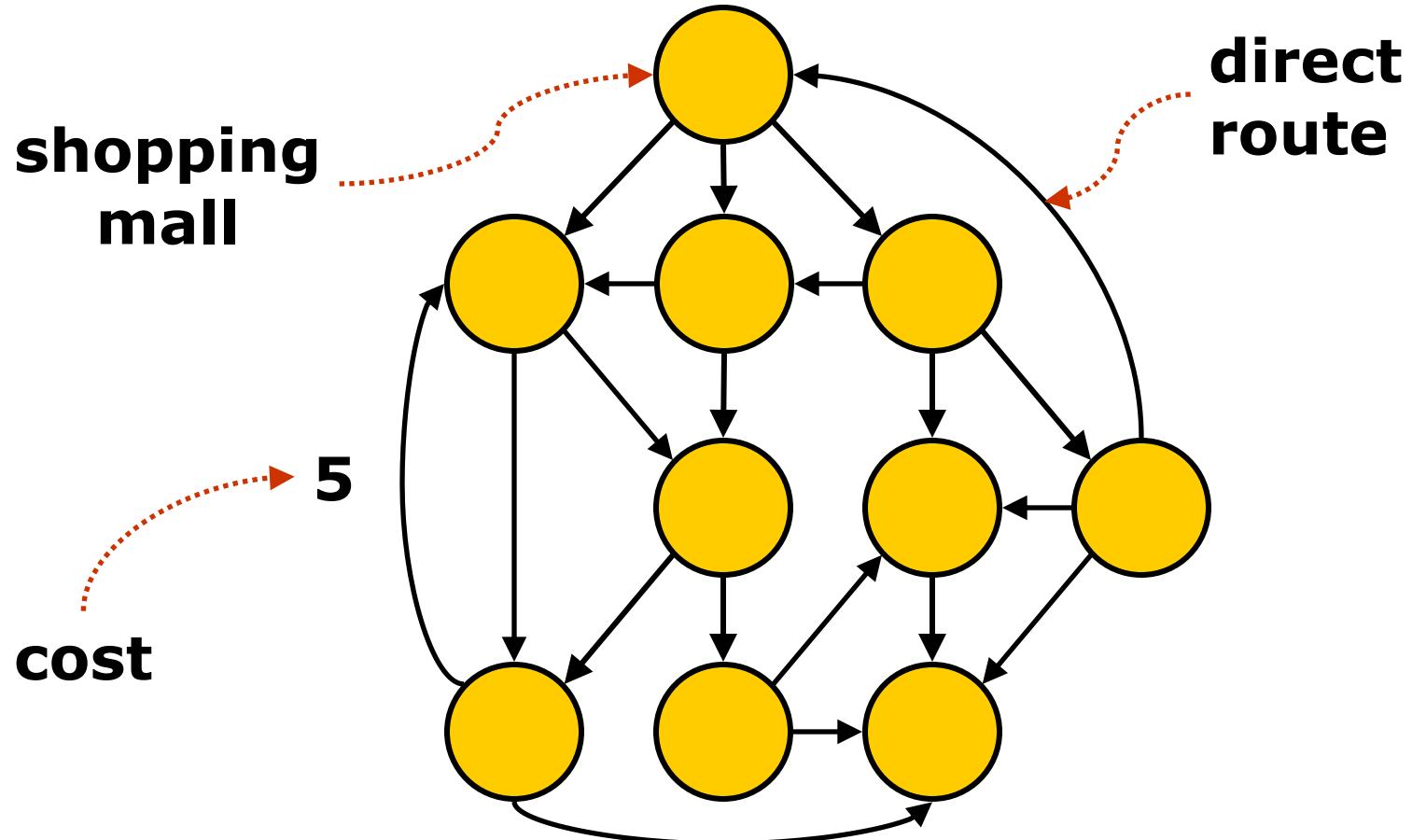

CS2040 Data Structures and Algorithms

Lecture Note #12

Graphs

Part 3: Shortest Path Algorithms

Travel Planning



Question

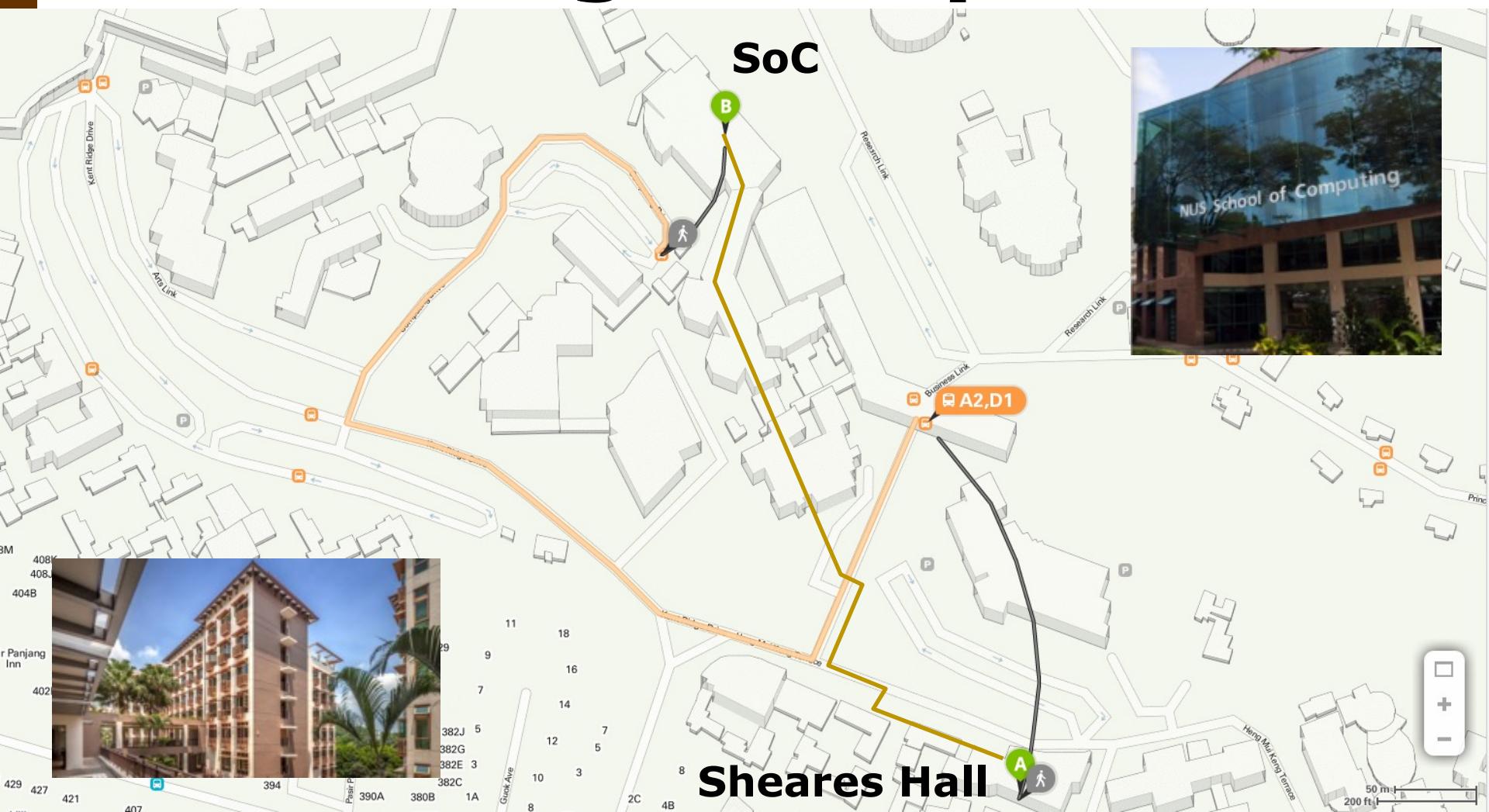
- What is the shortest way to travel between A and B?

“SHORTEST PATH PROBLEM”

- How to minimize the cost of visiting n cities such that we visit each city exactly once, and finishing at the city where we start from?

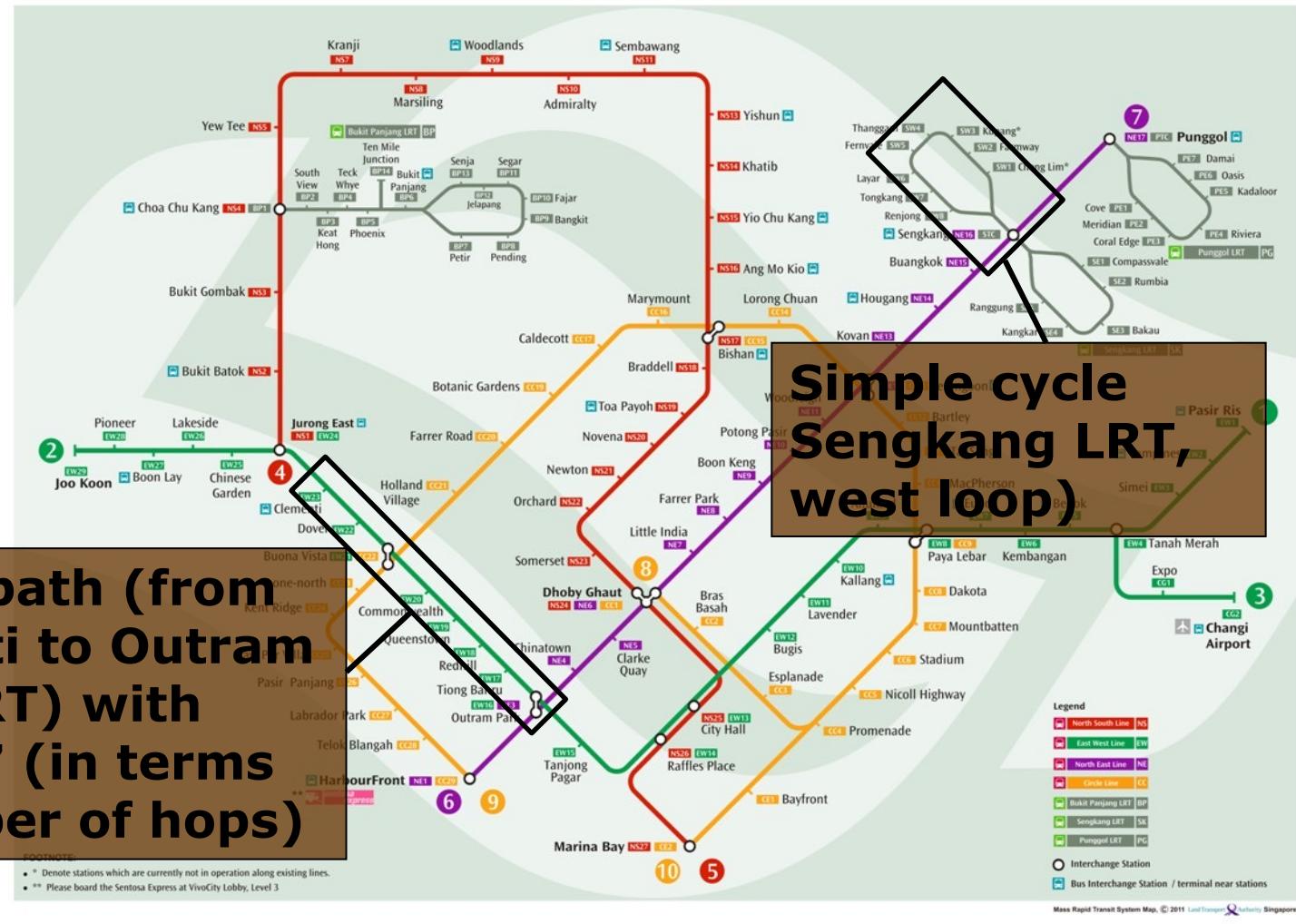
**“TRAVELING SALESMAN PROBLEM
(TSP)”**

Motivating Example

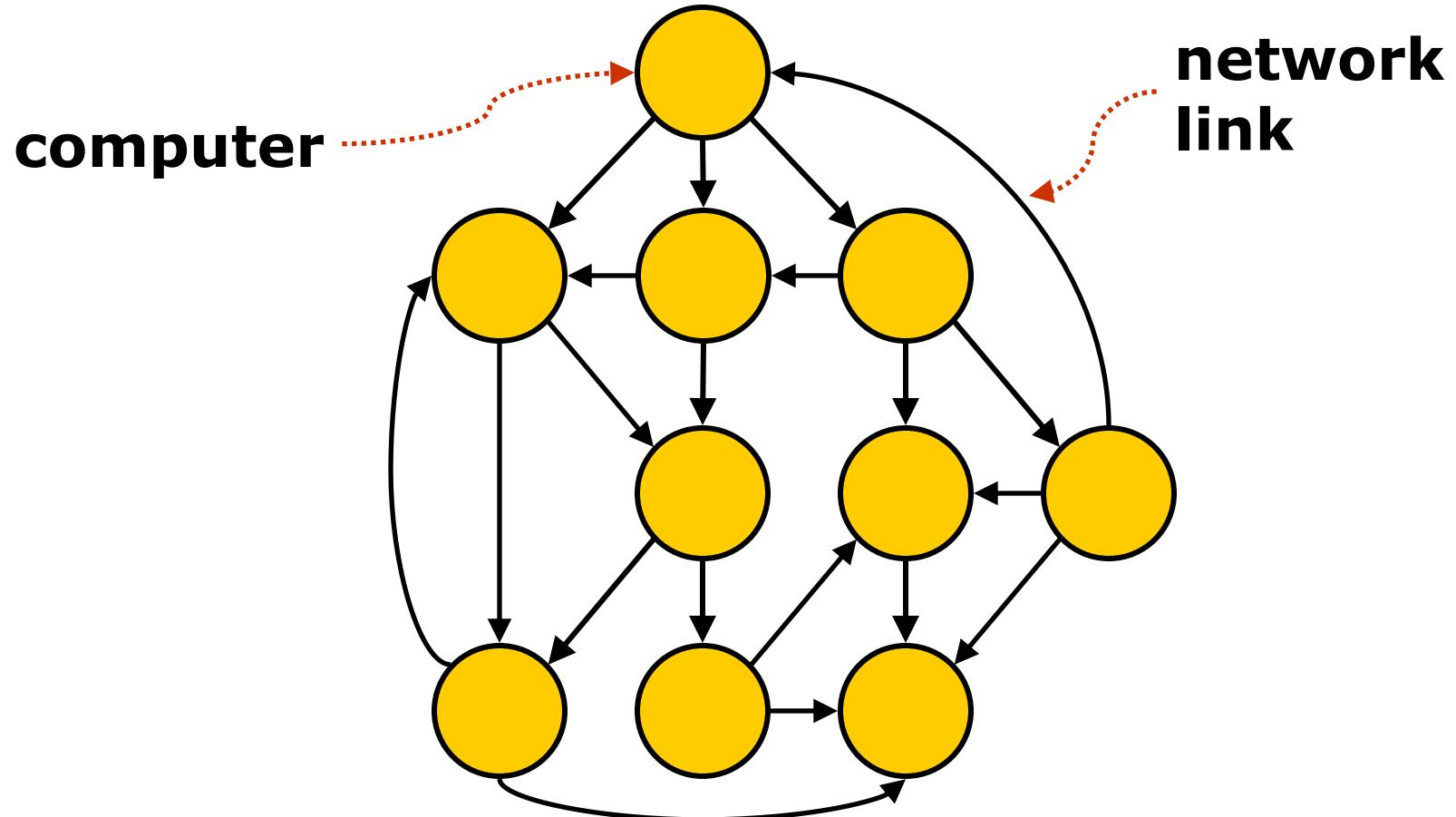


Transportation Network

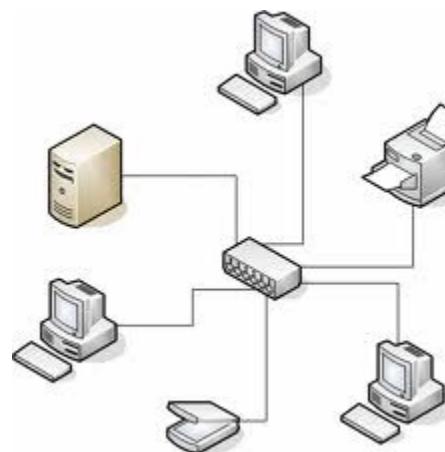
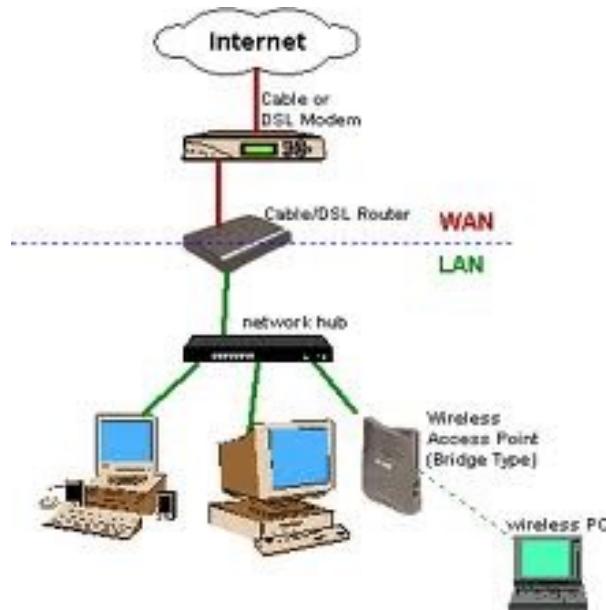
MRT & LRT System map



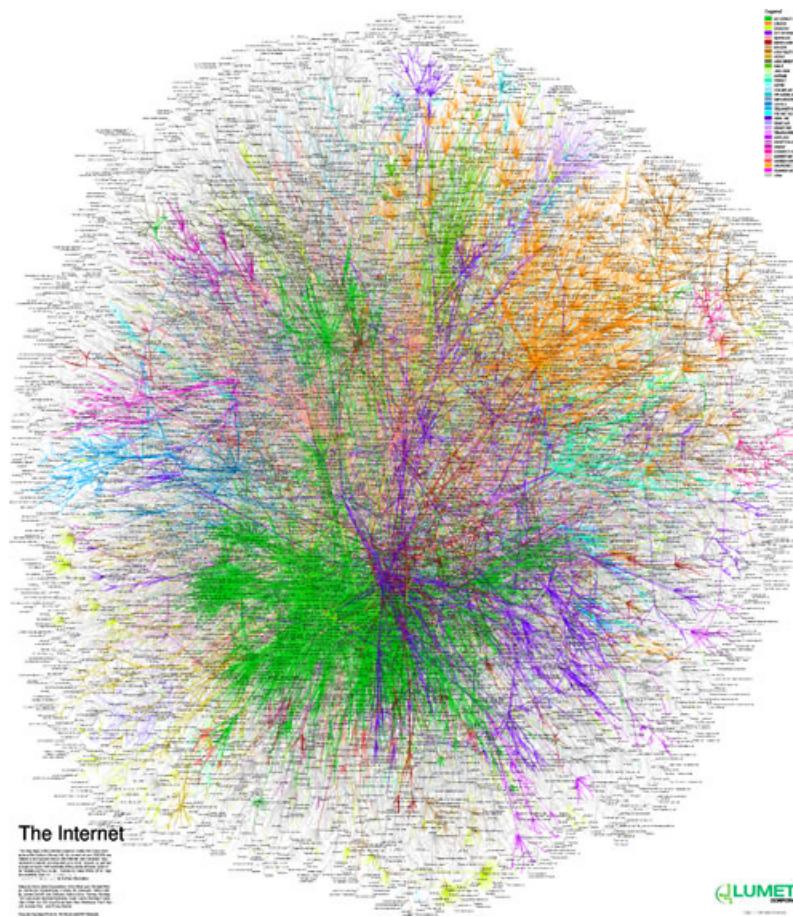
Internet



Internet / Computer Networks



Internet / Computer Networks



Question

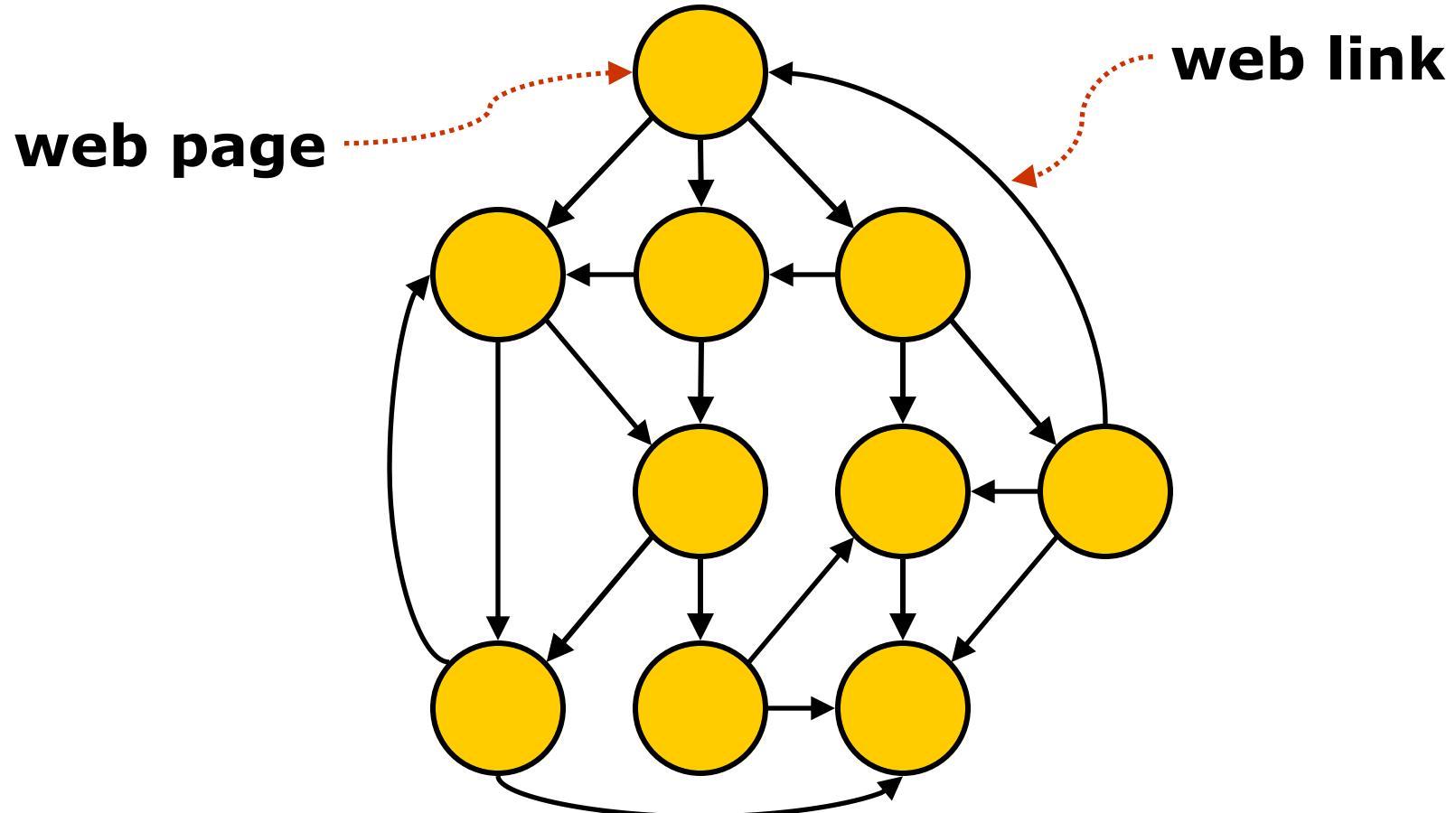
- What is the shortest route to send a packet from A to B?

“SHORTEST PATH PROBLEM”

Communication Network



The Web



Social Networks (1)



- Facebook, Instagram, etc.
- “Six-degrees of separation”
- How is any actor connected to Kevin Bacon (“The Oracle of Bacon”), e.g.:

Chris Hemsworth has a Bacon number of 2. [Find a different link](#)

Chris Hemsworth
was in
Red Dawn
with
Michael Beach
was in
Patriots Day
with
Kevin Bacon

[Kevin Bacon](#) to [Chris Hemsworth](#) [Find link](#) [More options >>](#)

Angelina Jolie has a Bacon number of 2. [Find a different link](#)

Angelina Jolie
was in
Sky Captain and the World of Tomorrow
with
Giovanni Ribisi
was in
She's Having a Baby
with
Kevin Bacon

[Kevin Bacon](#) to [Angelina Jolie](#) [Find link](#) [More options >>](#)

Brad Pitt has a Bacon number of 1. [Find a different link](#)

Brad Pitt
was in
Beyond All Boundaries
with
Kevin Bacon

[Kevin Bacon](#) to [Brad Pitt](#) [Find link](#) [More options >>](#)

Mathematician
Paul
Erdős



Social Networks (2)

- Co-authors of scientific publications also form a social network, e.g., Erdős Number:

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MR Erdos Number = 4

Roger Zimmermann	coauthored with	Min-Te Sun	MR3002903
Min-Te Sun	coauthored with	Chih-Wei Yi	MR2366154
Chih-Wei Yi	coauthored with	Foong Frances Yao	MR2725737
Foong Frances Yao	coauthored with	Paul ¹ Erdős	MR0561031

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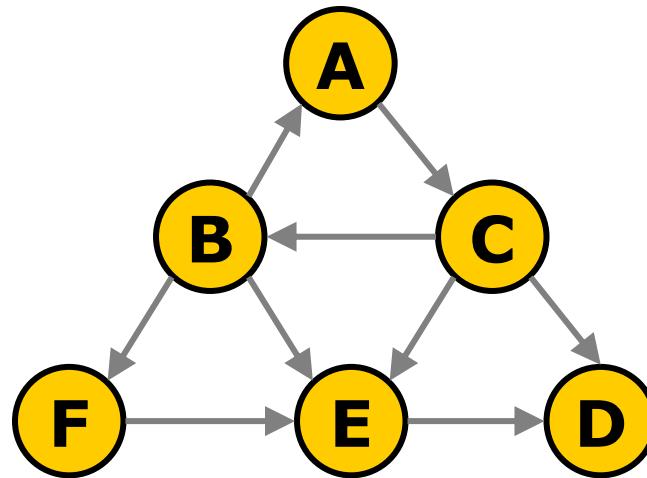


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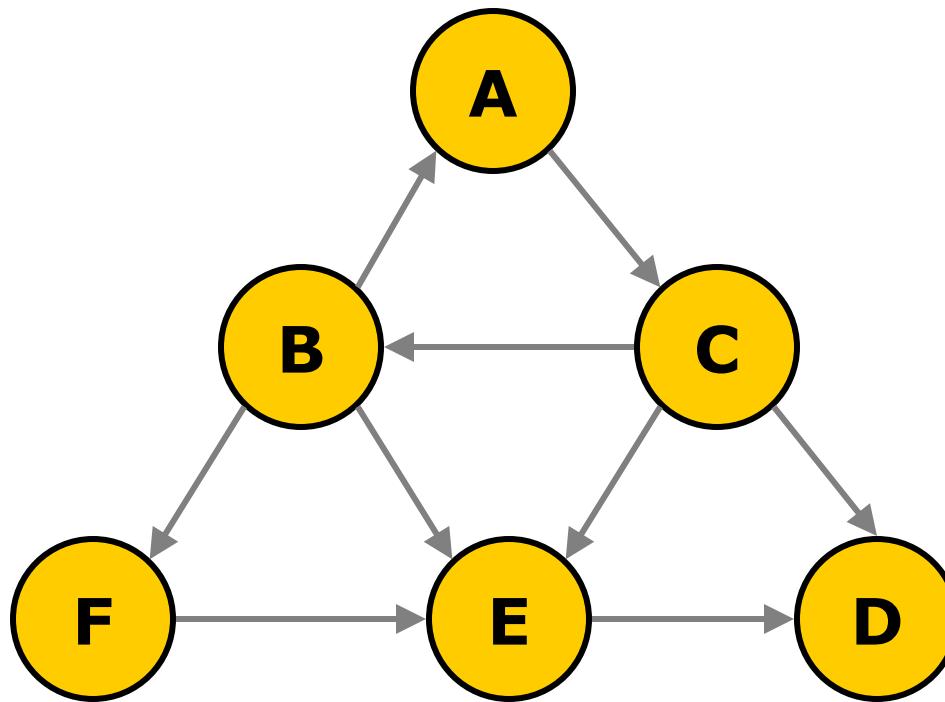
Definition

A path on a graph G is a sequence of vertices $v_0, v_1, v_2, \dots, v_n$ where $(v_i, v_{i+1}) \in E$

The cost of a path is the sum of the cost of all edges in the path.



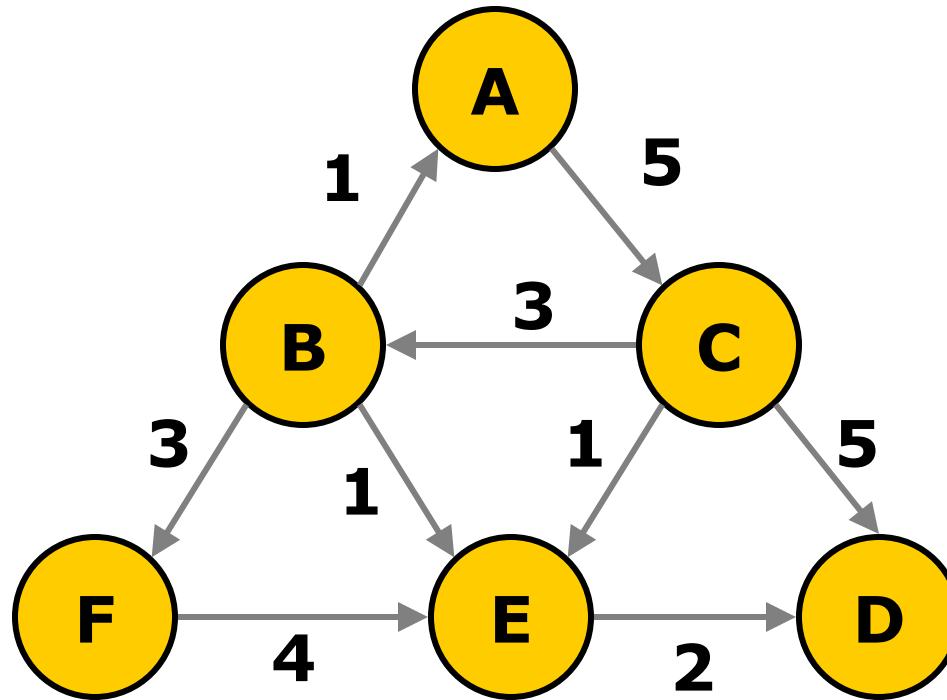
Unweighted shortest path



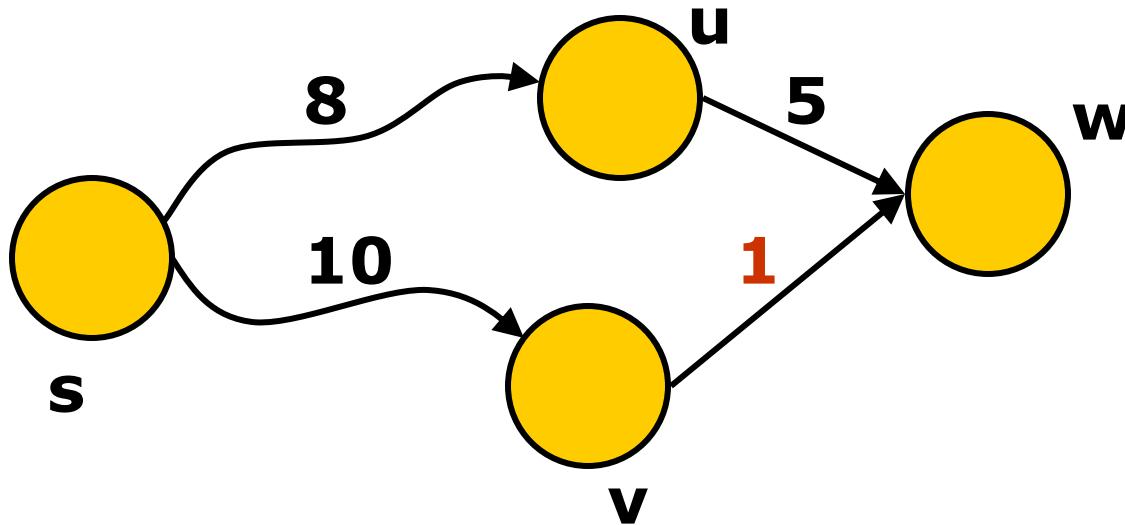
ShortestPath(s)

- Run BFS(s)
 - w.level: shortest distance from s
 - w.parent: shortest path from s

Positive weighted shortest path

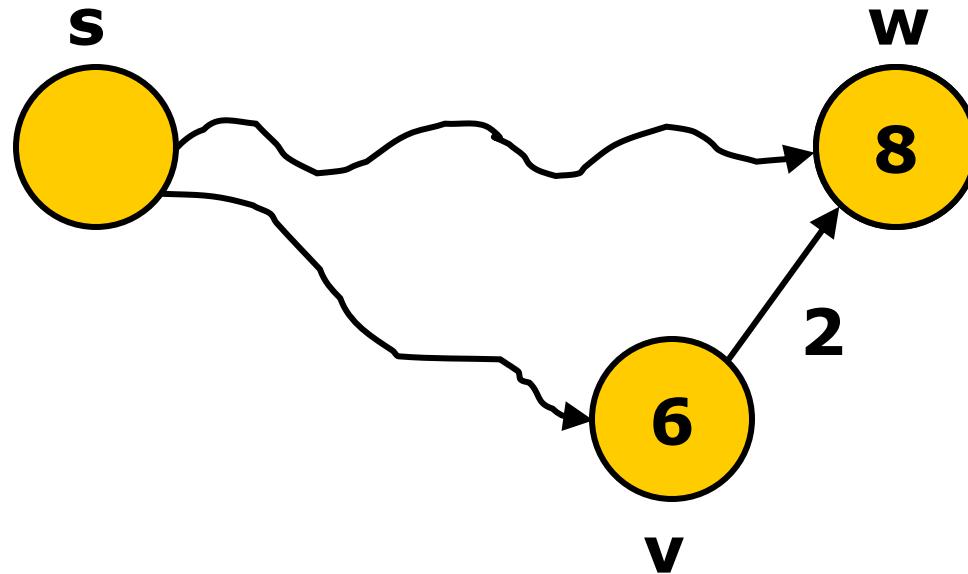


BFS(s) does not work

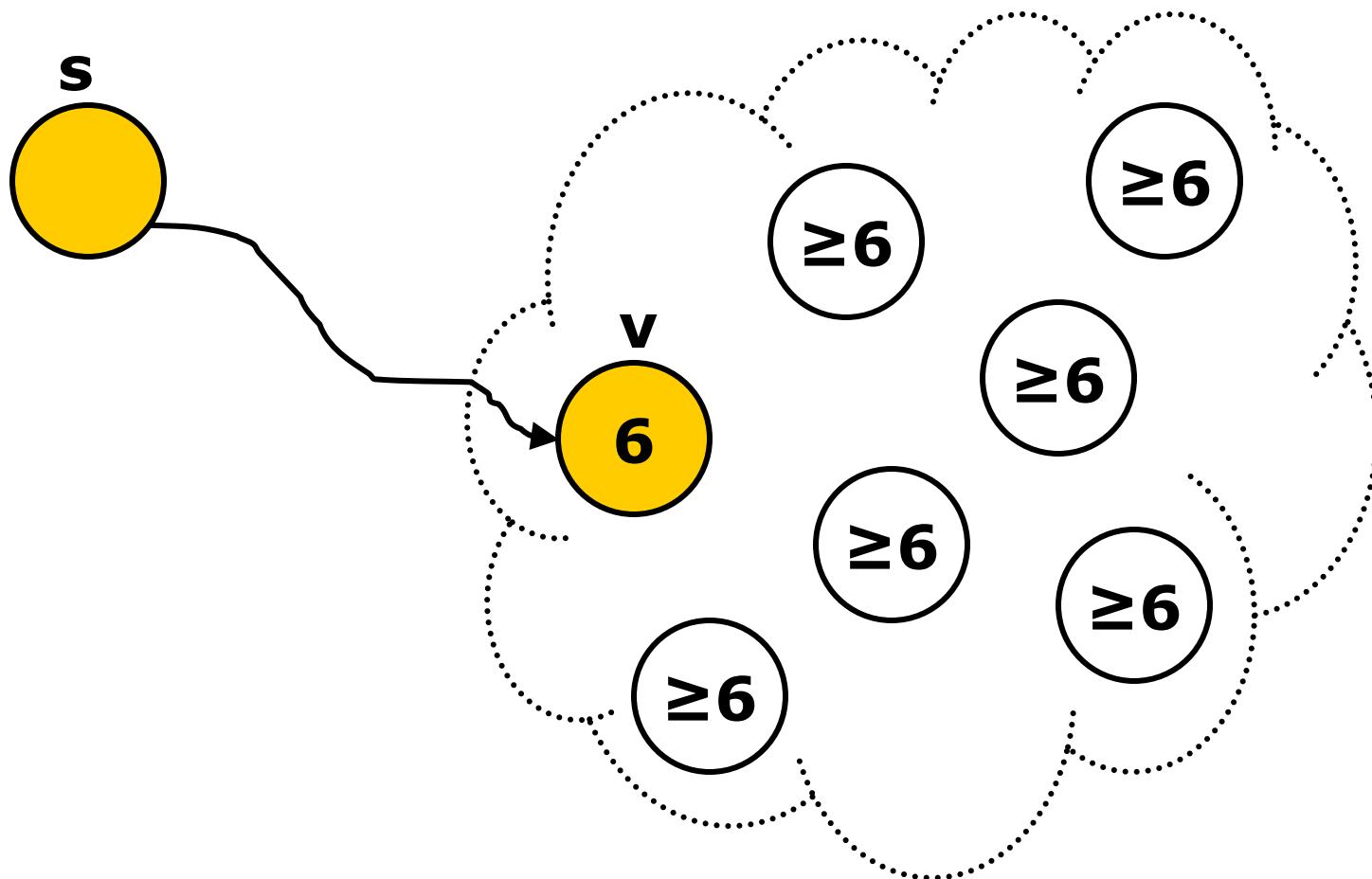


- Must keep track of smallest distance so far
- If we found a new, shorter path, update the distance.

Observation 1



Observation 2



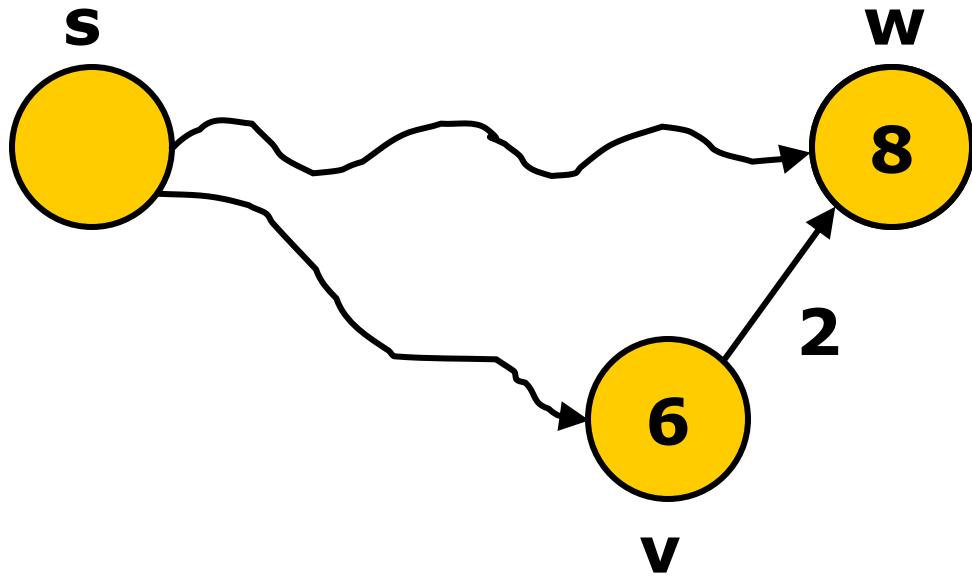
Definition

distance(v) : shortest distance so far from s to v

parent(v) : previous node on the shortest path so far from s to v

weight(u, v) : the weight of edge from u to v

Example



$\text{distance}(w) = 8$
 $\text{weight}(v,w) = 2$
 $\text{parent}(w) = v$

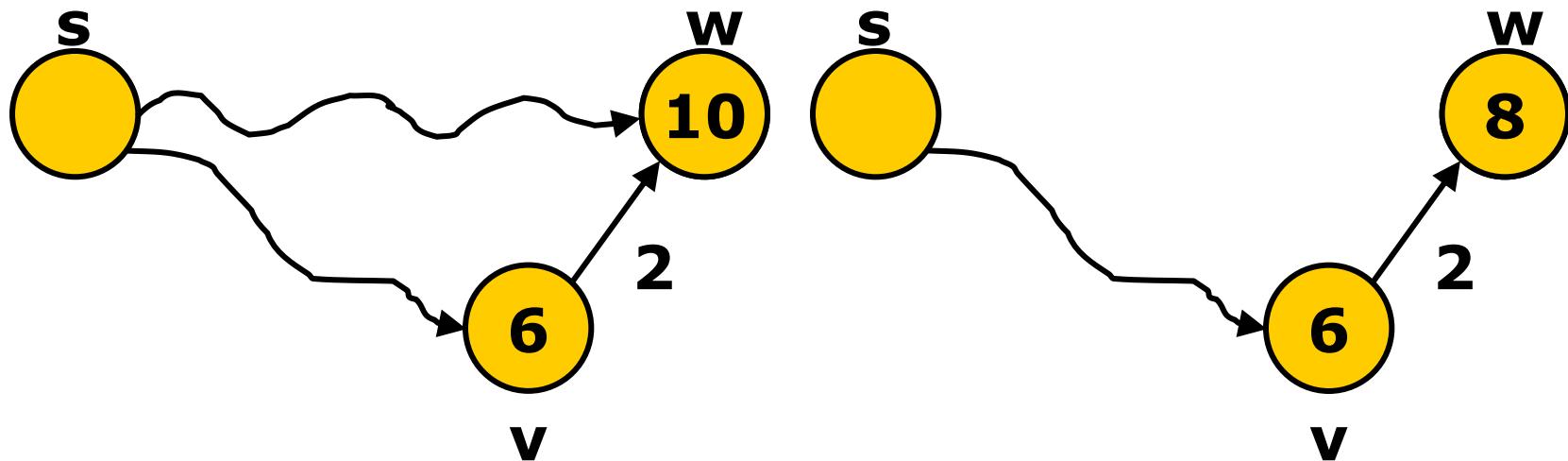
Relax(v, w)

$$d = \text{distance}(v) + \text{weight}(v, w)$$

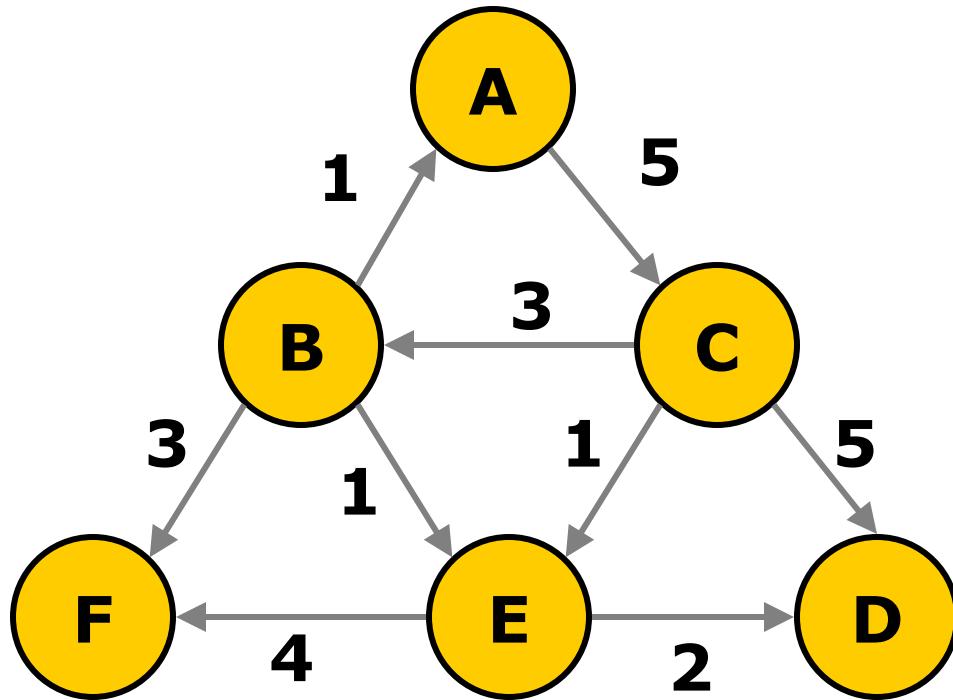
if $\text{distance}(w) > d$ **then**

$$\text{distance}(w) = d$$

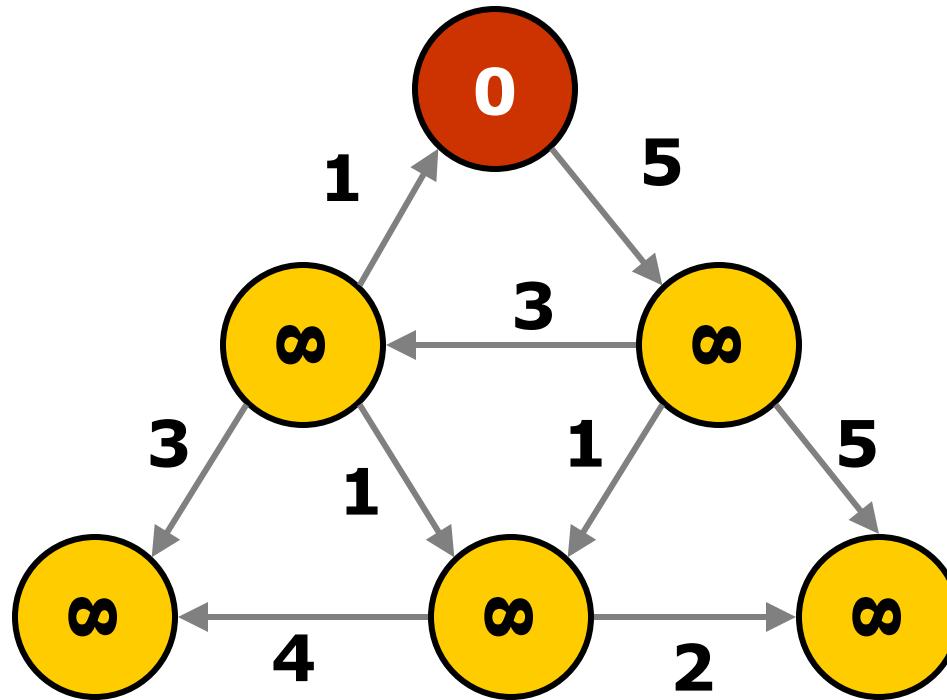
$$\text{parent}(w) = v$$



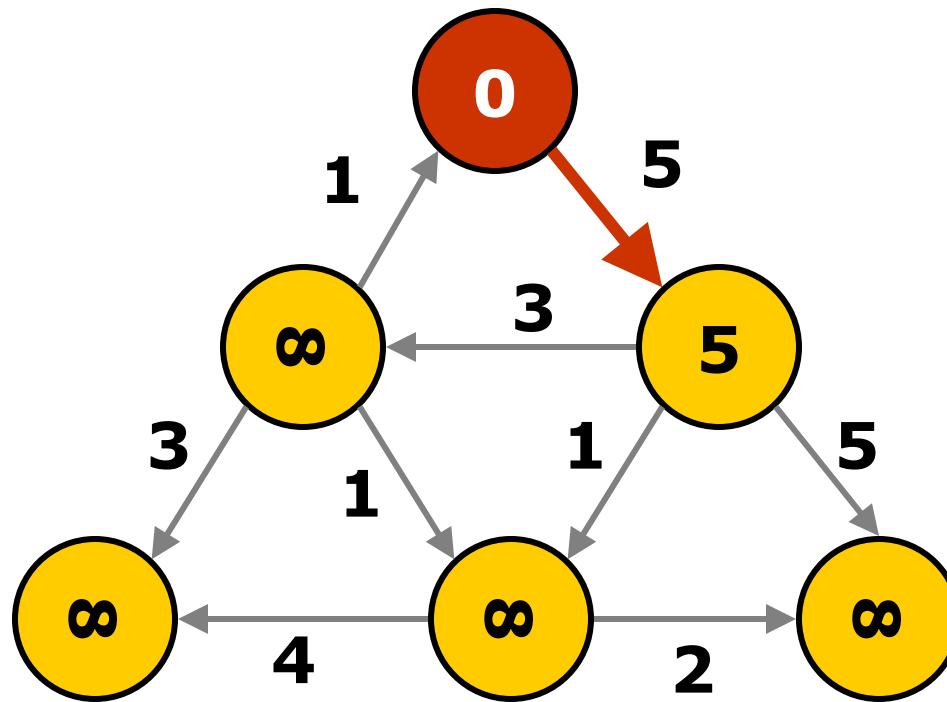
Dijkstra's algorithm



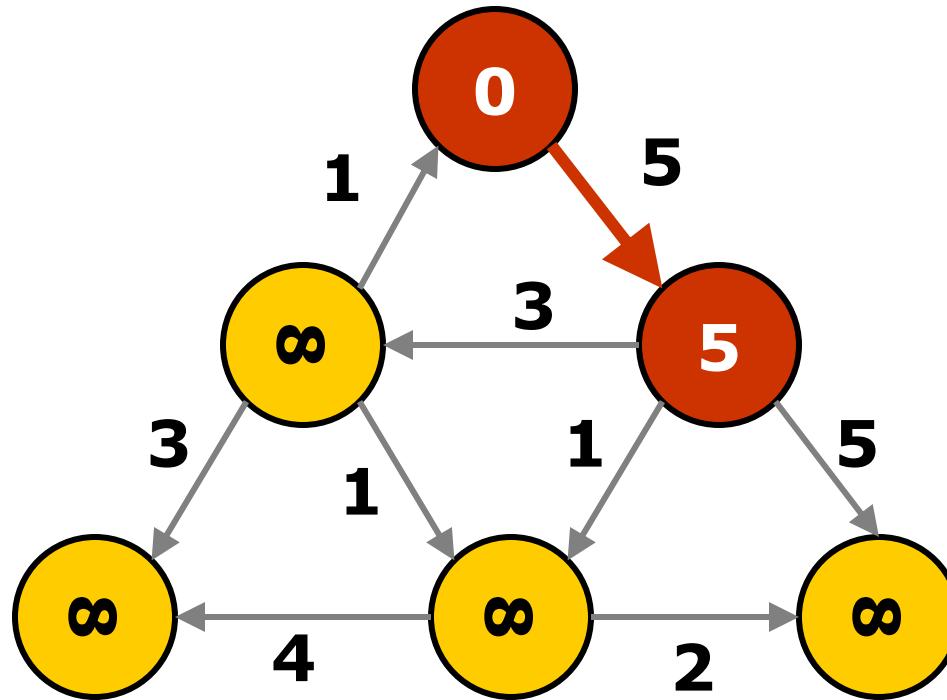
Dijkstra's algorithm



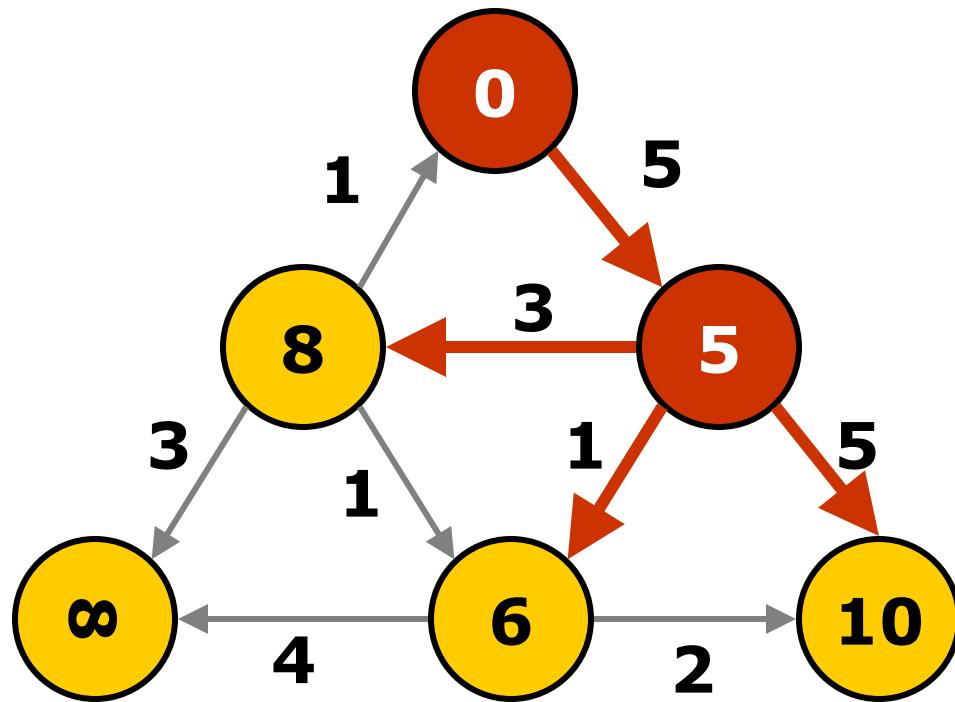
Dijkstra's algorithm



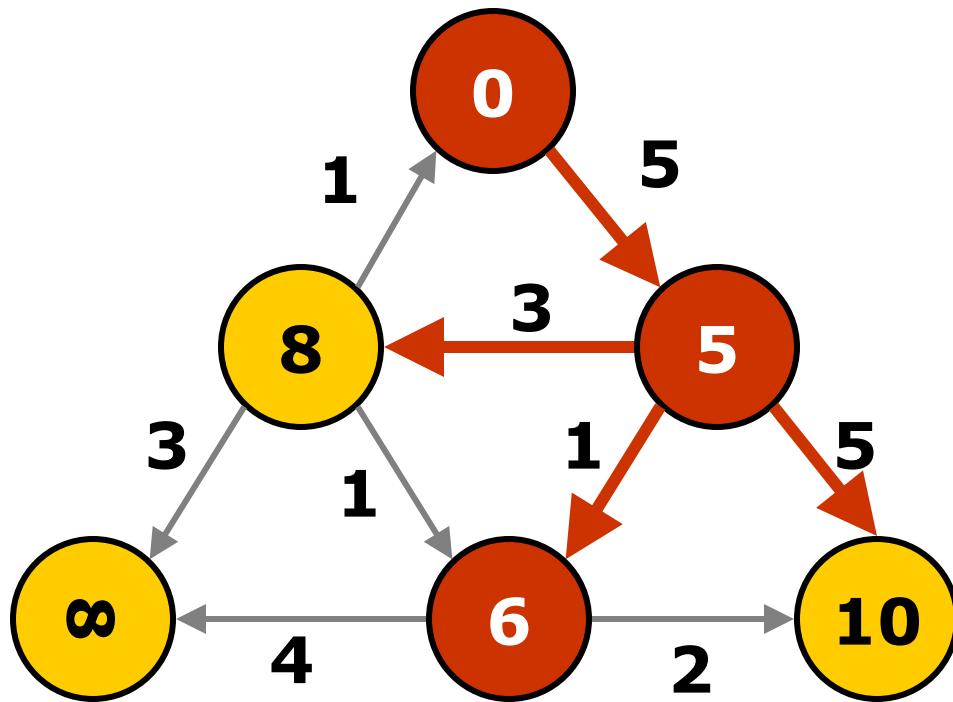
Dijkstra's algorithm



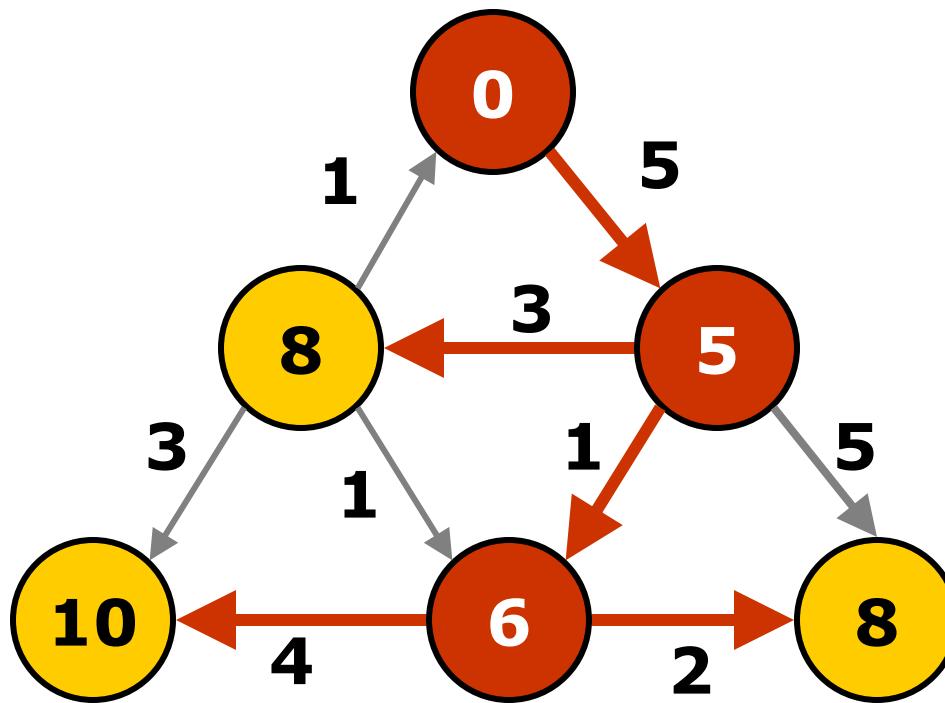
Dijkstra's algorithm



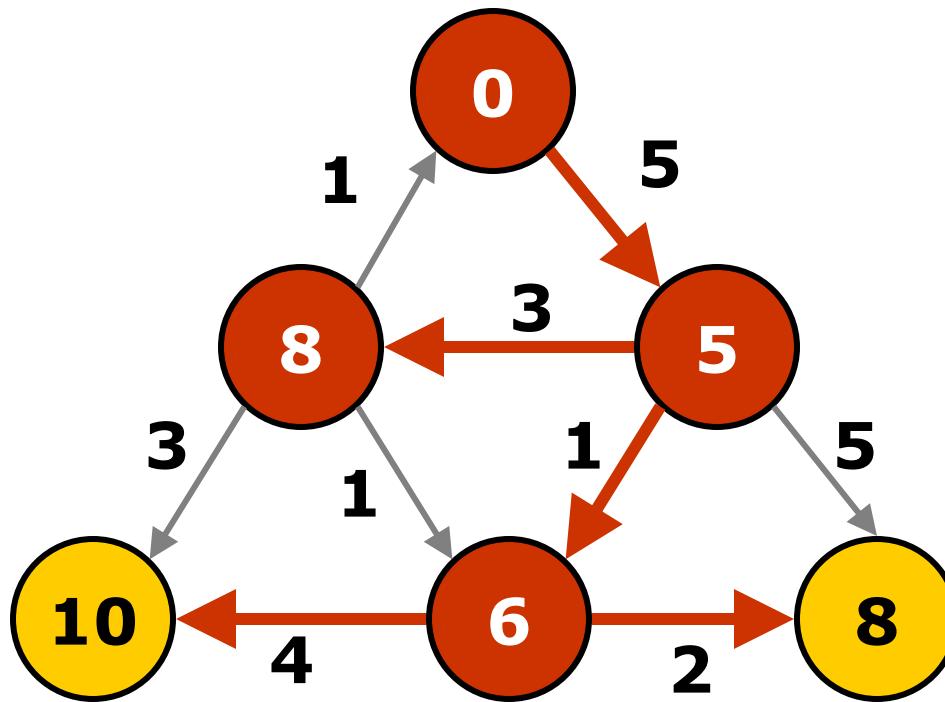
Dijkstra's algorithm



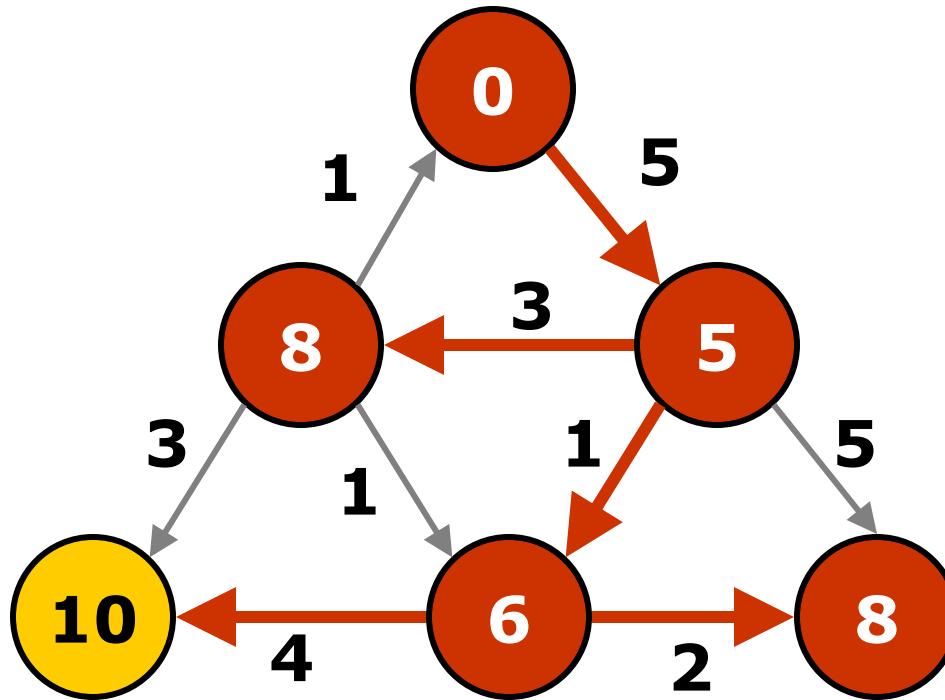
Dijkstra's algorithm



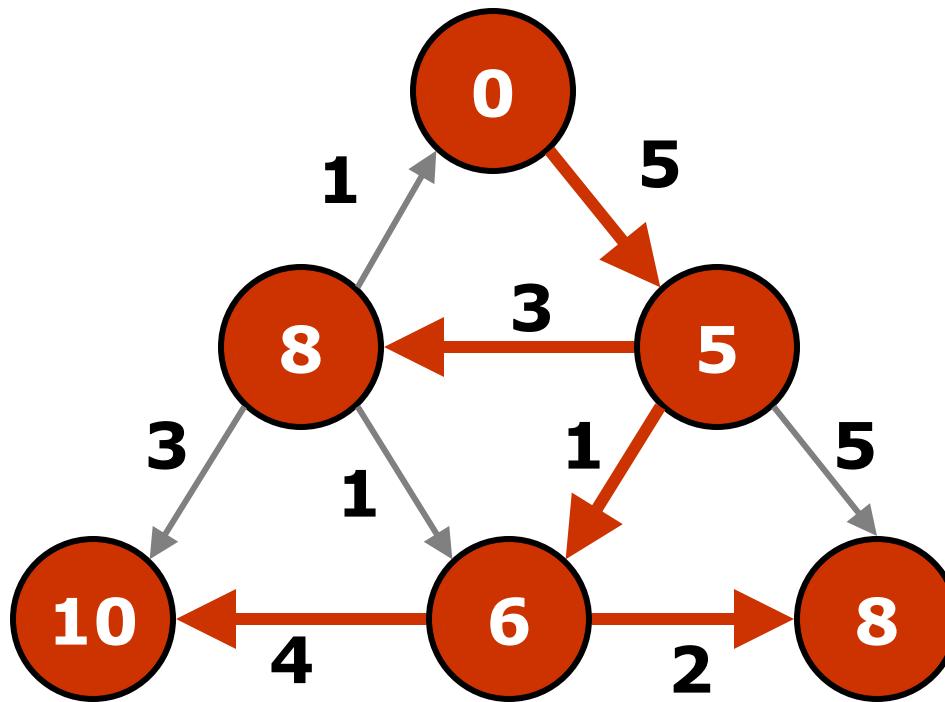
Dijkstra's algorithm



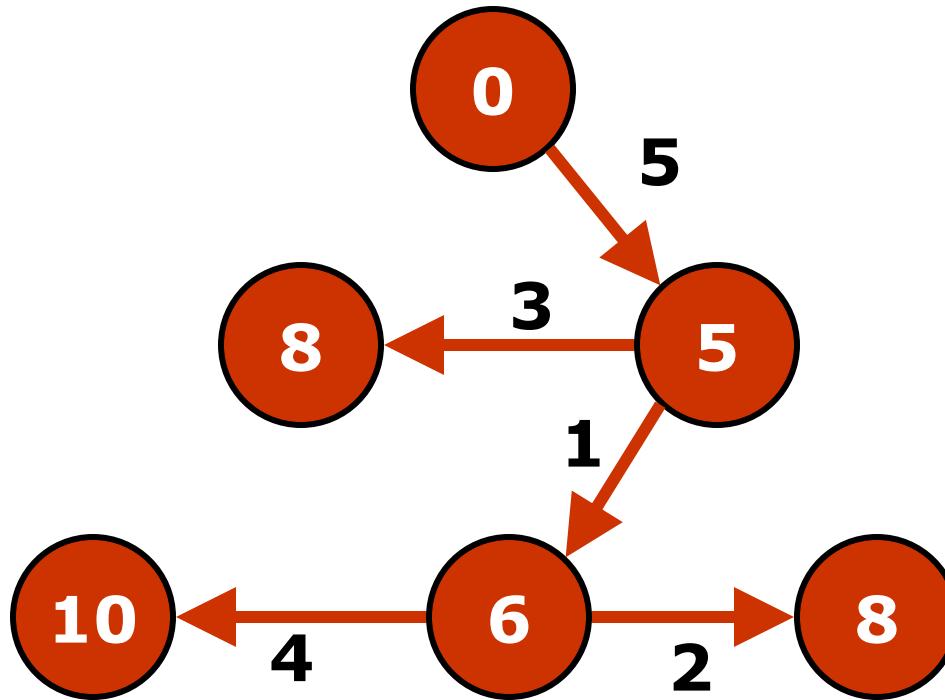
Dijkstra's algorithm



Dijkstra's algorithm



Dijkstra's algorithm



Dijkstra's algorithm

color all vertices yellow

foreach vertex w

 distance(w) = INFINITY

distance(s) = 0

Dijkstra's algorithm

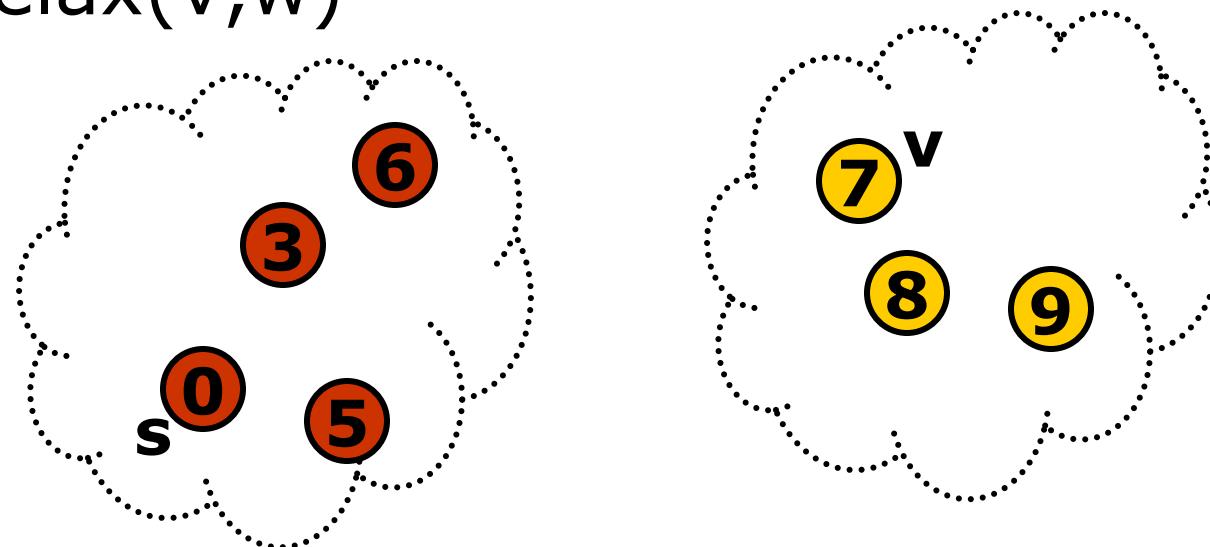
while there are yellow vertices

$v = \text{yellow vertex with min distance}(v)$

 color v red

foreach neighbour w of v

 relax(v, w)



Complexity



Running time $O(V^2 + E)$

color all vertices yellow

foreach vertex w

 distance(w) = INFINITY

distance(s) = 0

while there are yellow vertices

 v = yellow vertex with min distance(v)

 color v red

foreach neighbour w of v

 relax(v,w)

Using priority queue

```
foreach vertex w  
    distance(w) = INFINITY  
distance(s) = 0  
pq = new PriorityQueue(V)
```

```
while pq is not empty  
    v = pq.deleteMin()  
foreach neighbour w of v  
    relax(v,w)
```

Initialization $O(V)$

```
foreach vertex w  
    distance(w) = INFINITY  
distance(s) = 0  
pq = new PriorityQueue(V)
```

Main loop

while pq is not empty

 v = pq.deleteMin()

foreach neighbour w of v

 relax(v,w)

Main loop $O((V+E) \log V)$

while pq is not empty

 v = pq.deleteMin() // $\log(V)$

foreach neighbour w of v // $(\log(V) * adj(v))$

 d = distance(v) + cost(v,w) // $adj(v)$

if distance(w) > d **then**

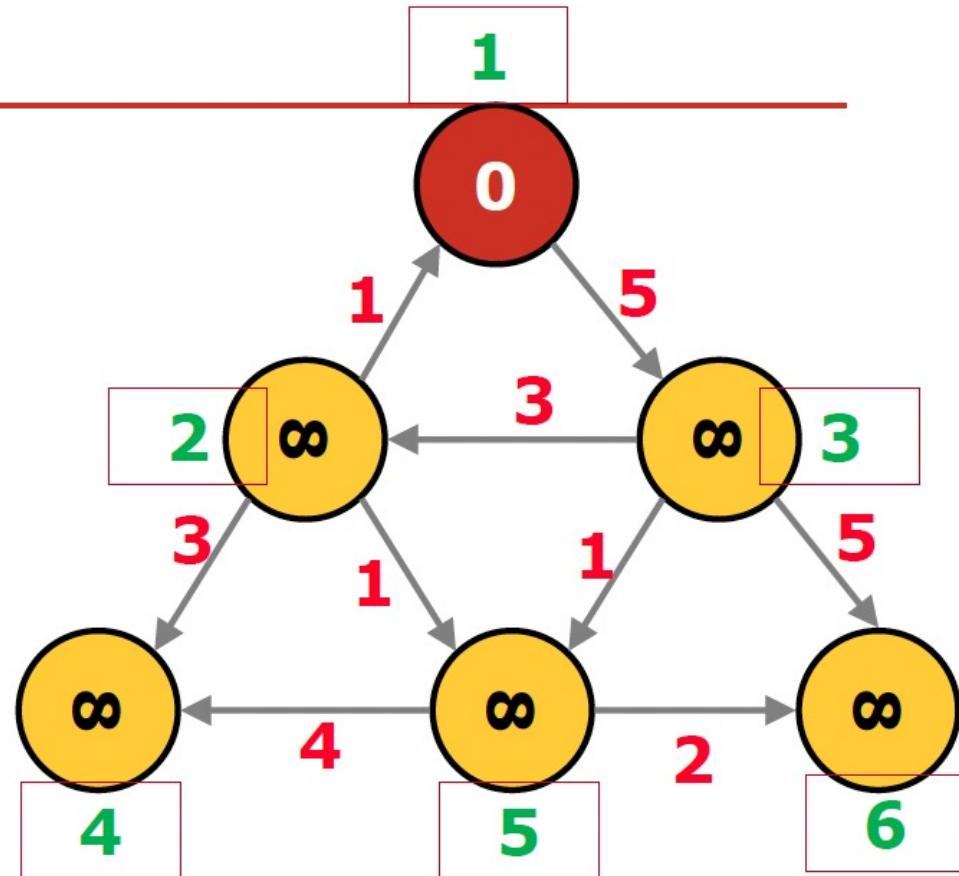
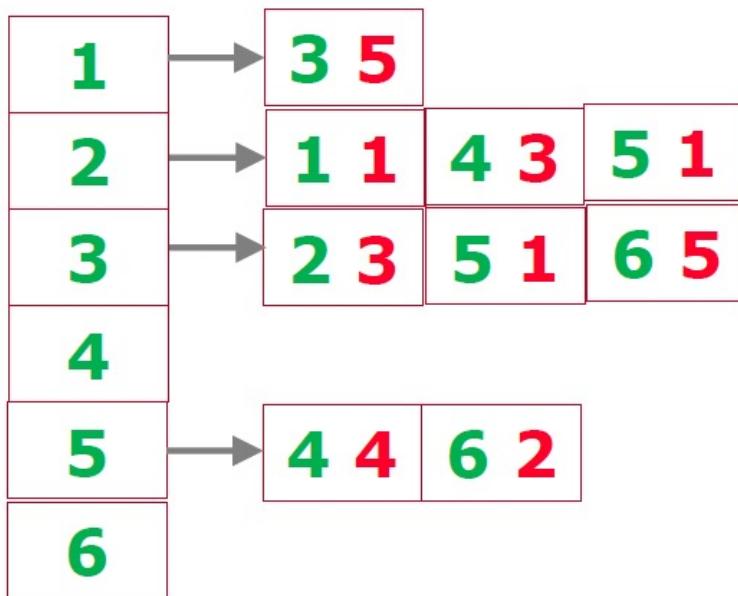
 // $distance(w) = d$

 pq.decreaseKey(w, d)

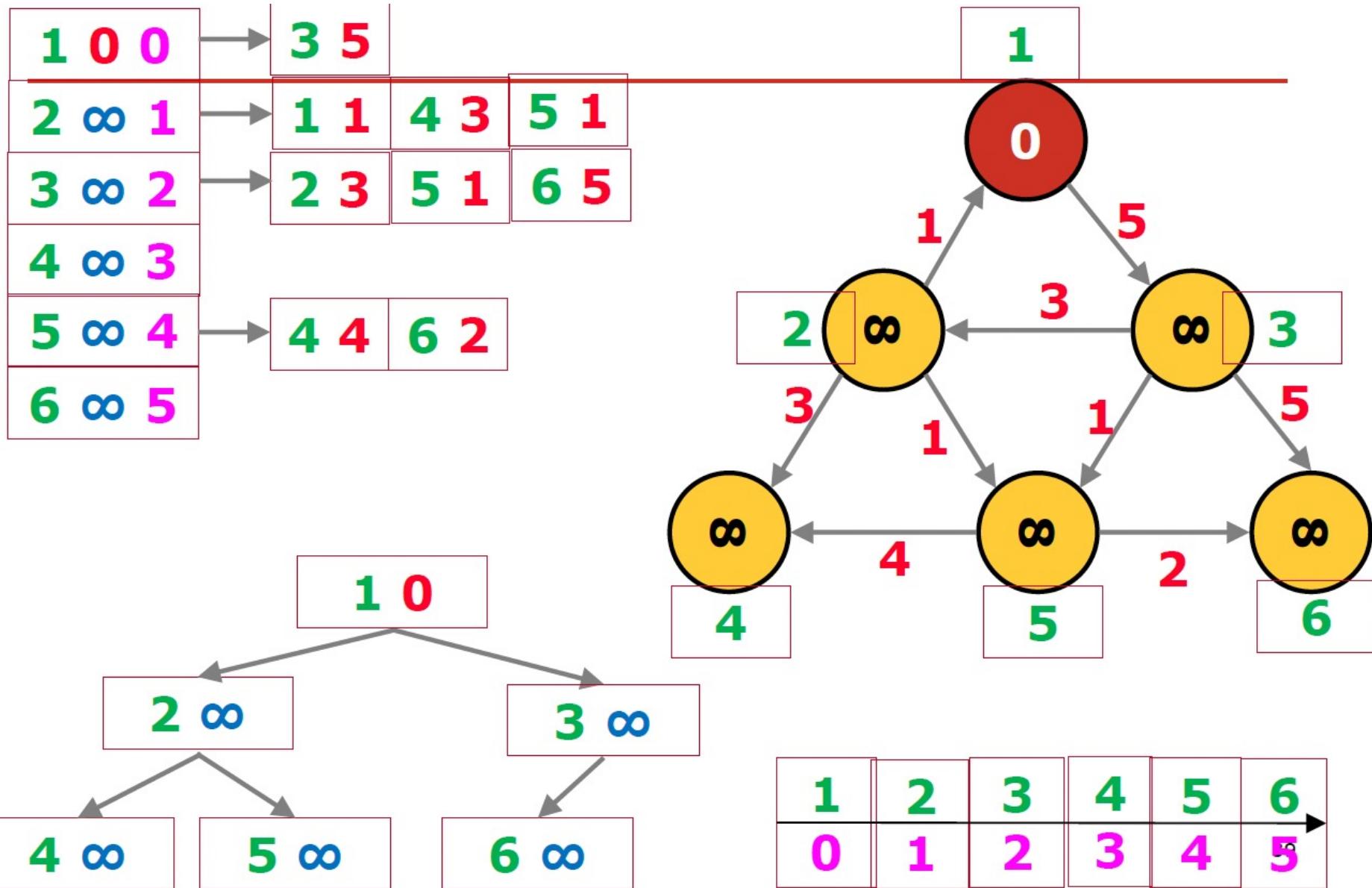
 parent(w) = v

// sum($\log(V) + \log(V) * adj(v)$)

Dijkstra's algorithm

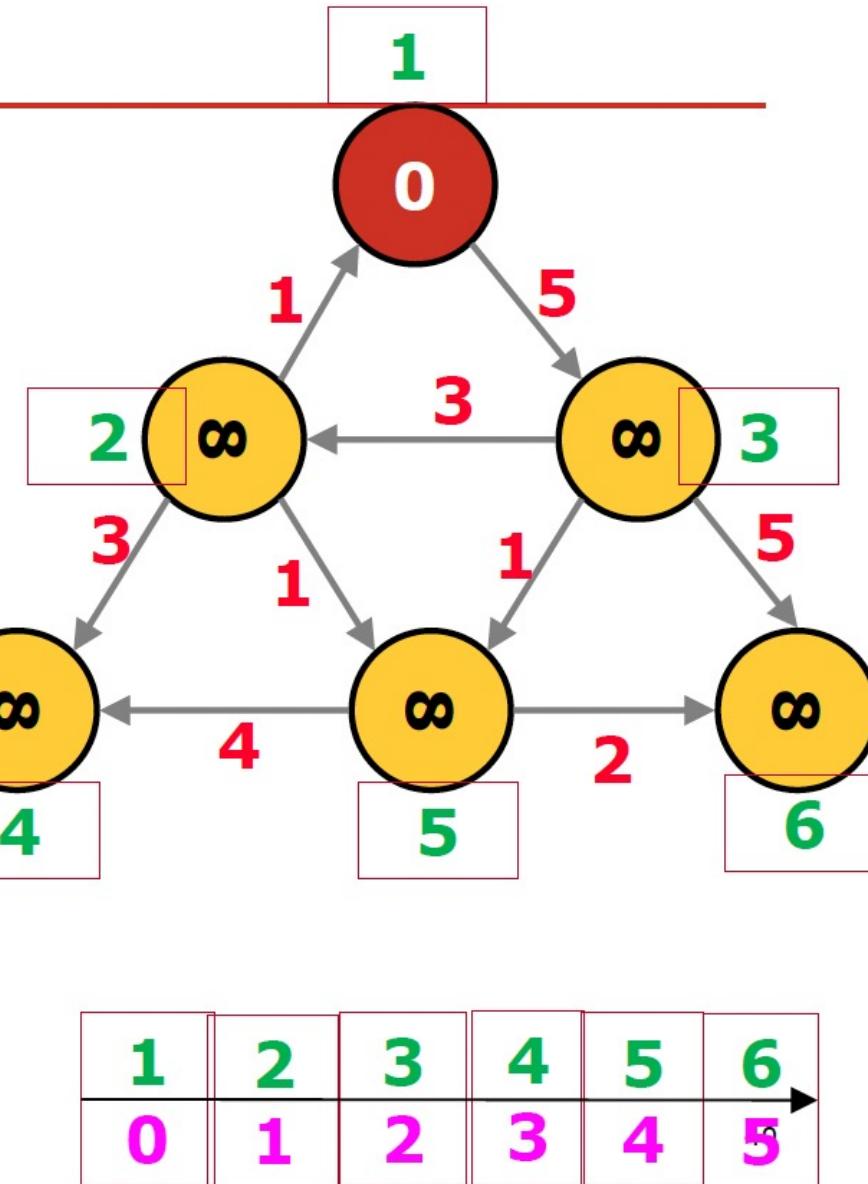


Dijkstra's algorithm



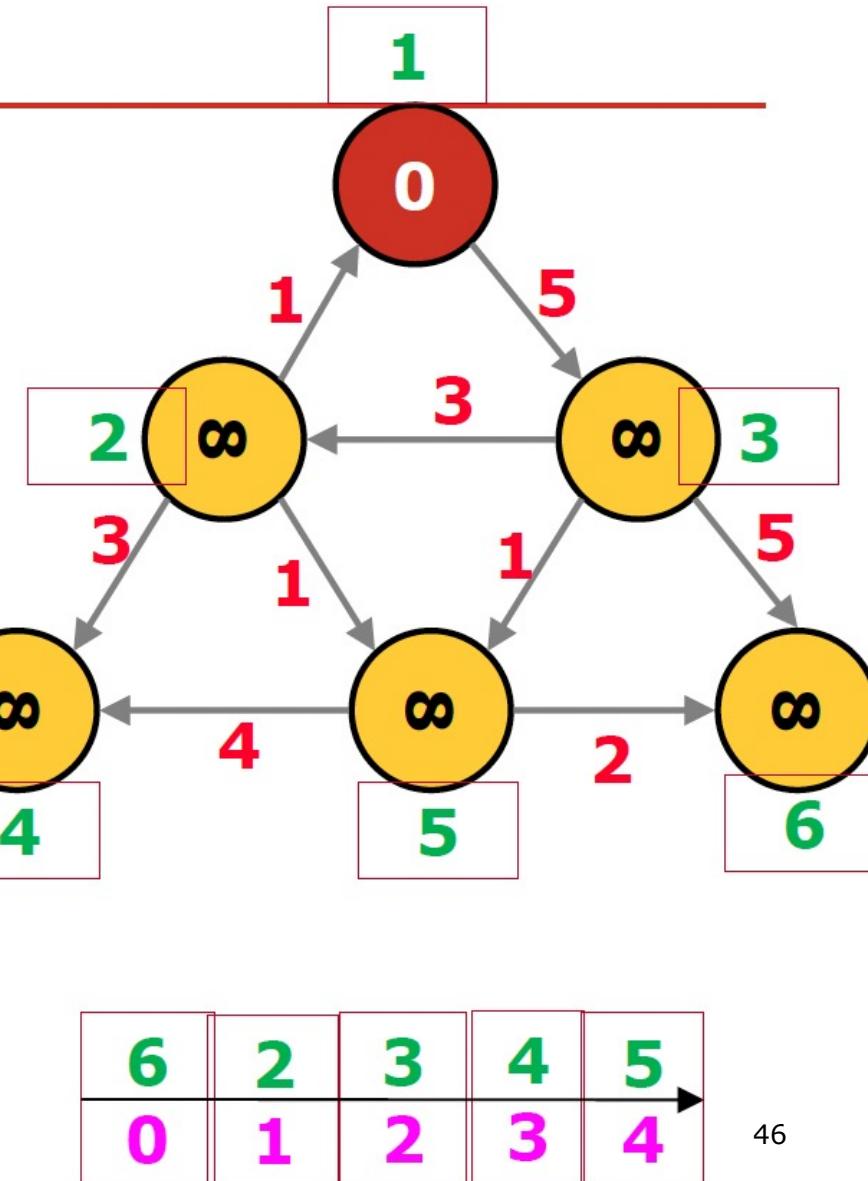
pq.deleteMin()

1 0 0	3 5
2 ∞ 1	1 1 4 3 5 1
3 ∞ 2	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 4	4 4 6 2
6 ∞ 5	

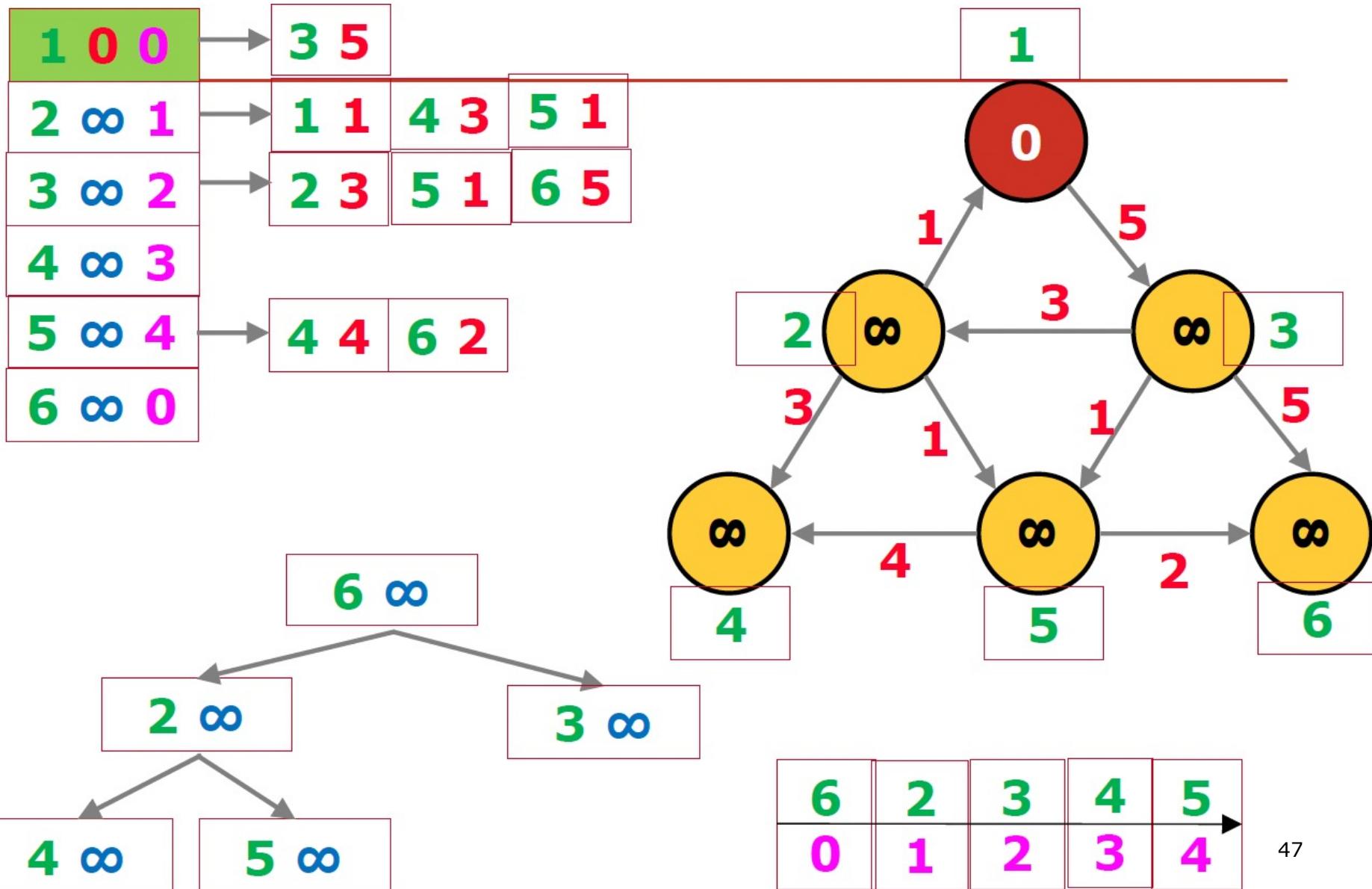


pq.deleteMin()

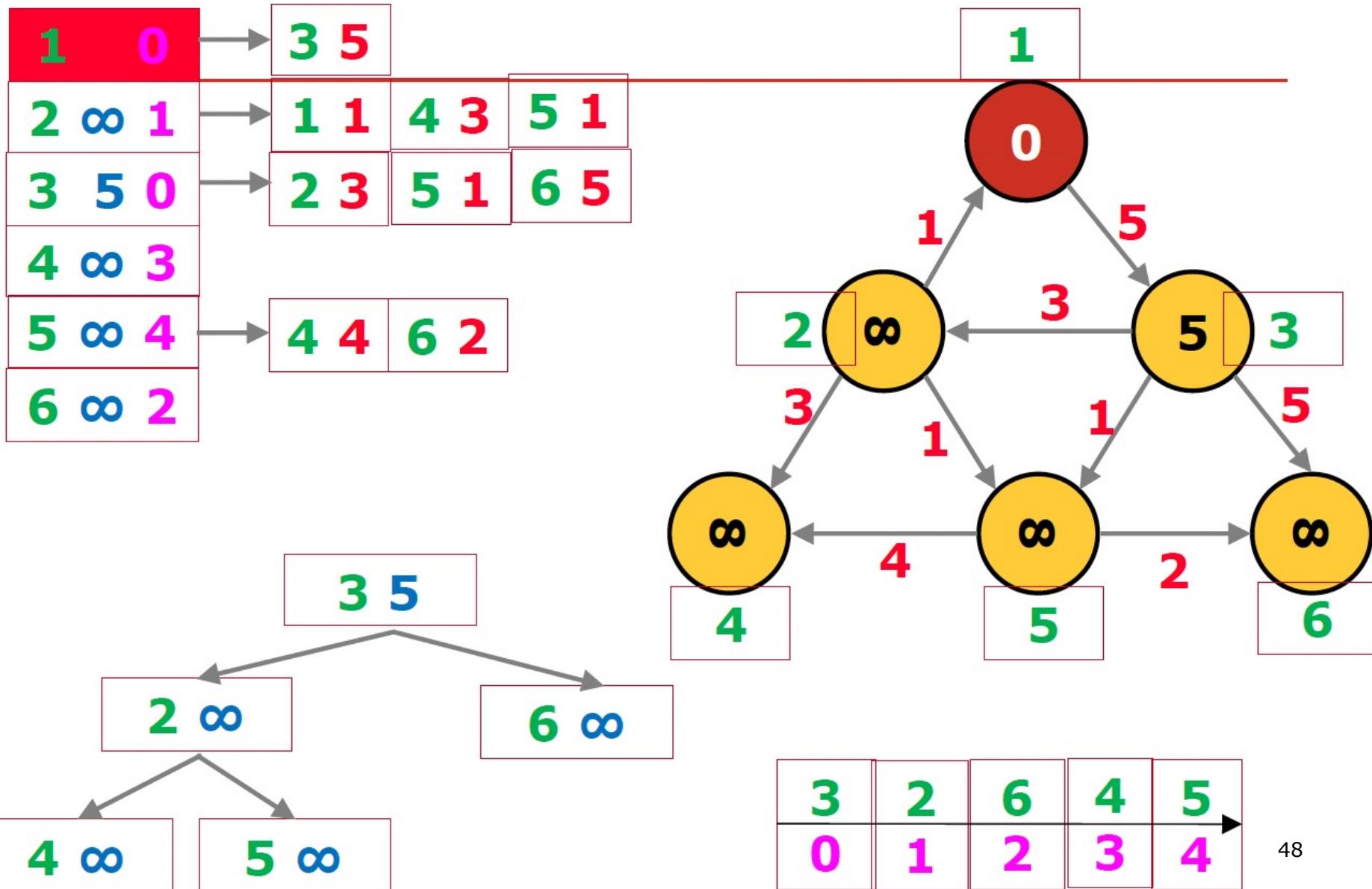
1 0 0	3 5
2 ∞ 1	1 1 4 3 5 1
3 ∞ 2	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 4	4 4 6 2
6 ∞ 0	



pq.decreaseKey(3,5)

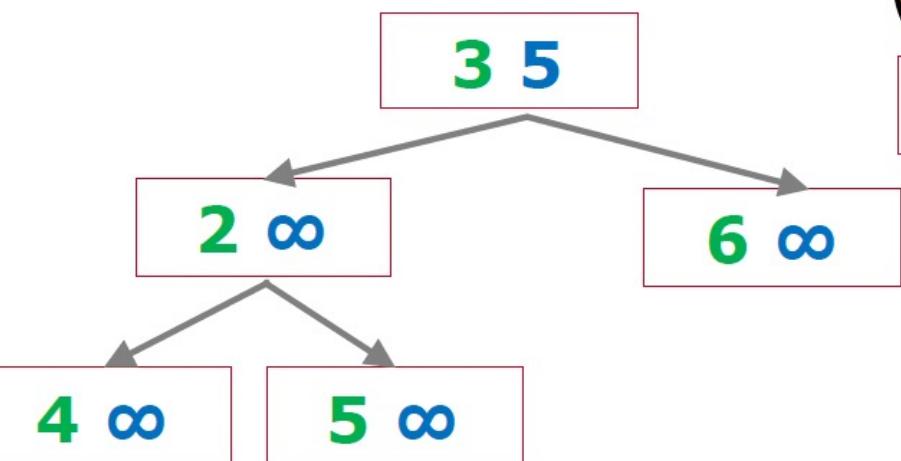
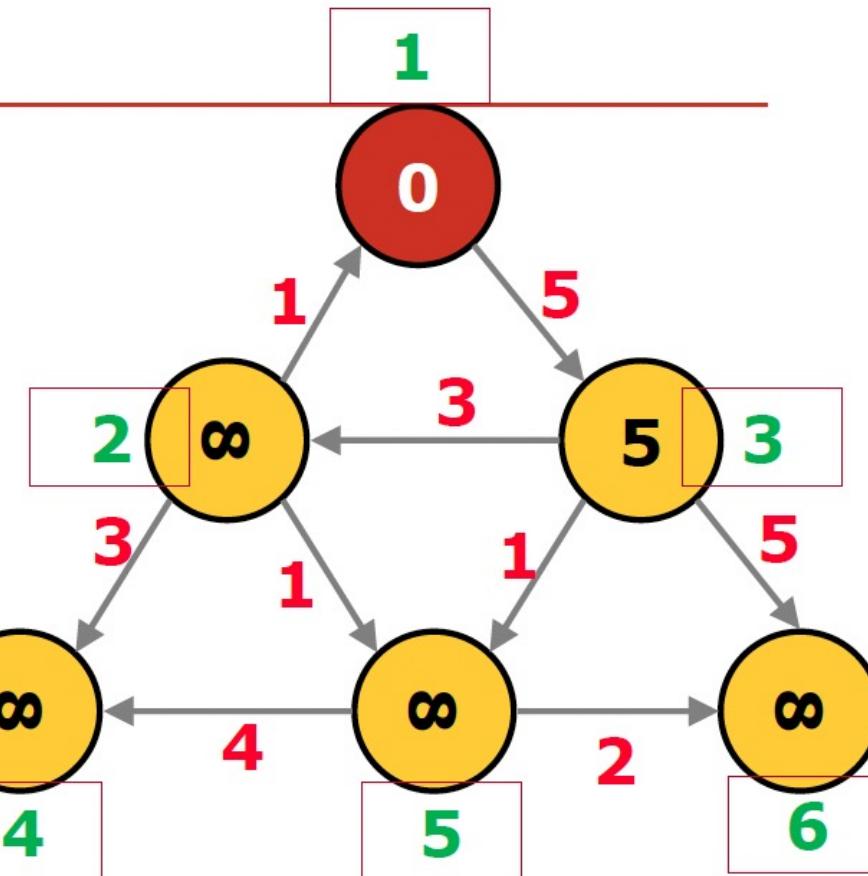


pq.decreaseKey(3,5)



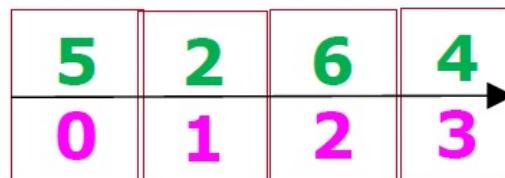
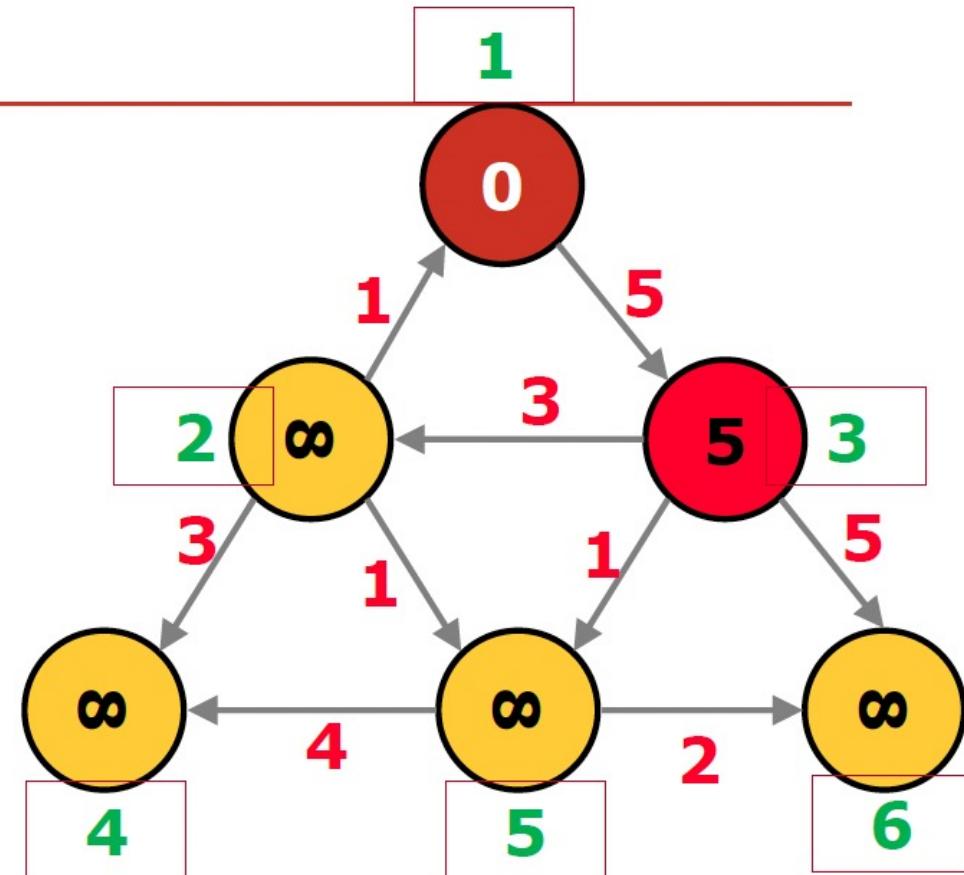
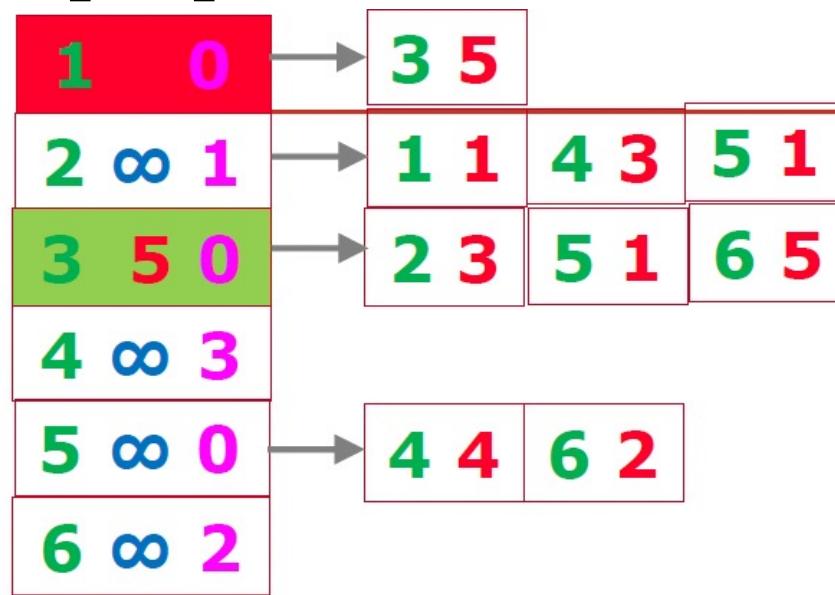
pq.deleteMin()

1 0	3 5
2 ∞ 1	1 1 4 3 5 1
3 5 0	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 4	4 4 6 2
6 ∞ 2	



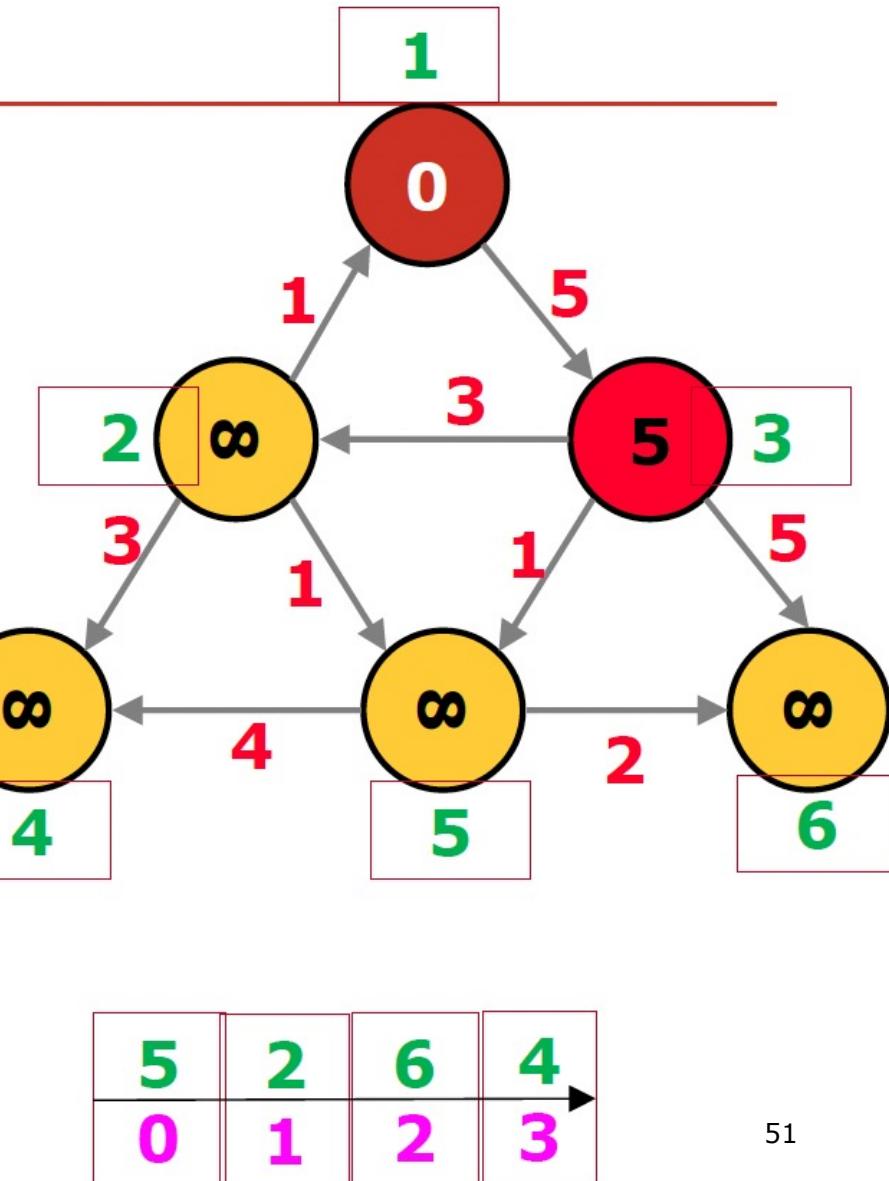
3	2	6	4	5
0	1	2	3	4

pq.deleteMin()



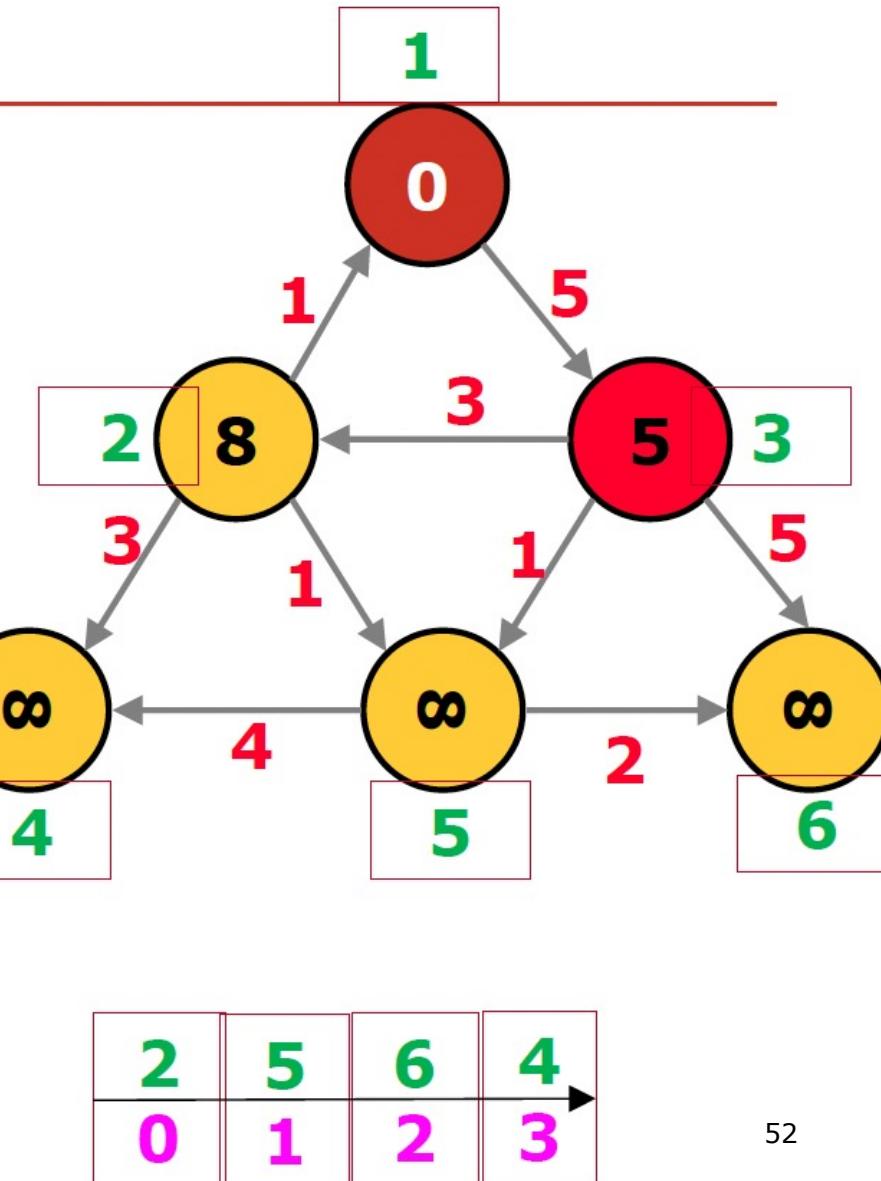
pq.decreaseKey(2,8)

1 0	3 5
2 ∞ 1	1 1 4 3 5 1
3 5 0	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 0	4 4 6 2
6 ∞ 2	



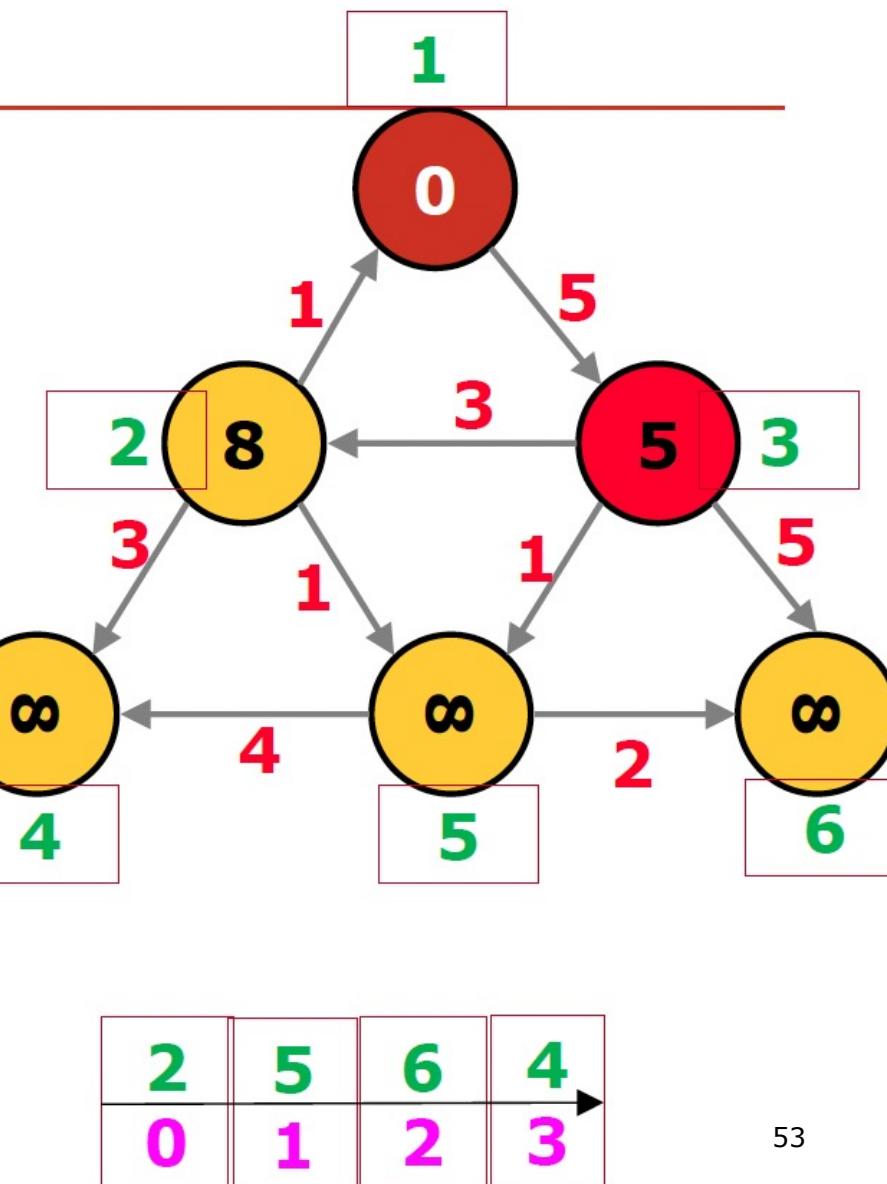
pq.decreaseKey(2,8)

1 0	3 5
2 8 0	1 1 4 3 5 1
3 5 0	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 1	4 4 6 2
6 ∞ 2	

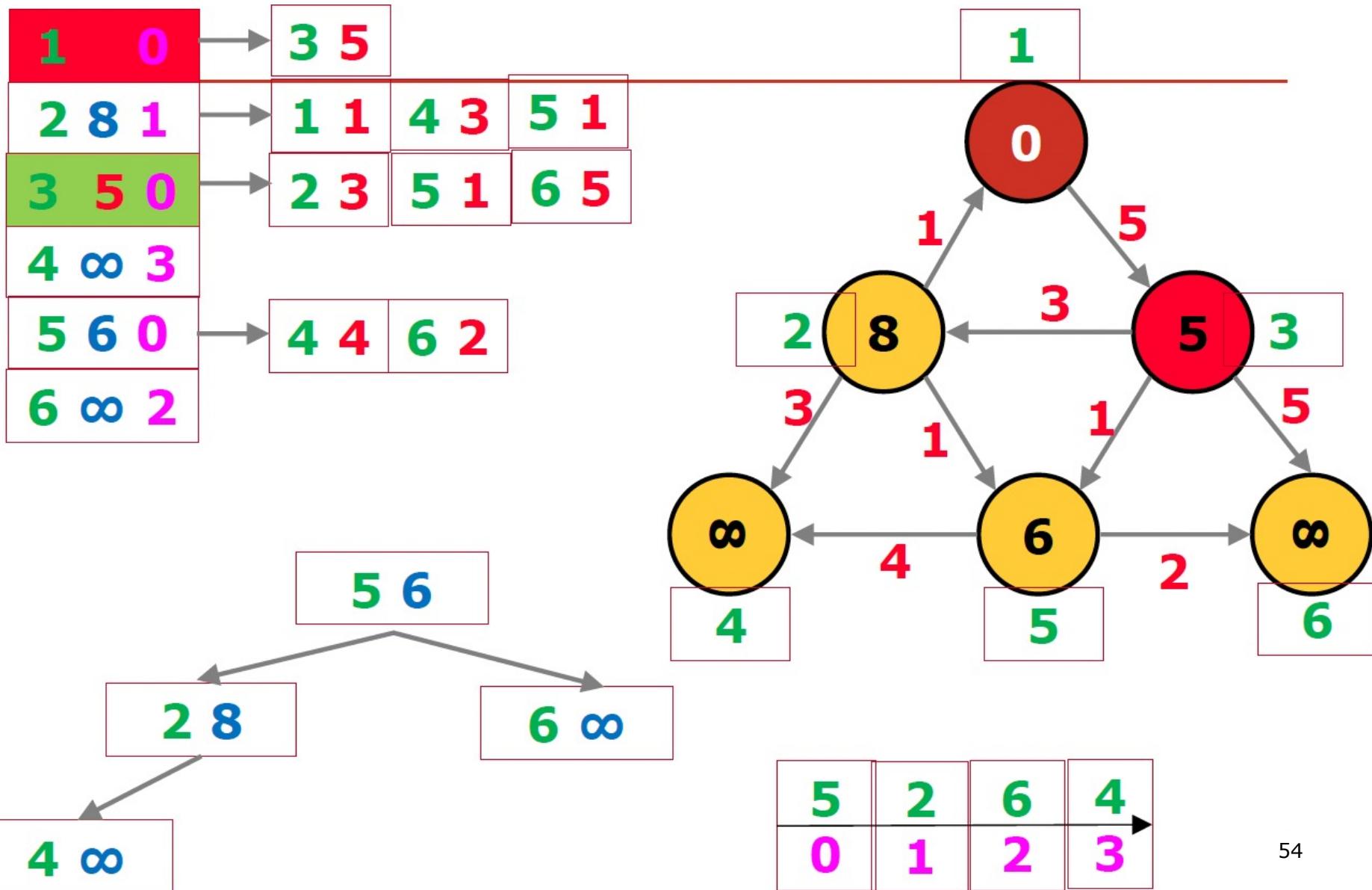


pq.decreaseKey(5,6)

1 0	3 5
2 8 0	1 1 4 3 5 1
3 5 0	2 3 5 1 6 5
4 ∞ 3	
5 ∞ 1	4 4 6 2
6 ∞ 2	

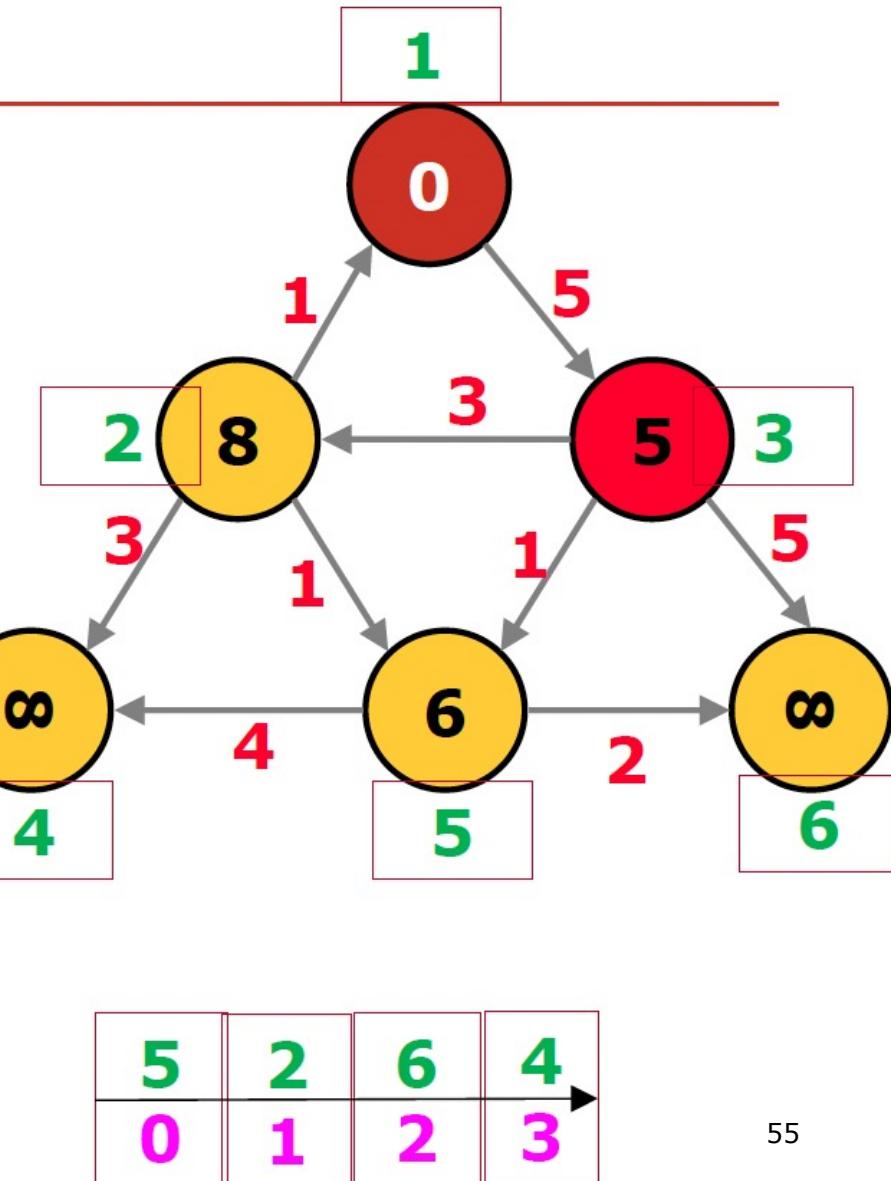


pq.decreaseKey(5,6)



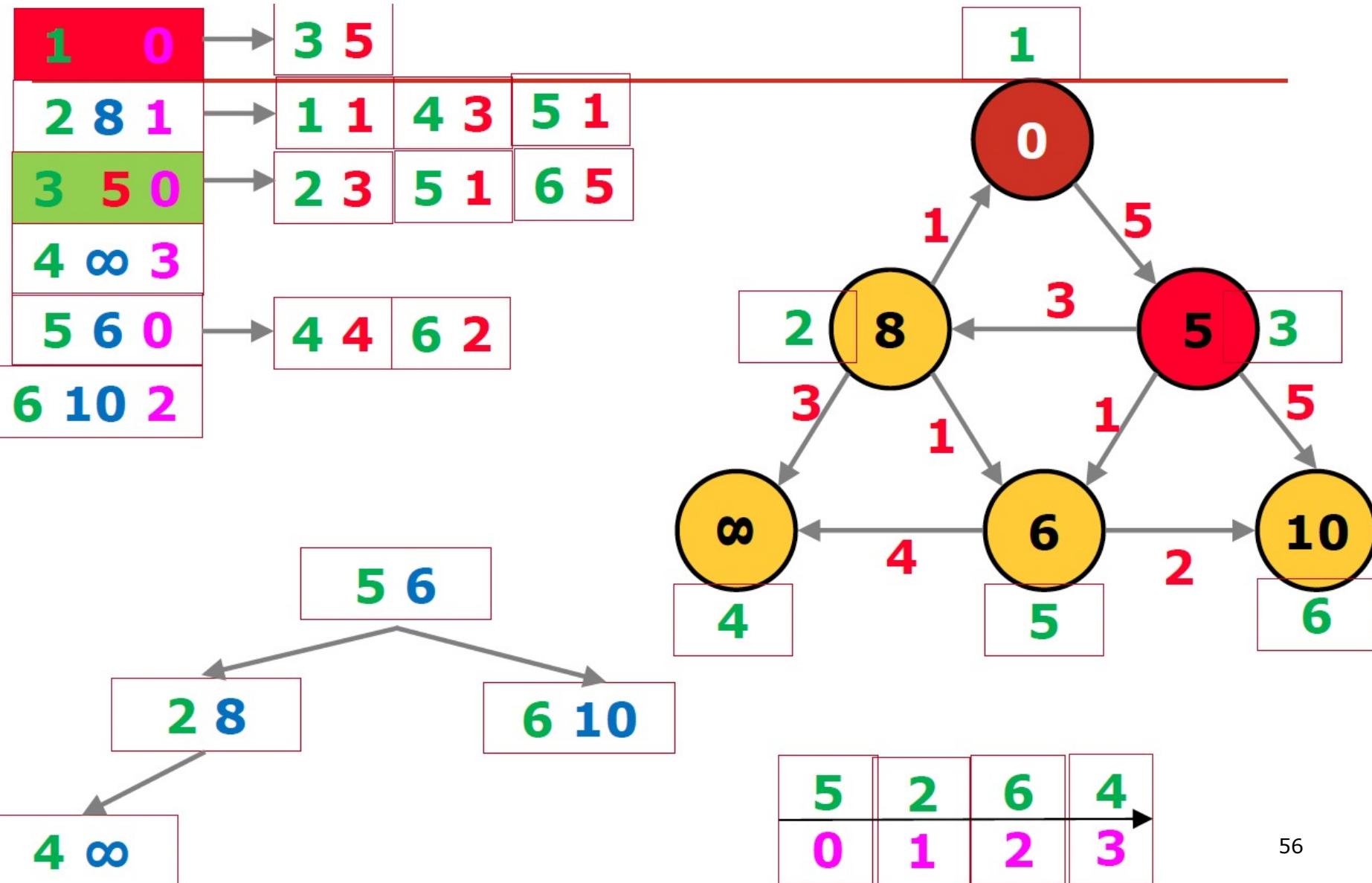
pq.decreaseKey(6,10)

1 0	3 5
2 8 1	1 1 4 3 5 1
3 5 0	2 3 5 1 6 5
4 ∞ 3	
5 6 0	4 4 6 2
6 ∞ 2	

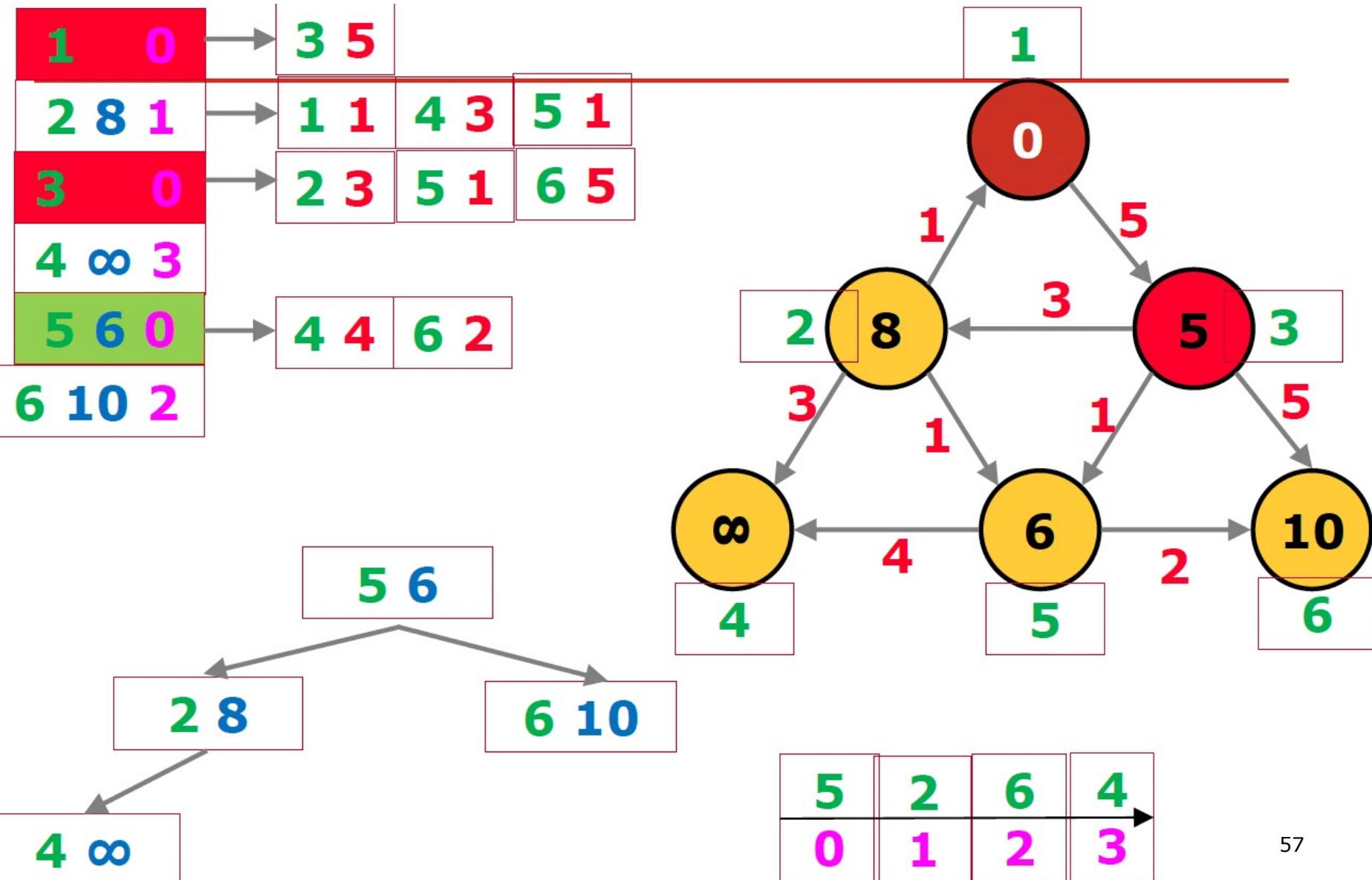


4 ∞

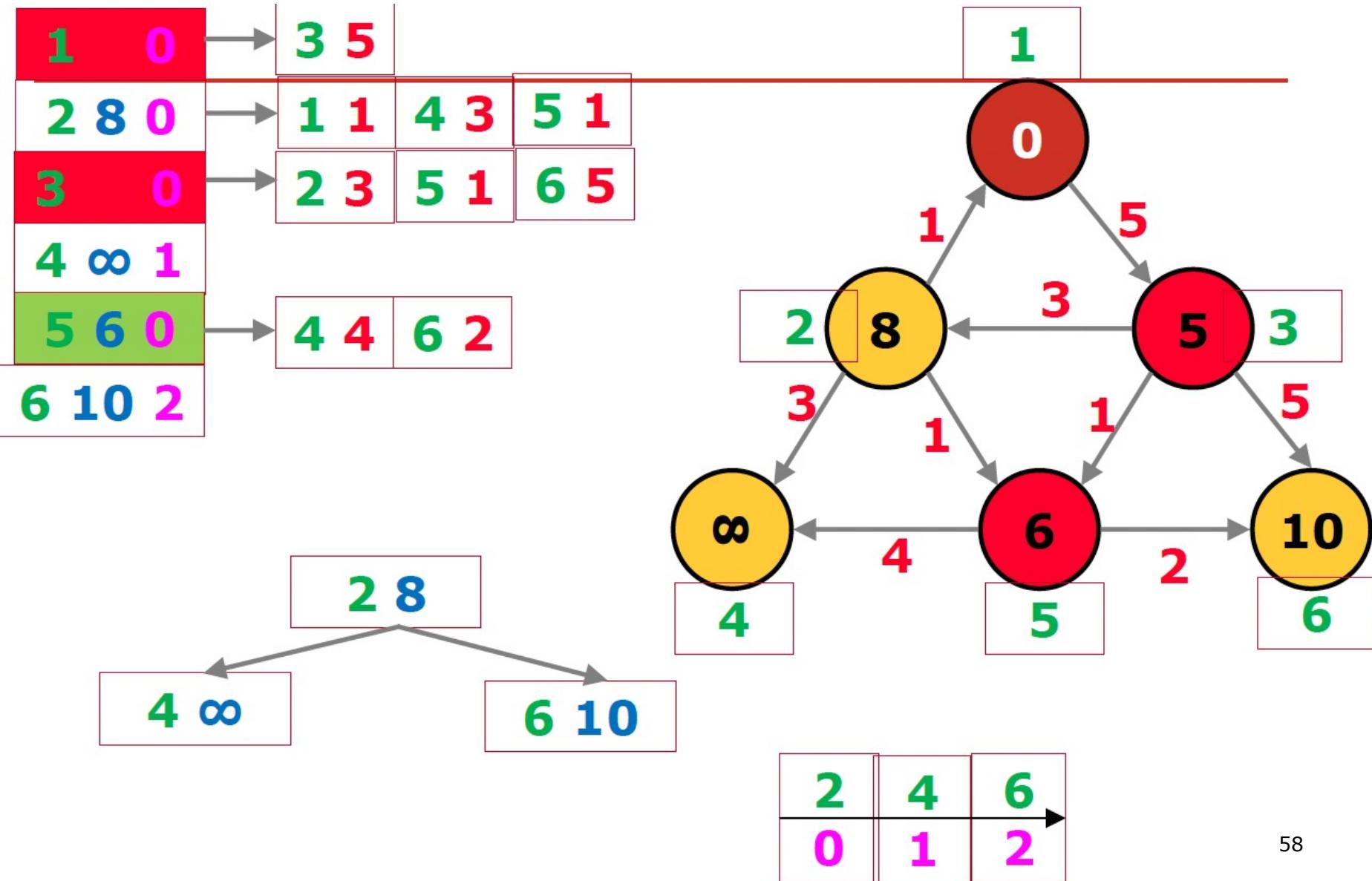
pq.decreaseKey(6,10)



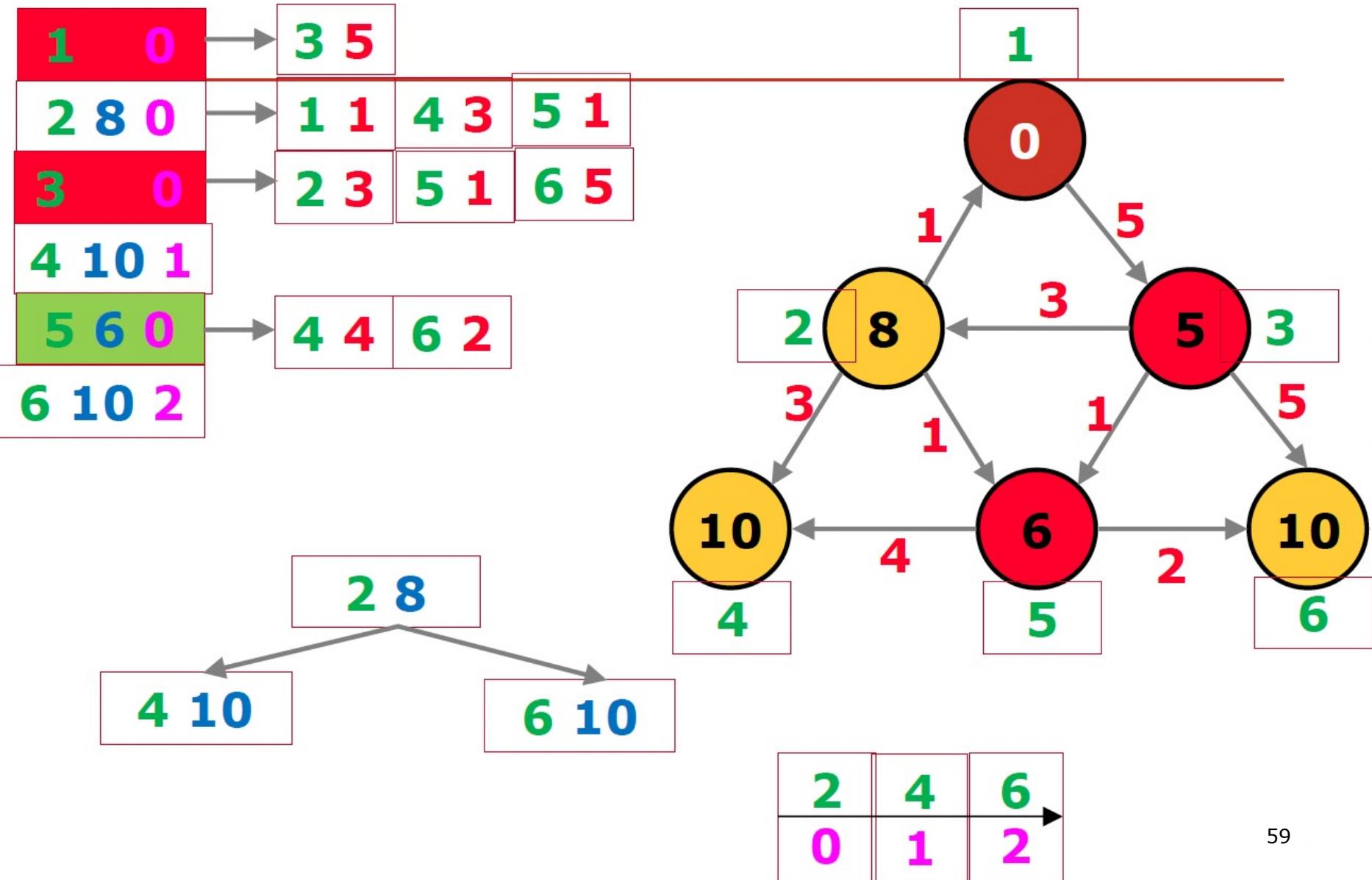
pq.deleteMin()



pq.deleteMin()

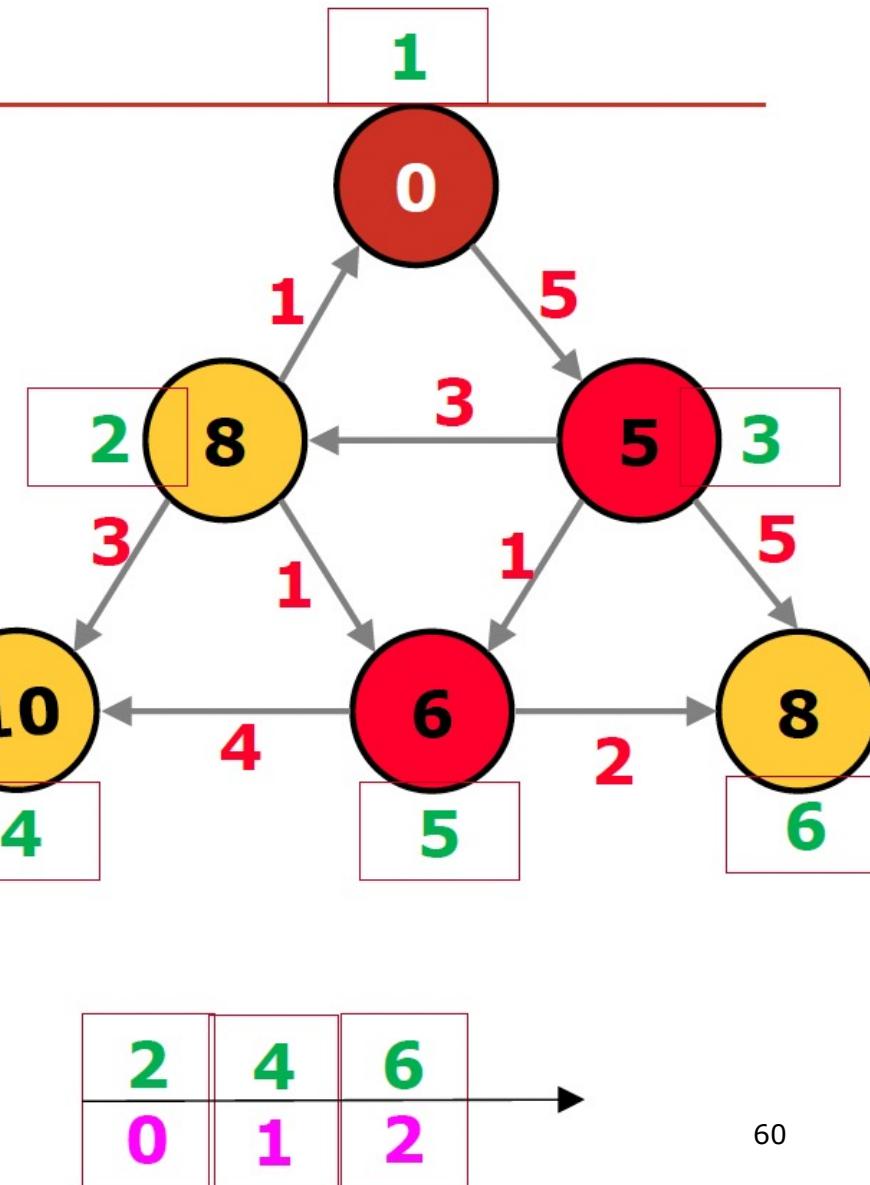


pq.decreaseKey(4,10)



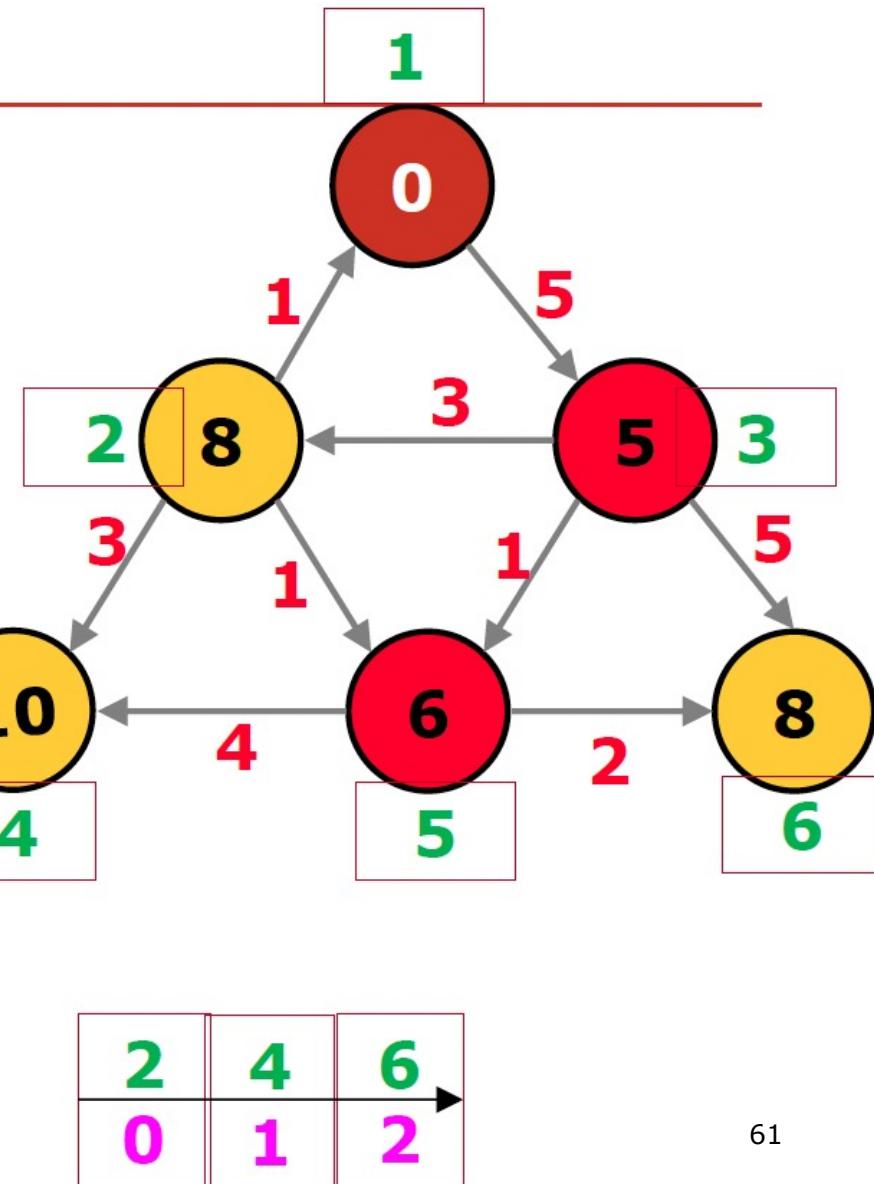
pq.decreaseKey(6,8)

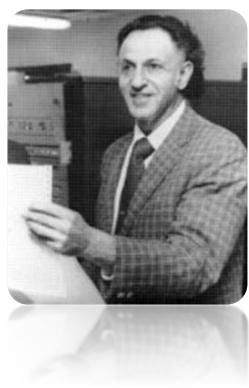
1 0	3 5
2 8 1	1 1 4 3 5 1
3 0	2 3 5 1 6 5
4 10	
5 6 0	4 4 6 2
6 8 2	



pq.deleteMin()

1 0	3 5
2 8 0	1 1 4 3 5 1
3 0	2 3 5 1 6 5
4 10 1	
5 6 0	4 4 6 2
6 8 2	





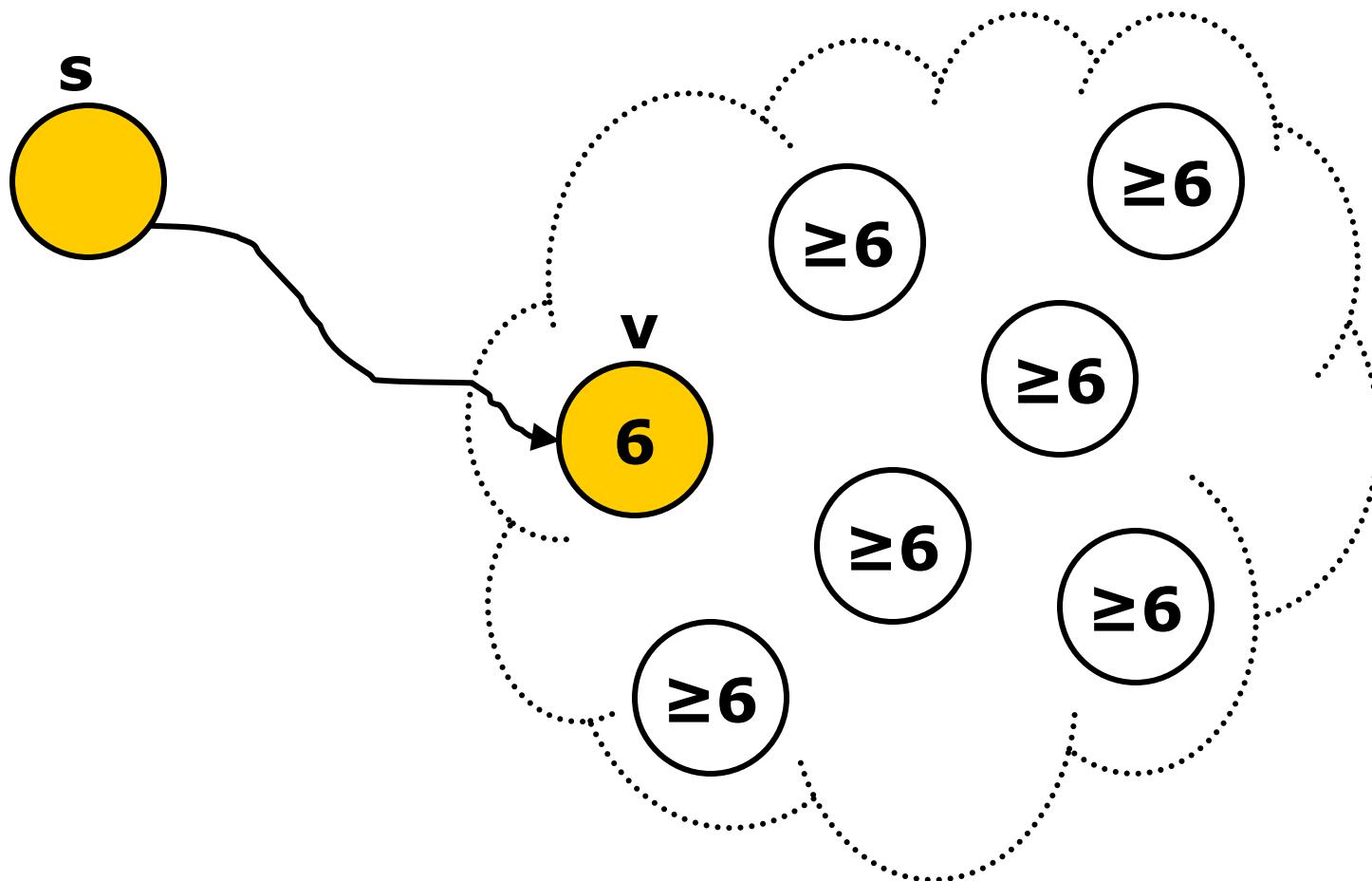
Bellman-Ford

Shortest path algorithm

What if the graph has negative weight?

- Dijkstra's shortest path algorithm will not work.
- **Why?**

Observation 2



The problem

- Given a graph and a source vertex src in graph, find shortest paths from src to all vertices in the given graph.
- The graph may contain **negative weight edges**.

The problem

- If there is a negative weight cycle, then shortest distances are not calculated, negative weight cycle is reported.
- *Bellman-Ford is also simpler than Dijkstra*
- *But time complexity of Bellman-Ford is $O(VE)$, which is more than Dijkstra.*

Data structure

```
class Edge {  
    int src, dest, weight;  
    Edge() {  
        src = dest = weight = 0;  
    }  
}  
  
int V, E;  
Edge [] edge;
```

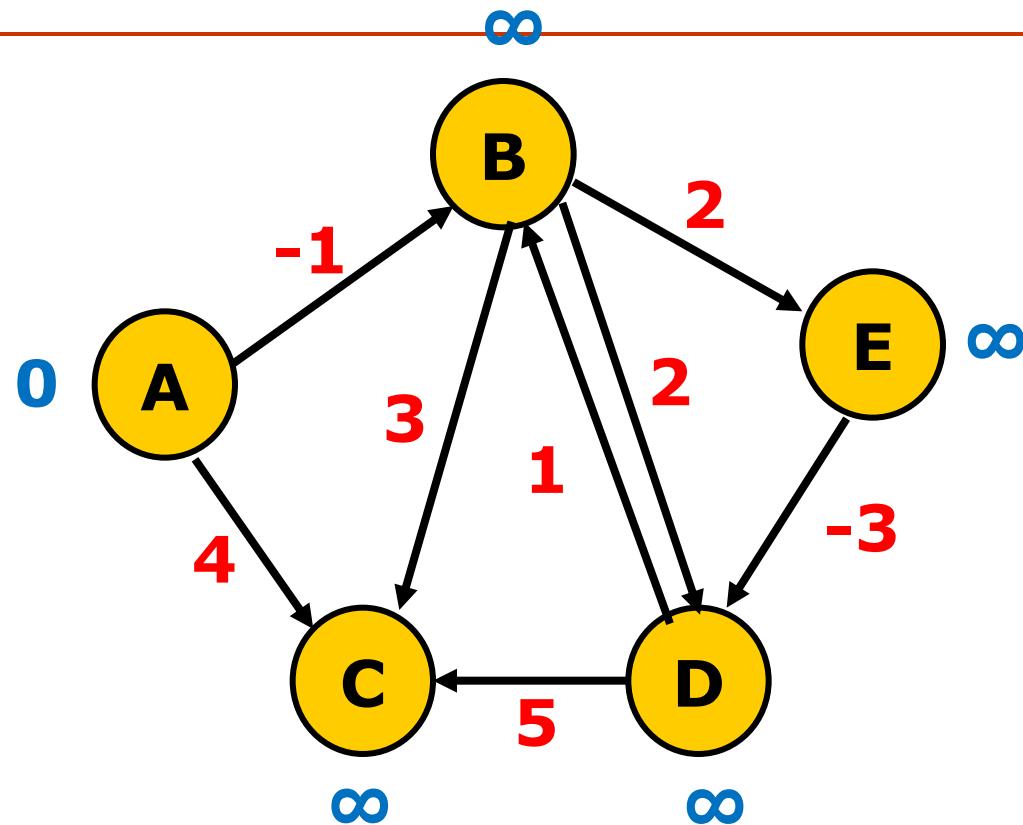
The algorithm

□ Initialization

- Initializes distances from the source to all vertices as infinite and distance to the source itself as 0.
- Create an array `dist[]` of size $|V|$ with all values as infinite except `dist[src]` where `src` is source vertex.

- ```
int [] dist = new int[V];
for (int i = 0; i < V; ++i) {
 dist[i] = Integer.MAX_VALUE;
dist[src] = 0;
```

## □ Example, for a graph with 5 vertices.



| Vertex | A | B        | C        | D        | E        |
|--------|---|----------|----------|----------|----------|
| dist   | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ |

# The algorithm

- calculates shortest distances.

---

Do following  $|V|-1$  times where  $|V|$  is the number of vertices in the graph.

Do following for each edge  $u-v$

If  $\text{dist}[v] > \text{dist}[u] + \text{weight of edge } uv$ ,

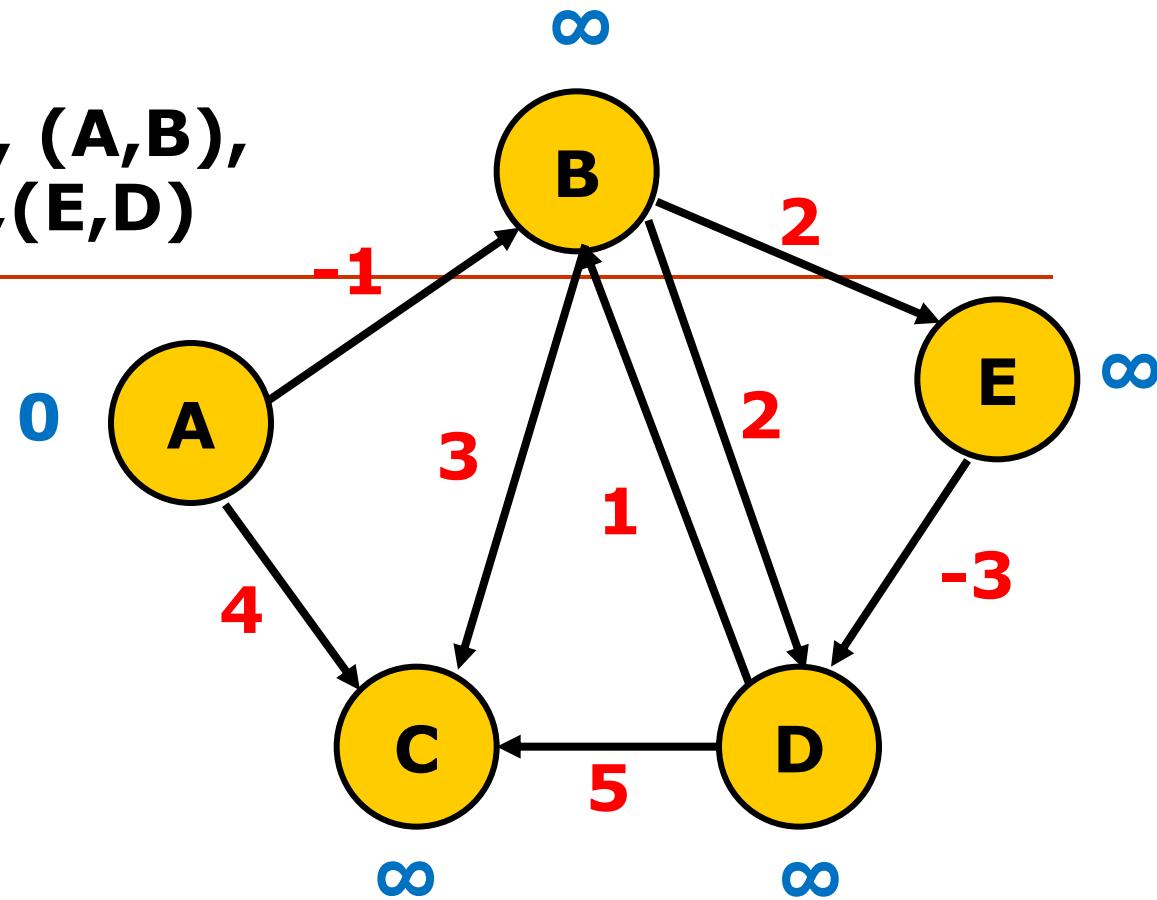
then update  $\text{dist}[v]$

$\text{dist}[v] = \text{dist}[u] + \text{weight of edge } uv$

- Note that the sequence in which the edges are processed are not important

## Process sequence:

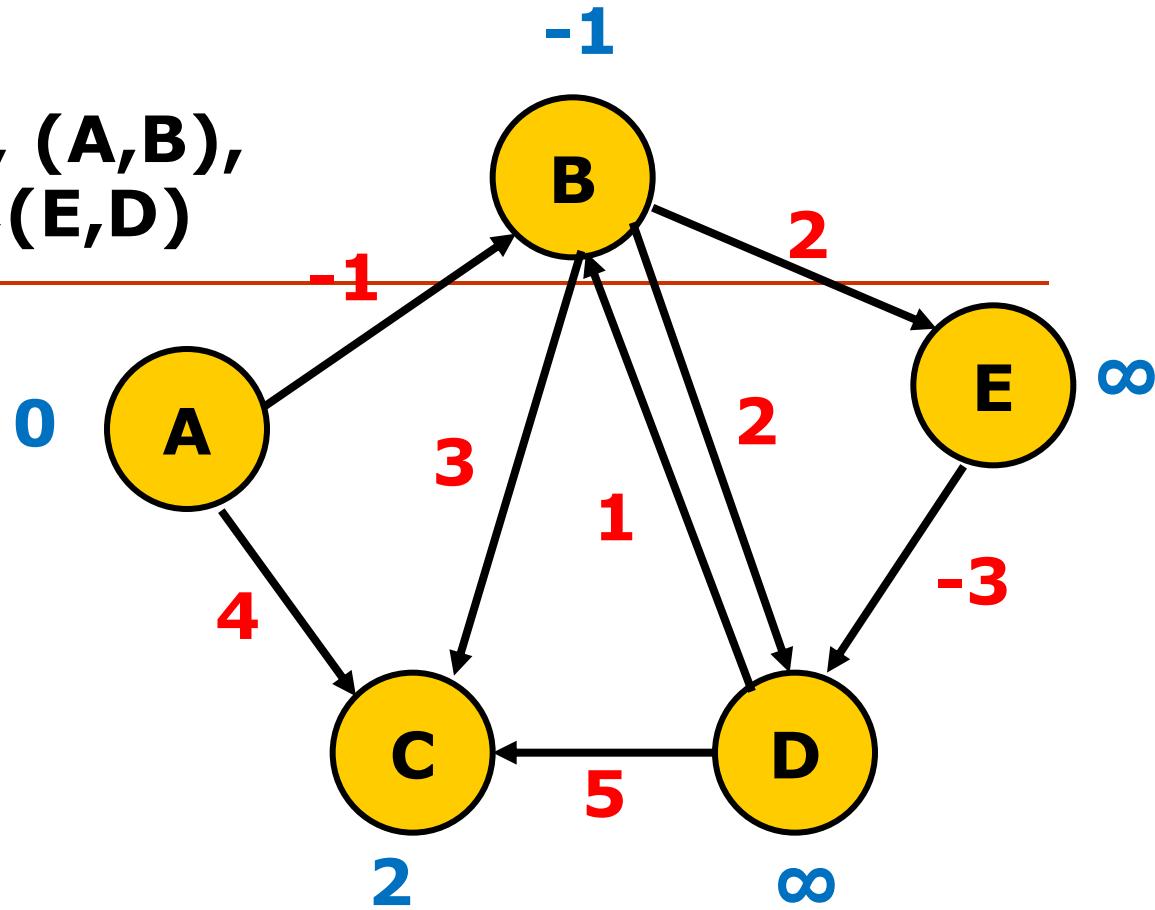
(B,E), (D,B), (B,D), (A,B),  
(A,C), (D,C), (B,C),(E,D)



| Vertex | A | B        | C        | D        | E        |
|--------|---|----------|----------|----------|----------|
| dist   | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ |

## Process sequence:

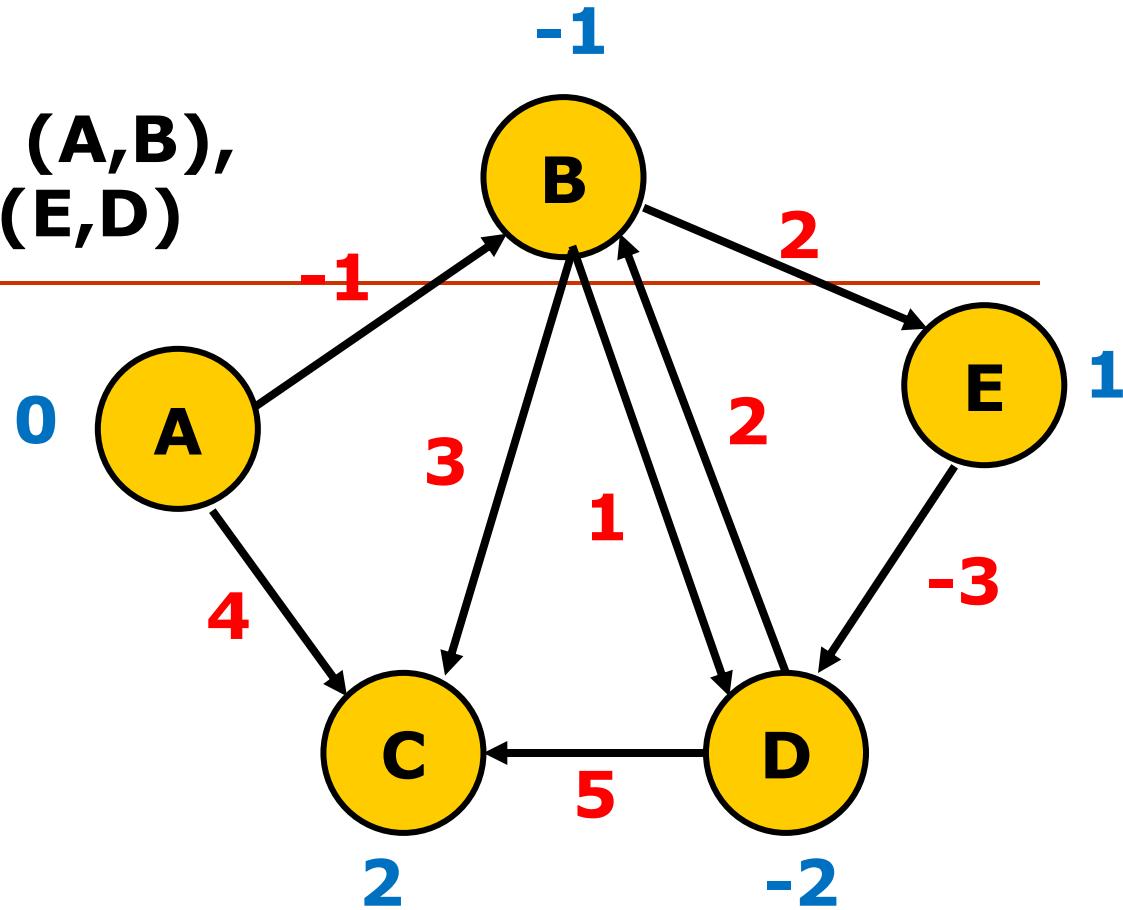
(B,E), (D,B), (B,D), (A,B),  
(A,C), (D,C), (B,C),(E,D)



| Vertex | A | B  | C | D        | E        |
|--------|---|----|---|----------|----------|
| dist   | 0 | -1 | 2 | $\infty$ | $\infty$ |

## Process sequence:

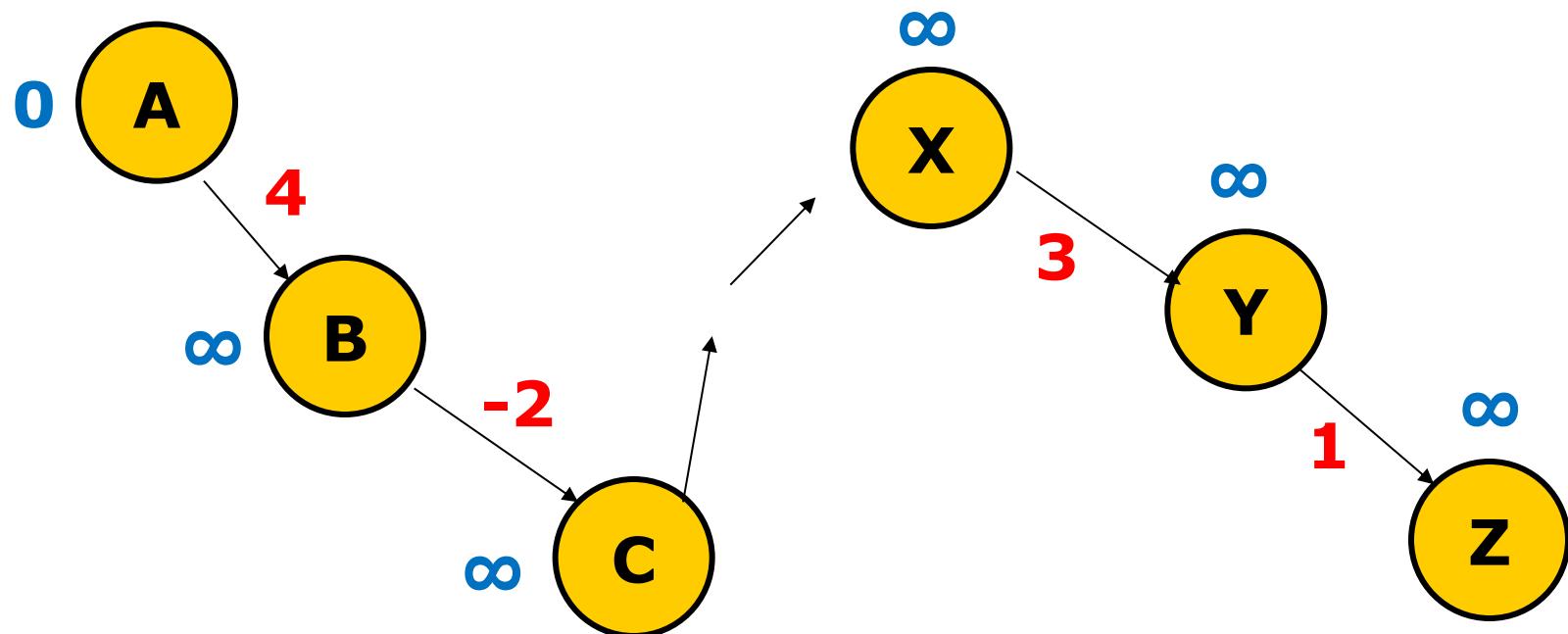
(B,E), (D,B), (B,D), (A,B),  
 (A,C), (D,C), (B,C),(E,D)



| Vertex | A | B  | C | D        | E        |
|--------|---|----|---|----------|----------|
| dist   | 0 | -1 | 2 | $\infty$ | $\infty$ |
|        | 0 | -1 | 2 | 1        | 1        |
|        | 0 | -1 | 2 | -2       | 1        |

# Why need to do $|V-1|$ times?

- As the sequence that you process the edges are random, you might end up only updating one node in each pass.



# The algorithm

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- Report if there is a negative weight cycle
  - Do following for each edge  $u-v$   
.....If  $\text{dist}[v] > \text{dist}[u] + \text{weight of edge } uv$ ,  
then “Graph contains negative weight cycle”
- The idea is, the previous step guarantees the shortest distances if the graph doesn't contain a negative weight cycle. If we iterate through all edges one more time and get a shorter path for any vertex, then there is a negative weight cycle

# Complexity

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- Initialisation  $O(V)$

- ```
int [] dist = new int[V];
for (int i = 0; i < V; ++i) {
    dist[i] = Integer.MAX_VALUE;
dist[src] = 0;
```

- calculates shortest distances. $O(VE)$

- $|V-1| * |E|$