

1 Introduction

Some questions to ask before starting on a problem

- Extract out important keywords (what DS to use?)
- Edge cases? e.g. if size==0 or size==1,
- Trivial cases? can just hardcode

Code styling

- CS2030 Code Styling Guide
- Google Java Styling Guide
- **Modularity**: use method to print answers inside main method

```
1  \\ print answer
2  ans = simulate(n,k,m);
3  printAns();
```

- **No global variables**

2 Java

How to throw exception?

```
1 public class MyException extends
   Exception {
2     private int var;
3     public MyException(int var) {
4         this.var = var
5     }
6     public int getVar() {
7         return this.var;
8     }
9 }
10
11 public class Main {
12     public static void main(String[] args
13     ) {
14         try {
15             ...
16             throw new MyException(errorVar);
17         } catch (MyException e) {
18             System.out.println(e.getVar());
19         }
20 }
```

3 Data Structures

$$O(1) < O(\log(n)) < O(n^c) \text{ where } c < 1$$

$$O(n) < O(\log(n!)) = O(n \log(n)) < O(n^2)$$

$$O(n^k) [\text{where } k > 2] < O(k^n) [\text{where } k \geq 1] < O(n!)$$

How to implement Data Structures?

- Composition: use well-known DS as an attribute of the implemented DS
- Inheritance: extends well-known DS

3.1 Linked List

- Motivation: implementation of list using array needs to occupy contiguous memory space (can result in memory error)

- Variants of linked list:
 - Tailed (need to maintain head and tail)
 - Circular
 - Doubly linked (prev and next attributes for ListNode)
- How to find cycle?

Answer: use fast and slow pointers

```
1     slow = slow.next;
2     fast = fast.next.next;
```

- **[IMPT]** Drawing pictures is very important to visualize the program!

Java API: ArrayList or LinkedList

```
\\ constructor
ArrayList<Integer> list = new
    ArrayList<Integer>();
```

3.2 Stack

```
// to construct an array of generics
E[] arr = (E[]) new Object[size];
/*
// does not work
E[] arr = new E[size]
*/
```

Uses:

- **[IMPT]** Converting infix to postfix expression (Lecture 4 Slide 28)
- **[IMPT]** Evaluating postfix expression

3.3 Queue

Uses:

- **[IMPT]** Breadth-first traversal of trees
- Sliding Window (especially important for contiguous blocks of stuff)

4 Recursion

[IMPT] Recipe for recursion (3 fingers)

1. General recursive case: identify simpler instances of the same problem
2. Base case: cases that we can solve without recursion
3. Be sure that we are able to reach the simplest instance so that we won't end up in infinite loop

Uses

- Insert item into sorted LinkedList
- Tower of Hanoi
- **[IMPT]** Combination (n choose k)
- Binary search
- Finding k -th smallest element (use pivot element p)
 - move elements $< p$ to the left of p
 - move elements $> p$ to the right of p
- Printing all permutations of a String

Overloading: same function name but with different parameters (useful in Java)

Backtracking

- Solving problems recursively by trying to build a solution incrementally, one piece at a time, removing those solutions that fail to satisfy the constraints of the problem at any point in time
- e.g. Queens Lab 4B: board is fixed queens can be added or removed!

5 Sorting

Some definitions

- **Sort key**: use particular value of an object to do comparison and sort
- **In-place**: requires only a constant amount of extra space during the sorting process
- **Stable**: relative order of elements with the same key value is preserved by the algorithm

Some ideas used in sorting:

- Internal vs external sort
- Iterative vs recursive
- Comparison vs non-comparison based
e.g. radix sort
- Divide and conquer

Applications

- Uniqueness testing
- Deleting duplicates
- Frequency counting
- Efficient searching

	Iterative	Recursive
Comparison	Bubble, Selection, Insertion	Quick, Merge
Non-comparison		Radix

5.1 Algorithms

5.1.1 Selection Sort

Time complexity: $O(n^2)$

Limitation: Not stable

5.1.2 Bubble Sort

Time complexity: $O(n^2)$

- Using flag: $O(n)$ isSorted, is the input already sorted?

5.1.3 Insertion Sort

Time complexity:

- Best case: input already sorted ($O(n)$)
- Worst case: input reversely sorted ($O(n^2)$)

5.1.4 Merge Sort

Time complexity:

- merge(arr, left, mid, right) is $O(\text{right} - \text{left} + 1)$
- merge is called $\log n$ times
- Hence $O(n \log n)$

Limitations:

- Need temporary array to store values during the merge process (not in-place)

5.1.5 Quick Sort

Time complexity:

- partition()
- quicksort(a, i, p)
- Worst case is when it is already sorted, so the first group (elements < p) is empty: $O(n^2)$
- Best case: occurs when array is divided into 2 equal halves
 - Depth is $\log n$
 - Each level takes n comparisons (including swaps)
 - Hence $O(n \log n)$ which is also the average case

Limitation: Not stable

5.1.6 Radix Sort

Treat each data as a character string: no comparison needed

Trick: sort by unit digit \rightarrow tenth digit \rightarrow hundredth and so on...

Time complexity:

- Initialize 10 groups (queues) to group the elements
- Complexity is $O(dn)$ where d is the maximum number of digits of the n numeric strings in the array

Limitation: Not in-place

5.1.7 Bucket Sort

How it works:

- There are b buckets, and each element arr is inserted into bucket according to a function e.g. $(\text{int}) \text{arr}[j] * 10$
- Similar to radix sort but b can be any number (base?) e.g. Tut 5 Q 3(b) where $N \leq \text{arr}[i] \leq 3N$, we can have $3N$ buckets $1, 2, 3, \dots, 3N$ so that each bucket contains only 1 element
- So only 1 pass is needed a.k.a. $O(3N)$ time
- Possible problem: takes up alot of space?

	Worst Case	Best Case	In-place?	Stable?
Selection	$O(n^2)$	$O(n^2)$		No
Insertion	$O(n^2)$	$O(n)$		
Bubble	$O(n^2)$	$O(n^2)$		
Bubble (Flag)	$O(n^2)$	$O(n)$		
Merge	$O(n \log n)$	$O(n \log n)$	No	
Radix	$O(dn)$	$O(dn)$	No	
Quick	$O(n^2)$	$O(n \log n)$		No

5.2 Java Sorting

For list/arrays:

- To convert arrays to list use Arrays.asList
- Arrays.sort or Collections.sort

For others: use Collections.sort(list, compObj)

```
import java.util.Comparator;
class ObjComparator implements
    Comparator<Obj> {
```

```

3 public int compare(Obj o1, Obj o2) {
4     // if positive, o1 > o2
5     // if negative, o1 < o2
6     // if zero,      o1 = o2
7 }
8 public boolean equals(Object obj) {
9     // check to see if we have the
10    same comparator object
11    return this == obj;
12 }

```

6 Hashing

Map ADT: <key, value> pairs mapping with 3 basic operations

- **Retrieval:** retrieve value using the given key
- **Insertion:** insert/replace a value using the given key
- **Deletion:** delete the <key, value> pair using the given key

Hash Table: data structure that uses a **hash function** to efficiently map keys to values, for efficient search and retrieval

Types of Tables:

- Direct Addressing Table
 - Restrictions:
 - * Keys must be non-negative integer values
 - * Range of keys must be small
 - * Keys must be dense
- Hash Tables
 - Map large integers to smaller integers (mod?)
 - Map non-integers to integers
 - **Collision:** hash function does not guarantee two different keys go to two different slots
two different keys have the same **hash value**
 - Criteria of good hash functions
 - * Fast to compute
 - * Scatter keys evenly
 - * Less collisions
 - * Need less slots
 - Perfect hash functions: *one-to-one* mapping between keys and hash values *i.e.* no collision occurs
 - Minimal perfect hash functions: table size is the same as the number of keywords supplied
 - **Uniform Hash functions:** distributes keys evenly in the hash table (e.g. mod, floor function)

$$\text{hash}(k) = \left\lfloor \frac{km}{X} \right\rfloor \text{ where } k = 0, 1, 2, \dots, X - 1$$

- * Division method: map into a table with m slots

$$\text{hash}(k) = k \bmod m$$

- * Multiplication method:

1. Multiply by a constant real number A between 0 and 1
*Knuth recommends $A = 1/\phi = 0.618033$ to minimize collisions
2. Extract the fractional part
3. Multiply by m , the hash table size
 $\text{hash}(k) = \lfloor m(kA - \lfloor kA \rfloor) \rfloor$

- How to choose m ?
 - * Pick a prime number close to a power of two
 - * power of 10 or 2 are no good cos it's the same as extracting the last few digits of decimal/binary representation
- **Hashing of Strings**
 - * Summing all the characters is no good: because strings with same letters but different orders will collide
 - * How to solve: take into account order of characters!

```

1 hash(s):
2     sum=0
3     for each character c in s:
4         sum = sum*31+s
5     return sum%m

```

6.1 Collision Resolution

$$\alpha(\text{load factor}) = \frac{n(\text{total number of keys})}{m(\text{number of slots})}$$

α measures how full the hash table is

Criteria of good collision resolution method

- Minimize clustering
- Always find an empty slot if it exists
- Give different probe sequences when 2 initial probes are the same (secondary hash function)
- Fast

6.1.1 Separate Chaining

- Use LinkedList to store keys with the same slot location
- Ideally can sort the LinkedList based on key to aid in searching

Some problems:

- find(key) and delete(key) takes $O(n)$ time
- α is the average length of the LinkedList and will increase when n increases
 - Hence it is good to keep α bounded \Rightarrow reconstruct the whole table when α exceeds a bound
- Not cache friendly

6.1.2 Linear Probing

Probe sequence:

```

1 hash(key)
2 hash(key+1)%m
3 hash(key+2)%m ...

```

- **Insert:**
When we get a collision, we scan linearly for the next available slot and put the key there
- **Find:**
Probe sequence increases linearly from hash(k) until current key is equal to the key we want to find
- **Delete**
 - **[IMPT]** Cannot simply remove a value because find() only works when contiguous cells are occupied

- So how? Use lazy deletion (three different states of a slot)
 - * Occupied
 - * Occupied but mark as deleted
 - * Empty

Some problems:

- **Primary clustering:** Can create many consecutive slots, increasing running time of find/insert/delete $O(n)$

Modified linear probing: (d and m are co-primes) to avoid primary clustering

```
1 hash(key)
2 hash(key+1*d)%m
3 hash(key+2*d)%m ...
```

6.1.3 Quadratic Probing

```
1 hash(key)
2 hash(key+1^2)%m
3 hash(key+2^2)%m ...
```

Theorem of Quadratic Probing

If $\alpha < 0.5$ (half-full) and m is prime, then we can always find an empty slot

Some problems

- When table is more than half-full, there can be endless looping!
 - To avoid table half-full, we can **resize** the table
 - Usually new $m = 2 \times m$
 - But also need to re-hash all existing keys (expensive operation)
- **Secondary clustering:** if two keys have the same initial position, their probe sequences are the same, but not as bad as linear probing

6.1.4 Double Hashing

Use a secondary hash function

```
1 hash(key)
2 hash(key+1*hash2(key))%m
3 hash(key+2*hash2(key))%m ...
```

Note that the secondary hash function must not evaluate to 0 (otherwise it's the same as separate chaining if not worse because of infinite loop)

$$\text{hash}_2(\text{key}) = p - (\text{key} \bmod p)$$

7 Trees

Some terminologies: ancestor, descendant, parent, sibling, child, root, leaf node

- Internal node: has one or more children, but root node is not an internal node
- Level of a node: level of root is 0, depends on how far it is from the root
- Height: maximum level of the nodes
- Size: number of nodes

- **Binary tree:** each node has at most 2 ordered children
- **Full binary tree:** all nodes at level $< h$ have two children, where h is the height of the tree
- **Complete binary tree:** full down to level $h - 1$, with level h filled in from left to right

Implementations

- Reference based
- Array based

```
1 class BinaryTree {
2     int root;
3     int free; // free space
4     TreeNode tree[];
5 }
6
```

- What is free space?
the last element where the slot is free, if there are multiple free slots, all the slots before the last will link towards the last one \Rightarrow last one is the pointer of the free
- Representing complete tree using an array: use heap?

$$i_{\text{left}} = i * 2 + 1, i_{\text{parent}} = i / 2$$

7.1 Traversals

7.1.1 Post-order traversal

Traverse the root after traversing the left and right subtrees

```
1 postorder(T) {
2     if T is not empty then {
3         postorder(T.left)
4         postorder(T.right)
5         print(T.item)
6     }}
```

7.1.2 Pre-order traversal

Traverse the root before traversing the left and right subtrees

```
1 preorder(T) {
2     if T is not empty then {
3         print(T.item)
4         postorder(T.left)
5         postorder(T.right)
6     }}
```

7.1.3 In-order traversal

Traverse the root in between traversing the left and right subtrees (**Do a sweep from left to right**)

```
1 inorder(T) {
2     if T is not empty then {
3         postorder(T.left)
4         print(T.item)
5         postorder(T.right)
6     }}
```

7.1.4 Level-order traversal

Traverse the tree level by level and from left to right (Queue is important)

```

1 levelorder(T) {
2   if T is empty return
3   Q = new Queue
4   Q.enqueue(T)
5
6   while Q is not empty {
7     curr = Q.dequeue()
8     print curr.item
9     if curr.left is not empty {
10      Q.enqueue(curr.left)
11    } if curr.right is not empty {
12      Q.enqueue(curr.right)
13    }
14  }

```

7.1.5 Evaluation of Expression Tree

Note that post-order, in-order, and pre-order of expression tree will produce postfix, infix, and prefix expressions [IMPT]
Recursive procedure!

7.2 Binary Search Trees (BST)

Some operations: Usually $O(h)$, but note that it's possible that $h = n$ if it is skewed (hence need AVL Tree)

- Find min/max element
- Search for x
- Insertion
- Deletion (3 cases)
 - node to be deleted T has no children
 - T has only 1 child (left)
 - node to be deleted T has two children \Rightarrow replace with **successor (smallest element in the right subtree)**
- Successor/Predecessor
[IMPT] note that if this was to be implemented, we need a `.parent` attribute as an addition to the `.child` attribute
- Inorder traversal \Rightarrow each node will be traversed not more than 3 times! wow

7.3 AVL Trees

Property:

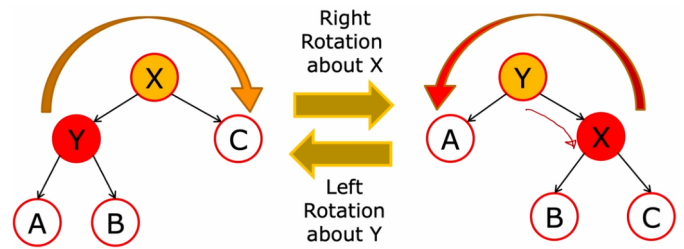
- At any node, the difference in height between left and right subtree is at most 1 (invariant)

$$|h_l - h_r| \leq 1$$

- A height balanced tree with N vertices has height $h < 2 \times \log_2(N) \Rightarrow h = O(\log(N))$
- Minimal AVL Tree of height h : having the height h and fewest possible number of nodes

Operations

- `rotateRight()/rotateLeft()`



- `insert()`: do BST to find the appropriate node to insert to, then have two cases, and also need to pass through parents to see if they are height-balanced
 - insert outside: single rotation
 - insert inside: double rotation
- Find k -th smallest item
store `.size` attribute and do recursive stuff [IMPT]
Quickselect and partition on unsorted array
Running time:
 - BST: $O(h)$
 - Unsorted array: Best case is $O(N)$, Worst case is $O(N^2)$

7.4 TreeMap Java API

- `higherkey()`, `floorkey()`: similar to predecessor and successor
- Has sorted key in tree structure

8 Priority Queue

Property

- Insert item with a given key
- Remove the item with maximum key

Implementations

- Unsorted list: insertion takes $O(1)$ but deletion takes $O(n)$ to remove the maximum key
- Sorted list: insertion takes $O(n)$ time but deletion takes $O(n)$ time
- Heap!

8.1 Heap

Properties:

- A **complete binary tree**
 - Either is empty,
 - , or satisfies the **heap property**: for every node v , the search key in v is greater or equal to those in the children of v
- Usually we talk about max heap
- Some access stuff

```

1 left(i)   = 2*i + 1
2 right(i)  = 2*i + 2
3 parent(i) = floor((i-1)/2)

```

Operations

- `heapRebuild(i)`: swap down from index i until it reaches a leaf and satisfies the heap property
- `heapify()`: build a heap from an unsorted array (utilises `heapRebuild`) and is used for `heapSort`
 - Running time** = $O(n)$

- Total number of nodes = $n = 2^{h+1} - 1$
- Total number of bubbling down = $n - h - 1$ which is less than the total number of edges connecting the nodes
- heapSort: partition the unsorted array into two parts, the heap and sorted portion; remove the max value from heap and put it into the sorted portion so that eventually the array is in ascending order
 - In-place
 - Not stable (because of bubbling/swapping operations)
 - Complexity = $O(n \log n)$

9 Graphs

10 Java Tricks

- OOP is important (CardGame)
 - If it involves an array, OOP is useful, methods can just modify properties/attributes of the object class (e.g. `reversed=true; increment=4`)
 - * Especially true if only need to print statement at the end
- Invariance: property that stays constant???
- Lab 5C: Pancakes: Use number of inversions if it's even or not
- Use `StringBuilder` for return statements
 - Java `StringBuilder` API
 - Zigzag conversion
- Tut 07 \Rightarrow Contiguous cells can be represented by start and end only