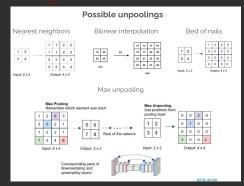
·self-supervised algorithm (locals generated from cinput)

· reconstruct input ofter compressing it.

Transposed completion



## Unpoline



Varietional outsencoder - VAE

· Like AE, but you learn parameters of a distribution

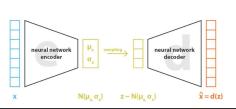
Madeling your dote

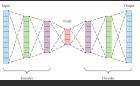
. In the middle of the natural, the lotent space, Similar points emade a similar inputs

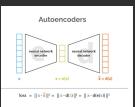
· of inference time you sample points from the distribution and pass to the saccolor, it generates a new image not in the TR set.

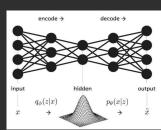
. Inerative models

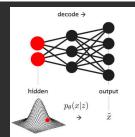
• During training we predict the  $\mu_{\chi^*}\,\sigma_{\chi^*}$  we sample from N( $\!\mu_\chi,\sigma_\chi\!$  and generate an output.











The total loss is a combination of the two:

$$J_{
m VAE} = \overline{J_{
m reconstruction}} + eta \overline{J_{
m KL}}$$

where  $\beta$  is a weighting factor that controls the trade-off between reconstruction and regularization.

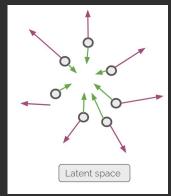
The two losses compete with each other:

- Reconstruction Loss wants to separate points to improve decoding accuracy.
- KL Loss wants to group points together to ensure a continuous, smooth latent space.

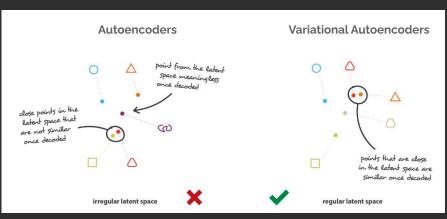
If  $\beta$  is too low  $\rightarrow$  The model ignores regularization and memorizes the training data (like a standard Autoencoder).

If  $\beta$  is too **high**  $\rightarrow$  The model learns a smooth latent space but with poor reconstruction quality.

 $loss \; = \; || \; x \; - \; \stackrel{\textstyle \star}{x'} ||^2 \; + \; KL[ \; N(\mu_x, \sigma_x), \; N(0, 1) \; ] \; = \; || \; x \; - \; d(z) \; ||^2 \; + \; KL[ \; N(\mu_x, \sigma_x), \; N(0, 1) \; ]$ 



# Latent space differences





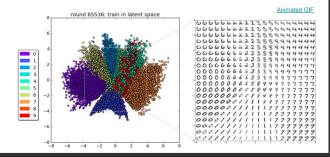
#### What happens?

- The latent representations (colored blobs) are scattered and do not overlap.
- Each point is encoded into a separate region of the latent space.
- . The space is sparse, making interpolation between points difficult.
- This can lead to overfitting and poor generalization when sampling new data.

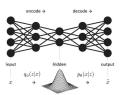
#### What happens?

- The latent space clusters better with smooth transitions between different groups.
- Different representations overlap, forming a continuous distribution.
- The model generalizes better, meaning it can generate smooth interpolations and meaningful new samples.

### Variational Autoencoders - Latent space reconstruction



 Variational Autoencoders (VAE) are good at learning representations (interpretable dimensions, possibility to set complex priors).



 Generative Adversarial Networks (GANs) are good at generating new samples (clever loss). Trickier to train.

