

ATML - Tutorial 3

PROBLEM SET 3 - SOLUTIONS

EXERCISE 1.1

It suffices to observe that

$$-\int_0^T \dot{X}_t^\top S_t dt = X_0 S_0 + \int_0^T X_t^\top dS_t$$

and thus

$$\mathbb{E} \left[-\int_0^t \dot{X}_s^\top S_s ds \right] = X_0 S_0$$

does not depend on $X \in \mathcal{A}$.

EXERCISE 1.2

$\forall X \in \mathcal{A} \quad \forall t \leq \tau < T$ using equation (2) we have

$$C_t^*(X_t) \leq \mathbb{E}_t \left[\int_t^\tau (\dot{X}_u^2 + \lambda X_u S_u) du + C_\tau^*(X_\tau) \right]$$

$$= \mathbb{E}_t \left[C_\tau^*(X_\tau) + \int_0^\tau (\dot{X}_u^2 + \lambda X_u S_u) du \right] - \int_0^t (\dot{X}_u^2 + \lambda X_u S_u) du$$

Hence,

$$C_t^*(X_t) + \int_0^t (\dot{X}_u^2 + \lambda X_u S_u) du$$

$$\leq \mathbb{E}_t \left[C_\tau^*(X_\tau) + \int_0^\tau (\dot{X}_u^2 + \lambda X_u S_u) du \right]$$

EXERCISE 1.3

Define $\varphi(v, b) := bv + v^2$ and observe that

$$\varphi(v, b) \geq -\frac{1}{2}b^2 \quad \forall v, b \in \mathbb{R}.$$

Define

$$f(s, x, v, a, b, z) := z + \frac{\sigma^2}{2} s^2 a + \varphi(v, b) + \lambda x s.$$

The drift of dM_t is

$$\begin{aligned} & \partial_t G + \frac{\sigma^2}{2} S_t^2 \partial_{ss}^2 G + \dot{X}_t \partial_x G + \dot{X}_t^2 + \lambda X_t S_t \\ &= f(S_t, X_t, \dot{X}_t, \partial_{ss}^2 G, \partial_x G, \partial_t G) \\ &\geq \partial_t G + \frac{\sigma^2}{2} S_t^2 \partial_{ss}^2 G - \frac{1}{2} (\partial_x G)^2 + \lambda X_t S_t. \end{aligned}$$

Therefore if the RHS is non-negative, the drift of dM_t is non-negative.

EXERCISE 1.4

(2) Straightforward computation.

(b) We only need to argue that

$$\lim_{t \uparrow T} \mathbb{E} \left[\frac{X_t^2}{T-t} \right] = 0 \quad \forall X \in \mathcal{A}.$$

By Jensen inequality we have that

$$\begin{aligned} X_t^2 &= (X_T - X_t)^2 = \left(\int_t^T \dot{X}_u du \right)^2 \\ &\leq (T-t)^2 \int_t^T \dot{X}_u^2 du. \end{aligned}$$

Therefore,

$$\frac{1}{T-t} \mathbb{E} [X_t^2] \leq (T-t) \mathbb{E} \left[\int_t^T \dot{X}_u^2 du \right] \rightarrow 0.$$

EXERCISE 1.5

Using Itô's formula and equation (3) we have

$$\begin{aligned} G^*(t, X_t, S_t) &= G^*(0, X_0, S_0) \\ &\quad + \int_0^t \left(\partial_t G^* + \dot{X}_u \partial_x G^* + \frac{\sigma^2}{2} S_u^2 \partial_s^2 G^* \right) du \\ &\quad + \int_0^t \partial_s G^* dS_u \\ &= \int_0^t \left(\frac{1}{4} (\partial_x G^*)^2 - 1 X_u S_u + \dot{X}_u \partial_x G^* \right) du \\ &\quad + \int_0^t \partial_s G^* dS_u. \end{aligned}$$

Since $\forall v, b \in \mathbb{R}$ it holds $\frac{1}{4}b^2 + bv \geq -v^2$, it follows

$$\begin{aligned} G^*(t, X_t, S_t) &\geq G^*(0, X_0, S_0) \\ &\quad + \int_0^t \left(-\dot{X}_u^2 - 1 X_u S_u \right) du + \int_0^t \partial_s G^* dS_u. \end{aligned}$$

We conclude by taking expectation on both sides and using EXERCISE 1.4(b).

EXERCISE 1.6

It suffices to observe that $X^* \in \mathcal{A}$ and

$$G^*(0, X_0, S_0) = \mathbb{E} \left[\int_0^T \left((\dot{X}_t^*)^2 + 1 X_t^* S_t \right) dt \right].$$

