi (이신영)

Whiteboard to review

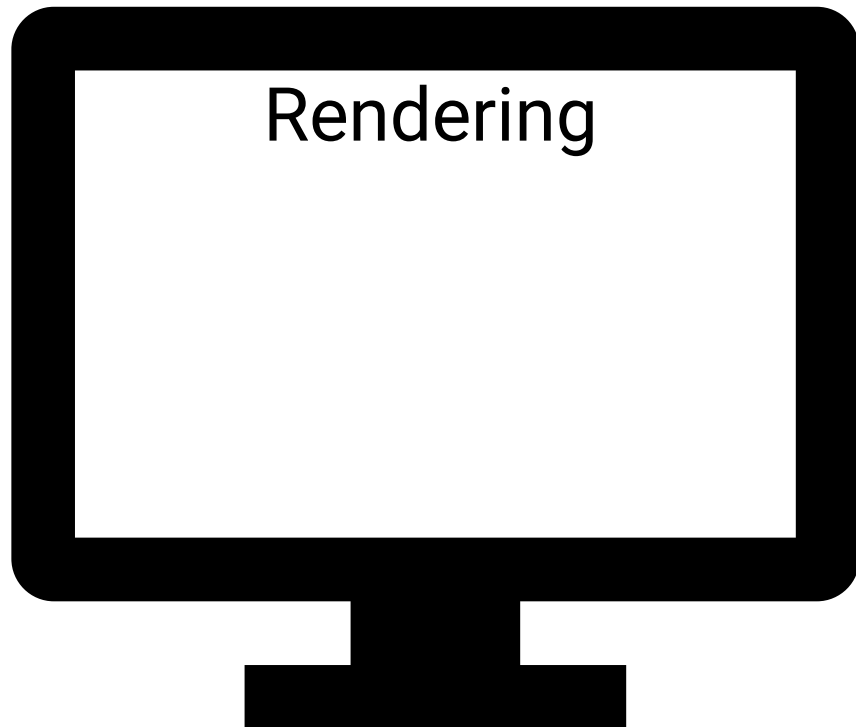
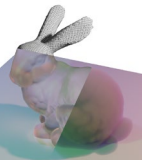


Natural phenomena
(physical law)

Radiometry:

Rendering equation

$$L(p, \hat{\omega}) = L_e(p, \hat{\omega}) + \int_{\mathbb{S}^2} L(r(p, \hat{\omega}'), -\hat{\omega}') \rho(p, \hat{\omega}', \hat{\omega}) d\hat{\omega}'$$



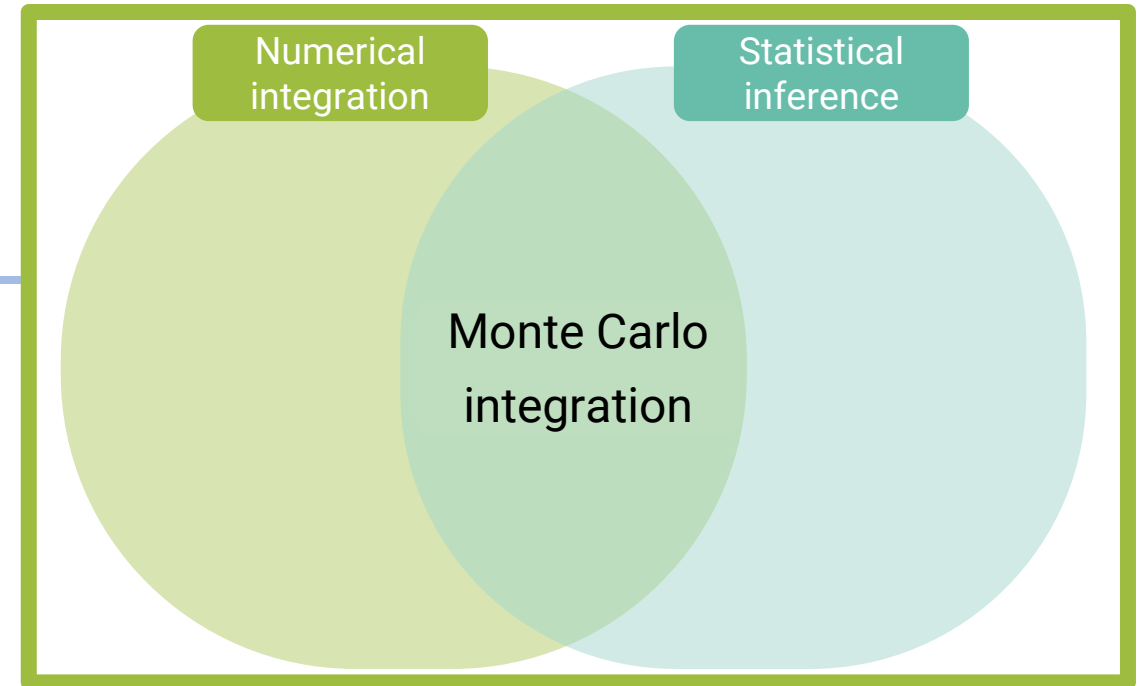
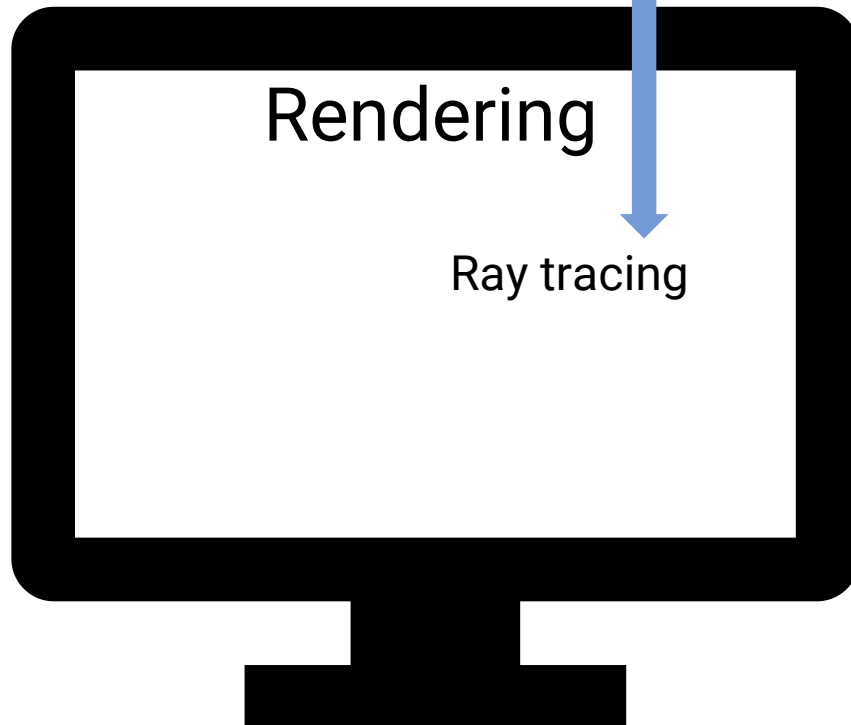


Natural phenomena
(physical law)

Radiometry:

Rendering equation

$$L(p, \hat{\omega}) = L_e(p, \hat{\omega}) + \int_{\mathbb{S}^2} L(r(p, \hat{\omega}'), -\hat{\omega}') \rho(p, \hat{\omega}', \hat{\omega}) d\hat{\omega}'$$



Radiometry



Implementation

Ver 0.1: Normal integrator

Radiometry

Impl.



Ver 0.2: + inheriting `mi.Integrator``

Impl.

Ver 0.3: Direct illumination
using BSDF sampling

Radiometry

Monte
Carlo

Ver 0.4: Direct illumination
using Emitter sampling

Monte
Carlo

Ver 0.5: Multiple importance sampling

Monte
Carlo

Ver 0.6: + Dirac delta

Monte
Carlo

Ver 0.7: Path tracing with fixed depth

Radiometry

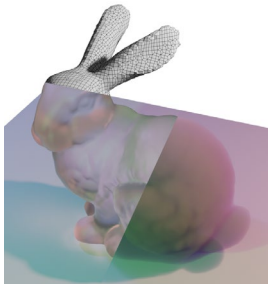
Ver 0.8: + Dr.Jit megakernel:
``active`` masks and ``mi.Loop``

Impl.

Ver 1.0: + Russian roulette

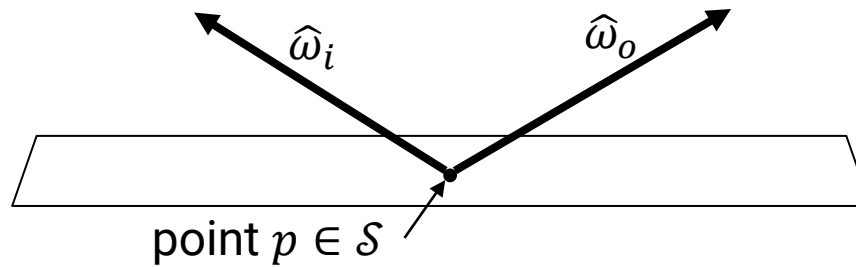
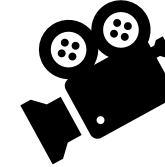
Radiometry

Monte
Carlo



Review: rendering equation

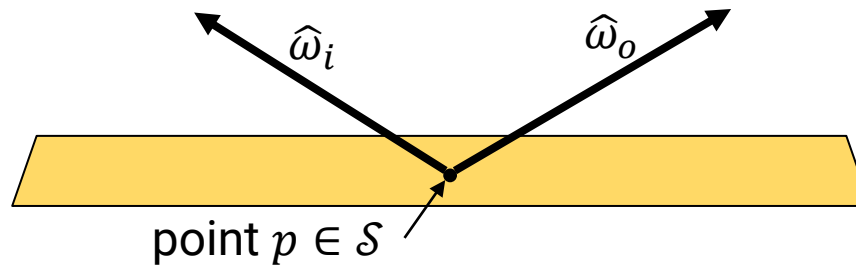
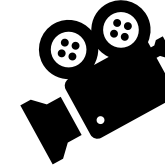
Rendering equation



From definition of BRDFs...

$$L^{(\text{out})}(p, \hat{\omega}_o) = \int_{\mathbb{S}^2} L^{(\text{in})}(p, \hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation



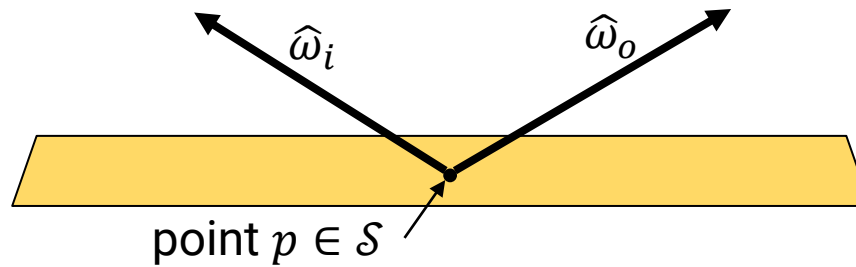
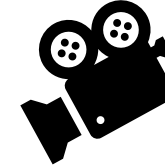
From definition of BRDFs...

+ Emission

Rendering equation
(light transport equation)

$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \omega_{\hat{o}}) + \int_{\mathbb{S}^2} L^{(\text{in})}(p, \hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation

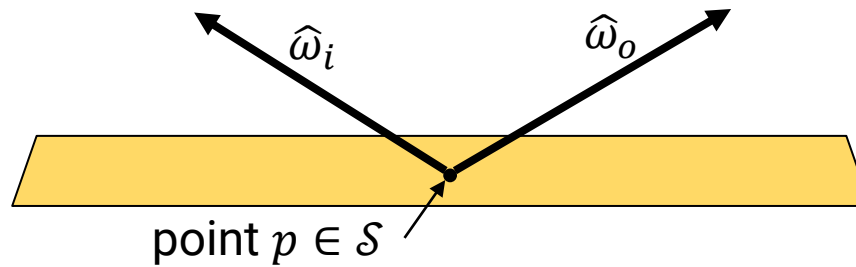
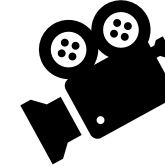


Q. What are knowns and unknowns?

Rendering equation
(light transport equation)

$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \hat{\omega}_o) + \int_{\mathbb{S}^2} L^{(\text{in})}(p, \hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation



Q. What are knowns and unknowns?

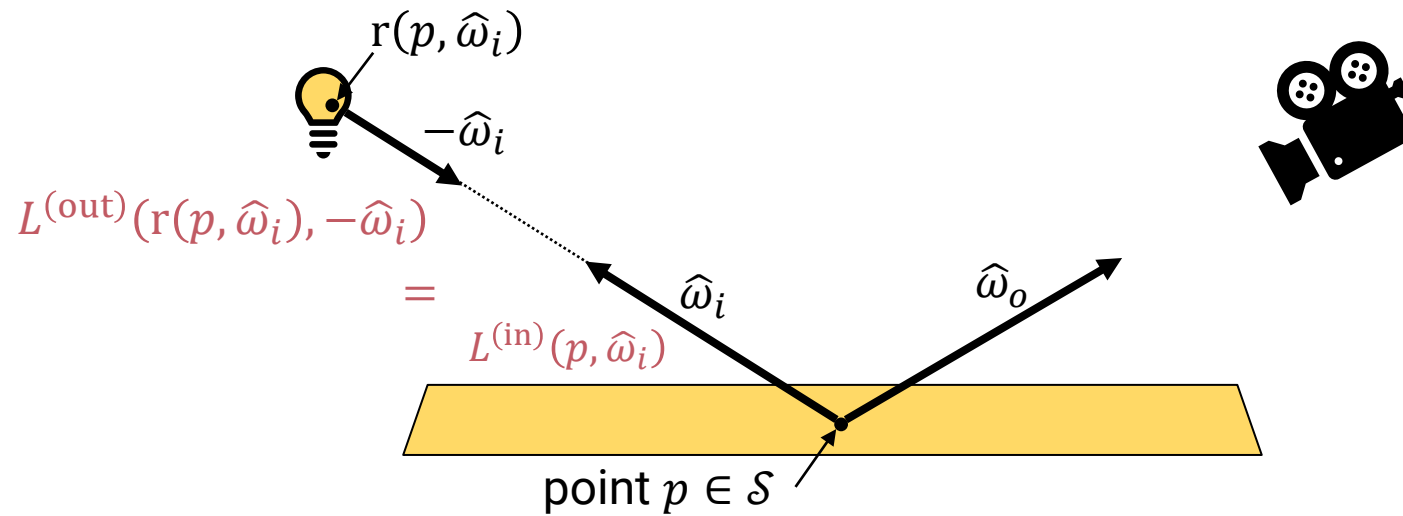
Rendering equation
(light transport equation)

$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \hat{\omega}_o) + \int_{\mathbb{S}^2} L^{(\text{in})}(p, \hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

known

unknown

Rendering equation

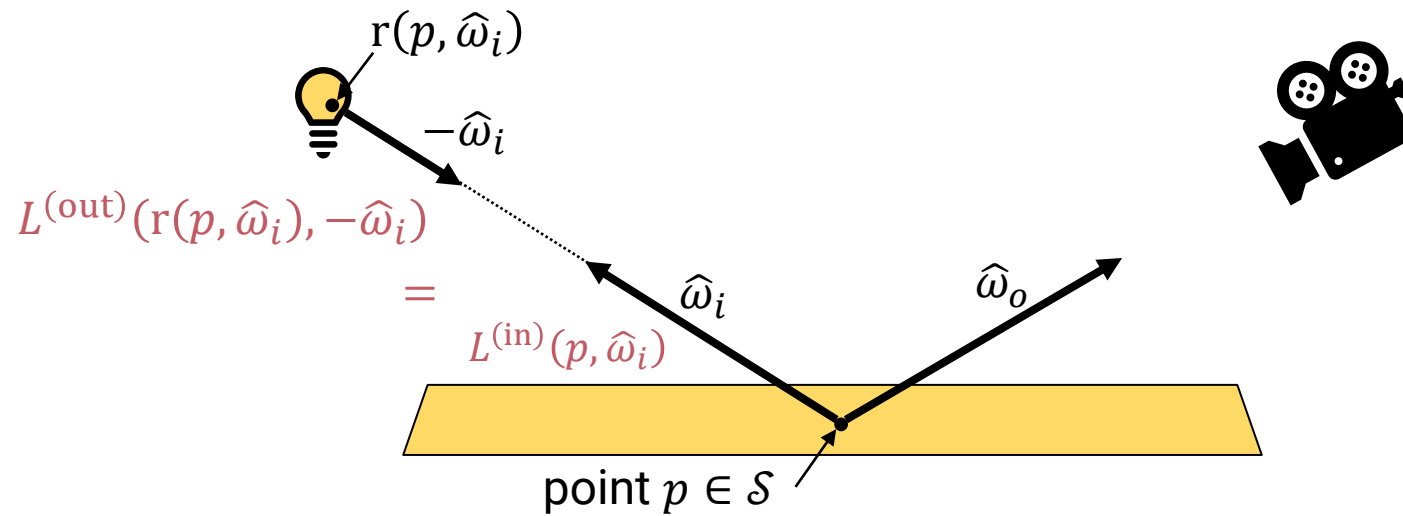


Q. Any relationship between $L^{(out)}$ and $L^{(in)}$?

Rendering equation
(light transport equation)

$$L^{(out)}(p, \hat{\omega}_o) = L_e(p, \omega_{\hat{o}}) + \int_{\mathbb{S}^2} L^{(in)}(p, \hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation

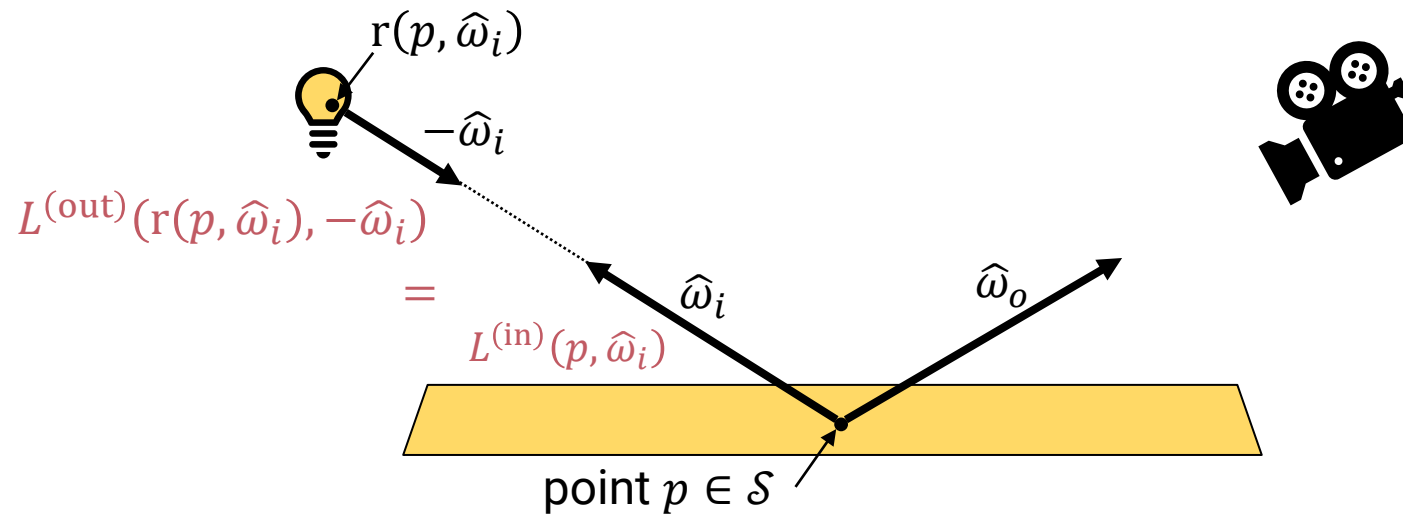


Q. Any relationship between $L^{(out)}$ and $L^{(in)}$?

Rendering equation
(light transport equation)

$$L^{(out)}(p, \hat{\omega}_o) = L_e(p, \hat{\omega}_o) + \int_{\mathbb{S}^2} L^{(out)}(r(p, \hat{\omega}_i), -\hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation

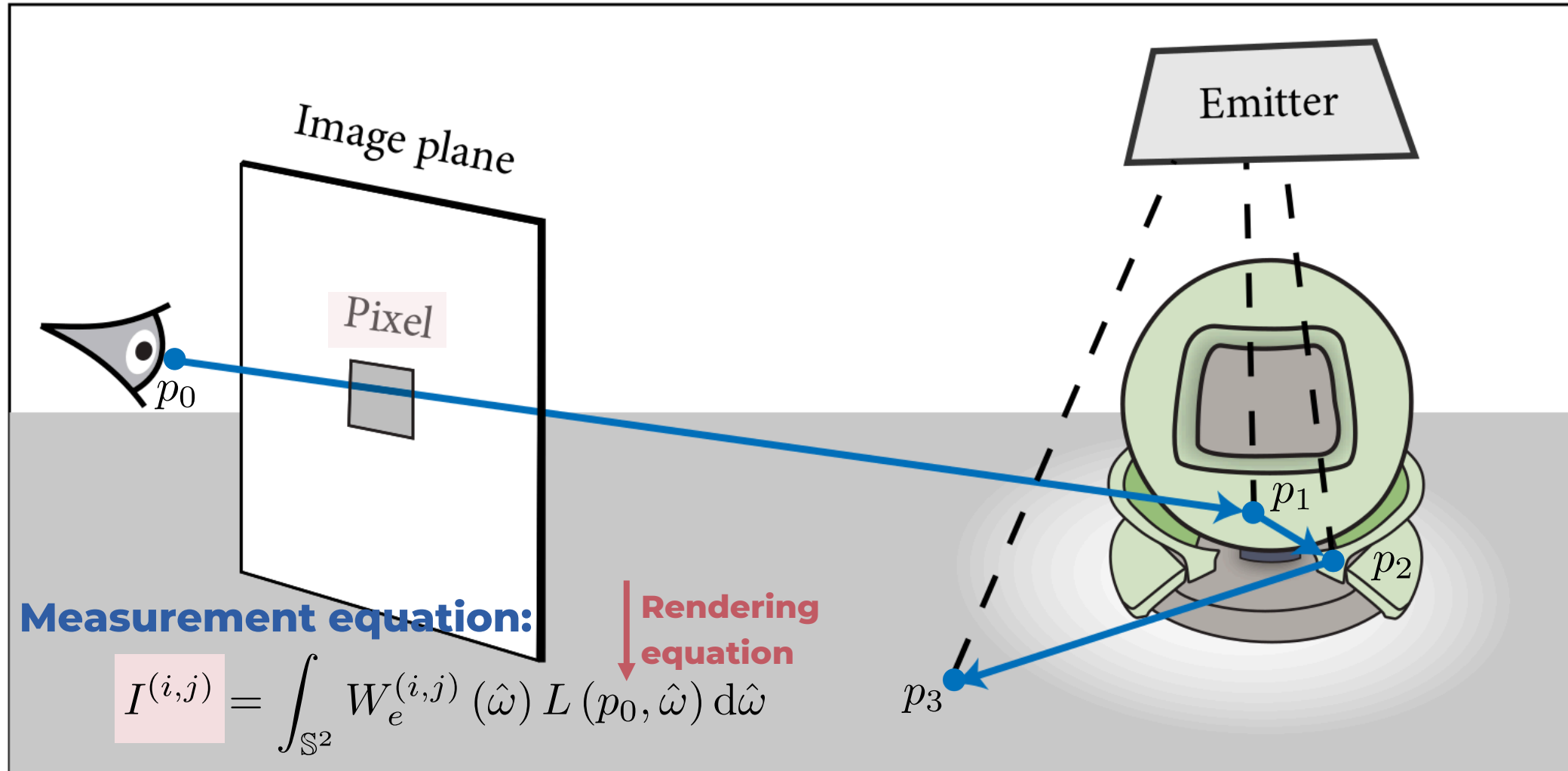


Q. Any relationship between $L^{(out)}$ and $L^{(in)}$?

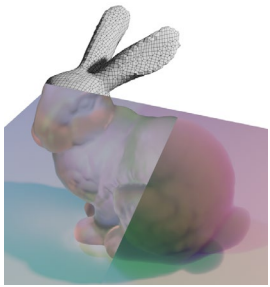
Rendering equation
(light transport equation)

$$L^{(out)}(p, \hat{\omega}_o) = L_e(p, \hat{\omega}_o) + \int_{\mathbb{S}^2} L^{(out)}(r(p, \hat{\omega}_i), -\hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation



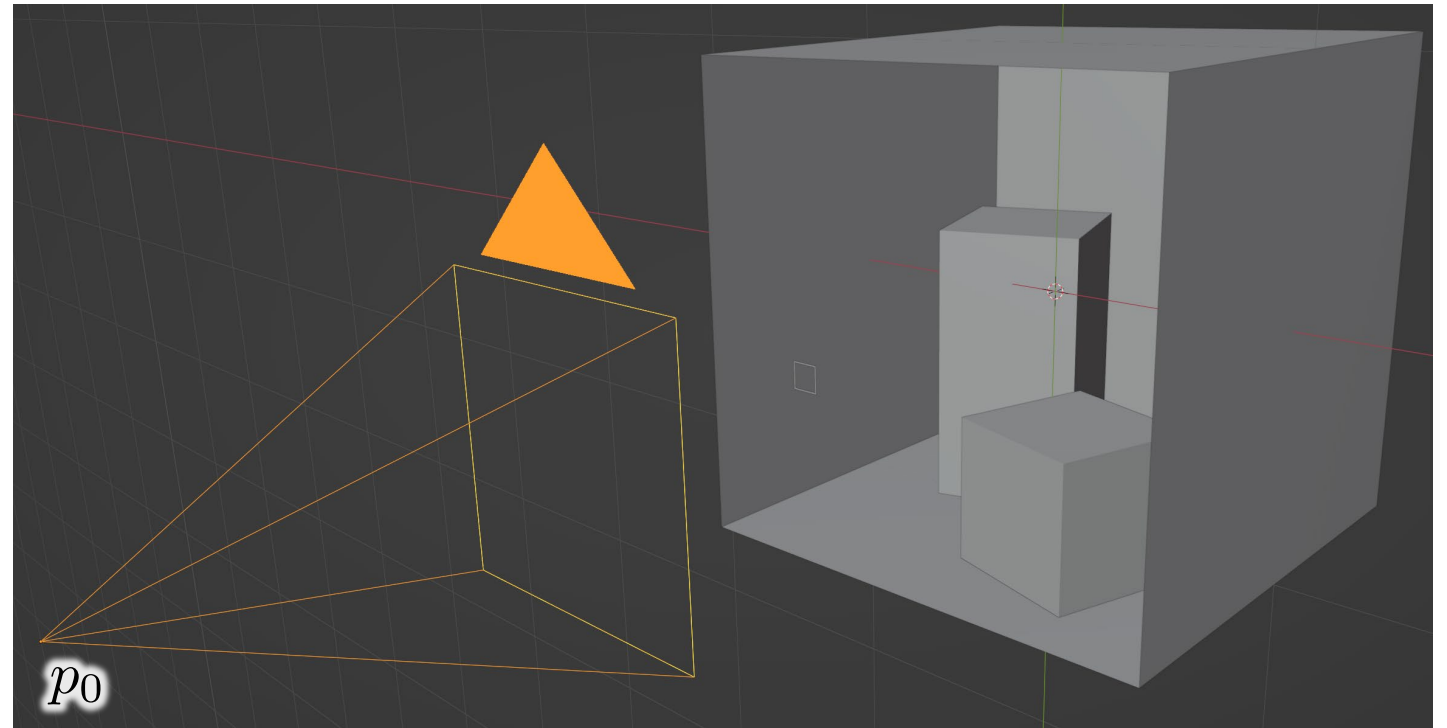
[https://mitsuba.readthedocs.io/en/latest/_images/integrator_path_figure.png]



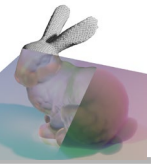
Path Tracing



``scene: mi.Scene``

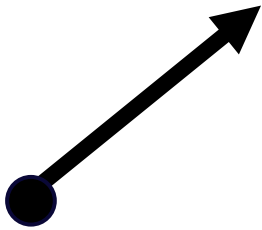


``sensor: mi.Sensor``

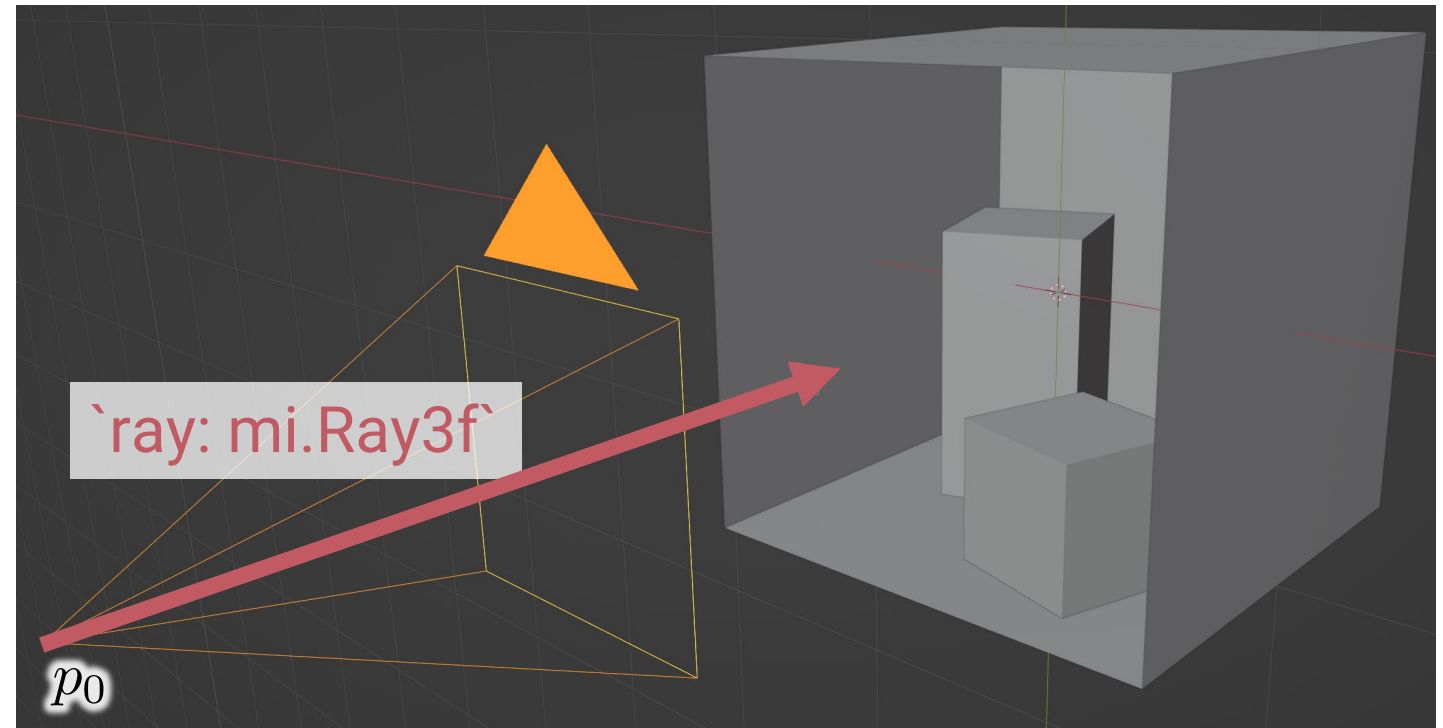


1. `ray = sensor.sample_ray()`

class: `mi.Ray3f`
ray.o: `Point3f`
ray.d: `Vector3f`



``scene: mi.Scene``



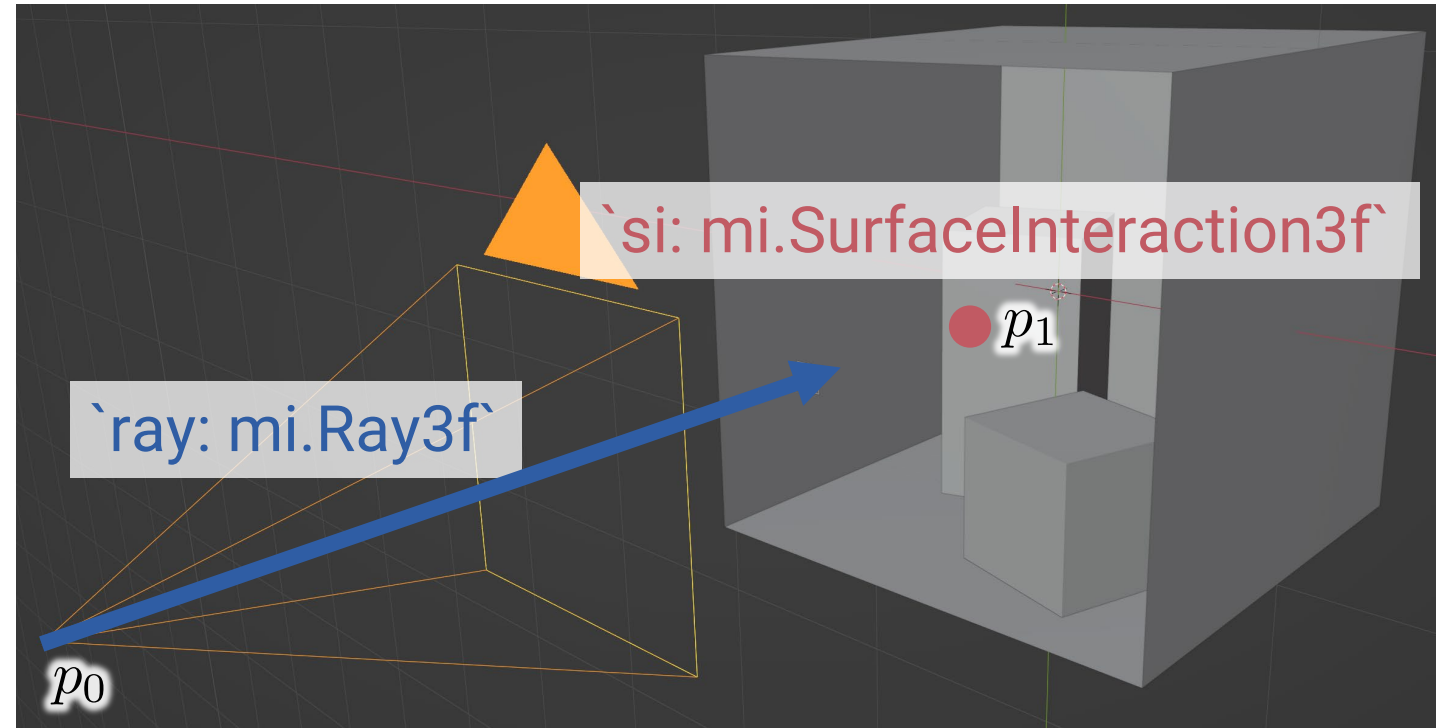
``sensor: mi.Sensor``



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`

class: `mi.SurfaceInteraction3f`
 `si.p: Point3f`
 `si.wi: -ray.d in local coordinates`

``scene: mi.Scene``

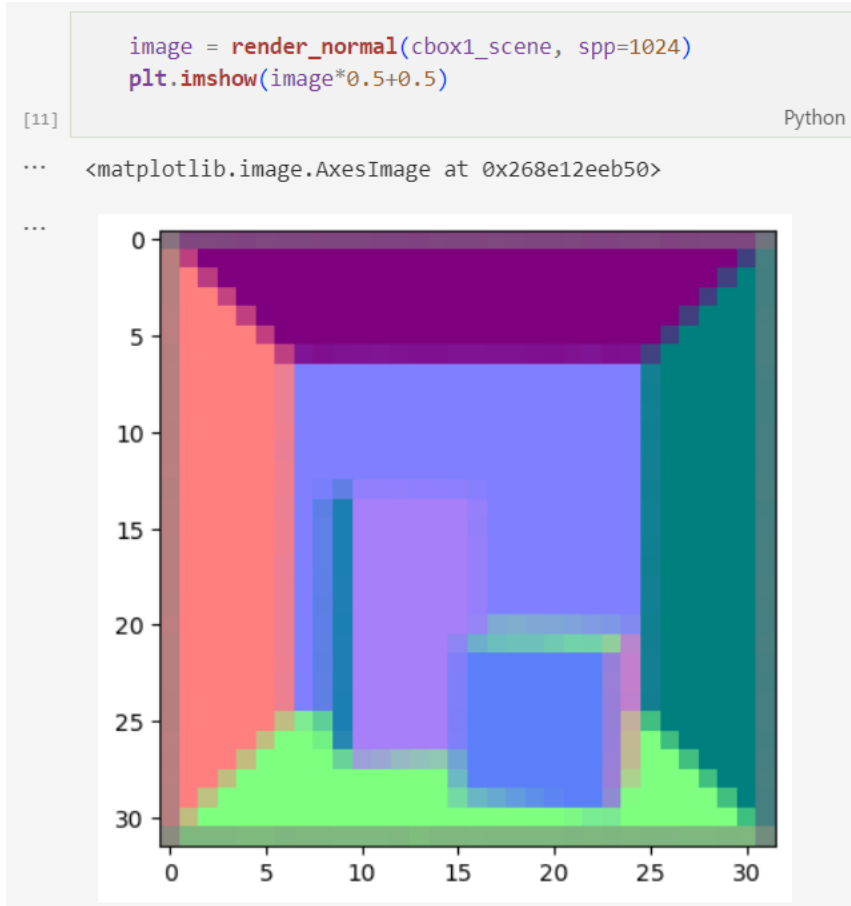


``sensor: mi.Sensor``

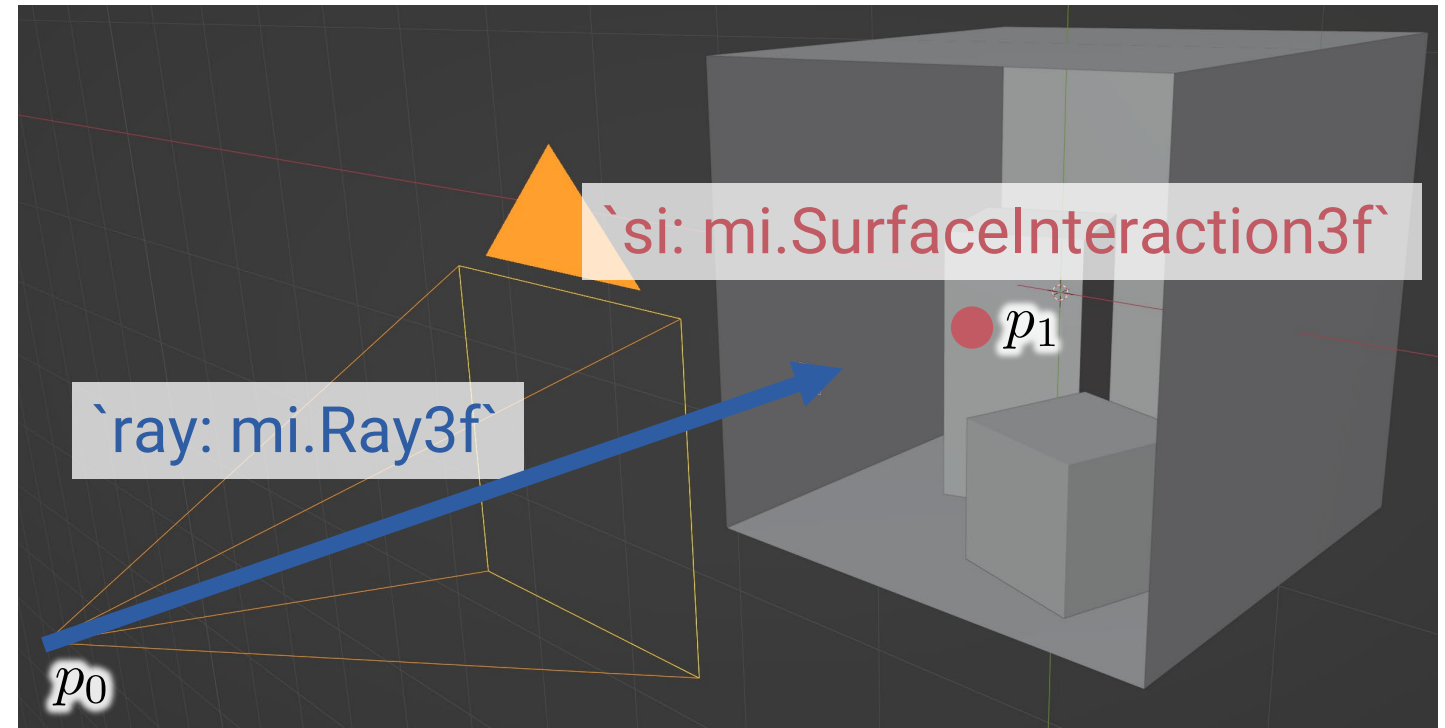


Task: *Check we obtained correct ``ray`` and ``si`` by visualizing normal vectors at ``si``*

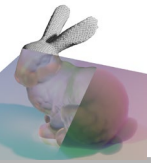
1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`



``scene: mi.Scene``



``sensor: mi.Sensor``



Task: Rewrite your code as a subclass of `mi.Integrator``

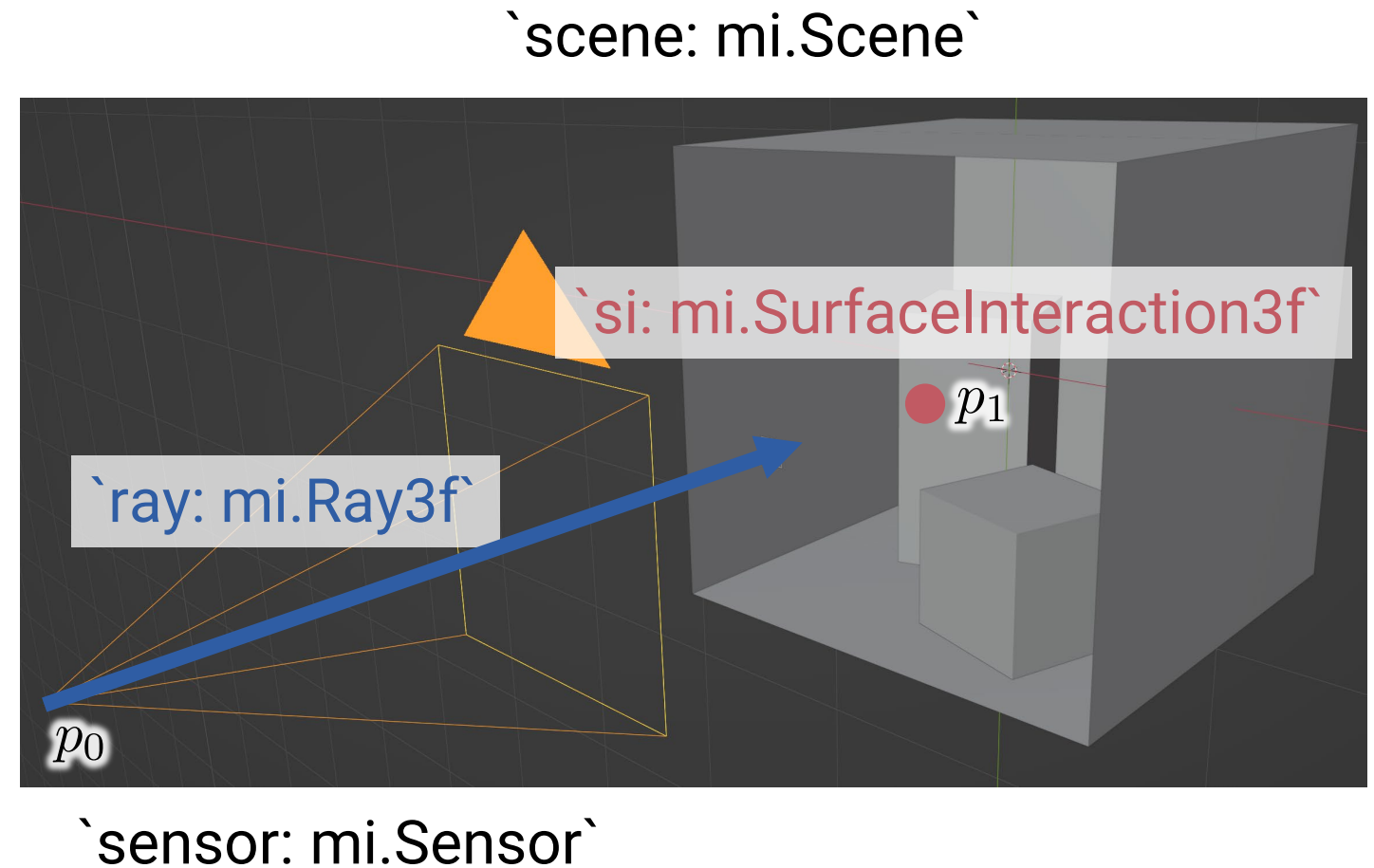
```
class: mi.Integrator
```

Just use the existing method

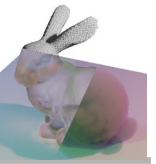
```
def render(scene):  
    generate `ray`  
     $\hat{L} \leftarrow \text{self.sample}(\text{scene}, \text{ray})$   
    Estimate measurement equation  
     $\hat{I} \leftarrow \frac{w_e(W)}{p_{\text{Sensor}}(W)} \hat{L}$ 
```

Override to estimate $L(p_1, \hat{w})$ from Ver. 0.3

```
def sample(scene, ray):  
    given `ray`  
    find  $\hat{L}(\text{si. p}, -\text{ray. d})$ 
```



HW Ver. 0.3: BSDF sampling



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`

```
class: mi.BSDF
```

```
# Methods
```

```
def eval(si, w):
```

$$f_s^\perp = f_s(w, si.wi) \cos \theta_i$$

```
def sample(..., si):
```

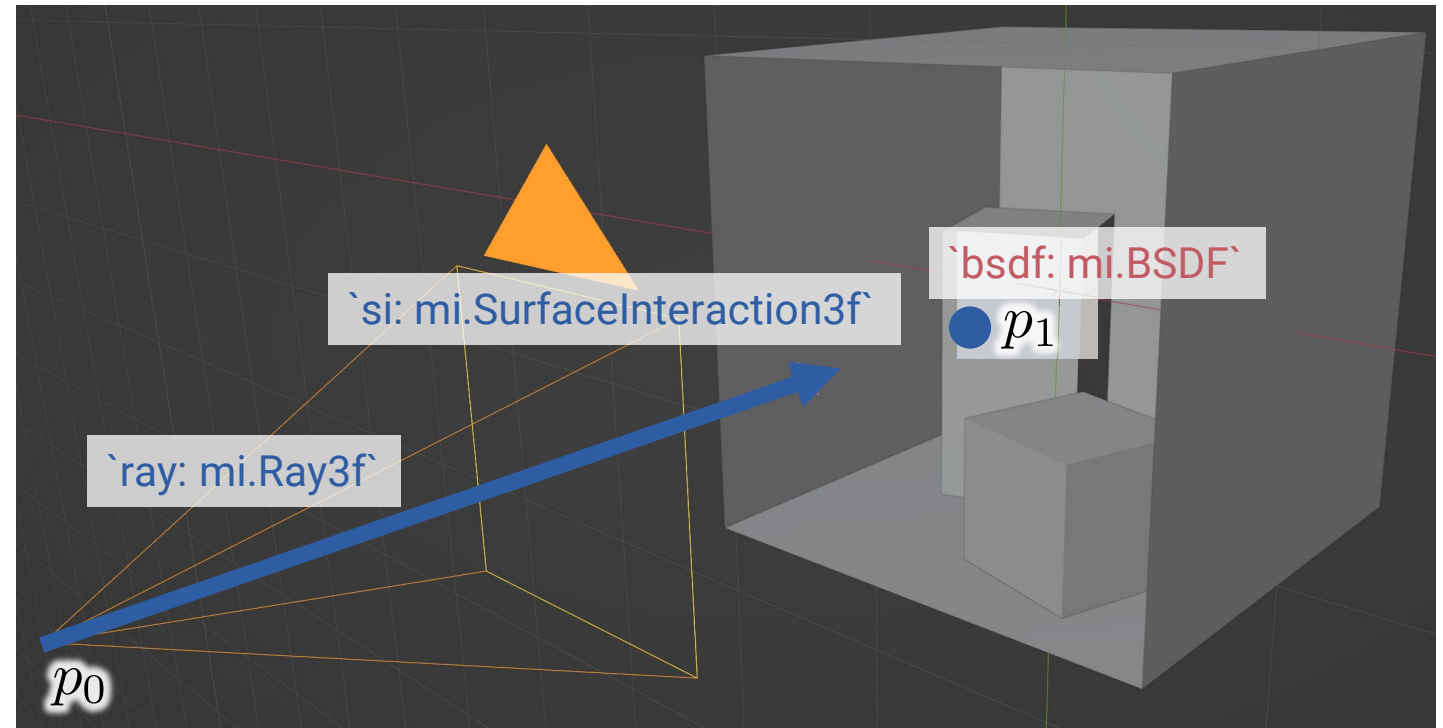
generate a random direction w ,

with a PDF

$$\text{hopefully} \propto f_s(w, si.wi) \cos \theta$$

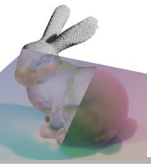
```
def pdf():
```

get PDF for the above method



HW Ver. 0.3: BSDF sampling

Radiometry



Mitsuba 3 implementation convention

Impl.

```
2. si = scene.ray_intersect(ray)
```

```
3. bsdf = si.bsdf()
```

```
ctx = mi.BSDFContext() # Configuration of finite options. Just use default one now
```

```
u_1d = sampler.next_1d() # np.random.rand(1), not used now
```

```
u_2d = sampler.next_2d() # np.random.rand(2)
```

```
bsdf_sample, bsdf_weight = bsdf.sample(ctx, si, u_1d, u_2d)
```

```
# Methods
```

```
def eval(si, w):
```

```
     $f_s^\perp = f_s(w, si.wi)$ 
```

```
def sample(..., si):
```

```
    generate a random
```

```
    with a PDF
```

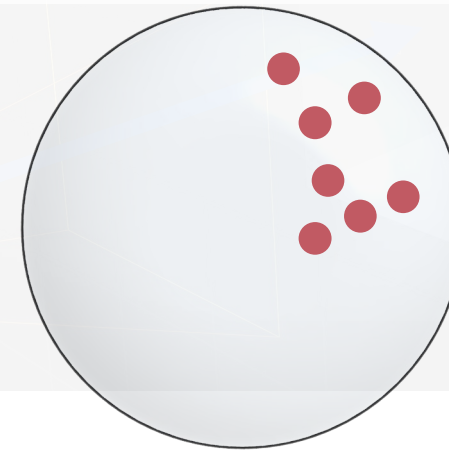
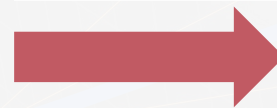
```
    hopefully  $\propto f_s(w)$ 
```

```
def pdf():
```

```
    get PDF for the above method
```



`u_2d = sampler.next_2d()`

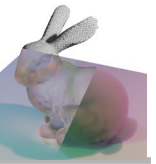


`bsdf.sample(ctx, si, u_1d, u_2d)`

HW Ver. 0.3: BSDF sampling

Radiometry

Monte Carlo



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`

class: `mi.BSDF`

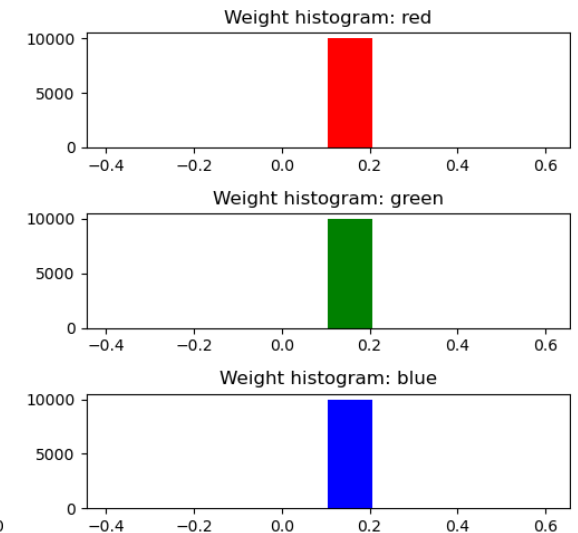
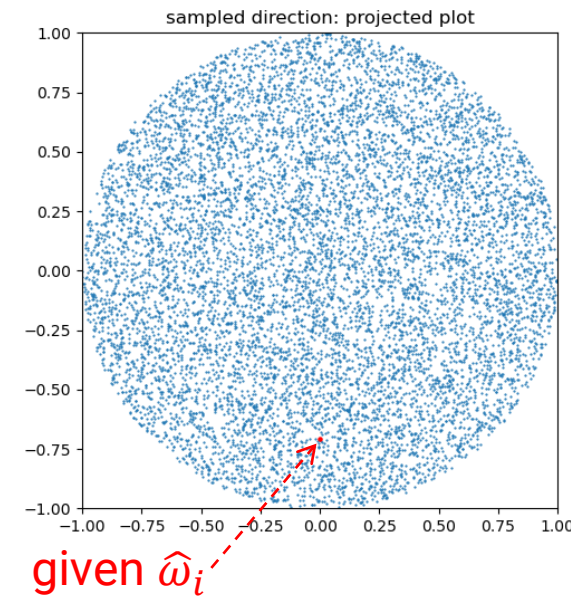
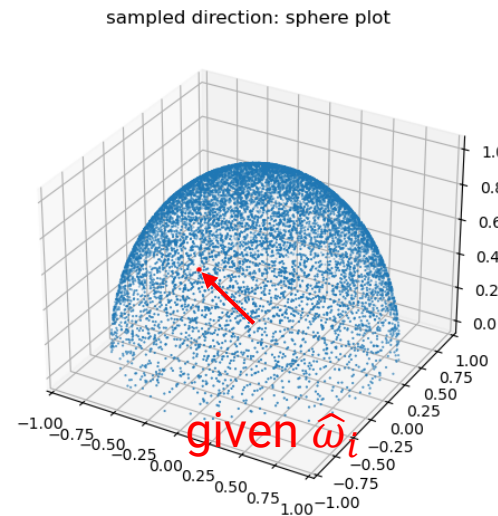
Methods

`def eval():`

`def sample():`

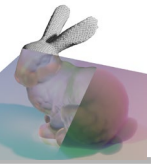
`def pdf():`

Diffuse BSDF



HW Ver. 0.3: BSDF sampling

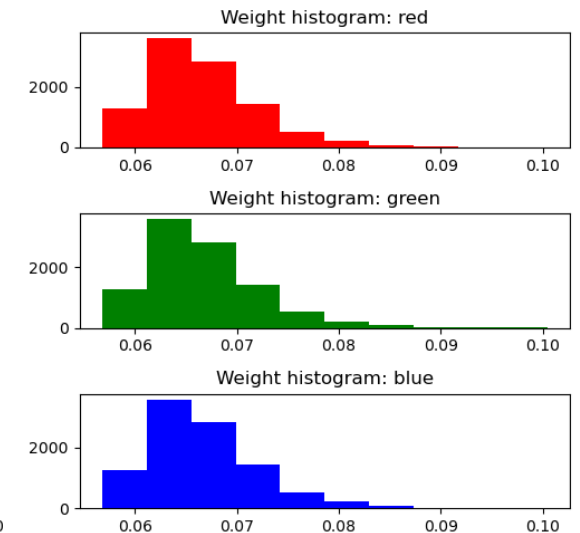
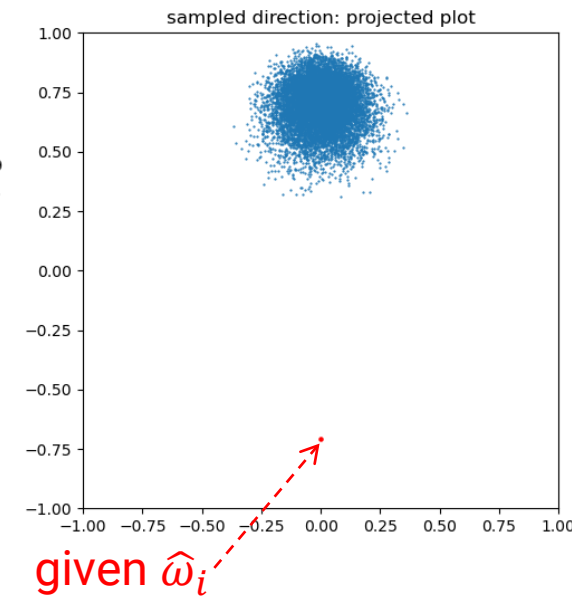
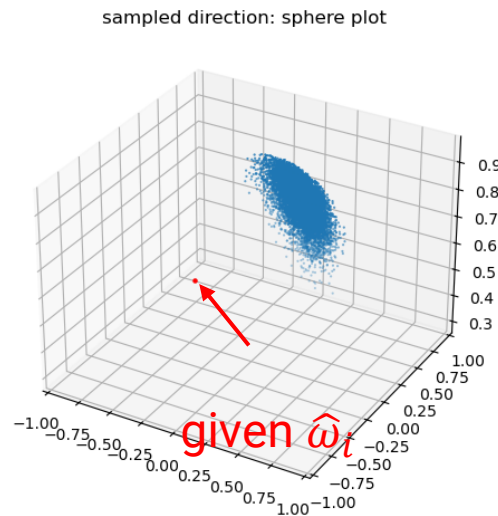
Radiometry



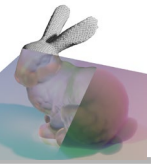
1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`

```
class: mi.BSDF
# Methods
def eval():
def sample():
def pdf():
```

Rough plastic BSDF



HW Ver. 0.3: BSDF sampling



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`
4. `bsdf_sample, bsdf_weight`
 `= bsdf.sample(..., si, ...)`

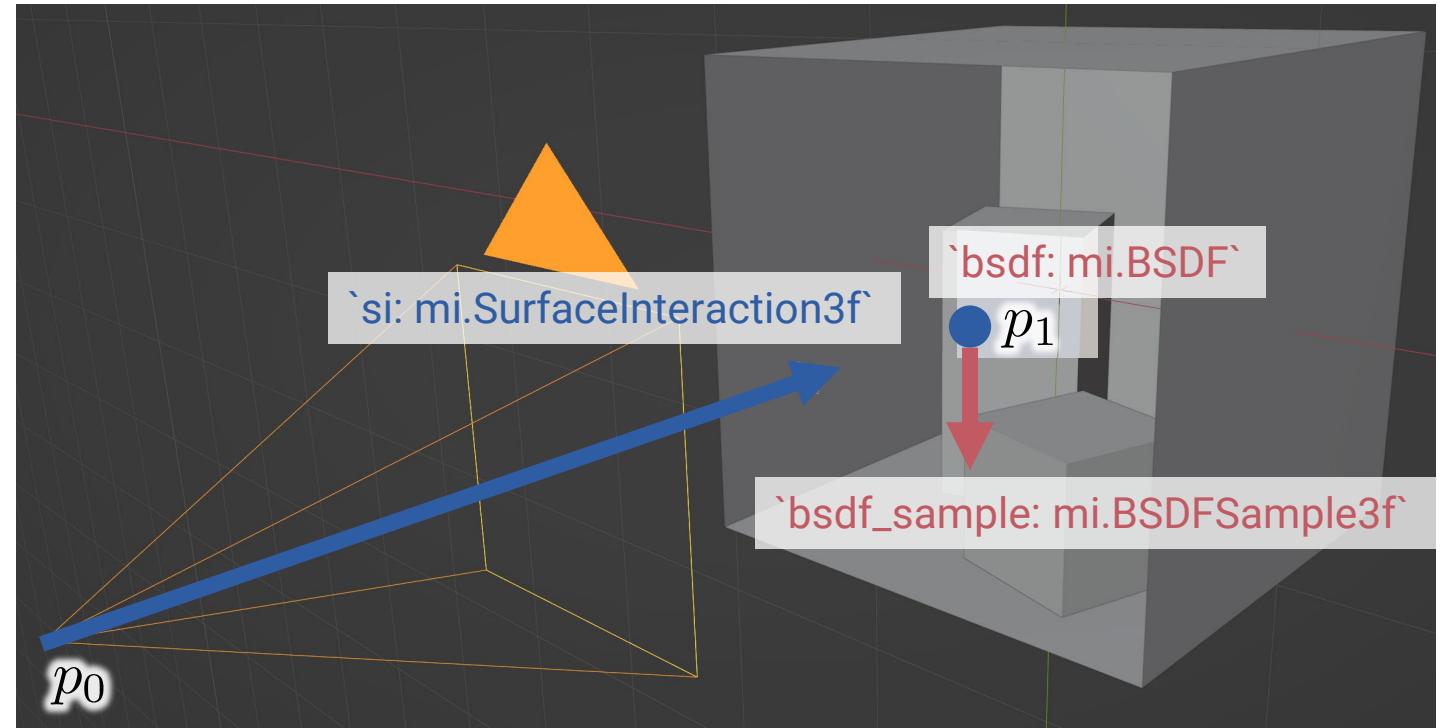
`bsdf_weight: mi.Spectrum`

$$= \frac{f_s(\text{bsdf_sample}, \text{si}) \cos \theta_i}{p(\text{bsdf_sample})}$$

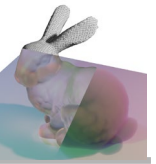
`class: mi.BSDFSample3f`

`wo`: sampled direction, in local coordinates

`pdf`: PDF value at ``wo``



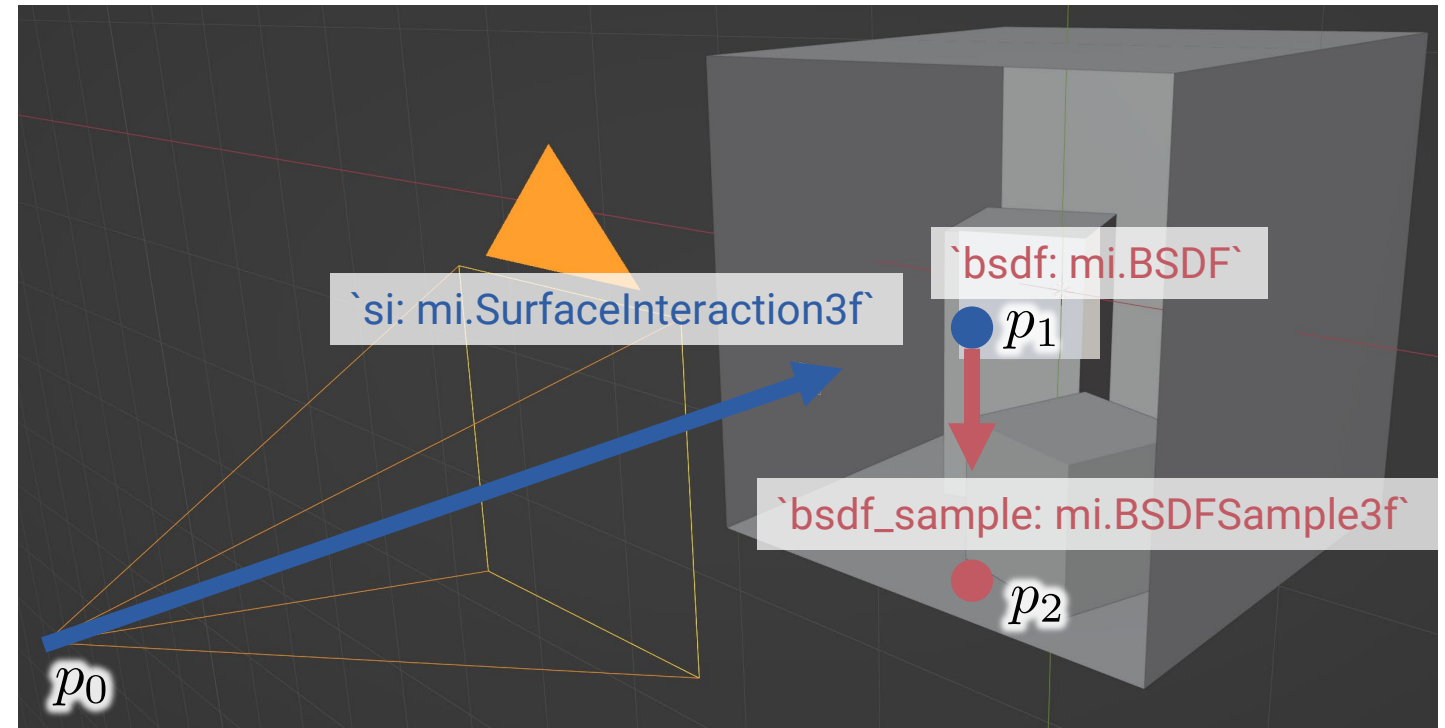
HW Ver. 0.3: BSDF sampling



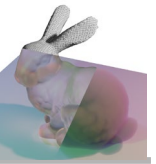
1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`
4. `bsdf_sample, bsdf_weight`
 `= bsdf.sample(..., si, ...)`
5. find p_2
 - See ``spawn_ray`` in ``tutorial3_BSDF.ipynb``
6. Evaluate \hat{L}
 - $\hat{L} = L_{e,10} + \hat{L}_{BSDF,210}$
 - $\hat{L}_{BSDF,210} = \frac{f_{S,210}^\perp L_{e,21}}{p_{BSDF}(\hat{\omega}_{12})}$

$p_{BSDF}(\hat{\omega}_{12})$

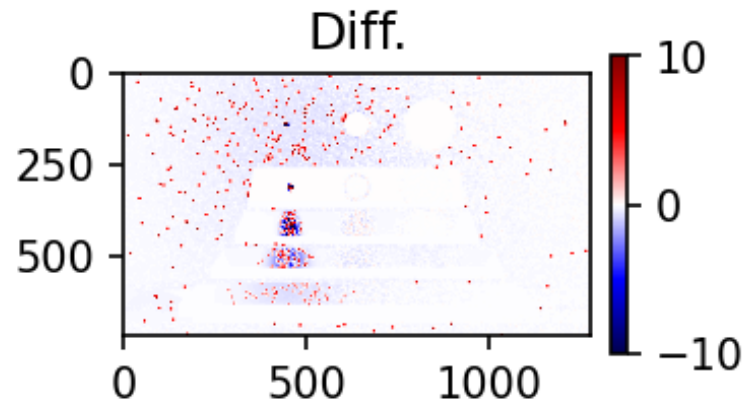
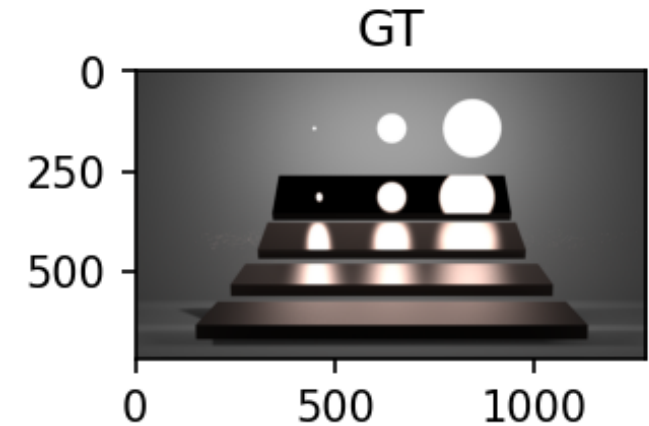
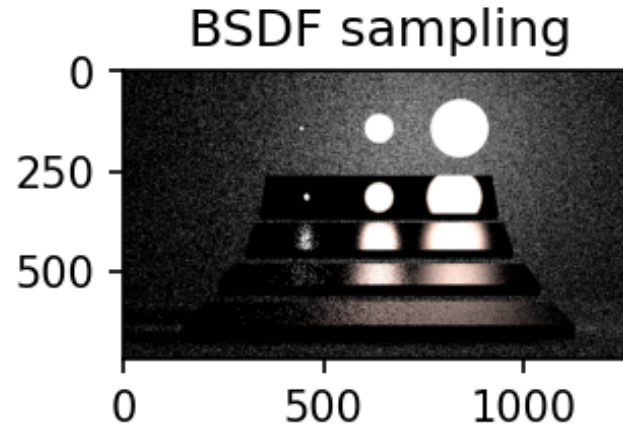
bsdf_weight



HW Ver. 0.3: BSDF sampling

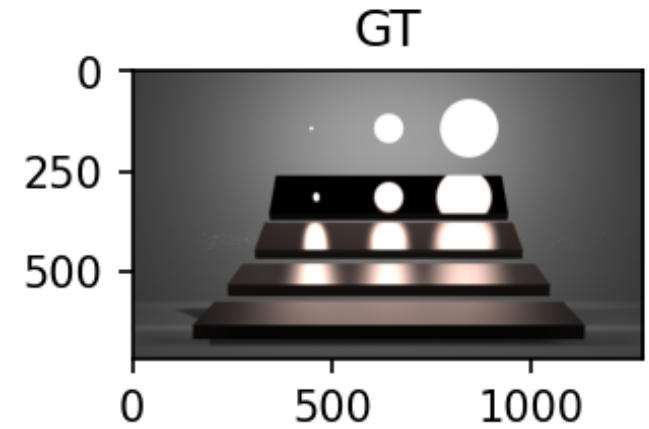
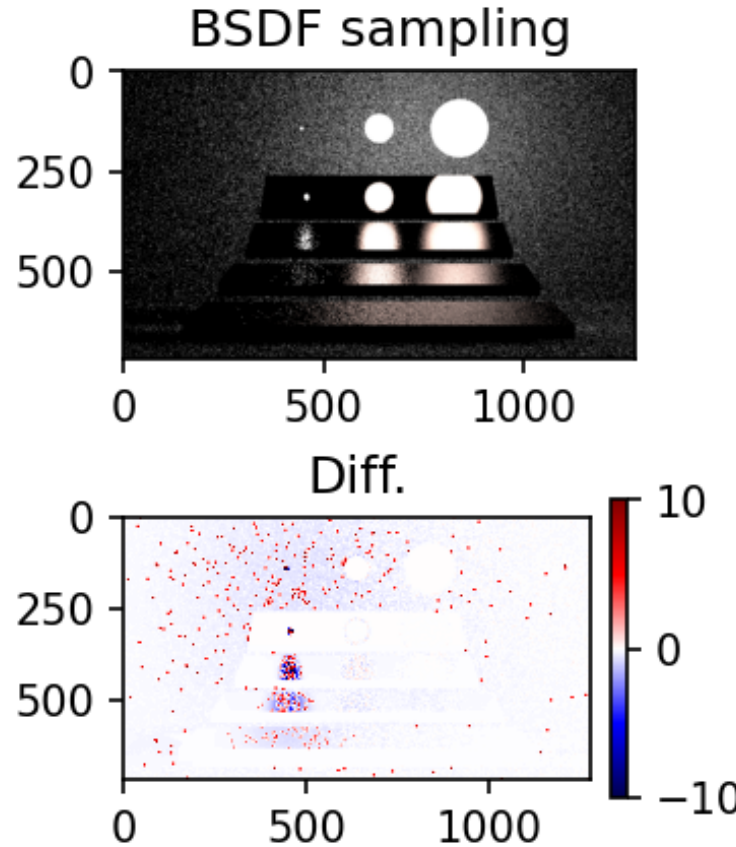


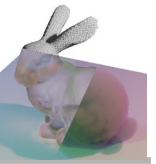
1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`
4. `bsdf_sample, bsdf_weight`
 `= bsdf.sample(..., si, ...)`
5. find p_2
 - See ``spawn_ray`` in ``tutorial3_BSDF.ipynb``
6. Evaluate \hat{L}
 - $\hat{L} = L_{e,10} + \hat{L}_{BSDF,210}$
 - $\hat{L}_{BSDF,210} = \frac{f_{S,210}^\perp L_{e,21}}{p_{BSDF}(\hat{\omega}_{12})}$





Where does noise come from?





Where does noise come from?

Resulting radiance \hat{L} has high variance

← $L_e(\hat{\omega}_{21})$ has high variance

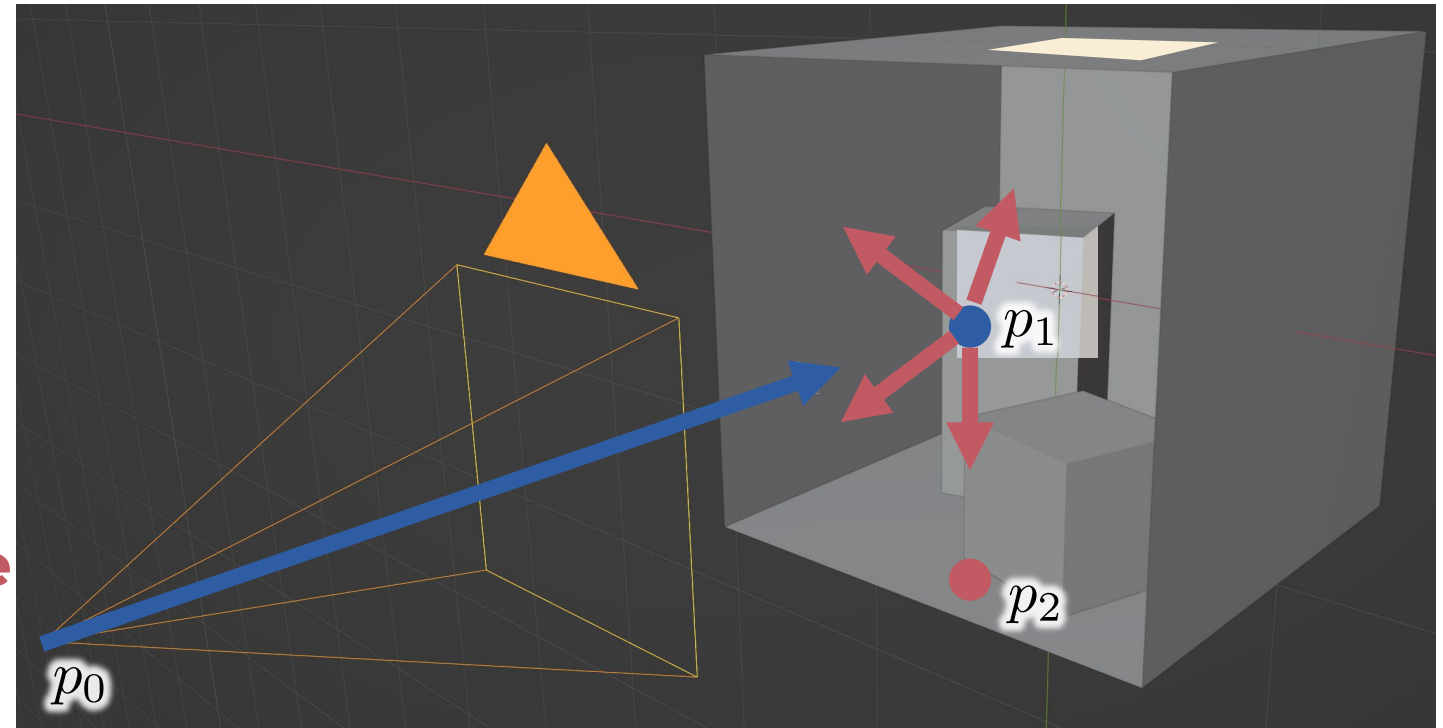
← $\hat{\omega}_{21} = \text{bsdf.sample}()$ rarely hits an emitter

How will amount of noise change if emitters become smaller?

Variance (noise) \uparrow

How zero-area emitter?

Biased (inaccurate)

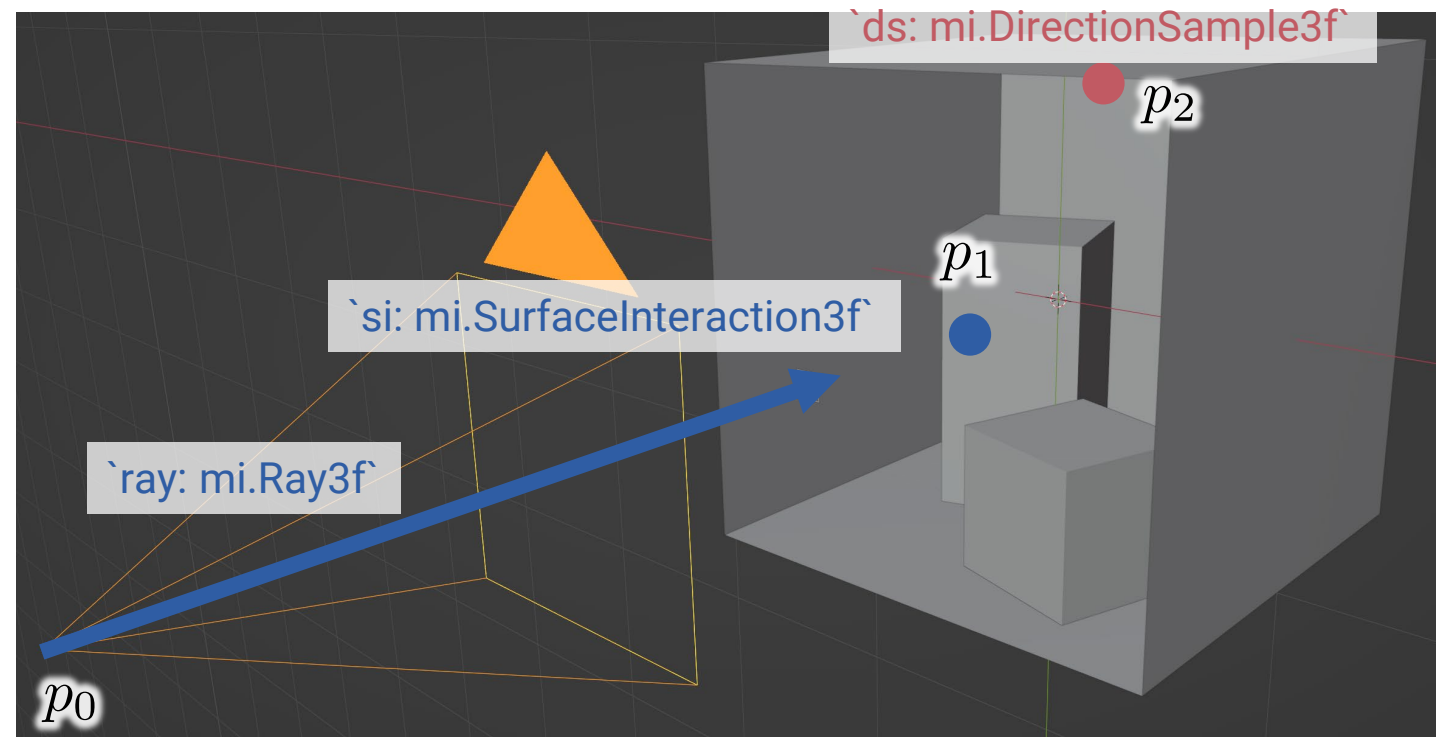


HW Ver. 0.4: Emitter sampling (light sampling)



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `ds, em_weight = scene.sample_emitter_direction(si)`

```
class: mi.scene
# Methods
def sample_emitter_direction():
def eval_emitter_direction():
def pdf_emitter_direction():
```



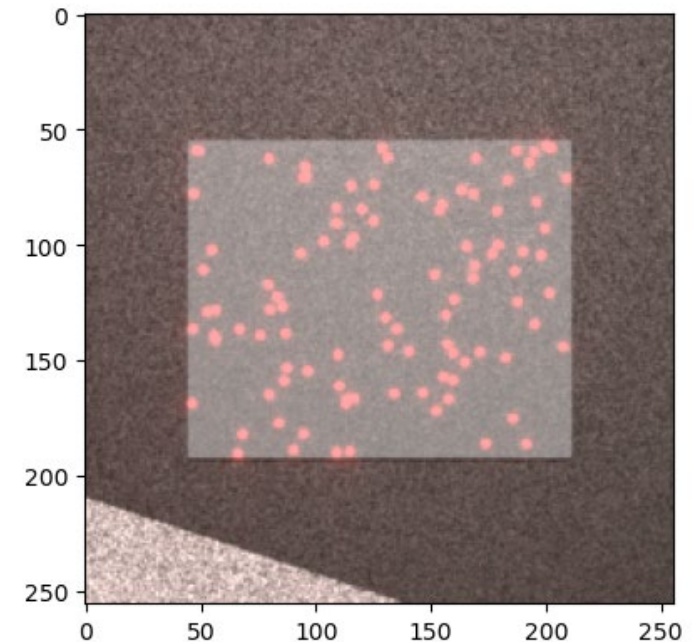
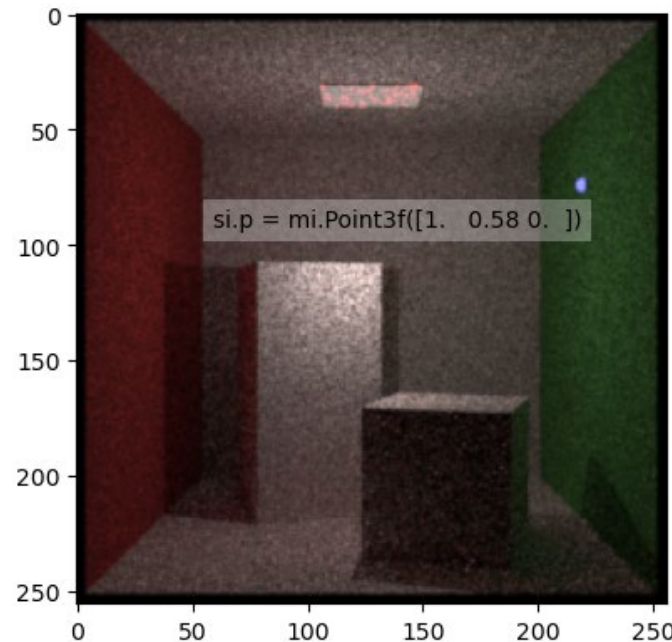
HW Ver. 0.4: Emitter sampling



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `ds, em_weight = scene.sample_emitter_direction(si)`

```
class: mi.scene
# Methods
def sample_emitter_direction():
    (occlusion test option argument)
    (see tutorial4)
def eval_emitter_direction():
def pdf_emitter_direction():
```

```
for i in range(N):
    scene.sample_emitter_direction(si, sampler.next_2d())
```

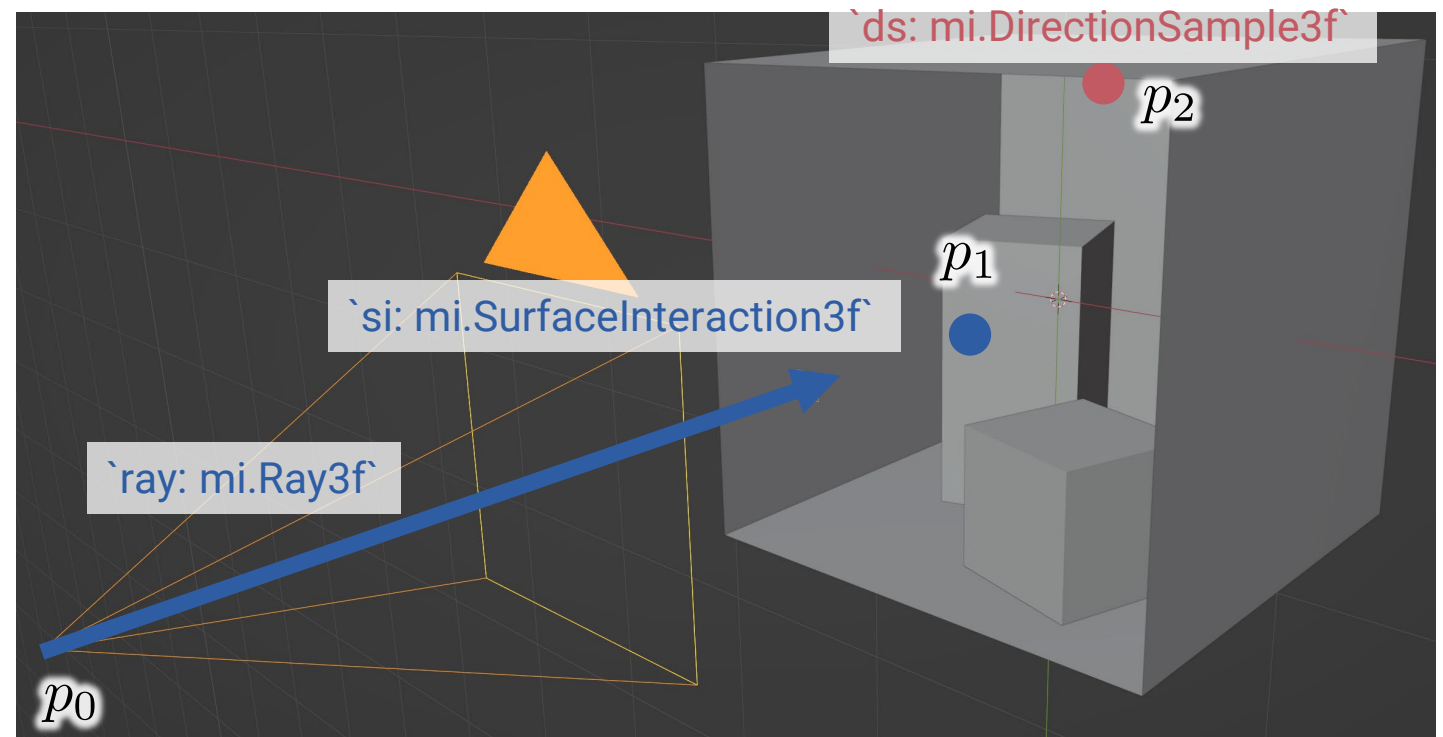


HW Ver. 0.4: Emitter sampling (light sampling)



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `ds, em_weight = scene.sample_emitter_direction(si)`
4. Evaluate \hat{L}

- $\hat{L} = L_{e,10} + \hat{L}_{Emitter,210}$
- $\hat{L}_{Emitter,210} = \frac{f_{s,210}^\perp L_{e,21}}{p_{Emitter}(\hat{\omega}_{12})}$
em_weight



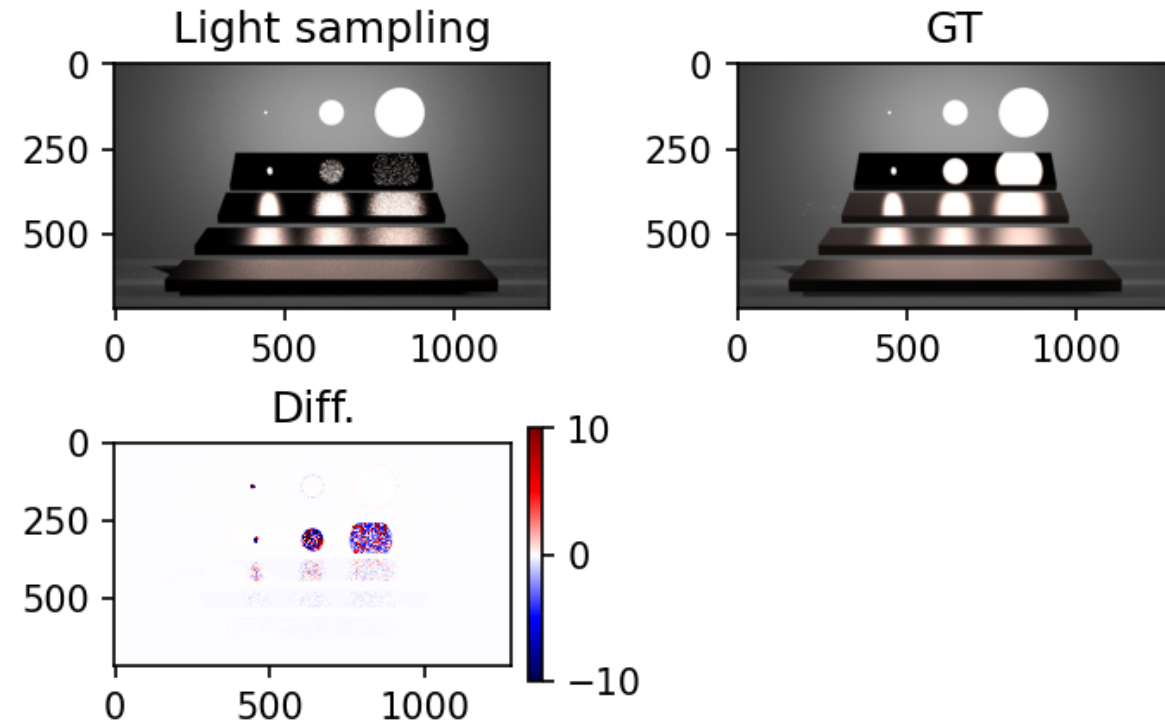
HW Ver. 0.4: Emitter sampling (light sampling)



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `ds, em_weight = scene.sample_emitter_direction(si)`

4. Evaluate \hat{L}

- $\hat{L} = L_{e,10} + \hat{L}_{Emitter,210}$
- $\hat{L}_{Emitter,210} = \frac{f_{s,210}^\perp L_{e,21}}{\underbrace{p_{Emitter}(\hat{\omega}_{12})}_{\text{em_weight}}}$



HW Ver. 0.4: Emitter sampling (light sampling)



Where does noise come from?

Resulting radiance \hat{L} has high variance

← $f_s(p_1, \hat{w}_{21}, \hat{w}_{20})$ has high variance

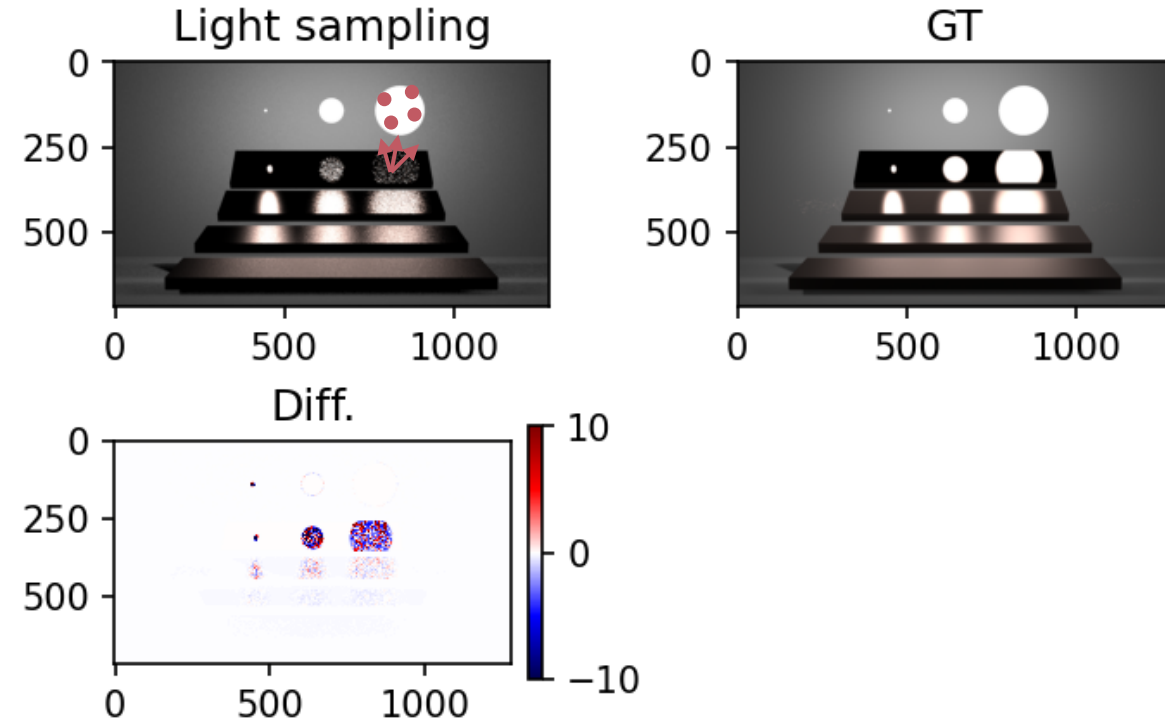
← $p_2 = \text{scene.sample_emitter_direction}()$
rarely hits a (major part of) BSDF lobe

How will amount of noise change if BSDFs become more specular?

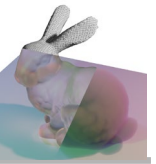
Variance (noise) ↑

How about ideal specular BSDF?

Biased (inaccurate)



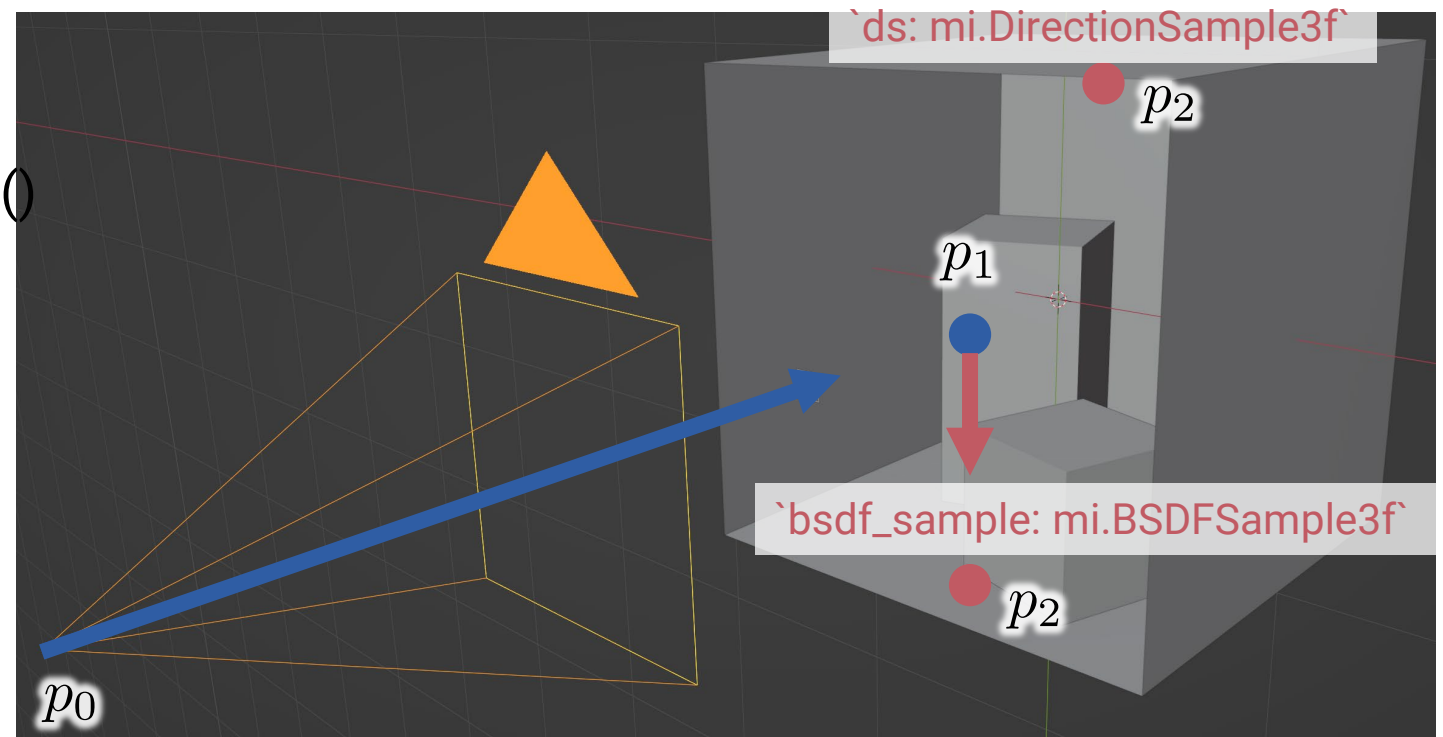
HW Ver. 0.5: Multiple importance sampling



1. `ray = sensor.sample_ray()`
2. `si = scene.ray_intersect(ray)`
3. `bsdf = si.bsdf()`
4. `bsdf_sample, bsdf_weight`
 `= bsdf.sample()`
5. `ds, em_weight`
 `= scene.sample_emitter_direction()`
6. Evaluate \hat{L}

- $\hat{L}_{BSDF,210} = \frac{f_{S,210}^{\perp} L_{e,21}}{p_{BSDF}(\hat{\omega}_{12})}$
- $\hat{L}_{Emitter,210} = \frac{f_{S,210}^{\perp} L_{e,21}}{p_{Emitter}(\hat{\omega}_{12})}$
- $\hat{L} = L_{e,10} + w_B \hat{L}_{BSDF,210} + w_E \hat{L}_{Emitter,210}$

MIS weight



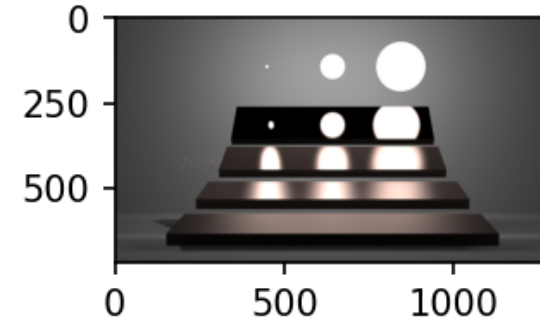
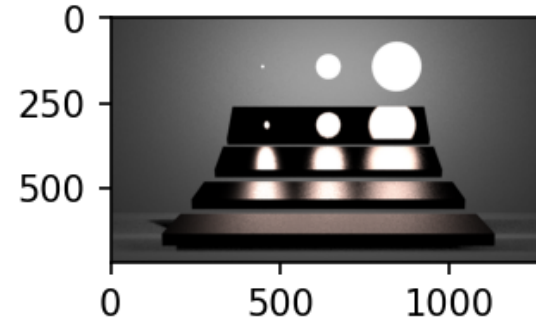
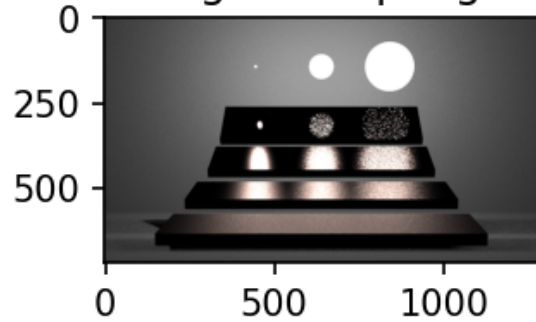
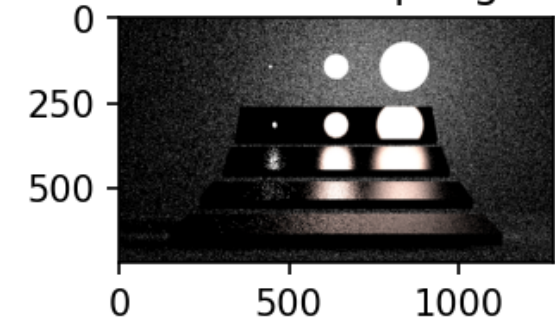


BSDF sampling

Light sampling

MIS

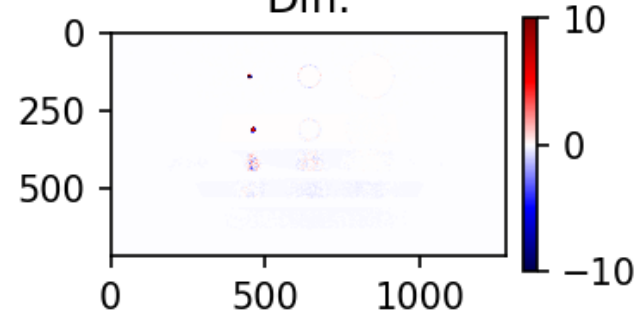
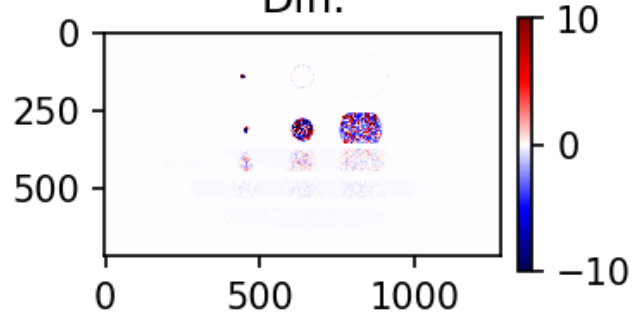
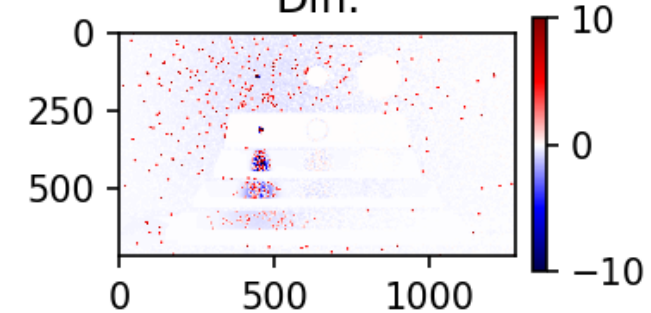
GT

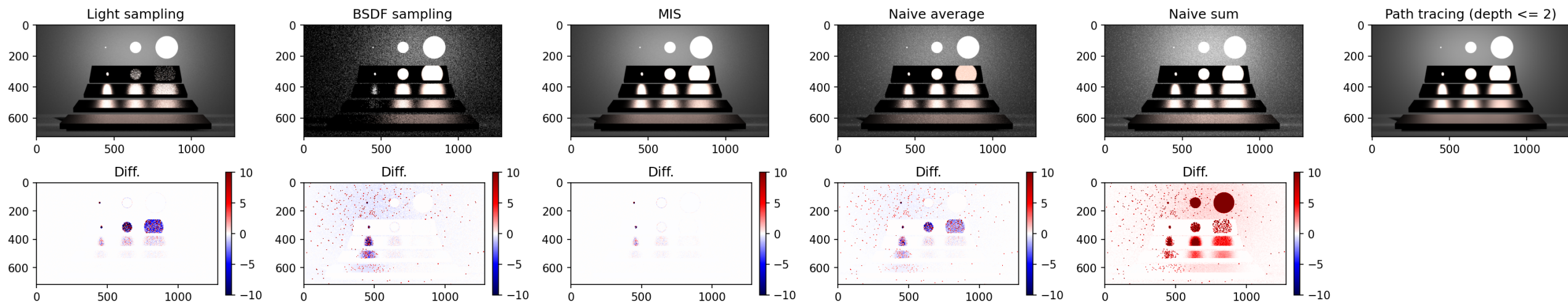
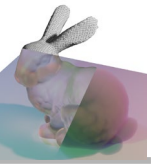


Diff.

Diff.

Diff.

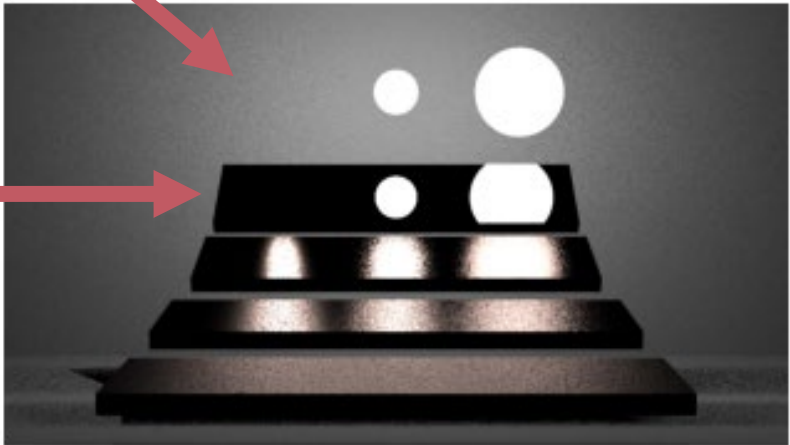




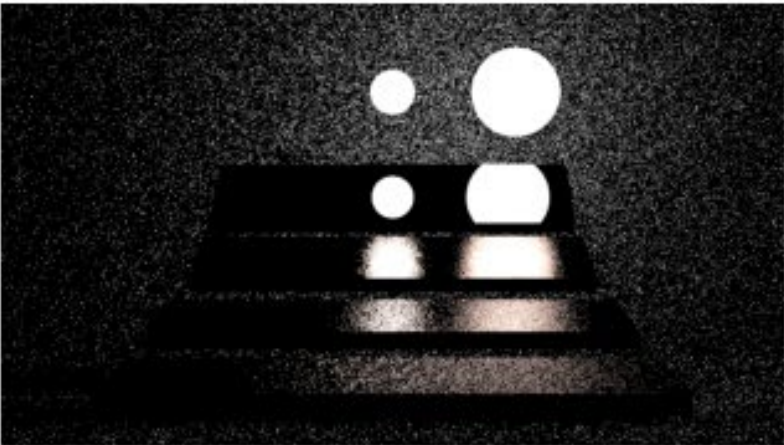


Dirac delta source
(point light)

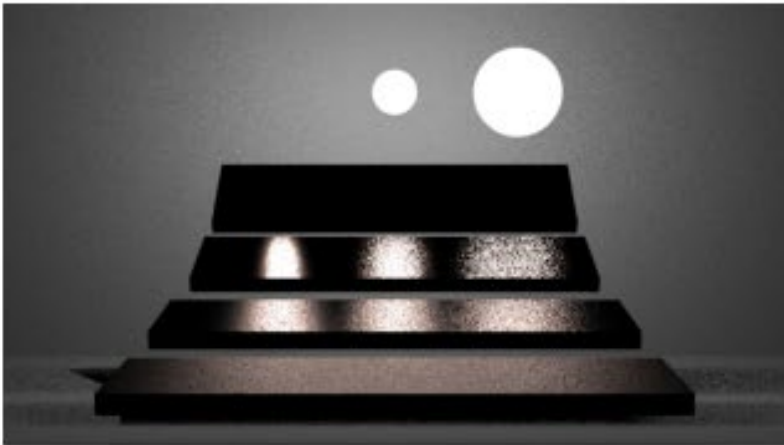
Dirac delta BSDF
(ideal specular)



BSDF sampling



Emitter sampling



MIS (Ver. 0.5)



Monte Carlo Integration: revisit



When is the MC integration correct (unbiased)?

$$\int_{\mathcal{X}} f(x) dx = I = \mathbb{E} \left[\hat{I} = \frac{1}{N} \sum_{n=1}^N \frac{f(X_n)}{p_X(X_n)} \right]$$

For any $x \in \mathcal{X}$, if $f(x) \neq 0$ then $p_X(x) > 0$

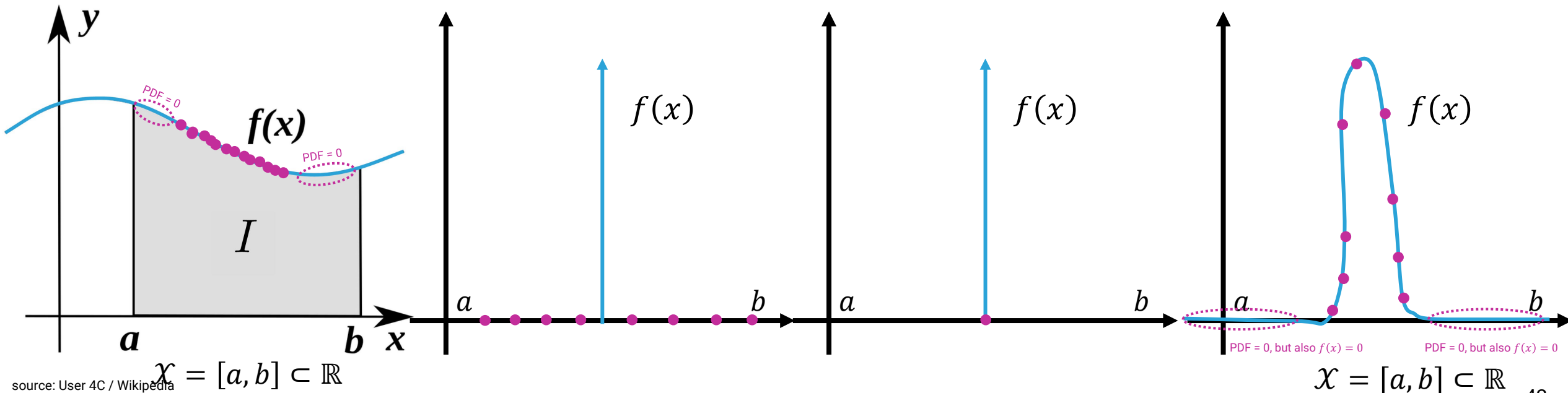
, and if $f(x) \propto \delta(x)$ then $p_X(x) \propto \delta(x)$

Failure case

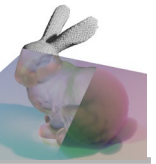
Failure case

Okay

Okay



HW Ver. 0.6: + Dirac delta



Rendering equation



$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \omega_{\hat{o}}) + \int_{\mathbb{S}^2} L^{(\text{out})}(r(p, \hat{\omega}_i), -\hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Recursive!

$$L(p, \hat{\omega}_o) = L_e + \int_{\mathbb{S}^2} L f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation



$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \hat{\omega}_o) + \int_{\mathbb{S}^2} L^{(\text{out})}(r(p, \hat{\omega}_i), -\hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Recursive!

$$L(p, \hat{\omega}_o) = L_e + \int_{\mathbb{S}^2} \left[L'_e + \int_{\mathbb{S}^2} L f'_s |\hat{n} \cdot \hat{\omega}'_i| d\hat{\omega}'_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Rendering equation



$$L^{(\text{out})}(p, \hat{\omega}_o) = L_e(p, \omega_{\hat{o}}) + \int_{\mathbb{S}^2} L^{(\text{out})}(r(p, \hat{\omega}_i), -\hat{\omega}_i) f_s(p, \hat{\omega}_i, \hat{\omega}_o) |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

Recursive!

$$L(p, \hat{\omega}_o) = L_e + \int_{\mathbb{S}^2} \left[L'_e + \int_{\mathbb{S}^2} \left[L''_e + \int_{\mathbb{S}^2} L f'_s |\hat{n} \cdot \hat{\omega}_i'| d\hat{\omega}_i' \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

...

$$\begin{aligned} L(p, \hat{\omega}_o) &= L_e \\ &+ \int_{\mathbb{S}^2} L'_e f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L''_e f'_s |\hat{n} \cdot \hat{\omega}_i'| d\hat{\omega}_i' \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L'''_e f''_s |\hat{n} \cdot \hat{\omega}_i''| d\hat{\omega}_i'' \right] f'_s |\hat{n} \cdot \hat{\omega}_i'| d\hat{\omega}_i' \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \end{aligned}$$

Rendering equation



Doesn't this series diverge?

Simple analogy, rather than rigorous functional analysis

For equation & infinite series for a simple real number

$$L = L_e + f_s L$$
$$L = \frac{L_e}{1 - f_s} = L_e \sum_{n=0}^{\infty} f_s^n, \text{ if } |f_s| < 1$$

energy conservation property makes it holds

$$L(p, \hat{\omega}_o) = L_e$$

$$+ \int_{\mathbb{S}^2} L'_e f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

$$+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L''_e f'_s |\hat{n} \cdot \hat{\omega}'_i| d\hat{\omega}'_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

$$+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L'''_e f''_s |\hat{n} \cdot \hat{\omega}''_i| d\hat{\omega}''_i \right] f'_s |\hat{n} \cdot \hat{\omega}'_i| d\hat{\omega}'_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i$$

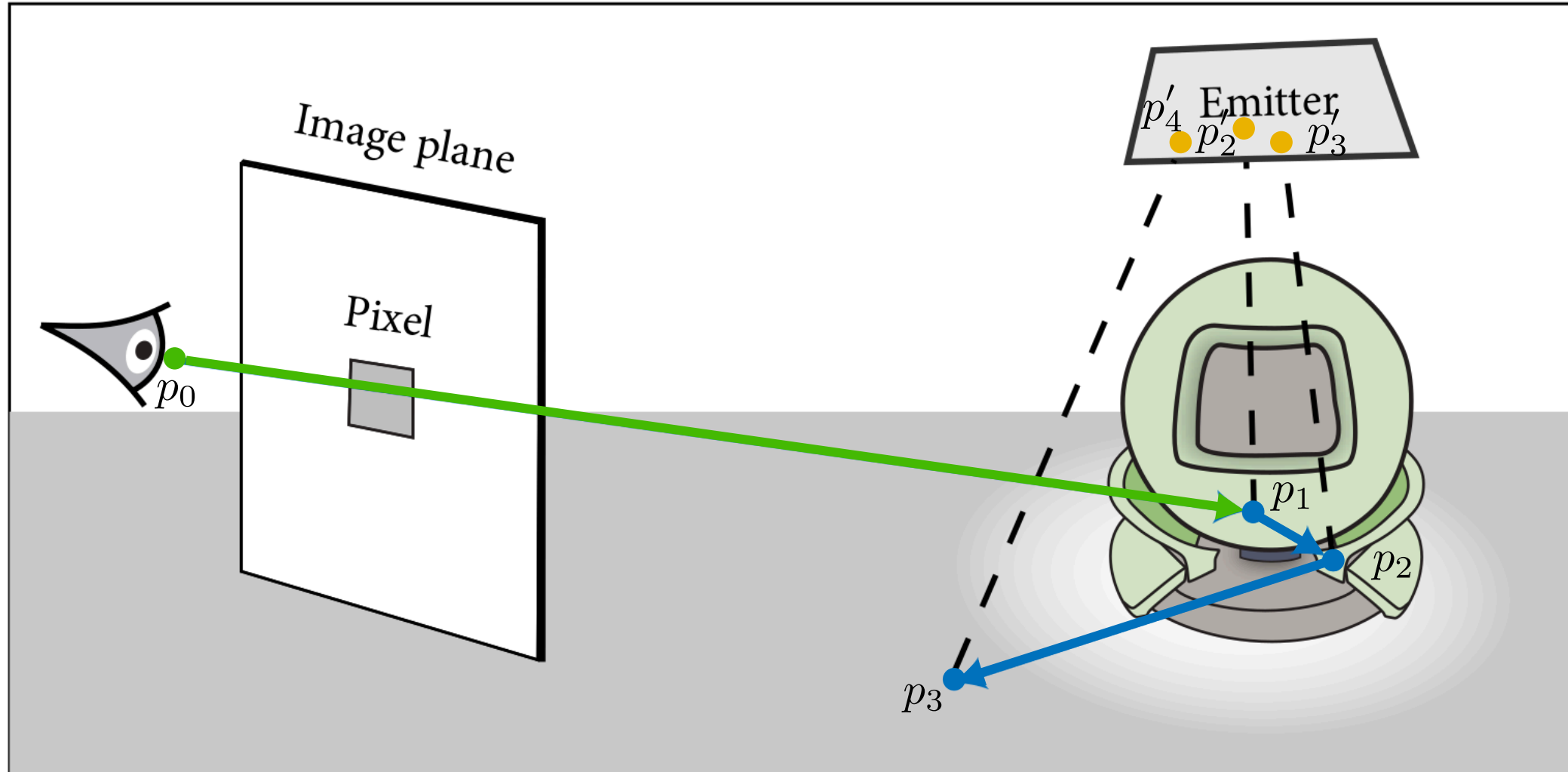
What image each line produces?

Rendering equation

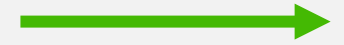


$$\begin{aligned} L(p, \hat{\omega}_o) &= L_e \\ &+ \int_{\mathbb{S}^2} L'_e f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L''_e f'_s |\hat{n} \cdot \hat{\omega}'_i| d\hat{\omega}'_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L'''_e f''_s |\hat{n} \cdot \hat{\omega}''_i| d\hat{\omega}''_i \right] f'_s |\hat{n} \cdot \hat{\omega}'_i| d\hat{\omega}'_i \right] f_s |\hat{n} \cdot \hat{\omega}_i| d\hat{\omega}_i \end{aligned}$$

Rendering equation for direct illumination



Sensor sampling



BSDF sampling



Emitter sampling



[https://mitsuba.readthedocs.io/en/latest/_images/integrator_path_figure.png]

Rendering equation



$$\begin{aligned} L(p_1, \hat{\omega}_{10}) &= L_{e,10} \\ &+ \int_{\mathbb{S}^2} L_{e,21} f_{s,210}^\perp d\hat{\omega}_{12} \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L_{e,32} f_{s,321}^\perp d\hat{\omega}'_i \right] f_{s,210}^\perp d\hat{\omega}_{23} \\ &+ \int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} \left[\int_{\mathbb{S}^2} L_{e,43} f_{s,432}^\perp d\hat{\omega}''_i \right] f_{s,321}^\perp d\hat{\omega}'_i \right] f_{s,210}^\perp d\hat{\omega}_{34} \end{aligned}$$

Rendering equation



$$\begin{aligned} L(p_1, \hat{\omega}_{10}) &= L_{e,10} \\ &+ \int_{\mathbb{S}^2} f_{s,210}^\perp L_{e,21} d\hat{\omega}_{12} \\ &+ \int_{\mathbb{S}^2} f_{s,210}^\perp \left[\int_{\mathbb{S}^2} f_{s,321}^\perp L_{e,32} d\hat{\omega}_{23} \right] d\hat{\omega}_{12} \\ &+ \int_{\mathbb{S}^2} f_{s,210}^\perp \left[\int_{\mathbb{S}^2} f_{s,321}^\perp \left[\int_{\mathbb{S}^2} f_{s,432}^\perp L_{e,43} d\hat{\omega}_{34} \right] d\hat{\omega}_{23} \right] d\hat{\omega}_{12} \end{aligned}$$

Integration domain: all paths (tuples of vertices)

integrand: path contribution $f(p_0 \dots p_j)$

Rendering equation



$$\begin{aligned}
 L(p_1, \hat{w}_{10}) &\approx L_{e,10} \\
 &+ \frac{f_{s,210}^\perp L_{e,21}}{p(W_{12})} \\
 &+ \frac{f_{s,210}^\perp f_{s,321}^\perp L_{e,32}}{p(W_{12})p(W_{23})} \\
 &+ \frac{f_{s,210}^\perp f_{s,321}^\perp f_{s,432}^\perp L_{e,43}}{p(W_{12})p(W_{23})p(W_{34})}
 \end{aligned}$$

$si = p_{i+1}$

$ds = p'_{i+2}$

$bsdf_sample.wo = \hat{w}_{i+1,i+2}$

```

def sample(self,
    mode: dr.ADMode,
    scene: mi.Scene,
    sampler: mi.Sampler,
    ray: mi.Ray3f,
    **kwargs # Absorbs unused arguments
) -> Tuple[mi.Spectrum,
    mi.Bool, mi.Spectrum]:
    # Standard BSDF evaluation context for path tracing
    bsdf_ctx = mi.BSDFContext()

    # Copy input arguments to avoid mutating the caller's state
    depth = mi.UInt32(0) # Depth of current vertex
    L = mi.Spectrum(0) # Radiance accumulator
    beta = mi.Spectrum(1) # Path throughput weight

    # Variables caching information from the previous bounce
    prev_si = dr.zeros(mi.SurfaceInteraction3f)
    prev_bsdf_pdf = mi.Float(1.0)
    prev_bsdf_delta = mi.Bool(True)

    for i in range(self.max_depth):
        si = scene.ray_intersect(ray)

        # Get the BSDF, potentially computes texture-space differentials
        bsdf = si.bsdf(ray)

        # ----- Direct emission -----

        # Compute MIS weight for emitter sample from previous bounce
        ds = mi.DirectionSample3f(scene, si=si, ref=prev_si)

        mis = mis_weight(
            prev_bsdf_pdf,
            scene.pdf_emitter_direction(prev_si, ds, ~prev_bsdf_delta)
        )

        Le = beta * mis * ds.emitter.eval(si)

        # ----- Emitter sampling -----
        ds, em_weight = scene.sample_emitter_direction(
            si, sampler.next_2d(), True)

        # Evaluate BSDF * cos(theta) differentially
        wo = si.to_local(ds.d)
        bsdf_value_em, bsdf_pdf_em = bsdf.eval_pdf(bsdf_ctx, si, wo)
        mis_em = dr.select(ds.delta, 1, mis_weight(ds.pdf, bsdf_pdf_em))
        Lr_dir = beta * mis_em * bsdf_value_em * em_weight

        # ----- Detached BSDF sampling -----
        bsdf_sample, bsdf_weight = bsdf.sample(bsdf_ctx, si,
            sampler.next_1d(),
            sampler.next_2d())
        L = L + Le + Lr_dir
        ray = si.spawn_ray(si.to_world(bsdf_sample.wo))
        beta *= bsdf_weight

        prev_si = si
        prev_bsdf_pdf = bsdf_sample.pdf
        prev_bsdf_delta = mi.has_flag(bsdf_sample.sampled_type, mi.BSDFFlags.Delta)

    return (
        L, # Radiance/differential radiance
        dr.neq(depth, 0), # Ray validity flag for alpha blending
        L # State for the differential phase
    )

```

Rendering equation



$$\begin{aligned} L(p_1, \hat{\omega}_{10}) &\approx L_{e,10} \\ &+ \frac{f_{s,210}^\perp L_{e,21}}{p(W_{12})} \\ &+ \frac{f_{s,210}^\perp f_{s,321}^\perp L_{e,32}}{p(W_{12})p(W_{23})} \\ &+ \frac{f_{s,210}^\perp f_{s,321}^\perp f_{s,432}^\perp L_{e,43}}{p(W_{12})p(W_{23})p(W_{34})} \end{aligned}$$

Rendering equation



$$L(p_1, \hat{\omega}_{10}) \approx L_{e,10}$$

$$\begin{aligned} & + w_B(W_{12,B}) \frac{f_{s,210}^\perp L_{e,21}}{p_B(W_{12,B})} + w_E(W_{12,E}) \frac{f_{s,210}^\perp L_{e,21}}{p_E(W_{12,E})} \\ & + w_B(W_{23,B}) \frac{f_{s,210}^\perp f_{s,321}^\perp L_{e,32}}{p_B(W_{12,B}) p_B(W_{23,B})} + w_E(W_{23,E}) \frac{f_{s,210}^\perp f_{s,321}^\perp L_{e,32}}{p_B(W_{12,B}) p_E(W_{23,E})} \\ & + w_B(W_{34,B}) \frac{f_{s,210}^\perp f_{s,321}^\perp f_{s,432}^\perp L_{e,43}}{p_B(W_{12,B}) p_B(W_{23,B}) p_B(W_{34,B})} + w_E(W_{34,E}) \frac{f_{s,210}^\perp f_{s,321}^\perp f_{s,432}^\perp L_{e,43}}{p_B(W_{12,B}) p_B(W_{23,B}) p_E(W_{34,E})} \end{aligned}$$

BSDF sampling

Emitter sampling

Rendering equation



$$L(p_1, \hat{\omega}_{10}) \approx L_{e,10}$$

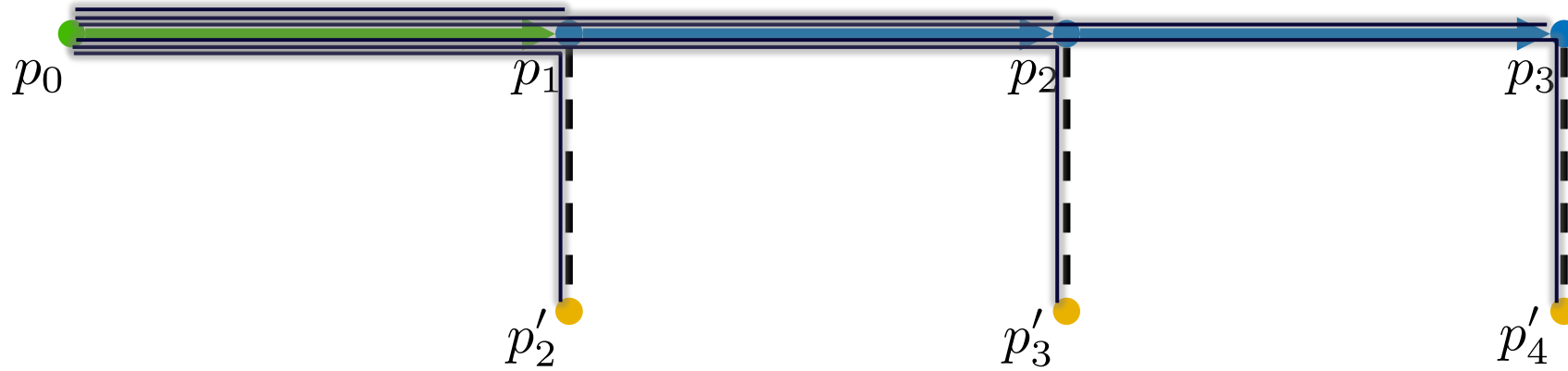
$$\begin{aligned}
 & + w_B(W_{12,B}) \frac{f_{s,210}^\perp L_{e,21}}{p_B(W_{12,B})} + w_E(W_{12,E}) \frac{f_{s,210}^\perp L_{e,21}}{p_E(W_{12,E})} \\
 & + \frac{f_{s,210}^\perp}{p_B(W_{12,B})} \left[w_B(W_{23,B}) \frac{f_{s,321}^\perp L_{e,32}}{p_B(W_{23,B})} + w_E(W_{23,E}) \frac{f_{s,321}^\perp L_{e,32}}{p_E(W_{23,E})} \right] \\
 & + \frac{f_{s,210}^\perp f_{s,321}^\perp}{p_B(W_{12,B}) p_B(W_{23,B})} \left[w_B(W_{34,B}) \frac{f_{s,432}^\perp L_{e,43}}{p_B(W_{34,B})} + w_E(W_{34,E}) \frac{f_{s,432}^\perp L_{e,43}}{p_E(W_{34,E})} \right]
 \end{aligned}$$

throughput variable β

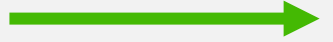
BSDF sampling

Emitter sampling

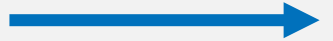
Rendering equation



Sensor sampling

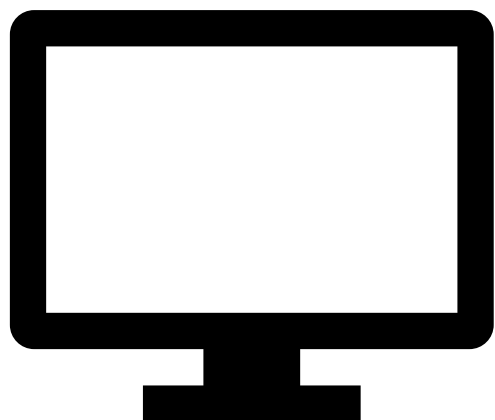


BSDF sampling

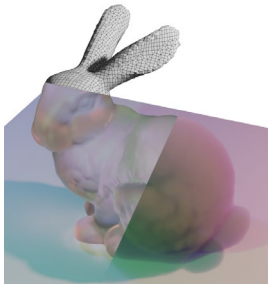


Emitter sampling



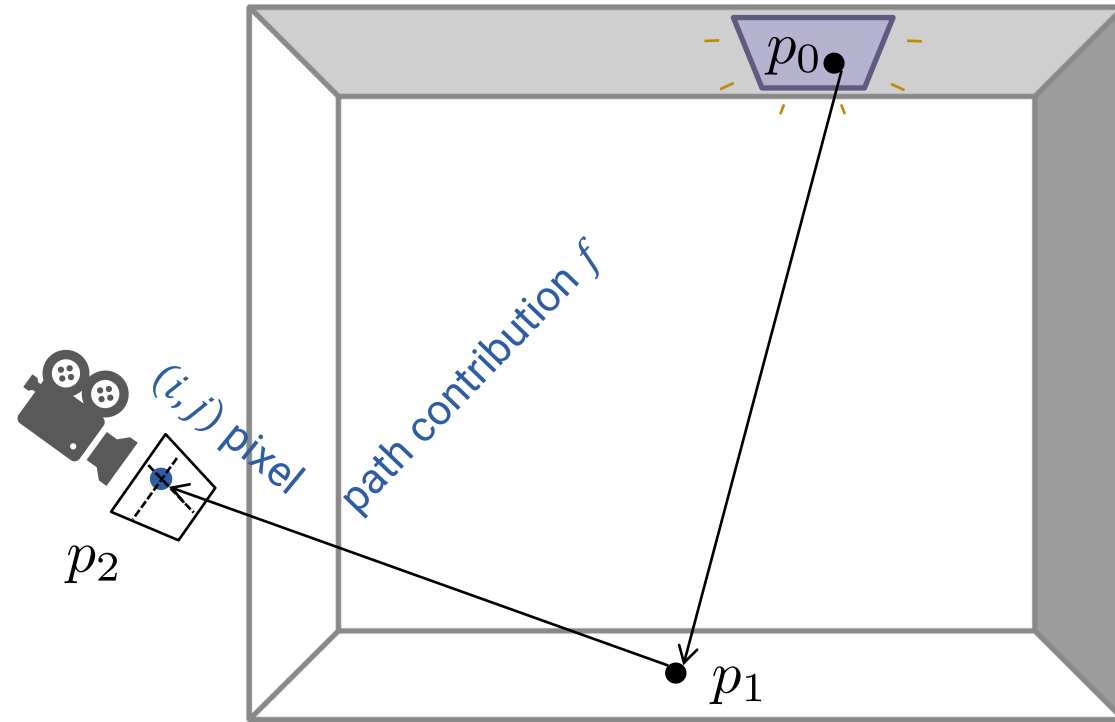






Preview: a simple path tracing

Rendering equation for direct illumination



Terminology and convention:

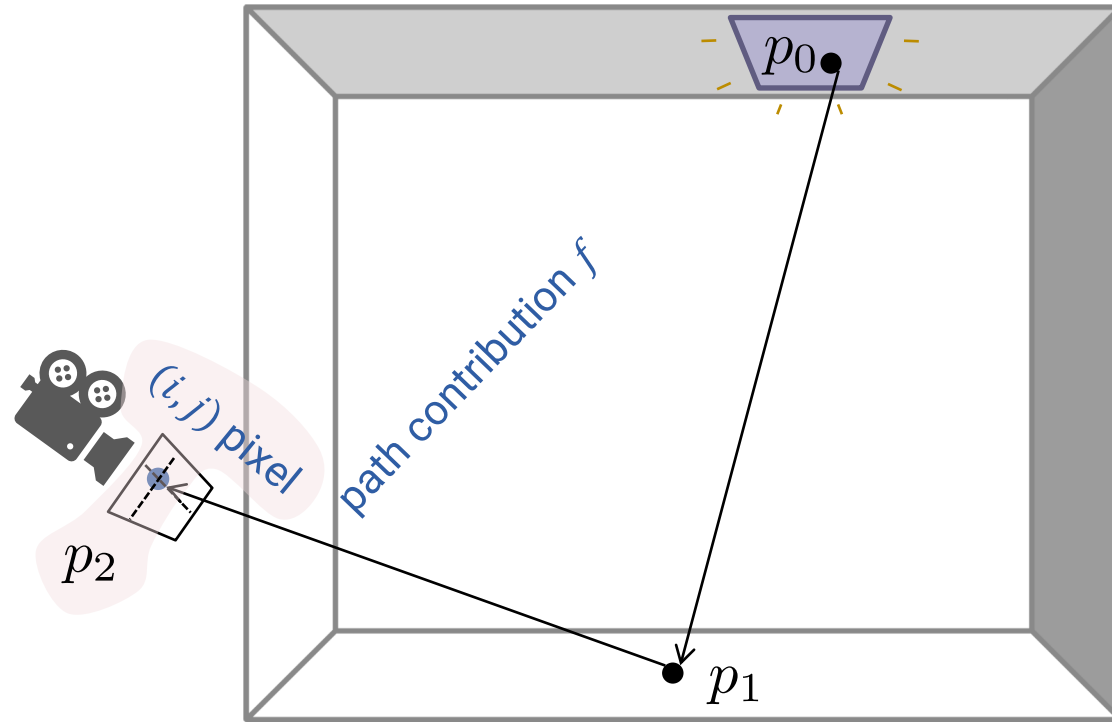
- Notation / actual light: $p_0 \rightarrow p_1 \rightarrow p_2$
- Computation: $p_2 \rightarrow p_1 \rightarrow p_0$
- # of bounces < depth < # of vertices

1

2

3

Rendering equation for direct illumination



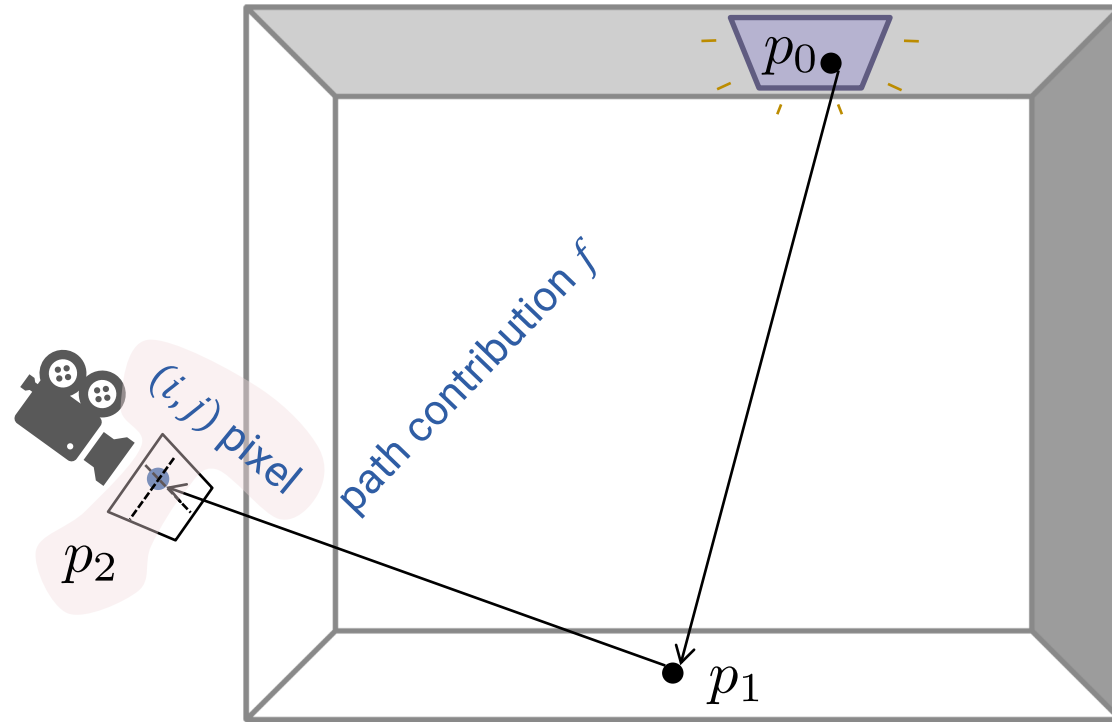
Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$

Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_2, \hat{\omega}) d\hat{\omega}$$

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$

Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_2, \hat{\omega}) d\hat{\omega}$$

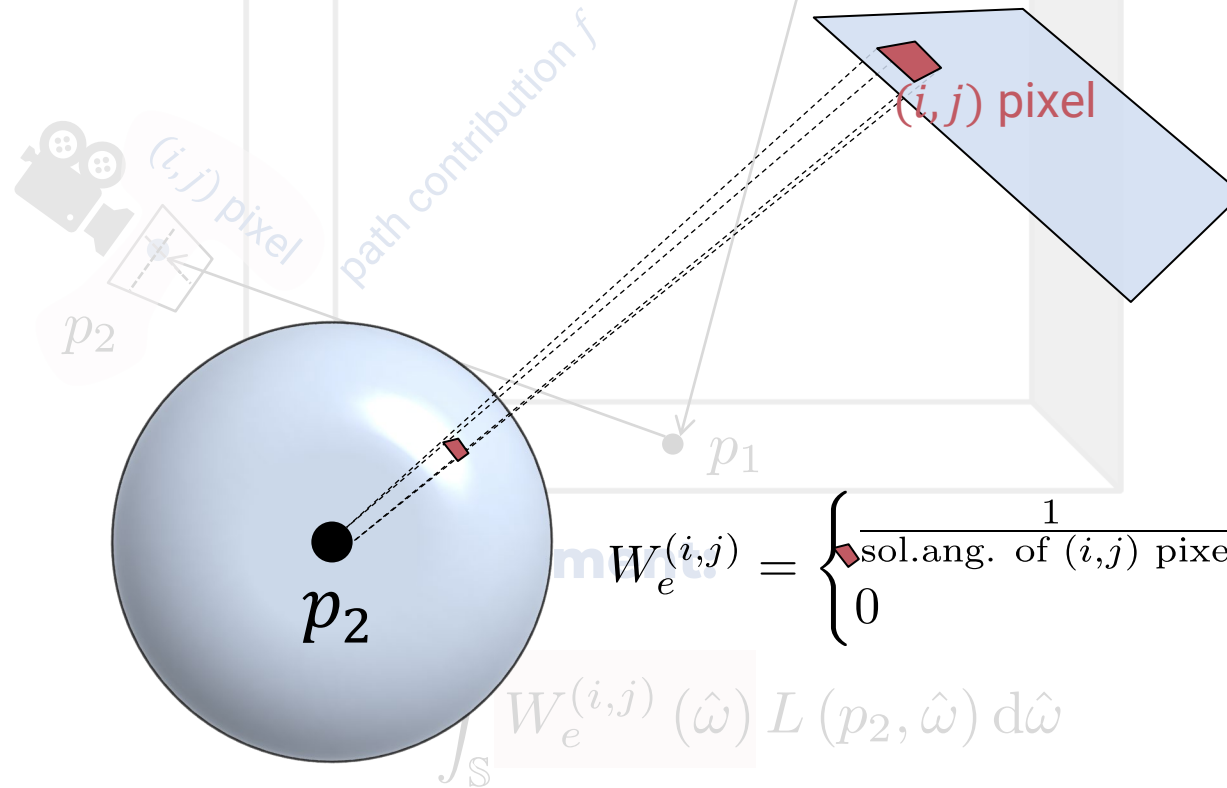
Rendering equation for direct illumination



Importance (pixel reconstruction filter) $W_e(p, \hat{\omega})$

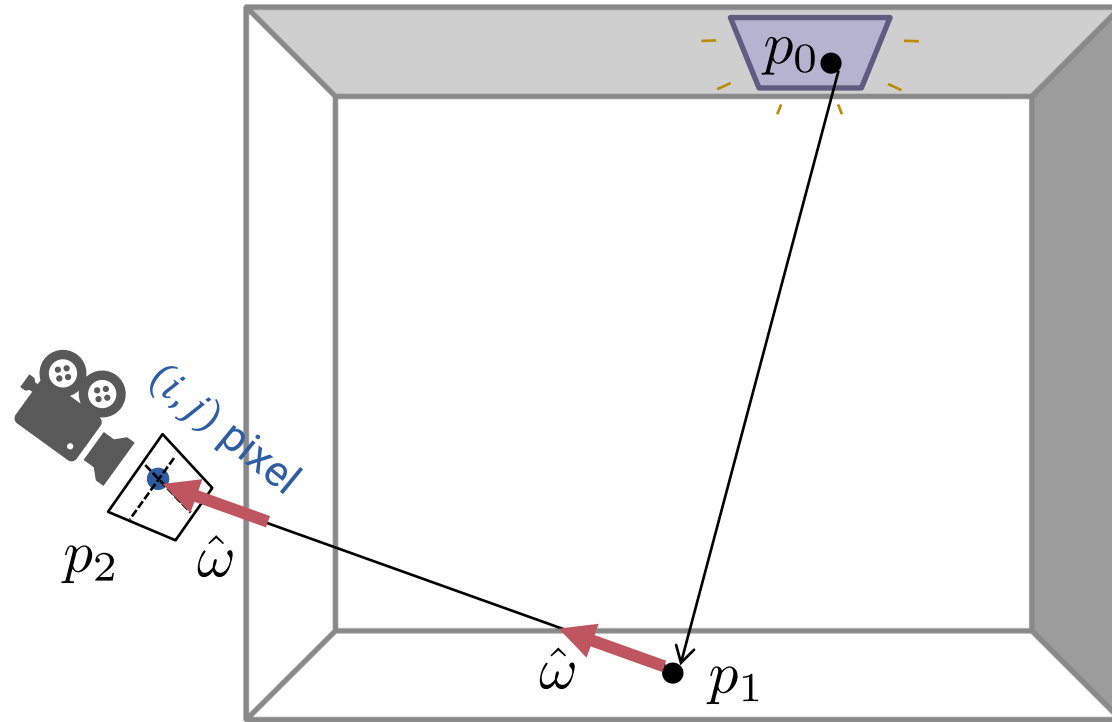
Notation:

$$\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$$



$\hat{\omega}$ in $\textcolor{red}{\diamond}(i, j)$ pixel
otherwise

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
- $r: \mathbb{R}^3 \times \mathbb{S}^2 \rightarrow \mathbb{R}^3$
 - ray intersection

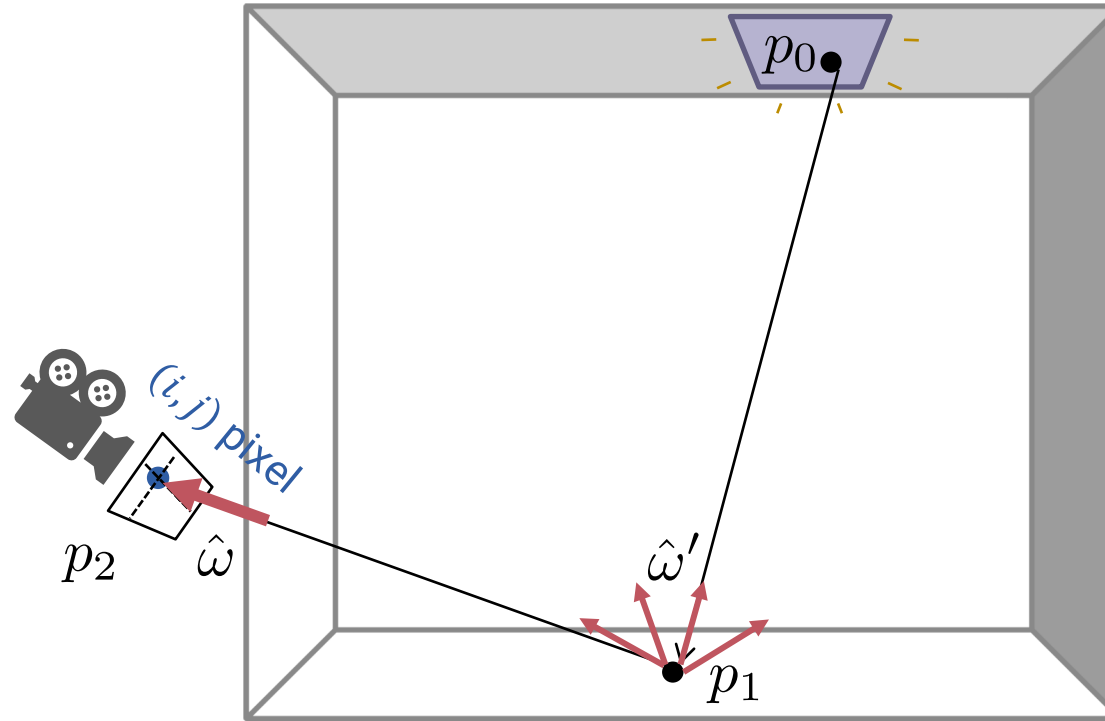
Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_2, \hat{\omega}) d\hat{\omega}$$

$$\leftarrow p_1 = r(p_2, -\hat{\omega})$$

$$L(p_2, \hat{\omega}) = L(p_1, \hat{\omega})$$

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
- $r: \mathbb{R}^3 \times \mathbb{S}^2 \rightarrow \mathbb{R}^3$
 - ray intersection

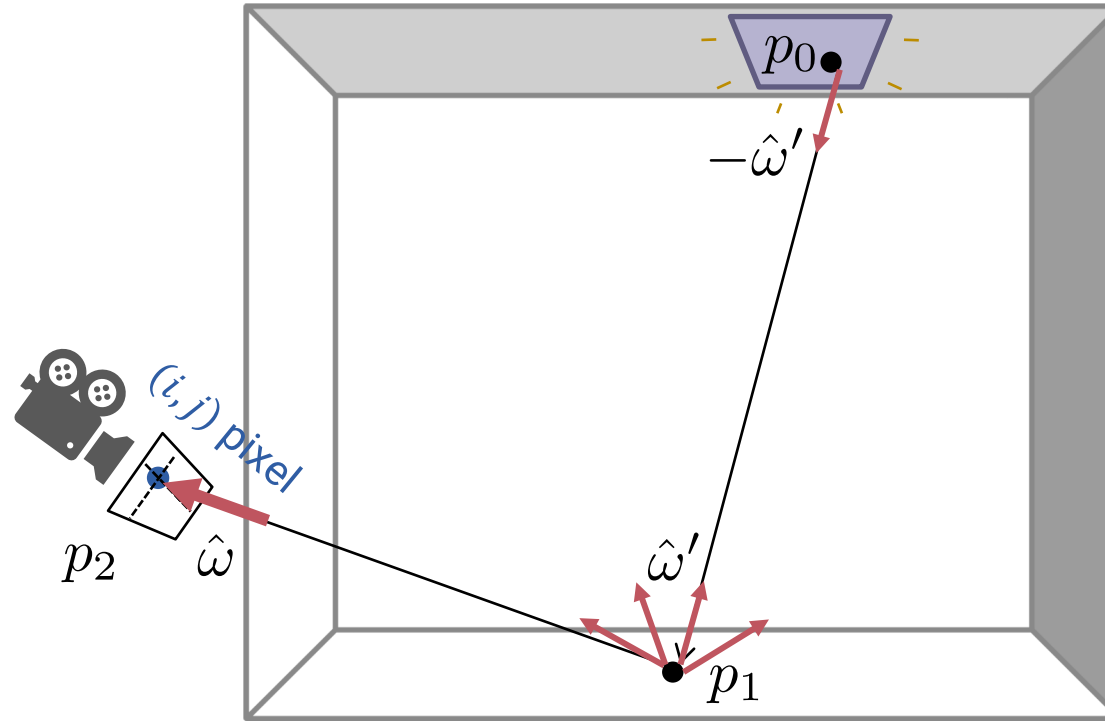
Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_1, \hat{\omega}) d\hat{\omega}$$

$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L^{(\text{in})}(p_1, \hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$$\leftarrow p_1 = r(p_2, -\hat{\omega})$$

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
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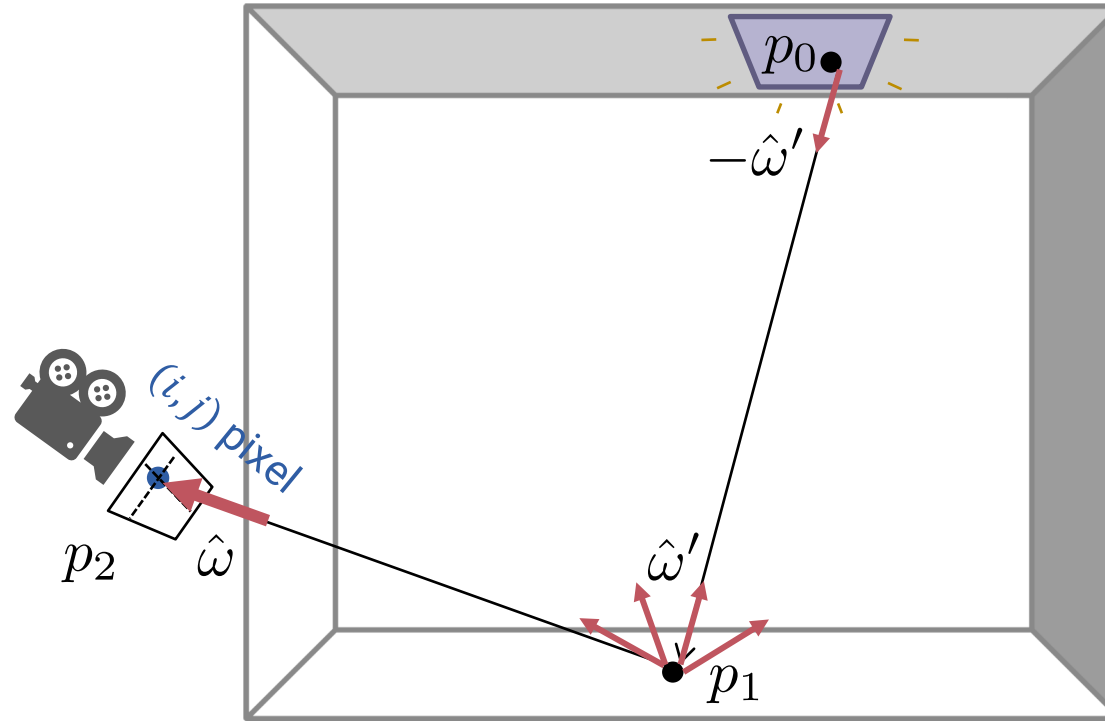
$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L^{(\text{in})}(p_1, \hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$$L^{(\text{in})}(p_1, \hat{\omega}') = L(p_0, -\hat{\omega}')$$

$$\leftarrow p_1 = r(p_2, -\hat{\omega})$$

$$\leftarrow p_0 = r(p_1, \hat{\omega}')$$

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
- $r: \mathbb{R}^3 \times \mathbb{S}^2 \rightarrow \mathbb{R}^3$
 - ray intersection

Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_1, \hat{\omega}) d\hat{\omega}$$

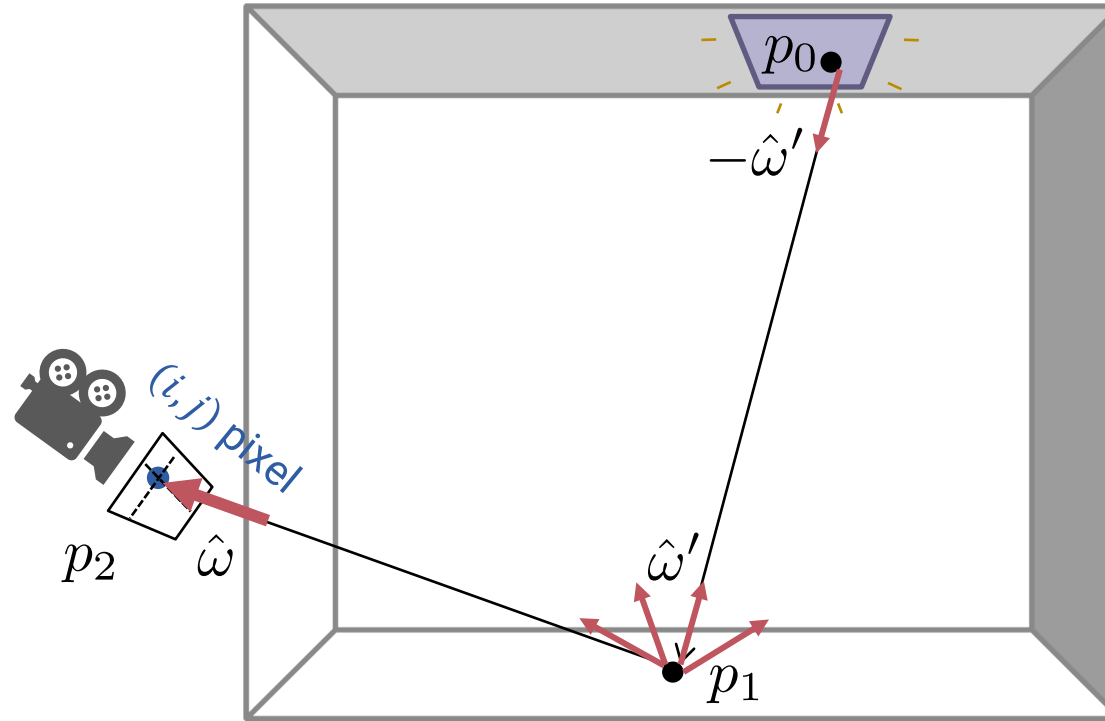
$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L^{(\text{in})}(p_1, \hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$\leftarrow p_1 = r(p_2, -\hat{\omega})$
 $\leftarrow p_0 = r(p_1, \hat{\omega}')$

Direct illumination only

~~$$L(p_0, -\hat{\omega}') = L_e(p_0, -\hat{\omega}') + \int_{\mathbb{S}} L^{(\text{in})}(p_0, \hat{\omega}'') \rho(p_0, \hat{\omega}'', -\hat{\omega}') |\hat{n} \cdot \hat{\omega}''| d\hat{\omega}''$$~~

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
- $r: \mathbb{R}^3 \times \mathbb{S}^2 \rightarrow \mathbb{R}^3$
 - ray intersection

Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_1, \hat{\omega}) d\hat{\omega}$$

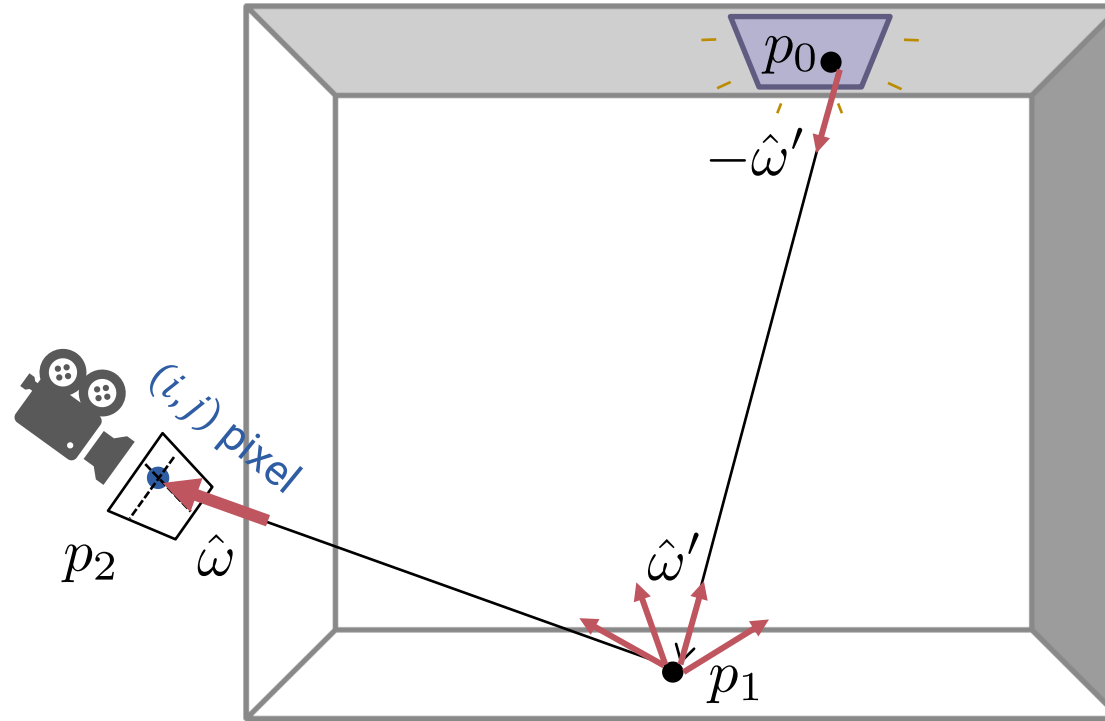
$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L^{(\text{in})}(p_1, \hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$$\leftarrow p_1 = r(p_2, -\hat{\omega})$$

$$\leftarrow p_0 = r(p_1, \hat{\omega}')$$

$$L(p_0, -\hat{\omega}') = L_e(p_0, -\hat{\omega}')$$

Rendering equation for direct illumination



Notation:

- $\hat{\omega}_{p_0 p_1} := \frac{p_1 - p_0}{\|p_1 - p_0\|}$
- $r: \mathbb{R}^3 \times \mathbb{S}^2 \rightarrow \mathbb{R}^3$
 - ray intersection

Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_1, \hat{\omega}) d\hat{\omega}$$

$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L_e(p_0, -\hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$$\begin{aligned} p_1 &= r(p_2, -\hat{\omega}) \\ p_0 &= r(p_1, \hat{\omega}') \end{aligned}$$



Ver 0.1: normal integrator

Why deterministic pseudo-random



1. Debugging
2. Several technique: [Path replay backproagation]



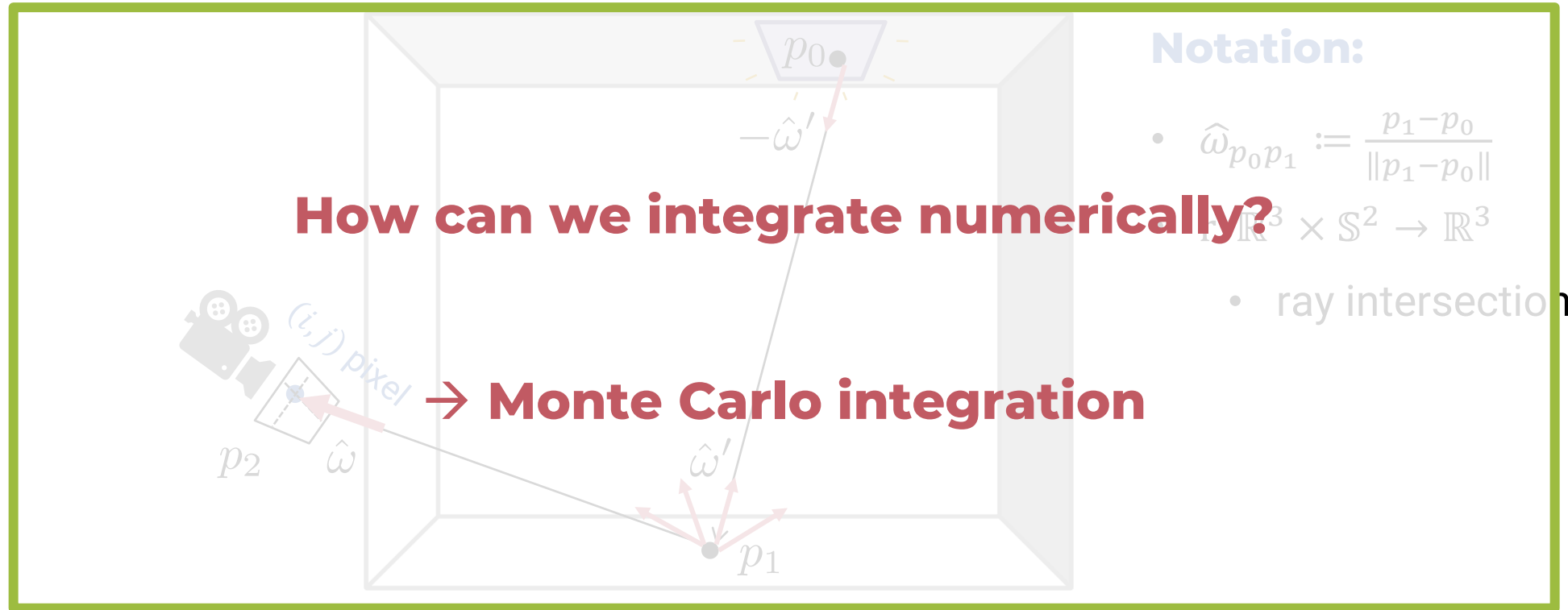
Vector

1. Math: addition, scalar multiplication
2. Bitmap vs. vector
3. (e.g. data structure, programming language)
 - Array, list, ...
 - ~ SIMD



- Random process method
 - Argument uniform dist. Generated

Rendering equation for direct illumination



Final measurement:

$$I^{(i,j)} = \int_{\mathbb{S}} W_e^{(i,j)}(\hat{\omega}) L(p_1, \hat{\omega}) d\hat{\omega}$$

$$L(p_1, \hat{\omega}) = L_e(p_1, \hat{\omega}) + \int_{\mathbb{S}} L_e(p_0, -\hat{\omega}') \rho(p_1, \hat{\omega}', \hat{\omega}) |\hat{n} \cdot \hat{\omega}'| d\hat{\omega}'$$

$\leftarrow p_1 = r(p_2, -\hat{\omega})$
 $p_0 = r(p_1, \hat{\omega}')$