

# Resolving Concurrency in Group Ratcheting Protocols

Secure Messaging Summit 2020

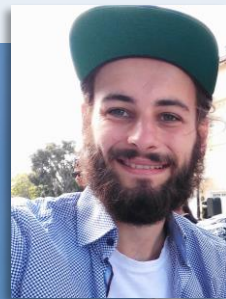
2020-09-03

**Cryptography Group**  
**New York University**

Alexander Bienstock, Yevgeniy Dodis,

**Horst Görtz Institute for IT Security**  
**Chair for Network and Data Security**  
**Ruhr University Bochum**

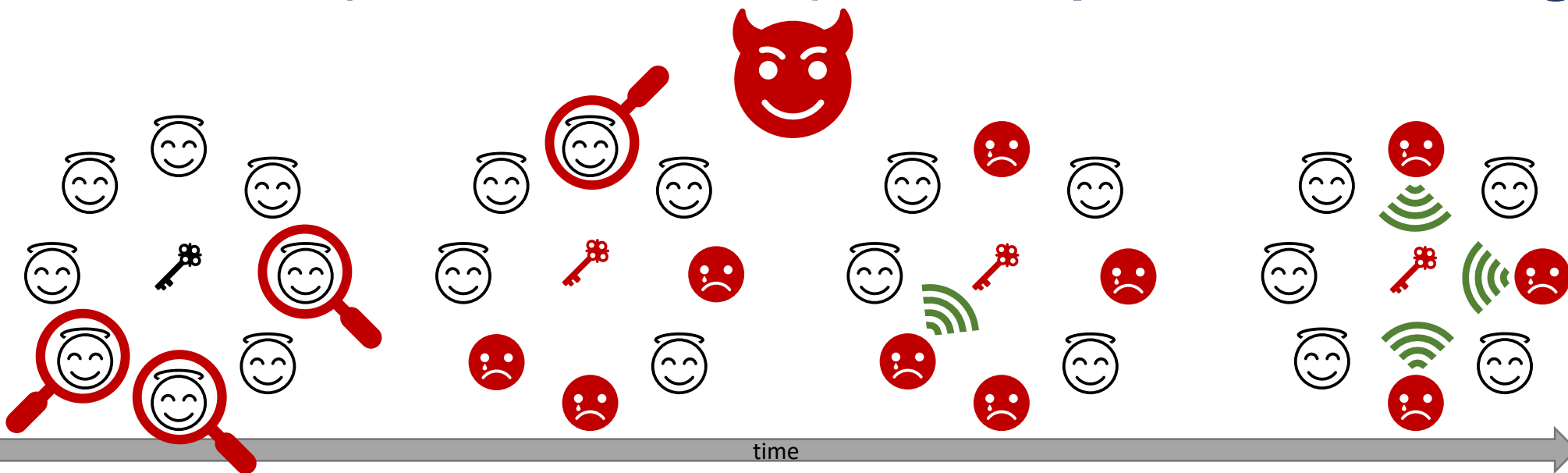
Paul Rösler



**RUB**



# (Concurrent) Group Ratcheting



- Group computes joint keys
- Exposure of local state temporarily
  - Long-term sessions, mobile devices etc.
  - Leaks group key until all states recovered

- Recovery:
  - Generate new secrets
  - Share public values

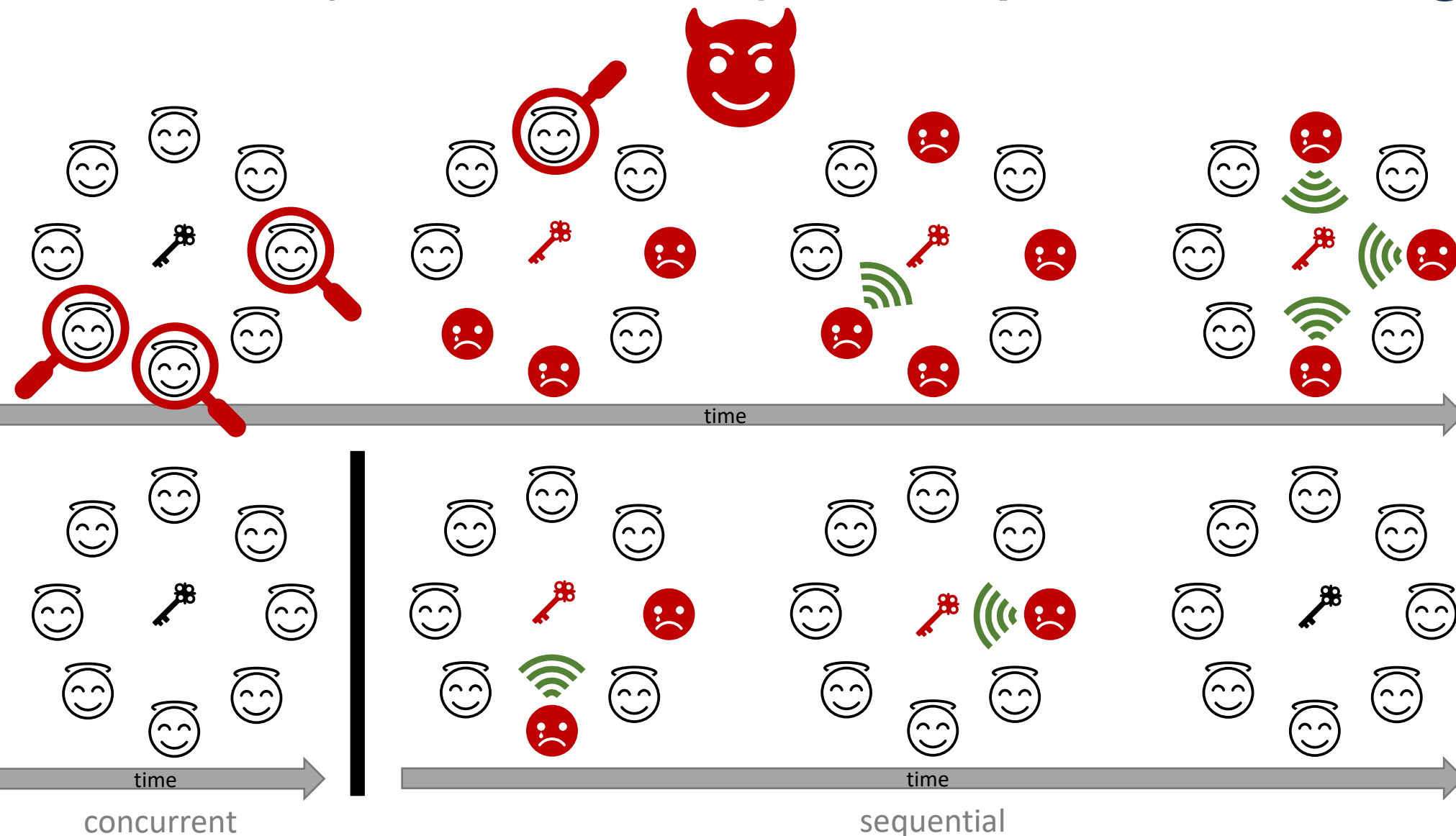
- Concurrent recovery

- Speedup




- Merge recoveries

Here: one group, concurrent users.  
[CHK'19]: Many groups, sequential users.

# (Concurrent) Group Ratcheting



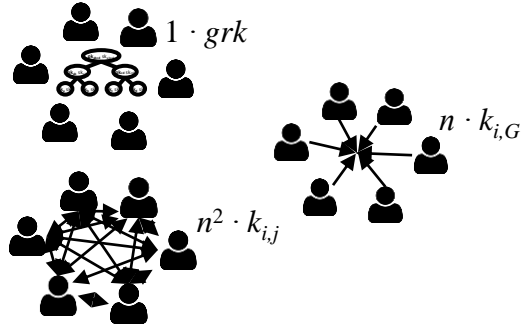
Target:

1. Post-Compromise Security 
2. Small shares 
3. Concurrency 

Otherwise:

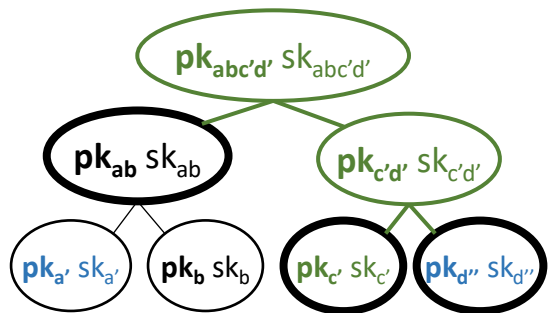
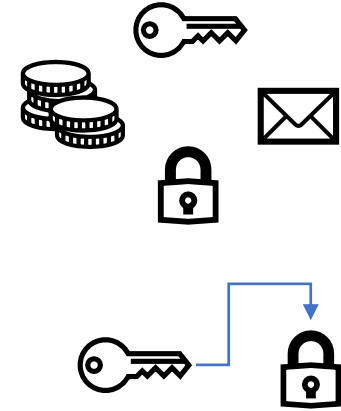
- Slow recovery from exposures
  - Consensus required
- Inapplicable to decentralized networks

# Agenda



Previous Work:  
What's the  
Problem?

Lower Bound:  
What's the minimal  
overhead?



Upper Bound:  
Almost optimal  
construction

Open Questions ...

$\Omega(t)$  vs.  $O(t \cdot (1 + \log(n/t)))$ ?  
NIKE?  
PCS-Delay?  
Forward-secrecy?  
Application to MLS

# Previous Work: What's the Problem?

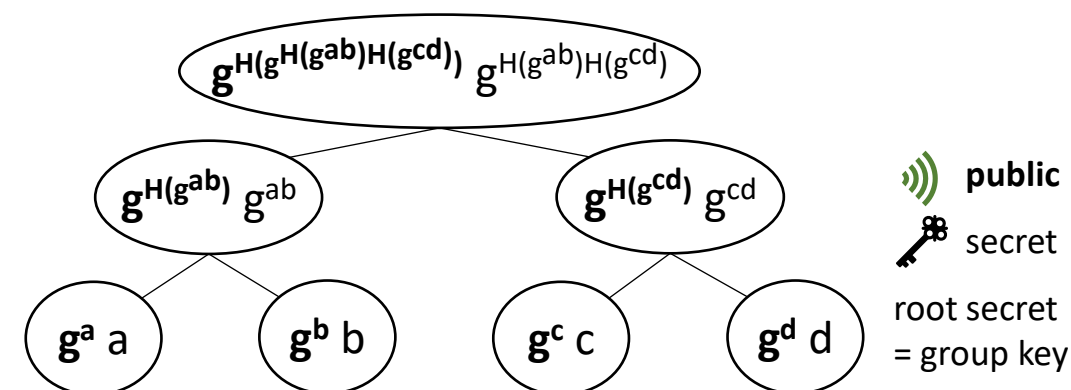
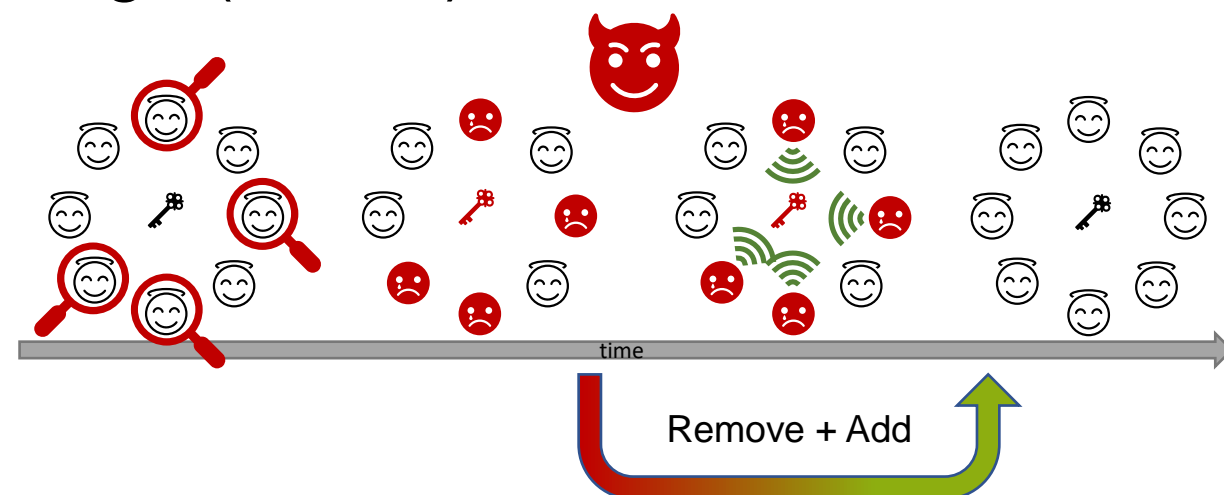
- Essentially: Dynamic group key exchange (DGKE)

- Expose = Unwanted member
- Recovery = Remove + Add (R&A)

- Many protocols from '80s – '00ers
- Tree-based DGKE best suited for asynchronous settings:

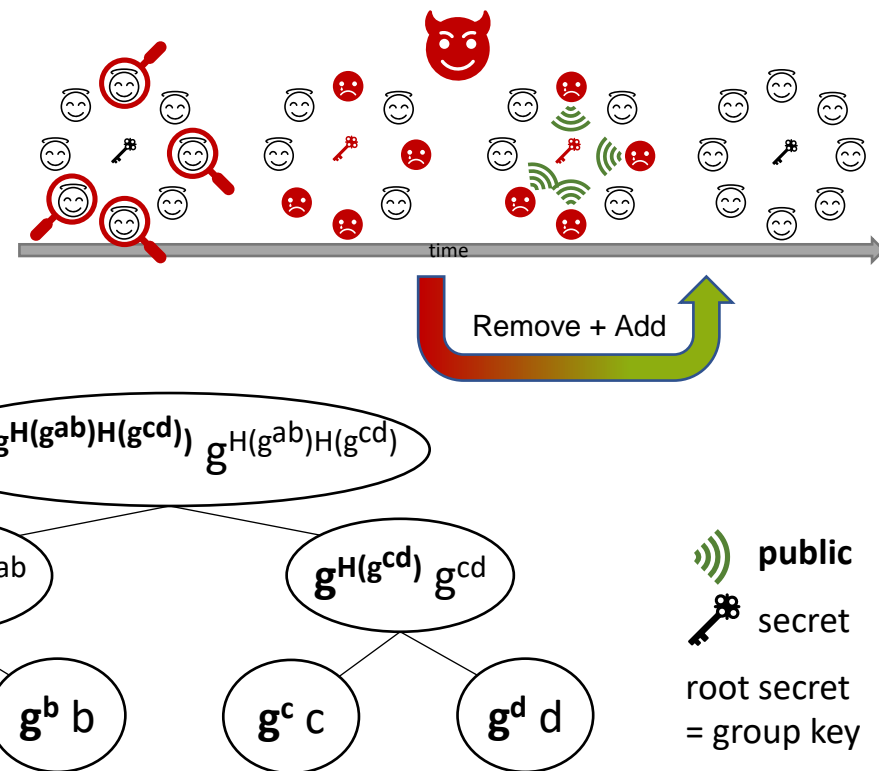
- Little communication for R&A:  $O(\log n)$
- (Almost) non-interactive for R&A

→ First known DH-tree-based protocol [KPT'04]



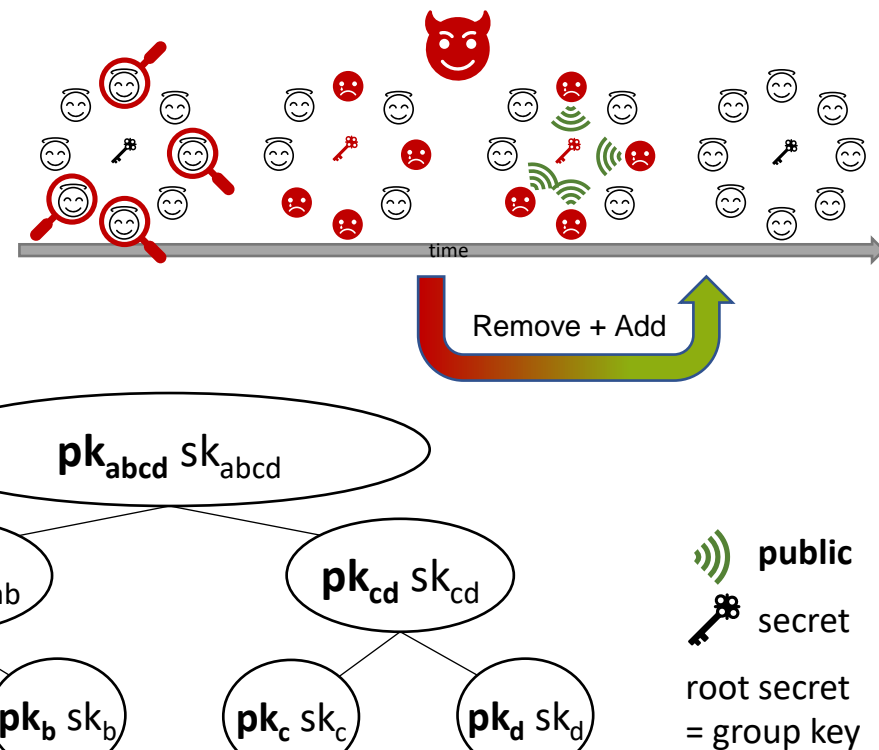
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  - Merge R&A [CCGMM'18]



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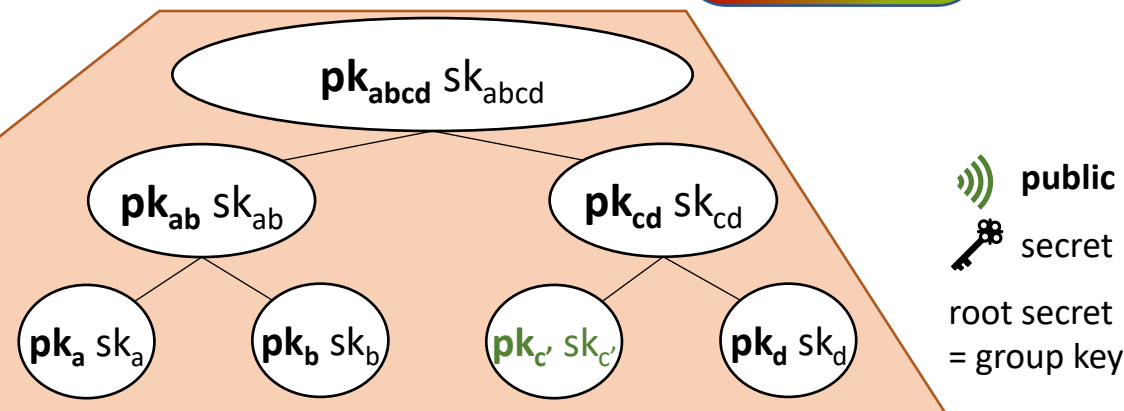
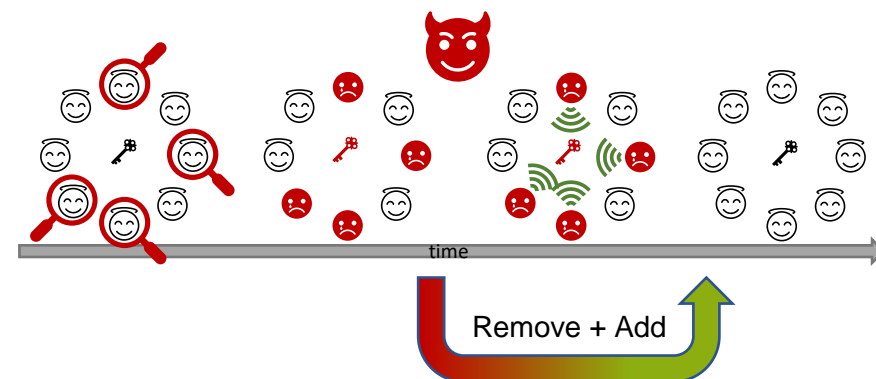
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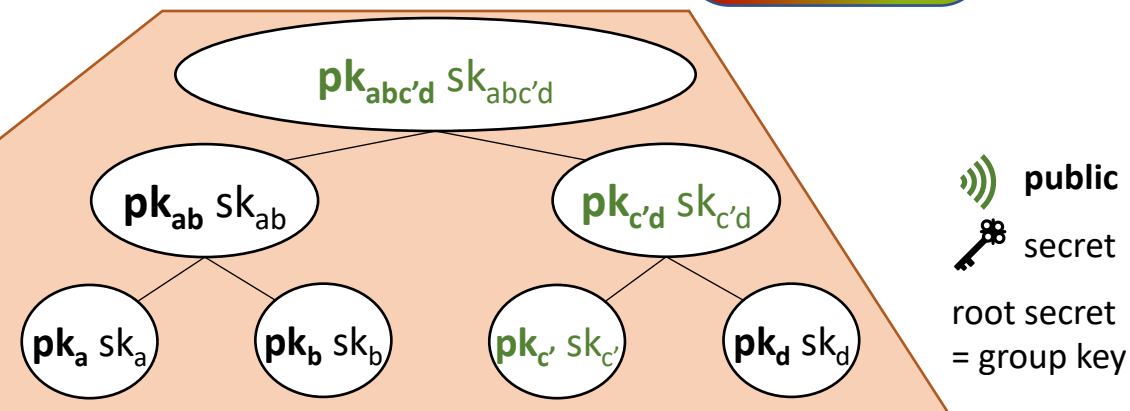
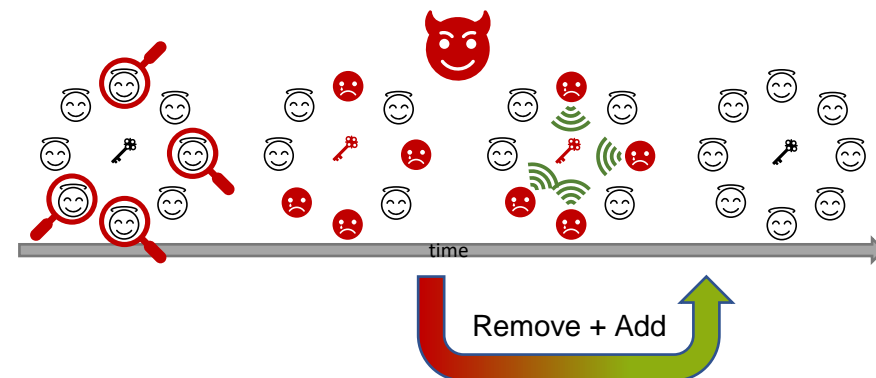
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- Recovery: sample  $x_{c'}$ ,  $sk_{c'} = x_{c'}$ ,  $pk_{c'} = \text{gen}(sk_{c'})$ ,  $x_{c'd} = H(x_{c'})$ ,  $\text{enc}(pk_d, x_{c'd})$ ,  $sk_{c'd} = x_{c'd}$ , ...



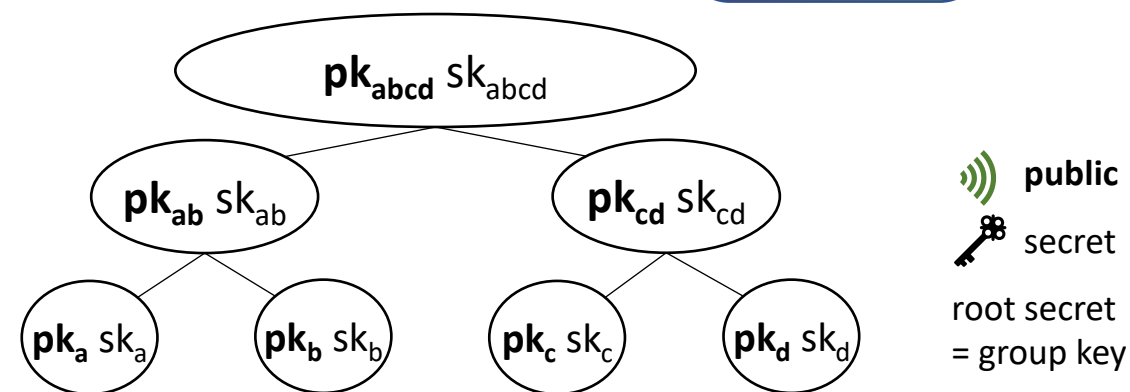
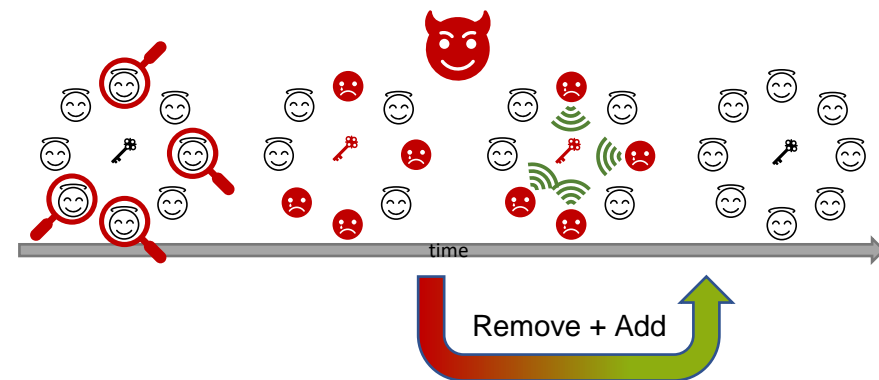
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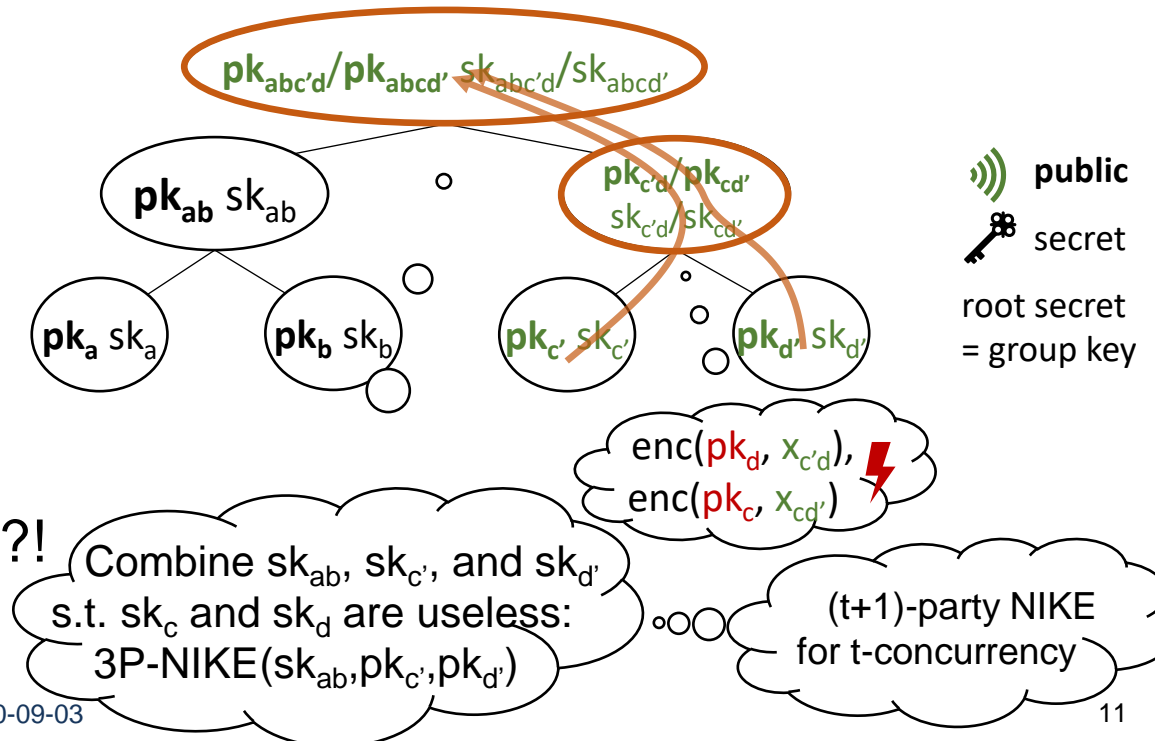
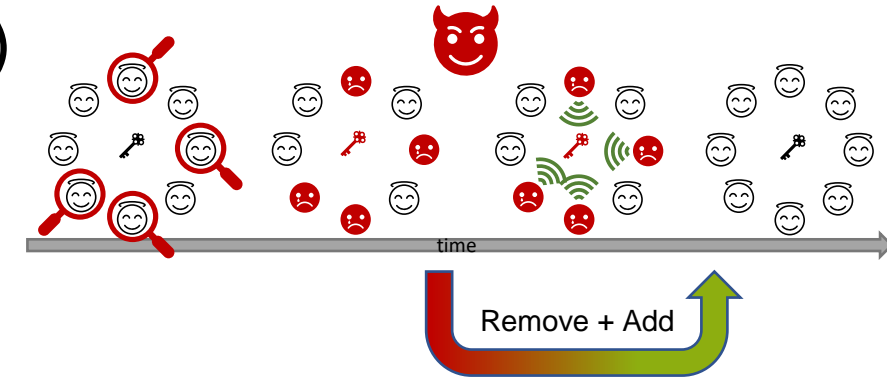
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- No concurrency

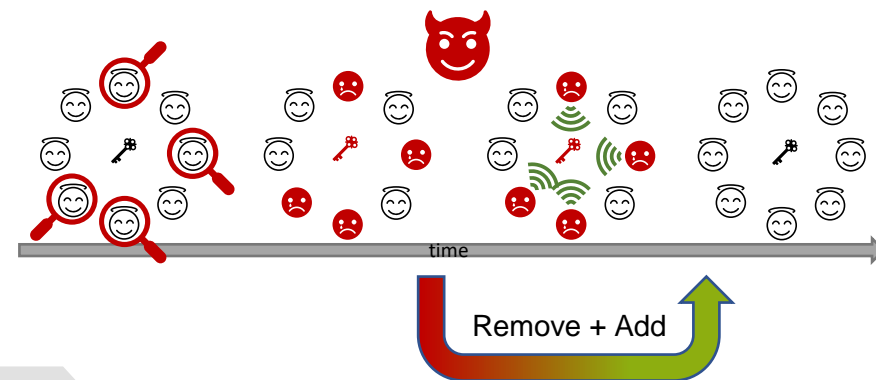
- Intersection of concurrently updated paths  
→ Merging under PCS without multiparty-NIKE?!



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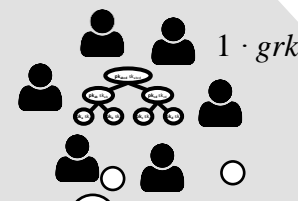
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PCS	Overhead	Concurrency
✓	$O(\log n)$	✗

MLSv9 worst-case:

(✓)	$O(n)$	(✓)
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- Rejects concurrent path updates
- Degrades to “n-tree”

Merge DH Tree [Weidner'19]:

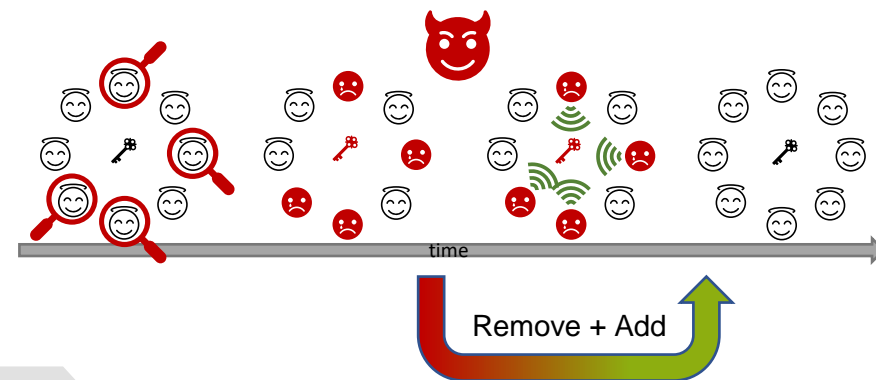
(✗)	$O(\log n)$	✓
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- New DH paths are merged
- Recovers only one user at a time

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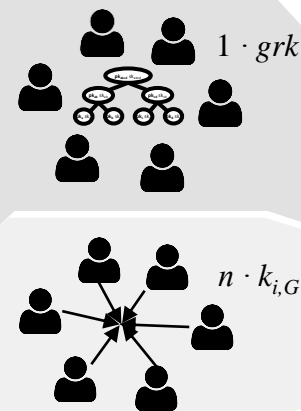
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- Real-World

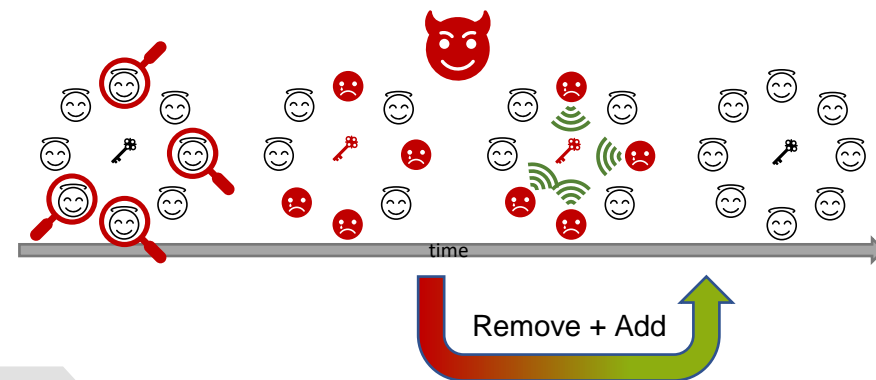
- Forward-secure hash chain [WhatsApp]

PCS	Overhead	Concurrency
✓	$O(\log n)$	✗
✗	$O(1)$	✓

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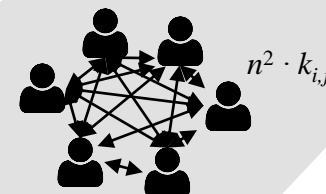
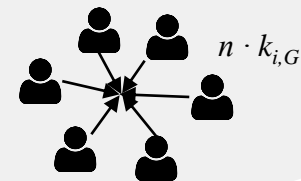
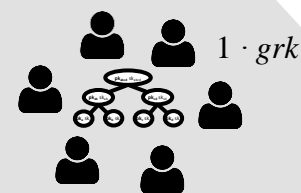
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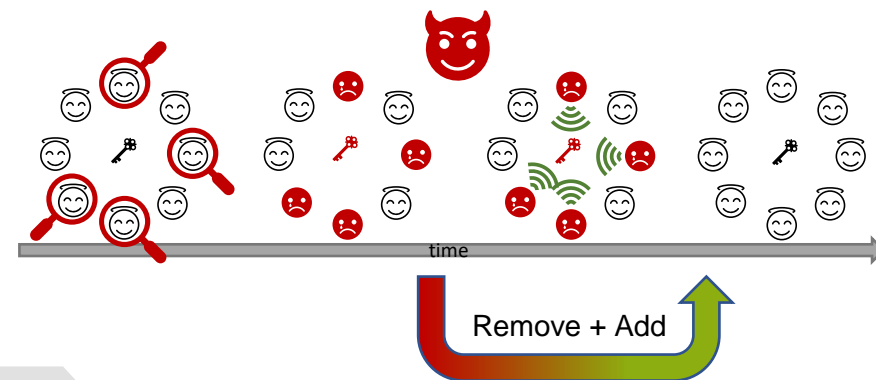
- Forward-secure hash chain [WhatsApp]
- Parallel pair-wise communication [Signal]

PCS	Overhead	Concurrency
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✗	$O(1)$	✓
✓	$O(n)$	✓

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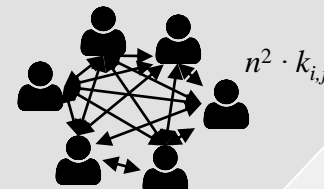
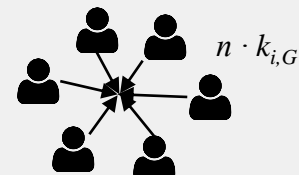
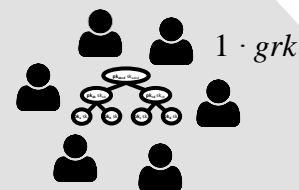
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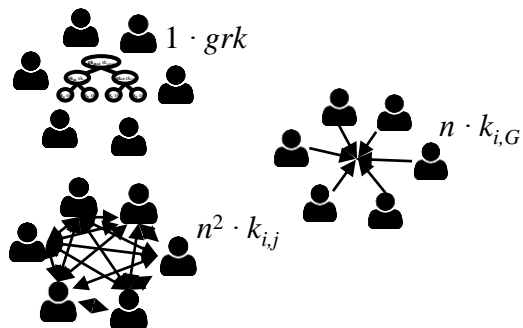
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PCS	Overhead	Concurrency
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✗	$O(1)$	✓
✓	$O(n)$	✓
✓	?	✓

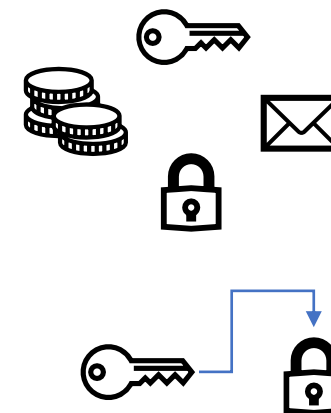


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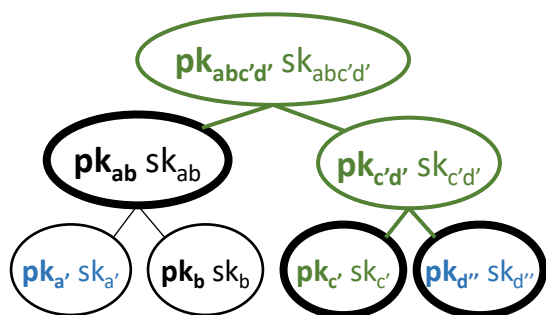


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What's the  
Problem?

Lower Bound:  
What's the minimal  
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PCS & Concurrency & Small overhead  
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PCS & Concurrency & Small overhead



Upper Bound:  
Almost optimal  
construction

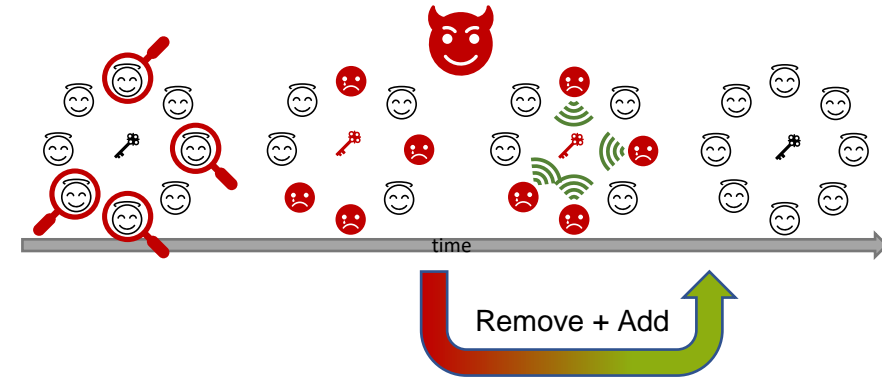
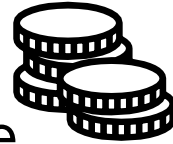
Open Questions ...

$\Omega(t)$  vs.  $O(t \cdot (1 + \log(n/t)))$ ?  
NIKE?  
PCS-Delay?  
Forward-secretity?  
Application to MLS

# Lower Bound: What's the minimal overhead?

- Symbolic model

- Variables are symbols without bit representation or algebraic structure
- Algorithms follow “transition rules”
- Round based execution



- **Fixed set of allowed building blocks** (for constructions with minimal overhead under PCS)

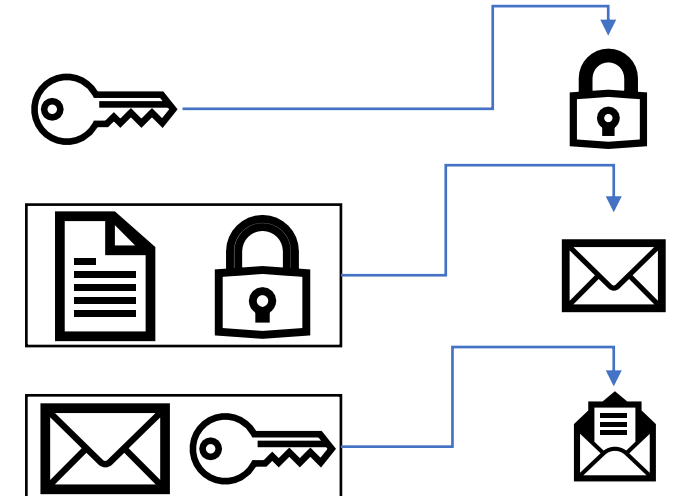
## Our “transition rules” model:

- (Dual) pseudo-random functions
- Key-updatable public key encryption (see [BRV20])
- Broadcast encryption

→ *More* than what previous constructions used

- Inspired by [MP04]:

# Lower bound $O(\log n)$ for forward-secure DGKE



# Lower Bound:

## What's the minimal overhead?

i-2 Exposure:

- No (shared) secrets

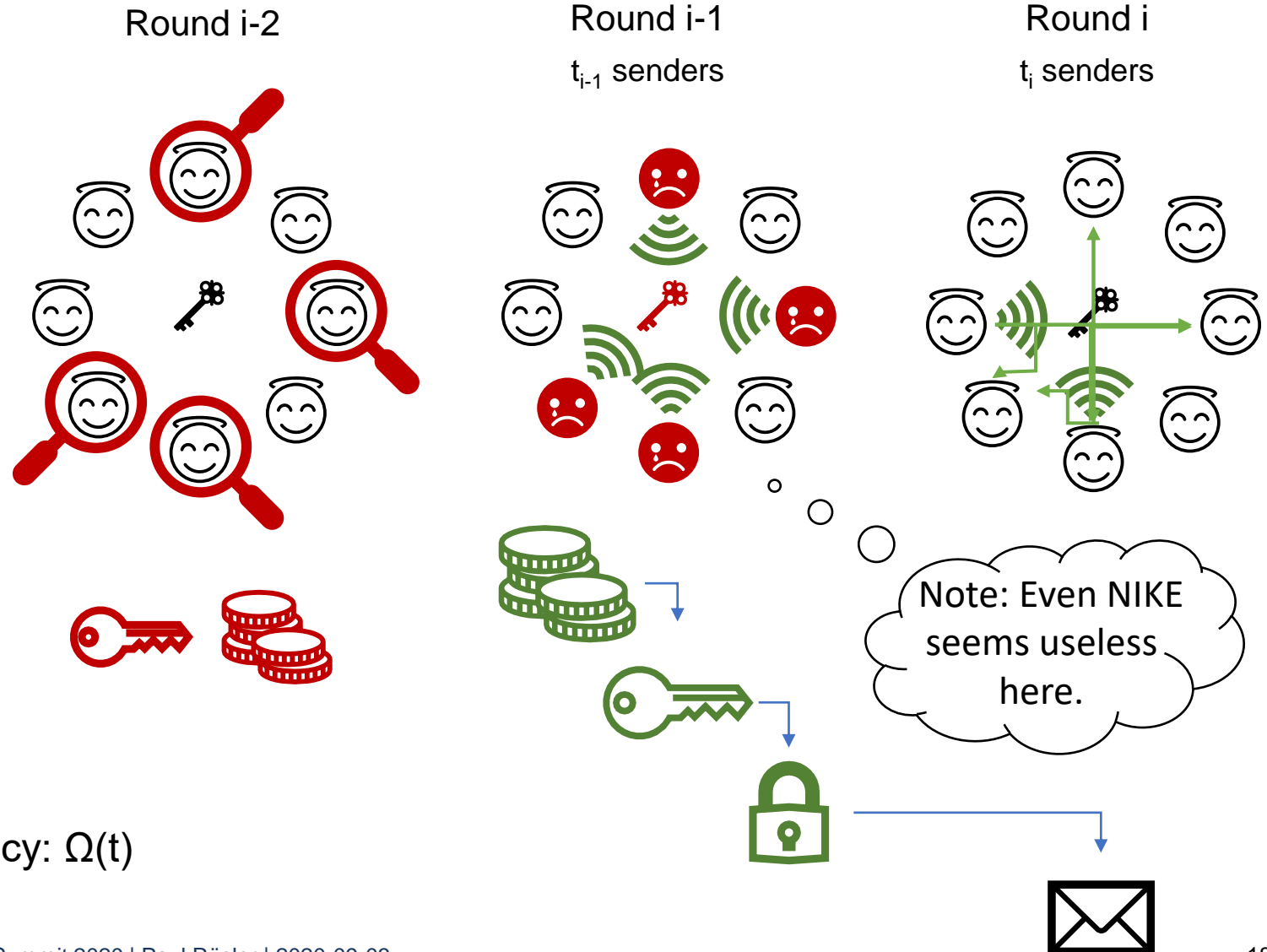
i-1 Recovery 1:

- Still no (shared) secrets
  - Sampling of new secrets
  - Sharing of derived values
- Still no (shared) secrets
- Though, public values of shared secrets

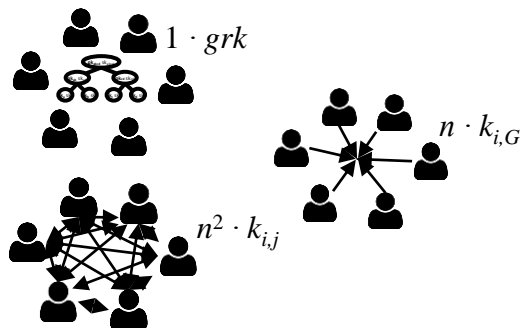
i Recovery 2:

- Respond to public values
  - All senders must respond as they cannot coordinate
- Each sender sends  $\geq (t_{i-1}-1)$  responses
- $\geq (t_{i-1}-1) \cdot t_i$  shares in round i

⇒ Overhead per recovery under t-concurrency:  $\Omega(t)$

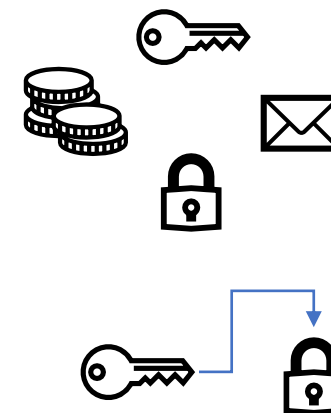


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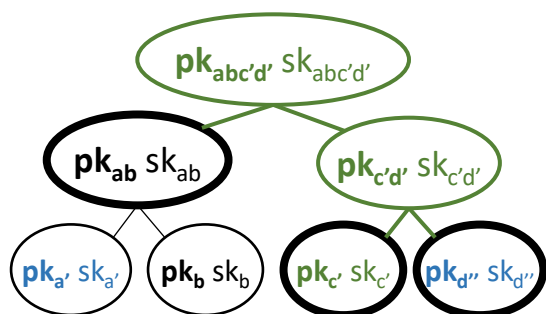


Realistic symbolic model:  
No coordination + PCS  
 $\Rightarrow \Omega(t)$

Upper Bound:  
Almost optimal construction

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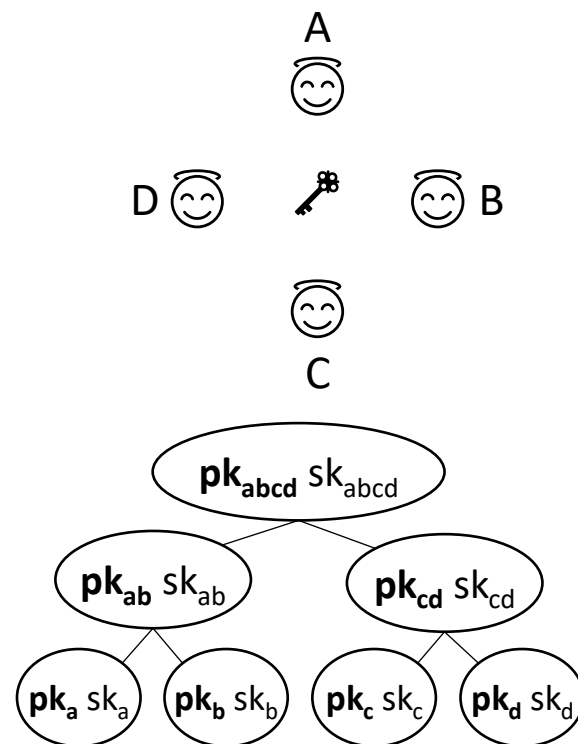
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PCS & Concurrency & Small overhead  
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# Upper Bound: Almost optimal construction

Key tree (with updatable KEM)



public

secret

root secret  
= group key

# Upper Bound: Almost optimal construction

Key tree (with updatable KEM)

i-2 Exposure:

- Paths of c and d *public*:  
 $sk_c, sk_d, sk_{cd}, sk_{abcd}$

i-1 Recovery 1:

- Generate and share new leaf key pairs:  
 $(sk_{c'}, pk_{c'}), (sk_{d'}, pk_{d'})$

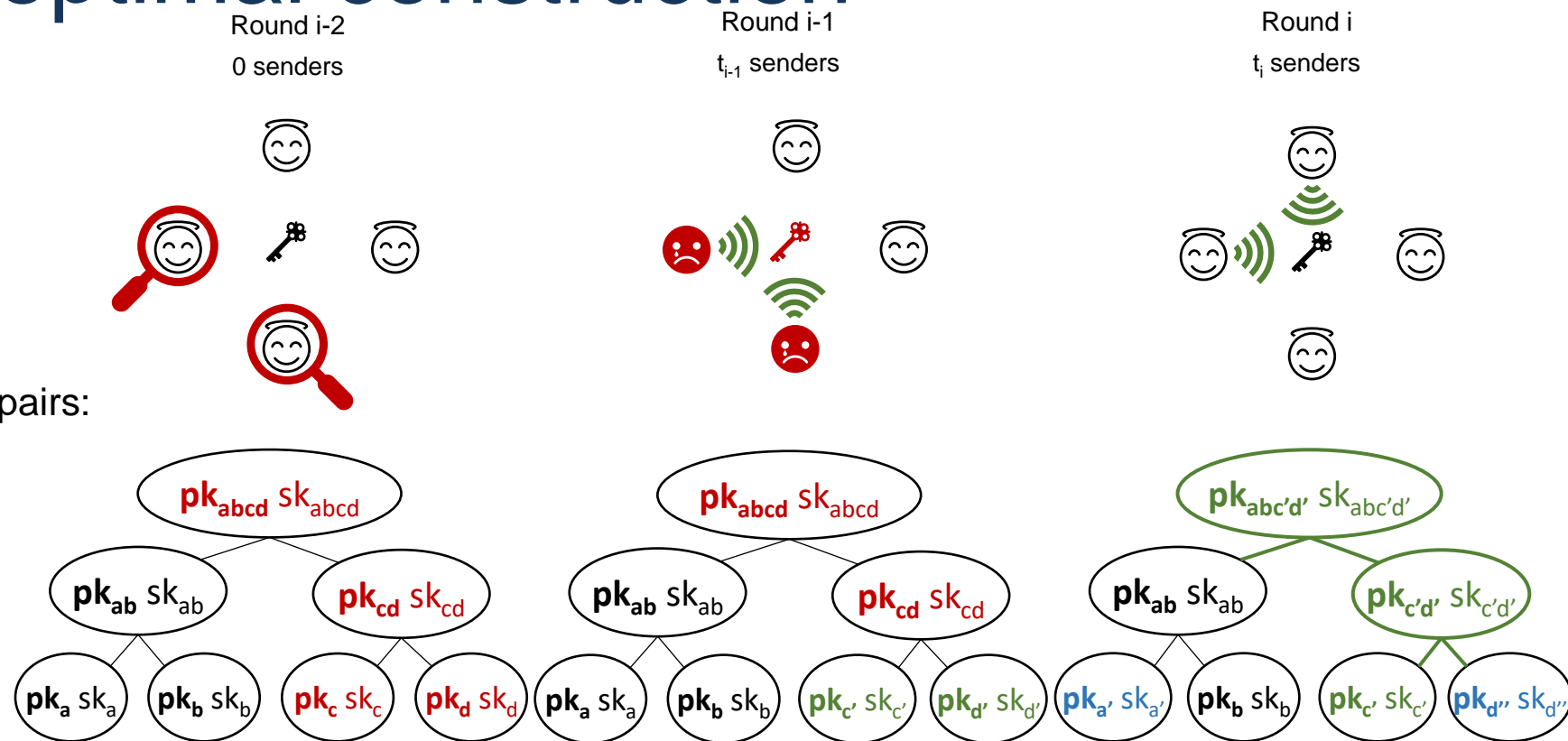
i Recovery 2:

a) See Recovery 1

- Each sender generates new paths for previous senders:

b) Sample  $x_{c'd'}$

c) Derive  $sk_{c'd'} = x_{c'd'}$ ,  $x_{abc'd'} = H(x_{c'd'})$ ,  $sk_{abc'd'} = x_{abc'd'}$ ,  $pk_{c'd'} = \text{gen}(sk_{c'd'})$ ,  $pk_{abc'd'} = \text{gen}(sk_{abc'd'})$



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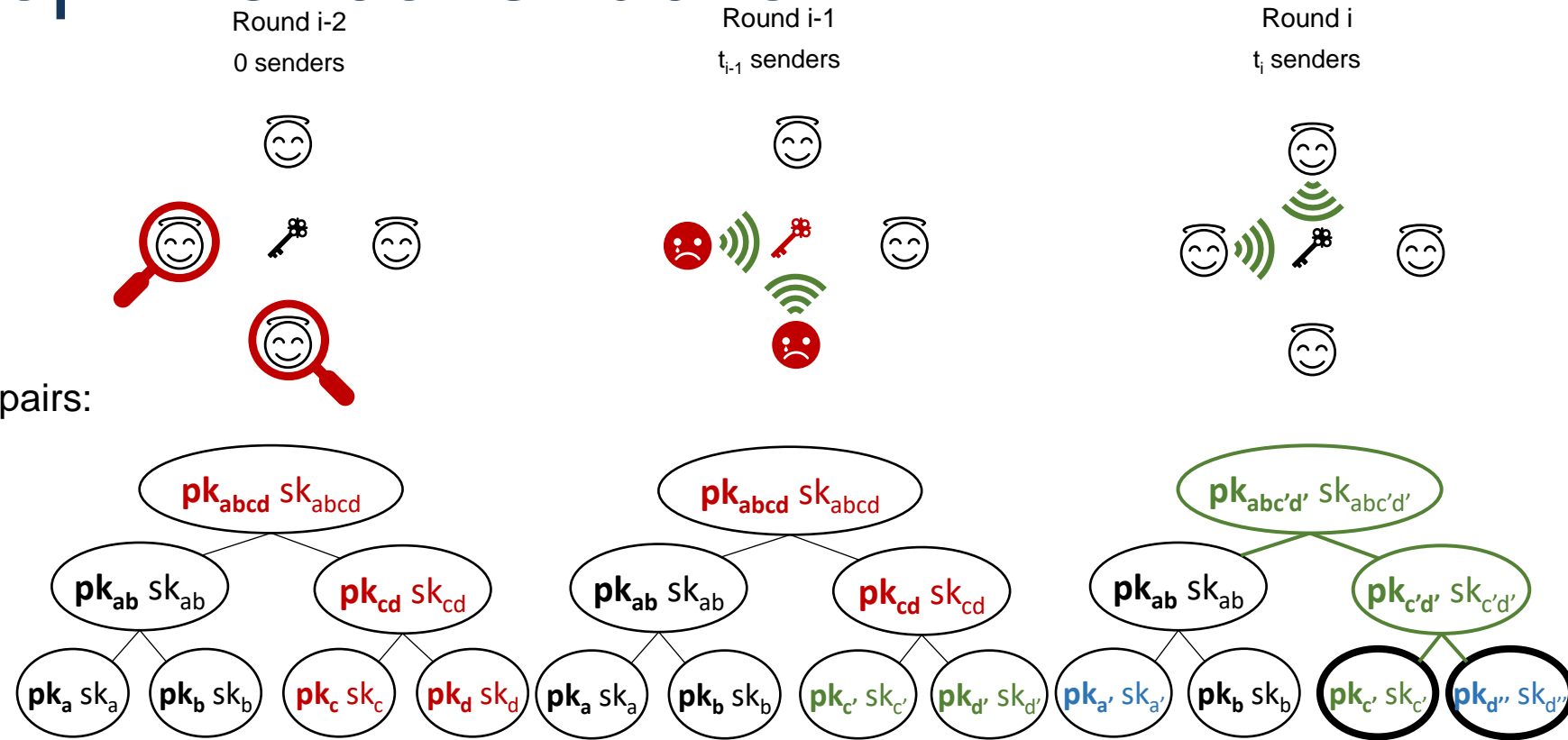
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d) Send  $\text{enc}(pk_{c'}, x_{c'd'})$ ,  $\text{enc}(pk_{d'}, x_{c'd'})$

→ **Number of leafs:**  $t_{i-1}$



root secret  
= group key



# Upper Bound: Almost optimal construction

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### i-2 Exposure:

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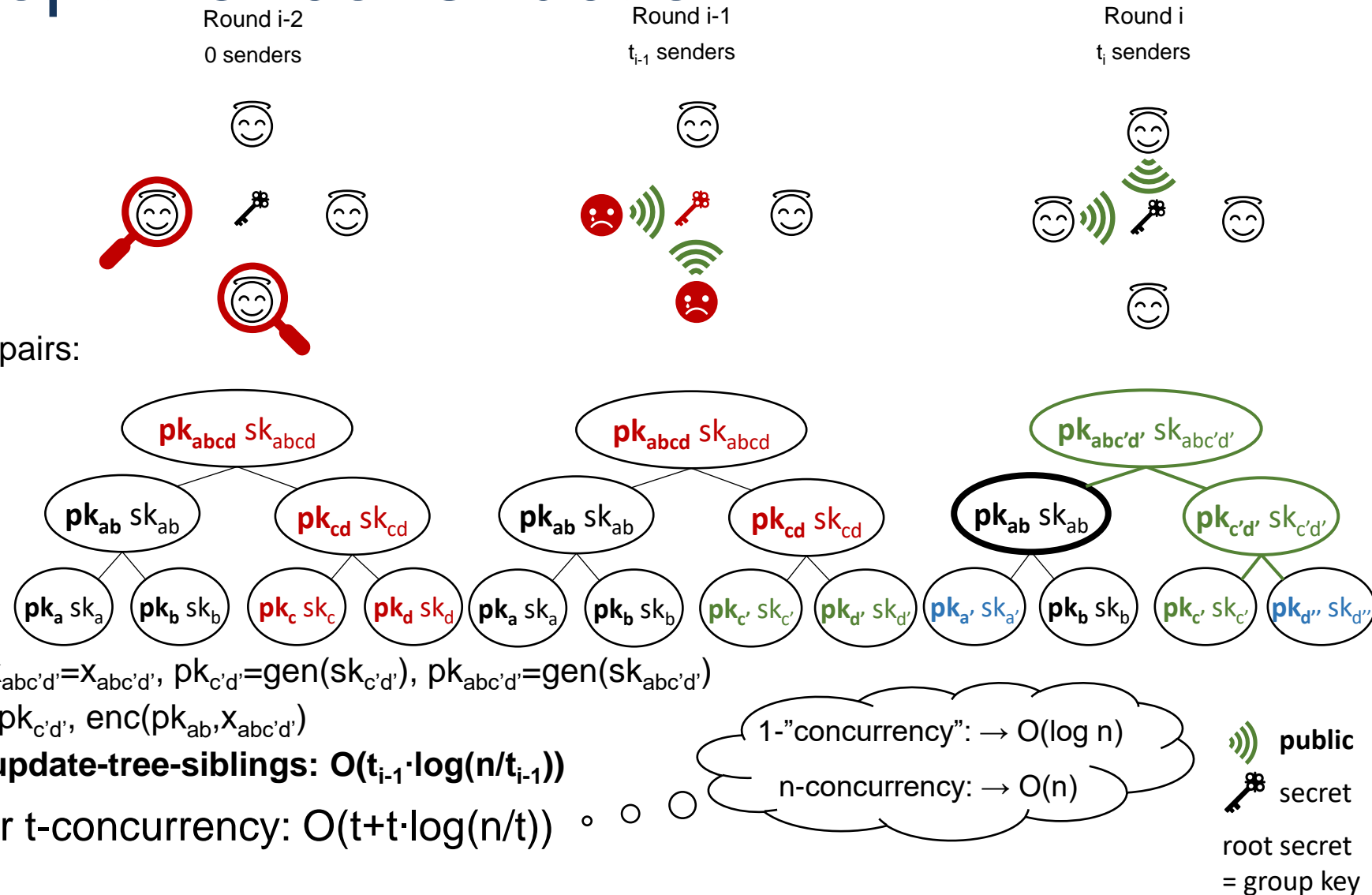
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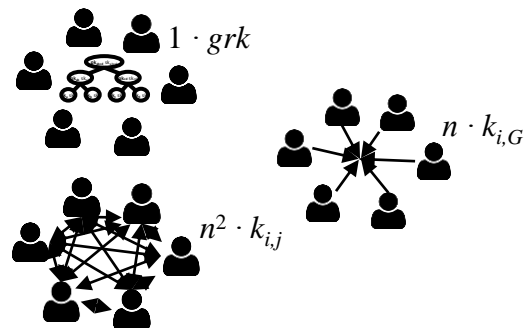
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→ Number of leafs:  $t_{i-1}$ , **number of update-tree-siblings:  $O(t_{i-1} \cdot \log(n/t_{i-1}))$**

⇒ Overhead per recovery under t-concurrency:  $O(t + t \cdot \log(n/t))$

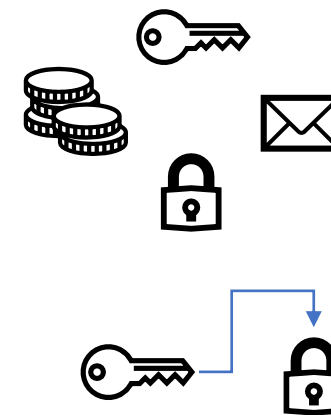


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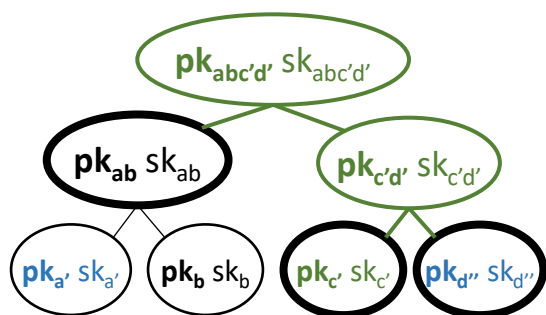


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Two-step recovery  
 $\Rightarrow O(t \cdot (1 + \log(n/t)))$

@roeslpa

Full details & formal proofs online *soonish*